

# Single-Ended Bus Transceiver

### **FEATURES**

- Operating Power Supply Range 6 V  $\leq$  V<sub>BAT</sub>  $\leq$  36 V
- Reverse Battery Protection Down to  $V_{BAT} \ge -24 \text{ V}$
- Standby Mode With Very Low Current Consumption  $I_{BAT(SB)} = 1 \mu A @ V_{DD} = 0.5 V$
- Low Quiescent Current in OFF Condition  $I_{BAT}$  = 120  $\mu A$  and  $I_{DD} \le 10 \ \mu A$
- ISO 9141 Compatible

- Overtemperature Shutdown Function For K Output
- Defined K Output OFF for Open GND
- Defined Receive Output Status for Open L or K Inputs
- Defined K Output OFF for TX Input Open
- 2-kV ESD
- Typical Transmit Speeds of 200 kBaud

### **DESCRIPTION**

The Si9243AEY is a monolithic bus transceiver designed to provide bidirectional serial communication in automotive diagnostic applications.

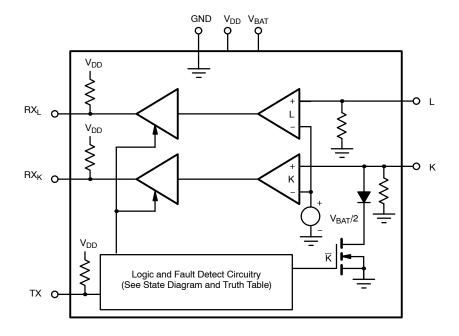
The device incorporates protection against overvoltages and short circuits to  $V_{BAT}$ . The transceiver pin is protected and can be driven beyond the  $V_{BAT}$  voltage.

The RX output is capable of driving CMOS or 1  $\times$  LSTTL load.

The Si9243AEY is built on the Vishay Siliconix BiC/DMOS process. This process supports bipolar transistors, CMOS, and DMOS. An epitaxial layer prevents latchup.

The Si9243AEY is available in a 8-pin SO package and operates over the automotive temperature range (-40 to 125°C). The Si9243AEY is available in both standard and lead (Pb)-free packages.

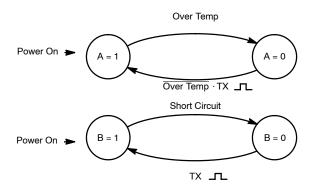
## PIN CONFIGURATION AND FUNCTIONAL BLOCK DIAGRAM



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# **OUTPUT TABLE AND STATE DIAGRAMS**



Note: Over Temp is an internal condition, not meant to be a logic signal.

INPU	STATE VARIABLE			UTPI TABL			
TX	L	Α	В	K	RXK	$RX_L$	Comments
0	0	1	1	0	0	0	
1	1	1	1	1	1	1	
0	1	1	1	0	0	1	
1	0	1	1	1	1	0	
Х	L	0	1	HiZ	K	L	Over Temp
0	L	1	0	HiZ	K	L	Short Circuit
1	1	1	1	1	1	1	Receive Mode
1	0	1	1	0	0	0	

X = "1" or "0"

HiZ = High Impedance State

# **ABSOLUTE MAXIMUM RATINGS**

Voltage Referenced to Ground	Voltage on V <sub>DD</sub> 7 V
Voltage On V <sub>BAT</sub> –24 V to 45 V	K Pin Only, Short Circuit Duration (to V <sub>BAT</sub> or GND) Continuous
Voltage K, L	Operating Temperature (T <sub>A</sub> ) –40 to 125°C
Voltage Difference V <sub>(VBAT, K, L)</sub>	Junction and Storage Temperature55 to 150°C
Voltage On Any Pin (Except V <sub>BAT</sub> , K, L) or Max. Current	Thermal Resistance $\Theta_{ extsf{JA}}$

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **RECOMMENDED OPERATING RANGE**

Voltage Referenced to Ground	K, L
V <sub>DD</sub>	Digital Inputs
V <sub>BAT</sub>	



Parameter   Symbol   V <sub>0.0</sub> = 4.5 to 5.5 V   Tempa   Minb   Typc   Maxb   Uri						Limits			1
Parameter   Symbol   V <sub>BAT</sub> = 6 to 36 V   Temp*   Min*   Typ*   Max*   Utransmitter and Logic Levels							–40 to 125°	С	Unit
TX Input Liow Voltage	Parameter	Symbol			<b>Temp</b> <sup>a</sup>	Min <sup>b</sup>	Typ <sup>c</sup>	Max <sup>b</sup>	
TX Input High Voltage	Transmitter and Logic Level	s					-		
TX Input High Voltage	TX Input Low Voltage	V <sub>ILT</sub>						1.5	.,
TX Input Pull-up Resistance   Pigx   VDo = 5.5 V, TX = 1.5 V, 3.5 V   Full   10   20   40   kt	TX Input High Voltage	V <sub>IHT</sub>			Full	3.5			V
K Transmit   R Couput Low Voltage   Volta   File	TX Input Capacitance <sup>d</sup>	C <sub>INT</sub>			Full			10	pF
K Output Low Voltage	TX Input Pull-up Resistance	R <sub>TX</sub>	V <sub>DD</sub> = 5.	5 V, TX = 1.5 V, 3.5 V	Full	10	20	40	kΩ
K Output Low Voltage	K Transmit	•	•						
R <sub>L</sub> = 510 Ω ± 5%, V <sub>BAT</sub> = 4.5 V   Full   V <sub>SAT</sub>   V <sub></sub>			$R_L$ = 510 $\Omega\pm 5\%$ , $V_{BAT}$ = 6 to 18 V		Full			0.2 V <sub>BAT</sub>	
K Output High Voltage	K Output Low Voltage	V <sub>OLK</sub>	$R_L = 1 \text{ k}\Omega \pm 5\%$ , $V_{BAT} = 16 \text{ to } 36 \text{ V}$		Full			0.2 V <sub>BAT</sub>	
$K \   \text{Output High Voltage} \qquad \qquad V_{OHK} \   \begin{array}{c ccccccccccccccccccccccccccccccccccc$			R <sub>L</sub> = 510					1.2	
K Output High Voltage					Full				V
R  <sub>L</sub> = 1 kΩ ±5%, V <sub>BAT</sub> = 16 to 36 V   Full   V <sub>BAT</sub>	K Output High Voltage	V <sub>OHK</sub>	11 0.0 22 ±0/0, VBAI - 4.0 10 V		ı uıı				
K Rise, Fall Times	, 5 5		$R_L$ = 1 k $\Omega$ ±5%, $V_{BAT}$ = 16 to 36 V		Full				
K Output Sink Resistance   Rsi   TX = 0 V	K Rise. Fall Times	t <sub>r</sub> . t <sub>f</sub>	5	See Test Circuit		· DAI		9.6	μS
Receiver   Receiver   Land K Input High Voltage   ViH   Full   ViH	<u> </u>				Full				Ω
Receiver   Land K Input High Voltage	<u>'</u>	Co	TX = 0 V		Full			20	pF
L and K Input Hysteresis <sup>c, d</sup> V <sub>HYS</sub> V <sub>H</sub>	Receiver		1						•
L and K Input Hysteresis <sup>c. d</sup> V <sub>HYS</sub> Full 0.0.05 V <sub>BAT</sub>	Land K Input High Voltage	\/			Eull	0.65			
L and K Input Hysteresis <sup>c. d</sup> V <sub>HYS</sub>   Full   V <sub>BAT</sub>   V <sub>BAT</sub>   V <sub>BAT</sub>   V <sub>BAT</sub>   Full   20 μ. μ. RX, and RXκ, Output Louronts   V <sub>BAT</sub>   V <sub>BAT</sub>   V <sub>BAT</sub>   Full   V <sub>BAT</sub>   V <sub>BAT</sub>   V <sub>BAT</sub>   Full   0.4   V <sub>BAT</sub>   V <sub>BA</sub>	Land K Input High Voltage	VIH			Full	$V_{BAT}$			V
$ \begin{array}{ c c c c } \hline Land K Input Currents & I_{IJH} & I_{IJH} & V_{IH} = V_{BAT} & Full & 20 & \mu \\ \hline RX_L and RX_K Output & VOLR & TX = 4 V & V_{ILK} N_{ILL} = 0.35 V_{BAT} & Full & 0.4 & 0.4 \\ \hline NX_L and RX_K Pull-up Resistance & R_{RX} & Full & 5 & 20 & kt \\ \hline RX_L and RX_K Pull-up Resistance & R_{RX} & Full & 5 & 20 & kt \\ \hline RX_K Turn On Delay & & & & & & & & & & & & & & & & & & &$	L and K Input Hysteresis <sup>c, d</sup>	V <sub>HYS</sub>			Full				
	·	l <sub>IH</sub>		V <sub>IH</sub> = V <sub>BAT</sub>	Full			20	μΑ
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		V <sub>OLR</sub>	TX = 4 V	$V_{ILK}$ , $V_{ILL} = 0.35 V_{BAT}$ $I_{OLR} = 1 \text{ mA}$	Full			0.4	V
$ \begin{array}{c} RX_{K} \ Turn \ On \ Delay \end{array} \qquad \begin{array}{c} C_{L} = 10 \ nF, \ See \ Test \ Circuit \\ \hline R_{L} = 1 \ k\Omega \pm 5\%, \ V_{BAT} = 16 \ to \ 36 \ V \\ C_{L} = 4.7 \ nF, \ See \ Test \ Circuit \\ \hline R_{L} = 10 \ nF, \ See \ Test \ Circuit \\ \hline R_{L} = 1 \ k\Omega \pm 5\%, \ V_{BAT} = 16 \ to \ 36 \ V \\ C_{L} = 4.7 \ nF, \ See \ Test \ Circuit \\ \hline R_{L} = 10 \ nF, \ R_$	RX <sub>L</sub> and RX <sub>K</sub> Pull-up Resistance	R <sub>RX</sub>			Full	5		20	kΩ
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		_			Full		3	10	- μs
$ RX_{K} \ Turn \ Off \ Delay \  \   \begin{array}{c} RL_{L} = 510 \ \Omega \ \pm 5\%, \ V_{BAT} = 6 \ to \ 18 \ V \\ C_{L} = 10 \ nF, \ See \ Est \ Circuit \  \   \end{array}   \begin{array}{c} Full \  \   & 3 \  \   & 10 \  \   \end{array}   \\ RL_{C} = 110 \ nF, \ See \ Est \ Circuit \  \   \end{array}     \\ RL_{C} = 14.7 \ nF, \ See \ Test \ Circuit \  \   \end{array}        \\ RL_{C} = 14.7 \ nF, \ See \ Test \ Circuit \  \    \end{array}              $	RX <sub>K</sub> Turn On Delay	t <sub>d(on)</sub>			Full		3	10	
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		t <sub>d(off)</sub>	$R_L$ = 510 $\Omega$ ±5%, $V_{BAT}$ = 6 to 18 $V$ $C_L$ = 10 nF, See Test Circuit		Full		3	10	
	RX <sub>K</sub> Turn Off Delay		$R_L$ = 1 k $\Omega$ ±5%, $V_{BAT}$ = 16 to 36 V $C_L$ = 4.7 nF, See Test Circuit		Full		3	10	
Bat Supply Current Off $ \begin{matrix} I_{BAT(off)} \end{matrix}  \begin{matrix} V_{IHT} \leq V_{TX}, V_{IHK} \leq V_{K}, V_{IHL} \leq V_{L} V_{BAT} \\ \leq 12  V \end{matrix} \qquad \qquad$	Supplies		1				I		
Bat Supply Current Off	Bat Supply Current On	I <sub>BAT(on)</sub>	TX =	0 V, V <sub>BAT</sub> ≤ 16 V	Full		1.2	3	mA
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Bat Supply Current Off	. ,			Full		120	220	^
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Bat Supply Current Standby	I <sub>BAT(SB)</sub>					< 1	10	μΑ
Logic Supply Current Off $I_{DD(off)}  V_{IHT} \leq V_{TX}, V_{IHK} \leq V_{K}, V_{IHL} \leq V_{L} V_{BAT} \qquad \text{Full} \qquad \qquad 10 \qquad \mu \text{ Miscellaneous}$ $TX \text{ Transmit Baud Rate} \qquad BR_{T} \qquad R_{L} = 510 \ \Omega, C_{L} = 10 \ nF \qquad Full \qquad 10.4 \qquad \text{Rate}$ $RX_{L} \text{ and } RX_{K} \text{ Receive Baud Rate}^{C} \qquad BR_{R} \qquad 6 \ V < V_{BAT} < 16 \ V, C_{RX} = 20 \ pF \qquad Full \qquad 200 \qquad \text{Receive Baud Rate}$ $TX \text{ Minimum Pulse Width}^{d, e} \qquad t_{TX} \qquad Full \qquad 1 \qquad \mu \text{ Minimum Pulse Width}^{d, e} \qquad t_{TX} \qquad Full \qquad 1 \qquad \mu \text{ Note Temperature Shutdown}^{d} \qquad T_{SHUT} \qquad Temperature Rising \qquad 160 \qquad 180 \qquad equation 100 \text{ Receive Baud Rate}^{d, e} \qquad equation 100  Receive$	Logic Supply Current On	` '			Full		1.4	2.3	mA
TX Transmit Baud Rate $BR_{T} \qquad R_{L} = 510 \ \Omega, \ C_{L} = 10 \ nF \qquad Full \qquad 10.4$ $RX_{L} \text{ and } RX_{K} \text{ Receive Baud Rate}^{c} \qquad BR_{R} \qquad 6 \ V < V_{BAT} < 16 \ V, \ C_{RX} = 20 \ pF \qquad Full \qquad 200$ $RX_{L} \text{ Transmission Frequency} \qquad f_{K-RXK} \qquad 6 \ V < V_{BAT} < 16 \ V, \ R_{K} = 510 \ \Omega, \ C_{K} \le 1.3 \ nF \qquad Full \qquad 50 \qquad 200 \qquad kH$ $TX \text{ Minimum Pulse Width}^{d, e} \qquad t_{TX} \qquad Full \qquad 1 \qquad \mu$ $Over \text{ Temperature Shutdown}^{d} \qquad T_{SHUT} \qquad Temperature \text{ Rising} \qquad 160 \qquad 180$					Full			10	μΑ
TX Transmit Baud Rate $BR_T \qquad R_L = 510~\Omega,~C_L = 10~nF \qquad Full \qquad 10.4 \qquad kBaud Rate \\ RX_L \text{ and } RX_K \text{ Receive Baud Rate}^c \qquad BR_R \qquad 6~V < V_{BAT} < 16~V,~C_{RX} = 20~pF \qquad Full \qquad 200 \qquad kBaud Rate \\ Transmission Frequency \qquad f_{K-RXK} \qquad 6~V < V_{BAT} < 16~V,~R_K = 510~\Omega,~C_K \le 1.3~nF \qquad Full \qquad 50 \qquad 200 \qquad kBaud Rate \\ TX \text{ Minimum Pulse Width}^{d,~e} \qquad t_{TX} \qquad \qquad Full \qquad 1 \qquad \qquad \mu \\ Over \text{ Temperature Shutdown}^d \qquad T_{SHUT} \qquad Temperature Rising \qquad 160 \qquad 180 \qquad \qquad 0 $	Miscellaneous	L	L		<u> </u>		L	1	
$\begin{array}{c ccccccccccccccccccccccccccccccccccc$		BR⊤	R <sub>I</sub> =	R <sub>1</sub> = 510 Ω C <sub>1</sub> = 10 nF		10.4			
$ \begin{array}{llllllllllllllllllllllllllllllllllll$		·					200		kBaud
TX Minimum Pulse Width <sup>d, e</sup> $t_{TX}$ Full 1 $\mu$ Over Temperature Shutdown <sup>d</sup> $t_{SHUT}$ Temperature Rising 160 180			_			50			kHz
Over Temperature Shutdown <sup>d</sup> T <sub>SHUT</sub> Temperature Rising 160 180			5 - VBAI 1 10 V, IIN - 010 32, OK = 1.0111						μS
•				Temperature Rising			180		L
	Temperature Shutdown Hysteresis <sup>c</sup>	T <sub>HYST</sub>	Tomperature Hong				30		°C

- Notes

  Room = 25°C, Cold and Hot = as determined by the operating temperature suffix.

  The algebraic convention whereby the most negative value is a minimum and the most positive a maximum, is used in this data sheet.

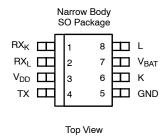
  Typical values are for DESIGN AID ONLY, not guaranteed nor subject to production testing.

  Guaranteed by design, not subject to production test.

  Minimum pulse width to reset a fault condition.



### **PIN CONFIGURATION**



ORDERING INFORMATION					
Part Number	Temperature Range				
Si9243AEY-T1	−40 to 125°C				
Si9243AEY-T1—E3 (Lead (Pb)-Free)					

PIN DESCRIPTION						
Pin Number	Symbol	Description				
1	RX <sub>K</sub>	K Receiver, Output				
2	$RX_L$	L Receiver, Output				
3	$V_{DD}$	Positive Power Supply				
4	TX	Transmit, Input				
5	GND	Ground Connection				
6	K	K Transmit/Receive, Bidirectional				
7	V <sub>BAT</sub>	Battery Power Supply				
8	L	L Transmit, Input				

### **FUNCTIONAL DESCRIPTION**

The Si9243AEY can be either in transmit or receive mode and it contains over temperature, and short circuit  $V_{BAT}$  fault detection circuits.

The voltage on the K and L pins are internally compared to  $V_{BAT/2}$ . If the voltage on the K or L pin is less than  $V_{BAT/2}$  then  $RX_K$  or  $RX_L$  output will be "low." If the voltage on the K or L pin is greater than  $V_{BAT/2}$  then  $RX_K$  or  $RX_L$  output will be "high.

In order to be in transmit mode, TX must be set "low." The TX signal is then internally inverted and turns the MOSFET on, causing the K pin to be "low." In transmit mode, the processor

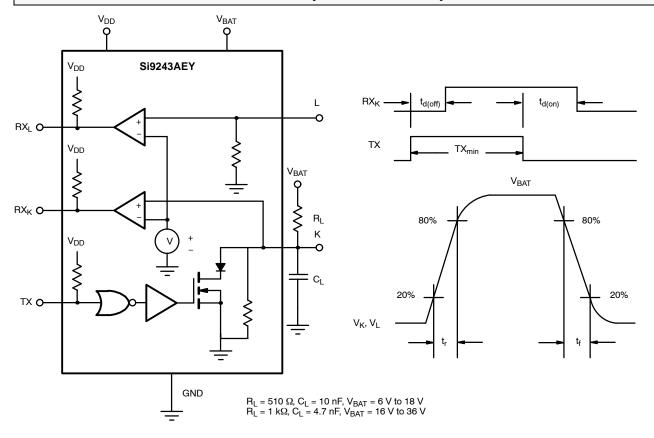
monitors the RX $_{\rm K}$  and TX. When the two mirror each other there is no fault. In the event of over temperature, or short circuit to V $_{\rm BAT}$ , the Si9243AEY will turn off the K output to protect the IC. The K pin will stay in high impedance and RX $_{\rm K}$  will follow the K pin. The fault will be reset when TX is toggled high. RX $_{\rm K}$ , RX $_{\rm L}$  and TX pins have internal pull up resistor to V $_{\rm DD}$  while K and L pins have internal pull down resistors. When any one of the TX, V $_{\rm BAT}$  or GND pins is open the K output is off.

When the TX pin is set "high" the Si9243AEY is in receive mode and the internal MOSFET is turned off.  $RX_L$  and  $RX_K$  outputs will follow L and K inputs respectively.

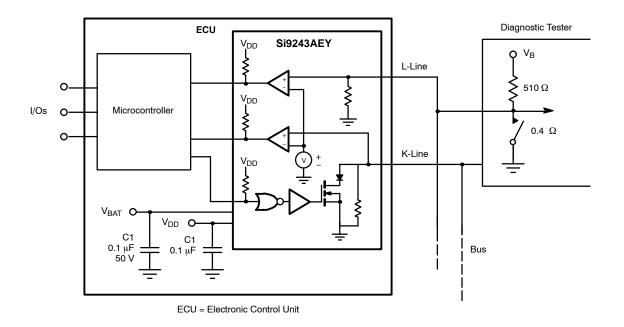




# TEST CIRCUIT AND TIMING DIAGRAMS (TRANSMIT ONLY)



# **APPLICATION CIRCUIT**



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Vishay

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