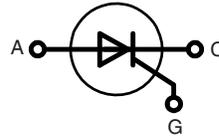


## Phase Control Thyristors Electrically Isolated Tab

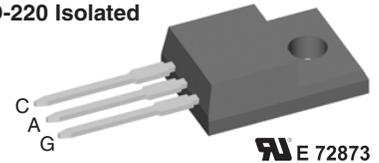
$$V_{RRM} = 800-1200 \text{ V}$$

$$I_{T(AV)M} = 16 \text{ A}$$

$V_{RSM}$	$V_{RRM}$	Type
$V_{DSM}$	$V_{DRM}$	
V	V	
800	800	CS 22-08io1M
1200	1200	CS 22-12io1M



TO-220 Isolated



A = Anode, C = Cathode, G = Gate  
Tab = Isolated

Symbol	Conditions	Maximum Ratings	
$I_{T(AV)M}$	$T_C = 85^\circ\text{C}$ 180° sine <sup>①</sup>	16	A
	$T_A = 25^\circ\text{C}$ 180° sine <sup>②</sup>	2.5	A
$I_{TSM}$	$T_{VJ} = 45^\circ\text{C}$	$t = 10 \text{ ms}$ (50 Hz), sine	300 A
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms}$ (60 Hz), sine	320 A
	$T_{VJ} = T_{VJM}$	$t = 10 \text{ ms}$ (50 Hz), sine	260 A
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms}$ (60 Hz), sine	280 A
$I^2t$	$T_{VJ} = 45^\circ\text{C}$	$t = 10 \text{ ms}$ (50 Hz), sine	450 A <sup>2</sup> s
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms}$ (60 Hz), sine	430 A <sup>2</sup> s
	$T_{VJ} = T_{VJM}$	$t = 10 \text{ ms}$ (50 Hz), sine	340 A <sup>2</sup> s
	$V_R = 0 \text{ V}$	$t = 8.3 \text{ ms}$ (60 Hz), sine	330 A <sup>2</sup> s
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50\text{Hz}$ , $t_p = 200\mu\text{s}$	repetitive, $I_T = 20 \text{ A}$	150 A/ $\mu\text{s}$
	$V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.08 \text{ A}$ $di_G/dt = 0.08 \text{ A}/\mu\text{s}$	non repetitive, $I_T = I_{T(AV)M}$	500 A/ $\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ , $V_{DR} = \frac{2}{3} V_{DRM}$ $R_{GK} = \infty$ , method 1 (linear voltage rise)		500 V/ $\mu\text{s}$
$P_{GM}$	$T_{VJ} = T_{VJM}$	$t_p = 30 \mu\text{s}$	10 W
	$I_T = I_{T(AV)M}$	$t_p = 300 \mu\text{s}$	5 W
$P_{GAV}$			0.5 W
$V_{RGM}$			10 V
$T_{VJ}$			-40...+150 °C
$T_{VJM}$			150 °C
$T_{stg}$			-40...+125 °C
$M_d$	Mounting torque	M 3 or UNC 4-40	0.5-0.8 Nm
<b>Weight</b>			3 g

<sup>①</sup> mounted on heatsink

<sup>②</sup> without heatsink

Data according to IEC 60747

### Features

- Thyristor for frequencies up to 400Hz
- International standard package
- Epoxy meets UL 94V-0
- High performance glass passivated chip
- Long-term stability of leakage current and blocking voltage
- Plastic overmolded tab for electrical isolation

### Applications

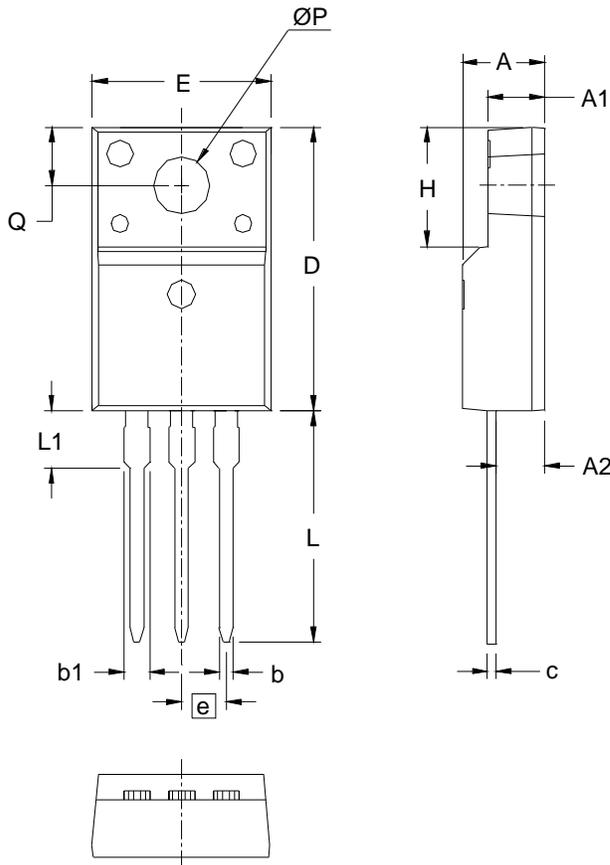
- Motor control
- Power converter
- AC power controller
- Light and temperature control
- SCR for inrush current limiting in power supplies or AC drive

### Advantages

- Space and weight savings
- Simple mounting

Symbol	Conditions	Characteristic Values	
$I_R, I_D$	$T_{VJ} = T_{VJM}, V_R = V_{RRM}, V_D = V_{DRM}$	$\leq$	4 mA
$V_T$	$I_T = 30 \text{ A}, T_{VJ} = 25^\circ\text{C}$	$\leq$	1.4 V
$V_{T0}$	For power-loss calculations only ( $T_{VJ} = 150^\circ\text{C}$ )		0.9 V
$r_T$			18 m $\Omega$
$V_{GT}$	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$	$\leq$ 2.5 V
		$T_{VJ} = -40^\circ\text{C}$	$\leq$ 3.5 V
$I_{GT}$	$V_D = 6 \text{ V}$	$T_{VJ} = 25^\circ\text{C}$	$\leq$ 30 mA
		$T_{VJ} = -40^\circ\text{C}$	$\leq$ 50 mA
$V_{GD}$	$T_{VJ} = T_{VJM}, V_D = \frac{2}{3} V_{DRM}$	$\leq$	0.2 V
$I_{GD}$		$\leq$	1 mA
$I_L$	$T_{VJ} = 25^\circ\text{C}, t_p = 10 \mu\text{s}$ $I_G = 0.08 \text{ A}, di_G/dt = 0.08 \text{ A}/\mu\text{s}$	$\leq$	100 mA
$I_H$	$T_{VJ} = 25^\circ\text{C}, V_D = 6 \text{ V}, R_{GK} = \infty$	$\leq$	80 mA
$t_{gd}$	$T_{VJ} = 25^\circ\text{C}, V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.08 \text{ A}, di_G/dt = 0.08 \text{ A}/\mu\text{s}$	$\leq$	2 $\mu\text{s}$
$R_{thJC}$	DC current		2.5 K/W
$R_{thCH}$	DC current	typ.	0.5 K/W
$R_{thJA}$	DC current		50 K/W
<b>a</b>	Max. acceleration, 50 Hz		50 m/s <sup>2</sup>

### Package Outline



SYM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	.177	.193	4.50	4.90
A1	.092	.108	2.34	2.74
A2	.101	.117	2.56	2.96
b	.028	.035	0.70	0.90
b1	.050	.058	1.27	1.47
c	.018	.024	0.45	0.60
D	.617	.633	15.67	16.07
E	.392	.408	9.96	10.36
e	.100 BSC		2.54 BSC	
H	.255	.271	6.48	6.88
L	.499	.523	12.68	13.28
L1	.119	.135	3.03	3.43
ØP	.121	.129	3.08	3.28
Q	.126	.134	3.20	3.40