

### **General Description**

The MAX31722/MAX31723 digital thermometers and thermostats with an SPITM/3-wire interface provide temperature readings that indicate the device temperature. No additional components are required; the devices are truly temperature-to-digital converters. Temperature readings are communicated from the device over an SPI interface or a 3-wire serial interface. The choice of interface is selectable by the user. For applications that require greater temperature resolution, the user can adjust the readout resolution from 9 to 12 bits. This is particularly useful in applications where thermal runaway conditions must be detected quickly. The thermostat has a dedicated open-drain output (TOUT). Two thermostat operating modes, comparator and interrupt, control thermostat operation based on user-defined nonvolatile trip points (THIGH and TLOW). Both devices feature a 1.7V to 3.7V supply rail.

### \_Applications

Networking Equipment
Cellular Base Stations
Industrial Equipment
Any Thermally Sensitive Systems

#### **Features**

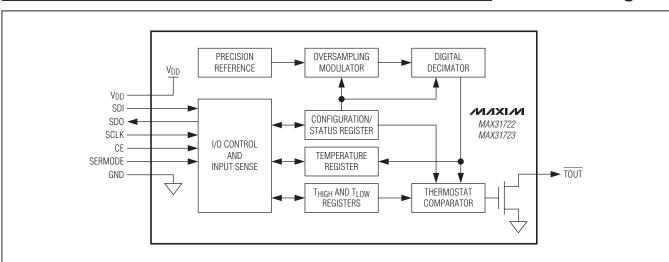
- ◆ Temperature Measurements Require No External Components
- ♦ Measures Temperatures from -55°C to +125°C
- ♦ MAX31722 Thermometer Accuracy is ±2.0°C
- ♦ MAX31723 Thermometer Accuracy is ±0.5°C
- ◆ Thermometer Resolution is Configurable from 9 to 12 Bits (0.5°C to 0.0625°C Resolution)
- Thermostat Output with User-Defined Nonvolatile Thresholds
- ◆ Data is Read from/Written to by SPI (Mode 0 and 2) or 3-Wire Serial Interface
- ♦ 1.7V to 3.7V Power-Supply Range
- ♦ Available in 8-Pin µMAX® Package

### **Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
<b>MAX31722</b> MUA+	-55°C to +125°C	8 µMAX
MAX31722MUA+T	-55°C to +125°C	8 µMAX
MAX31723MUA+	-55°C to +125°C	8 µMAX
MAX31723MUA+T	-55°C to +125°C	8 µMAX

<sup>+</sup>Denotes a lead(Pb)-free/RoHS-compliant package. T = Tape and reel.

### Functional Diagram



SPI is a trademark of Motorola, Inc.

µMAX is a registered trademark of Maxim Integrated Products, Inc.

Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

#### **ABSOLUTE MAXIMUM RATINGS**

Operating Junction Temperature Range55°C to	+125°C
Storage Temperature Range55°C to	+125°C
Lead Temperature (soldering, 10s)	.+300°C
Soldering Temperature (reflow)	.+260°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### RECOMMENDED OPERATING CHARACTERISTICS

 $(T_J = -55^{\circ}C \text{ to } +125^{\circ}C, \text{ unless otherwise noted.})$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP MAX	UNITS
Supply Voltage	$V_{DD}$	(Note 1)	1.7	3.7	V
Input Logic-High	VIH	(Note 1)	0.7 x V <sub>DD</sub>	$V_{DD} + 0.3$	V
Input Logic-Low	VIL	(Note 1)	-0.3	0.3 x V <sub>DD</sub>	V

#### DC ELECTRICAL CHARACTERISTICS

 $(V_{DD} = 1.7 \text{V to } 3.7 \text{V}, T_{J} = -55 ^{\circ}\text{C} \text{ to } +125 ^{\circ}\text{C}, \text{ unless otherwise noted.})$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
MAX31722 Thermometer Error	Tenn	-40°C to +85°C			±2.0	°C	
MAX31722 Memometer End	TERR	-55°C to +125°C			±3.0		
MAX31723 Thermometer Error	T <sub>ERR</sub>	0°C to +70°C			±0.5	°C	
MAXS1723 THEITHORIETE EITOF	LEKK	-55°C to +125°C			±2.0		
Resolution	Resolution		9		12	Bits	
		9-bit conversions			25		
Conversion Time	toony	10-bit conversions			50	ms	
Conversion Time	tCONVT	11-bit conversions	conversions 100				
		12-bit conversions		200			
Logic 0 Output (SDO, TOUT)	Vol	(Note 2)			0.4	V	
Logic 1 Output (SDO)	Voн	(Note 3)	V <sub>DD</sub> - 0.4			V	
Leakage Current	IL		-1		+1	μΑ	
		Active temperature conversions (Note 4)			1150		
		Communication only			100		
Active Current	Icc	EEPROM writes (-40°C to +85°C)			1150	μΑ	
		EEPROM writes during active temperature conversions (-40°C to +85°C)			1200		
Shutdown Current	ICC1				2	μΑ	

#### **AC ELECTRICAL CHARACTERISTICS: 3-WIRE INTERFACE**

 $(V_{DD} = 1.7V \text{ to } 3.7V, T_{J} = -55^{\circ}\text{C to } +125^{\circ}\text{C}, \text{ unless otherwise noted.})$  (Figures 1, 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Data to SCLK Setup	tDC	(Notes 5, 6)	35			ns
SCLK to Data Hold	tCDH	(Notes 5, 6)	35			ns
SCLK to Data Valid	tCDD	(Notes 5, 6, 7)			80	ns
SCLK Low Time	tCL	(Note 6)	100			ns
SCLK High Time	tcH	(Note 6)	100			ns
SCLK Frequency	tclk	(Note 6)	DC		5.0	MHz
SCLK Rise and Fall	t <sub>R</sub> , t <sub>F</sub>				200	ns
CE to SCLK Setup	tcc	(Note 6)	400			ns
SCLK to CE Hold	tCCH	(Note 6)	100			ns
CE Inactive Time	tcwH	(Note 6)	400			ns
CE to Output High-Z	tcdz	(Notes 5, 6)			40	ns
SCLK to Output High-Z	tccz	(Notes 5, 6)			40	ns

#### AC ELECTRICAL CHARACTERISTICS: SPI INTERFACE

 $(V_{DD} = 1.7V \text{ to } 3.7V, T_{J} = -55^{\circ}\text{C to } +125^{\circ}\text{C}, \text{ unless otherwise noted.})$  (Figures 3, 4)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Data to SCLK Setup	tDC	(Notes 5, 6)	35			ns
SCLK to Data Hold	tCDH	(Notes 5, 6)	35			ns
SCLK to Data Valid	tCDD	(Notes 5, 6, 7)			80	ns
SCLK Low Time	tCL	(Note 6)	100			ns
SCLK High Time	tCH	(Note 6)	100			ns
SCLK Frequency	tCLK	(Note 6)	DC		5.0	MHz
SCLK Rise and Fall	t <sub>R</sub> , t <sub>F</sub>				200	ns
CE to SCLK Setup	tcc	(Note 6)	400			ns
SCLK to CE Hold	tcch	(Note 6)	100			ns
CE Inactive Time	tcwH	(Note 6)	400			ns
CE to Output High-Z	tcdz	(Notes 5, 6)			40	ns

#### AC ELECTRICAL CHARACTERISTICS: EEPROM

(V<sub>DD</sub> = 1.7V to 3.7V,  $T_J$  = -55°C to +125°C, unless otherwise noted.)

PARAMETER	SYMBOL CONDITIONS		MIN	TYP	MAX	UNITS
EEPROM Write Cycle Time	twR	-40°C to +85°C (Note 8)			15	ms
EEPROM Write Endurance	l Neewr I	-40°C ≤ T <sub>A</sub> ≤ +85°C (Note 8)	20,000			Cycles
		$T_A = +25$ °C (Note 8)	80,000			Cycles

- Note 1: All voltages are referenced to ground. Currents entering the IC are specified positive, and currents exiting the IC are negative.
- Note 2: Logic 0 voltages are specified at a sink current of 3mA.
- Note 3: Logic 1 voltages are specified at a source current of 1mA.
- Note 4: ICC specified with SCLK = VDD and CE = GND.
- Note 5: Measured at  $V_{IH} = 0.7V \times V_{DD}$  or  $V_{IL} = 0.3 \times V_{DD}$  and 10ms maximum rise and fall times.
- Note 6: Measured with 50pF load.
- Note 7: Measured at VOH = 0.7 x VDD or VOL = 0.3 x VDD. Measured from the 50% point of SCLK to the VOH minimum of SDO.
- Note 8: VDD must be > 2.0V during EEPROM write cycles.



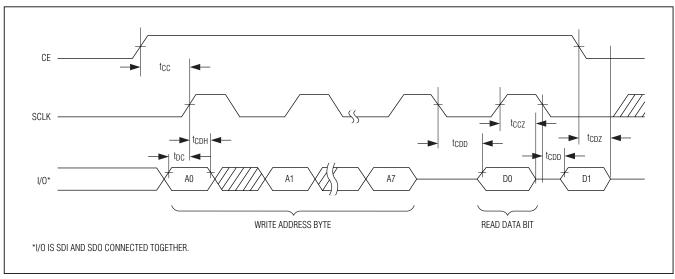


Figure 1. Timing Diagram: 3-Wire Read Data Transfer

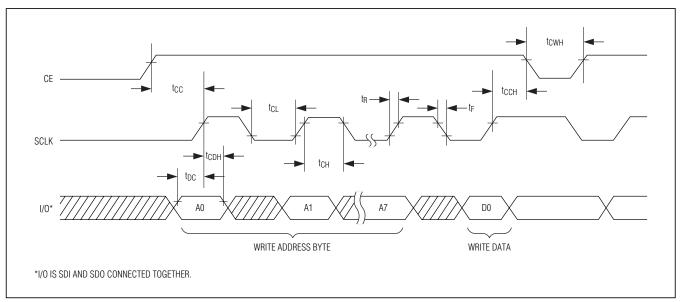


Figure 2. Timing Diagram: 3-Wire Write Data Transfer

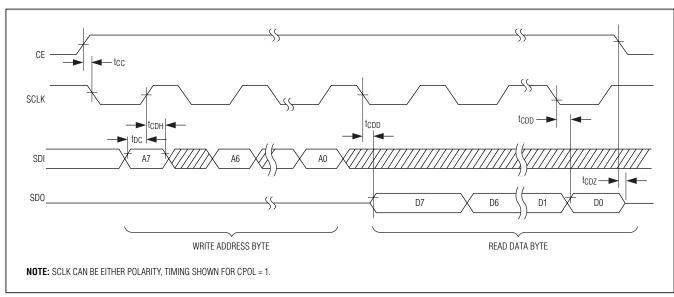


Figure 3. Timing Diagram: SPI Read Data Transfer

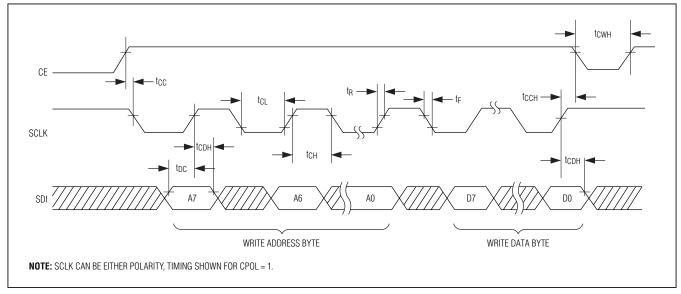
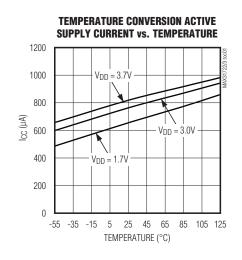
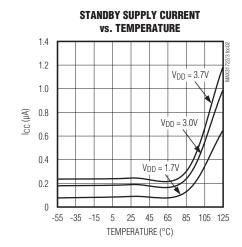


Figure 4. Timing Diagram: SPI Write Data Transfer

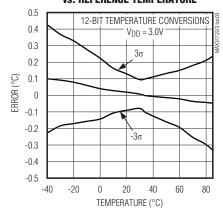
### **Typical Operating Characteristics**

 $(T_A = +25^{\circ}C, unless otherwise noted.)$ 

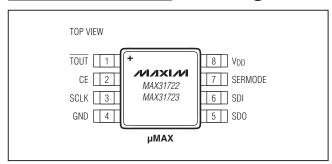




### TEMPERATURE CONVERSION ERROR vs. REFERENCE TEMPERATURE



#### **Pin Configuration**



### **Pin Description**

PIN	NAME	FUNCTION
1	TOUT	Thermostat Output. Open-drain output indicator for internal thermal alarm limits.
2	CE	Chip Enable. Must be asserted high for communication to take place for either the SPI or 3-wire interfaces.
3	SCLK	Serial-Clock Input. Used to synchronize data movement on the serial interface for either SPI or 3-wire interfaces.
4	GND	Ground. Ground connection.
5	SDO	Serial-Data Output. When SPI communication is selected, the SDO pin is the serial-data output for the SPI bus. When 3-wire communication is selected, this pin must be connected to the SDI pin. The SDI and SDO pins function as a single I/O pin when connected together.
6	SDI	Serial-Data Input. When SPI communication is selected, the SDI pin is the serial-data input for the SPI bus. When 3-wire communication is selected, this pin must be connected to the SDO pin. The SDI and SDO pins function as a single I/O pin when connected together.
7	SERMODE	Serial-Interface Mode Input. This pin selects which interface is used. When connected to V <sub>DD</sub> , SPI communication is selected. When connected to GND, 3-wire communication is selected.
8	VDD	Supply Voltage. Power-supply input.

### **Detailed Description**

The MAX31722/MAX31723 are factory-calibrated temperature sensors that require no external components. The user can alter the configuration/status register to place the device in a continuous temperature conversion mode or into a one-shot conversion mode. In the continuous conversion mode, the devices continuously convert the temperature and store the result in the temperature register. As conversions are performed in the background, reading the temperature register does not affect the conversion in progress. In the one-shot temperature conversion mode, the devices perform one temperature conversion, store the result in the temperature register, and then return to the shutdown state. This conversion mode is ideal for power-sensitive applications. The

temperature conversion results have a default resolution of 9 bits. In applications where small incremental temperature changes are critical, the user can change the conversion resolution from 9 bits to 10, 11, or 12. This is accomplished by programming the configuration/status register.

The devices can be configured as a thermostat, allowing for the  $\overline{\text{TOUT}}$  pin to behave as an interrupt, triggering when the programmed limits, Thigh and Tlow, are surpassed. The devices can communicate using either a serial peripheral interface (SPI) or standard 3-wire interface. The user can select either communication standard through the SERMODE pin, connecting it to VDD for SPI and to GND for 3-wire.



### Measuring Temperature

The core of the devices' functionality is its direct-to-digital temperature sensor. The devices measure temperature through the use of an on-chip temperature measurement technique with a -55°C to +125°C operating range. The devices power up in a power-conserving shutdown mode. After power-up, the devices can be placed in a continuous conversion mode or in a one-shot conversion mode. In the continuous conversion mode, the devices continuously compute the temperature and store the most recent result in the temperature register at addresses 01h (LSB) and 02h (MSB). As conversions are performed in the background, reading the temperature register does not affect the conversion in progress. The temperature value is not updated until the SPI or 3-wire interface is inactive. In other words, CE must be inactive for the temperature register to be updated with the most recent temperature conversion value. In the one-shot conversion mode, the devices perform one temperature conversion and then return to the shutdown mode, storing temperature in the temperature register. This conversion mode is ideal for power-sensitive applications. Details on how to change the setting after power-up are contained in the *Programming* section.

The resolution of the temperature conversion is configurable (9, 10, 11, or 12 bits) with 9 bits reading the default state. This equates to a temperature resolution of 0.5°C, 0.25°C, 0.125°C, or 0.0625°C. Following each conversion, thermal data is stored in the temperature register in two's complement format. The information can be retrieved over the SPI or 3-wire interface with the address set to the temperature register, 01h (LSB) and then 02h (MSB). Table 1 describes the exact relationship of output data to measured temperature. Table 1 assumes the devices are configured for 12-bit resolution. If the devices are configured in a lower resolution mode, those bits contain zeros. The data is transmitted serially over the digital interface, MSB first for SPI communication and LSB first for 3-wire communication. The MSB of the temperature register contains the sign (S) bit, denoting whether the temperature is positive or negative.

S	26	25	24	23	22	21	20
MSB	(UNITS = °C) LSB						
2-1	2-2	2-3	2-4	0	0	0	0

Figure 5. Temperature, THIGH, and TLOW Register Format

#### Table 1. 12-Bit Resolution Temperature/Data Relationship

TEMPERATURE (°C)	DIGITAL OUTPUT (BINARY)	DIGITAL OUTPUT (HEX)
+125	0111 1101 0000 0000	7D00
+25.0625	0001 1001 0001 0000	1910
+10.125	0000 1010 0010 0000	0A20
+0.5	0000 0000 1000 0000	0080
0	0000 0000 0000 0000	0000
-0.5	1111 1111 1000 0000	FF80
-10.125	1111 0101 1110 0000	F5E0
-25.0625	1110 0110 1111 0000	E6F0
-55	1100 1001 0000 0000	C900

#### **Thermostat**

The devices' thermostat can be programmed to power up in either comparator mode or interrupt mode, which activate and deactivate the open-drain thermostat output (TOUT) based on user-programmable trip points (THIGH and TLOW). The THIGH and TLOW registers contain Celsius temperature values in two's complement format and are stored in EEPROM memory. As such, the values are nonvolatile and can be programmed prior to installing the devices for stand-alone operation.

The data format of the THIGH and TLOW registers is identical to that of the temperature register (Figure 5). After every temperature conversion, the measurement is compared to the values stored in the THIGH and TLOW registers. The THIGH register is assigned to address locations 03h (LSB) and 04h (MSB), and the TLOW register is assigned to address locations 05h (LSB) and 06h (MSB). The TOUT output is updated based on the result of the comparison and the operating mode of the devices. The number of THIGH and TLOW bits used during the thermostat comparison is equal to the conversion resolution set by the R1 and R0 bits in the configuration/ status register. For example, if the resolution is 9 bits, only the nine MSBs of THIGH and TLOW are used by the thermostat comparator.

If the user does not wish to use the thermostat capabilities of the devices, the  $\overline{\text{TOUT}}$  output should be left unconnected. Note that if the thermostat is not used, the THIGH and TLOW registers can be used for general storage of system data.

#### **Comparator Mode**

When the thermostat is in comparator mode, TOUT can be programmed to operate with any amount of hysteresis. The TOUT output becomes active when the measured temperature exceeds the THIGH value. TOUT then stays active until the first time the temperature falls below the value stored in TLOW. Putting the devices into shutdown mode does not clear TOUT in comparator mode. Figure 6 illustrates thermostat comparator mode operation.

#### **Interrupt Mode**

In interrupt mode, the TOUT output first becomes active when the measured temperature exceeds the THIGH value. Once activated, in continuous conversion mode TOUT can only be cleared by either putting the devices into shutdown mode or by reading from any register (configuration/status, temperature, THIGH, or TLOW) on the devices. In one-shot mode, TOUT can only be cleared by reading from any register (configuration/status, temperature, THIGH, or TLOW) on the devices.

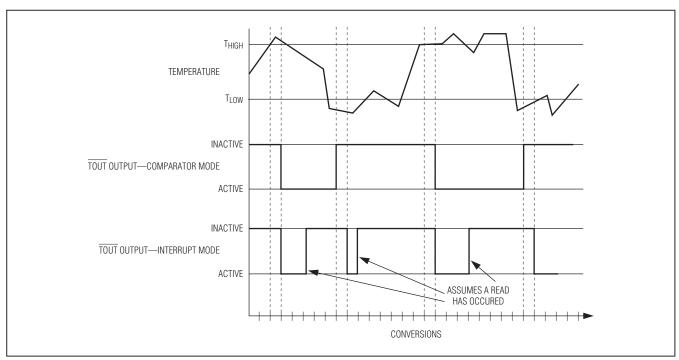


Figure 6. TOUT Operation Example

In either mode, once  $\overline{\text{TOUT}}$  has been deactivated, it is only reactivated when the measured temperature falls below the TLOW value. Thus, this interrupt/clear process is cyclical between THIGH and TLOW events (i.e, THIGH, clear, TLOW, clear, THIGH, clear, TLOW, clear, etc.). Figure 6 illustrates the thermostat interrupt mode operation.

### **Table 2. Register Address Structure**

READ ADDRESS (HEX)	WRITE ADDRESS (HEX)	ACTIVE REGISTER		
00	80	Configuration/Status		
01	No access	Temperature LSB		
02	No access	Temperature MSB		
03	83	THIGH LSB		
04	84	THIGH MSB		
05	85	T <sub>LOW</sub> LSB		
06	86	TLOW MSB		

### \_Programming

The area of interest in programming the devices is the configuration/status register. All programming is done through the SPI or 3-wire communication interface by selecting the appropriate address of the desired register location. Table 2 illustrates the addresses for the device registers.

#### **Configuration/Status Register Programming**

The configuration/status register is accessed in the devices with the 00h address for reads and the 80h address for writes. Data is read from or written to the configuration/status register MSB first for SPI communication and LSB first for 3-wire communication. Table 3 illustrates the format of the register, describes the effect each bit has on device functionality, and provides the bit's factory state.

Table 4 defines the resolution of the digital thermometer, based on the settings of the R1 and R0 bits. There is a direct trade-off between resolution and conversion time,

Table 3. Configuration/Status Register Bit Descriptions

BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0	
0	MEMW	NVB	1SHOT	TM	R1	R0	SD	1

BIT 7	This bit is always a value of 0.
BIT 6	MEMW: Memory write bit. Power-up state = 0. The user has read/write access to the MEMW bit, which is stored in the voltage memory.  0 = A write of the configuration/status register is stored in RAM memory.  1 = A write of the configuration/status register is stored in EEPROM.  Note: The status of this bit is ignored if a EEPROM write occurs to the other nonvolatile registers, Thigh and TLOW. The nonvolatile bits of the configuration/status register are written if a EEPROM write cycle occurs to the THIGH and TLOW registers.
BIT 5	NVB: Nonvolatile memory busy flag. Power-up state = 0 and is stored in volatile memory.  0 = Indicates that the nonvolatile memory is not busy.  1 = Indicates there is a write to a EEPROM memory cell in progress.
BIT 4	<b>1SHOT:</b> One-shot temperature conversion bit. Power-up state = 0 and is stored in volatile memory. 0 = Disables 1SHOT mode.  1 = If the SD bit is 1 (continuous temperature conversions are not taking place), a 1 written to the 1SHOT bit causes the devices to perform one temperature conversion and store the results in the temperature register at addresses 01h (LSB) and 02h (MSB). The bit clears itself to 0 upon completion of the temperature conversion. The user has read/write access to the 1SHOT bit, although writes to this bit are ignored if the SD bit is a 0 (continuous conversion mode).
BIT 3	TM: Thermostat operating mode. Factory power-up state = 0. The user has read/write access to the TM bit, which is stored in nonvolatile memory.  0 = The thermostat output is in comparator mode.  1 = The thermostat output is in interrupt mode.

\_\_/N/XI/N

Table 3. Configuration/Status Register Bit Descriptions (continued)

BIT 2	<b>R1:</b> Thermostat resolution bit 1. Factory power-up state = 0 and is stored in nonvolatile memory. Sets the conversion resolution (see Table 4).
BIT 1	<b>R0:</b> Thermostat resolution bit 0. Factory power-up state = 0 and is stored in nonvolatile memory. Sets the conversion resolution (see Table 4).
BIT 0	SD: Factory power-up state = 1. The user has read/write access to the SD bit, which is stored in nonvolatile memory.  0 = The devices continuously perform temperature conversions and store the last completed result in the temperature register.  1 = The conversion in progress is completed and stored, and then the devices revert to a low-power shutdown mode. The communication port remains active.

### Table 4. Thermometer Resolution Configuration

R1	R0	THERMOMETER RESOLUTION (BITS)	MAX CONVERSION TIME (ms)
0	0	9	25
0	1	10	50
1	0	11	100
1	1	12	200

as depicted in the *AC Electrical Characteristics*. The user has read/write access to the R1 and R0 bits, which are nonvolatile. See Table 4.

#### Serial Interface

The devices offer the flexibility to choose between two serial interface modes. They can communicate with the SPI interface or with a 3-wire interface. The interface method used is determined by the SERMODE pin. When SERMODE is connected to VDD, SPI communication is selected. When SERMODE is connected to ground, 3-wire communication is selected.

#### **Table 5. Function Table**

MODE	CE	SCLK	SDI	SDO
Disable reset	Low	Input disabled	Input disabled	High impedance
Write	High	CPOL = 1*, SCLK rising	Data bit latch	High impedance
		CPOL = 0, SCLK falling	Data bit laten	
Read	High	CPOL = 1, SCLK falling	X	Next data bit shift**
		CPOL = 0, SCLK rising		

Note: CPHA bit polarity must be set to 1.

#### Serial Peripheral Interface (SPI)

The SPI is a synchronous bus for address and data transfer. The SPI mode of serial communication is selected by connecting SERMODE to VDD. Four pins are used for the SPI: SDO (serial-data out), SDI (serial-data in), CE (chip enable), and SCLK (serial clock). The devices are the slave device in an SPI application, with the microcontroller being the master. SDI and SDO are the serial-data input and output pins for the devices, respectively. The CE input is used to initiate and terminate a data transfer. SCLK is used to synchronize data movement between the master (microcontroller) and the slave (IC) devices.

The serial clock (SCLK), which is generated by the microcontroller, is active only when CE is high and during address and data transfer to any device on the SPI bus. The inactive clock polarity is programmable in some microcontrollers. The devices offer an important feature in that the level of the inactive clock is determined by sampling SCLK when CE becomes active. Therefore, either SCLK polarity can be accommodated. Input data (SDI) is latched on the internal strobe edge and output data (SDO) is shifted out on the shift edge (see Table 5 and Figure 7). There is one clock for each bit transferred. Address and data bits are transferred in groups of eight, MSB first.

<sup>\*</sup>CPOL is the clock polarity bit that is set in the control register of the microcontroller.

<sup>\*\*</sup>SDO remains at high impedance until 8 bits of data are ready to be shifted out during a read.

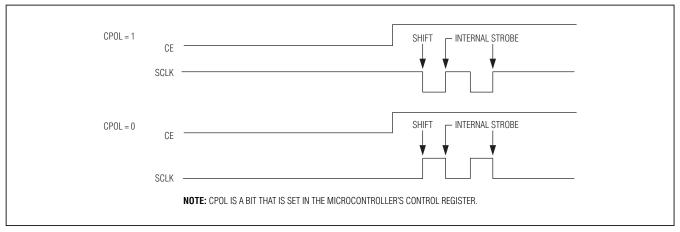


Figure 7. Serial Clock as a Function of Microcontroller Clock Polarity (CPOL)

#### **Address and Data Bytes**

Address and data bytes are shifted MSB first into the serial-data input (SDI) and out of the serial-data output (SDO). Any transfer requires the address of the byte to specify a write or a read, followed by one or more bytes of data. Data is transferred out of the SDO for a read operation and into the SDI for a write operation. The address byte is always the first byte entered after CE is driven high. The MSB (A7) of this byte determines if a read or write takes place. If A7 is 0, one or more read cycles occur. If A7 is 1, one or more write cycles occur.

Data transfers can occur 1 byte at a time in multiple-byte burst mode. After CE is driven high, an address is written to the devices. After the address, one or more data bytes can be written or read. For a single-byte transfer, 1 byte is read or written and then CE is driven low (see Figures 8 and 9). For a multiple-byte transfer, however, multiple bytes can be read or written to the devices after the address has been written (see Figure 10). A

single-byte burst read/write sequentially points through all memory locations and loops from 7Fh/FFh to 00h/80h. Invalid memory addresses report an FFh value.

#### 3-Wire Serial-Data Bus

The 3-wire communication mode operates similarly to the SPI mode. However, in 3-wire mode, there is one bidirectional I/O instead of separate data-in and data-out signals. The 3-wire consists of the I/O (SDI and SDO pins connected together), CE, and SCLK pins. In 3-wire mode, each byte is shifted in LSB first, unlike SPI mode where each byte is shifted in MSB first. As is the case with the SPI mode, an address byte is written to the devices followed by a single data byte or multiple data bytes. Figure 11 illustrates a read and write cycle. Figure 12 illustrates a multiple-byte burst transfer. In 3-wire mode, data is input on the rising edge of SCLK and output on the falling edge of SCLK.

\_\_/N/XI/M

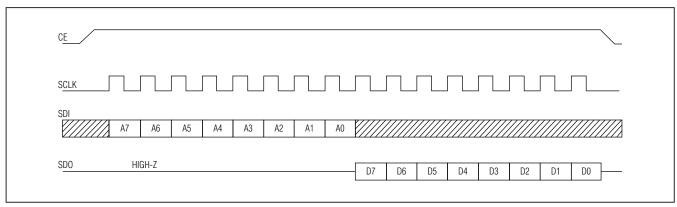


Figure 8. SPI Single-Byte Read

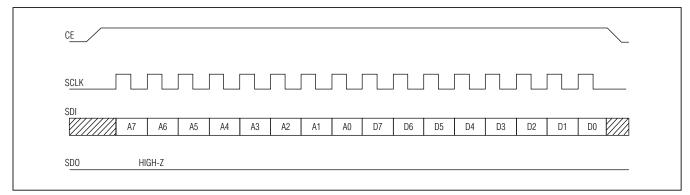


Figure 9. SPI Single-Byte Write

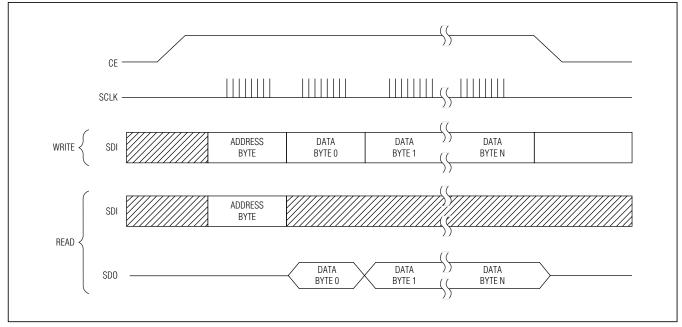


Figure 10. SPI Multiple-Byte Burst Transfer

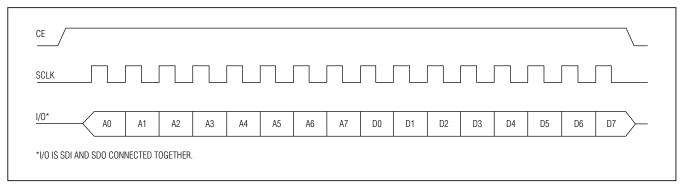


Figure 11. 3-Wire Single-Byte Transfer

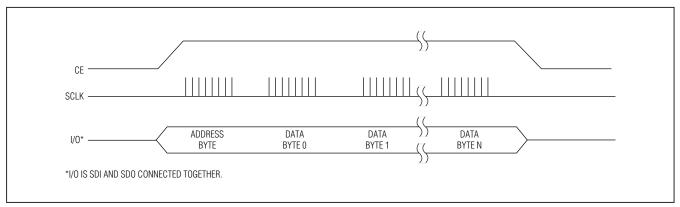


Figure 12. 3-Wire Multiple-Byte Burst Transfer

### Package Information

For the latest package outline information and land patterns, go to <u>www.maxim-ic.com/packages</u>. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
8 µMAX	U8+1	21-0036	90-0092

14 \_\_\_\_\_\_\_ **/VI/IXI/VI** 

### **Revision History**

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	11/10	Initial release	_

Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.