## ML2021

## Telephone Line Equalizer

## Features

- Slope, height, and bandwidth adjustable
- Optimized group delays ( 500 Hz to 6.4 kHz )
- On chip anti-alias filter
- Bypass mode
- Low supply current 6 mA typical from $\pm 5 \mathrm{~V}$ supplies
- TTL / CMOS compatible interface
- Double buffered data latch
- Selectable master clock 1.544 or 1.536 MHz
- Synchronous or asynchronous data loading capability
- Compatible with ML2003 and ML2004 logarithmic gain/attenuator

Block Diagram


## General Description

The ML2021 is a monolithic analog line equalizer for telephone applications. The ML2021 consists of a switched capacitor filter that realizes a family of frequency response curves optimized for telephone line equalization while minimizing group delay.

The ML2021 consists of a continuous anti-aliasing filter, three programmable switched capacitor equalization filters, an output smoothing filter, a $600 \Omega$ driver, and a digital section for the serial interface.

The equalization filters adjust the slope, height, and bandwidth of the frequency response. The desired frequency response is programmed by a digital 14-bit serial input data stream.

## Pin Connections



## Pin Description

| Name | Function |
| :--- | :--- |
| CLKSEL | Clock select input. This pin selects the frequency of the CLK input. If CLK is 1.536 MHz, set <br> CLKSEL = 1. If CLK is 1.544 MHz, set CLKSEL = 0. Pin has an internal pullup resistor to VCC. |
| SID | Serial input data. Digital input that contains serial data word which controls the filter frequency <br> response setting. |
| LATO | Output latch clock. Digital input which loads the data word back into the shift register from the latch. |
| SCK | Shift clock. Digital input which shifts the serial data on SID into the shift register on rising edges and <br> out onto SOD on falling edges. |
| SOD | Serial output data. Digital output of the shift register. |
| CLK | Master clock input. Digital input which generates clocks for the switched capacitor filters. <br> Frequency can be either 1.544 MHz or 1.536 MHz. |
| GND | Digital ground. 0 volts. All digital inputs and output are referenced to this ground. |
| LATI | Input latch clock. Digital input which loads data from the shift register into the latch. |
| VSS | Negative supply. -5 volts $\pm 10 \%$. |
| VIN | Analog input. |
| AGND | Analog ground. 0 volts. Analog input and output are referenced to this ground. |
| VOUT | Analog output. |
| PDN | Powerdown input. When PDN = 1, device is in powerdown mode. When PND = 0, device is in normal <br> operation. This pin has an internal pulldown resistor to GND. |
| VCC | Positive supply. 5 volts $\pm 10 \%$ |

## Absolute Maximum Ratings ${ }^{1}$

| Parameter | Min. | Max. | Units |
| :--- | :---: | :---: | :---: |
| Supply Voltage <br> VCC |  |  |  |
| VSS |  | +6.5 | V |
| AGND with respect to GND |  | -6.5 | V |
| Analog Input and Output | VSS -0.3 | VCC +0.3 | V |
| Digital Input and Outputs | $\mathrm{GND}-0.3$ | $\mathrm{VCC}+0.3$ | V |
| Input Current Per Pin |  | $\pm 25$ | mA |
| Power Dissipation |  | 750 | mW |
| Storage Temperature Range | -65 | +150 | ${ }^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering, 10 sec$)$ |  | 300 | ${ }^{\circ} \mathrm{C}$ |

## Operating Conditions

| Parameter | Min. | Max. | Units |
| :--- | :---: | :---: | :---: |
| Temperature Range ${ }^{2}$ |  |  |  |
| ML2021CX | 0 | 70 | ${ }^{\circ} \mathrm{C}$ |
| ML2021IX | -40 | 85 | ${ }^{\circ} \mathrm{C}$ |
| Supply Voltage |  |  |  |
| VCC | 4 | 6 | $V$ |
| VSS | -4 | -6 | V |

## Electrical Characteristics

Unless otherwise specified $T_{A}=T_{M I N}$ to $T_{M A X}, ~ V C C=5 V \pm 10 \%$, $\mathrm{V} S S=-5 \mathrm{~V} \pm 10 \%$, Data Word: $\overline{B P}=1$, Other Bits $=0, C L=100 \mathrm{pF}, \mathrm{RL}_{\mathrm{L}}=600 \Omega$, dBm measurements use $600 \Omega$ as reference load, $\mathrm{VIN}=-7 \mathrm{dBm}$,
1 kHz sinusoid CLK $=1.544 \mathrm{MHz} \pm 300 \mathrm{~Hz}$ and digital time measured at 1.4 V

| Symbol | Parameter | Notes | Conditions | Min | Typ. ${ }^{3}$ | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Analog |  |  |  |  |  |  |  |
| SR | Response, Slope Section | 4 | 1 kHz response |  |  | $\begin{gathered} 1.4 \pm 0.1 \\ 2.6 \pm 0.2 \\ 4 . \pm \pm 0.2 \\ 7.8 \pm 0.2 \\ 11.4 \pm 0.25 \\ 0 \pm 0.1 \\ 0.4 \pm 0.1 \\ 0.9 \pm 0.2 \\ 1.8 \pm 0.2 \\ 3.7 \pm 0.2 \\ 6.6 \pm 0.25 \end{gathered}$ |  |
| HR | Response, Height Section | 4 | 3250 Hz response referenced to 1 kHz response with $\overline{B P}=1$, other bits $=0$ $\begin{array}{ccccc} \text { NL/L } & \text { H3 } & \text { H2 } & \text { H1 } & \text { H0 } \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 & 1 \end{array}$ |  |  | $\begin{gathered} 0 \pm 0.15 \\ 0.5 \pm 0.2 \\ 1.1 \pm 0.2 \\ 2.3 \pm 0.2 \\ 5.7 \pm 0.3 \\ 11.1 \pm 0.3 \end{gathered}$ | $\begin{aligned} & \mathrm{dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \\ & \mathrm{~dB} \end{aligned}$ |
| BR | Response, Bandwidth Section (Q) | 4 | $\begin{array}{ccccccccc} \hline \mathrm{NL} / \mathrm{L} & \mathrm{~B} 3 & \mathrm{~B} 2 & \mathrm{~B} 1 & \underline{\mathrm{~B} 0} & \underline{\mathrm{H} 3} & \underline{\mathrm{H} 2} & \underline{\mathrm{H} 1} & \underline{\mathrm{H} 0} \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 & 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 & 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 1 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \end{array}$ |  |  | $\begin{gathered} 16.1 \pm 2.0 \\ 14.2 \pm 1.5 \\ 12.6 \pm 1.5 \\ 9.1 \pm 1.0 \\ 3.6 \pm 0.5 \\ 1.2 \pm 0.35 \end{gathered}$ |  |
| PK | BW Peak Frequency | 4 | H 3 thru $\mathrm{HO}=1$ | 3230 | 3250 | 3270 | Hz |
| AG | Absolute Gain, Flat Response | 4 | 0.5 kHz to 4 kHz | -0.1 | +0.1 | +0.3 | dB |
| AGB | Absolute Gain, Bypass Mode | 4 | 0.3 kHz to $4 \mathrm{kHz}, \overline{\mathrm{BP}}=0$ | -0.1 | +0.1 | +0.3 | dB |
| ICN | Idle Channel Noise | 4 | VIN $=0$ |  | 3 | 8 | dBrnc |
|  |  |  | VIN $=0$, All Data Bits $=1$ |  | 9 |  | dBrnc |
| HD | Harmonic Distortion | 4 | $\mathrm{VIN}=5 \mathrm{dBm}, 1 \mathrm{kHz}$ <br> Measure 2nd, 3rd, harmonic relative to fundamental |  |  | -48 | dB |
| SD | Signal to Distortion | 4 | $\mathrm{VIN}=-12 \mathrm{dBm}, 1 \mathrm{kHz}$ <br> C msg weighted | +48 |  |  | dB |
| SFN | Signal Frequency Noise | 5 | VIN $=0,4 \mathrm{kHz} \leq$ frequency $\leq 150 \mathrm{kHz}$ |  |  | -50 | dBm |
| PSRR | Power Supply Rejection | 4 | $\begin{aligned} & 200 \mathrm{mV} \text { p-p, } 1 \mathrm{kHz} \text { sine, VIN = } 0 \\ & \text { on VCC } \\ & \text { on VSS } \end{aligned}$ |  |  | $\begin{aligned} & -40 \\ & -40 \end{aligned}$ | $\begin{aligned} & \mathrm{dB} \\ & \mathrm{~dB} \end{aligned}$ |

## Electrical Characteristics (continued)

Unless otherwise specified $\mathrm{T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}, \mathrm{VCC}=5 \mathrm{~V} \pm 10 \%$, V SS $=-5 \mathrm{~V} \pm 10 \%$, Data Word: $\overline{\mathrm{BP}}=1$, Other Bits $=0, C L=100 \mathrm{pF}, \mathrm{RL}_{\mathrm{L}}=600 \Omega$, dBm measurements use $600 \Omega$ as reference load, $\mathrm{VIN}=-7 \mathrm{dBm}$, 1 kHz sinusoid CLK $=1.544 \mathrm{MHz} \pm 300 \mathrm{~Hz}$ and digital time measured at 1.4 V

| Symbol | Parameter | Notes | Conditions | Min | Typ. ${ }^{3}$ | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ZIN | Input Impedance, VIN | 4 |  | 100 |  |  | $\mathrm{k} \Omega$ |
| Vos | Output Offset Voltage | 4 | VIN $=0$ |  |  | $\pm 50$ | mV |
| VINR | Input Voltage Range | 4 |  | $\pm 2.0$ |  |  | V |
| Vosw | Output Voltage Swing | 4 | $R \mathrm{~L}=600 \Omega$ | $\pm 2.0$ |  |  | V |
| Digital and DC |  |  |  |  |  |  |  |
| VIL | Digital Input Low Voltage | 4 |  |  |  | 0.8 | V |
| VIH | Digital Input High Voltage | 4 |  | 2.0 |  |  | V |
| VOL | Digital Output Low Voltage | 4 | $\mathrm{IOL}=2 \mathrm{~mA}$ |  |  | 0.4 | V |
| VOH | Digital Output High Voltage | 4 | $\mathrm{IOH}=-1 \mathrm{~mA}$ | 4.0 |  |  | V |
| ILCLK | Input Current, CLK SEL | 4 | V IN $=0$ | 5 |  | 100 | $\mu \mathrm{A}$ |
| ILPDN | Input Current, PDN | 4 | VIN $=$ VCC | -3 |  | -100 | $\mu \mathrm{A}$ |
| IL | Input Current, All Other Inputs | 4 | VIN $=0$ to VCC |  |  | $\pm 10$ | $\mu \mathrm{A}$ |
| ICC | Vcc Supply Current | 4 | No output load, VIL = GND, $\mathrm{V}_{\mathrm{IH}}=\mathrm{VCC}, \mathrm{V}$ IN $=0$ |  |  | 10 | mA |
| ISS | VSS Supply Current | 4 | No output load, VIL = GND, V IH $=\mathrm{VCC}, \mathrm{V}$ IN $=0$ |  |  | -10 | mA |
| ICCP | Vcc Supply Current, Powerdown Mode | 4 | No output load, VIL = GND, $\mathrm{V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{CC}}$ |  |  | 1.2 | mA |
| ISSP | Vss Supply Current, Powerdown Mode | 4 | No output load, VIL = GND, $\mathrm{VIH}=\mathrm{VCC}$ |  |  | -1.2 | mA |
| AC Characteristics |  |  |  |  |  |  |  |
| tDC | Clock Duty Cycle | 5 |  | 40 |  | 60 | \% |
| tSCK | SCK On/Off Period | 4 |  | 250 |  |  | ns |
| ts | SID Data Setup Time | 4 |  | 50 |  |  | ns |
| th | SID Data Hold Time | 4 |  | 50 |  |  | ns |
| tD | SOD Data Delay | 4 |  | 0 |  | 125 | ns |
| tIPW | LATI Pulse Width | 4 |  | 50 |  |  | ns |
| tOPW | LATO Pulse Width | 4 |  | 50 |  |  | ns |
| tis, tos | LATI, LATO Setup Time | 4 |  | 50 |  |  | ns |
| tin, toh | LATI, LATO Hold Time | 5 |  | 50 |  |  | ns |
| tPLD | SOD Parallel Load Delay | 4 |  | 0 |  | 125 | ns |

## Notes

1. Absolute maximum ratings are limits beyond which the life of the integrated circuit may be impaired. All voltages unless otherwise specified are measured with respect to ground.
2. $0^{\circ} \mathrm{C}$ to $+70^{\circ} \mathrm{C}$ and $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ operating temperature range devices are $100 \%$ tested with temperature limits guaranteed by $100 \%$ testing, sampling, or by correlation with worst-case test conditions.
3. Typicals are parametric norm at $25^{\circ} \mathrm{C}$.
4. Parameter guaranteed and $100 \%$ production tested.
5. Parameter guaranteed. Parameters not $100 \%$ tested are not in outgoing quality level calculation.


Figure 1. Serial Timing Diagram


Figure 2. Typical Slope Filter Response-NL/L = 0 $\mathrm{B} 3-\mathrm{BO}, \mathrm{H} 3-\mathrm{HO}=0000, \mathrm{~S} 3-\mathrm{SO}=0000$ to 1111 .


Figure 3. Typical Slope Filter Response-NL/L = 1 B3-B0, H3-H0 = 0000, S3-S0 = 0000 to 1111 .



Figure 4. Typical Height Filter Response-NL/L = 0 $\mathrm{B} 3-\mathrm{BO}, \mathrm{S} 3-\mathrm{SO}=0000, \mathrm{H} 3-\mathrm{HO}=0000$ to 1111.



Figure 5. Typical Bandwidth Filter Response-NL/L = 0 $\mathrm{H} 3-\mathrm{HO}=1111 ; \mathrm{S} 3-\mathrm{SO}=0000 ; \mathrm{B} 3-\mathrm{BO}=0000$ to 1111 .

## Functional Description

The ML2021 consists of a continuous anti-alias filter, three programmable switched capacitor equalization filters, an output smoothing filter, an output driver, and a digital section for the serial interface.

## Anti-Alias Filter

The first section is a continuous anti-alias filter. This filter is needed to prevent aliasing of high frequency signal present on the input into the passband by the sampling action of the switched capacitor filters. This section is a continuous second order lowpass filter with a typical 3 dB frequency at 20 kHz and 30 dB of rejection at 124 kHz .

## Equalization Filters

The programmable filters implement a family of frequency response curves intended to compensate for the response of telephone lines.

This filter is composed of three distinct sections: slope, height, and bandwidth.

## Response of Slope, Height, and Bandwidth

The family of response curves generated by the slope section are shown in Figures 2 and 3. There are 4 slope select bits, S3-S0. These bits alter the slope of the highpass response under 1000 Hz , and as a result, the absolute gain above 1000 Hz will be unique for each setting. Table 1 gives typical 1 kHz gain values for all slope settings.

Table 1. Typ. 1kHz Gain for Slope Settings

| Slope <br> Setting | Rel 1kHz Gain (dB) |  |
| :---: | :---: | :---: |
|  | NL/L = 1 | NL/L = 0 |
| 0 | 0.0 | REL |
| 1 | 0.4 | 1.4 |
| 2 | 0.9 | 2.6 |
| 3 | 1.4 | 3.7 |
| 4 | 1.8 | 4.7 |
| 5 | 2.3 | 5.5 |
| 6 | 2.8 | 6.3 |
| 7 | 3.4 | 7.2 |
| 8 | 3.7 | 7.8 |
| 9 | 4.2 | 8.4 |
| 10 | 4.6 | 9.0 |
| 11 | 5.0 | 9.5 |
| 12 | 5.4 | 10.0 |
| 13 | 5.8 | 10.5 |
| 14 | 6.2 | 11.0 |
| 15 | 6.6 | 11.4 |

HT, BW Bits = 0

There is an additional bit, NL/L, that also affects the highpass response of the slope filter. The slope response curves in Figure 2 are with $\mathrm{NL} / \mathrm{L}=0$. These same response curves are shown in Figure 3 with NL/L = 1. Notice that the NL/L bit adds more droop in the highpass response below 2500 Hz .

The family of response curves generated by the height section are shown in Figure 4. There are 4 height select bits, H3-H0. This section creates a peak in the response at 3250 Hz and this filter controls the amount of peaking. Table 2 gives typical 1 kHz gain values for all height and bandwidth settings.

Table 2. Typ. 1kHz Gain for HT and BW Settings

| Relative 1kHz Gain (dB) |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| HT Setting |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
|  | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 |
|  | Rel | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.1 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.1 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.2 | 0.2 | 0.2 |
|  | 0 | 0 | 0 | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.1 | 0.1 | 0.2 | 0.2 | 0.3 | 0.3 | 0.4 |
|  | 0 | 0 | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.1 | 0.2 | 0.2 | 0.3 | 0.3 | 0.4 | 0.5 | 0.6 |
|  | 0 | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.1 | 0.2 | 0.3 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 |
|  | 0 | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.2 | 0.2 | 0.3 | 0.4 | 0.4 | 0.5 | 0.7 | 0.8 | 0.9 | 1.1 |
|  | 0 | 0 | 0.1 | 0.1 | 0.1 | 0.2 | 0.2 | 0.3 | 0.4 | 0.5 | 0.7 | 0.8 | 1.0 | 1.1 | 1.4 | 1.6 |
|  | 0 | 0 | 0.1 | 0.1 | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.8 | 0.9 | 1.1 | 1.4 | 1.6 | 1.9 | 2.3 |
|  | 0 | 0 | 0.1 | 0.1 | 0.2 | 0.3 | 0.4 | 0.5 | 0.7 | 0.8 | 1.0 | 1.2 | 1.5 | 1.7 | 2.0 | 2.4 |
|  | 0 | 0 | 0.1 | 0.1 | 0.2 | 0.3 | 0.4 | 0.5 | 0.7 | 0.9 | 1.1 | 1.3 | 1.6 | 1.8 | 2.1 | 2.5 |

Slope Bits $=0$
The family of response curves generated by the bandwidth section is shown in Figure 5. There are 4 bandwidth select bits, B3-B0. This section causes the response of the 3250 Hz peak to be widened, and as a result, this filter controls the bandwidth of the 3250 Hz peaked region.

## Transfer Function

The transfer function for the ML2021 is shown below. This transfer function is valid for magnitude response only. The actual magnitude response from an individual device may deviate from the computed response from the transfer function by typically $0-0.2 \mathrm{~dB}$.

$$
\begin{aligned}
& H(s)=\frac{c(s+b)}{b(s+c)} \times \frac{\left[s^{2}+h\left(\omega_{0} / Q\right) s+\omega_{0}{ }^{2}\right]}{\left[s^{2}+\left(\omega_{0} / Q\right) s+\omega_{0}{ }^{2}\right]} \times \frac{[\sin (\pi f / f c)]}{(\pi f / f c)} \\
& \mathrm{s}=\mathrm{j} \times 256000 \times \tan (\pi \mathrm{f} / 128000) \\
& \omega_{\mathrm{o}}=20463.77 \\
& \text { fc }=128000 \\
& \text { b,c : See Table 3. (slope) } \\
& \text { Q : See Table 4. (bandwidth) } \\
& \text { h : See Table } 5 . \quad \text { (height) }
\end{aligned}
$$

Table 3. Slope Response Factors (b,c)

|  | $\mathbf{b}$ | $\mathbf{b}$ |
| :--- | :--- | :--- |
| S3-0 | $\mathbf{N L} / \mathbf{L}=\mathbf{0}$ | $\mathbf{N L} / \mathbf{L}=\mathbf{1}$ |
| 0000 | $2.371759 \mathrm{E}+03$ | $1.116280 \mathrm{E}+04$ |
| 0001 | $1.985920 \mathrm{E}+03$ | $9.345141 \mathrm{E}+03$ |
| 0010 | $1.701779 \mathrm{E}+03$ | $8.007156 \mathrm{E}+03$ |
| 0011 | $1.493571 \mathrm{E}+03$ | $7.026999 \mathrm{E}+03$ |
| 0100 | $1.326721 \mathrm{E}+03$ | $6.241681 \mathrm{E}+03$ |
| 0101 | $1.196668 \mathrm{E}+03$ | $5.629636 \mathrm{E}+03$ |
| 0110 | $1.087277 \mathrm{E}+03$ | $5.114881 \mathrm{E}+03$ |
| 0111 | $9.983588 \mathrm{E}+02$ | $4.696487 \mathrm{E}+03$ |
| 1000 | $9.179889 \mathrm{E}+02$ | $4.318339 \mathrm{E}+03$ |
| 1001 | $8.537864 \mathrm{E}+02$ | $4.016273 \mathrm{E}+03$ |
| 1010 | $7.966049 \mathrm{E}+02$ | $3.747249 \mathrm{E}+03$ |
| 1011 | $7.478074 \mathrm{E}+02$ | $3.517676 \mathrm{E}+03$ |
| 1100 | $7.035099 \mathrm{E}+02$ | $3.309279 \mathrm{E}+03$ |
| 1101 | $6.651771 \mathrm{E}+02$ | $3.128945 \mathrm{E}+03$ |
| 1110 | $6.299477 \mathrm{E}+02$ | $2.963214 \mathrm{E}+03$ |
| 1111 | $5.990361 \mathrm{E}+02$ | $2.817797 \mathrm{E}+03$ |
|  | $\mathbf{c}$ | $\mathbf{c}$ |
| S3-0 | NL/L = 0 | NL/L $=\mathbf{1}$ |
| XXXX | $2.371759 \mathrm{E}+03$ | $1.116280 \mathrm{E}+04$ |

Table 4. Slope Response factors (b,c)

| B3-0 | $\mathbf{Q}$ |
| :--- | :--- |
| 0000 | 17.444906 |
| 0001 | 15.386148 |
| 0010 | 13.652451 |
| 0011 | 11.593677 |
| 0100 | 9.859960 |
| 0101 | 8.017864 |
| 0110 | 6.392453 |
| 0111 | 5.092080 |
| 1000 | 3.900003 |
| 1001 | 3.141338 |
| 1010 | 2.599369 |
| 1011 | 2.165724 |
| 1100 | 1.731965 |
| 1101 | 1.406509 |
| 1110 | 1.352248 |
| 1111 | 1.297981 |

Table 5. Height Response Factors (h)

| Code | $\mathbf{h}$ |
| :--- | :--- |
| 0000 | 1.000000 |
| 0001 | 1.071519 |
| 0010 | 1.148154 |
| 0011 | 1.230269 |
| 0100 | 1.318257 |
| 0101 | 1.445438 |
| 0110 | 1.603245 |
| 0111 | 1.757924 |
| 1000 | 1.949845 |
| 1001 | 2.137962 |
| 1010 | 2.317395 |
| 1011 | 2.540973 |
| 1100 | 2.786121 |
| 1101 | 3.019951 |
| 1110 | 3.311311 |
| 1111 | 3.672823 |

## Group Delay

The difference between the ML2020 and ML2021 is the elimination of a 60 Hz highpass filter in order to eliminate positive group delay at low frequency.

The group delay through the ML2021 can be minimized such that less than $50 \mu$ s of group delay can be achieved in both unloaded and cable loaded conditions relative to 1804 Hz in the frequency range of 504 to 3004 Hz . Minimum group delays are dependant upon using the proper setting for slope, height, and bandwidth for a give equalization requirement.

## Smoothing Filter

The equalizer filters are followed by a continuous second order smoothing filter that removes the high frequency sample information generated by the action of the switched capacitor filters. This filter provides a continuous analog signal at the output, Vout.

## Output Buffer

The final stage in the ML2021 is the output buffer. This amplifier has internal gain of 1 and is capable of driving $600 \Omega, 100 \mathrm{pF}$ loads. Thus, it is suitable for driving telephone hybrids directly without any external amplifier.

## Bypass Mode

The filter sections can be bypassed by setting the bypass data bit, $\overline{\mathrm{BP}}$, to 0 . Since the switched capacitor filters are bypassed in this mode, frequency response effects of the switched capacitor filters are eliminated. Thus, this mode offers very flat response and low noise over the $300-4000 \mathrm{~Hz}$ frequency range.

## Filter Clock

The master clock, CLK, is used to generate the internal clocks for the switched capacitor filters. The frequency of CLK can be either 1.544 MHz or 1.536 MHz . However, the internal clock frequency must be kept at 1.536 MHz to guarantee accurate frequency response. The CLKSEL pin enables a bit swallower circuit to keep the internal clock frequency set to 1.536 MHz . When 1.544 MHz clock is used, CLKSEL should be set to logic level 0 , and one bit out of every 193 bits is removed (swallowed) to reduce the internal frequency to 1.536 MHz . When 1.536 MHz clock is used, CLKSEL should be set to logic level 1, and the internal clock rate is the same as the external clock rate.

## Serial Interface

The architecture of the digital section is shown in the preceding block diagram.

A timing diagram for the serial interface is shown in Figure 6. The serial input data, SID, is loaded into a shift register on rising edges of the shift clock, SCK. The data word is parallel loaded into a latch when the input latch signal, LATI, is
high. The LATI pulse must occur when SCK is low. A new data word can be loaded into the shift register without disturbing the existing data word in the latch.

The parallel outputs of the latch control the filter response curves. The order of the data word bits in the latch is shown in Figure 7.

Note that bit 0 is the first bit of the data word clocked into the shift register.

The device has the capability to read out the data word stored in the latch. This is done by parallel loading the data from the latch back into the shift register when the latch signal, LATO, is high. The LATO pulse must occur when SCK is low. Then, the data word can be shifted out of the register
serially to the output, SOD, on falling edges of the shift clock, SCK.

The loading and reading of the data word can be done continuously or in bursts. Since the shift register and latch circuitry inside the device is static, there are no minimum frequency requirements on the clocks or data pulses. However, there is some coupling of the digital signals in the ana$\log$ section. If this coupling is undesirable, the data can be clocked in bursts during non critical intervals, or the data rate can be done at a frequency outside the analog frequency range.

The clocks used to shift and latch data (SCK, LATI, LATO) are not related internally to the master clock and can occur asynchronous to CLK.


Figure 6. Serial Timing


Figure 7. 14-Bit Latch

## Powerdown Mode

A powerdown mode can be selected with pin PDN. When PDN $=1$, the device is powered down. In this state, the power consumption is reduced by removing power from the analog section and forcing the analog output, VOUT, to a high impedance state. While the device is in power down mode, the digital section is still functional and the current data word remains stored in the latch. The master clock, CLK, can be left active or removed during powerdown mode. When PDN $=0$, the device is in normal operation.

## Power Supplies

The digital section inside the device is powered between VCC and GND, or 5 volts. The analog section is powered between $V_{C C}$ and $V_{S S}$, or $\pm 5$ volts. The analog section uses AGND as the reference point.

GND and AGND are totally isolated inside the device to minimize coupling from the digital section into the analog section. Typically this is less than $100 \mu \mathrm{~V}$. However, ANGD and GND should be tied together physically near the device and close to the common power supply ground connection.

The power supply rejection of VCC and VSS to the analog output is greater than -60 dB at 1 kHz , typically. If decoupling of the power supplies is still necessary in a system, $V_{C C}$ and VSS should be decoupled with respect to AGND.

## Applications



Figure 8. Typical Serial Interface


Figure 9. Controlling Multiple ML2021 and ML2004 With
Only 3 Digital Lines Using One Long Data Word

## Ordering Information

| Part Number | Temperature Range | Package |
| :---: | :---: | :---: |
| ML2021CP | $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ | Molded DIP (P16) |
| ML2021CS | $0^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}$ | Molded SOIC (S18) |
| ML2021IP | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | Molded DIP (P16) |
| ML2021IS | $-40^{\circ} \mathrm{C}$ to $85^{\circ} \mathrm{C}$ | Molded SOIC (S18) |

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