

### **General Description**

The MAX186/MAX188 are 12-bit data-acquisition systems that combine an 8-channel multiplexer, high-bandwidth track/hold, and serial interface together with high conversion speed and ultra-low power consumption. The devices operate with a single +5V supply or dual  $\pm5V$  supplies. The analog inputs are software configurable for unipolar/bipolar and single-ended/differential operation.

The 4-wire serial interface directly connects to SPI<sup>™</sup>, QSPI<sup>™</sup> and Microwire<sup>™</sup> devices without external logic. A serial strobe output allows direct connection to TMS320 family digital signal processors. The MAX186/MAX188 use either the internal clock or an external serial-interface clock to perform successive-approximation A/D conversions. The serial interface can operate beyond 4MHz when the internal clock is used.

The MAX186 has an internal 4.096V reference while the MAX188 requires an external reference. Both parts have a reference-buffer amplifier that simplifies gain trim .

The MAX186/MAX188 provide a hard-wired SHDN pin and two software-selectable power-down modes. Accessing the serial interface automatically powers up the devices, and the quick turn-on time allows the MAX186/MAX188 to be shut down between every conversion. Using this technique of powering down between conversions, supply current can be cut to under 10 $\mu$ A at reduced sampling rates.

The MAX186/MAX188 are available in 20-pin DIP and SO packages, and in a shrink small-outline package (SSOP), that occupies 30% less area than an 8-pin DIP. For applications that call for a parallel interface, see the MAX180/MAX181 data sheet. For anti-aliasing filters, consult the MAX274/MAX275 data sheet.



Portable Data Logging Data-Acquisition High-Accuracy Process Control Automatic Testing Robotics Battery-Powered Instruments Medical Instruments

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# Low-Power, 8-Channel, Serial 12-Bit ADCs

### \_Features

- 8-Channel Single-Ended or 4-Channel Differential Inputs
- Single +5V or ±5V Operation
- Low Power: 1.5mA (operating mode) 2μA (power-down mode)
- Internal Track/Hold, 133kHz Sampling Rate
- Internal 4.096V Reference (MAX186)
- SPI-, QSPI-, Microwire-, TMS320-Compatible 4-Wire Serial Interface
- ♦ Software-Configurable Unipolar or Bipolar Inputs
- ♦ 20-Pin DIP, SO, SSOP Packages
- Evaluation Kit Available

### \_Ordering Information

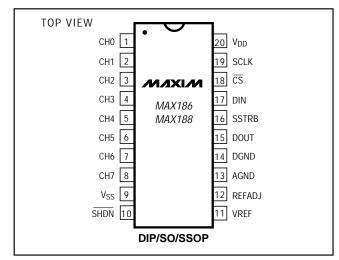
PART <sup>†</sup>	TEMP. RANGE	PIN-PACKAGE
MAX186_CPP	0°C to +70°C	20 Plastic DIP
MAX186_CWP	0°C to +70°C	20 SO
MAX186_CAP	0°C to +70°C	20 SSOP
MAX186DC/D	0°C to +70°C	Dice*
MAX186_EPP	-40°C to +85°C	20 Plastic DIP
MAX186_EWP	-40°C to +85°C	20 SO
MAX186_EAP	-40°C to +85°C	20 SSOP
MAX186_MJP	-55°C to +125°C	20 CERDIP**

### Ordering Information continued on last page.

 NOTE: Parts are offered in grades A, B, C and D (grades defined in Electrical Characteristics). When ordering, please specify grade. Contact factory for availability of A-grade in SSOP package.
 \* Dice are specified at +25°C, DC parameters only.

\* Contact factory for availability and processing to MIL-STD-883.

### Pin Configuration



Maxim Integrated Products 1

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### **ABSOLUTE MAXIMUM RATINGS**

Cont	-0.3V to +6V	V <sub>DD</sub> to AGND
Pla	+0.3V to -6V	V <sub>SS</sub> to AGND
SC	0.3V to +12V	V <sub>DD</sub> to V <sub>SS</sub>
SS	-0.3V to +0.3V	AGND to DGND
CE	$\dots (V_{SS} - 0.3V)$ to $(V_{DD} + 0.3V)$	CH0-CH7 to AGND, DGND
Ope	±20mA	CH0–CH7 Total Input Current
MA	0.3V to (V <sub>DD</sub> + 0.3V)	VREF to AGND
MA	0.3V to (V <sub>DD</sub> + 0.3V)	REFADJ to AGND
MA	0.3V to (V <sub>DD</sub> + 0.3V)	Digital Inputs to DGND
Stora	0.3V to (V <sub>DD</sub> + 0.3V)	Digital Outputs to DGND
Lead	25mA	Digital Output Sink Current

Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
Plastic DIP (derate 11.11mW/°C above +70°C)
SO (derate 10.00mW/°C above +70°C)800mW
SSOP (derate 8.00mW/°C above +70°C)640mW
CERDIP (derate 11.11mW/°C above +70°C)889mW
Operating Temperature Ranges:
MAX186_C/MAX188_C0°C to +70°C
MAX186_E/MAX188_E40°C to +85°C
MAX186_M/MAX188_M55°C to +125°C
Storage Temperature Range60°C to +150°C
Lead Temperature (soldering, 10sec)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **ELECTRICAL CHARACTERISTICS**

 $(V_{DD} = 5V \pm 5\%)$ ; VSS = 0V or -5V; f<sub>CLK</sub> = 2.0MHz, external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps): MAX186-4.7\muF capacitor at VREF pin; MAX188-external reference, VREF = 4.096V applied to VREF pin; T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.)

PARAMETER	SYMBOL	CON	DITIONS	MIN	TYP	MAX	UNITS
DC ACCURACY (Note 1)				•			
Resolution				12			Bits
		MAX186A/MAX188A				±0.5	
		MAX186B/MAX188B				±0.5	
Relative Accuracy (Note 2)		MAX186C				±1.0	LSB
		MAX188C				±0.75	
		MAX186D/MAX188D				±1.0	
Differential Nonlinearity	DNL	No missing codes over temperature				±1	LSB
		MAX186A/MAX188A				±2.0	
Offset Error		MAX186B/MAX188B MAX186C/MAX188C MAX186D/MAX188D				±3.0	LSB
Unset EITU						±3.0	
						±3.0	
		MAX186 (all grades)				±3.0	
		External reference 4.096V (MAX188)	MAX188A			±1.5	LSB
Gain Error (Note 3)			MAX188B			±2.0	
			MAX188C			±2.0	
			MAX188D			$\pm 3.0$	
Gain Temperature Coefficient		External reference, 4.	.096V		±0.8		ppm/°C
Channel-to-Channel Offset Matching					±0.1		LSB
<b>DYNAMIC SPECIFICATIONS</b> (1	0kHz sine w	ave input, 4.096V <sub>P-P</sub> , 1	33ksps, 2.0MHz external	clock, bip	olar input	mode)	
Signal-to-Noise + Distortion Ratio	SINAD			70			dB
Total Harmonic Distortion (up to the 5th harmonic)	THD					-80	dB
Spurious-Free Dynamic Range	SFDR			80			dB
Channel-to-Channel Crosstalk		65kHz, V <sub>IN</sub> = 4.096V <sub>F</sub>	P-P (Note 4)		-85		dB



### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = 5V \pm 5\%; V_{SS} = 0V \text{ or } -5V; f_{CLK} = 2.0MHz$ , external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186—4.7µF capacitor at VREF pin; MAX188—external reference, VREF = 4.096V applied to VREF pin; TA = T\_{MIN} to T\_MAX, unless otherwise noted.)

PARAMETER	SYMBOL	COND	ITIONS	MIN	TYP	MAX	UNITS
Small-Signal Bandwidth	1	-3dB rolloff			4.5		MHz
Full-Power Bandwidth					800		kHz
CONVERSION RATE	1						
Conversion Time (Note E)	taanu	Internal clock		5.5		10	
Conversion Time (Note 5)	t conv	External clock, 2MHz	, 12 clocks/conversion	6			μs
Track/Hold Acquisition Time	taz					1.5	μs
Aperture Delay					10		ns
Aperture Jitter					<50		ps
Internal Clock Frequency					1.7		MHz
		External compensation	on, 4.7µF	0.1		2.0	
External Clock Frequency Range		Internal compensation	n (Note 6)	0.1		0.4	MHz
		Used for data transfe	r only		10		
ANALOG INPUT							
Input Voltage Range, Single-Ended and Differential		Unipolar, V <sub>SS</sub> = 0V				0 to VREF	V
(Note 9)		Bipolar, V <sub>SS</sub> = -5V				±VREF/2	v
Multiplexer Leakage Current		On/off leakage current, $V_{IN} = \pm 5V$			±0.01	±1	μΑ
Input Capacitance		(Note 6)			16		рF
INTERNAL REFERENCE (MAX18	86 only, refe						
VREF Output Voltage		$T_A = +25^{\circ}C$		4.076	4.096	4.116	V
VREF Short-Circuit Current						30	mA
		MAX186A, MAX186B,	MAX186_C		±30	±50	
VREF Tempco		MAX186C	MAX186_E		±30	±60	ppm/°C
Viter rempeo			MAX186_M		±30	±80	
		MAX186D			±30		
		0mA to 0.5mA output	load		2.5		mV
Load Regulation (Note 7)							
-		Internal compensation	n	0			цЕ
Load Regulation (Note 7) Capacitive Bypass at VREF		Internal compensation External compensation	n on	4.7			μF
Capacitive Bypass at VREF		Internal compensation External compensation Internal compensation	n on n	-			
Capacitive Bypass at VREF Capacitive Bypass at REFADJ		Internal compensation External compensation	n on n	4.7			μF
Capacitive Bypass at VREF Capacitive Bypass at REFADJ REFADJ Adjustment Range		Internal compensation External compensation Internal compensation External compensation	n pn n pn	4.7 0.01	±1.5		
Capacitive Bypass at VREF Capacitive Bypass at REFADJ	REF (Buffer c	Internal compensation External compensation Internal compensation External compensation	n pn n pn	4.7 0.01			μF
Capacitive Bypass at VREF Capacitive Bypass at REFADJ REFADJ Adjustment Range EXTERNAL REFERENCE AT VR	REF (Buffer o	Internal compensation External compensation Internal compensation External compensation	n pn n pn	4.7 0.01		V <sub>DD +</sub> 50mV	μF
Capacitive Bypass at VREF Capacitive Bypass at REFADJ REFADJ Adjustment Range EXTERNAL REFERENCE AT VR	REF (Buffer of	Internal compensation External compensation Internal compensation External compensation	n pn n pn	4.7 0.01 0.01		VDD + 50mV 350	μF %
Capacitive Bypass at VREF Capacitive Bypass at REFADJ REFADJ Adjustment Range <b>EXTERNAL REFERENCE AT VR</b> Input Voltage Range	REF (Buffer o	Internal compensation External compensation Internal compensation External compensation	n pn n pn	4.7 0.01 0.01	±1.5	50mV	μF % V
Capacitive Bypass at REFADJ REFADJ Adjustment Range EXTERNAL REFERENCE AT VR Input Voltage Range Input Current	REF (Buffer of	Internal compensation External compensation Internal compensation External compensation	n pn n pn	4.7 0.01 0.01 2.50	±1.5	50mV	μF % V μA

**MAX186/MAX188** 



### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = 5V \pm 5\%; V_{SS} = 0V \text{ or } -5V; f_{CLK} = 2.0MHz$ , external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186—4.7µF capacitor at VREF pin; MAX188—external reference, VREF = 4.096V applied to VREF pin; TA = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
EXTERNAL REFERENCE AT RE	FADJ						
		Internal compensation mode	0				
Capacitive Bypass at VREF		External compensation mode	4.7			μF	
Defense of Duffer Cali		MAX186		1.678			
Reference-Buffer Gain		MAX188		1.638		V/V	
		MAX186			±50		
REFADJ Input Current		MAX188			±5	μA	
DIGITAL INPUTS (DIN, SCLK, C	S, SHDN)		I		<b>I</b>		
DIN, SCLK, CS Input High Voltage	VINH		2.4			V	
DIN, SCLK, CS Input Low Voltage	V <sub>INL</sub>				0.8	V	
DIN, SCLK, CS Input Hysteresis	V <sub>HYST</sub>			0.15		V	
DIN, SCLK, CS Input Leakage	l <sub>IN</sub>	$V_{IN} = OV \text{ or } V_{DD}$			±1	μA	
DIN, SCLK, CS Input Capacitance	CIN	(Note 6)			15	рF	
SHDN Input High Voltage	V <sub>INH</sub>		V <sub>DD</sub> - 0.5			V	
SHDN Input Low Voltage	VINL				0.5	V	
SHDN Input Current, High	I <sub>INH</sub>	SHDN = V <sub>DD</sub>			4.0	μA	
SHDN Input Current, Low	linl	SHDN = 0V	-4.0			μΑ	
SHDN Input Mid Voltage	Vim		1.5		V <sub>DD</sub> -1.5	V	
SHDN Voltage, Floating	VFLT	SHDN = open		2.75		V	
SHDN Max Allowed Leakage, Mid Input		SHDN = open	-100		100	nA	
DIGITAL OUTPUTS (DOUT, SST	RB)		1				
Output Voltage Low	Mai	I <sub>SINK</sub> = 5mA			0.4	V	
Output voltage Low	Vol	I <sub>SINK</sub> = 16mA		0.3		V	
Output Voltage High	Voh	ISOURCE = 1mA	4			V	
Three-State Leakage Current	١L	$\overline{\text{CS}} = 5\text{V}$			±10	μA	
Three-State Output Capacitance	Cout	$\overline{\text{CS}}$ = 5V (Note 6)			15	рF	
POWER REQUIREMENTS							
Positive Supply Voltage	VDD			$5\pm5\%$		V	
Negative Supply Voltage	V <sub>SS</sub>			0 or -5 ±5%		V	
		Operating mode		1.5	2.5	mA	
Positive Supply Current	IDD	Fast power-down		30	70		
		Full power-down		2	10	μA	
Nagativa Supply Current	laa	Operating mode and fast power-down			50		
Negative Supply Current	ISS	Full power-down			10	μA	

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### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{DD} = 5V \pm 5\%; V_{SS} = 0V \text{ or } -5V; f_{CLK} = 2.0MHz$ , external clock (50% duty cycle); 15 clocks/conversion cycle (133ksps); MAX186—4.7µF capacitor at VREF pin; MAX188—external reference, VREF = 4.096V applied to VREF pin; TA = T\_{MIN} to T\_MAX, unless otherwise noted.)

PARAMETER	SYMBOL	CONDITIONS		ТҮР	MAX	UNITS
Positive Supply Rejection (Note 8)	PSR	$V_{DD} = 5V \pm 5\%$ ; external reference, 4.096V; full-scale input		±0.06	±0.5	mV
Negative Supply Rejection (Note 8)	PSR	V <sub>SS</sub> = -5V ±5%; external reference, 4.096V; full-scale input		±0.01	±0.5	mV

**Note 1:** Tested at  $V_{DD} = 5.0V$ ;  $V_{SS} = 0V$ ; unipolar input mode.

**Note 2:** Relative accuracy is the deviation of the analog value at any code from its theoretical value after the full-scale range has been calibrated.

Note 3: MAX186 – internal reference, offset nulled; MAX188 – external reference (VREF = +4.096V), offset nulled.

**Note 4:** Ground on-channel; sine wave applied to all off channels.

Note 5: Conversion time defined as the number of clock cycles times the clock period; clock has 50% duty cycle.

Note 6: Guaranteed by design. Not subject to production testing.

Note 7: External load should not change during conversion for specified accuracy.

Note 8: Measured at  $V_{SUPPLY}$  +5% and  $V_{SUPPLY}$  -5% only.

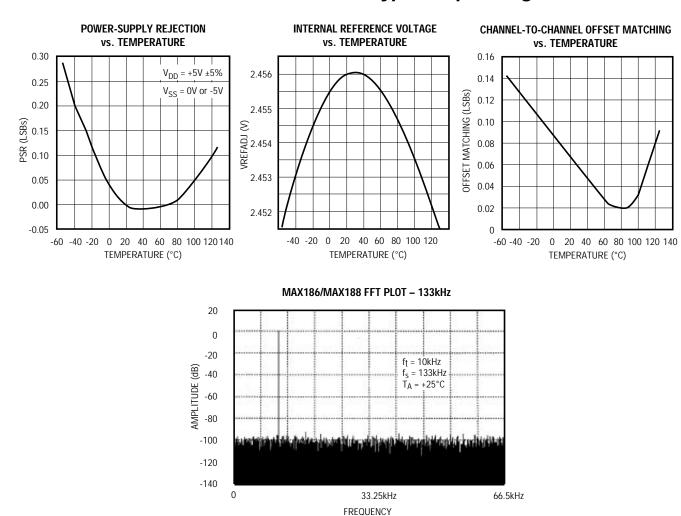
Note 9: The common-mode range for the analog inputs is from  $V_{SS}$  to  $V_{DD}$ .

### TIMING CHARACTERISTICS

(V<sub>DD</sub> = 5V  $\pm$ 5%; V<sub>SS</sub> =0V or -5V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted.)

PARAMETER	SYMBOL	COND	DITIONS	MIN	ТҮР	МАХ	UNITS
Acquisition Time	t <sub>AZ</sub>			1.5			μs
DIN to SCLK Setup	t <sub>DS</sub>			100			ns
DIN to SCLK Hold	t <sub>DH</sub>					0	ns
SCLK Fall to Output Data Valid	t <sub>DO</sub>	$C_{I,OAD} = 100 pF$	MAX18C/E	20		150	ns
	<sup>1</sup> DO	CLOAD - TOOPT	MAX18M	20		200	ns
CS Fall to Output Enable	t <sub>DV</sub>	C <sub>LOAD</sub> = 100pF				100	ns
CS Rise to Output Disable	t <sub>TR</sub>	$C_{LOAD} = 100 pF$				100	ns
CS to SCLK Rise Setup	t <sub>CSS</sub>			100			ns
CS to SCLK Rise Hold	t <sub>CSH</sub>			0			ns
SCLK Pulse Width High	t <sub>CH</sub>			200			ns
SCLK Pulse Width Low	t <sub>CL</sub>			200			ns
SCLK Fall to SSTRB	t <sub>SSTRB</sub>	$C_{LOAD} = 100 pF$				200	ns
CS Fall to SSTRB Output Enable (Note 6)	t <sub>SDV</sub>	External clock mode only, C <sub>LOAD</sub> = 100pF				200	ns
CS Rise to SSTRB Output Disable (Note 6)	t <sub>STR</sub>	External clock mode only, C <sub>LOAD</sub> = 100pF				200	ns
SSTRB Rise to SCLK Rise (Note 6)	t <sub>SCK</sub>	Internal clock mode	only	0			ns

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### **Typical Operating Characteristics**

### \_Pin Description

PIN	NAME	FUNCTION
1-8	CH0-CH7	Sampling Analog Inputs
9	V <sub>SS</sub>	Negative Supply Voltage. Tie to -5V ±5% or AGND
10	SHDN	Three-Level Shutdown Input. Pulling SHDN low shuts the MAX186/MAX188 down to 10µA (max) supply current, otherwise the MAX186/MAX188 are fully operational. Pulling SHDN high puts the reference-buffer amplifier in internal compensation mode. Letting SHDN float puts the reference-buffer amplifier in external compensation mode.
11	VREF	Reference Voltage for analog-to-digital conversion. Also, Output of the Reference Buffer Amplifier (4.096V in the MAX186, 1.638 x REFADJ in the MAX188). Add a 4.7µF capacitor to ground when using external compensation mode. Also functions as an input when used with a precision external reference.

## Pin Description (continued)

PIN	NAME	FUNCTION
12	REFADJ	Input to the Reference-Buffer Amplifier. To disable the reference-buffer amplifier, tie REFADJ to $V_{DD}$ .
13	AGND	Analog Ground. Also IN- Input for single-ended conversions.
14	DGND	Digital Ground
15	DOUT	Serial Data Output. Data is clocked out at the falling edge of SCLK. High impedance when $\overline{CS}$ is high.
16	SSTRB	Serial Strobe Output. In internal clock mode, SSTRB goes low when the MAX186/MAX188 begin the A/D conversion and goes high when the conversion is done. In external clock mode, SSTRB pulses high for one clock period before the MSB decision. High impedance when CS is high (external mode).
17	DIN	Serial Data Input. Data is clocked in at the rising edge of SCLK.
18	CS	Active-Low Chip Select. Data will not be clocked into DIN unless $\overline{CS}$ is low. When $\overline{CS}$ is high, DOUT is high impedance.
19	SCLK	Serial Clock Input. Clocks data in and out of serial interface. In external clock mode, SCLK also sets the conversion speed. (Duty cycle must be 40% to 60% in external clock mode.)
20	V <sub>DD</sub>	Positive Supply Voltage, +5V ±5%

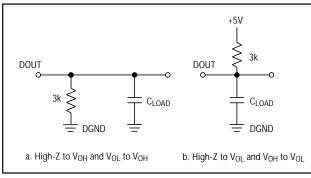


Figure 1. Load Circuits for Enable Time

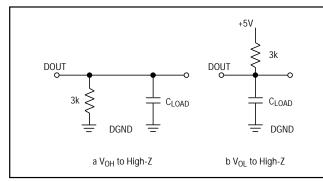


Figure 2. Load Circuits for Disabled Time

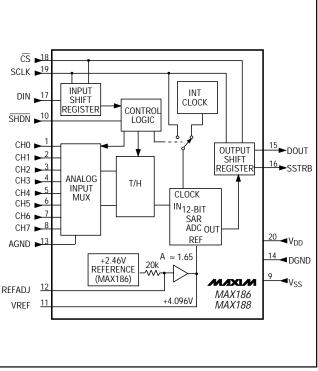


Figure 3. Block Diagram

MAX186/MAX188

### \_Detailed Description

The MAX186/MAX188 use a successive-approximation conversion technique and input track/hold (T/H) circuitry to convert an analog signal to a 12-bit digital output. A flexible serial interface provides easy interface to microprocessors. No external hold capacitors are required. Figure 3 shows the block diagram for the MAX186/MAX188.

### **Pseudo-Differential Input**

The sampling architecture of the ADC's analog comparator is illustrated in the Equivalent Input Circuit (Figure 4). In single-ended mode, IN+ is internally switched to CH0-CH7 and IN- is switched to AGND. In differential mode, IN+ and IN- are selected from pairs of CH0/CH1, CH2/CH3, CH4/CH5 and CH6/CH7. Configure the channels with Table 3 and Table 4.

In differential mode, IN- and IN+ are internally switched to either one of the analog inputs. This configuration is pseudo-differential to the effect that only the signal at IN+ is sampled. The return side (IN-) must remain stable within  $\pm 0.5$ LSB ( $\pm 0.1$ LSB for best results) with respect to AGND during a conversion. Accomplish this by connecting a  $0.1\mu$ F capacitor from AIN- (the selected analog input, respectively) to AGND.

During the acquisition interval, the channel selected as the positive input (IN+) charges capacitor  $C_{HOLD}$ . The acquisition interval spans three SCLK cycles and ends on the falling SCLK edge after the last bit of the input control word has been entered. At the end of the acquisition interval, the T/H switch opens, retaining charge on  $C_{HOLD}$  as a sample of the signal at IN+.

The conversion interval begins with the input multiplexer switching  $C_{HOLD}$  from the positive input (IN+) to the negative input (IN-). In single-ended mode, IN- is simply AGND. This unbalances node ZERO at the input of the comparator. The capacitive DAC adjusts during the remainder of the conversion cycle to restore node ZERO to 0V within the limits of 12-bit resolution. This action is equivalent to transferring a charge of 16pF x [(V<sub>IN</sub>+) - (V<sub>IN</sub>-)] from C<sub>HOLD</sub> to the binary-weighted capacitive DAC, which in turn forms a digital representation of the analog input signal.

The T/H enters its tracking mode on the falling clock edge after the fifth bit of the 8-bit control word has been shifted in. The T/H enters its hold mode on the falling clock edge after the eighth bit of the control word has been shifted in. If the converter is set up for

Track/Hold



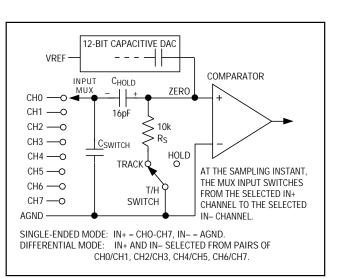


Figure 4. Equivalent Input Circuit

single-ended inputs, IN- is connected to AGND, and the converter samples the "+" input. If the converter is set up for differential inputs, IN- connects to the "-" input, and the difference of |IN+ - IN-| is sampled. At the end of the conversion, the positive input connects back to IN+, and C<sub>HOLD</sub> charges to the input signal.

The time required for the T/H to acquire an input signal is a function of how quickly its input capacitance is charged. If the input signal's source impedance is high, the acquisition time lengthens and more time must be allowed between conversions. Acquisition time is calculated by:

$$t_{AZ} = 9 x (R_S + R_{IN}) x 16 pF$$
,

where  $R_{IN} = 5k\Omega$ ,  $R_S =$  the source impedance of the input signal, and  $t_{AZ}$  is never less than 1.5µs. Note that source impedances below  $5k\Omega$  do not significantly affect the AC performance of the ADC. Higher source impedances can be used if an input capacitor is connected to the analog inputs, as shown in Figure 5. Note that the input capacitor forms an RC filter with the input source impedance, limiting the ADC's signal bandwidth.

### Input Bandwidth

The ADC's input tracking circuitry has a 4.5MHz small-signal bandwidth, so it is possible to digitize high-speed transient events and measure periodic signals with bandwidths exceeding the ADC's sampling rate by using undersampling techniques. To avoid high-frequency signals being aliased into the frequency band of interest, anti-alias filtering is recommended.



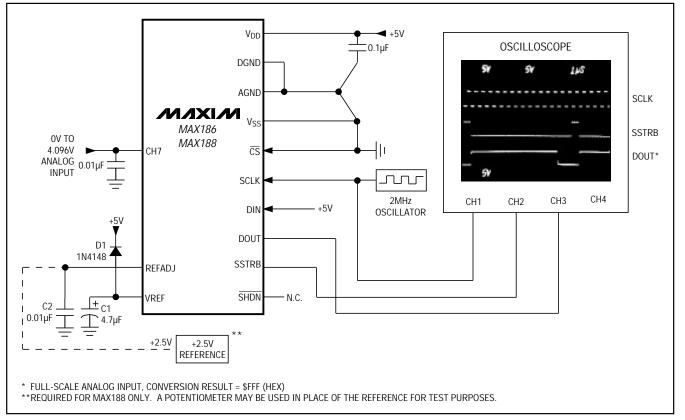


Figure 5. Quick-Look Circuit

### **Analog Input Range and Input Protection**

Internal protection diodes, which clamp the analog input to  $V_{DD}$  and  $V_{SS}$ , allow the channel input pins to swing from  $V_{SS}$  - 0.3V to  $V_{DD}$  + 0.3V without damage. However, for accurate conversions near full scale, the inputs must not exceed  $V_{DD}$  by more than 50mV, or be lower than  $V_{SS}$  by 50mV.

### If the analog input exceeds 50mV beyond the supplies, do not forward bias the protection diodes of off-channels over two milliamperes, as excessive current will degrade the conversion accuracy of the on-channel.

The full-scale input voltage depends on the voltage at VREF. See Tables 1a and 1b.

### **Quick Look**

To evaluate the analog performance of the MAX186/MAX188 quickly, use the circuit of Figure 5. The MAX186/MAX188 require a control byte to be written to DIN before each conversion. Tying DIN to +5V feeds in control bytes of \$FF (HEX), which trigger

Table 1a.	Unipolar Full Scale and Zero Scale
-----------	------------------------------------

Reference	Zero Scale	Full Scale
Internal Reference (MAX186 only)	0V	+4.096V
External Reference at REFADJ	0V	V <sub>REFADJ</sub> x A*
at VREF	0V	VREF

\* A = 1.678 for the MAX186, 1.638 for the MAX188

# Table 1b. Bipolar Full Scale, Zero Scale, andNegative Full Scale

Reference	Reference Negative Full Scale		Full Scale
Internal Reference (MAX186 only)	-4.096V/2	0V	+4.096V/2
External Reference at REFADJ	-1/2V <sub>REFADJ</sub> x A*	0V	+1/2V <sub>REFADJ</sub> x A*
at VREF	-1/2 VREF	0V	+1/2 VREF

\* A = 1.678 for the MAX186, 1.638 for the MAX188

single-ended unipolar conversions on CH7 in external clock mode without powering down between conversions. In external clock mode, the SSTRB output pulses high for one clock period before the most significant bit of the 12-bit conversion result comes out of DOUT. Varying the analog input to CH7 should alter the sequence of bits from DOUT. A total of 15 clock cycles is required per conversion. All transitions of the SSTRB and DOUT outputs occur on the falling edge of SCLK.

### How to Start a Conversion

A conversion is started on the MAX186/MAX188 by clocking a control byte into DIN. Each rising edge on SCLK, with  $\overline{CS}$  low, clocks a bit from DIN into the MAX186/MAX188's internal shift register. After  $\overline{CS}$  falls, the first arriving logic "1" bit defines the MSB of the control byte. Until this first "start" bit arrives, any number of logic "0" bits can be clocked into DIN with no effect. Table 2 shows the control-byte format.

The MAX186/MAX188 are fully compatible with Microwire and SPI devices. For SPI, select the correct clock polarity and sampling edge in the SPI control registers: set CPOL = 0 and CPHA = 0. Microwire and SPI both transmit a byte and receive a byte at the same time. Using the *Typical Operating Circuit*, the simplest software interface requires only three 8-bit transfers to perform a conversion (one 8-bit transfer to configure the ADC, and two more 8-bit transfers to clock out the 12-bit conversion result).

### Example: Simple Software Interface

Make sure the CPU's serial interface runs in master mode so the CPU generates the serial clock. Choose a clock frequency from 100kHz to 2MHz.

1) Set up the control byte for external clock mode, call it TB1. TB1 should be of the format: 1XXXXX11 Binary, where the Xs denote the particular channel and conversion-mode selected.

Bit 7 (MSB)	Bit 6	Bit 5	E	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0 (LSB)
START	SEL2	SEL1	ç	SELO	UNI/BIP	SGL/DIF	PD1	PD0
Bit	Name	Descri	ption					
7(MSB)	START	The firs	st logic " <b>1</b> "	bit after	$\overline{\text{CS}}$ goes low def	ines the beginnin	g of the contro	l byte.
6 5 4	SEL2 SEL1 SEL0		three bits s ables 3 and		nich of the eight c	hannels are used	for the conver	sion.
3	UNI/BIP	mode,	an analog	input sig	Selects unipolar o gnal from 0V to VR REF/2 to +VREF/2	EF can be conve		
2	SGL/DIF	<b>1</b> = single ended, <b>0</b> = differential. Selects single-ended or differential conversions. In single-ended mode, input signal voltages are referred to AGND. In differential mode, the voltage difference between two channels is measured. See Tables 3 and 4.						
1	PD1	Selects	s clock and	power-	down modes.			
0(LSB)	PD0	PD1	PD0	Mode				
		0	0		ower-down (I <sub>Q</sub> = 1	•		
		0	1		power-down (I <sub>Q</sub> =	30µA)		
		1	0		al clock mode			
		1	1	Exter	nal clock mode			

### Table 2. Control-Byte Format

SEL2	SEL1	SEL0	CH0	CH1	CH2	СНЗ	CH4	CH5	CH6	CH7	AGND
0	0	0	+								_
1	0	0		+							_
0	0	1			+						_
1	0	1				+					_
0	1	0					+				_
1	1	0						+			_
0	1	1							+		_
1	1	1								+	_

### Table 3. Channel Selection in Single-Ended Mode (SGL/DIFF = 1)

SEL2	SEL1	SEL0	CH0	CH1	CH2	CH3	CH4	CH5	CH6	CH7
0	0	0	+	_						
0	0	1			+	_				
0	1	0					+	_		
0	1	1							+	_
1	0	0	_	+						
1	0	1			-	+				
1	1	0					_	+		
1	1	1							_	+

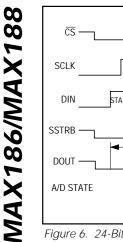
- 2) Use a general-purpose I/O line on the CPU to pull  $\overline{\text{CS}}$  on the MAX186/MAX188 low.
- 3) Transmit TB1 and simultaneously receive a byte and call it RB1. Ignore RB1.
- 4) Transmit a byte of all zeros (\$00 HEX) and simultaneously receive byte RB2.
- 5) Transmit a byte of all zeros (\$00 HEX) and simultaneously receive byte RB3.
- 6) Pull  $\overline{\text{CS}}$  on the MAX186/MAX188 high.

Figure 6 shows the timing for this sequence. Bytes RB2 and RB3 will contain the result of the conversion padded with one leading zero and three trailing zeros. The total conversion time is a function of the serial clock frequency and the amount of dead time between 8-bit transfers. Make sure that the total conversion time does not exceed 120µs, to avoid excessive T/H droop.

### Digital Output

In unipolar input mode, the output is straight binary (see Figure 15). For bipolar inputs, the output is twos-complement (see Figure 16). Data is clocked out at the falling edge of SCLK in MSB-first format.

# MAX186/MAX188



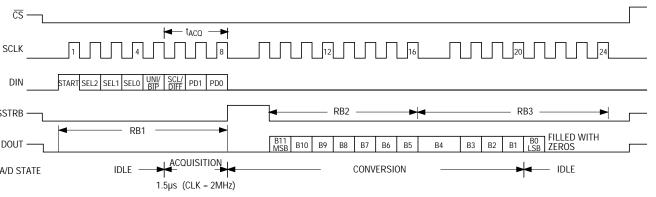


Figure 6. 24-Bit External Clock Mode Conversion Timing (SPI, QSPI and Microwire Compatible)

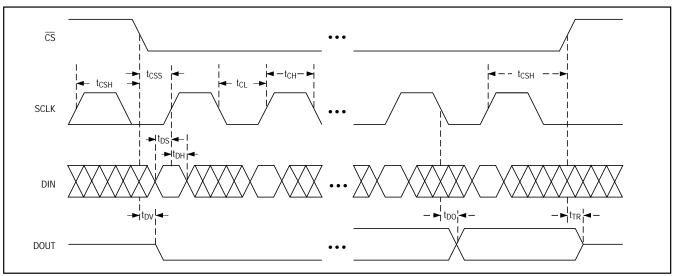


Figure 7. Detailed Serial-Interface Timing

### Internal and External Clock Modes

The MAX186/MAX188 may use either an external serial clock or the internal clock to perform the successive-approximation conversion. In both clock modes, the external clock shifts data in and out of the MAX186/MAX188. The T/H acquires the input signal as the last three bits of the control byte are clocked into DIN. Bits PD1 and PD0 of the control byte program the clock mode. Figures 7 through 10 show the timing characteristics common to both modes.

### External Clock

In external clock mode, the external clock not only shifts data in and out, it also drives the analog-to-digital con-

version steps. SSTRB pulses high for one clock period after the last bit of the control byte. Successive-approximation bit decisions are made and appear at DOUT on each of the next 12 SCLK falling edges (see Figure 6). SSTRB and DOUT go into a high-impedance state when CS goes high; after the next CS falling edge, SSTRB will output a logic low. Figure 8 shows the SSTRB timing in external clock mode.

The conversion must complete in some minimum time, or else droop on the sample-and-hold capacitors may degrade conversion results. Use internal clock mode if the clock period exceeds 10µs, or if serial-clock interruptions could cause the conversion interval to exceed 120µs.

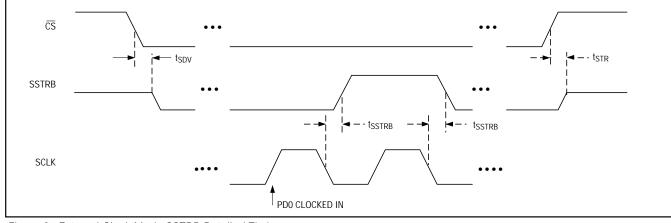


Figure 8. External Clock Mode SSTRB Detailed Timing

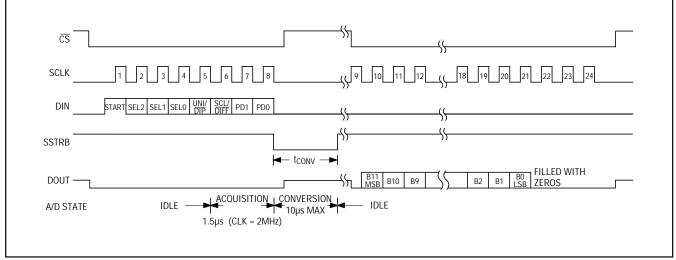


Figure 9. Internal Clock Mode Timing

### Internal Clock

In internal clock mode, the MAX186/MAX188 generate their own conversion clock internally. This frees the microprocessor from the burden of running the SAR conversion clock, and allows the conversion results to be read back at the processor's convenience, at any clock rate from zero to typically 10MHz. SSTRB goes low at the start of the conversion and then goes high when the conversion is complete. SSTRB will be low for a maximum of 10µs, during which time SCLK should remain low for best noise performance. An internal register stores data when the conversion is in progress. SCLK clocks the data out at this register at any time after the conversion is complete. After SSTRB goes high, the next falling clock edge

will produce the MSB of the conversion at DOUT, followed by the remaining bits in MSB-first format (see Figure 9).  $\overline{CS}$  does not need to be held low once a conversion is started. Pulling  $\overline{CS}$  high prevents data from being clocked into the MAX186/MAX188 and threestates DOUT, but it does not adversely effect an internal clock-mode conversion already in progress. When internal clock mode is selected, SSTRB does not go into a high-impedance state when  $\overline{CS}$  goes high.

Figure 10 shows the SSTRB timing in internal clock mode. In internal clock mode, data can be shifted in and out of the MAX186/MAX188 at clock rates exceeding 4.0MHz, provided that the minimum acquisition time,  $t_{AZ}$ , is kept above 1.5µs.

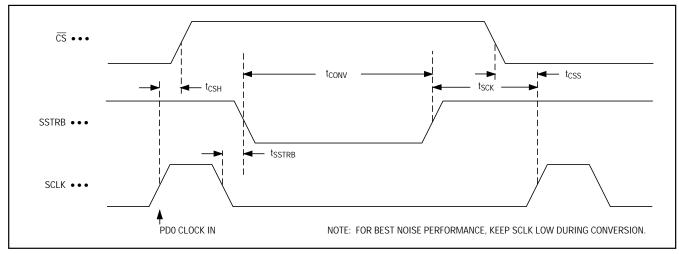


Figure 10. Internal Clock Mode SSTRB Detailed Timing

### **Data Framing**

The falling edge of  $\overline{CS}$  does **not** start a conversion on the MAX186/MAX188. The first logic high clocked into DIN is interpreted as a start bit and defines the first bit of the control byte. A conversion starts on the falling edge of SCLK, after the eighth bit of the control byte (the PD0 bit) is clocked into DIN. The start bit is defined as:

The first high bit clocked into DIN with  $\overline{CS}$  low anytime the converter is idle, e.g. after V<sub>CC</sub> is applied.

### OR

The first high bit clocked into DIN after bit 5 of a conversion in progress is clocked onto the DOUT pin.

If a falling edge on  $\overline{\text{CS}}$  forces a start bit before bit 5 (B5) becomes available, then the current conversion will be terminated and a new one started. Thus, the fastest the MAX186/MAX188 can run is 15 clocks per conversion. Figure 11a shows the serial-interface timing necessary to perform a conversion every 15 SCLK cycles in external clock mode. If  $\overline{\text{CS}}$  is low and SCLK is continuous, guarantee a start bit by first clocking in 16 zeros.

Most microcontrollers require that conversions occur in multiples of 8 SCLK clocks; 16 clocks per conversion will typically be the fastest that a microcontroller can drive the MAX186/MAX188. Figure 11b shows the serial-interface timing necessary to perform a conversion every 16 SCLK cycles in external clock mode.

### **Applications Information**

### **Power-On Reset**

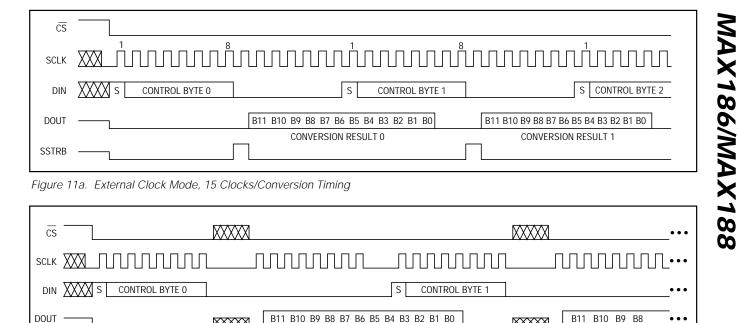
When power is first applied and if  $\overline{SHDN}$  is not pulled low, internal power-on reset circuitry will activate the MAX186/MAX188 in internal clock mode, ready to convert with SSTRB = high. After the power supplies have been stabilized, the internal reset time is 100µs and no conversions should be performed during this phase. SSTRB is high on power-up and, if  $\overline{CS}$  is low, the first logical 1 on DIN will be interpreted as a start bit. Until a conversion takes place, DOUT will shift out zeros.

### **Reference-Buffer Compensation**

In addition to its shutdown function, the SHDN pin also selects internal or external compensation. The compensation affects both power-up time and maximum conversion speed. Compensated or not, the minimum clock rate is 100kHz due to droop on the sample-and-hold.

To select external compensation, float  $\overline{SHDN}$ . See the *Typical Operating Circuit*, which uses a 4.7µF capacitor at VREF. A value of 4.7µF or greater ensures stability and allows operation of the converter at the full clock speed of 2MHz. External compensation increases power-up time (see the *Choosing Power-Down Mode* section, and Table 5).

Internal compensation requires no external capacitor at VREF, and is selected by pulling SHDN high. Internal compensation allows for shortest power-up times, but is only available using an external clock and reduces the maximum clock rate to 400kHz.



CONVERSION RESULT 0

Figure 11b. External Clock Mode, 16 Clocks/Conversion Timing

XXXXX

### Power-Down

### Choosing Power-Down Mode

You can save power by placing the converter in a low-current shutdown state between conversions. Select full power-down or fast power-down mode via bits 7 and 8 of the DIN control byte with SHDN high or floating (see Tables 2 and 6). Pull SHDN low at any time to shut down the converter completely. SHDN overrides bits 7 and 8 of DIN word (see Table 7).

Full power-down mode turns off all chip functions that draw quiescent current, reducing IDD and ISS typically to 2µA.

Fast power-down mode turns off all circuitry except the bandgap reference. With the fast power-down mode, the supply current is 30µA. Power-up time can be shortened to 5µs in internal compensation mode.

In both software shutdown modes, the serial interface remains operational, however, the ADC will not convert. Table 5 illustrates how the choice of reference-buffer compensation and power-down mode affects both power-up delay and maximum sample rate.

In external compensation mode, the power-up time is 20ms with a 4.7µF compensation capacitor (200ms with a 33µF capacitor) when the capacitor is fully discharged. In fast power-down, you can eliminate start-up time by using low-leakage capacitors that will not discharge more than 1/2LSB while shut down. In shutdown, the capacitor has to supply the current into the reference (1.5µA typ) and the transient currents at power-up.

XXXXX

Figures 12a and 12b illustrate the various power-down sequences in both external and internal clock modes.

### Software Power-Down

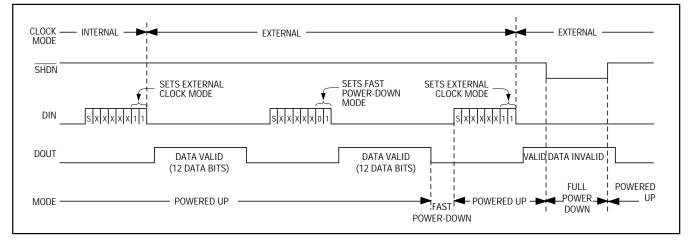
**CONVERSION RESULT 1** 

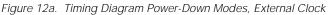
Software power-down is activated using bits PD1 and PD0 of the control byte. As shown in Table 6, PD1 and PD0 also specify the clock mode. When software shutdown is asserted, the ADC will continue to operate in the last specified clock mode until the conversion is complete. Then the ADC powers down into a low quiescent-current state. In internal clock mode, the interface remains active and conversion results may be clocked out while the MAX186/MAX188 have already entered a software power-down.

The first logical 1 on DIN will be interpreted as a start bit, and powers up the MAX186/MAX188. Following the start bit, the data input word or control byte also determines clock and power-down modes. For example, if the DIN word contains PD1 = 1, then the chip will remain powered up. If PD1 = 0, a power-down will resume after one conversion.









### Table 5. Typical Power-Up Delay Times

Reference Buffer	Reference- Buffer Compensation Mode	VREF Capacitor (µF)	Power- Down Mode	Power-Up Delay (sec)	Maximum Sampling Rate (ksps)
Enabled	Internal		Fast	5µ	26
Enabled	Internal		Full	300µ	26
Enabled	External	4.7	Fast	See Figure 14c	133
Enabled	External	4.7	Full	See Figure 14c	133
Disabled			Fast	2μ	133
Disabled			Full	2μ	133

### Table 6. Software Shutdown and Clock Mode

PD1	PD0	Device Mode
1	1	External Clock Mode
1	0	Internal Clock Mode
0	1	Fast Power-Down Mode
0	0	Full Power-Down Mode

# Table 7. Hard-Wired Shutdown andCompensation Mode

SHDN State	Device Mode	Reference-Buffer Compensation
1	Enabled	Internal Compensation
Floating	Enabled	External Compensation
0	Full Power-Dow	n N/A

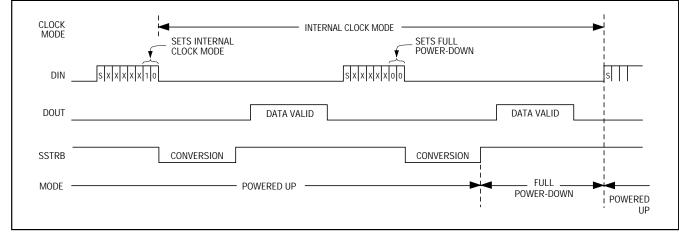


Figure 12b. Timing Diagram Power-Down Modes, Internal Clock

### Hardware Power-Down

The SHDN pin places the converter into the full power-down mode. Unlike with the software shut-down modes, conversion is not completed. It stops coincidentally with SHDN being brought low. There is no power-up delay if an external reference is used and is not shut down. The SHDN pin also selects internal or external reference compensation (see Table 7).

### **Power-Down Sequencing**

The MAX186/MAX188 auto power-down modes can save considerable power when operating at less than maximum sample rates. The following discussion illustrates the various power-down sequences.

### Lowest Power at up to 500 Conversions/Channel/Second

The following examples illustrate two different power-down sequences. Other combinations of clock rates, compensation modes, and power-down modes may give lowest power consumption in other applications.

Figure 14a depicts the MAX186 power consumption for one or eight channel conversions utilizing full power-down mode and internal reference compensation. A 0.01 $\mu$ F bypass capacitor at REFADJ forms an RC filter with the internal 20k $\Omega$  reference resistor with a 0.2ms time constant. To achieve full 12-bit accuracy, 10 time constants or 2ms are required after power-up. Waiting 2ms in FASTPD mode instead of full power-up will reduce the power consumption by a factor of 10 or more. This is achieved by using the sequence shown in Figure 13.

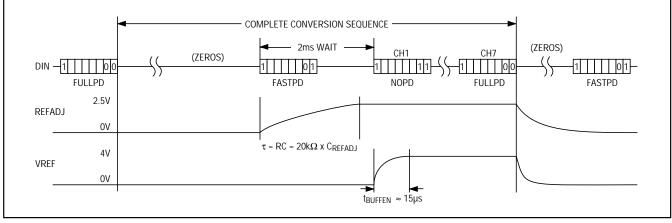


Figure 13. MAX186 FULLPD/FASTPD Power-Up Sequence

MIXX/M

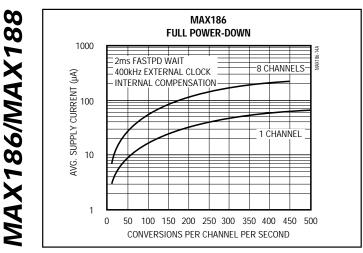


Figure 14a. MAX186 Supply Current vs. Sample Rate/Second, FULLPD, 400kHz Clock

### Lowest Power at Higher Throughputs

Figure 14b shows the power consumption with external-reference compensation in fast power-down, with one and eight channels converted. The external 4.7µF compensation requires a 50µs wait after power-up, accomplished by 75 idle clocks after a dummy conversion. This circuit combines fast multi-channel conversion with lowest power consumption possible. Full power-down mode may provide increased power savings in applications where the MAX186/MAX188 are inactive for long periods of time, but where intermittent bursts of high-speed conversions are required.

### **External and Internal References**

The MAX186 can be used with an internal or external reference, whereas an external reference is required for the MAX188. Diode D1 shown in the *Typical Operating Circuit* ensures correct start-up. Any standard signal diode can be used. For both parts, an external reference can either be connected directly at the VREF terminal or at the REFADJ pin.

An internal buffer is designed to provide 4.096V at VREF for both the MAX186 and MAX188. The MAX186's internally trimmed 2.46V reference is buffered with a gain of 1.678. The MAX188's buffer is trimmed with a buffer gain of 1.638 to scale an external 2.5V reference at REFADJ to 4.096V at VREF.

### MAX186 Internal Reference

The full-scale range of the MAX186 with internal reference is 4.096V with unipolar inputs, and  $\pm 2.048V$  with bipolar inputs. The internal reference voltage is adjustable to  $\pm 1.5\%$  with the Reference-Adjust Circuit of Figure 17.



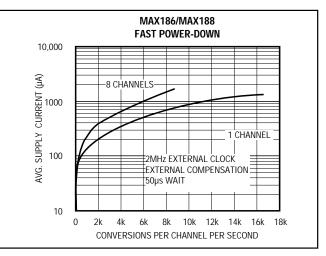


Figure 14b. MAX186/MAX188 Supply Current vs. Sample Rate/Second, FASTPD, 2MHz Clock

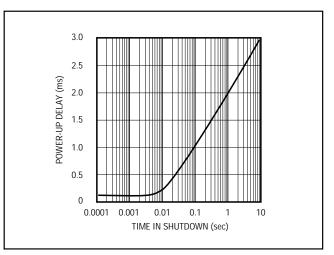


Figure 14c. Typical Power-Up Delay vs. Time in Shutdown

### External Reference

With both the MAX186 and MAX188, an external reference can be placed at either the input (REFADJ) or the output (VREF) of the internal buffer amplifier. The REFADJ input impedance is typically  $20k\Omega$  for the MAX186 and higher than  $100k\Omega$  for the MAX188, where the internal reference is omitted. At VREF, the input impedance is a minimum of  $12k\Omega$  for DC currents. During conversion, an external reference at VREF must be able to deliver up to  $350\mu$ A DC load current and have an output impedance of  $10\Omega$  or less. If the reference has higher output impedance or is noisy, bypass it close to the VREF pin with a  $4.7\mu$ F capacitor.



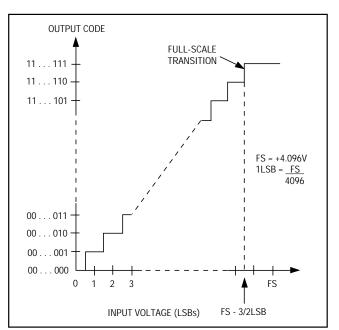


Figure 15. MAX186/MAX188 Unipolar Transfer Function, 4.096V = Full Scale

Using the buffered REFADJ input avoids external buffering of the reference. To use the direct VREF input, disable the internal buffer by tying REFADJ to  $V_{DD}$ .

### **Transfer Function and Gain Adjust**

Figure 15 depicts the nominal, unipolar input/output (I/O) transfer function, and Figure 16 shows the bipolar input/output transfer function. Code transitions occur halfway between successive integer LSB values. Output coding is binary with 1 LSB = 1.00mV (4.096V/4096) for unipolar operation and 1 LSB = 1.00mV ((4.096V/2 - -4.096V/2)/4096) for bipolar operation.

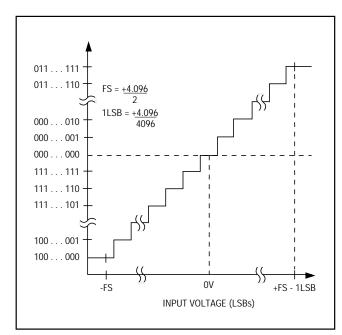
Figure 17, the MAX186 Reference-Adjust Circuit, shows how to adjust the ADC gain in applications that use the internal reference. The circuit provides  $\pm 1.5\%$ ( $\pm 65$ LSBs) of gain adjustment range.

### Layout, Grounding, Bypassing

For best performance, use printed circuit boards. Wire-wrap boards are not recommended. Board layout should ensure that digital and analog signal lines are separated from each other. Do not run analog and digital (especially clock) lines parallel to one another, or digital lines underneath the ADC package.

Figure 18 shows the recommended system ground connections. A single-point analog ground ("star" ground point) should be established at AGND, separate from the logic ground. All other analog grounds

# Low-Power, 8-Channel, Serial 12-Bit ADCs



*Figure 16. MAX186/MAX188 Bipolar Transfer Function,* ±4.096V/2 = *Full Scale* 

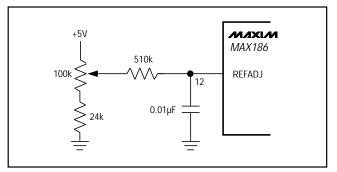


Figure 17. MAX186 Reference-Adjust Circuit

and DGND should be connected to this ground. No other digital system ground should be connected to this single-point analog ground. The ground return to the power supply for this ground should be low impedance and as short as possible for noise-free operation.

High-frequency noise in the V<sub>DD</sub> power supply may affect the high-speed comparator in the ADC. Bypass these supplies to the single-point analog ground with 0.1µF and 4.7µF bypass capacitors close to the MAX186/MAX188. Minimize capacitor lead lengths for best supply-noise rejection. If the +5V power supply is very noisy, a 10 $\Omega$  resistor can be connected as a low-pass filter, as shown in Figure 18.

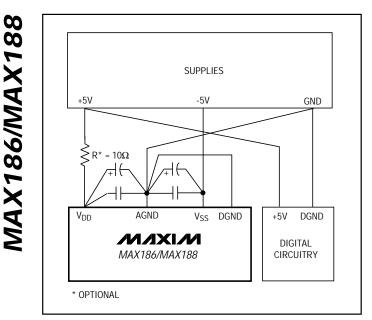


Figure 18. Power-Supply Grounding Connection

### High-Speed Digital Interfacing with QSPI

The MAX186/MAX188 can interface with QSPI at high throughput rates using the circuit in Figure 19. This QSPI circuit can be programmed to do a conversion on each of the eight channels. The result is stored in memory without taxing the CPU since QSPI incorporates its own micro-sequencer. Figure 19 depicts the MAX186, but the same circuit could be used with the MAX188 by adding an external reference to VREF and connecting REFADJ to V<sub>DD</sub>.

Figure 20 details the code that sets up QSPI for autonomous operation. In external clock mode, the MAX186/MAX188 perform a single-ended, unipolar conversion on each of their eight analog input channels. Figure 21, QSPI Assembly-Code Timing, shows the timing associated with the assembly code of Figure 20. The first byte clocked into the MAX186/MAX188 is the control byte, which triggers the first conversion on CH0. The last two bytes clocked into the MAX186/MAX188 are all zero and clock out the results of the CH7 conversion.

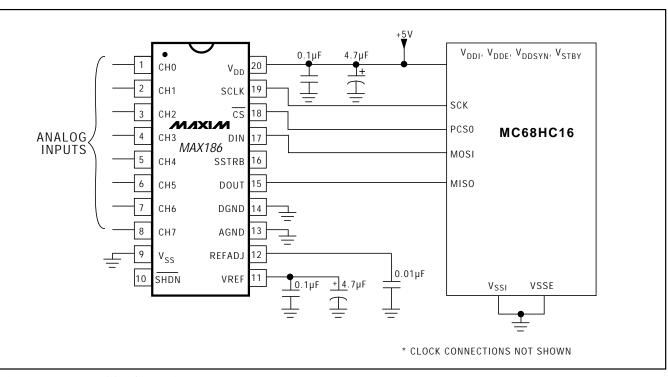


Figure 19. MAX186 QSPI Connection

\*Title : MAX186.ASM Description : This is a shell program for using a stand-alone 68HC16 without any external memory. The internal 1K RAM is put into bank \$0F to maintain 68HC11 code compatibility. This program was written with software provided in the Motorola 68HC16 Evaluation Kit. Roger J.A. Chen, Applications Engineer MAXIM Integrated Products November 20, 1992 INCLUDE 'EQUATES.ASM' ;Equates for common reg addrs 'ORG00000.ASM' ;initialize reset vector INCLUDE INCLUDE 'ORG00008.ASM' ;initialize interrupt vectors ORG \$0200 ;start program after interrupt vectors INCLUDE 'INITSYS.ASM' ;set EK=F,XK=0,YK=0,ZK=0 ;set sys clock at 16.78 MHz, COP off INCLUDE 'INITRAM.ASM' ;turn on internal SRAM at \$10000 ;set stack (SK=1, SP=03FE) MAIN: JSR INITQSPI MAINLOOP: JSR READ186 WAIT: LDAA SPSR ANDA #\$80 BEQ WAIT ;wait for QSPI to finish **BRA MAINLOOP** ENDPROGRAM: INITQSPI: ;This routine sets up the QSPI microsequencer to operate on its own. The sequencer will read all eight channels of a MAX186/MAX188 each time ; it is triggered. The A/D converter results will be left in the receive data RAM. Each 16 bit receive data RAM location will ;have a leading zero, 12 bits of conversion result and three zeros. Receive RAM Bits 15 14 13 12 11 10 09 08 07 06 05 04 03 02 01 00 :A/D Result 0 MSB LSB 0 0 0 \*\*\*\*\* Initialize the QSPI Registers \*\*\*\*\*\* PSHA PSHB LDAA #%01111000 STAA QPDR ;idle state for PCS0-3 = high LDAA #%01111011 STAA QPAR ;assign port D to be QSPI LDAA #%01111110 STAA QDDR ;only MISO is an input LDD #\$8008 STD SPCR0 ;master mode, 16 bits/transfer, ;CPOL=CPHA=0,1MHz Ser Clock LDD #\$0000 STD SPCR1 ;set delay between PCS0 and SCK,

M/X/M

**MAX186/MAX188** 

MAX186/MAX188

;set delay between transfers							
LDD #\$0800 STD SPCR2 ;set ENDQP to \$8 for 9 transfers							
***** Initialize QSPI Command RAM *****							
LDAA #\$80 ;CONT=1,BITSE=0,DT=0,DSCK=0,PCS0=ACTIVE							
STAA \$FD40 ;store first byte in COMMAND RAM	store first byte in COMMAND RAM						
LDAA #\$C0 ;CONT=1,BITSE=1,DT=0,DSCK=0,PCS0=ACTIVE							
STAA \$FD41 STAA \$FD42							
STAA \$FD43							
STAA \$FD44							
STAA \$FD45 STAA \$FD46							
STAA \$FD47							
LDAA #\$40 ;CONT=0,BITSE=1,DT=0,DSCK=0,PCS0=ACTIVE							
STAA \$FD48 ***** Initialize QSPI Transmit RAM *****							
LDD #\$008F							
STD \$FD20 LDD #\$00CF							
STD \$FD22							
LDD #\$009F							
STD \$FD24 LDD #\$00DF							
STD \$FD26							
LDD #\$00AF							
STD \$FD28 LDD #\$00EF							
STD \$FD2A							
LDD #\$00BF							
STD \$FD2C LDD #\$00FF							
STD \$FD2E							
LDD #\$0000							
STD \$FD30 PULB							
PULA							
RTS							
READ186: This routine triggers the QSPI microsequencer to autonomously							
rigger conversions on all 8 channels of the MAX186. Each							
conversion result is stored in the receive data RAM.							
PSHA LDAA #\$80							
ORAA SPCR1							
STAA SPCR1 ;just set SPE							
PULA RTS							
***** Interrupts/Exceptions *****							
BDM: BGND ;exception vectors point here							
Figure 20. MAX186/MAX188 Assembly-Code Listing (continued)							

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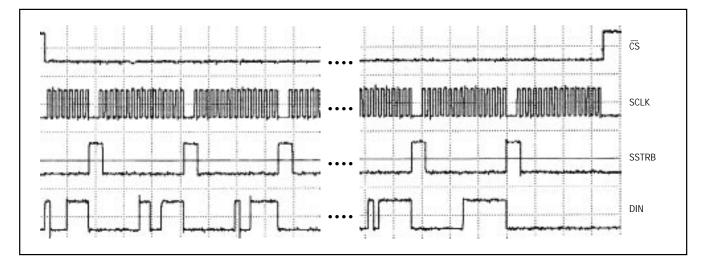


Figure 21. QSPI Assembly-Code Timing

### TMS320C3x to MAX186 Interface

Figure 22 shows an application circuit to interface the MAX186/MAX188 to the TMS320 in external clock mode. The timing diagram for this interface circuit is shown in Figure 23.

Use the following steps to initiate a conversion in the MAX186/MAX188 and to read the results:

- The TMS320 should be configured with CLKX (transmit clock) as an active-high output clock and CLKR (TMS320 receive clock) as an active-high input clock. CLKX and CLKR of the TMS320 are tied together with the SCLK input of the MAX186/MAX188.
- 2) The MAX186/MAX188 CS is driven low by the XF\_ I/O port of the TMS320 to enable data to be clocked into DIN of the MAX186/MAX188.
- An 8-bit word (1XXXXX11) should be written to the MAX186/MAX188 to initiate a conversion and place the device into external clock mode. Refer to Table 2 to select the proper XXXXX bit values for your specific application.
- 4) The SSTRB output of the MAX186/MAX188 is monitored via the FSR input of the TMS320. A falling edge on the SSTRB output indicates that the conversion is in progress and data is ready to be received from the MAX186/MAX188.

 XF
 CS

 CLKX
 SCLK

 TMS320C3x
 MAX186

 CLKR
 MAX186

 DX
 DIN

 DR
 DOUT

 FSR
 SSTRB

Figure 22. MAX186/MAX188 to TMS320 Serial Interface

- The TMS320 reads in one data bit on each of the next 16 rising edges of SCLK. These data bits represent the 12-bit conversion result followed by four trailing bits, which should be ignored.
- 6) Pull CS high to disable the MAX186/MAX188 until the next conversion is initiated.

MAX186/MAX188



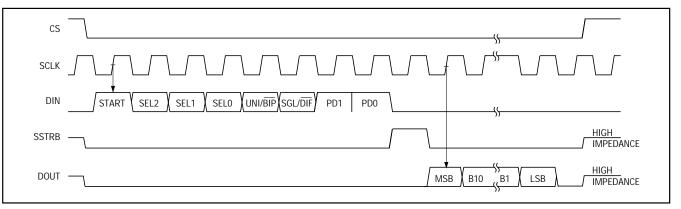
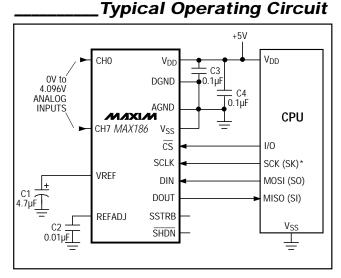


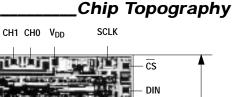
Figure 23. TMS320 Serial Interface Timing Diagram

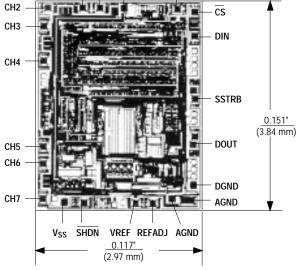


### \_Ordering Information (continued)

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PART <sup>†</sup>	TEMP. RANGE	PIN-PACKAGE
MAX188_CPP	0°C to +70°C	20 Plastic DIP
MAX188_CWP	0°C to +70°C	20 SO
MAX188_CAP	0°C to +70°C	20 SSOP
MAX188DC/D	0°C to +70°C	Dice*
MAX188_EPP	-40°C to +85°C	Plastic DIP
MAX188_EWP	-40°C to +85°C	20 SO
MAX188_EAP	-40°C to +85°C	20 SSOP
MAX188_MJP	-55°C to +125°C	20 CERDIP**
PART	TEMP. RANGE	BOARD TYPE

0°C to +70°C





### **MAX186/MAX188**

TRANSISTOR COUNT: 2278; SUBSTRATE CONNECTED TO VDD

† NOTE: Parts are offered in grades A, B, C and D (grades defined in Electrical Characteristics). When ordering, please specify grade.

Dice are specified at +25°C, DC parameters only.

\* \* Contact factory for availability and processing to MIL-STD-883.

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