

# **CAT5114**

# 32-Tap Digitally Programmable Potentiometer (DPP™)



# **FEATURES**

- 32-position linear taper potentiometer
- Non-volatile EEPROM wiper storage
- 10nA ultra-low standby current
- Single supply operation: 2.5V-6.0V
- Increment Up/Down serial interface
- Resistance values: 10kΩ, 50kΩ and 100kΩ
- Available in PDIP, SOIC, TSSOP, MSOP and space saving 2x3mm TDFN packages

# **APPLICATIONS**

- Automated product calibration
- Remote control adjustments
- Offset, gain and zero control
- Tamper-proof calibrations
- Contrast, brightness and volume controls
- Motor controls and feedback systems
- Programmable analog functions

# **DESCRIPTION**

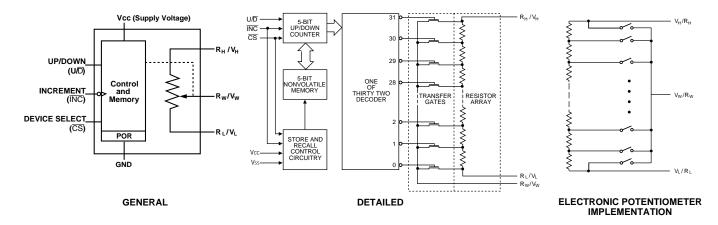
The CAT5114 is a single digitally programmable potentiometer (DPP™) designed as a electronic replacement for mechanical potentiometers and trim pots. Ideal for automated adjustments on high volume production lines, they are also well suited for applications where equipment requiring periodic adjustment is either difficult to access or located in a hazardous or remote environment.

The CAT5114 contains a 32-tap series resistor array connected between two terminals  $R_H$  and  $R_L$ . An up/down counter and decoder that are controlled by three input pins, determines which tap is connected to the wiper,  $R_W$ . The wiper setting, stored in nonvolatile memory, is not lost when the device is powered down and is automatically reinstated when power is returned. The wiper can be adjusted to test

new system values without effecting the stored setting. Wiper-control of the CAT5114 is accomplished with three input control pins,  $\overline{CS}$ ,  $U/\overline{D}$ , and  $\overline{INC}$ . The  $\overline{INC}$  input increments the wiper in the direction which is determined by the logic state of the  $U/\overline{D}$  input. The  $\overline{CS}$  input is used to select the device and also store the wiper position prior to power down.

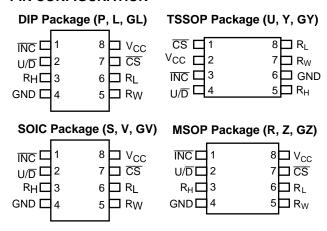
The digitally programmable potentiometer can be used as a three-terminal resistive divider or as a two-terminal variable resistor. DPPs bring variability and programmability to a wide variety of applications including control, parameter adjustments, and signal processing.

### **FUNCTIONAL DIAGRAM**

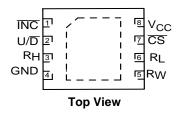




### PIN CONFIGURATION



### TDFN Package (SP2, VP2, GP2)



# PIN FUNCTIONS

Pin Name	Function	
INC	Increment Control	
U/D	Up/Down Control	
RH	Potentiometer High Terminal	
GND	Ground	
Rw	Potentiometer Wiper Terminal	
RL	Potentiometer Low Terminal	
CS	Chip Select	
V <sub>CC</sub>	Supply Voltage	

### PIN DESCRIPTIONS

**INC**: Increment Control Input

The  $\overline{INC}$  input moves the wiper in the up or down direction determined by the condition of the U/ $\overline{D}$  input.

**U/D**: Up/Down Control Input

The U/ $\overline{D}$  input controls the direction of the wiper movement. When in a high state and  $\overline{CS}$  is low, any high-to-low transition on  $\overline{INC}$  will cause the wiper to move one increment toward the R<sub>H</sub> terminal. When in a low state and  $\overline{CS}$  is low, any high-to-low transition on  $\overline{INC}$  will cause the wiper to move one increment towards the R<sub>L</sub> terminal.

RH: High End Potentiometer Terminal

 $R_H$  is the high end terminal of the potentiometer. It is not required that this terminal be connected to a potential greater than the  $R_L$  terminal. Voltage applied to the  $R_H$  terminal cannot exceed the supply voltage,  $V_{CC}$  or go below ground, GND.

Rw: Wiper Potentiometer Terminal

Rw is the wiper terminal of the potentiometer. Its position on the resistor array is controlled by the control inputs,  $\overline{\text{INC}}$ , U/ $\overline{\text{D}}$  and  $\overline{\text{CS}}$ . Voltage applied to the Rw terminal cannot exceed the supply voltage, V<sub>CC</sub> or go below ground, GND.

RL: Low End Potentiometer Terminal

 $R_{L}$  is the low end terminal of the potentiometer. It is not required that this terminal be connected to a potential less than the  $R_{H}$  terminal. Voltage applied to the  $R_{L}$  terminal cannot exceed the supply voltage,  $V_{CC}$  or go below ground, GND.  $R_{L}$  and  $R_{H}$  are electrically interchangeable.

**CS**: Chip Select

The chip select input is used to activate the control input of the CAT5114 and is active low. When in a high state, activity on the  $\overline{\text{INC}}$  and  $\text{U}/\overline{\text{D}}$  inputs will not affect or change the position of the wiper.



### **DEVICE OPERATION**

The CAT5114 operates like a digitally controlled potentiometer with  $R_H$  and  $R_L$  equivalent to the high and low terminals and  $R_W$  equivalent to the mechanical potentiometer's wiper. There are 32 available tap positions including the resistor end points,  $R_H$  and  $R_L$ . There are 31 resistor elements connected in series between the  $R_H$  and  $R_L$  terminals. The wiper terminal is connected to one of the 32 taps and controlled by three inputs,  $\overline{INC}$ ,  $U/\overline{D}$  and  $\overline{CS}$ . These inputs control a five-bit up/down counter whose output is decoded to select the wiper position. The selected wiper position can be stored in nonvolatile memory using the  $\overline{INC}$  and  $\overline{CS}$  inputs.

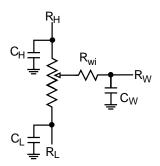
With  $\overline{\text{CS}}$  set LOW the CAT5114 is selected and will respond to the U/ $\overline{\text{D}}$  and  $\overline{\text{INC}}$  inputs. HIGH to LOW transitions on  $\overline{\text{INC}}$  will increment or decrement the

wiper (depending on the state of the  $U/\overline{D}$  input and five-bit counter). The wiper, when at either fixed terminal, acts like its mechanical equivalent and does not move beyond the last position. The value of the counter is stored in nonvolatile memory whenever  $\overline{CS}$  transitions HIGH while the  $\overline{INC}$  input is also HIGH. When the CAT5114 is powered-down, the last stored wiper counter position is maintained in the nonvolatile memory. When power is restored, the contents of the memory are recalled and the counter is set to the value stored.

With INC set low, the CAT5114 may be de-selected and powered down without storing the current wiper position in nonvolatile memory. This allows the system to always power up to a preset value stored in nonvolatile memory.

### **OPERATION MODES**

ĪNC	<u>cs</u>	U/D	Operation
High to Low	Low	High Wiper toward	
High to Low	Low	Low	Wiper toward L
High	Low to High	Х	Store Wiper Position
Low	Low to High	Х	No Store, Return to Standby
X	High	X	Standby



**Potentiometer Equivalent Circuit** 



### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage V <sub>CC</sub> to GND	0.5V to +7V
•	
CS to GND	-0.5V to $V_{\rm CC}$ +0.5V
ĪNC to GND	
U/D to GND	-0.5V to $V_{CC}$ +0.5V
H to GND	$-0.5V$ to $V_{CC} + 0.5V$
L to GND	$-0.5V$ to $V_{CC} + 0.5V$
W to GND	$-0.5V$ to $V_{CC} + 0.5V$

# **Operating Ambient Temperature**

Commercial ('C' or Blank s	uffix) 0°C to +70°C
Industrial ('I' suffix)	– 40°C to +85°C
Junction Temperature	+150°C
Storage Temperature	65°C to +150°C
Lead Soldering (10 sec max)	+300°C

<sup>\*</sup> Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. Absolute Maximum Ratings are limited values applied individually while other parameters are within specified operating conditions, and functional operation at any of these conditions is NOT implied. Device performance and reliability may be impaired by exposure to absolute rating conditions for extended periods of time.

### **RELIABILITY CHARACTERISTICS**

Symbol	Parameter	Test Method	Min	Тур	Max	Units
V <sub>ZAP</sub> <sup>(1)</sup>	ESD Susceptibility	MIL-STD-883, Test Method 3015	2000			Volts
I <sub>LTH</sub> <sup>(1)(2)</sup>	Latch-Up	JEDEC Standard 17	100			mA
T <sub>DR</sub>	Data Retention	MIL-STD-883, Test Method 1008	100			Years
N <sub>END</sub>	Endurance	MIL-STD-883, Test Method 1003	1,000,000			Stores

# DC Electrical Characteristics: V<sub>CC</sub> = +2.5V to +6.0V unless otherwise specified **Power Supply**

Symbol	Parameter	Conditions	Min	Тур	Max	Units
V <sub>CC</sub>	Operating Voltage Range		2.5		6.0	V
I <sub>CC1</sub>	Supply Current (Increment)	$V_{CC} = 6V$ , $f = 1MHz$ , $I_W=0$			100	μΑ
		$V_{CC} = 6V$ , $f = 250kHz$ , $I_{W}=0$			50	
I <sub>CC2</sub>	Supply Current (Write)	Programming, V <sub>CC</sub> = 6V			1	mA
		$V_{CC} = 3V$			500	μΑ
ISB <sub>1</sub> (2)	Supply Current (Standby)	CS=V <sub>CC</sub> -0.3V		0.01	1	μΑ
		U/D, INC=V <sub>CC</sub> -0.3V or GND				

# **Logic Inputs**

Symbol	Parameter	Conditions	Min	Тур	Max	Units
I <sub>IH</sub>	Input Leakage Current	$V_{IN} = V_{CC}$			10	μΑ
I <sub>IL</sub>	Input Leakage Current	$V_{IN} = 0V$			-10	μΑ
V <sub>IH1</sub>	TTL High Level Input Voltage	$4.5V \leq V_{CC} \leq 5.5V$	2		Vcc	V
V <sub>IL1</sub>	TTL Low Level Input Voltage		0		0.8	V
V <sub>IH2</sub>	CMOS High Level Input Voltage	$2.5V \le V_{CC} \le 6V$	V <sub>CC</sub> x 0.7		V <sub>CC</sub> + 0.3	٧
V <sub>IL2</sub>	CMOS Low Level Input Voltage		-0.3		V <sub>CC</sub> x 0.2	V

- NOTES: (1) This parameter is tested initially and after a design or process change that affects the parameter.
  (2) Latch-up protection is provided for stresses up to 100mA on address and data pins from -1V to V<sub>CC</sub> + 1V
  - (3) I<sub>W</sub>=source or sink
  - (4) These parameters are periodically sampled and are not 100% tested.



# **Potentiometer Parameters**

Symbol	Parameter	Conditions	Min	Тур	Max	Units
		-10 Device		10		
$R_{POT}$	Potentiometer Resistance	-50 Device		50		kΩ
		-00 Device		100		
R <sub>TOL</sub>	Pot Resistance Tolerance				± 20	%
$V_{RH}$	Voltage on R <sub>H</sub> pin		0		Vcc	V
$V_{RL}$	Voltage on R <sub>L</sub> pin		0		Vcc	V
RES	Resolution			3.2		%
INL	Integral Linearity Error	$I_W \le 2\mu A$		0.5	1	LSB
DNL	Differential Linearity Error	$I_W \le 2\mu A$		0.25	0.5	LSB
R <sub>Wi</sub>	Wiper Resistance	$V_{CC} = 5V$ , $I_W = 1mA$			400	Ω
		$V_{CC} = 2.5V$ , $I_{W} = 1mA$			1	kΩ
lw	Wiper Current				1	mA
TC <sub>RPOT</sub>	TC of Pot Resistance			300		ppm/ºC
TCRATIO	Ratiometric TC				20	ppm/ºC
Riso	Isolation Resistance			TBD		Ω
VN	Noise	100kHz / 1kHz		8/24		nV/√H <sub>z</sub>
C <sub>H</sub> /C <sub>L</sub> /C <sub>W</sub>	Potentiometer Capacitances			8/8/25		pF
fc	Frequency Response	Passive Attenuator, 10kΩ		1.7		MHz
	1	1				



# **AC CONDITIONS OF TEST**

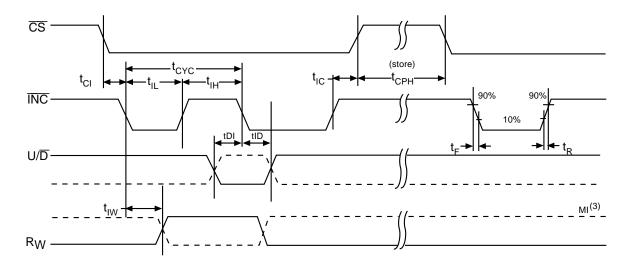
V <sub>CC</sub> Range	$2.5V \le V_{CC} \le 6V$
Input Pulse Levels	0.2V <sub>CC</sub> to 0.7V <sub>CC</sub>
Input Rise and Fall Times	10ns
Input Reference Levels	0.5V <sub>CC</sub>

# **AC OPERATING CHARACTERISTICS:**

 $V_{CC}$  = +2.5V to +6.0V,  $V_{H}$  =  $V_{CC}$ ,  $V_{L}$  = 0V, unless otherwise specified

Symbol	Parameter	Min	Typ <sup>(1)</sup>	Max	Units
t <sub>CI</sub>	CS to INC Setup	100			ns
t <sub>DI</sub>	U/D to INC Setup	50			ns
t <sub>ID</sub>	U/D to INC Hold	100			ns
t <sub>IL</sub>	INC LOW Period	250			ns
t <sub>IH</sub>	INC HIGH Period	250			ns
t <sub>IC</sub>	INC Inactive to CS Inactive	1			μs
t <sub>CPH</sub>	CS Deselect Time (NO STORE)	100			ns
t <sub>CPH</sub>	CS Deselect Time (STORE)	10			ms
t <sub>IW</sub>	INC to V <sub>OUT</sub> Change		1	5	μs
t <sub>CYC</sub>	INC Cycle Time	1			μs
t <sub>R</sub> , t <sub>F</sub> <sup>(2)</sup>	INC Input Rise and Fall Time			500	μs
t <sub>PU</sub> <sup>(2)</sup>	Power-up to Wiper Stable			1	msec
twR	Store Cycle		5	10	ms

# A. C. TIMING



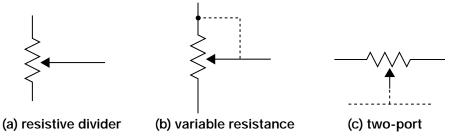
- (1) Typical values are for T<sub>A</sub>=25°C and nominal supply voltage.
   (2) This parameter is periodically sampled and not 100% tested.
- (3) MI in the A.C. Timing diagram refers to the minimum incremental change in the W output due to a change in the wiper position.

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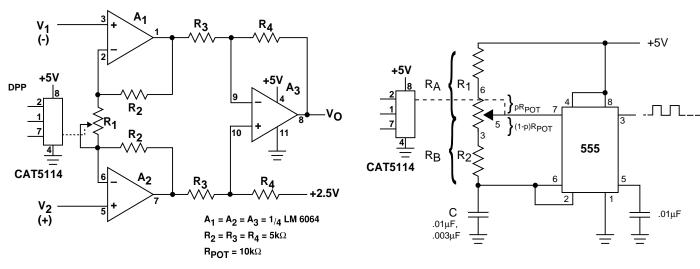


# **APPLICATION INFORMATION**

# **Potentiometer Configurations**

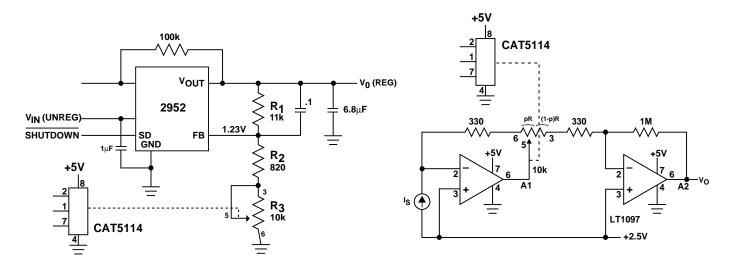


# **Applications**



**Programmable Instrumentation Amplifier** 

Programmable Sq. Wave Oscillator (555)

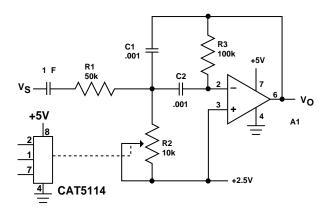


**Programmable Voltage Regulator** 

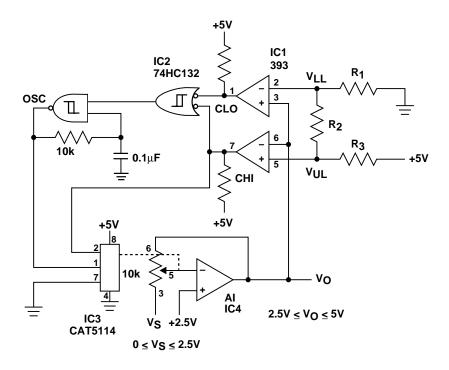
Programmable I to V convertor



# **APPLICATION INFORMATION**



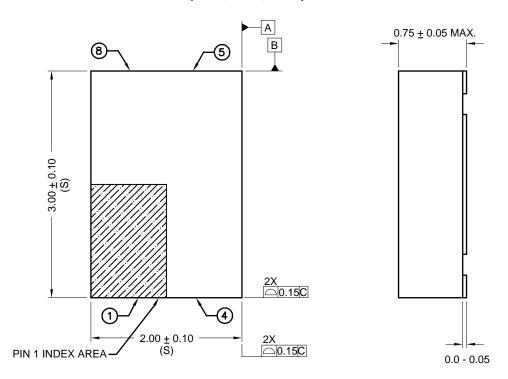
**Programmable Bandpass Filter** 

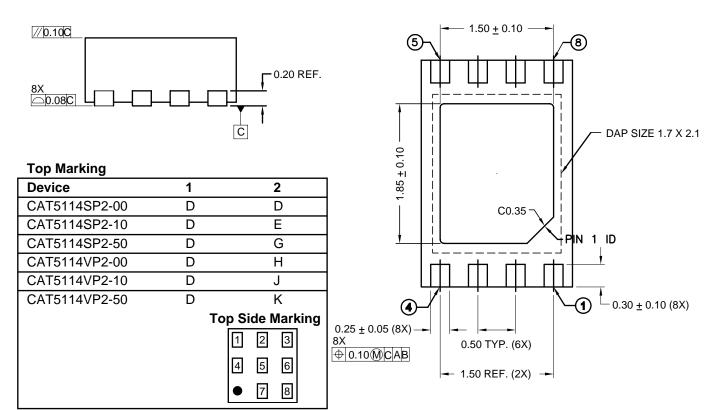


**Automatic Gain Control** 



# 8-PAD TDFN 2 x 3 mm PACKAGE (SP2, VP2, GP2)



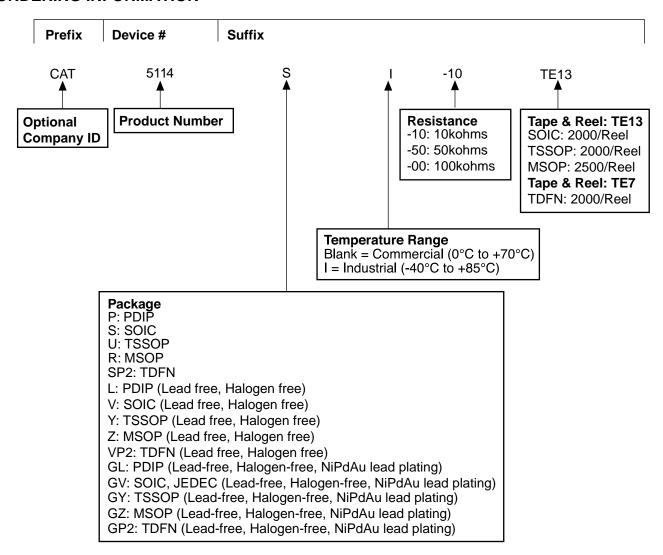


### NOTE:

- 1. ALL DIMENSIONS IN MM. ANGLES IN DEGREES.
- 2. COPLANARITY APPLIES TO THE EXPOSED PAD AS WELL AS THE TERMNALS. COPLANARITY SHALL NOT EXCEED 0.08 MM.
- 3. WARPAGE SHALL NOT EXCEED 0.10 MM.
- 4. PACKAGE LENGTH / PACKAGE WIDTH ARE NOT CONSIDERED AS SPECIAL CHARACTERISTIC.



# ORDERING INFORMATION



# Notes:

(1) The device used in the above example is a CAT5114 SI-10TE13 (SOIC, 10K Ohms, Industrial Temperature, Tape & Reel)

# **REVISION HISTORY**

Date	Rev.	Reason	
10/9/2003	G	Revised Features	
		Revised DC Electrical Characteristics	
3/10/2004	Н	Update Potentiometer Parameters	
3/29/2004	I	Changed Green Package marking for SOIC from W to V	
		Updated Ordering Information (removed old 5112 references)	
4/12/2004	J	Updated Reel Ordering Information	
8/31/2004	K	Added TDFN package in all areas	
04/08/2005	L	Update Ordering Information	
07/28/2005	М	Update Pin Configuration	
		Application Information	
		Ordering Information	

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