-0.06 %FS (typ)



National Semiconductor DAC101S101/DAC101S101Q

10-Bit Micro Power, RRO Digital-to-Analog Converter

General Description

The DAC101S101 is a full-featured, general purpose 10-bit voltage-output digital-to-analog converter (DAC) that can operate from a single +2.7V to 5.5V supply and consumes just 175 µA of current at 3.6 Volts. The on-chip output amplifier allows rail-to-rail output swing and the three wire serial interface operates at clock rates up to 30 MHz over the specified supply voltage range and is compatible with standard SPI™. QSPI, MICROWIRE and DSP interfaces. Competitive devices are limited to 20 MHz clock rates at supply voltages in the 2.7V to 3.6V range.

The supply voltage for the DAC101S101 serves as its voltage reference, providing the widest possible output dynamic range. A power-on reset circuit ensures that the DAC output powers up to zero volts and remains there until there is a valid write to the device. A power-down feature reduces power consumption to less than a microWatt.

The low power consumption and small packages of the DAC101S101 make it an excellent choice for use in battery operated equipment.

The DAC101S101 is a direct replacement for the AD5310 and is one of a family of pin compatible DACs, including the 8-bit DAC081S101 and the 12-bit DAC121S101. The DAC101S101 operates over the extended industrial temperature range of -40°C to +105°C while the DAC101S101Q operates over the Grade 1 automotive temperature range of -40°C to +125°C. The DAC101S101 is available in a 6-lead TSOT and an 8-lead MSOP and the DAC101S101Q is availabe in the 6-lead TSOT only.

Features

- DAC101S101Q is AEC-Q100 Grade 1 qualified and is manufactured on an Automotive Grade Flow.
- **Guaranteed Monotonicity**
- Low Power Operation
- Rail-to-Rail Voltage Output
- Power-on Reset to Zero Volts Output
- Wide Temperature Range of -40°C to +125°C
- Wide Power Supply Range of +2.7V to +5.5V
- **Small Packages**
- Power Down Feature

Key Specifications

Resolution 10 bits DNL +0.15, -0.05 LSB (typ)

Output Settling Time 8 µs (typ) Zero Code Error 3.3 mV (typ)

Full-Scale Error Power Consumption

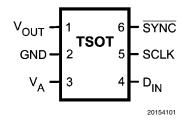
— Normal Mode 0.63 mW (3.6V) / 1.41 mW (5.5V) typ $0.14 \mu W (3.6V) / 0.33 \mu W (5.5V) typ$ Pwr Down

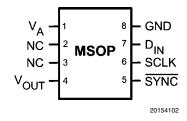
Mode

Applications

- Battery-Powered Instruments
- Digital Gain and Offset Adjustment
- Programmable Voltage & Current Sources
- **Programmable Attenuators**
- Automotive

Pin Configuration



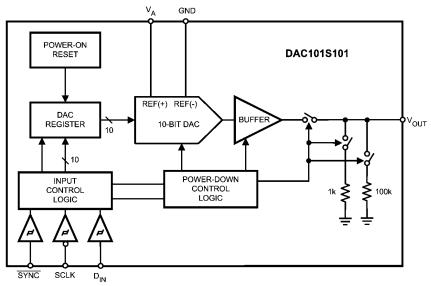


SPI™ is a trademark of Motorola, Inc.

Ordering Information

Order Numbers	Temperature Range	Package	Top Mark	Feature
DAC101S101CIMM	-40°C ≤ T _A ≤ $+105$ °C	MSOP	X62C	
DAC101S101CIMMX	-40°C ≤ T _A ≤ +105°C	MSOP T/R	7020	
DAC101S101CIMK	-40°C ≤ T _A ≤ +105°C	TSOT	X63C	
DAC101S101CIMKX	-40°C ≤ T _A ≤ +105°C	TSOT T/R	7030	
DAC101S101QCMK	-40°C ≤ T _A ≤ +125°C	TSOT		AEC-Q100 Grade 1
DAC101S101QCMKX	-40 °C \leq T _A \leq $+125$ °C	TSOT T/R	Q63C	Qualified; Automotive Grade Production Flow
DAC101S101EVAL	Evaluation Board	TSOT		

Block Diagram



20154103

Pin Descriptions

TSOT (SOT-23) Pin No.	MSOP Pin No.	Symbol	Description	
1	4	V _{OUT}	DAC Analog Output Voltage.	
2	8	GND	Ground reference for all on-chip circuitry.	
3	1	V _A	Power supply and Reference input. Should be decoupled to GND.	
4	7	D _{IN}	Serial Data Input. Data is clocked into the 16-bit shift register on the falling edges of SCLK after the fall of SYNC.	
5	6	SCLK	Serial Clock Input. Data is clocked into the input shift register on the f edges of this pin.	
6	5	SYNC	Frame synchronization input for the data input. When this pin goes low, it enables the input shift register and data is transferred on the falling edges of SCLK. The DAC is updated on the 16th clock cycle unless SYNC is brought high before the 16th clock, in which case the rising edge of SYNC acts as an interrupt and the write sequence is ignored by the DAC.	
	2, 3	NC	No Connect. There is no internal connection to these pins.	

Absolute Maximum Ratings (Note 1, Note

2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage, V _A	6.5V
Voltage on any Input Pin	$-0.3V$ to $(V_A + 0.3V)$
Input Current at Any Pin (Note 3)	10 mA
Package Input Current (Note 3)	20 mA
Power Consumption at T _A = 25°C	See (Note 4)
ESD Susceptibility (<i>Note 5</i>) Human Body Model Machine Model	2500V 250V
Soldering Temperature, Infrared, 10 Seconds (<i>Note 6</i>)	235°C
Storage Temperature	-65°C to +150°C

Operating Ratings (Note 1, Note 2)

Operating Temperature Range

 $\begin{array}{lll} {\rm DAC101S101} & & -40^{\circ}{\rm C} \leq {\rm T_A} \leq +105^{\circ}{\rm C} \\ {\rm DAC101S101Q} & & -40^{\circ}{\rm C} \leq {\rm T_A} \leq +125^{\circ}{\rm C} \\ {\rm Supply Voltage, V_A} & & +2.7{\rm V to 5.5V} \\ {\rm Any \ Input \ Voltage \ } & -0.1 \ {\rm V \ to \ } ({\rm V_A} + 0.1 \ {\rm V}) \\ {\rm Output \ Load} & & 0 \ {\rm to 1500 \ pF} \\ {\rm SCLK \ Frequency} & {\rm Up \ to \ 30 \ MHz} \\ \end{array}$

Package Thermal Resistances

Package	θ_{JA}
8-Lead MSOP	240°C/W
6-Lead TSOT	250°C/W

Electrical Characteristics

The following specifications apply for $V_A = +2.7V$ to +5.5V, $R_L = 2k\Omega$ to GND, $C_L = 200$ pF to GND, $f_{SCLK} = 30$ MHz, input code range 12 to 1011. **Boldface limits apply for T_{MIN} \le T_A \le T_{MAX}**: all other limits $T_A = 25^{\circ}C$, unless otherwise specified.

Symbol	symbol Parameter Conditions		Typical	Limits	Units
	Farameter	Conditions	(Note 9)	(Note 9)	(Limits)
STATIC PE	RFORMANCE				
	Resolution			10	Bits (min)
	Monotonicity			10	Bits (min)
INL	Integral Non-Linearity	Over Decimal codes 12 to 1011	±0.6	±2.8	LSB (max)
DNL	Differential Non-Linearity	V _A = 2.7V to 5.5V	+0.15	+0.35	LSB (max)
	Differential Non-Linearity		-0.05	-0.2	LSB (min)
ZE	Zero Code Error	$I_{OUT} = 0$	+3.3	+15	mV (max)
FSE	Full-Scale Error	I _{OUT} = 0	-0.06	-1.0	%FSR (max)
GE	Gain Error	All ones Loaded to DAC register	-0.10	±1.0	%FSR (max)
ZCED	Zero Code Error Drift		-20		μV/°C
TO OF	Coin Furay Townson	V _A = 3V	-0.7		ppm/°C
TC GE	Gain Error Tempco	V _A = 5V	-1.0		ppm/°C
OUTPUT C	HARACTERISTICS			•	
	Output Voltage Range	(Note 10)		0	V (min)
	Output Voltage Harige	(Note 10)		V _A	V (max)
		$V_A = 3V, I_{OUT} = 10 \mu A$	1.8		mV
ZCO	Zava Cada Outrout	$V_A = 3V, I_{OUT} = 100 \mu A$	5.0		mV
200	Zero Code Output	$V_A = 5V$, $I_{OUT} = 10 \mu A$	3.7		mV
		$V_A = 5V$, $I_{OUT} = 100 \mu A$	5.4		mV
		V _A = 3V, I _{OUT} = 10 μA	2.997		V
500		V _A = 3V, I _{OUT} = 100 μA	2.990		V
FSO	Full Scale Output	$V_A = 5V$, $I_{OUT} = 10 \mu A$	4.995		V
		$V_A = 5V$, $I_{OUT} = 100 \mu A$	4.992		V
	Mariana I and Compathana	$R_L = \infty$	1500		pF
	Maximum Load Capacitance	$R_L = 2k\Omega$	1500		pF
	DC Output Impedance		1.3		Ohm

Symbol	Parameter	Conditi	ons	Typical (Note 9)	Limits (Note 9)	Units (Limits)
		$V_A = 5V$, $V_{OUT} = 0V$, Input code = 3FFh		-63	, ,	mA
		$V_{\Delta} = 3V, V_{OLIT} = 0V,$				
		Input code = 3FFh		-50		mA
Ios	Output Short Circuit Current	$V_A = 5V$, $V_{OUT} = 5V$,				_
		Input code = 000h		74		mA
		$V_A = 3V, V_{OUT} = 3V,$		53		mA
		Input code = 000h		33		IIIA
OGIC INP		T		1		1
I _{IN}	Input Current (Note 10)				±1	μA (max)
V_{IL}	Input Low Voltage (<i>Note 10</i>)	$V_A = 5V$			0.8	V (max)
		V _A = 3V			0.5	V (max)
V_{IH}	Input High Voltage (<i>Note 10</i>)	V _A = 5V			2.4	V (min)
	, ,	V _A = 3V			2.1	V (min)
C _{IN}	Input Capacitance (Note 10)				3	pF (max)
OWER RE	EQUIREMENTS	I	lv 5 5 V	050	200	A (
		Normal Mode	$V_A = 5.5V$	256	332	μA (max
		f _{SCLK} = 30 MHz	$V_A = 3.6V$	174	226	μA (max
		Normal Mode	$V_A = 5.5V$	221	297	μA (max
		f _{SCLK} = 20 MHz	V _A = 3.6V	154	207	μA (max
		Normal Mode	$V_A = 5.5V$	145		μA (max
I _A	Supply Current (output unloaded)	f _{SCLK} = 0	V _A = 3.6V	113		μA (max
		All PD Modes,	$V_A = 5.0V$	83		μA (max
		f _{SCLK} = 30 MHz	$V_A = 3.0V$	42		μA (max
		All PD Modes, f _{SCLK} = 20 MHz	$V_A = 5.0V$	56		μA (max
			$V_A = 3.0V$	28	1.0	μA (max
		All PD Modes, f _{SCLK} = 0 (<i>Note 10</i>)	$V_A = 5.5V$	0.06	1.0	μA (max
		+	$V_A = 3.6V$	0.04	1.0	μA (max
		Normal Mode f _{SCLK} = 30 MHz	$V_A = 5.5V$	1.41	1.83	mW (max
		-	$V_A = 3.6V$	0.63	0.81	mW (max
		Normal Mode f _{SCLK} = 20 MHz	$V_A = 5.5V$ $V_A = 3.6V$	1.22	1.63	mW (max
			$V_A = 5.6V$ $V_A = 5.5V$	0.55	0.74	mW (max
	Barray Carray marking (autout	Normal Mode f _{SCLK} = 0	$V_A = 3.6V$	0.80		μW (max
P_{C}	Power Consumption (output unloaded)		$V_A = 5.0V$ $V_A = 5.0V$	0.41		μW (max μW (max
	unioaueu)	All PD Modes, f _{SCLK} = 30 MHz	$V_A = 3.0V$ $V_A = 3.0V$	0.42		μW (max
		All PD Modes,	$V_A = 5.0V$ $V_A = 5.0V$	0.13		μW (max
		f _{SCLK} = 20 MHz	$V_A = 3.0V$ $V_A = 3.0V$	0.28		μW (max
		All PD Modes,	$V_A = 5.5V$	0.08	5.5	μW (max
		$f_{SCLK} = 0 $ (<i>Note 10</i>)	$V_A = 3.6V$	0.33	3.6	μW (max
		SULK - (111111)	$V_A = 5.0 V$ $V_A = 5 V$	91	0.0	μνν (max %
I_{OUT} / I_{A}	Power Efficiency	$I_{LOAD} = 2mA$	$V_A = 3V$	94		%
			I * A - O *	1 34		/0

A.C. and Timing Characteristics

The following specifications apply for $V_A = +2.7V$ to +5.5V, $R_L = 2k\Omega$ to GND, $C_L = 200$ pF to GND, $f_{SCLK} = 30$ MHz, input code range 12 to 1011. **Boldface limits apply for T_{MIN} \le T_A \le T_{MAX}**: all other limits $T_A = 25^{\circ}C$, unless otherwise specified.

Symbol	Parameter	Conductions		Typical	Limits	Units (Limits)
f _{SCLK}	SCLK Frequency				30	MHz (max)
t _s	Output Voltage Settling Time (Note 10)	100h to 300h code change, $R_L = 2k\Omega$	C _L ≤ 200 pF	5	7.5	μs (max)
SR	Output Slew Rate		•	1		V/µs
	Glitch Impulse	Code change from 200	h to 1FFh	12		nV-sec
	Digital Feedthrough			0.5		nV-sec
+	Wake-Up Time	$V_A = 5V$		6		μs
t _{WU}	wake-op fillie	$V_A = 3V$		39		μs
1/f _{SCLK}	SCLK Cycle Time				33	ns (min)
t _H	SCLK High time			5	13	ns (min)
t _L	SCLK Low Time			5	13	ns (min)
t _{SUCL}	Set-up Time SYNC to SCLK Rising Edge			-15	0	ns (min)
t _{SUD}	Data Set-Up Time			2.5	5	ns (min)
t _{DHD}	Data Hold Time			2.5	4.5	ns (min)
100114 (21112 22 24 27 27 27 27 27 27 27 27 27 27 27 27 27	SCLK fall to rise of SYNC	V _A = 5V		0	3	ns (min)
t _{CS}	SCLN Iall to lise of SYNC	V _A = 3V		-2	1	ns (min)
+	SYNC High Time	$2.7 \le V_A \le 3.6$		9	20	ns (min)
t _{SYNC}	13 TNO High Hime	$3.6 \le V_A \le 5.5$		5	10	ns (min)

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics. The guaranteed specifications apply only for the test conditions listed. Some performance characteristics may degrade when the device is not operated under the listed test conditions.

Note 2: All voltages are measured with respect to GND = 0V, unless otherwise specified

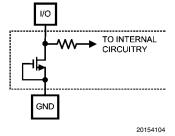
Note 3: When the input voltage at any pin exceeds the power supplies (that is, less than GND, or greater than V_A), the current at that pin should be limited to 10 mA. The 20 mA maximum package input current rating limits the number of pins that can safely exceed the power supplies with an input current of 10 mA to two.

Note 4: The absolute maximum junction temperature $(T_J max)$ for this device is 150°C. The maximum allowable power dissipation is dictated by $T_J max$, the junction-to-ambient thermal resistance (θ_{JA}) , and the ambient temperature (T_A) , and can be calculated using the formula $P_D MAX = (T_J max - T_A) / \theta_{JA}$. The values for maximum power dissipation will be reached only when the device is operated in a severe fault condition (e.g., when input or output pins are driven beyond the power supply voltages, or the power supply polarity is reversed). Obviously, such conditions should always be avoided.

Note 5: Human body model is 100 pF capacitor discharged through a 1.5 kΩ resistor. Machine model is 220 pF discharged through ZERO Ohms.

Note 6: See the section entitled "Surface Mount" found in any post 1986 National Semiconductor Linear Data Book for methods of soldering surface mount devices.

Note 7: The analog inputs are protected as shown below. Input voltage magnitudes up to $V_A + 300$ mV or to 300 mV below GND will not damage this device. However, errors in the conversion result can occur if any input goes above V_A or below GND by more than 100 mV. For example, if V_A is 2.7 V_{DC} , ensure that -100mV \leq input voltages \leq 2.8 V_{DC} to ensure accurate conversions.



Note 8: To guarantee accuracy, it is required that V_A be well bypassed.

Note 9: Typical figures are at T_J = 25°C, and represent most likely parametric norms. Test limits are guaranteed to National's AOQL (Average Outgoing Quality

Note 10: This parameter is guaranteed by design and/or characterization and is not tested in production.

Specification Definitions

DIFFERENTIAL NON-LINEARITY (DNL) is the measure of the maximum deviation from the ideal step size of 1 LSB, which is $V_{\rm REF}$ / 1024 = $V_{\rm A}$ / 1024.

DIGITAL FEEDTHROUGH is a measure of the energy injected into the analog output of the DAC from the digital inputs when the DAC outputs are not updated. It is measured with a full-scale code change on the data bus.

FULL-SCALE ERROR is the difference between the actual output voltage with a full scale code (3FFh) loaded into the DAC and the value of $V_A \times 1023 / 1024$.

GAIN ERROR is the deviation from the ideal slope of the transfer function. It can be calculated from Zero and Full-Scale Errors as GE = FSE - ZE, where GE is Gain error, FSE is Full-Scale Error and ZE is Zero Error.

GLITCH IMPULSE is the energy injected into the analog output when the input code to the DAC register changes. It is specified as the area of the glitch in nanovolt-seconds.

INTEGRAL NON-LINEARITY (INL) is a measure of the deviation of each individual code from a straight line through the input to output transfer function. The deviation of any given code from this straight line is measured from the center of that code value. The end point method is used. INL for this product is specified over a limited range, per the Electrical Tables.

LEAST SIGNIFICANT BIT (LSB) is the bit that has the smallest value or weight of all bits in a word. This value is

$$LSB = V_{REF} / 2^n$$

where V_{REF} is the supply voltage for this product, and "n" is the DAC resolution in bits, which is 10 for the DAC101S101.

MAXIMUM LOAD CAPACITANCE is the maximum capacitance that can be driven by the DAC with output stability maintained.

MONOTONICITY is the condition of being monotonic, where the DAC has an output that never decreases when the output code increases.

MOST SIGNIFICANT BIT (MSB) is the bit that has the largest value or weight of all bits in a word. Its value is 1/2 of V_{RFF} .

POWER EFFICIENCY is the ratio of the output current to the total supply current. The output current comes from the power supply. The difference between the supply and output currents, is the power consumed by the device without a load.

SETTLING TIME is the time for the output to settle within 1/2 LSB of the final value.

WAKE-UP TIME is the time for the output to settle within 1/2 LSB of the final value after the device is commanded to the active mode from any of the power down modes.

ZERO CODE ERROR is the output error, or voltage, present at the DAC output after a code of 000h has been entered.

Transfer Characteristic

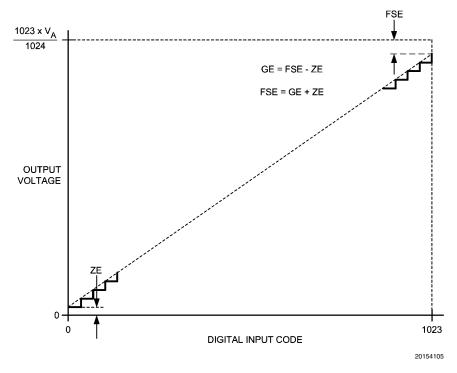


FIGURE 1. Input / Output Transfer Characteristic

Timing Diagram

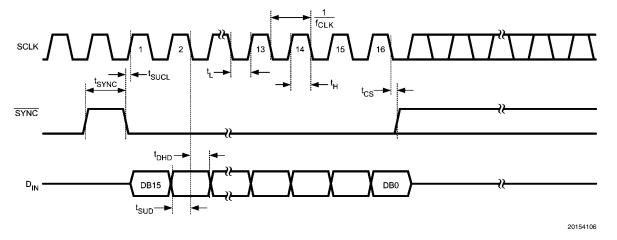
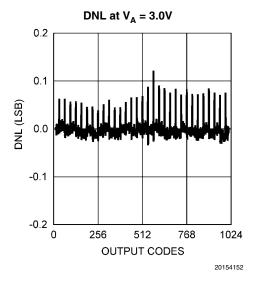
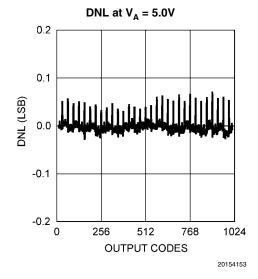
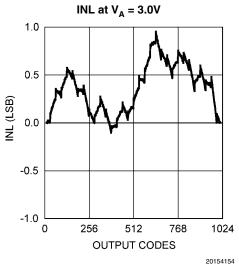


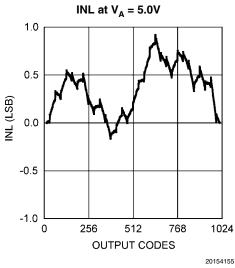
FIGURE 2. DAC101S101 Timing

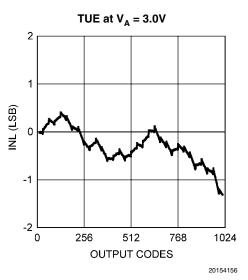
Typical Performance Characteristics f_{SCLK} = 30 MHz, T_A = 25C, Input Code Range 12 to 1011, unless otherwise stated

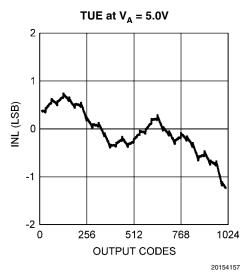


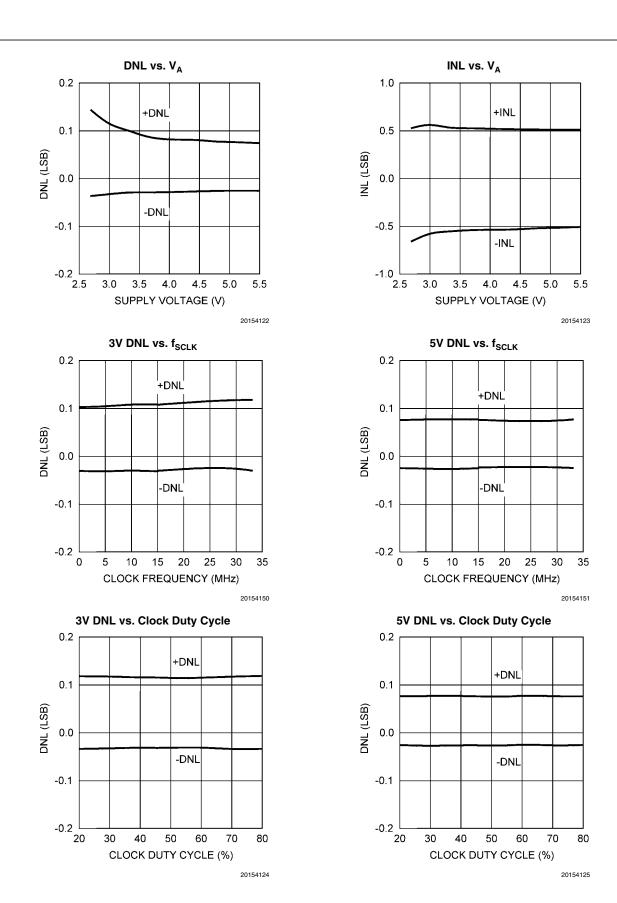


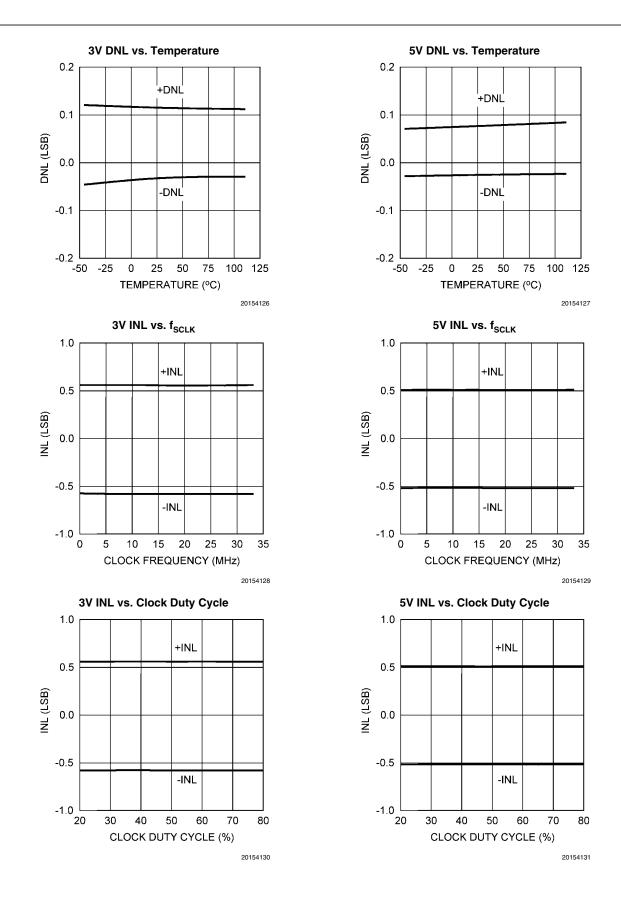


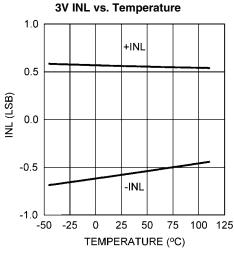


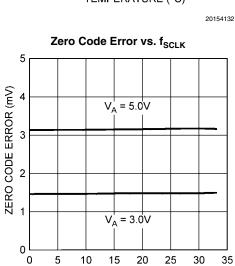




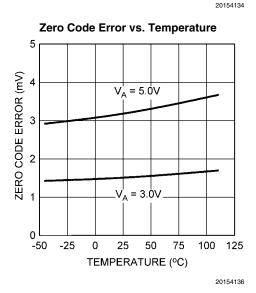


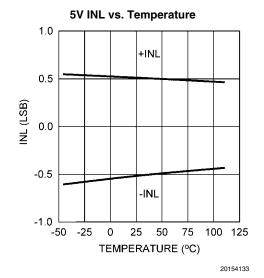


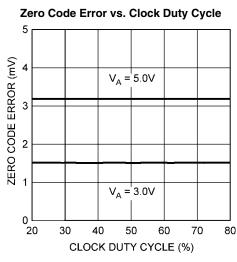


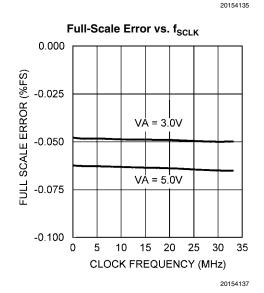


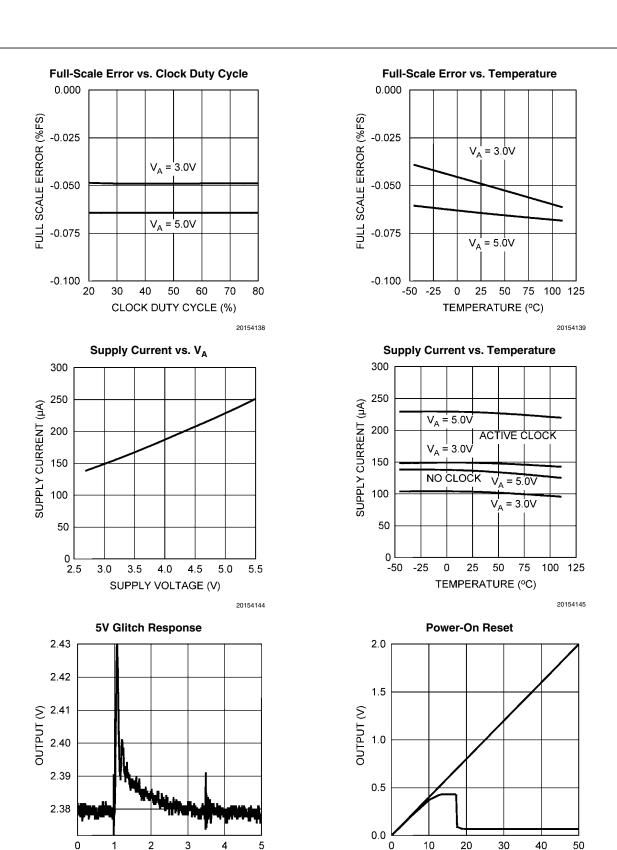
CLOCK FREQUENCY (MHz)











TIME (µs)

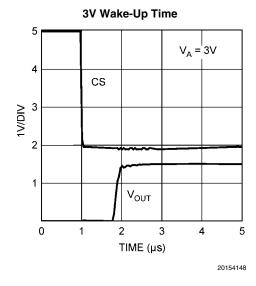
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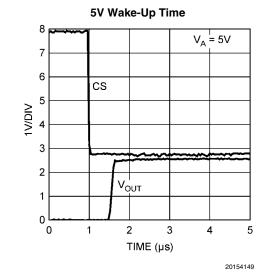
12 www.national.com

TIME (µs)

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1





1.0 Functional Description

1.1 DAC SECTION

The DAC101S101 is fabricated on a CMOS process with an architecture that consists of a resistor string and switches that are followed by an output buffer. The power supply serves as the reference voltage. The input coding is straight binary with an ideal output voltage of:

$$V_{OUT} = V_A x (D / 1024)$$

where *D* is the decimal equivalent of the binary code that is loaded into the DAC register and can take on any value between 0 and 1023.

1.2 RESISTOR STRING

The resistor string is shown in *Figure 3*. This string consists of 1024 equal valued resistors in series with a switch at each junction of two resistors, plus a switch to ground. The code loaded into the DAC register determines which switch is closed, connecting the proper node to the amplifier. This configuration guarantees that the DAC is monotonic.

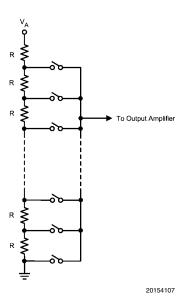


FIGURE 3. DAC Resistor String

1.3 OUTPUT AMPLIFIER

The output buffer amplifier is a rail-to-rail type, providing an output voltage range of 0V to V_A . All amplifiers, even rail-to-rail types, exhibit a loss of linearity as the output approaches the supply rails (0V and V_A , in this case). For this reason, linearity is specified over less than the full output range of the DAC. The output capabilities of the amplifier are described in the Electrical Tables.

1.4 SERIAL INTERFACE

The three-wire interface is compatible with SPI, QSPI and MICROWIRE as well as most DSPs. See the Timing Diagram for information on a write sequence.

A write sequence begins by bringing the $\overline{\text{SYNC}}$ line low. Once $\overline{\text{SYNC}}$ is low, the data on the D_{IN} line is clocked into the 16-bit serial input register on the falling edges of SCLK. On the 16th falling clock edge, the last data bit is clocked in and the programmed function (a change in the mode of operation and/or a change in the DAC register contents) is executed. At this point the $\overline{\text{SYNC}}$ line may be kept low or brought high. In either

case, it must be brought high for the minimum specified time before the next write sequence so that a falling edge of SYNC can initiate the next write cycle.

Since the $\overline{\text{SYNC}}$ and D_{IN} buffers draw more current when they are high, they should be idled low between write sequences to minimize power consumption.

1.5 INPUT SHIFT REGISTER

The input shift register, *Figure 4*, has sixteen bits. The first two bits are "don't cares" and are followed by two bits that determine the mode of operation (normal mode or one of three power-down modes). The contents of the serial input register are transferred to the DAC register on the sixteenth falling edge of SCLK. See Timing Diagram, *Figure 2*.

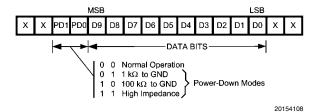


FIGURE 4. Input Register Contents

Normally, the SYNC line is kept low for at least 16 falling edges of SCLK and the DAC is updated on the 16th SCLK falling edge. However, if SYNC is brought high before the 16th falling edge, the shift register is reset and the write sequence is invalid. The DAC register is not updated and there is no change in the mode of operation.

1.6 POWER-ON RESET

The power-on reset circuit controls the output voltage during power-up. The DAC register is filled with zeros and the output voltage is 0 Volts and remains there until a valid write sequence is made to the DAC.

1.7 POWER-DOWN MODES

The DAC101S101 has four modes of operation. These modes are set with two bits (DB13 and DB12) in the control register.

TABLE 1. Modes of Operation

DB13	DB12	Operating Mode	
0	0	Normal Operation	
0	1	Power-Down with 1kΩ to GND	
1	0	Power-Down with $100k\Omega$ to GND	
1	1	Power-Down with Hi-Z	

When both DB13 and DB12 are 0, the device operates normally. For the other three possible combinations of these bits the supply current drops to its power-down level and the output is pulled down with either a $1k\Omega$ or a $100K\Omega$ resistor, or is in a high impedance state, as described in *Table 1*.

The bias generator, output amplifier, the resistor string and other linear circuitry are all shut down in any of the power-down modes. However, the contents of the DAC register are unaffected when in power-down. Minimum power consumption is achieved in the power-down mode with SCLK disabled and $\overline{\text{SYNC}}$ and D_{IN} idled low. The time to exit power-down (Wake-Up Time) is typically t_{WU} µsec as stated in the A.C. and Timing Characteristics Table.

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2.0 Applications Information

The simplicity of the DAC101S101 implies ease of use. However, it is important to recognize that any data converter that utilizes its supply voltage as its reference voltage will have essentially zero PSRR (Power Supply Rejection Ratio). Therefore, it is necessary to provide a noise-free supply voltage to the device.

2.1 DSP/MICROPROCESSOR INTERFACING

Interfacing the DAC101S101 to microprocessors and DSPs is quite simple. The following guidelines are offered to hasten the design process.

2.1.1 ADSP-2101/ADSP2103 Interfacing

Figure 5 shows a serial interface between the DAC101S101 and the ADSP-2101/ADSP2103. The DSP should be set to operate in the SPORT Transmit Alternate Framing Mode. It is programmed through the SPORT control register and should be configured for Internal Clock Operation, Active Low Framing and 16-bit Word Length. Transmission is started by writing a word to the Tx register after the SPORT mode has been enabled.

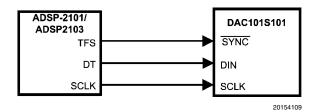


FIGURE 5. ADSP-2101/2103 Interface

2.1.2 80C51/80L51 Interface

A serial interface between the DAC101S101 and the 80C51/80L51 microcontroller is shown in *Figure 6*. The SYNC signal comes from a bit-programmable pin on the microcontroller. The example shown here uses port line P3.3. This line is taken low when data is to transmitted to the DAC101S101. Since the 80C51/80L51 transmits 8-bit bytes, only eight falling clock edges occur in the transmit cycle. To load data into the DAC, the P3.3 line must be left low after the first eight bits are transmitted. A second write cycle is initiated to transmit the second byte of data, after which port line P3.3 is brought high. The 80C51/80L51 transmit routine must recognize that the 80C51/80L51 transmits data with the LSB first while the DAC101S101 requires data with the MSB first.

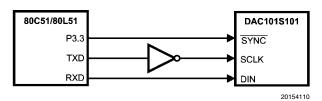


FIGURE 6. 80C51/80L51 Interface

2.1.3 68HC11 Interface

A serial interface between the DAC101S101 and the 68HC11 microcontroller is shown in $Figure\ 7$. The \overline{SYNC} line of the DAC101S101 is driven from a port line (PC7 in the figure), similar to the 80C51/80L51.

The 68HC11 should be configured with its CPOL bit as a zero and its CPHA bit as a one. This configuration causes data on

the MOSI output to be valid on the falling edge of SCLK. PC7 is taken low to transmit data to the DAC. The 68HC11 transmits data in 8-bit bytes with eight falling clock edges. Data is transmitted with the MSB first. PC7 must remain low after the first eight bits are transferred. A second write cycle is initiated to transmit the second byte of data to the DAC, after which PC7 should be raised to end the write sequence.

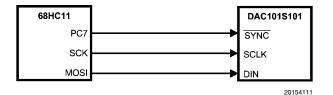


FIGURE 7. 68HC11 Interface

2.1.4 Microwire Interface

Figure 8 shows an interface between a Microwire compatible device and the DAC101S101. Data is clocked out on the rising edges of the SCLK signal.

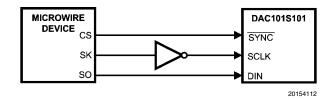


FIGURE 8. Microwire Interface

2.2 USING REFERENCES AS POWER SUPPLIES

Recall the need for a quiet supply source for devices that use their power supply voltage as a reference voltage.

Since the DAC101S101 consumes very little power, a reference source may be used as the supply voltage. The advantages of using a reference source over a voltage regulator are accuracy and stability. Some low noise regulators can also be used for the power supply of the DAC101S101. Listed below are a few power supply options for the DAC101S101.

2.2.1 LM4130

The LM4130 reference, with its 0.05% accuracy over temperature, is a good choice as a power source for the DAC101S101. Its primary disadvantage is the lack of a 3V and 5V versions. However, the 4.096V version is useful if a 0 to 4.095V output range is desirable or acceptable. Bypassing the VIN pin with a 0.1 μ F capacitor and the VOUT pin with a 2.2 μ F capacitor will improve stability and reduce output noise. The LM4130 comes in a space-saving 5-pin SOT23.

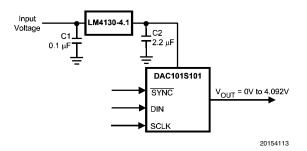


FIGURE 9. The LM4130 as a power supply

2.2.2 LM4050

Available with accuracy of 0.44%, the LM4050 shunt reference is also a good choice as a power regulator for the DAC101S101. It does not come in a 3 Volt version, but 4.096V and 5V versions are available. It comes in a space-saving 3-pin SOT23.

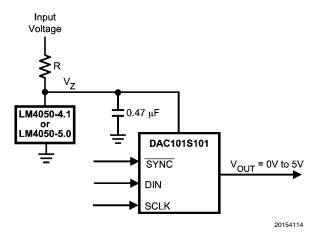


FIGURE 10. The LM4050 as a power supply

The minimum resistor value in the circuit of *Figure 10* should be chosen such that the maximum current through the LM4050 does not exceed its 15 mA rating. The conditions for maximum current include the input voltage at its maximum, the LM4050 voltage at its minimum, the resistor value at its minimum due to tolerance, and the DAC101S101 draws zero current. The maximum resistor value must allow the LM4050 to draw more than its minimum current for regulation plus the maximum DAC101S101 current in full operation. The conditions for minimum current include the input voltage at its minimum, the LM4050 voltage at its maximum, the resistor value at its maximum due to tolerance, and the DAC101S101 draws its maximum current. These conditions can be summarized as

$$R(min) = (\ V_{IN}(max) - V_{Z}(min)\ /\ (I_{A}(min) + I_{Z}(max))$$
 and

$$R(max) = (V_{IN}(min) - V_{Z}(max) / (I_{A}(max) + I_{Z}(min))$$

where $\rm V_Z(min)$ and $\rm V_Z(max)$ are the nominal LM4050 output voltages \pm the LM4050 output tolerance over temperature, $\rm I_Z$ (max) is the maximum allowable current through the LM4050, $\rm I_Z(min)$ is the minimum current required by the LM4050 for proper regulation, $\rm I_A(max)$ is the maximum DAC101S101 supply current, and $\rm I_A(min)$ is the minimum DAC101S101 supply current.

2.2.3 LP3985

The LP3985 is a low noise, ultra low dropout voltage regulator with a 3% accuracy over temperature. It is a good choice for applications that do not require a precision reference for the DAC101S101. It comes in 3.0V, 3.3V and 5V versions, among

others, and sports a low 30 μV noise specification at low frequencies. Since low frequency noise is relatively difficult to filter, this specification could be important for some applications. The LP3985 comes in a space-saving 5-pin SOT23 and 5-bump micro SMD packages.

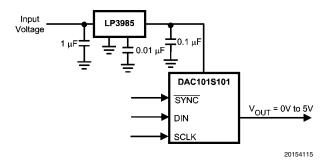


FIGURE 11. Using the LP3985 regulator

An input capacitance of 1.0µF without any ESR requirement is required at the LP3985 input, while a 1.0µF ceramic capacitor with an ESR requirement of $5m\Omega$ to $500m\Omega$ is required at the output. Careful interpretation and understanding of the capacitor specification is required to ensure correct device operation.

2.2.4 LP2980

The LP2980 is an ultra low dropout regulator with a 0.5% or 1.0% accuracy over temperature, depending upon grade. It is available in 3.0V, 3.3V and 5V versions, among others.

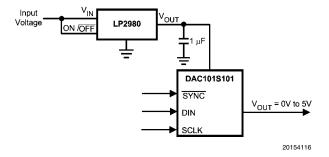


FIGURE 12. Using the LP2980 regulator

Like any low dropout regulator, the LP2980 requires an output capacitor for loop stability. This output capacitor must be at least $1.0\mu F$ over temperature, but values of $2.2\mu F$ or more will provide even better performance. The ESR of this capacitor should be within the range specified in the LP2980 data sheet. Surface-mount solid tantalum capacitors offer a good combination of small size and ESR. Ceramic capacitors are attractive due to their small size but generally have ESR values that are too low for use with the LP2980. Aluminum electrolytic capacitors are typically not a good choice due to their large size and have ESR values that may be too high at low temperatures.

2.3 BIPOLAR OPERATION

The DAC101S101 is designed for single supply operation and thus has a unipolar output. However, a bipolar output may be obtained with the circuit in *Figure 13*. This circuit will provide an output voltage range of ± 5 Volts. A rail-to-rail amplifier should be used if the amplifier supplies are limited to ± 5 V.

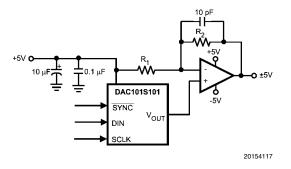


FIGURE 13. Bipolar Operation

The output voltage of this circuit for any code is found to be $V_O = (V_A \times (D / 1024) \times ((R1 + R2) / R1) - V_A \times R2 / R1)$ where D is the input code in decimal form. With $V_A = 5V$ and R1 = R2,

$$V_O = (10 \times D / 1024) - 5V$$

A list of rail-to-rail amplifiers suitable for this application are indicated in *Table 2*.

TABLE 2. Some Rail-to-Rail Amplifiers

AMP	PKGS	Typ V _{os}	Typ I _{SUPPLY}	
LMC7111	DIP-8 0.9 mV		25 μA	
LIVIO7111	SOT23-5	0.9111	25 μΑ	
LM7301	SO-8	0.03 mV	620 µA	
LIVI7 30 T	SOT23-5	0.03 1117	020 μΑ	
LM8261	SOT23-5	0.7 mV	1 mA	

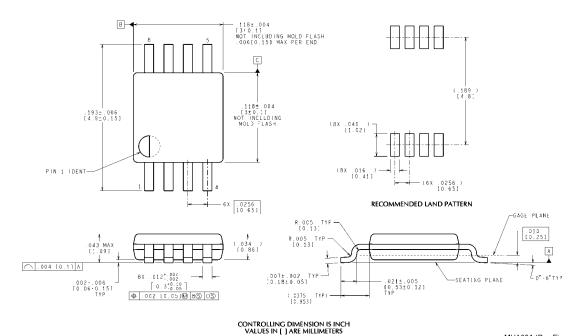
2.4 LAYOUT, GROUNDING, AND BYPASSING

For best accuracy and minimum noise, the printed circuit board containing the DAC101S101 should have separate analog and digital areas. The areas are defined by the locations of the analog and digital power planes. Both of these planes should be located in the same board laver. There should be a single ground plane. A single ground plane is preferred if digital return current does not flow through the analog ground area. Frequently a single ground plane design will utilize a "fencing" technique to prevent the mixing of analog and digital ground current. Separate ground planes should only be utilized when the fencing technique is inadequate. The separate ground planes must be connected in one place. preferably near the DAC101S101. Special care is required to guarantee that digital signals with fast edge rates do not pass over split ground planes. They must always have a continuous return path below their traces.

The DAC101S101 power supply should be bypassed with a $10\mu\text{F}$ and a $0.1\mu\text{F}$ capacitor as close as possible to the device with the $0.1\mu\text{F}$ right at the device supply pin. The $10\mu\text{F}$ capacitor should be a tantalum type and the $0.1\mu\text{F}$ capacitor should be a low ESL, low ESR type. The power supply for the DAC101S101 should only be used for analog circuits.

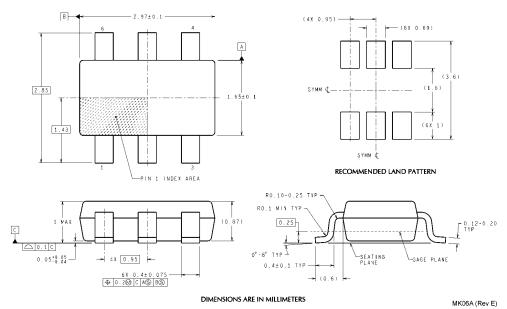
Avoid crossover of analog and digital signals and keep the clock and data lines on the component side of the board. The clock and data lines should have controlled impedances.

Physical Dimensions inches (millimeters) unless otherwise noted



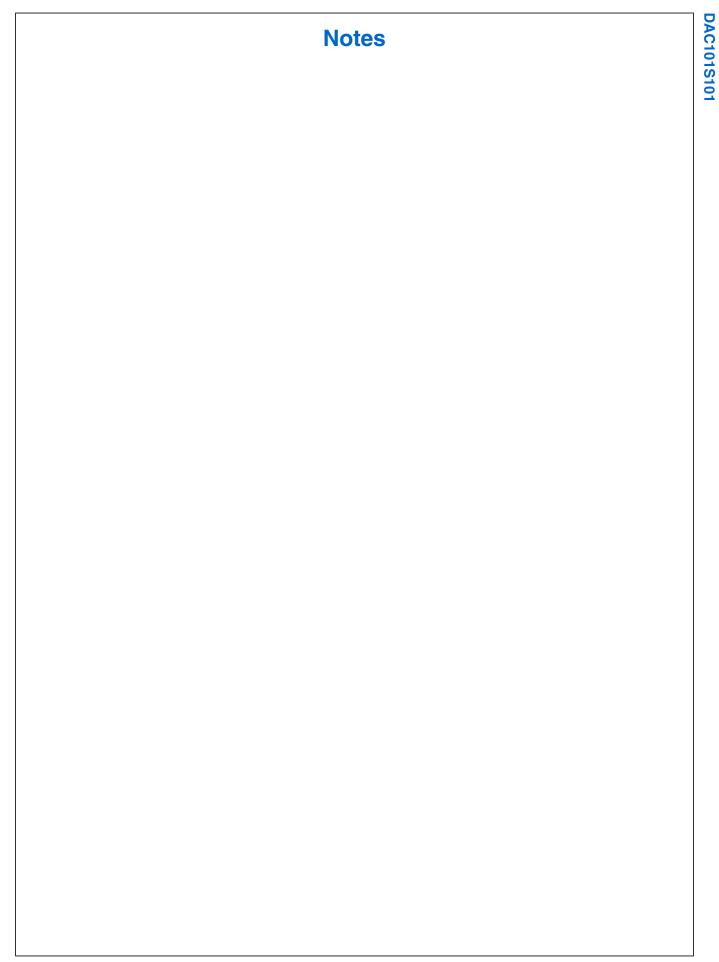
8-Lead MSOP Order Number DAC101S101CIMM NS Package Number MUA08A

MUA08A (Rev F)



6-Lead TSOT
Order Numbers DAC101S101CIMK and DAC101S101QCMK
NS Package Number MK06A

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Notes

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