

EZ-USB® NX2LP-Flex™ Flexible USB NAND Flash Controller

CY7C68033/CY7C68034 Silicon Features

- Certified compliant for bus- or self-powered USB 2.0 operation (TID# 40490118)
- Single-chip, integrated USB 2.0 transceiver and smart SIE
- Ultra low power – 43 mA typical current draw in any mode
- Enhanced 8051 core
 - Firmware runs from internal RAM that is downloaded from NAND Flash at startup
 - No external EEPROM required
- 15 KBytes of on-chip code/data RAM
 - Default NAND firmware – 8 kB
 - Default free space – 7 kB
- Four programmable bulk/interrupt/isochronous endpoints
 - Buffering options: double, triple, and quad
- Additional programmable (bulk/interrupt) 64-byte endpoint
- SmartMedia standard hardware ECC generation with 1-bit correction and 2-bit detection
- General programmable interface (GPIO)
 - Enables direct connection to most parallel interfaces
 - Programmable waveform descriptors and configuration registers to define waveforms
 - Supports multiple ready (RDY) inputs and control (CTL) outputs
- 12 fully programmable general purpose I/O (GPIO) pins

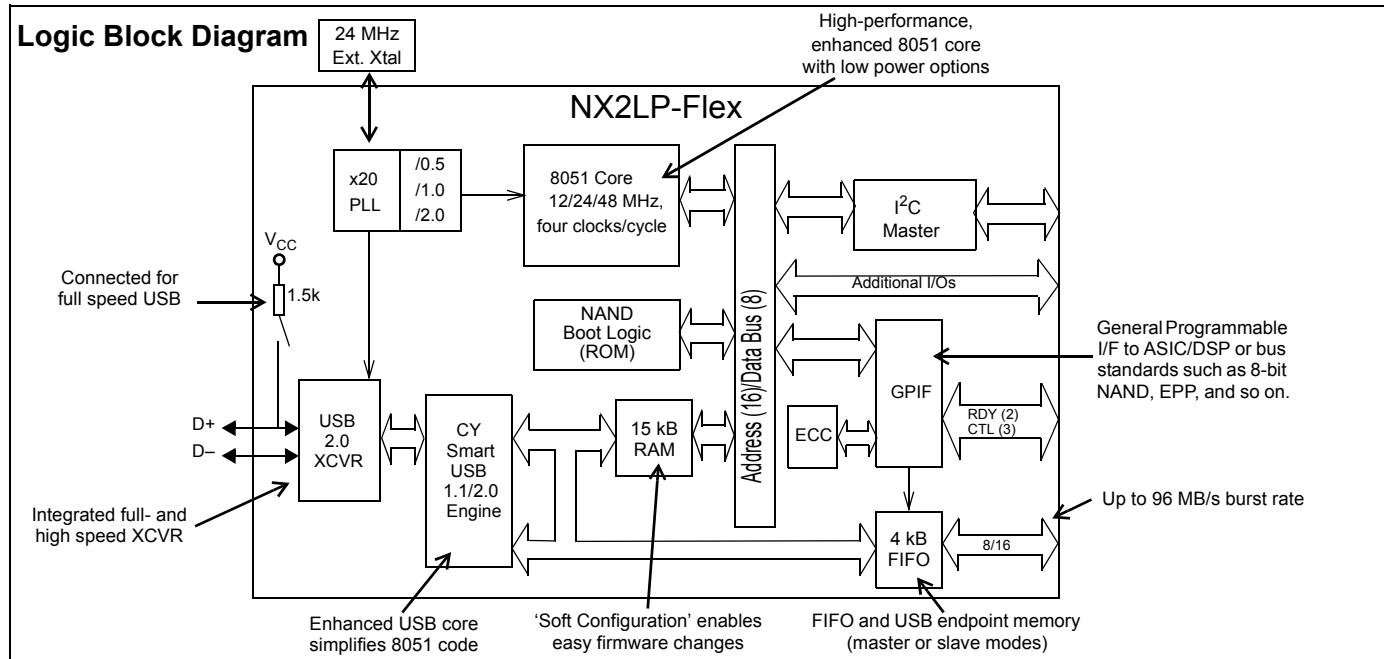
- Integrated, industry-standard enhanced 8051
 - 48-MHz, 24-MHz, or 12-MHz CPU operation
 - Four clocks for each instruction cycle
 - Three counter/timers
 - Expanded interrupt system
 - Two data pointers
- 3.3-V operation with 5 V tolerant inputs
- Vectored USB interrupts and GPIF/FIFO interrupts
- Separate data buffers for the setup and data portions of a control transfer
- Integrated I²C controller, runs at 100 or 400 kHz
- Four integrated FIFOs
 - Integrated glue logic and FIFOs lower system cost
 - Automatic conversion to and from 16-bit buses
 - Master or slave operation
 - Uses external clock or asynchronous strobes
 - Easy interface to ASIC and DSP ICs
- Available in space saving 56-pin QFN package

CY7C68034 Only Silicon Features

- Ideal for battery powered applications
 - Suspend current: 100 µA (typ)

CY7C68033 Only Silicon Features

- Ideal for non-battery powered applications
 - Suspend current: 300 µA (typ)



Default NAND Firmware Features

Because the NX2LP-Flex® is intended for NAND Flash-based USB mass storage applications, a default firmware image is included in the development kit with the following features:

- High (480 Mbps) or full (12 Mbps) speed USB support
- NAND sizes supported per chip select
 - 512 bytes for up to 1 Gb capacity
 - 2K bytes for up to 8 Gb capacity
 - 4K bytes for up to 16 Gb capacity
- 12 configurable GPIO pins
 - Two dedicated chip enable (CE#) pins
 - Six configurable CE#/GPIO pins
 - Up to eight NAND Flash single-device (single-die) chips are supported
 - Up to four NAND Flash dual-device (dual-die) chips are supported
 - Compile option enables unused CE# pins to be configured as GPIOs
 - Four dedicated GPIO pins
- Industry standard ECC NAND Flash correction
 - 1 bit for every 256-bit correction
 - 2-bit error detection

- Industry standard (SmartMedia) page management for wear leveling algorithm, bad block handling, and physical to logical management.
- 8-bit NAND Flash interface support
- Support for 30 ns, 50 ns, and 100 ns NAND Flash timing
- Complies with the USB mass storage class specification revision 1.0

The default firmware image implements a USB 2.0 NAND Flash controller. This controller adheres to the *Mass Storage Class Bulk-Only Transport Specification*. The USB port of the NX2LP-Flex is connected to a host computer directly or through the downstream port of a USB hub. The host software issues commands and data to the NX2LP-Flex and receives status and data from the NX2LP-Flex using standard USB protocol.

The default firmware image supports industry leading 8-bit NAND Flash interfaces and both common NAND page sizes of 512 and 2k bytes. Up to eight CE# pins enable the NX2LP-Flex to be connected to up to eight single or four dual-die NAND Flash chips.

Complete source code and documentation for the default firmware image are included in the [NX2LP-Flex development kit](#) to enable customization for meeting design requirements. Additionally, compile options for the default firmware enable quick configuration of some features to decrease design effort and increase time-to-market advantages.

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Acronyms

Acronym	Description
ASIC	application specific integrated circuit
CPU	central processing unit
DSP	digital signal processor
ECC	error correcting codes
GPIF	general programmable interface
GPIO	general purpose I/O
IC	integrated circuit
ICE	in-circuit emulator
I/O	input/output
LSb	least-significant bit
LVD	low voltage detect
MSb	most-significant bit
PLL	phase locked loop
PCB	printed circuit board
POR	power on reset
PSoC®	Programmable System-on-Chip
SCL	serial clock
SDA	serial data line
RAM	random access memory
USB	universal serial bus
USB-IF	USB implementor's forum

Overview

Cypress Semiconductor Corporation's EZ-USB® NX2LP-Flex (CY7C68033/CY7C68034) is a firmware-based, programmable version of the EZ-USB NX2LP (CY7C68023/CY7C68024), which is a fixed-function, low power USB 2.0 NAND Flash controller. By integrating the USB 2.0 transceiver, serial interface engine (SIE), enhanced 8051 microcontroller, and a programmable peripheral interface in a single chip, Cypress has created a very cost-effective solution that enables feature-rich NAND Flash-based applications.

The ingenious architecture of NX2LP-Flex results in USB data transfer rates of over 53 Mbytes per second, the maximum allowable USB 2.0 bandwidth, while still using a low cost 8051 microcontroller in a small 56-pin QFN package. Because it incorporates the USB 2.0 transceiver, the NX2LP-Flex is more economical, providing a smaller footprint solution than external USB 2.0 SIE or transceiver implementations. With EZ-USB NX2LP-Flex, the Cypress Smart SIE handles most of the USB 1.1 and 2.0 protocol, freeing the embedded microcontroller for application-specific functions and decreasing development time while ensuring USB compatibility.

The GPIF and master/slave endpoint FIFO (8- or 16-bit data bus) provide an easy and glueless interface to popular interfaces such as UTOPIA, EPP, I²C, PCMCIA, and most DSP processors.

Applications

The NX2LP-Flex enables designers to add extra functionality to basic NAND Flash mass storage designs, or to interface them with other peripheral devices. Applications may include:

- NAND Flash-based GPS devices
- NAND Flash-based DVB video capture devices
- Wireless pointer/presenter tools with NAND Flash storage
- NAND Flash-based MPEG/TV conversion devices
- Legacy conversion devices with NAND Flash storage
- NAND Flash-based cameras
- NAND Flash mass storage device with biometric (for example, fingerprint) security
- Home PNA devices with NAND Flash storage
- Wireless LAN with NAND Flash storage
- NAND Flash-based MP3 players
- LAN networking with NAND Flash storage

Figure 1. Example DVB Block Diagram

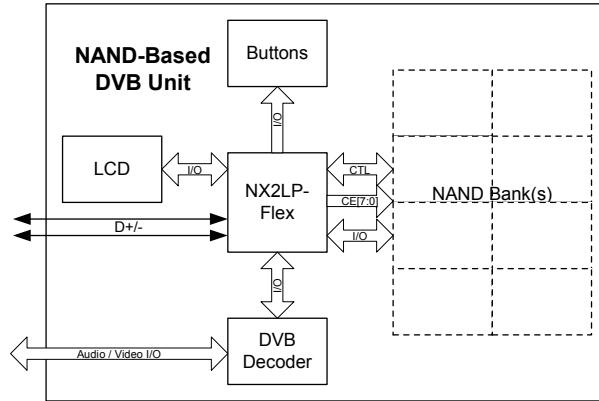
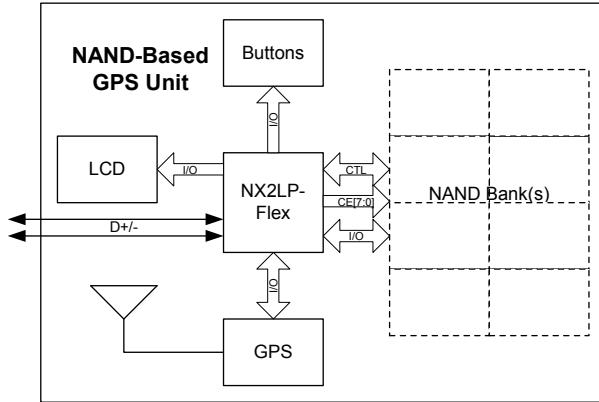


Figure 2. Example GPS Block Diagram



The “Reference Designs” section of the Cypress web site provides additional tools for typical USB 2.0 applications. Each reference design comes complete with firmware source and object code, schematics, and documentation.

Functional Overview

USB Signaling Speed

NX2LP-Flex operates at two of the three rates defined in the USB Specification Revision 2.0, dated April 27, 2000:

- Full speed, with a signaling bit rate of 12 Mbps
- High speed, with a signaling bit rate of 480 Mbps.

NX2LP-Flex does not support the low speed signaling mode of 1.5 Mbps.

8051 Microprocessor

The 8051 microprocessor embedded in the NX2LP-Flex has 256 bytes of register RAM, an expanded interrupt system and three timer/counters.

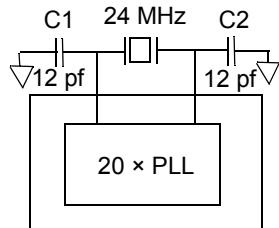
8051 Clock Frequency

NX2LP-Flex has an on-chip oscillator circuit that uses an external 24 MHz (± 100 ppm) crystal with the following characteristics:

- Parallel resonant
- Fundamental mode
- 500 μ W drive level
- 12 pF (5% tolerance) load capacitors.

An on-chip PLL multiplies the 24-MHz oscillator up to 480 MHz, as required by the transceiver/PHY, and internal counters divide it down for use as the 8051 clock. The default 8051 clock frequency is 12 MHz. The clock frequency of the 8051 can be changed by the 8051 through the CPUCS register, dynamically

Figure 3. Crystal Configuration



12-pF capacitor values assumes a trace capacitance
of 3 pF per side on a four-layer FR4 PCA

Special Function Registers

Certain 8051 SFR addresses are populated to provide fast access to critical NX2LP-Flex functions. These SFR additions are shown in [Table 1](#) on page 6. Bold type indicates non-standard, enhanced 8051 registers. The two SFR rows that end with '0' and '8' contain bit-addressable registers. The four I/O ports A–D use the SFR addresses used in the standard 8051 for ports 0–3, which are not implemented in NX2LP-Flex. Because of the faster and more efficient SFR addressing, the NX2LP-Flex I/O ports are not addressable in external RAM space (using the MOVX instruction).

I²C Bus

NX2LP supports the I²C bus as a master only at 100/400 kHz. SCL and SDA pins have open-drain outputs and hysteresis inputs. These signals must be pulled up to 3.3V, even if no I²C device is connected. The I²C bus is disabled at startup and only available for use after the initial NAND access.

Table 1. Special Function Registers

x	8x	9x	Ax	Bx	Cx	Dx	Ex	Fx
0	IOA	IOB	IOC	IOD	SCON1	PSW	ACC	B
1	SP	EXIF	INT2CLR	IOE	SBUF1			
2	DPL0	MPAGE	INT4CLR	OEA				
3	DPH0			OEB				
4	DPL1			OEC				
5	DPH1			OED				
6	DPS			OEE				
7	PCON							
8	TCON	SCON0	IE	IP	T2CON	EICON	EIE	EIP
9	TMOD	SBUF0						
A	TL0	AUTOPTRH1	EP2468STAT	EP01STAT	RCAP2L			
B	TL1	AUTOPTRL1	EP24FIFOFLGS	GPIFTRIG	RCAP2H			
C	TH0	RESERVED	EP68FIFOFLGS		TL2			
D	TH1	AUTOPTRH2		GPIFSGLDATH	TH2			
E	CKCON	AUTOPTRL2		GPIFSGLDATLX				
F		RESERVED	AUTOPTRSETUP	GPIFSGLDATLNOX				

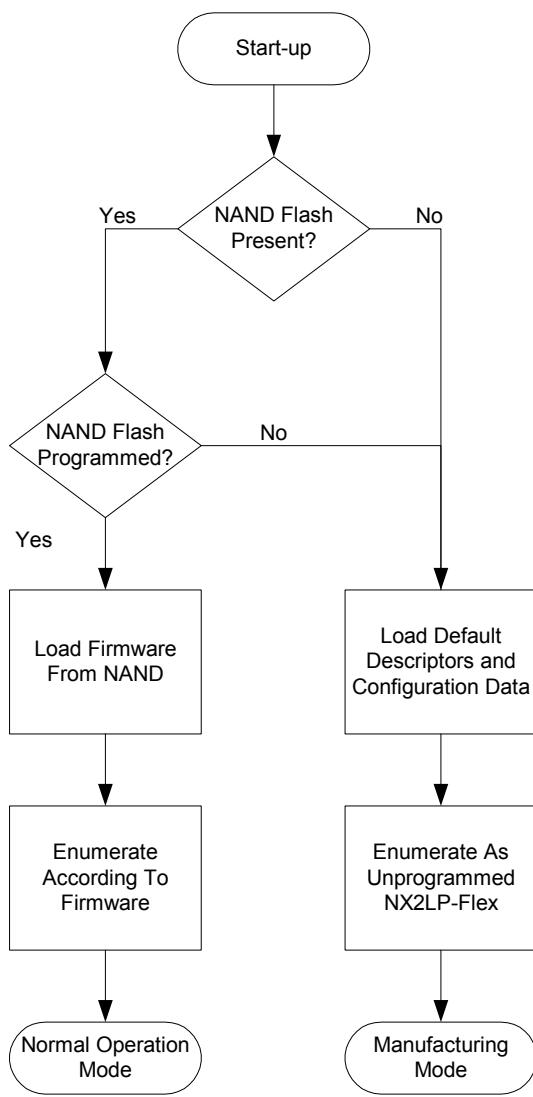
Buses

The NX2LP-Flex features an 8- or 16-bit 'FIFO' bidirectional data bus, multiplexed on I/O ports B and D.

The default firmware image implements an 8-bit data bus in GPIF master mode. It is recommended that additional interfaces added to the default firmware image use this 8-bit data bus.

Enumeration

During the startup sequence, internal logic checks for the presence of NAND Flash with valid firmware. If valid firmware is found, the NX2LP-Flex loads it and operates according to the firmware. If no NAND Flash is detected, or if no valid firmware is found, the NX2LP-Flex uses the default values from internal ROM space for manufacturing mode operation. The two modes of operation are described in the section [Normal Operation Mode](#) and [Manufacturing Mode](#) on page 7.

Figure 4. NX2LP-Flex Enumeration Sequence


Normal Operation Mode

In normal operation mode, the NX2LP-Flex behaves as a USB 2.0 Mass Storage Class NAND Flash controller. This includes all typical USB device states (powered, configured, and so on). The USB descriptors are returned according to the data stored in the configuration data memory area. Normal read and write access to the NAND Flash is available in this mode.

Manufacturing Mode

In manufacturing mode, the NX2LP-Flex enumerates using the default descriptors and configuration data that are stored in internal ROM space. This mode enables for first time programming of the configuration data memory area, and board level manufacturing tests.

Default Silicon ID Values

To facilitate proper USB enumeration when no programmed NAND Flash is present, the NX2LP-Flex has default silicon ID values stored in ROM space. The default silicon ID values should only be used for development purposes. Designers must use their own Vendor ID for final products. A Vendor ID is obtained through registration with the USB Implementor's Forum (USB-IF). If the NX2LP-Flex is used as a mass storage class device, a unique USB serial number is required for each device to comply with the USB Mass Storage class specification.

Cypress provides all the software tools and drivers necessary to properly programme and test the NX2LP-Flex. Refer to the documentation in the development kit for more information on these topics.

Table 2. Default Silicon ID Values

Default VID/PID/DID		
Vendor ID	0x04B4	Cypress Semiconductor
Product ID	0x8613	EZ-USB® Default
Device release	0xA ⁿ nnn	Depends on chip revision (nnn = chip revision, where first silicon = 001)

ReEnumeration™

Cypress's ReEnumeration feature is used in conjunction with the NX2LP-Flex manufacturing software tools to enable first-time NAND programming. It is only available when used in conjunction with the NX2LP-Flex manufacturing tools, and is not enabled during normal operation.

Bus-powered Applications

The NX2LP-Flex fully supports bus-powered designs by enumerating with less than 100 mA, as required by the USB 2.0 specification.

Interrupt System

INT2 Interrupt Request and Enable Registers

NX2LP-Flex implements an autovector feature for INT2 and INT4. There are 27 INT2 (USB) vectors and 14 INT4 (FIFO/GPIF) vectors. For more details, refer to the [EZ-USB Technical Reference Manual \(TRM\)](#).

USB-Interrupt Autovectors

The main USB interrupt is shared by 27 interrupt sources. To save the code and processing time normally required to identify the individual USB interrupt source, the NX2LP-Flex provides a second level of interrupt vectoring, called Autovectoring. When a USB interrupt is asserted, the NX2LP-Flex pushes the program counter to its stack and then jumps to address 0x0500; it expects to find a 'jump' instruction to the USB Interrupt service routine here.

Developers familiar with Cypress's programmable USB devices should note that these interrupt vector values differ from those used in other EZ-USB microcontrollers. This is due to the additional NAND boot logic that is present in the NX2LP-Flex ROM space. Also, these values are fixed and cannot be changed in the firmware.

Table 3. INT2 USB Interrupts

USB Interrupt Table For INT2			
Priority	INT2VEC Value	Source	Notes
1	0x500	SUDAV	Setup data available
2	0x504	SOF	Start of frame (or microframe)
3	0x508	SUTOK	Setup token received
4	0x50C	SUSPEND	USB suspend request
5	0x510	USB RESET	Bus reset
6	0x514	HISPEED	Entered high speed operation
7	0x518	EP0ACK	NX2LP ACK'd the CONTROL handshake
8	0x51C		Reserved
9	0x520	EP0-IN	EP0-IN ready to be loaded with data
10	0x524	EP0-OUT	EP0-OUT has USB data
11	0x528	EP1-IN	EP1-IN ready to be loaded with data
12	0x52C	EP1-OUT	EP1-OUT has USB data
13	0x530	EP2	IN: buffer available. OUT: buffer has data
14	0x534	EP4	IN: buffer available. OUT: buffer has data
15	0x538	EP6	IN: buffer available. OUT: buffer has data
16	0x53C	EP8	IN: buffer available. OUT: buffer has data
17	0x540	IBN	IN-Bulk-NAK (any IN endpoint)
18	0x544		Reserved
19	0x548	EP0PING	EP0 OUT was pinged and it NAK'd
20	0x54C	EP1PING	EP1 OUT was pinged and it NAK'd
21	0x550	EP2PING	EP2 OUT was pinged and it NAK'd
22	0x554	EP4PING	EP4 OUT was pinged and it NAK'd
23	0x558	EP6PING	EP6 OUT was pinged and it NAK'd
24	0x55C	EP8PING	EP8 OUT was pinged and it NAK'd
25	0x560	ERRLIMIT	Bus errors exceeded the programmed limit
26	0x564		Reserved
27	0x568		Reserved
28	0x56C		Reserved
29	0x570	EP2ISOERR	ISO EP2 OUT PID sequence error
30	0x574	EP4ISOERR	ISO EP4 OUT PID sequence error
31	0x578	EP6ISOERR	ISO EP6 OUT PID sequence error
32	0x57C	EP8ISOERR	ISO EP8 OUT PID sequence error

If autovectoring is enabled (AV2EN = 1 in the INTSET-UP register), the NX2LP-Flex substitutes its INT2VEC byte. Therefore, if the high byte ('page') of a jump-table address is preloaded at location 0x544, the automatically inserted INT2VEC byte at 0x545 directs the jump to the correct address out of the 27 addresses within the page.

FIFO/GPIF Interrupt (INT4)

Just as the USB Interrupt is shared among 27 individual USB-interrupt sources, the FIFO/GPIF interrupt is shared among 14 individual FIFO/GPIF sources. The FIFO/GPIF Interrupt, such as the USB Interrupt, can employ autovectoring. [Table 4](#) shows the priority and INT4VEC values for the 14 FIFO/GPIF interrupt sources.

Table 4. Individual FIFO/GPIF Interrupt Sources

Priority	INT4VEC Value	Source	Notes
1	0x580	EP2PF	Endpoint 2 programmable flag
2	0x584	EP4PF	Endpoint 4 programmable flag
3	0x588	EP6PF	Endpoint 6 programmable flag
4	0x58C	EP8PF	Endpoint 8 programmable flag
5	0x590	EP2EF	Endpoint 2 empty flag
6	0x594	EP4EF	Endpoint 4 empty flag
7	0x598	EP6EF	Endpoint 6 empty flag
8	0x59C	EP8EF	Endpoint 8 empty flag
9	0x5A0	EP2FF	Endpoint 2 full flag
10	0x5A4	EP4FF	Endpoint 4 full flag
11	0x5A8	EP6FF	Endpoint 6 full flag
12	0x5AC	EP8FF	Endpoint 8 full flag
13	0x5B0	GPIFDONE	GPIF operation complete
14	0x5B4	GPIFWF	GPIF waveform

If autovectoring is enabled (AV4EN = 1 in the INTSET-UP register), the NX2LP-Flex substitutes its INT4VEC byte. Therefore, if the high byte ('page') of a jump-table address is preloaded at location 0x554, the automatically inserted INT4VEC byte at 0x555 directs the jump to the correct address out of the 14 addresses within the page. When the ISR occurs, the NX2LP-Flex pushes the program counter to its stack and then jumps to address 0x553; it expects to find a 'jump' instruction to the ISR Interrupt service routine here.

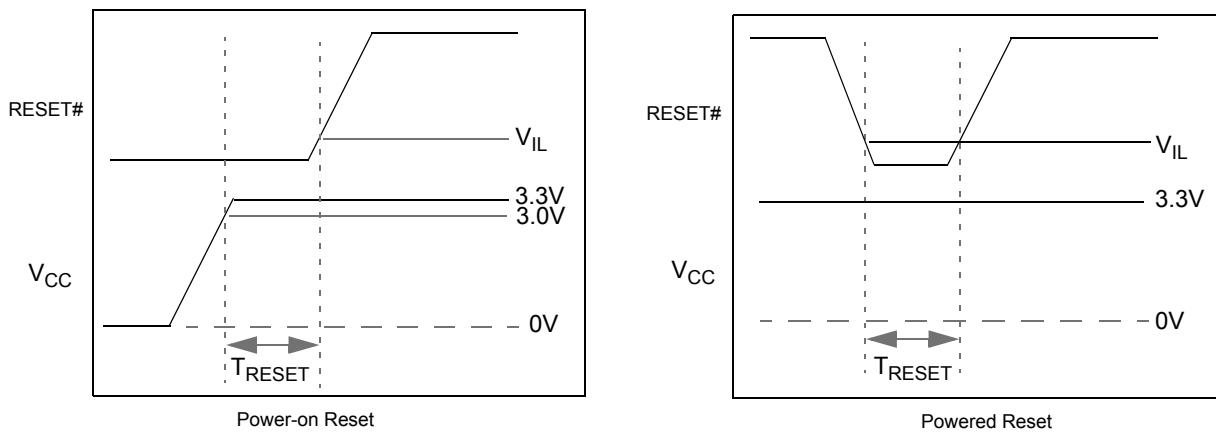
Reset and Wakeup

Reset Pin

The input pin RESET#, resets the NX2LP-Flex when asserted. This pin has hysteresis and is active LOW. When a crystal is

used as the clock source for the NX2LP-Flex, the reset period must enable the stabilization of the crystal and the PLL. This reset period should be approximately 5 ms after V_{CC} has reached 3.0V. If the crystal input pin is driven by a clock signal, the internal PLL stabilizes in 200 µs after V_{CC} has reached 3.0V^[1]. Figure 5 shows a POR condition and a reset applied during operation. A POR is defined as the time reset is asserted while power is being applied to the circuit. A powered reset is defined to be when the NX2LP-Flex has previously been powered on and operating and the RESET# pin is asserted.

For more information on power on reset implementation for the EZ-USB family of products, refer to the application note [EZ-USB FX2™/AT2™/SX2™](#).

Figure 5. Reset Timing Plots


Note

1. If the external clock is powered at the same time as the CY7C68033/CY7C68034 and has a stabilization wait period, it must be added to the 200 µs.

Table 5. Reset Timing Values

Condition	T _{RESET}
Power-on reset with crystal	5 ms
Power-on reset with external clock source	200 μ s + Clock stability time
Powered reset	200 μ s

Wakeup Pins

The 8051 puts itself and the rest of the chip into a power down mode by setting PCON.0 = 1. This stops the oscillator and PLL. When WAKEUP is asserted by external logic, the oscillator restarts, after the PLL stabilizes, and then the 8051 receives a wakeup interrupt. This applies whether or not NX2LP-Flex is connected to the USB.

The NX2LP-Flex exits the power down (USB suspend) state using one of the following methods:

- USB bus activity (if D+/D– lines are left floating, noise on these lines may indicate activity to the NX2LP-Flex and initiate a wakeup).
- External logic asserts the WAKEUP pin
- External logic asserts the PA3/WU2 pin.

The second wakeup pin, WU2, can also be configured as a GPIO pin. This enables a simple external R-C network to be used as a periodic wakeup source. Note that WAKEUP is, by default, active LOW.

Program/Data RAM

Internal ROM/RAM Size

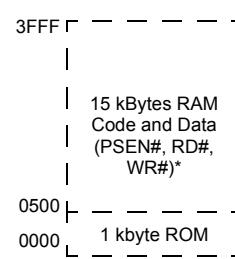
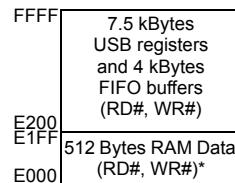
The NX2LP-Flex has 1 kBytes ROM and 15 kBytes of internal program/data RAM, where PSEN#/RD# signals are internally ORed to enable the 8051 to access it as both program and data memory. No USB control registers appear in this space.

Internal Code Memory

This mode implements the internal block of RAM (starting at 0x0500) as combined code and data memory, as shown in Figure 6.

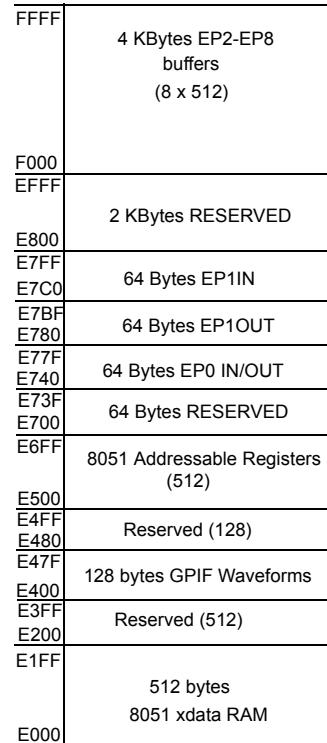
Only the internal and scratch pad RAM spaces have the following access:

- USB download (only supported by the Cypress manufacturing tool)
- Setup data pointer
- NAND boot access.

Figure 6. Internal Code Memory


*SUDPTR, USB download, NAND boot access

Register Addresses

Figure 7. Internal Register Addresses


Endpoint RAM

Size

- 3 × 64 bytes (Endpoints 0 and 1)
- 8 × 512 bytes (Endpoints 2, 4, 6, 8)

Organization

- EP0
 - Bidirectional endpoint zero, 64-byte buffer
- EP1IN, EP1OUT
 - 64-byte buffers, bulk or interrupt
- EP2,4,6,8
 - Eight 512-byte buffers, bulk, interrupt, or isochronous.
 - EP4 and EP8 can be double buffered, while EP2 and 6 can be either double, triple, or quad buffered.

For high speed endpoint configuration options, see [Figure 8](#).

Setup Data Buffer

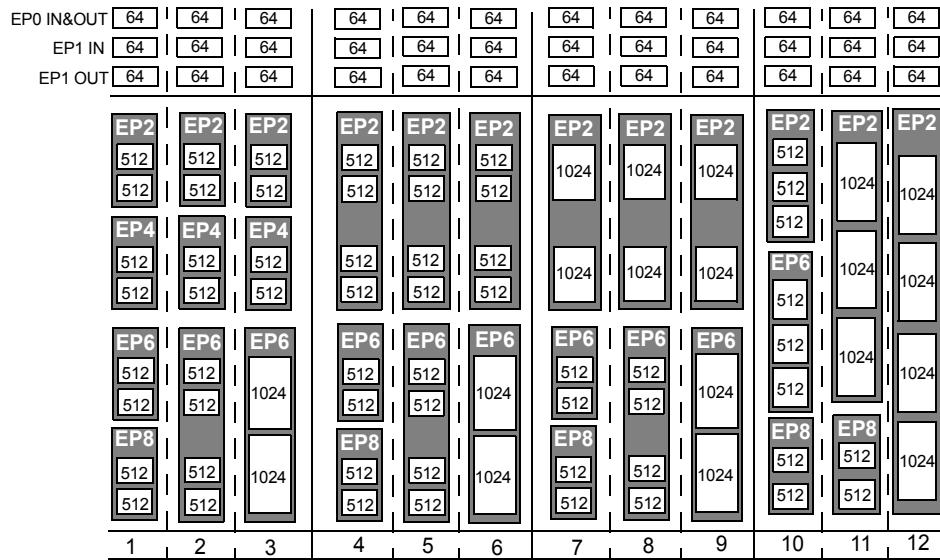
A separate 8-byte buffer at 0xE6B8-0xE6BF holds the setup data from a CONTROL transfer.

Endpoint Configurations (High Speed Mode)

Endpoints 0 and 1 are the same for every configuration. Endpoint 0 is the only control endpoint, and endpoint 1 can be either bulk or interrupt. The endpoint buffers can be configured in any 1 of the 12 configurations shown in the vertical columns. When operating in full speed bulk mode, only the first 64 bytes of each buffer are used. For example, in high speed the max packet size is 512 bytes, but in full speed it is 64 bytes. Even though a buffer is configured to be a 512 byte buffer, in full speed only the first 64 bytes are used. The unused endpoint buffer space is not available for other operations. The following is an example endpoint configuration:

EP2–1024 double buffered; EP6–512 quad buffered (column 8 in [Figure 8](#)).

Figure 8. Endpoint Configuration



Default Full Speed Alternate Settings

Table 6. Default Full Speed Alternate Settings^[1, 2]

Alternate Setting	0	1	2	3
ep0	64	64	64	64
ep1out	0	64 bulk	64 int	64 int
ep1in	0	64 bulk	64 int	64 int
ep2	0	64 bulk out (2×)	64 int out (2×)	64 iso out (2×)
ep4	0	64 bulk out (2×)	64 bulk out (2×)	64 bulk out (2×)
ep6	0	64 bulk in (2×)	64 int in (2×)	64 iso in (2×)
ep8	0	64 bulk in (2×)	64 bulk in (2×)	64 bulk in (2×)

1. '0' means 'not implemented.'

2. '2×' means 'double buffered.'

Default High Speed Alternate Settings

Table 7. Default High Speed Alternate Settings^[1, 2]

Alternate Setting	0	1	2	3
ep0	64	64	64	64
ep1out	0	512 bulk ^[3]	64 int	64 int
ep1in	0	512 bulk ^[3]	64 int	64 int
ep2	0	512 bulk out (2×)	512 int out (2×)	512 iso out (2×)
ep4	0	512 bulk out (2×)	512 bulk out (2×)	512 bulk out (2×)
ep6	0	512 bulk in (2×)	512 int in (2×)	512 iso in (2×)
ep8	0	512 bulk in (2×)	512 bulk in (2×)	512 bulk in (2×)

1. '0' means 'not implemented.'

2. '2×' means 'double buffered.'

3. Even though these buffers are 64 bytes, they are reported as 512 for USB 2.0 compliance. The user must never transfer packets larger than 64 bytes to EP1.

External FIFO Interface

Architecture

The NX2LP-Flex slave FIFO architecture has eight 512-byte blocks in the endpoint RAM that directly serve as FIFO memories, and are controlled by FIFO control signals (such as SLCS#, SLRD, SLWR, SLOE, PKTEND, and flags).

In operation, some of the eight RAM blocks fill or empty from the SIE, while the others are connected to the I/O transfer logic. The transfer logic takes two forms: the GPIF for internally generated control signals or the slave FIFO interface for externally controlled transfers.

Master/Slave Control Signals

The NX2LP-Flex endpoint FIFOs are implemented as eight physically distinct 256x16 RAM blocks. The 8051/SIE can switch any of the RAM blocks between two domains, the USB (SIE) domain and the 8051-I/O Unit domain. This switching is done virtually instantaneously, giving essentially zero transfer time between 'USB FIFOs' and 'Slave FIFOs.' Since they are physically the same memory, no bytes are actually transferred between buffers.

At any time, some RAM blocks are filling/emptying with USB data under SIE control, while other RAM blocks are available to the 8051 and/or the I/O control unit. The RAM blocks operate as single-port in the USB domain and dual-port in the 8051-I/O domain. The blocks can be configured as single, double, triple, or quad buffered as previously shown.

The I/O control unit implements either an internal-master (M for master) or external-master (S for Slave) interface.

In master (M) mode, the GPIF internally controls FIFOADR[1:0] to select a FIFO. The two RDY pins can be used as flag inputs from an external FIFO or other logic if desired. The GPIF can be run from an internally derived clock (IFCLK), at a rate that transfers data up to 96 Megabytes/s (48 MHz IFCLK with 16-bit interface).

In slave (S) mode, the NX2LP-Flex accepts an internally derived clock (IFCLK, max. frequency 48 MHz) and SLCS#, SLRD, SLWR, SLOE, PKTEND signals from external logic. Each endpoint can individually be selected for byte or word operation

by an internal configuration bit and a Slave FIFO output enable signal SLOE enables data of the selected width. External logic must ensure that the output enable signal is inactive when writing data to a slave FIFO. The slave interface must operate asynchronously, where the SLRD and SLWR signals act directly as strobes, rather than a clock qualifier as in a synchronous mode. The signals SLRD, SLWR, SLOE and PKTEND are gated by the signal SLCS#.

GPIF and FIFO Clock Rates

An 8051 register bit selects one of two frequencies for the internally supplied interface clock: 30 MHz and 48 MHz. A bit within the IFCONFIG register inverts the IFCLK signal.

The default NAND firmware image implements a 48 MHz internally supplied interface clock. The NAND boot logic uses the same configuration to implement 100-ns timing on the NAND bus to support proper detection of all NAND Flash types.

GPIF

The GPIF is a flexible 8- or 16-bit parallel interface driven by a user-programmable finite state machine. It enables the NX2LP-Flex to perform local bus mastering and can implement a wide variety of protocols such as 8-bit NAND interface, printer parallel port, and Utopia. The default NAND firmware and boot logic uses GPIF functionality to interface with NAND Flash.

The GPIF on the NX2LP-Flex features three programmable control outputs (CTL) and two general purpose ready inputs (RDY). The GPIF data bus width can be 8 or 16 bits. Because the default NAND firmware image implements an 8-bit data bus and up to eight chip enable pins on the GPIF ports, it is recommended that designs based upon the default firmware image also use an 8-bit data bus.

Each GPIF vector defines the state of the control outputs and determines what state a ready input (or multiple inputs) must be before proceeding. The GPIF vector can be programmed to advance a FIFO to the next data value, advance an address, and so on. A sequence of the GPIF vectors make up a single waveform that is executed to perform the desired data move between the NX2LP-Flex and the external device.

Three Control OUT Signals

The NX2LP-Flex exposes three control signals, CTL[2:0]. CTLx waveform edges can be programmed to make transitions as fast as once per clock (20.8 ns using a 48 MHz clock).

Two Ready IN Signals

The 8051 programs the GPIF unit to test the RDY pins for GPIF branching. The 56-pin package brings out two signals, RDY[1:0].

Long Transfer Mode

In GPIF master mode, the 8051 appropriately sets GPIF transaction count registers (GPIFTCB3, GPIFTCB2, GPIFTCB1, or GPIFTCB0) for unattended transfers of up to 2^{32} transactions. The GPIF automatically throttles data flow to prevent underflow or overflow until the full number of requested transactions complete. The GPIF decrements the value in these registers to represent the current status of the transaction.

ECC Generation^[2]

The NX2LP-Flex can calculate error correcting codes (ECCs) on data that passes across its GPIF or slave FIFO interfaces. There are two ECC configurations:

- Two ECCs, each calculated over 256 bytes (SmartMedia Standard)
- One ECC calculated over 512 bytes.

The following two ECC configurations are selected by the ECCM bit. The ECC can correct any one-bit error or detect any two-bit error.

ECCM = 0

Two 3-byte ECCs, each calculated over a 256-byte block of data. This configuration conforms to the SmartMedia Standard and is used by both the NAND boot logic and default NAND firmware image.

When any value is written to ECCRESET and data is then passed across the GPIF or slave FIFO interface, the ECC for the first 256 bytes of data is calculated and stored in ECC1. The ECC for the next 256 bytes of data is stored in ECC2. After the second ECC is calculated, the values in the ECCx registers do not change until ECCRESET is written again, even if more data is subsequently passed across the interface.

ECCM = 1

One 3-byte ECC calculated over a 512-byte block of data.

When any value is written to ECCRESET and data is then passed across the GPIF or slave FIFO interface, the ECC for the first 512 bytes of data is calculated and stored in ECC1; ECC2 is unused. After the ECC is calculated, the value in ECC1 does not change until ECCRESET is written again, even if more data is subsequently passed across the interface

Autopointer Access

NX2LP-Flex provides two identical autopointers. They are similar to the internal 8051 data pointers, but with an additional feature: they can optionally increment after every memory access. Also, the autopointers can point to any NX2LP-Flex register or endpoint buffer space.

I²C Controller

NX2LP has one I²C port that the 8051, once running uses to control external I²C devices. The I²C port operates in master mode only. The I²C port is disabled at startup and only available for use after the initial NAND access.

I²C Port Pins

The I²C pins SCL and SDA must have external 2.2-kΩ pull up resistors even if no EEPROM is connected to the NX2LP.

I²C Interface General-Purpose Access

The 8051 can control peripherals connected to the I²C bus using the I²CTL and I²DATA registers. NX2LP provides I²C master control only and is never an I²C slave.

Note

2. To use the ECC logic, the GPIF or Slave FIFO interface must be configured for byte-wide operation.

Pin Assignments

Figure 9 and *Figure 10* on page 15 identify all signals for the 56-pin NX2LP-Flex package.

Three modes of operation are available for the NX2LP-Flex: Port mode, GPIF Master mode, and Slave FIFO mode. These modes define the signals on the right edge of each column in *Figure 9*. The right-most column details the signal functionality from the

default NAND firmware image, which actually utilizes GPIF Master mode. The signals on the left edge of the 'Port' column are common to all modes of the NX2LP-Flex. The 8051 selects the interface mode using the IFCONFIG[1:0] register bits. Port mode is the power-on default configuration.

Figure 10 on page 15 details the pinout of the 56-pin package and lists pin names for all modes of operation. Pin names with an asterisk (*) feature programmable polarity.

Figure 9. Port and Signal Mapping

Port	GPIF Master	Slave FIFO	Default NAND Firmware Use
XTALIN	PD7 ↔ FD[15]	↔ FD[15]	↔ CE7#/GPIO7
XTALOUT	PD6 ↔ FD[14]	↔ FD[14]	↔ CE6#/GPIO6
RESET#	PD5 ↔ FD[13]	↔ FD[13]	↔ CE5#/GPIO5
WAKEUP#	PD4 ↔ FD[12]	↔ FD[12]	↔ CE4#/GPIO4
SCL	PD3 ↔ FD[11]	↔ FD[11]	↔ CE3#/GPIO3
SDATA	PD2 ↔ FD[10]	↔ FD[10]	↔ CE2#/GPIO2
	PD1 ↔ FD[9]	↔ FD[9]	↔ CE1#
	PD0 ↔ FD[8]	↔ FD[8]	↔ CE0#
	PB7 ↔ FD[7]	↔ FD[7]	↔ DD7
	PB6 ↔ FD[6]	↔ FD[6]	↔ DD6
	PB5 ↔ FD[5]	↔ FD[5]	↔ DD5
	PB4 ↔ FD[4]	↔ FD[4]	↔ DD4
	PB3 ↔ FD[3]	↔ FD[3]	↔ DD3
	PB2 ↔ FD[2]	↔ FD[2]	↔ DD2
	PB1 ↔ FD[1]	↔ FD[1]	↔ DD1
	PB0 ↔ FD[0]	↔ FD[0]	↔ DD0
	→ RDY0 → RDY1	→ SLRD → SLWR	→ R_B1# → R_B2#
	← CTL0 ← CTL1 ← CTL2	← FLAGA ← FLAGB ← FLAGC	← WE# ← RE0# ← RE1#
DPLUS	PA7 ↔ PA7	↔ FLAGD/SLCS#/PA7	↔ GPIO1
DMINUS	PA6 ↔ PA6	↔ PKTEND	↔ GPIO0
	PA5 ↔ PA5	↔ FIFOADR1	↔ WP_SW#
	PA4 ↔ PA4	↔ FIFOADR0	↔ WP_NF#
	WU2/PA3 ↔ PA3/WU2	↔ PA3/WU2	↔ LED2#
	PA2 ↔ PA2	↔ SLOE	→ LED1#
	INT1#/PA1 ↔ PA1/INT1#	↔ PA1/INT1#	↔ ALE
	INT0#/PA0 ↔ PA0/INT0#	↔ PA0/INT0#	↔ CLE
GPIO8	↔ GPIO8	↔ GPIO8	↔ GPIO8
GPIO9	↔ GPIO9	↔ GPIO9	↔ GPIO9

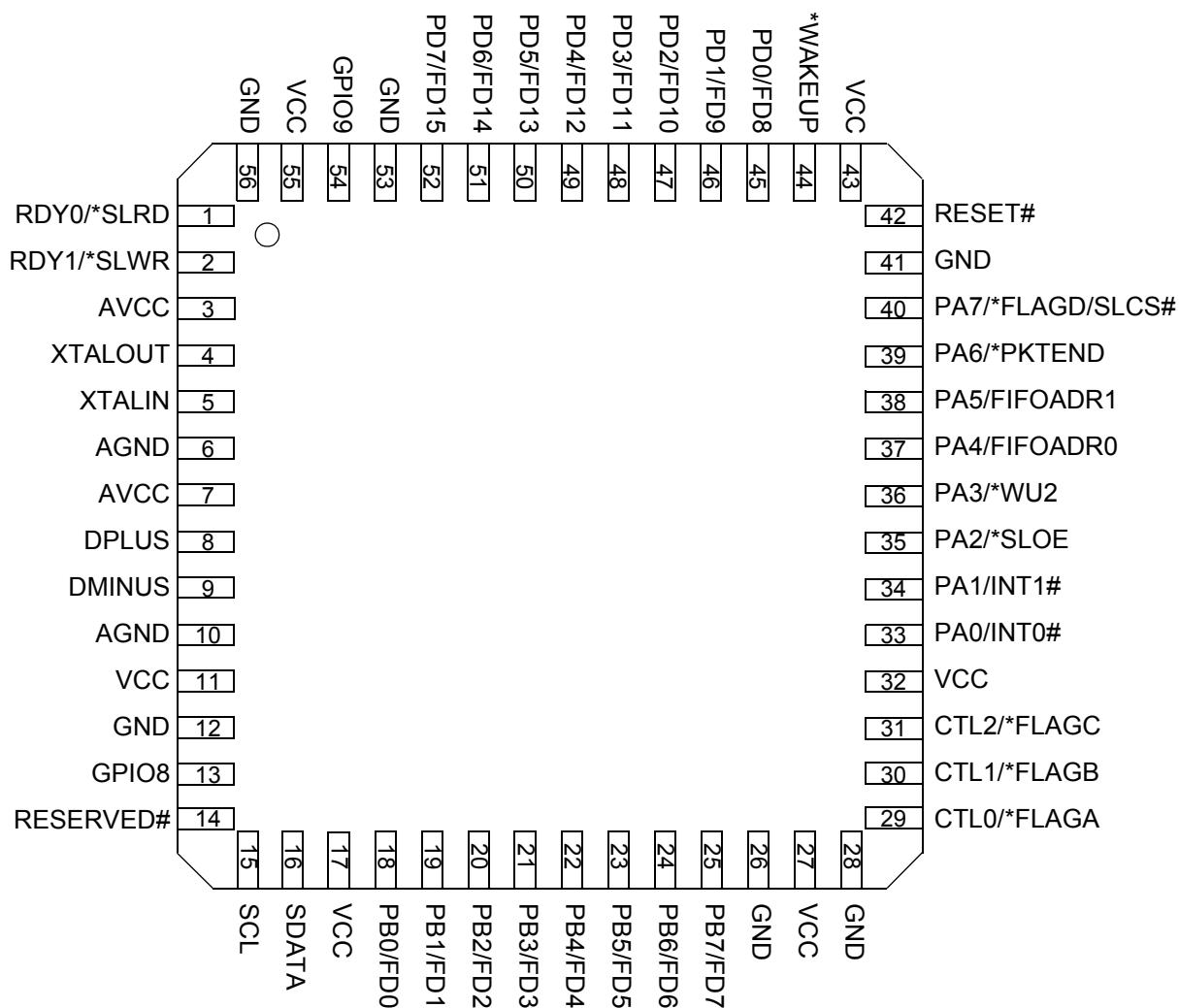
Figure 10. CY7C68033/CY7C68034 56-pin QFN Pin Assignment


Table 8. NX2LP-Flex Pin Descriptions [1]

56 QFN Pin Number	Default Pin Name	NAND Firmware Usage	Pin Type	Default State	Description
9	DMINUS	N/A	I/O/Z	Z	USB D– Signal. Connect to the USB D– signal.
8	DPLUS	N/A	I/O/Z	Z	USB D+ Signal. Connect to the USB D+ signal.
42	RESET#	N/A	Input	N/A	Active LOW Reset. Resets the entire chip. See section "Reset and Wakeup" on page 9 for more details.
5	XTALIN	N/A	Input	N/A	Crystal Input. Connect this signal to a 24 MHz parallel-resonant, fundamental mode crystal and load capacitor to GND. It is also correct to drive XTALIN with an external 24 MHz square wave derived from another clock source. When driving from an external source, the driving signal should be a 3.3V square wave.
4	XTALOUT	N/A	Output	N/A	Crystal Output. Connect this signal to a 24 MHz parallel-resonant, fundamental mode crystal and load capacitor to GND. If an external clock is used to drive XTALIN, leave this pin open.
54	GPIO9	GPIO9	O/Z	12 MHz	GPIO9 is a bidirectional I/O port pin.
1	RDY0 or SLRD	R_B1#	Input	N/A	Multiplexed pin whose function is selected by IFCONFIG[1:0]. RDY0 is a GPIF input signal. SLRD is the input-only read strobe with programmable polarity (FIFOPINPOLAR[3]) for the slave FIFOs connected to FD[7:0] or FD[15:0]. R_B1# is a NAND Ready/Busy input signal.
2	RDY1 or SLWR	R_B2#	Input	N/A	Multiplexed pin whose function is selected by IFCONFIG[1:0]. RDY1 is a GPIF input signal. SLWR is the input-only write strobe with programmable polarity (FIFOPINPOLAR[2]) for the slave FIFOs connected to FD[7:0] or FD[15:0]. R_B2# is a NAND Ready/Busy input signal.
29	CTL0 or FLAGA	WE#	O/Z	H	Multiplexed pin whose function is selected by IFCONFIG[1:0]. CTL0 is a GPIF control output. FLAGA is a programmable slave-FIFO output status flag signal. Defaults to programmable for the FIFO selected by the FIFOADR[1:0] pins. WE# is the NAND write enable output signal.
30	CTL1 or FLAGB	RE0#	O/Z	H	Multiplexed pin whose function is selected by IFCONFIG[1:0]. CTL1 is a GPIF control output. FLAGB is a programmable slave-FIFO output status flag signal. Defaults to FULL for the FIFO selected by the FIFOADR[1:0] pins. RE0# is a NAND read enable output signal.
31	CTL2 or FLAGC	RE1#	O/Z	H	Multiplexed pin whose function is selected by IFCONFIG[1:0]. CTL2 is a GPIF control output. FLAGC is a programmable slave-FIFO output status flag signal. Defaults to EMPTY for the FIFO selected by the FIFOADR[1:0] pins. RE1# is a NAND read enable output signal.

Table 8. NX2LP-Flex Pin Descriptions (continued)^[1]

56 QFN Pin Number	Default Pin Name	NAND Firmware Usage	Pin Type	Default State	Description
13	GPIO8	GPIO8	I/O/Z	I	GPIO8: is a bidirectional I/O port pin.
14	Reserved#	N/A	Input	N/A	Reserved. Connect to ground.
15	SCL	N/A	OD	Z	Clock for the I ² C interface. Connect to VCC with a 2.2K resistor, even if no I ² C peripheral is attached.
16	SDATA	N/A	OD	Z	Data for the I ² C interface. Connect to VCC with a 2.2K resistor, even if no I ² C peripheral is attached.
44	WAKEUP	Unused	Input	N/A	USB Wakeup. If the 8051 is in suspend, asserting this pin starts up the oscillator and interrupts the 8051 to allow it to exit the suspend mode. Holding WAKEUP asserted inhibits the EZ-USB chip from suspending. This pin has programmable polarity, controlled by WAKEUP[4].
Port A					
33	PA0 or INT0#	CLE	I/O/Z	I (PA0)	Multiplexed pin whose function is selected by PORTACFG[0] PA0 is a bidirectional I/O port pin. INT0# is the active-LOW 8051 INT0 interrupt input signal, which is either edge triggered (IT0 = 1) or level triggered (IT0 = 0). CLE is the NAND Command Latch Enable signal.
34	PA1 or INT1#	ALE	I/O/Z	I (PA1)	Multiplexed pin whose function is selected by PORTACFG[1] PA1 is a bidirectional I/O port pin. INT1# is the active-LOW 8051 INT1 interrupt input signal, which is either edge triggered (IT1 = 1) or level triggered (IT1 = 0). ALE is the NAND Address Latch Enable signal.
35	PA2 or SLOE	LED1#	I/O/Z	I (PA2)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PA2 is a bidirectional I/O port pin. SLOE is an input-only output enable with programmable polarity (FIFOPINPOLAR[4]) for the slave FIFOs connected to FD[7:0] or FD[15:0]. LED1# is the data activity indicator LED sink pin.
36	PA3 or WU2	LED2#	I/O/Z	I (PA3)	Multiplexed pin whose function is selected by WAKEUP[7] and OEA[3] PA3 is a bidirectional I/O port pin. WU2 is an alternate source for USB Wakeup , enabled by WU2EN bit (WAKEUP[1]) and polarity set by WU2POL (WAKEUP[4]). If the 8051 is in suspend and WU2EN = 1, a transition on this pin starts up the oscillator and interrupts the 8051 to allow it to exit the suspend mode. Asserting this pin inhibits the chip from suspending, if WU2EN = 1. LED2# is the chip activity indicator LED sink pin.
37	PA4 or FIFOADR0	WP_NF#	I/O/Z	I (PA4)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PA4 is a bidirectional I/O port pin. FIFOADR0 is an input-only address select for the slave FIFOs connected to FD[7:0] or FD[15:0]. WP_NF# is the NAND write-protect control output signal.
38	PA5 or FIFOADR1	WP_SW#	I/O/Z	I (PA5)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PA5 is a bidirectional I/O port pin. FIFOADR1 is an input-only address select for the slave FIFOs connected to FD[7:0] or FD[15:0]. WP_SW# is the NAND write-protect switch input signal.

Table 8. NX2LP-Flex Pin Descriptions (continued)^[1]

56 QFN Pin Number	Default Pin Name	NAND Firmware Usage	Pin Type	Default State	Description
39	PA6 or PKTEND	GPIO0 (Input)	I/O/Z	I (PA6)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] bits. PA6 is a bidirectional I/O port pin. PKTEND is an input used to commit the FIFO packet data to the endpoint and whose polarity is programmable via FIFOPIN-POLAR[5]. GPIO1 is a general purpose I/O signal.
40	PA7 or FLAGD or SLCS#	GPIO1 (Input)	I/O/Z	I (PA7)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and PORTACFG[7] bits. PA7 is a bidirectional I/O port pin. FLAGD is a programmable slave-FIFO output status flag signal. SLCS# gates all other slave FIFO enable/strobes GPIO0 is a general purpose I/O signal.
Port B					
18	PB0 or FD[0]	DD0	I/O/Z	I (PB0)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB0 is a bidirectional I/O port pin. FD[0] is the bidirectional FIFO/GPIF data bus. DD0 is a bidirectional NAND data bus signal.
19	PB1 or FD[1]	DD1	I/O/Z	I (PB1)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB1 is a bidirectional I/O port pin. FD[1] is the bidirectional FIFO/GPIF data bus. DD1 is a bidirectional NAND data bus signal.
20	PB2 or FD[2]	DD2	I/O/Z	I (PB2)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB2 is a bidirectional I/O port pin. FD[2] is the bidirectional FIFO/GPIF data bus. DD2 is a bidirectional NAND data bus signal.
21	PB3 or FD[3]	DD3	I/O/Z	I (PB3)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB3 is a bidirectional I/O port pin. FD[3] is the bidirectional FIFO/GPIF data bus. DD3 is a bidirectional NAND data bus signal.
22	PB4 or FD[4]	DD4	I/O/Z	I (PB4)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB4 is a bidirectional I/O port pin. FD[4] is the bidirectional FIFO/GPIF data bus. DD4 is a bidirectional NAND data bus signal.
23	PB5 or FD[5]	DD5	I/O/Z	I (PB5)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB5 is a bidirectional I/O port pin. FD[5] is the bidirectional FIFO/GPIF data bus. DD5 is a bidirectional NAND data bus signal.
24	PB6 or FD[6]	DD6	I/O/Z	I (PB6)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB6 is a bidirectional I/O port pin. FD[6] is the bidirectional FIFO/GPIF data bus. DD6 is a bidirectional NAND data bus signal.
25	PB7 or FD[7]	DD7	I/O/Z	I (PB7)	Multiplexed pin whose function is selected by IFCONFIG[1:0]. PB7 is a bidirectional I/O port pin. FD[7] is the bidirectional FIFO/GPIF data bus. DD7 is a bidirectional NAND data bus signal.
PORT D					
45	PD0 or FD[8]	CEO#	I/O/Z	I (PD0)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[8] is the bidirectional FIFO/GPIF data bus. CEO# is a NAND chip enable output signal.

Table 8. NX2LP-Flex Pin Descriptions (continued)^[1]

56 QFN Pin Number	Default Pin Name	NAND Firmware Usage	Pin Type	Default State	Description
46	PD1 or FD[9]	CE1#	I/O/Z	I (PD1)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[9] is the bidirectional FIFO/GPIF data bus. CE1# is a NAND chip enable output signal.
47	PD2 or FD[10]	CE2# or GPIO2	I/O/Z	I (PD2)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[10] is the bidirectional FIFO/GPIF data bus. CE2# is a NAND chip enable output signal. GPIO2 is a general purpose I/O signal.
48	PD3 or FD[11]	CE3# or GPIO3	I/O/Z	I (PD3)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[11] is the bidirectional FIFO/GPIF data bus. CE3# is a NAND chip enable output signal. GPIO3 is a general purpose I/O signal.
49	PD4 or FD[12]	CE4# or GPIO4	I/O/Z	I (PD4)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[12] is the bidirectional FIFO/GPIF data bus. CE4# is a NAND chip enable output signal. GPIO4 is a general purpose I/O signal.
50	PD5 or FD[13]	CE5# or GPIO5	I/O/Z	I (PD5)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[13] is the bidirectional FIFO/GPIF data bus. CE5# is a NAND chip enable output signal. GPIO5 is a general purpose I/O signal.
51	PD6 or FD[14]	CE6# or GPIO6	I/O/Z	I (PD6)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[14] is the bidirectional FIFO/GPIF data bus. CE6# is a NAND chip enable output signal. GPIO6 is a general purpose I/O signal.
52	PD7 or FD[15]	CE7# or GPIO7	I/O/Z	I (PD7)	Multiplexed pin whose function is selected by the IFCONFIG[1:0] and EPxFIFOFCFG.0 (wordwide) bits. FD[15] is the bidirectional FIFO/GPIF data bus. CE7# is a NAND chip enable output signal. GPIO7 is a general purpose I/O signal.

Power and Ground

3 7	AVCC	N/A	Power	N/A	Analog V_{CC} . Connect this pin to 3.3V power source. This signal provides power to the analog section of the chip.
6 10	AGND	N/A	Ground	N/A	Analog Ground . Connect to ground with as short a path as possible.
11 17 27 32 43 55	VCC	N/A	Power	N/A	V_{CC} . Connect to 3.3V power source.
12 26 28 41 53 56	GND	N/A	Ground	N/A	Ground .

1. Unused inputs should not be left floating. Tie either HIGH or LOW as appropriate. Outputs should only be pulled up or down to ensure signals at power up and in standby. Note also that no pins should be driven while the device is powered down.

Table 9. NX2LP-Flex Register Summary (continued)

Hex	Size	Name	Description	b7	b6	b5	b4	b3	b2	b1	b0	Default	Access
BF	1	GPIFSGLDAT LN0X ^[2]	GPIF Data L w/No Trigger	D7	D6	D5	D4	D3	D2	D1	D0	xxxxxxx	R
C0	1	SCON1 ^[2]	Serial Port 1 Control (bit addressable)	SM0_1	SM1_1	SM2_1	REN_1	TB8_1	RB8_1	TI_1	RI_1	00000000	RW
C1	1	SBUF1 ^[2]	Serial Port 1 Data Buffer	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
C2	6	reserved											
C8	1	T2CON	Timer/Counter 2 Control (bit addressable)	TF2	EXF2	RCLK	TCLK	EXEN2	TR2	CT2	CPRL2	00000000	RW
C9	1	reserved											
CA	1	RCAP2L	Capture for Timer 2, auto-reload, up-counter	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
CB	1	RCAP2H	Capture for Timer 2, auto-reload, up-counter	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
CC	1	TL2	Timer 2 reload L	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
CD	1	TH2	Timer 2 reload H	D15	D14	D13	D12	D11	D10	D9	D8	00000000	RW
CE	2	reserved											
D0	1	PSW	Program Status Word (bit addressable)	CY	AC	F0	RS1	RS0	OV	F1	P	00000000	RW
D1	7	reserved											
D8	1	EICON ^[2]	External Interrupt Control	SMOD1	1	ERESI	RESI	INT6	0	0	0	01000000	RW
D9	7	reserved											
E0	1	ACC	Accumulator (bit addressable)	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
E1	7	reserved											
E8	1	EIE ^[2]	External Interrupt Enable(s)	1	1	1	EX6	EX5	EX4	EI ^C	EUSB	11100000	RW
E9	7	reserved											
F0	1	B	B (bit addressable)	D7	D6	D5	D4	D3	D2	D1	D0	00000000	RW
F1	7	reserved											
F8	1	EIP ^[2]	External Interrupt Priority Control	1	1	1	PX6	PX5	PX4	PI ^C	PUSB	11100000	RW
F9	7	reserved											

1. The register can only be reset, it cannot be set.
2. SFRs not part of the standard 8051 architecture.
3. If no NAND is detected by the SIE then the default is 00000000.

R = all bits read-only

W = all bits write-only

r = read-only bit

w = write-only bit

b = both read/write bit

Absolute Maximum Ratings

Exceeding maximum ratings may impair the useful life of the device. These user guidelines are not tested.

Storage Temperature.....	-65°C to +150°C
Ambient Temperature with Power Supplied.....	0°C to +70°C
Supply Voltage to Ground Potential.....	-0.5 V to +4.0 V
DC Input Voltage to Any Input Pin	+5.25V ^[3]
DC Voltage Applied to Outputs in High Z State	-0.5V to V _{CC} + 0.5 V
Power Dissipation.....	300 mW

Static Discharge Voltage.....	> 2000 V
Max Output Current, per I/O port.....	10 mA

Operating Conditions

T _A (Ambient Temperature Under Bias).....	0°C to +70°C
Supply Voltage.....	+3.00 V to +3.60 V
Ground Voltage.....	0 V
F _{Osc} (Oscillator or Crystal Frequency)....	24 MHz ± 100 ppm (Parallel Resonant)

DC Characteristics

Table 10. DC Characteristics

Parameter	Description	Conditions	Min	Typ	Max	Unit
V _{CC}	Supply voltage		3.00	3.3	3.60	V
V _{CC} ramp up	0 to 3.3V		200			μs
V _{IH}	Input HIGH voltage		2		5.25	V
V _{IL}	Input LOW voltage		-0.5		0.8	V
V _{IH_X}	Crystal input HIGH voltage		2		5.25	V
V _{IL_X}	Crystal input LOW voltage		-0.5		0.8	V
I _I	Input leakage current	0 < V _{IN} < V _{CC}			±10	μA
V _{OH}	Output voltage HIGH	I _{OUT} = 4 mA	2.4			V
V _{OL}	Output LOW voltage	I _{OUT} = -4 mA			0.4	V
I _{OH}	Output current HIGH				4	mA
I _{OL}	Output current LOW				4	mA
C _{IN}	Input pin capacitance	Except D+/D-			10	pF
		D+/D-			15	pF
I _{SUSP}	Suspend current CY7C68034	Connected	300	380 ^[4]		μA
		Disconnected	100	150 ^[4]		μA
	Suspend current CY7C68033	Connected	0.5	1.2 ^[4]		mA
		Disconnected	0.3	1.0 ^[4]		mA
I _{CC}	Supply current	8051 running, connected to USB HS	43			mA
		8051 running, connected to USB FS	35			mA
I _{UNCONFIG}	Unconfigured current	Before bMaxPower granted by host	43			mA
T _{RESET}	Reset time after valid power	V _{CC} min = 3.0 V	5.0			ms
	Pin reset after powered on		200			μs

USB Transceiver

USB 2.0-compliant in full and high speed modes.

AC Electrical Characteristics

USB Transceiver

USB 2.0-compliant in full- and high speed modes.

Notes

- 3. Applying power to I/O pins when the chip is not powered is not recommended
- 4. Measured at Max V_{CC}, 25°C.

Slave FIFO Asynchronous Read

Figure 11. Slave FIFO Asynchronous Read Timing Diagram^[5]

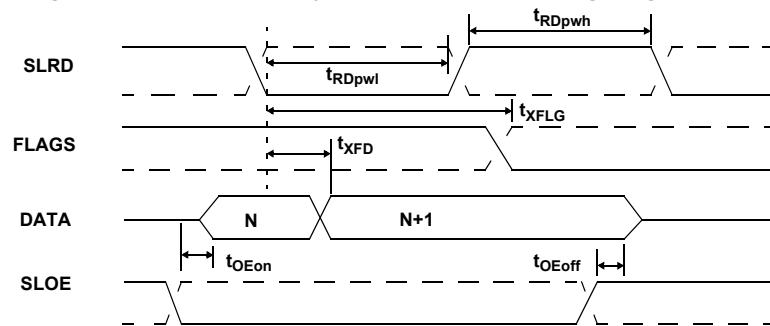


Table 11. Slave FIFO Asynchronous Read Parameters^[1]

Parameter	Description	Min	Max	Unit
t_{RDpwl}	SLRD pulse width LOW	50		ns
t_{RDpwh}	SLRD pulse width HIGH	50		ns
t_{XFLG}	SLRD to FLAGS output propagation delay		70	ns
t_{XFD}	SLRD to FIFO data output propagation delay		15	ns
t_{OEon}	SLOE turn on to FIFO data valid		10.5	ns
t_{OEoff}	SLOE turn off to FIFO data hold		10.5	ns

1. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.

Slave FIFO Asynchronous Write

Figure 12. Slave FIFO Asynchronous Write Timing Diagram^[5]

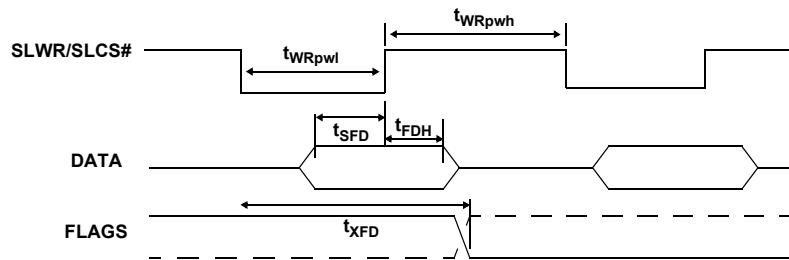


Table 12. Slave FIFO Asynchronous Write Parameters with Internally Sourced IFCLK^[1]

Parameter	Description	Min	Max	Unit
t_{WRpwl}	SLWR pulse LOW	50		ns
t_{WRpwh}	SLWR pulse HIGH	70		ns
t_{SFD}	SLWR to FIFO DATA setup time	10		ns
t_{FDH}	FIFO DATA to SLWR hold time	10		ns
t_{XFD}	SLWR to FLAGS output propagation delay		70	ns

1. GPIO asynchronous RDY_x signals have a minimum setup time of 50 ns when using internal 48 MHz IFCLK.

Notes

5. Dashed lines denote signals with programmable polarity.

Slave FIFO Asynchronous Packet End Strobe

Figure 13. Slave FIFO Asynchronous Packet End Strobe Timing Diagram^[2]

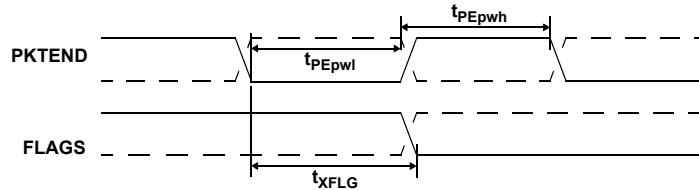


Table 13. Slave FIFO Asynchronous Packet End Strobe Parameters^[1]

Parameter	Description	Min	Max	Unit
t_{PEpwl}	PKTEND pulse width LOW	50		ns
t_{PWpwh}	PKTEND pulse width HIGH	50		ns
t_{XFLG}	PKTEND to FLAGS output propagation delay		115	ns

1. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.

Slave FIFO Output Enable

Figure 14. Slave FIFO Output Enable Timing Diagram^[5]

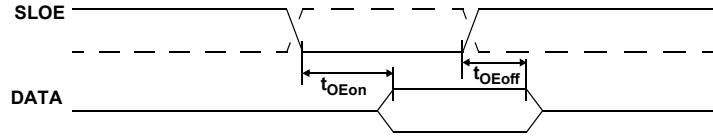


Table 14. Slave FIFO Output Enable Parameters

Parameter	Description	Min	Max	Unit
t_{OEon}	SLOE assert to FIFO DATA output		10.5	ns
t_{OEoff}	SLOE deassert to FIFO DATA hold		10.5	ns

Slave FIFO Address to Flags/Data

Figure 15. Slave FIFO Address to Flags/Data Timing Diagram^[5]

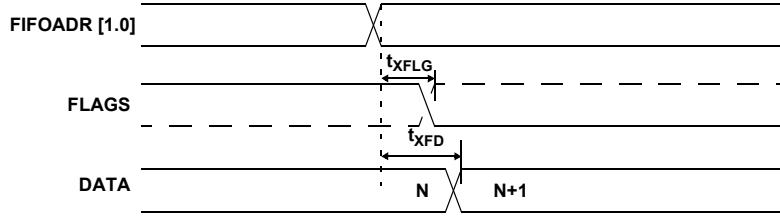


Table 15. Slave FIFO Address to Flags/Data Parameters

Parameter	Description	Min	Max	Unit
t_{XFLG}	FIFOADR[1:0] to FLAGS output propagation delay		10.7	ns
t_{XFD}	FIFOADR[1:0] to FIFODATA output propagation delay		14.3	ns

Slave FIFO Asynchronous Address

Figure 16. Slave FIFO Asynchronous Address Timing Diagram^[5]

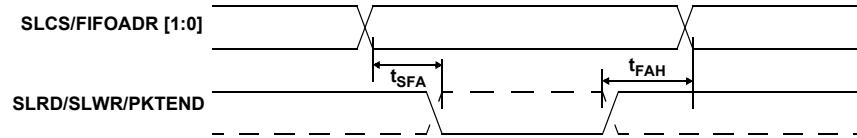


Table 16. Slave FIFO Asynchronous Address Parameters^[1]

Parameter	Description	Min	Max	Unit
t _{SFA}	FIFOADR[1:0] to SLRD/SLWR/PKTEND Setup Time	10		ns
t _{FAH}	RD/WR/PKTEND to FIFOADR[1:0] Hold Time	10		ns

1. Slave FIFO asynchronous parameter values use internal IFCLK setting at 48 MHz.

Sequence Diagram

Sequence Diagram of a Single and Burst Asynchronous Read

Figure 17. Slave FIFO Asynchronous Read Sequence and Timing Diagram^[5]

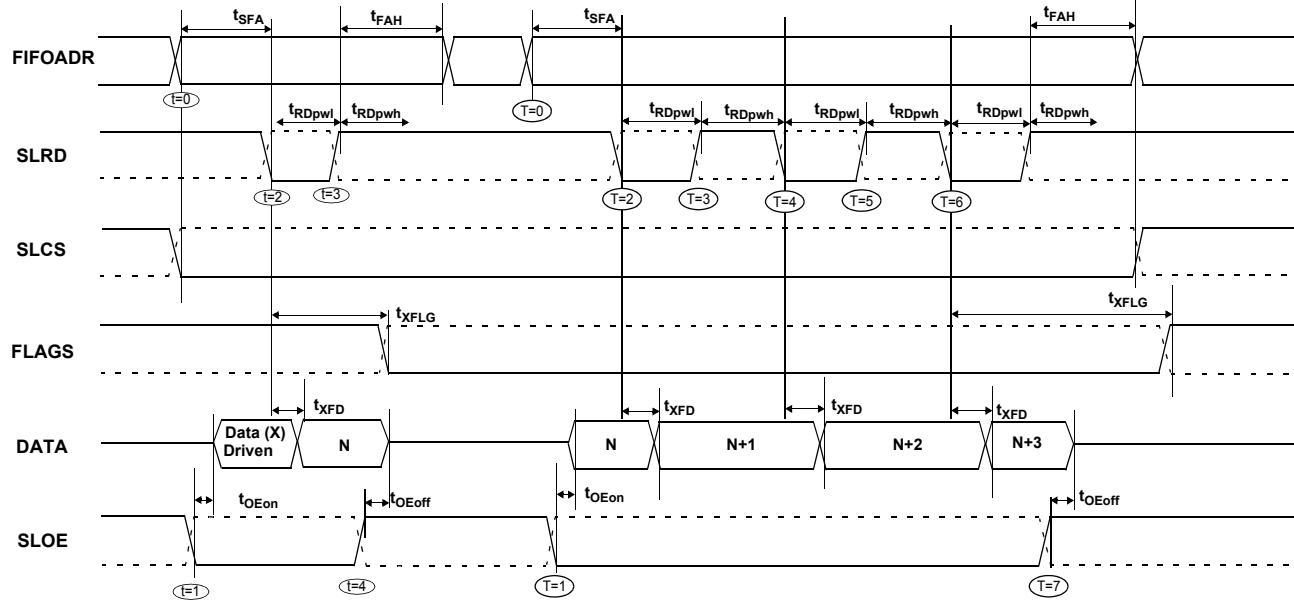


Figure 18. Slave FIFO Asynchronous Read Sequence of Events Diagram

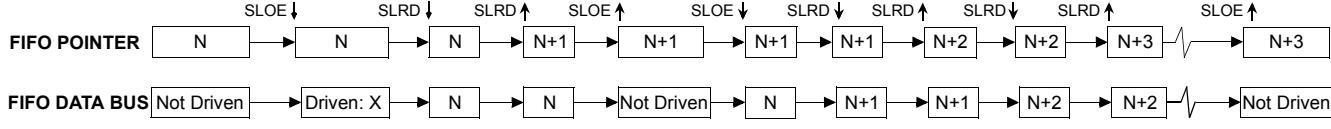


Figure 17 on page 30 shows the timing relationship of the SLAVE FIFO signals during an asynchronous FIFO read. It shows a single read followed by a burst read.

- At $t = 0$ the FIFO address is stable and the SLCS signal is asserted.
- At $t = 1$, SLOE is asserted. This results in the data bus being driven. The data that is driven on to the bus is previous data, it data that was in the FIFO from a prior read cycle.
- At $t = 2$, SLRD is asserted. The SLRD must meet the minimum active pulse of t_{RDpwl} and minimum de-active pulse width of t_{RDpwh} . If SLCS is used then, SLCS must be in asserted with SLRD or before SLRD is asserted (that is the SLCS and SLRD signals must both be asserted to start a valid read condition).

Sequence Diagram of a Single and Burst Asynchronous Write

Figure 19. Slave FIFO Asynchronous Write Sequence and Timing Diagram^[5]

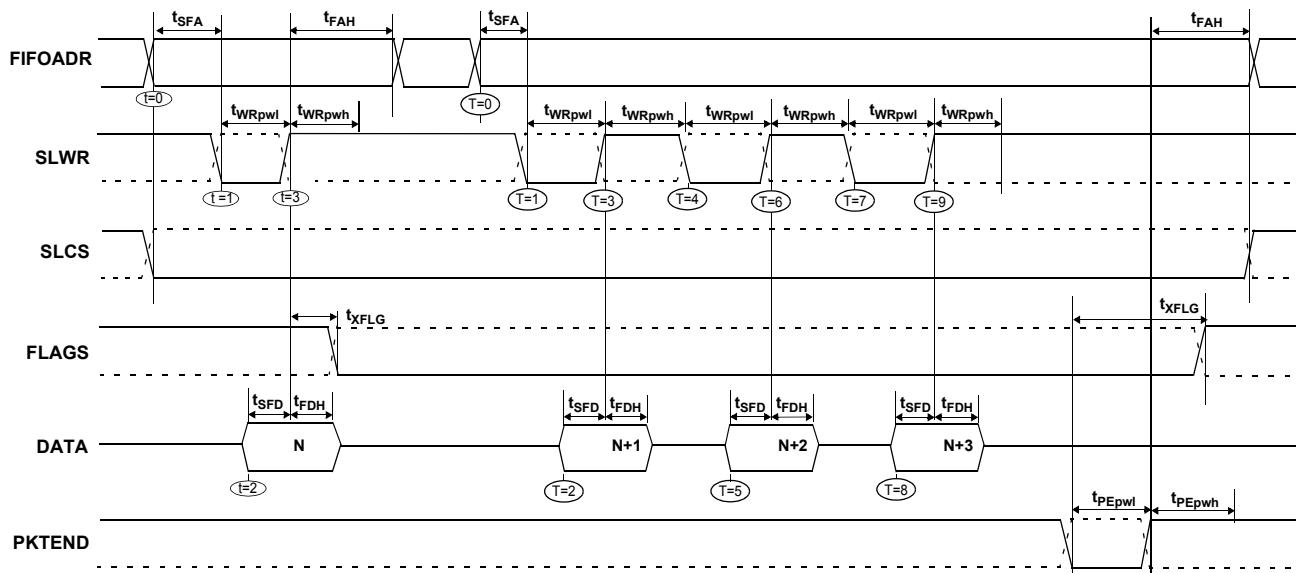


Figure 19 shows the timing relationship of the SLAVE FIFO write in an asynchronous mode. The diagram shows a single write followed by a burst write of three bytes and committing the 4-byte-short packet using PKTEND.

- At $t = 0$ the FIFO address is applied, insuring that it meets the setup time of t_{SFA} . If SLCS is used, it must also be asserted (SLCS may be tied low in some applications).
- At $t = 1$ SLWR is asserted. SLWR must meet the minimum active pulse of t_{WRpwl} and minimum de-active pulse width of t_{WRpwh} . If the SLCS is used, it must be in asserted with SLWR or before SLWR is asserted.
- At $t = 2$, data must be present on the bus t_{SFD} before the deasserting edge of SLWR.

At $t = 3$, deasserting SLWR causes the data to be written from the data bus to the FIFO and then increments the FIFO pointer.

- The data that is driven, after asserting SLRD, is the updated data from the FIFO. This data is valid after a propagation delay of t_{xFD} from the activating edge of SLRD. In **Figure 17**, data N is the first valid data read from the FIFO. For data to appear on the data bus during the read cycle (that is SLRD is asserted), SLOE MUST be in an asserted state. SLRD and SLOE can also be tied together.

The same sequence of events is also shown for a burst read marked with $T = 0$ through 5.

Note In burst read mode, during SLOE is assertion, the data bus is in a driven state and outputs the previous data. After SLRD is asserted, the data from the FIFO is driven on the data bus (SLOE must also be asserted) and then the FIFO pointer is incremented.

The FIFO flag is also updated after t_{XFLG} from the deasserting edge of SLWR.

The same sequence of events are shown for a burst write and is indicated by the timing marks of $T = 0$ through 5.

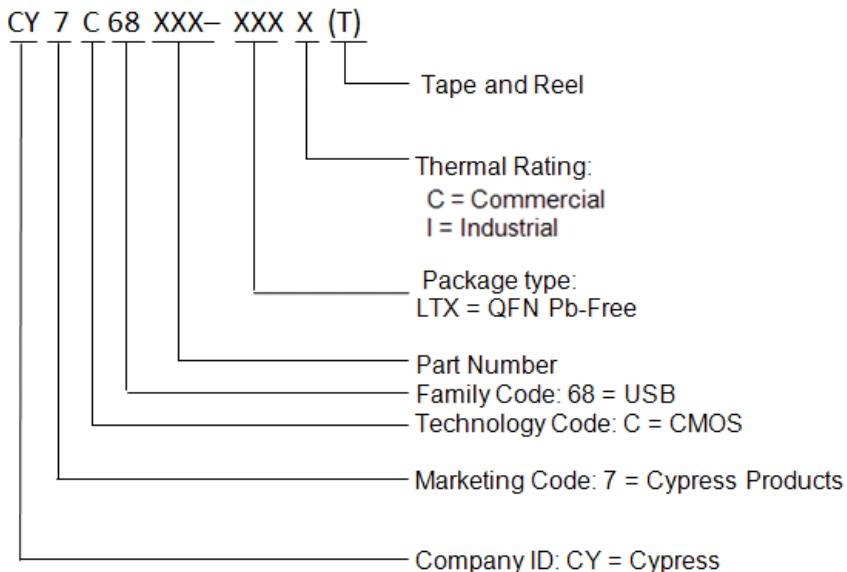
Note In the burst write mode, after SLWR is deasserted, the data is written to the FIFO and then the FIFO pointer is incremented to the next byte in the FIFO. The FIFO pointer is post incremented.

As shown in **Figure 19** after the four bytes are written to the FIFO and SLWR is deasserted, the short 4-byte packet can be committed to the host using the PKTEND. The external device should be designed to not assert SLWR and the PKTEND signal at the same time. It should be designed to assert the PKTEND after SLWR is deasserted and met the minimum de-asserted pulse width. The FIFOADDR lines are to be held constant during the PKTEND assertion.

Ordering Information

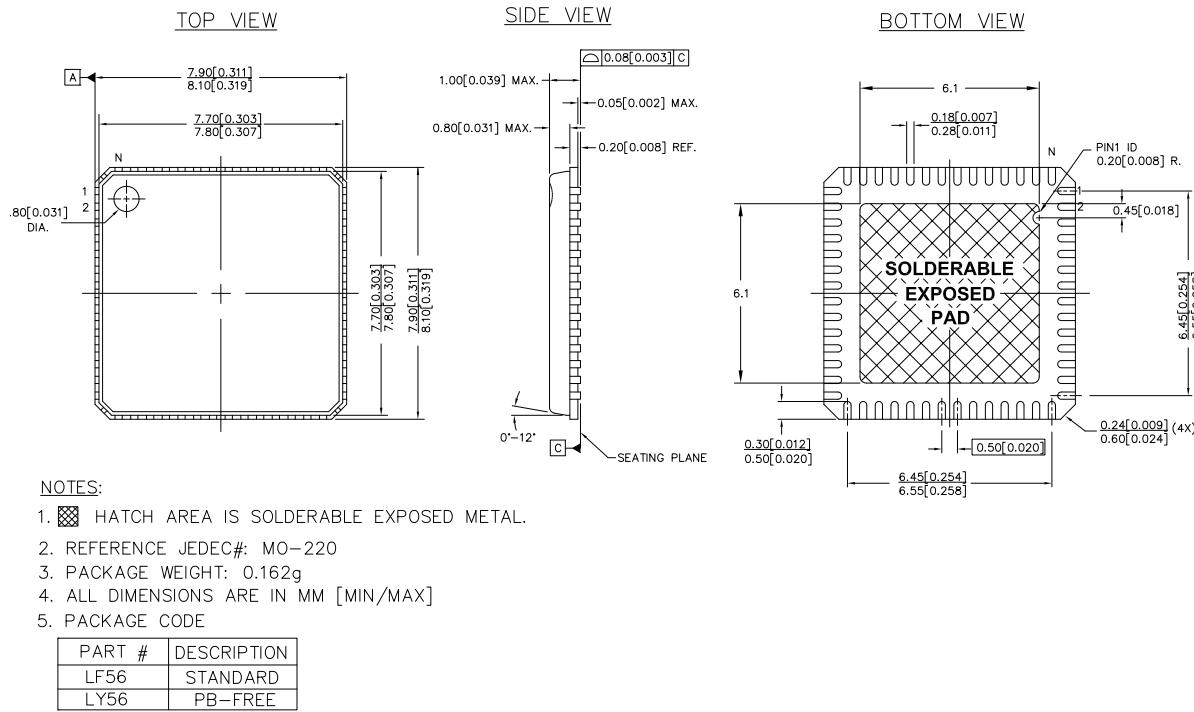
Ordering Code	Description
Silicon for battery-powered applications	
CY7C68034-56LTXC	8 X 8 mm, 56 QFN (Sawn)
Silicon for non-battery-powered applications	
CY7C68033-56LTXC	8 X 8 mm, 56 QFN (Sawn)
Development Kit	
CY3686	EZ-USB NX2LP-Flex Development Kit

Ordering Code Definitions

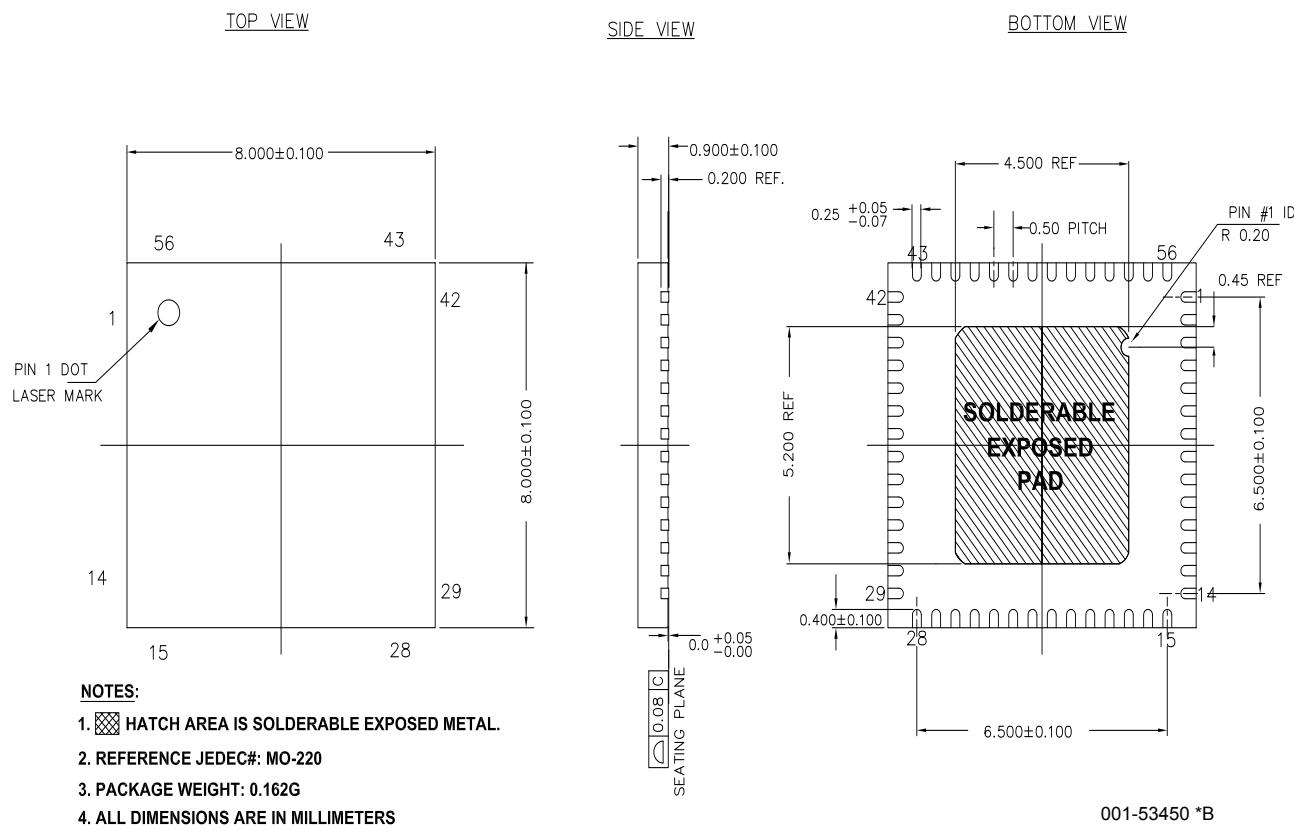


Package Diagram

Figure 20. 56-Pin QFN 8 x 8 mm LF56A



51-85144 *H

Figure 21. 56-Pin QFN (8 X 8 X 0.9 MM) - Sawn


PCB Layout Recommendations

Follow these recommendations^[6] to ensure reliable high performance operation:

- At least a four-layer impedance controlled boards is recommended to maintain signal quality.
- Specify impedance targets (ask your board vendor what they can achieve) to meet USB specifications.
- To control impedance, maintain trace widths and trace spacing.
- Minimize any stubs to avoid reflected signals.
- Connections between the USB connector shell and signal ground must be done near the USB connector.
- Bypass/flyback caps on VBUS, near connector, are recommended.
- DPLUS and DMINUS trace lengths should be kept to within 2 mm of each other in length, with preferred length of 20–30 mm.
- Maintain a solid ground plane under the DPLUS and DMINUS traces. Do not allow the plane to be split under these traces.
- No vias should be placed on the DPLUS or DMINUS trace routing unless absolutely necessary.
- Isolate the DPLUS and DMINUS traces from all other signal traces as much as possible.

Quad Flat Package No Leads (QFN) Package Design Notes

Electrical contact of the part to the printed circuit board (PCB) is made by soldering the leads on the bottom surface of the package to the PCB. Therefore, special attention is required to the heat transfer area below the package to provide a good thermal bond to the circuit board. Design a copper (Cu) fill into the PCB as a thermal pad under the package. Heat is transferred from the NX2LP-Flex to the PCB through the device's metal paddle on the bottom side of the package. It is then conducted from the PCB's thermal pad to the inner ground plane by a 5 x 5 array of vias. A via is a plated through hole in the PCB with a finished diameter of 13 mil. The QFN's metal die paddle must be soldered to the PCB's thermal pad. Solder mask is placed on the board top side over each via to resist solder flow into the via. The mask on the top side also minimizes outgassing during the solder reflow process.

For further information on this package design, refer to the application note [Application Note for Surface Mount Assembly of Amkor's Eutectic and Lead-Free CSP^l™ Wafer Level Chip Scale Packages](#). This application note provides detailed information on board mounting guidelines, soldering flow, rework process, and so on.

Note

6. Source for recommendations: [EZ-USB FX2™ PCB Design Recommendations](#) and [High Speed USB Platform Design Guidelines](#).

Figure 22 displays a cross-sectional area underneath the package. The cross section is of only one via. The solder paste template needs to be designed to enable at least 50% solder coverage. The thickness of the solder paste template should be 5 mil. It is recommended that 'No Clean' type 3 solder paste is used for mounting the part. Nitrogen purge is recommended during reflow.

Figure 23 is a plot of the solder mask pattern and Figure 24 displays an X-Ray image of the assembly (darker areas indicate solder).

Figure 22. Cross-section of the Area Underneath the QFN Package.

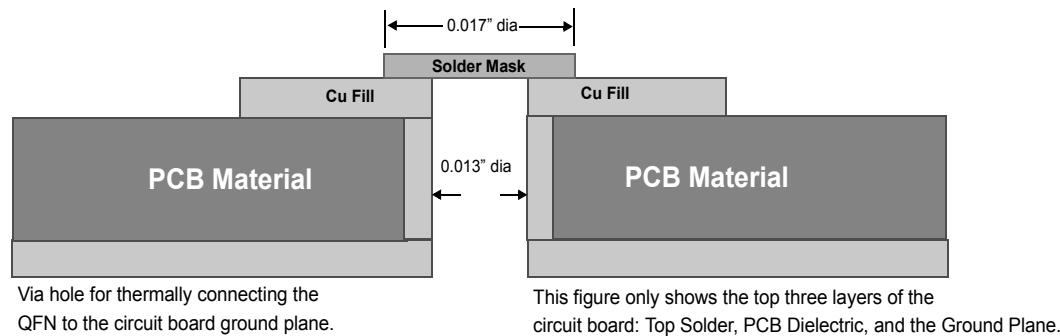


Figure 23. Plot of the Solder Mask (White Area)

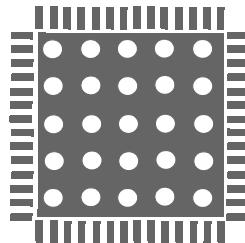
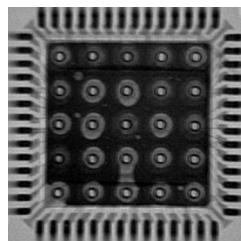


Figure 24. X-ray Image of the Assembly



Document History Page

Document Title: CY7C68033/CY7C68034 EZ-USB® NX2LP-Flex™ Flexible USB NAND Flash Controller
Document Number: 001-04247

REV.	ECN NO.	Submission Date	Orig. of Change	Description of Change
**	388499	See ECN	GIR	Preliminary draft
*A	394699	See ECN	XUT	Minor Change: Upload data sheet to external website. Publicly announcing the parts. No physical changes to document were made
*B	400518	See ECN	GIR	Took 'Preliminary' off the top of all pages. Corrected the first bulleted item. Corrected Figure 3-2 caption. Added new logo
*C	433952	See ECN	RGL	Added I ² C functionality
*D	498295	See ECN	KKU	Updated Data sheet format Changed In/Output reference from I/O to I/O Changed set-up to setup Changed IFCLK and CLKOUT pins to GPIO8 and GPIO9. Removed external IFCLK
*E	2717536	06/11/2009	DPT	Added 56 QFN (8 X 8 mm) package diagram and added CY7C68033-56LTXC and CY7C68034-56LTXC part information in the Ordering Information table
*F	2728424	07/02/2009	GNKK	Updated revision in the footer
*G	2896281	03/19/2010	ODC	Removed inactive parts. Updated package diagram. Added table of contents. Updated links in Sales, Solutions and Legal Information.
*H	2933818	05/18/2010	SHAH/AESA	Added Contents and Acronyms Updated Default NAND Firmware Features Formatted table footnotes.

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