

Technical Specification

PKM 4000D PINB series

DC/DC converters, Input 36-75 V, Output up to 35 A/132 W

EN/LZT 146 416 R3A February 2010

© Ericsson AB

Key Features

- Industry standard Quarter-brick. 57.9 x 36.8 x 9.35 mm (2.28 x 1.45 x 0.368 in)
- High efficiency, typ. 93.5% at 12 Vout half load
- 1500 Vdc input to output isolation
- Meets isolation requirements equivalent to basic insulation according to IEC/EN/UL 60950
- More than 1.67 million hours MTBF

General Characteristics

- · Output over voltage protection
- Over temperature protection
- Output short-circuit protection
- Hiccup over current protection as an option
- · Remote control
- Output voltage adjust function
- · Highly automated manufacturing ensures quality
- ISO 9001/14001 certified supplier



Safety Approvals



Design for Environment





Meets requirements in hightemperature lead-free soldering processes.

Contents

| Ordering Information General Information Safety Specification | | 2 |
|---|-----------------|----|
| Absolute Maximum Ratings | | |
| Electrical Specification | | |
| 3.3V, 35 A / 115W | PKM 4110D PINB | 5 |
| 5.0V, 25 A / 125W | PKM 4111D PINB | 9 |
| 12V, 11A / 132W | PKM 4113D PINB1 | 3 |
| I5V, 8A / 120W | PKM 4115D PINB1 | 7 |
| EMC Specification | 2 | 12 |
| Operating Information | 2 | |
| Fhermal Consideration | 2 | |
| Connections | 2 | |
| Mechanical Information | | |
| Soldering Information | 2 | |
| Delivery Information | 2 | |
| Product Qualification Specification | 2 | |



| | • |
|--|----------------------------------|
| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

Ordering Information

| Product program | Output |
|-----------------|---------------------|
| PKM 4110D PI | 3.3 V, 35 A / 115 W |
| PKM 4111D PI | 5 V, 25 A / 125 W |
| PKM 4113D PI | 12 V, 11 A / 132 W |
| PKM 4115D PI | 15 V, 8 A / 120 W |

Product number and Packaging

| PKM 4XXXD PI n ₁ n ₂ n ₃ n ₄ n ₅ | | | | | | |
|---|----------------|----------------|----------------|----------------|----------------|--|
| Options | n ₁ | n ₂ | n ₃ | n ₄ | n ₅ | |
| Remote Control logic | 0 | | | | | |
| Baseplate | | o | | | | |
| Hiccup OCP | | | o | | | |
| Increased stand-off height | | | | О | | |
| Lead length | | | | | О | |

| Options | Desc | ription |
|----------------|----------|--|
| n_1 | Р | Negative * Positive |
| n_2 | NB | Without baseplate * With baseplate |
| n_3 | НС | Hiccup OCP |
| n ₄ | M | Standard stand-off height * Increased stand-off height |
| n_5 | LA LB | 5.30 mm * 3.69 mm 4.57 mm |

Example a through-hole mounted, positive logic, short pin product with increased stand-off height would be PKM 4111DPIPNBMLB.

General Information

Reliability

The Mean Time Between Failure (MTBF) is calculated at full output power and an operating ambient temperature (T_A) of +40°C, which is a typical condition in Information and Communication Technology (ICT) equipment. Different methods could be used to calculate the predicted MTBF and failure rate which may give different results. Ericsson Power Modules currently Telcordia SR332.

Predicted MTBF for the series is:

 1.67 million hours according to Telcordia SR332, issue 1, Black box technique.

The Ericsson failure rate data system is based on field tracking data. The data corresponds to actual failure rates of components used in ICT equipment in temperature controlled environments ($T_A = -5...+65$ °C).

Telcordia SR332 is a commonly used standard method intended for reliability calculations in ICT equipment. The parts count procedure used in this method was originally modelled on the methods from MIL-HDBK-217F, Reliability Predictions of Electronic Equipment. It assumes that no reliability data is available on the actual units and devices for which the predictions are to be made, i.e. all predictions are based on generic reliability parameters.

Compatibility with RoHS requirements

The products are compatible with the relevant clauses and requirements of the RoHS directive 2002/95/EC and have a maximum concentration value of 0.1% by weight in homogeneous materials for lead, mercury, hexavalent chromium, PBB and PBDE and of 0.01% by weight in homogeneous materials for cadmium.

Exemptions in the RoHS directive utilized in Ericsson Power Modules products include:

- Lead in high melting temperature type solder (used to solder the die in semiconductor packages)
- Lead in glass of electronics components and in electronic ceramic parts (e.g. fill material in chip resistors)
- Lead as an alloying element in copper alloy containing up to 4% lead by weight (used in connection pins made of Brass)

Quality Statement

The products are designed and manufactured in an industrial environment where quality systems and methods like ISO 9000, 6σ (sigma), and SPC are intensively in use to boost the continuous improvements strategy. Infant mortality or early failures in the products are screened out and they are subjected to an ATE-based final test. Conservative design rules, design reviews and product qualifications, plus the high competence of an engaged work force, contribute to the high quality of our products.

Warranty

Warranty period and conditions are defined in Ericsson Power Modules General Terms and Conditions of Sale.

Limitation of Liability

Ericsson Power Modules does not make any other warranties, expressed or implied including any warranty of merchantability or fitness for a particular purpose (including, but not limited to, use in life support applications, where malfunctions of product can cause injury to a person's health or life).

© Ericsson AB 2009

The information and specifications in this technical specification is believed to be correct at the time of publication. However, no liability is accepted for

^{*} Standard variant (i.e. no option selected).





| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

inaccuracies, printing errors or for any consequences thereof. Ericsson AB reserves the right to change the contents of this technical specification at any time without prior notice.

Safety Specification

General information

Ericsson Power Modules DC/DC converters and DC/DC regulators are designed in accordance with safety standards IEC/EN/UL60950, Safety of Information Technology Equipment.

IEC/EN/UL60950 contains requirements to prevent injury or damage due to the following hazards:

- Electrical shock
- Energy hazards
- Fire
- · Mechanical and heat hazards
- Radiation hazards
- · Chemical hazards

On-board DC-DC converters and DC/DC regulators are defined as component power supplies. As components they cannot fully comply with the provisions of any Safety requirements without "Conditions of Acceptability". Clearance between conductors and between conductive parts of the component power supply and conductors on the board in the final product must meet the applicable Safety requirements. Certain conditions of acceptability apply for component power supplies with limited stand-off (see Mechanical Information for further information). It is the responsibility of the installer to ensure that the final product housing these components complies with the requirements of all applicable Safety standards and Directives for the final product.

Component power supplies for general use should comply with the requirements in IEC60950, EN60950 and UL60950 "Safety of information technology equipment".

There are other more product related standards, e.g. IEEE802.3af "Ethernet LAN/MAN Data terminal equipment power", and ETS300132-2 "Power supply interface at the input to telecommunications equipment; part 2: DC", but all of these standards are based on IEC/EN/UL60950 with regards to safety.

Ericsson Power Modules DC/DC converters and DC/DC regulators are UL60950 recognized and certified in accordance with EN60950.

The flammability rating for all construction parts of the products meets requirements for V-0 class material according to IEC 60695-11-10.

The products should be installed in the end-use equipment, in accordance with the requirements of the ultimate application. Normally the output of the DC/DC converter is

considered as SELV (Safety Extra Low Voltage) and the input source must be isolated by minimum Double or Reinforced Insulation from the primary circuit (AC mains) in accordance with IEC/EN/UL60950.

Isolated DC/DC converters

It is recommended that a slow blow fuse with a rating twice the maximum input current per selected product be used at the input of each DC/DC converter. If an input filter is used in the circuit the fuse should be placed in front of the input filter

In the rare event of a component problem in the input filter or in the DC/DC converter that imposes a short circuit on the input source, this fuse will provide the following functions:

- Isolate the faulty DC/DC converter from the input power source so as not to affect the operation of other parts of the system.
- Protect the distribution wiring from excessive current and power loss thus preventing hazardous overheating.

The galvanic isolation is verified in an electric strength test. The test voltage ($V_{\rm iso}$) between input and output is 1500 Vdc or 2250 Vdc for 60 seconds (refer to product specification).

Leakage current is less than 1 µA at nominal input voltage.

24 V DC systems

The input voltage to the DC/DC converter is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.

48 and 60 V DC systems

If the input voltage to the DC/DC converter is 75 Vdc or less, then the output remains SELV (Safety Extra Low Voltage) under normal and abnormal operating conditions.

Single fault testing in the input power supply circuit should be performed with the DC/DC converter connected to demonstrate that the input voltage does not exceed 75 Vdc.

If the input power source circuit is a DC power system, the source may be treated as a TNV2 circuit and testing has demonstrated compliance with SELV limits and isolation requirements equivalent to Basic Insulation in accordance with IEC/EN/UL60950.

Non-isolated DC/DC regulators

The input voltage to the DC/DC regulator is SELV (Safety Extra Low Voltage) and the output remains SELV under normal and abnormal operating conditions.







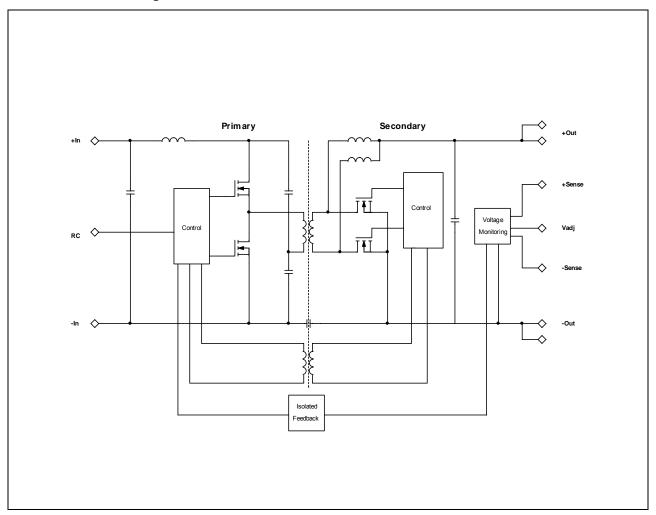
| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 | |
|--|----------------------------------|--|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB | |

Absolute Maximum Ratings

| Char | Characteristics | | | typ | max | Unit |
|------------------|---|-----------------------|------|-----|------|------|
| T _{P1} | Operating Temperature (see Thermal Consideration section) | | -40 | | +110 | °C |
| Ts | Storage temperature | | -55 | | +125 | °C |
| Vı | Input voltage | | -0.5 | | +80 | V |
| V_{iso} | Isolation voltage (input to output test voltage) | | | | 1500 | Vdc |
| V_{tr} | Input voltage transient (tp 100 ms) | | | | 100 | V |
| \/ | Remote Control pin voltage | Positive logic option | -0.5 | | +15 | V |
| V_{RC} | (see Operating Information section) Negative Id | Negative logic option | -0.5 | | +15 | V |
| V_{adj} | V _{adj} Adjust pin voltage (see Operating Information section) | | -0.5 | | +5 | V |

Stress in excess of Absolute Maximum Ratings may cause permanent damage. Absolute Maximum Ratings, sometimes referred to as no destruction limits, are normally tested with one parameter at a time exceeding the limits in the Electrical Specification. If exposed to stress above these limits, function and performance may degrade in an unspecified manner.

Fundamental Circuit Diagram







| | • |
|--|----------------------------------|
| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

3.3V, 35A /115W Electrical Specification

Input voltage range

PKM 4110D PINB

 T_{P1} = -40 to +90°C, V_I = 36 to 75 V, sense pins connected to output pins unless otherwise specified under Conditions. Typical values given at: T_{P1} = +25°C, V_I = 53 V_I max I_O , unless otherwise specified under Conditions. Additional C_{in} = 0 μ F.See Operating Information section for selection of capacitor types.

| V | input voitage range | | 30 | | 7.5 | v |
|-------------------|--|--|------|------------|------|-------------|
| V _{loff} | Turn-off input voltage | Decreasing input voltage | 30.0 | 32.0 | 33.5 | V |
| V _{Ion} | Turn-on input voltage | Increasing input voltage | 32.0 | 34.0 | 35.5 | V |
| Cı | Internal input capacitance | | | 6.0 | | μF |
| Po | Output power | | 0 | | 115 | W |
| | | 50 % of max I _O | | 91.4 | | |
| _ | | max I _O | | 90.3 | | 0/ |
| η | Efficiency | 50 % of max I _O , V _I = 48 V | | 91.7 | | - % |
| | | max I _O , V _I = 48 V | | 90.2 | | |
| P _d | Power Dissipation | max I _O | | 12.7 | 16.5 | W |
| Pii | Input idling power | I _O = 0 A, V _I = 53 V | | 2.6 | | W |
| P _{RC} | Input standby power | V _I = 53 V (turned off with RC) | | 0.15 | | W |
| fs | Switching frequency | 0-100 % of max I _O | 180 | 200 | 220 | kHz |
| | | | | | | |
| Voi | Output voltage initial setting and accuracy | T _{P1} = +25°C, V _I = 53 V, I _O = 50 A | 3.24 | 3.30 | 3.36 | V |
| | Output adjust range | See operating information | 2.97 | | 3.63 | V |
| | Output voltage tolerance band | 0-100 % of max I _O | 3.23 | | 3.37 | V |
| V_{o} | Idling voltage | I _O = 0 A | 3.23 | | 3.37 | V |
| | Line regulation | max I _O | | 5 | 15 | mV |
| | Load regulation | V _I = 53 V, 0-100 % of max I _O | | 5 | 15 | mV |
| V_{tr} | Load transient voltage deviation | V ₁ = 53 V, Load step 25-75-25 % of max I _o , di/dt = 5 A/μs | | ±250 | ±300 | mV |
| t _{tr} | Load transient recovery time | see Note 1 | | 70 | 100 | μs |
| t _r | Ramp-up time (from 10-90 % of V _{Oi}) | 10-100 % of max I _O | 1 | 4 | 6 | ms |
| ts | Start-up time (from V _i connection to 90 % of V _{Oi}) | | 8 | 14 | 20 | ms |
| t _f | V _I shut-down fall time (from V _I off to 10 % of V _O) | max I _o | | 0.12 | | ms |
| | | I _O = 0.35 A | | 0.01 15 | | S |
| + | RC start-up time | max I _O | | 0.09 | | ms |
| t _{RC} | RC shut-down fall time (from RC off to 10 % of V _O) | - | | 0.09 | | ms |
| 1 | Output current | I _O = 0.35 A | 0 | 0.009 | 35 | s A |
| l _o | Current limit threshold | T. c may T | 38 | 44 | 50 | A |
| I _{lim} | Short circuit current | $T_{P1} < max T_{P1}$ $T_{P1} = 25^{\circ}C$ | 30 | 52 | 58 | |
| Isc | Recommended Capacitive Load | * * | 0 | IJZ | 3500 | Α μF |
| V _{Oac} | Output ripple & noise | T _{P1} = 25°C, see Note 2 See ripple & noise section, | 0 | 80 | 120 | μr mVp-p |
| OVP | Over voltage protection | max I_0 , V_{0i} $T_{P1} = +25^{\circ}C$, $V_1 = 53$ V, 0-100 % of max I_0 | 3.6 | 4.2 | 4.8 | V |

Note 2: Aluminium electrolytic capacitors, ESR is lower than 10m ohm.



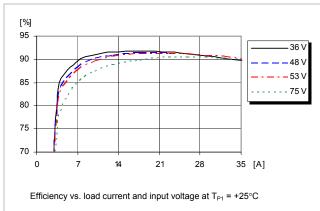


EN/LZT 146 416 R3A February 2010 © Ericsson AB

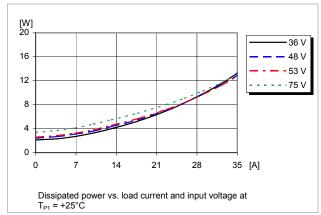
3.3V, 35A /115W Typical Characteristics

PKM 4110D PINB

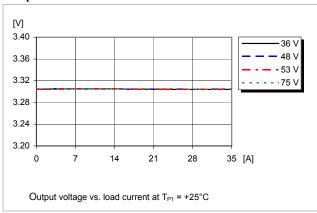
Efficiency



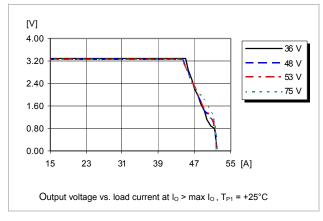
Power Dissipation



Output Characteristics



Current Limit Characteristics





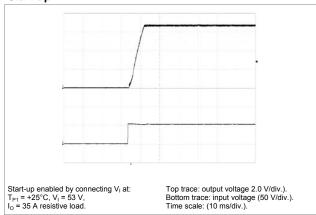
EN/LZT 146 416 R3A February 2010

© Ericsson AB

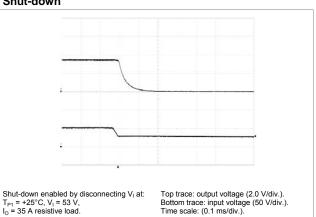
3.3V, 35A /115W Typical Characteristics

PKM 4110D PINB

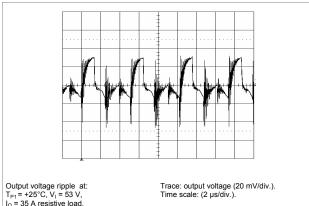
Start-up



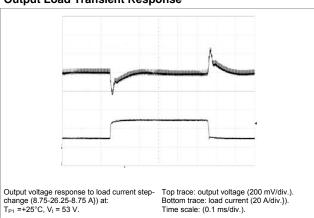
Shut-down



Output Ripple & Noise



Output Load Transient Response



Output Voltage Adjust (see operating information)

Passive adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$Radj = \left(\frac{5.11 \times 3.3 (100 + \Delta\%)}{1.225 \times \Delta\%} - \frac{511}{\Delta\%} - 10.22\right) \text{ k}\Omega$$

Example: Increase 4% =>Vout = 3.43 Vdc

$$\left(\frac{5.11 \times 3.3 (100 + 4)}{1.225 \times 4} - \frac{511}{4} - 10.22\right) \text{ k}\Omega = 219.9 \text{ k}\Omega$$

Output Voltage Adjust Downwards, Increase:

$$Radj = 5.11 \left(\frac{100}{\Delta\%} - 2 \right) \text{ k}\Omega$$

Example: Decrease 2% =>V_{out} = 3.23 Vdc $k\Omega = 404.32 \text{ } k\Omega$

$$5.11\left(\frac{100}{2} - 2\right) \text{ k}\Omega = 245.3 \text{ k}\Omega$$



8



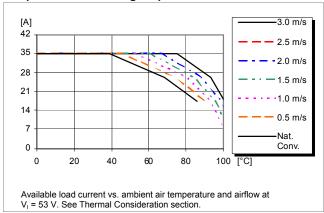
PKM 4000D PINB series
DC/DC converters, Input 36-75 V, Output up to 35 A/132 W

EN/LZT 146 416 R3A February 2010 © Ericsson AB

3.3V, 35A /115W Typical Characteristics

PKM 4110D PINB

Output Current Derating - Open frame

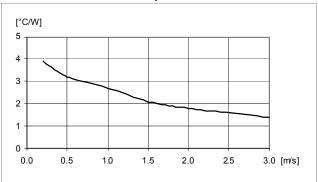


Output Current Derating - Base plate

[A] 3.0 m/s 42 35 2.0 m/s 28 $1.5 \, \text{m/s}$ 21 1.0 m/s 14 $0.5 \, \text{m/s}$ 7 0 Nat 0 20 40 60 80 100 [℃]

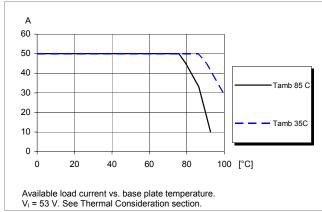
Available load current vs. ambient air temperature and airflow at V_1 = 53 V. See Thermal Consideration section.

Thermal Resistance - Base plate



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section. $V_{\rm I}$ = 53 V.

Output Current Derating - Cold wall sealed box





9



 V_{l}

| | • |
|--|----------------------------------|
| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

36

5.0V, 25A /125W Electrical Specification

Input voltage range

PKM 4111D PINB

 T_{P1} = -40 to +90°C, V_I = 36 to 75 V, sense pins connected to output pins unless otherwise specified under Conditions. Typical values given at: T_{P1} = +25°C, V_I = 53 V_I max I_O , unless otherwise specified under Conditions. Additional C_{in} = 0 μ F.See Operating Information section for selection of capacitor types.

| - 1 | | | | | | |
|-----------------------|---|--|------|------|------|-------|
| V_{loff} | Turn-off input voltage | Decreasing input voltage | 30.0 | 32.0 | 33.5 | V |
| V _{Ion} | Turn-on input voltage | Increasing input voltage | 32.0 | 34.0 | 35.5 | V |
| Cı | Internal input capacitance | | | 6.0 | | μF |
| Po | Output power | | 0 | | 125 | W |
| | | 50 % of max I _O | | 91.8 | | |
| _ | T#inianay | max I _O | | 91.3 | | 0/ |
| η | Efficiency | 50 % of max I _O , V _I = 48 V | | 92.1 | | - % |
| | | max I _O , V _I = 48 V | | 91.4 | | |
| P _d | Power Dissipation | max I _O | | 11.8 | 14.1 | W |
| Pli | Input idling power | I _O = 0 A, V _I = 53 V | | 2.9 | | W |
| P _{RC} | Input standby power | V _I = 53 V (turned off with RC) | | 0.15 | | W |
| fs | Switching frequency | 0-100 % of max I _O | 180 | 200 | 220 | kHz |
| | • | | | | | · L |
| V _{Oi} | Output voltage initial setting and accuracy | T _{P1} = +25°C, V _I = 53 V, I _O = 25 A | 4.90 | 5.00 | 5.10 | V |
| | Output adjust range | See operating information | 4.50 | | 5.50 | V |
| | Output voltage tolerance band | 0-100 % of max I _O | 4.80 | | 5.20 | V |
| Vo | Idling voltage | I _O = 0 A | 4.80 | | 5.20 | V |
| | Line regulation | max I _O | | 5 | 15 | mV |
| | Load regulation | V _I = 53 V, 0-100 % of max I _O | | 5 | 15 | mV |
| V _{tr} | Load transient voltage deviation | V ₁ = 53 V, Load step 25-75-25 % of max I _O , di/dt = 5 A/μs | | ±200 | ±300 | mV |
| t _{tr} | Load transient recovery time | see Note 1 | | 20 | 50 | μs |
| t _r | Ramp-up time (from 10–90 % of V _{Oi}) | 10-100 % of max I _O | 1 | 5 | 15 | ms |
| ts | Start-up time (from V _I connection to 90 % of V _{Oi}) | 10 100 % of max 1 ₀ | 7 | 10 | 30 | ms |
| t _f | V _I shut-down fall time | max I _O | | 0.2 | | ms |
| • | (from V ₁ off to 10 % of V ₀) | I _O = 0.4 A | | 0.02 | | S |
| | RC start-up time | max I ₀ | | 9 | | ms |
| t _{RC} | RC shut-down fall time | max I _o | | 0.2 | | ms |
| | (from RC off to 10 % of V _O) | I _O = 0.4 A | _ | 0.02 | | s |
| lo | Output current | | 0 | | 25 | Α |
| l _{lim} | Current limit threshold | $T_{P1} < max T_{P1}$ | 28 | 32 | 36 | Α |
| I _{sc} | Short circuit current | T _{P1} = 25°C | | 40 | 45 | Α |
| C _{out} | Recommended Capacitive Load | T _{P1} = 25°C, see Note 2 | 0 | | 2500 | μF |
| V_{Oac} | Output ripple & noise | See ripple & noise section, max I _o , V _{oi} | | 60 | 130 | mVp-p |
| OVP | Over voltage protection | $T_{P1} = +25^{\circ}C$, $V_{I} = 53 \text{ V}$, 0-100 % of | 6.2 | 6.8 | 7.2 | V |

Note 1: 6 pieces of 470uF aluminium solid capacitors are connected to the module.

Note 2: Aluminium electrolytic capacitors, ESR is lower than 10 mohm.





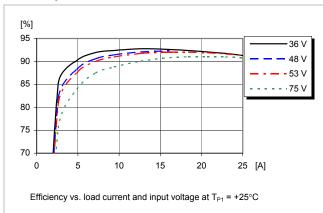
EN/LZT 146 416 R3A February 2010

© Ericsson AB

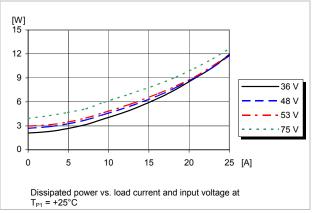
5.0V, 25A /125W Typical Characteristics

PKM 4111D PINB

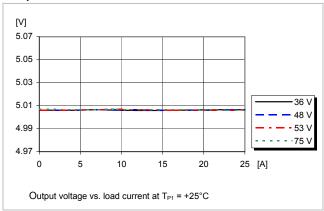
Efficiency



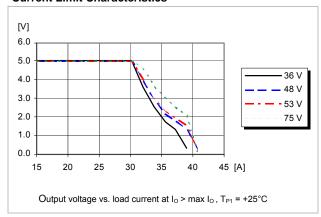
Power Dissipation



Output Characteristics



Current Limit Characteristics







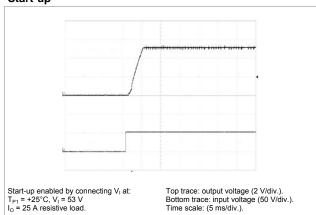
EN/LZT 146 416 R3A February 2010

© Ericsson AB

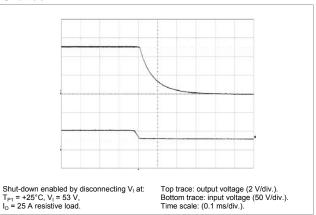
5.0V, 25A /125W Typical Characteristics

PKM 4111D PINB

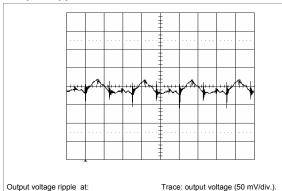
Start-up



Shut-down



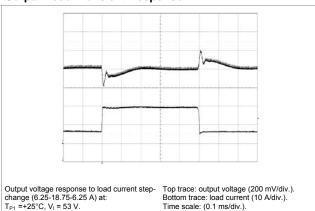
Output Ripple & Noise



Output voltage ripple at: T_{P1} = +25°C, V_I = 53 V, In = 25 A resistive load.

Trace: output voltage (50 mV/div.). Time scale: (2 μ s/div.).

Output Load Transient Response



Output Voltage Adjust (see operating information)

Passive adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$Radj = \left(\frac{5.11 \times 5.0 \left(100 + \Delta\%\right)}{1.225 \times \Delta\%} - \frac{511}{\Delta\%} - 10.22\right) \text{ k}\Omega$$

Example: Increase 4% =>Vout = 5.20 Vdc

$$\left(\frac{5.11 \times 5.0(100 + 4)}{1.225 \times 4} - \frac{511}{4} - 10.22\right) \text{ k}\Omega = 404.3 \text{ k}\Omega$$

Output Voltage Adjust Downwards, Increase:

$$Radj = 5.11 \left(\frac{100}{\Delta\%} - 2 \right) k\Omega$$

Example: Decrease 2% =>V_{out} = 4.90 Vdc

 $k\Omega = 404.32 \ k\Omega$

$$5.11 \left(\frac{100}{2} - 2 \right) \text{ k}\Omega = 245.3 \text{ k}\Omega$$



PKM 4000D PINB series

DC/DC converters, Input 36-75 V, Output up to 35 A/132 W

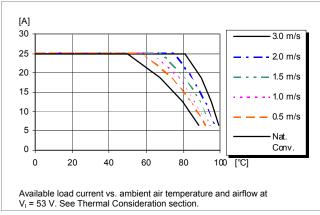
EN/LZT 146 416 R3A February 2010

© Ericsson AB

5.0V, 25A /125W Typical Characteristics

PKM 4111D PINB

Output Current Derating - Open frame

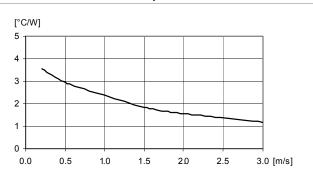


Output Current Derating - Base plate

[A] 30 -3.0 m/s 25 2.0 m/s 20 15 1.0 m/s 10 0.5 m/s 5 0 Conv 0 20 40 60 80 100 [°C]

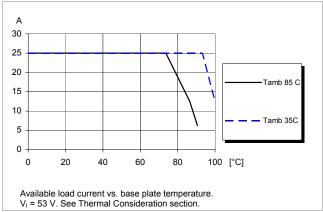
Available load current vs. ambient air temperature and airflow at V_1 = 53 V. See Thermal Consideration section.

Thermal Resistance - Base plate



Thermal resistance vs. airspeed measured at the converter. Tested in wind tunnel with airflow and test conditions as per the Thermal consideration section. $V_{\rm I}$ = 53 V.

Output Current Derating - Cold wall sealed box







| | • |
|--|----------------------------------|
| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

12V, 11A/132W Electrical Specification

PKM 4113D PINB

 T_{P1} = -40 to +90°C, V_I = 38 to 75 V, sense pins connected to output pins unless otherwise specified under Conditions. Typical values given at: T_{P1} = +25°C, V_I = 53 V_I max I_O , unless otherwise specified under Conditions. Additional C_{in} = 0 μ F.See Operating Information section for selection of capacitor types.

| $\begin{array}{c} V_{Oi} & accuracy \\ & accuracy \\ \hline & Output adjust \\ Output voltag \\ \hline & Output voltag \\ \hline & Idling voltage \\ \hline & Line regulation \\ \hline & Load transier \\ voltage devia \\ \hline & t_r & Load transier \\ t_r & Ramp-up time \\ (from 10-90 \%) \\ \hline & t_s & Start-up time \\ (from V_i connect the form V_i off to 1 \\ \hline & RC start-up time \\ & RC start-$ | et voltage t capacitance er pation cower by power equency ge initial setting and | Decreasing input voltage Increasing input voltage 50 % of max I _O max I _O 50 % of max I _O , V _I = 48 V max I _O , V _I = 48 V max I _O I _O = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _O T _{P1} = +25°C, V _I = 53 V, I _O = 40 A | 30 32 0 | 31 33 6.0 93.5 94.2 93.8 94.3 8.1 2.7 0.14 | 32 34 132 | V V μF W |
|---|---|--|---------------|---|-----------------|-----------------------|
| $\begin{array}{c c} C_1 & \text{Internal input} \\ P_O & \text{Output power} \\ \hline \\ P_O & \text{Output power} \\ \hline \\ P_D & \text{Output power} \\ \hline \\ P_D & \text{Power Dissip} \\ P_D & \text{Input idling power} \\ P_D & \text{Input idling power} \\ \hline \\ V_O & \text{Output voltag accuracy} \\ \hline \\ V_O & \text{Output voltag accuracy} \\ \hline \\ V_O & \text{Idling voltage} \\ \hline \\ Line regulation \\ Load regulation \\ Load transier voltage deviate \\ V_{tr} & \text{Load transier voltage deviate} \\ \hline \\ V_T & \text{Ramp-up time (from V_1 connectors)} \\ \hline \\ V_T & \text{Shut-down (from V_1 off to 1)} \\ \hline \\ RC & \text{Start-up time (from V_1 off to 1)} \\ \hline \\ RC & \text{Start-up time (from V_1 off to 1)} \\ \hline \\ RC & \text{Start-up time (from V_2 off to 1)} \\ \hline \\ RC & \text{Start-up time (from V_3 off to 1)} \\ \hline \\ RC & \text{Start-up time (from RC off to 1)} \\ \hline \\ RC & \text{Output currer} \\ \hline \\ \end{array}$ | pation ower by power equency ge initial setting and | 50 % of max I _O max I _O 50 % of max I _O , V _I = 48 V max I _O , V _I = 48 V max I _O I _O = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _O | 0 | 93.5 94.2 93.8 94.3 8.1 2.7 0.14 | 132 | μF W % |
| $\begin{array}{cccc} P_{O} & \text{Output power} \\ \\ P_{d} & \text{Power Dissip} \\ P_{li} & \text{Input idling pr} \\ P_{RC} & \text{Input standby} \\ f_{s} & \text{Switching free} \\ \\ V_{Oi} & \begin{array}{ccccc} \text{Output voltag} \\ \text{accuracy} \\ \\ \text{Output voltag} \\ \\ \text{Output voltage} \\ \\ \text{Line regulatio} \\ \text{Load regulatio} \\ \text{Load transier} \\ voltage devia \\ \\ t_{r} & \text{Load transier} \\ t_{r} & \text{Ramp-up time} \\ \text{(from 10-90 \%} \\ \\ t_{s} & \begin{array}{ccccc} \text{Start-up time} \\ \text{(from V}_{i} \text{ connect} \\ \\ \text{Incominion of the properties} \\ \\ \text{Connect} \\ \\ \text{Connect} \\ \\ \text{RC start-up time} \\ \\ \text{(from RC off to 100 m)} \\ \\ \text{RC start-up time} \\ \\ \text{Connect} $ | pation power y power equency ge initial setting and | max I _o 50 % of max I _o , V _I = 48 V max I _o , V _I = 48 V max I _o I _o = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _o | | 93.5 94.2 93.8 94.3 8.1 2.7 0.14 | | - % - % |
| $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | pation ower y power equency ge initial setting and | max I _o 50 % of max I _o , V _I = 48 V max I _o , V _I = 48 V max I _o I _o = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _o | | 94.2 93.8 94.3 8.1 2.7 0.14 | | - % - W |
| $\begin{array}{c c} P_d & Power Dissip \\ P_{li} & Input idling po \\ P_{RC} & Input standby \\ f_s & Switching free \\ \hline \\ V_{Oi} & Output voltag \\ accuracy \\ \hline \\ Output voltag \\ Output voltag \\ Idling voltage \\ Line regulation \\ Load regulation \\ Load transier \\ voltage devia \\ t_r & Load transier \\ t_r & Ramp-up time \\ (from V_1 connect \\ from V_1 connect \\ t_r & V_1 shut-down \\ (from V_1 off to 1) \\ \hline \\ RC start-up time \\ (from RC off to 1) \\ \hline \\ RC shut-down \\ (from RC off to 1) \\ \hline \\ RC & Output currer \\ \hline \end{array}$ | y power equency ge initial setting and | max I _o 50 % of max I _o , V _I = 48 V max I _o , V _I = 48 V max I _o I _o = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _o | 180 | 94.2 93.8 94.3 8.1 2.7 0.14 | 12 | W |
| $\begin{array}{c c} P_d & Power Dissip \\ P_{li} & Input idling po \\ P_{RC} & Input standby \\ f_s & Switching free \\ \hline \\ V_{Oi} & Output voltag \\ accuracy \\ \hline \\ Output voltag \\ Output voltag \\ Idling voltage \\ Line regulation \\ Load regulation \\ Load transier \\ voltage devia \\ t_r & Load transier \\ t_r & Ramp-up time \\ (from V_1 connect \\ from V_1 connect \\ t_r & V_1 shut-down \\ (from V_1 off to 1) \\ \hline \\ RC start-up time \\ (from RC off to 1) \\ \hline \\ RC shut-down \\ (from RC off to 1) \\ \hline \\ RC & Output currer \\ \hline \end{array}$ | y power equency ge initial setting and | 50 % of max I_0 , V_1 = 48 V max I_0 , V_1 = 48 V max I_0 I_0 = 0 A, V_1 = 53 V V_1 = 53 V (turned off with RC) 0-100 % of max I_0 | 180 | 93.8 94.3 8.1 2.7 0.14 | 12 | W |
| $\begin{array}{c c} P_d & Power Dissip \\ P_{li} & Input idling po \\ P_{RC} & Input standby \\ f_s & Switching free \\ \hline \\ V_{Oi} & Output voltag \\ accuracy \\ \hline \\ Output voltag \\ Output voltag \\ Idling voltage \\ Line regulation \\ Load regulation \\ Load transier \\ voltage devia \\ t_r & Load transier \\ t_r & Ramp-up time \\ (from V_1 connect \\ from V_1 connect \\ t_r & V_1 shut-down \\ (from V_1 off to 1) \\ \hline \\ RC start-up time \\ (from RC off to 1) \\ \hline \\ RC shut-down \\ (from RC off to 1) \\ \hline \\ RC & Output currer \\ \hline \end{array}$ | y power equency ge initial setting and | $\begin{array}{llllllllllllllllllllllllllllllllllll$ | 180 | 94.3 8.1 2.7 0.14 | 12 | W |
| $\begin{array}{c c} P_{li} & Input idling poly \\ P_{RC} & Input standby \\ f_s & Switching free \\ \hline \\ V_{Oi} & Output voltag \\ accuracy \\ Output adjust \\ Output voltag \\ Idling voltage \\ Line regulation \\ Load regulation \\ Load transier \\ voltage devia \\ t_{tr} & Load transier \\ voltage devia \\ t_{r} & Load transier \\ t_{r} & Ramp-up time \\ (from 10-90 \%) \\ t_{s} & Start-up time \\ (from V_{i} connect \\ t_{f} & V_{i} shut-down \\ (from V_{i} off to 1) \\ \hline \\ RC start-up time \\ (from RC off to 1) \\ \hline \\ RC shut-down \\ (from RC off to 1) \\ \hline \\ Output currer \\ \hline \end{array}$ | y power equency ge initial setting and | max I _o I _o = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _o | 180 | 8.1 2.7 0.14 | 12 | |
| $\begin{array}{c c} P_{li} & Input idling poly \\ P_{RC} & Input standby \\ f_s & Switching free \\ \hline \\ V_{Oi} & Output voltag \\ accuracy \\ Output adjust \\ Output voltag \\ Idling voltage \\ Line regulation \\ Load regulation \\ Load transier \\ voltage devia \\ t_{tr} & Load transier \\ voltage devia \\ t_{r} & Load transier \\ t_{r} & Ramp-up time \\ (from 10-90 \%) \\ t_{s} & Start-up time \\ (from V_{i} connect \\ t_{f} & V_{i} shut-down \\ (from V_{i} off to 1) \\ \hline \\ RC start-up time \\ (from RC off to 1) \\ \hline \\ RC shut-down \\ (from RC off to 1) \\ \hline \\ Output currer \\ \hline \end{array}$ | y power equency ge initial setting and | I _O = 0 A, V _I = 53 V V _I = 53 V (turned off with RC) 0-100 % of max I _O | 180 | 2.7 0.14 | 12 | |
| $\begin{array}{c c} P_{RC} & Input standby \\ f_s & Switching free \\ \hline \\ V_{Oi} & Output voltage accuracy \\ \hline \\ Output adjust \\ Output voltage \\ Idling voltage \\ Ine regulation \\ Ine regul$ | y power equency ge initial setting and | V _I = 53 V (turned off with RC) 0-100 % of max I _O | 180 | 0.14 | | ۱۸/ |
| $\begin{array}{c c} f_s & Switching free \\ \hline \\ V_{Oi} & Output voltag \\ accuracy \\ \hline \\ V_O & Output voltag \\ \hline \\ Output voltag \\ \hline \\ Uotput Voltag \\ \hline \\ V_t \\ $ | equency | 0-100 % of max I _O | 180 | | | VV |
| $V_{Oi} \qquad \begin{array}{c} Output \ voltag\\ accuracy \\ \hline \\ Output \ adjust \\ \hline \\ Output \ voltag\\ \hline \\ Output \ voltag\\ \hline \\ Utput \ voltage \\ \hline \\ Idling \ voltage \\ \hline \\ Line \ regulatio \\ \hline \\ Load \ transier \\ voltage \ devia \\ \hline \\ t_r \qquad Load \ transier \\ voltage \ devia \\ \hline \\ t_r \qquad Load \ transier \\ \hline \\ Ramp-up \ time \\ (from \ 10-90\ \% \\ \hline \\ t_s \qquad Start-up \ time \\ (from \ V_i \ connect \\ \hline \\ V_i \ shut-down \\ (from \ V_i \ off \ to \ 1) \\ \hline \\ RC \ start-up \ time \\ (from \ V_i \ off \ to \ 1) \\ \hline \\ RC \ shut-down \\ (from \ RC \ off \ to \ 1) \\ \hline \\ I_O \qquad Output \ currer \\ \hline \end{array}$ | ge initial setting and | | 180 | 200 | | W |
| $\begin{array}{c} V_{Oi} & accuracy \\ & accuracy \\ \hline & Output adjust \\ Output voltag \\ \hline & Output voltag \\ \hline & Idling voltage \\ \hline & Line regulation \\ \hline & Load transier \\ voltage devia \\ \hline & t_r & Load transier \\ t_r & Ramp-up time \\ (from 10-90 \%) \\ \hline & t_s & Start-up time \\ (from V_i connect the form V_i off to 1 \\ \hline & RC start-up time \\ & RC start-$ | | T _{P1} = +25°C, V _I = 53 V, I _O = 40 A | | 200 | 220 | kHz |
| $\begin{array}{c} V_{Oi} & accuracy \\ & accuracy \\ \hline & Output adjust \\ Output voltag \\ \hline & Output voltag \\ \hline & Idling voltage \\ \hline & Line regulation \\ \hline & Load transier \\ voltage devia \\ \hline & t_r & Load transier \\ t_r & Ramp-up time \\ (from 10-90 \%) \\ \hline & t_s & Start-up time \\ (from V_i connect the form V_i off to 1 \\ \hline & RC start-up time \\ & RC start-$ | | T _{P1} = +25°C, V _I = 53 V, I _O = 40 A | | | - | |
| $V_{O} \begin{tabular}{ll} \hline Output voltag \\ \hline Output voltag \\ \hline Idling voltage \\ \hline Line regulation \\ \hline Load regulation \\ \hline Load transier \\ voltage devia \\ \hline t_{r} \begin{tabular}{ll} Load transier \\ voltage devia \\ \hline t_{r} \begin{tabular}{ll} Load transier \\ \hline Load transier \\ \hline t_{r} \begin{tabular}{ll} Ramp-up time \\ (from 10-90 \%) \\ \hline t_{s} \begin{tabular}{ll} Start-up time \\ (from V_{1} connect \\ from V_{1} off to 1) \\ \hline \hline RC start-up time \\ RC start-up time \\ (from RC off to 1) \\ \hline \\ RC \begin{tabular}{ll} RC \begin{tabular}{ll} RC \begin{tabular}{ll} Start-up time \\ (from V_{1} connect \\ from V_{2} connect \\ \hline \\ RC \begin{tabular}{ll} Start-up time \\ (from V_{2} connect \\ from V_{3} connect \\ \hline \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ $ | A | | 11.8 | 12 | 12.2 | V |
| Vo | t range | See operating information | 10.8 | | 13.2 | V |
| $\begin{array}{c c} & \\ \hline Line\ regulatio \\ \hline Load\ regulatio \\ \hline V_{tr} & Load\ transier \\ voltage\ devia \\ t_{tr} & Load\ transier \\ \hline t_r & Ramp-up\ time \\ (from\ 10-90\ \% \\ t_s & Start-up\ time \\ (from\ V_i\ connect \\ t_f & V_i\ shut-down \\ (from\ V_i\ off\ to\ 1) \\ \hline \hline RC\ start-up\ time \\ RC\ shut-down \\ (from\ RC\ off\ to\ 1) \\ \hline \ RC\ shut-down \\ (from\ RC\ off\ to\ 1) \\ \hline \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$ | ge tolerance band | 0-100 % of max I _O | 11.7 | | 12.3 | V |
| $\begin{tabular}{l l l l l l l l l l l l l l l l l l l $ | Э | I _O = 0 A | 11.8 | | 12.2 | V |
| $\begin{array}{ccc} V_{tr} & Load \ transier \\ voltage \ devia \\ t_{tr} & Load \ transier \\ t_{r} & Ramp-up \ time \\ (from \ 10-90 \ \% \\ t_{s} & Start-up \ time \\ (from \ V_{i} \ connect \\ t_{f} & V_{i} \ shut-down \\ (from \ V_{i} \ off \ to \ 1 \\ \hline RC \ start-up \ time \\ RC \ shut-down \\ (from \ RC \ off \ to \ 1 \\ \hline I_{O} & Output \ currer \\ \end{array}$ | on | max I _o | | 10 | 20 | mV |
| $\begin{array}{lll} V_{tr} & \text{voltage devia} \\ t_{tr} & \text{Load transier} \\ t_{r} & \text{Ramp-up time} \\ (from 10-90 \%) \\ t_{s} & \text{Start-up time} \\ (from V_{i} \text{ connect}) \\ t_{f} & V_{i} \text{ shut-down} \\ (from V_{i} \text{ off to 1}) \\ \hline & \text{RC start-up time} \\ \text{RC shut-down} \\ (from RC \text{ off to}) \\ \hline l_{O} & \text{Output currer} \end{array}$ | ion | V _I = 53 V, 0-100 % of max I _O | | 10 | 20 | mV |
| $\begin{array}{lll} t_r & Ramp-up \ time \\ (from \ 10-90 \ \% \\ t_s & Start-up \ time \\ (from \ V_i \ connect \\ t_f & V_i \ shut-down \\ (from \ V_i \ off \ to \ 1 \\ \hline RC \ start-up \ time \\ RC \ shut-down \\ (from \ RC \ off \ to \ 1 \\ \hline Output \ currer \end{array}$ | | V _i = 53 V, Load step 25-75-25 % of | | ±300 | ±450 | mV |
| $\begin{array}{ccc} t_r & & & & & & \\ & & & & & & \\ t_s & & & & & \\ & & & & & \\ Start-up time \\ & & & & \\ from \ V_1 connec \\ & & & \\ t_f & & & & \\ V_1 shut-down \\ & & & \\ from \ V_1 off to 1 \\ & & \\ & & & \\ RC \ start-up \ ti \\ & & \\ RC \ shut-dow \\ & & \\ from \ RC \ off \ to \\ & & \\ I_O & & \\ Output \ currer \end{array}$ | nt recovery time | max I _o , di/dt = 5A/µs,see Note 1 | | 100 | 170 | μs |
| $\begin{array}{c} t_s & (\text{from V}_i \text{ connect} \\ t_f & V_i \text{ shut-down} \\ (\text{from V}_i \text{ off to 1} \\ \hline & RC \text{ start-up ti} \\ \hline & RC \text{ shut-dow} \\ (\text{from RC off to} \\ \hline & I_O & \text{Output currer} \\ \end{array}$ | | 10-100 % of max I _O | 4 | 6 | 20 | ms |
| $ \begin{array}{c} t_{\rm f} & ({\rm from} \ V_{\rm l} {\rm off} \ {\rm to} \ 1 \\ & {\rm RC \ start-up \ ti} \\ & {\rm RC \ shut-dow} \\ ({\rm from} \ {\rm RC \ off \ to} \ 1 \\ & {\rm Output \ currer} \end{array} $ | ection to 90 % of V _{Oi}) | 10 100 % of max 10 | 6 | 8 | 20 | ms |
| RC start-up ti RC shut-dow (from RC off to | | max I _o | | 0.3 | | ms |
| t_{RC} RC shut-dow (from RC off to I_{O} Output currer | | I _O = 0 A | | 9 | | S |
| (from RC off to Output currer | ime | max I _O | | 8 | | ms |
| I _o Output currer | | max I _O | | 0.3 | | ms |
| · · | | I _O = 0 A | | 9 | | S |
| | | | 0 | | 11 | Α |
| | | $T_{P1} < max T_{P1}$ | 12 | 15 | 19 | Α |
| I _{sc} Short circuit of | threshold | T _{P1} = 25°C, see Note 2 | | 21 | | Α |
| C _{out} Recommende | current | T_{P1} = 25°C, see Note 3 | 0 | | 1100 | μF |
| V _{Oac} Output ripple | | | | 100 | 150 | mVp-p |
| OVP Over voltage | current led Capacitive Load | See ripple & noise section, max I ₀ , V ₀ T _{P1} = +25°C, V ₁ = 53 V, 0-100 % of | | | | |

Note 2: short circuit load is 5mohm.

Note 3: Aluminium electrolytic capacitors, ESR is lower than 10 mohm.





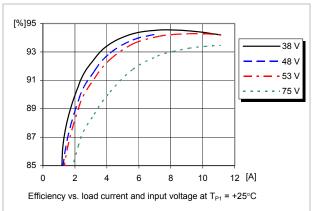
EN/LZT 146 416 R3A February 2010

© Ericsson AB

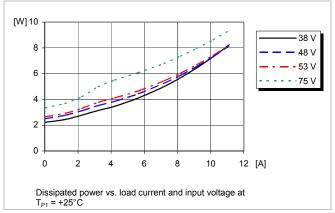
12V, 11A /132W Typical Characteristics

PKM 4113D PINB

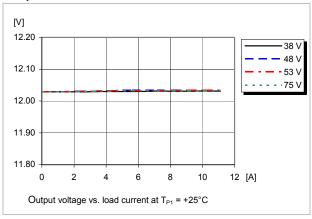
Efficiency



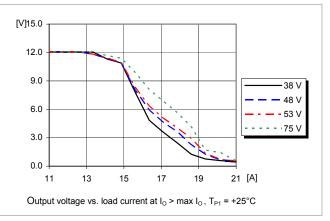
Power Dissipation



Output Characteristics



Current Limit Characteristics





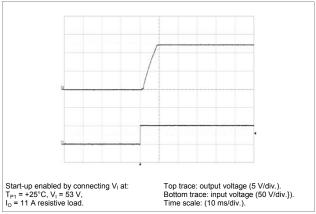


EN/LZT 146 416 R3A February 2010 PKM 4000D PINB series DC/DC converters, Input 36-75 V, Output up to 35 A/132 W © Ericsson AB

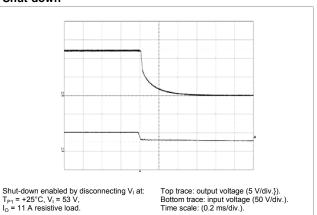
12V, 11A /132W Typical Characteristics

PKM 4113D PINB

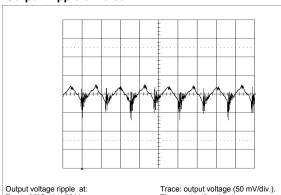




Shut-down



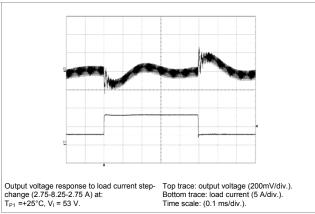
Output Ripple & Noise



Output voltage ripple at: T_{P1} = +25°C, V_I = 53 V, I_O = 11 A resistive load.

Trace: output voltage (50 mV/div.). Time scale: (2 μ s/div.).

Output Load Transient Response



Output Voltage Adjust (see operating information)

Passive adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

Radj =
$$\left(\frac{5.11 \times 12 \times (100 + \Delta\%)}{1.225 \times \Delta\%} - \frac{511}{\Delta\%} - 10.22\right) \text{ k}\Omega$$

Example: Increase 4% =>Vout = 12.48 Vdc

$$\left(\frac{5.11 \times 12 \times (100 + 4)}{1.225 \times 4} - \frac{511}{4} - 10.22\right) \text{ k}\Omega = 1163.5 \text{ k}\Omega$$

Output Voltage Adjust Downwards, Increase:

$$Radj = 5.11 \left(\frac{100}{\Delta\%} - 2 \right) \text{ k}\Omega$$

Example: Decrease 2% =>Vout = 11.76 Vdc

$$5.11\left(\frac{100}{2} - 2\right) \text{ k}\Omega = 245.3 \text{ k}\Omega$$



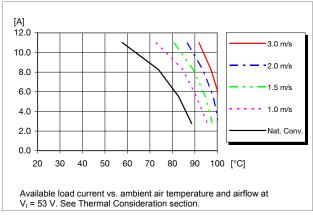


| | • |
|--|----------------------------------|
| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

12V, 11A /132W Typical Characteristics

PKM 4113D PINB

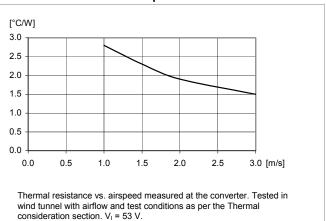
Output Current Derating - Open frame



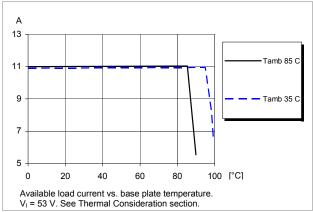
Output Current Derating - Base plate

12.0 10.0 2.0 m/s 8.0 1.5 m/s 6.0 1.0 m/s 4.0 Nat. Conv. 2.0 0.0 40 50 60 70 80 90 100 [°C] Available load current vs. ambient air temperature and airflow at V_I = 53 V. See Thermal Consideration section.

Thermal Resistance - Base plate



Output Current Derating - Cold wall sealed box





Technical Specification



PKM 4000D PINB series

DC/DC converters, Input 36-75 V, Output up to 35 A/132 W

EN/LZT 146 416 R3A February 2010

© Ericsson AB

15V, 8A /120W Electrical Specification

PKM 4115D PINB

 T_{P1} = -40 to +90°C, V_1 = 36 to 75 V, sense pins connected to output pins unless otherwise specified under Conditions. Typical values given at: T_{P1} = +25°C, V_1 = 53 V_1 max I_0 , unless otherwise specified under Conditions. Additional C_{in} = 0 μ F.See Operating Information section for selection of capacitor types.

| eristics | Conditions | min | typ | max | Unit | |
|---|--|-------|---------------------|---------------------|---------------------|--|
| Input voltage range | | 36 | | 75 | ٧ | |
| Turn-off input voltage | Decreasing input voltage 29.0 | | 31.3 | 33.0 | V | |
| Turn-on input voltage | Increasing input voltage | 32.0 | 33.9 | 35.5 | V | |
| Internal input capacitance | | | 6.0 | | μF | |
| Output power | | 0 | | 120 | W | |
| | 50 % of max I _O | | 91.4 | | | |
| Efficiency | max I _O | | 92.7 | | 1 | |
| Eniciency | 50 % of max I _O , V _I = 48 V | | 92.0 | | - % | |
| | max I _O , V _I = 48 V | | 92.9 | | 1 | |
| Power Dissipation | max I ₀ | | 9.4 | 13 | W | |
| Input idling power | I _O = 0 A, V _I = 53 V | | 4.0 | | W | |
| Input standby power | V _I = 53 V (turned off with RC) | | 0.11 | | W | |
| Switching frequency | 0-100 % of max I _O | 180 | 200 | 220 | kHz | |
| | | | | | 1 | |
| Output voltage initial setting and accuracy | T _{P1} = +25°C, V _I = 53 V, I _O = 8 A | 14.70 | 15.00 | 15.30 | V | |
| Output adjust range | See operating information | 12.00 | | 16.50 | V | |
| Output voltage tolerance band | 0-100 % of max I _O | 14.55 | | 15.45 | V | |
| Idling voltage | I _O = 0 A | 14.70 | | 15.30 | V | |
| Line regulation | max I _O , see Note 1 | | 2 | 30 | mV | |
| Load regulation | V _I = 53 V, 0-100 % of max I _O | | 8 | 20 | mV | |
| Load transient voltage deviation | V _I = 53 V, Load step 25-75-25 % of max I _o , di/dt = 1 A/μs | | ±300 | ±550 | mV | |
| Load transient recovery time | see Note 2 | | 260 | 300 | μs | |
| Ramp-up time (from 10-90 % of V _{Oi}) | 10-100 % of max lo | 9 | 11 | 15 | ms | |
| Start-up time (from V _I connection to 90 % of V _{Oi}) | - | 15 | 20 | 30 | ms | |
| V _I shut-down fall time | max I _o | | | | ms | |
| | | | | | S | |
| | - | | | | ms | |
| | - | | | | ms | |
| | I _O = 0 A | 0 | 2.4 | 0 | S | |
| • | | - | 11.0 | | A | |
| | | 9 | | | A | |
| | | | 14 | | A | |
| Recommended Capacitive Load | | U | | 800 | μF | |
| Output ripple & noise | max I _O , V _{Oi} | | 50 | 150 | mVp-p | |
| Over voltage protection | T_{P1} = +25°C, V_1 = 53 V, 0-100 % of max I_0 | | 19.2 | | V | |
| | Input voltage range Turn-off input voltage Turn-on input voltage Internal input capacitance Output power Efficiency Power Dissipation Input idling power Input standby power Switching frequency Output voltage initial setting and accuracy Output adjust range Output voltage tolerance band Idling voltage Line regulation Load regulation Load transient voltage deviation Load transient recovery time Ramp-up time (from 10-90 % of V _{OI}) Start-up time (from V _I connection to 90 % of V _{OI}) V _I shut-down fall time (from V _I of to 10 % of V _O) RC start-up time RC shut-down fall time (from RC off to 10 % of V _O) Output current Current limit threshold Short circuit current Recommended Capacitive Load Output ripple & noise | | Input voltage range | Input voltage range | Input voltage range | |

Note 1: There can be some voltage drop at Vin<38V, full load, easier to occur at high temperature.

Note 2: one 470uF +one 330uF low ESR electrolytic capacitors are connected to the module.

Note 3: Aluminium electrolytic capacitors, ESR is lower than 10m ohm.





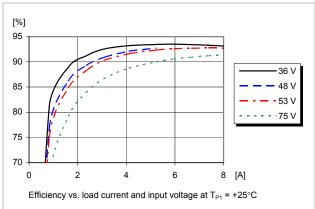
EN/LZT 146 416 R3A February 2010

© Ericsson AB

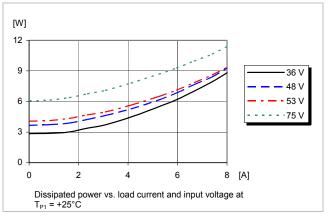
15V, 8A /120W Typical Characteristics

PKM 4115D PINB

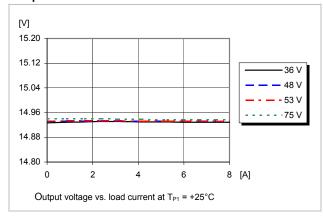
Efficiency



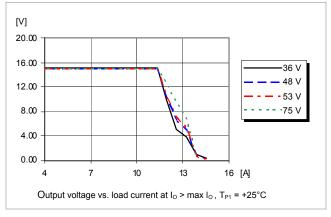
Power Dissipation



Output Characteristics



Current Limit Characteristics







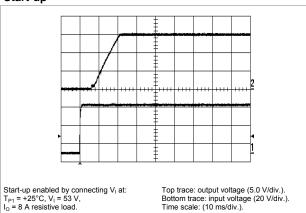
EN/LZT 146 416 R3A February 2010

© Ericsson AB

15V, 8A /120W Typical Characteristics

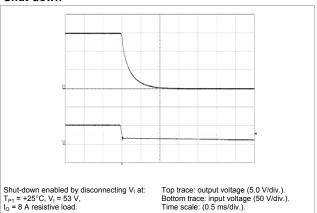
PKM 4115D PINB

Start-up



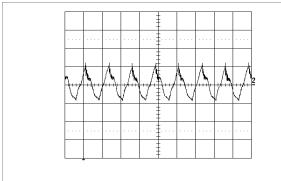
Bottom trace: input voltage (20 V/div.). Time scale: (10 ms/div.).

Shut-down



Bottom trace: input voltage (50 V/div.). Time scale: (0.5 ms/div.).

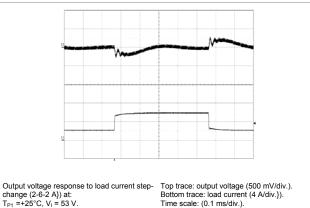
Output Ripple & Noise



Output voltage ripple at: T_{P1} = +25°C, V_I = 53 V, In = 8 A resistive load.

Trace: output voltage (20 mV/div.). Time scale: (2 μ s/div.).

Output Load Transient Response



Output Voltage Adjust (see operating information)

Passive adjust

The resistor value for an adjusted output voltage is calculated by using the following equations:

Output Voltage Adjust Upwards, Increase:

$$Radj = \left(\frac{5.11 \times 15(100 + \Delta\%)}{1.225 \times \Delta\%} - \frac{511}{\Delta\%} - 10.22\right) k\Omega$$

Example: Increase 4% =>V_{out} = 15.6 Vdc

$$\left(\frac{5.11 \times 15(100 + 4)}{1.225 \times 4} - \frac{511}{4} - 10.22\right) k\Omega = 1488.89 \, k\Omega$$

Output Voltage Adjust Downwards, decrease:

$$Radj = 5.11 \left(\frac{100}{\Delta\%} - 2 \right) \text{ k}\Omega$$

Example: Decrease 2% =>V_{out} = 14.7 Vdc

$$5.11\left(\frac{100}{2} - 2\right) \text{ k}\Omega = 245.3 \text{ k}\Omega$$



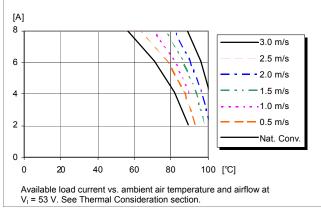


| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| | © Ericsson AB |
| Do/Do converters, input 30-73 v, Output up to 33 A/ 132 vv | C Encodon / LD |

15V, 8A /120W Typical Characteristics

PKM 4115D PINB

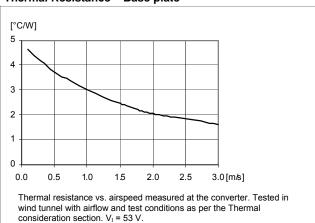
Output Current Derating - Open frame



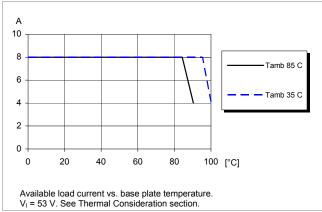
Output Current Derating – Base plate

[A] 8 3.0 m/s 2.5 m/s 6 2.0 m/s 1.5 m/s 1.0 m/s 0.5 m/s 2 Nat. Conv. 40 60 80 100 [℃] Available load current vs. ambient air temperature and airflow at V_I = 53 V. See Thermal Consideration section.

Thermal Resistance - Base plate



Output Current Derating - Cold wall sealed box



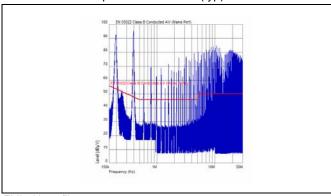


| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

EMC Specification

Conducted EMI measured according to EN55022, CISPR 22 and FCC part 15J (see test set-up). See Design Note 009 for further information. The fundamental switching frequency is 200 kHz for PKM 4111D PINB@ $V_I = 53 \text{ V}$, max I_O .

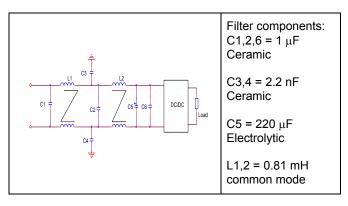
Conducted EMI Input terminal value (typ)

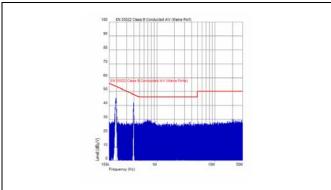


EMI without filter

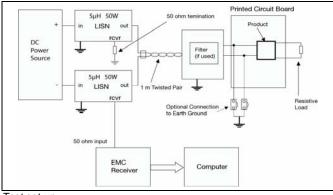
External filter (class B)

Required external input filter in order to meet class B in EN 55022, CISPR 22 and FCC part 15J.





EMI with filter



Test set-up

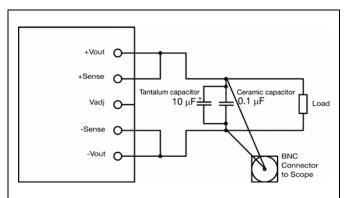
Layout recommendations

The radiated EMI performance of the Product will depend on the PCB layout and ground layer design. It is also important to consider the stand-off of the product. If a ground layer is used, it should be connected to the output of the product and the equipment ground or chassis.

A ground layer will increase the stray capacitance in the PCB and improve the high frequency EMC performance.

Output ripple and noise

Output ripple and noise measured according to figure below. See Design Note 022 for detailed information.



Output ripple and noise test setup



| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

Operating information

Input Voltage

The input voltage range 36 to 75Vdc meets the requirements of the European Telecom Standard ETS 300 132-2 for normal input voltage range in –48 and –60 Vdc systems, -40.5 to -57.0 V and –50.0 to -72 V respectively.

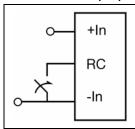
At input voltages exceeding 75 V, the power loss will be higher than at normal input voltage and T_{P1} must be limited to absolute max +110°C. The absolute maximum continuous input voltage is 80 Vdc.

Turn-off Input Voltage

The products monitor the input voltage and will turn on and turn off at predetermined levels.

The minimum hysteresis between turn on and turn off input voltage is 1V.

Remote Control (RC)



The products are fitted with a remote control function referenced to the primary negative input connection (-In), with negative and positive logic options available. The RC function allows the product to be turned on/off by an external device like a semiconductor or mechanical switch.

The maximum required sink current is 1 mA. When the RC pin is left open, the voltage generated on the RC pin is 5.0-7.0 V. The standard product is provided with "negative logic" remote control and will be off until the RC pin is connected to the -In. To turn on the product the voltage between RC pin and -In should be less than 1V. To turn off the converter the RC pin should be left open, or connected to a voltage higher than 13 V referenced to -In. In situations where it is desired to have the product to power up automatically without the need for control signals or a switch, the RC pin can be wired directly to -In.

The second option is "positive logic" remote control, which can be ordered by adding the suffix "P" to the end of the part number. When the RC pin is left open, the product starts up automatically when the input voltage is applied. Turn off is achieved by connecting the RC pin to the -In. To ensure safe turn off the voltage difference between RC pin and the -In pin shall be less than 1V. The product will restart automatically when this connection is opened.

See Design Note 021 for detailed information.

Input and Output Impedance

The impedance of both the input source and the load will interact with the impedance of the product. It is important that the input source has low characteristic impedance. The products are designed for stable operation without external capacitors connected to the input or output. The performance

in some applications can be enhanced by addition of external capacitance as described under External Decoupling Capacitors.

If the input voltage source contains significant inductance, the addition of a 22 - 100 μF capacitor across the input of the product will ensure stable operation. The capacitor is not required when powering the product from an input source with an inductance below 10 μH . The minimum required capacitance value depends on the output power and the input voltage. The higher output power the higher input capacitance is needed. Approximately doubled capacitance value is required for a 24 V input voltage source compared to a 48V input voltage source.

External Decoupling Capacitors

When powering loads with significant dynamic current requirements, the voltage regulation at the point of load can be improved by addition of decoupling capacitors at the load. The most effective technique is to locate low ESR ceramic and electrolytic capacitors as close to the load as possible, using several parallel capacitors to lower the effective ESR. The ceramic capacitors will handle high-frequency dynamic load changes while the electrolytic capacitors are used to handle low frequency dynamic load changes. It is equally important to use low resistance and low inductance PCB layouts and cabling.

External decoupling capacitors will become part of the product's control loop. The control loop is optimized for a wide range of external capacitance and the maximum recommended value that could be used without any additional analysis is found in the Electrical specification.

The ESR of the capacitors is a very important parameter. Stable operation is guaranteed with a verified ESR value of >5 m Ω across the output connections.

For further information please contact your local Ericsson Power Modules representative.

Output Voltage Adjust (Vadj)

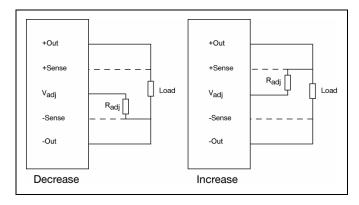
The products have an Output Voltage Adjust pin (V_{adj}) . This pin can be used to adjust the output voltage above or below Output voltage initial setting.

When increasing the output voltage, the voltage at the output pins (including any remote sense compensation) must be kept below the threshold of the over voltage protection, (OVP) to prevent the product from shutting down. At increased output voltages the maximum power rating of the product remains the same, and the max output current must be decreased correspondingly.

To increase the voltage the resistor should be connected between the V_{adj} pin and +Sense pin. The resistor value of the Output voltage adjust function is according to information given under the Output section for the respective product. To decrease the output voltage, the resistor should be connected between the V_{adj} pin and —Sense pin.



EN/LZT 146 416 R3A February 2010
© Ericsson AB



Parallel Operation

Two products may be paralleled for redundancy if the total power is equal or less than P_{O} max. It is not recommended to parallel the products without using external current sharing circuits.

See Design Note 006 for detailed information.

Remote Sense

The products have remote sense that can be used to compensate for voltage drops between the output and the point of load. The sense traces should be located close to the PCB ground layer to reduce noise susceptibility. The remote sense circuitry will compensate for up to 10% voltage drop between output pins and the point of load.

If the remote sense is not needed +Sense should be connected to +Out and -Sense should be connected to -Out.

Over Temperature Protection (OTP)

The products are protected from thermal overload by an internal over temperature shutdown circuit.

When T_{P1} as defined in thermal consideration section exceeds 135°C the product will shut down. The product will make continuous attempts to start up (non-latching mode) and resume normal operation automatically when the temperature has dropped >15°C below the temperature threshold.

Over Voltage Protection (OVP)

The products have output over voltage protection that will shut down the product in over voltage conditions. The product will make continuous attempts to start up (non-latching mode) and resume normal operation automatically after removal of the over voltage condition.

Over Current Protection (OCP)

The products include current limiting circuitry for protection at continuous overload.

PKMD standard module, the output voltage will decrease towards zero for output currents in excess of max output current (lomax).

The converter will resume normal operation after removal of

the overload. The load distribution system should be designed to carry the maximum output short circuit current specified.

The PKMD series include hiccup OCP option, the output voltage will decrease when the output current in excess of its current limit point, when the load continue to increase to some higher level, the module will enter into hiccup mode.

During hiccup, the module will try to restart and shutdown again for the overload. When the overload is removed, the products will continue to work normally.

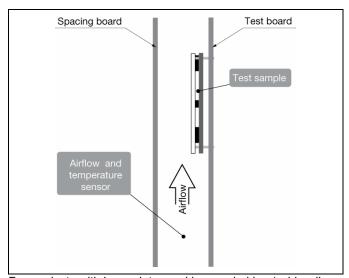
Thermal Consideration

General

The products are designed to operate in different thermal environments and sufficient cooling must be provided to ensure reliable operation.

For products mounted on a PCB without a heat sink attached, cooling is achieved mainly by conduction, from the pins to the host board, and convection, which is dependant on the airflow across the product. Increased airflow enhances the cooling of the product. The Output Current Derating graph found in the Output section for each model provides the available output current vs. ambient air temperature and air velocity at $V_1 = 53 \text{ V}$.

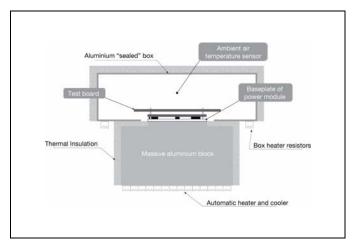
The product is tested on a 254 x 254 mm, 35 μ m (1 oz), 16-layer test board mounted vertically in a wind tunnel with a cross-section of 608 x 203 mm.

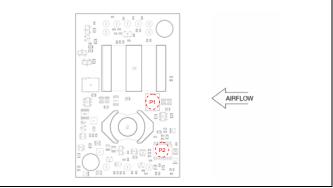


For products with base plate used in a sealed box/cold wall application, cooling is achieved mainly by conduction through the cold wall. The Output Current Derating graphs are found in the Output section for each module. The product is tested in a sealed box test set up with ambient temperatures 85 and 35°C. See Design Note 028 for further details.



EN/LZT 146 416 R3A February 2010 © Ericsson AB



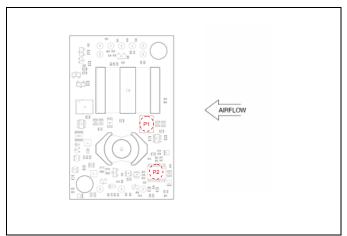


Base plate

Definition of product operating temperature

The product operating temperatures is used to monitor the temperature of the product, and proper thermal conditions can be verified by measuring the temperature at positions P1, P2. The temperature at these positions T_{P1} , T_{P2} should not exceed the maximum temperatures in the table below. The number of measurement points may vary with different thermal design and topology. Temperatures above maximum T_{P1} , measured at the reference point P1 are not allowed and may cause permanent damage.

| Position | Description | Max Temp. |
|----------|-------------|-------------------------|
| P1 | MOSFET | T _{P1} =125° C |
| P2 | Control IC | T _{P2} =125° C |



Open frame

Ambient Temperature Calculation

For products with base plate the maximum allowed ambient temperature can be calculated by using the thermal resistance.

- 1. The power loss is calculated by using the formula $((1/\eta) 1) \times$ output power = power losses (Pd). H = efficiency of product. E.g. 89.5% = 0.895
- 2. Find the thermal resistance (Rth) in the Thermal Resistance graph found in the Output section for each model. *Note that the thermal resistance can be significantly reduced if a heat sink is mounted on the top of the base plate.*

Calculate the temperature increase (ΔT). ΔT = Rth x Pd

3. Max allowed ambient temperature is: Max T_{P1} - ΔT .

E.g. PKM 4111D PINBat 1.5m/s:

1.
$$((\frac{1}{0.91}) - 1) \times 125 \text{ W} = 12.4\text{W}$$

2. $12.4 \text{ W} \times 3.5^{\circ}\text{C/W} = 43.4^{\circ}\text{C}$

3. $125 \,^{\circ}\text{C} - 43.4 \,^{\circ}\text{C} = \text{max}$ ambient temperature is $81.6 \,^{\circ}\text{C}$

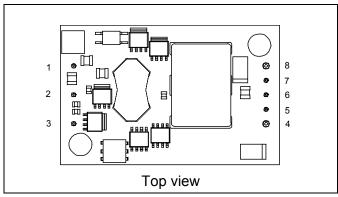
The actual temperature will be dependent on several factors such as the PCB size, number of layers and direction of airflow.





| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

Connections



| Pin | Designation | Function |
|-----|-------------|-----------------------|
| 1 | +In | Positive input |
| 2 | RC | Remote control |
| 3 | - In | Negative input |
| 4 | - Out | Negative output |
| 5 | - Sen | Negative remote sense |
| 6 | Vadj | Output voltage adjust |
| 7 | + Sen | Positive remote sense |
| 8 | + Out | Positive output |



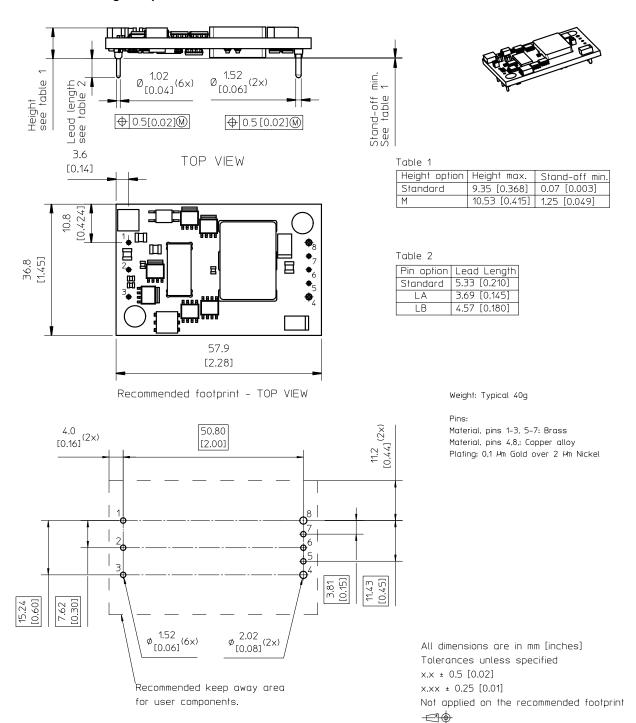
PKM 4000D PINB series

DC/DC converters, Input 36-75 V, Output up to 35 A/132 W

EN/LZT 146 416 R3A February 2010

© Ericsson AB

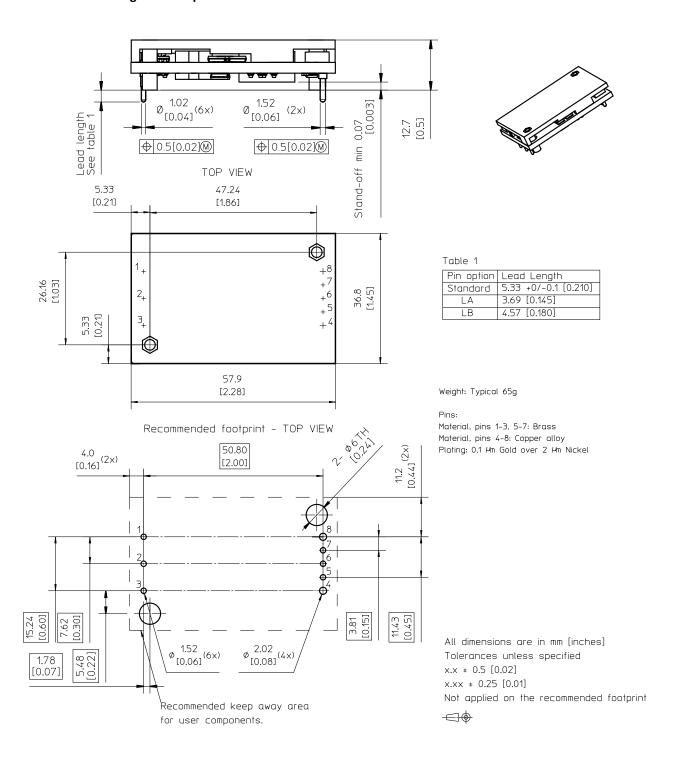
Mechanical Drawing for open frame with holes





| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

Mechanical Drawing for base plate with inserts





| PKM 4000D PINB series | EN/LZT 146 416 R3A February 2010 |
|--|----------------------------------|
| DC/DC converters, Input 36-75 V, Output up to 35 A/132 W | © Ericsson AB |

Soldering Information - Hole Mounting

The hole mounted product is intended for plated through hole mounting by wave or manual soldering. The pin temperature is specified to maximum to 270°C for maximum 10 seconds.

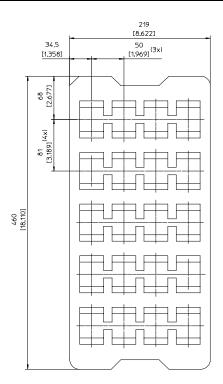
A maximum preheat rate of 4° C/s and maximum preheat temperature of 150° C is suggested. When soldering by hand, care should be taken to avoid direct contact between the hot soldering iron tip and the pins for more than a few seconds in order to prevent overheating.

A no-clean flux is recommended to avoid entrapment of cleaning fluids in cavities inside the product or between the product and the host board. The cleaning residues may affect long time reliability and isolation voltage.

Delivery Package Information

The products are delivered in antistatic trays

| The products and delivered in distinctions trays | | | |
|--|---|--|--|
| Tray Specifications | | | |
| Material | Antistatic PS | | |
| Surface resistance | 10 ⁵ < Ohm/square < 10 ¹² | | |
| Tray capacity | 20 products/tray | | |
| Tray weight | 140 g empty, 940 g full | | |
| Box capacity | 20 products/full box | | |





Technical Specification



PKM 4000D PINB series
DC/DC converters, Input 36-75 V, Output up to 35 A/132 W

EN/LZT 146 416 R3A February 2010
© Ericsson AB

Product Qualification Specification

| Characteristics | | | |
|---|-------------------------------------|--|--|
| | | | T The state of the |
| External visual inspection | IPC-A-610 | | |
| Change of temperature (Temperature cycling) | IEC 60068-2-14 Na | Temperature range Number of cycles Dwell/transfer time | -40 to 100°C 300 30 min/0-1 min |
| Cold (in operation) | IEC 60068-2-1 Ad | Temperature T _A Duration | -40°C 2 h |
| Damp heat | IEC 60068-2-67 Cy | Temperature Humidity Duration | 85°C 85 % RH 1000 hours |
| Storage test | IEC 60068-2-2 Ba | Temperature Duration | 125°C 1000 h |
| Immersion in cleaning solvents | IEC 60068-2-45 XA, method 2 | Water Glycol ether Isopropyl alcohol | 55°C 35°C 35°C |
| Mechanical shock | IEC 60068-2-27 Ea | Peak acceleration Duration Pulse shape Directions Number of pulses | 200 g 3 ms Half sine 6 18 |
| Solder heat stability | IEC 60068-2-20 Tb, method 1A | Solder temperature Duration | 260°C 10 s |
| Robustness of terminations | IEC 60068-2-21 Test Ua1 | Through hole mount products | All leads |
| Solder-ability | IEC 60068-2-58 test Td ¹ | Preconditioning Temperature, SnPb Eutectic Temperature, Pb-free | 150°C dry bake 16 h 215°C 235°C |
| Vibration random | IEC 60068-2-34 Eb, | Frequency Spectral density Duration | 10 to 500 Hz 0.025 g²/Hz 10 min in each 3 directions |
| Vibration sinusoidal | IEC 60068-2-6 Fc | Frequency Acceleration Duration | 10 to 500 Hz 10 g 2 h in each 3 directions |