

Pattern Matching Sensor

Affordable F10 Vision Sensor with One-Touch Setup, 8-bank memory, and RS-232C/RS-422 Communication

- Ensures fast, accurate inspections such as label pattern match, print verification, label placement, and conformity (rejects upside-down, tilted or double labels)
- Up to 8 model and threshold settings can be saved and selected with banking function
- Choice of extra wide, wide, medium and narrow field of view remote cameras
- Includes a controller, remote camera head with built in visible target guide, light source and lens



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Ordering Information _____

HEADS

Item	Setting distance	Sensing area	Part number
Red LED (Extra wide field of view)	160±16 mm (6.30±0.63 in)	40 × 32 mm (1.57 x 1.26 in)	F10-S50R
Red LED (wide field of view)	100±10 mm (3.94±0.39 in)	25 × 20 mm (0.98 x 0.78 in)	F10-S30R
Green LED (medium field of view)	50±5 mm (1.97±0.20 in)	12 × 10 mm (0.47 x 0.39 in)	F10-S15R
Green LED (narrow field of view)	33±1.5 mm (1.30±0.06 in)	4.5 × 3.5 mm (0.18 x 0.14 in)	F10-S05R

■ AMPLIFIERS

Туре	Output	No. of registered models	Part number
Standard models	NPN	1	F10-C20
	PNP		F10-C25
Models with bank function and RS-232C	NPN	8 (one model per bank)	F10-C50
and RS-422 interface	PNP		F10-C55

CABLES

Туре	Length	Part number
RS-232C	2 m	F10-VR2
RS-422	2 m	F10-VR4

Specifications _____

■ RATINGS/CHARACTERISTICS

Heads

Optical and Lighting System Specifications

Item	Specifications			
	F10-S50R	F10-S30R	F10-S15R	F10-S05R
Setting distance	160±16 mm (6.30±0.63 in)	100±10 mm (3.93±0.39 in)	50±5 mm (1.97±0.20 in)	33±1.5 mm (1.30±0.06 in)
Sensing area	40 mm × 32 mm (1.57 x 1.26 in)	25 mm × 20 mm (0.98 × 0.79 in)	12 mm × 10 mm (0.47 × 0.39 in)	4.5 mm × 3.5 mm (0.18 × 0.14 in)
Guide light projection size	A: 40 mm (1.57 in) B: 32 mm (1.26 in) C: 13 mm (0.51 in) D: 10 mm (0.39 in) E: 32 mm (1.26 in) (typ.)	A: 25 mm (0.98 in) B: 20 mm (0.79 in) C: 8 mm (0.31 in) D: 6 mm (0.24 in) E: 20 mm (0.79 in) (typ.)	A: 12 mm (0.47 in) B: 10 mm (0.39 in) C: 4 mm (0.16 in) D: 3 mm (0.12 in) E: 10 mm (0.39 in) (typ.)	A: 4.5 mm (0.18 in) B: 3.5 mm (0.14 in) C: 1.5 mm (0.06 in) D: 1.0 mm (0.04 in) E: 3.5 mm (0.14 in) (typ.)
Built-in lens	Focus: f9.8 (fixed) Diaphragm: F2.8 (fixed)			Focus: f14.8 (fixed) Diaphragm: F3.5 (fixed)
Object lighting method	Pulse lighting (pulse width is	s synchronized with electroni	c shutter in operation)	
Object light source (emission wavelength)	8 red LEDs (680 nm) 8 green LEDs (540 nm)			
Main object color combination			Black and white, red and w and white, green and black	
Guide light projection source (emission wavelength)	1 green LED (540 nm) 1 blue LED (470 nm)			
Guide light projection method	Pulse lighting			

Camera Image Performance Specifications

Item	Specifications		
	F10-S50R F10-S30R F10-S15R F10-S05R		
Camera image element	1/5-inch CCD		
Shutter function	Electronic shutter at a speed range between 1/34722 s and 1/2894 s (automatically set during teaching)		

General Specifications

Item		Specification	
Ambient temperature	Operating	0°C to 40°C (32°F to 104°F) with no icing or condensation	
	Storage	-25°C to 60°C (-13°F to 140°F) with no icing or condensation	
Ambient humidity	Operating	35% to 85% (with no condensation)	
	Storage	35% to 85% (with no condensation)	
Operating environment		With no corrosive gas	
Input power supply		16.2 to 19.8 VDC (provided from amplifier)	
Current consumption		150 mA max.	
Insulation resistance		20 MΩ min. (at 500 VDC)	
Dielectric strength		1,000 VAC at 50/60 Hz for 1 min	
Degree of protection		IEC 60529 IP64	
Vibration resistance (when using mounting bracket)		10 to 150 Hz, half-amplitude of 0.75 mm max. or 100 m/s ² max. for 32 min each in X, Y, and Z directions	
Shock resistance (when using mounting b	oracket)	Peak acceleration: 300 m/s ² 3 times each in X, Y, and Z directions	
Connection		Prewired (standard cable length: 2 m)	
Casing material Case		Aluminum die cast	
	Front cover	Acrylic resin	
Weight (when packed)		Approx. 400 g (Unit: approx. 300 g (including cable))	
Accessories provided		Mounting bracket, 8 x M4 mounting screws, instruction manual	

■ AMPLIFIERS

Performance Specifications

Item	Specification	
Model	F10-C20/C50 F10-C25/C55	
Output type	NPN	PNP
Measurement item	Pattern measurement/plain measurement	
Number of models	C20/C25: 1 model, C50/C55: 1 model per bank	
Bank selection	C20/C25: None, C50/C55: 8 banks	
Automatic teaching function	Yes	
Model size	Normal or wide mode (selectable)	
Measurement processing time	3.6 ms in normal mode and 10.8 ms in wide mode (con	tinuous operation)
Output signal (2 points)	Control output and enable output: NPN open collector with load voltage of 30 V max., load current of 50 mA max. and residual voltage of 1.2 V max.	Control output and enable output: PNP open collector with load voltage of 30 V max., load current of 50 mA max. and residual voltage of 2.0 V max.
Output selection	Matching output: ON when image matches the registered model.	
	Not matching output: ON when image does not match the registered model.	
Input signal C20/C25 (4 points) C30/C35/C50/C55 (7 points)	External trigger input (with minimum pulse width of 1 ms), continuous measurement input, moving object teaching input, or stationary object teaching input	External trigger input (with minimum pulse width of 1 ms), continuous measurement input, moving object teaching input, or stationary object teaching input
	Input is ON: Short-circuited to 0 V with short-circuit current of 1 mA max. or 1.5 V max. Input is OFF: Open or input voltage of 5 V min. (Max. input voltage: +26.4 VDC)	Input is ON: Short-circuited to Vcc or 9 V min. (Max. input voltage: +26.4 VDC) Input is OFF: Open or input voltage of 5 V max.
Head interface (1 channel)	Available Head: F10-S50R, F10-S30R, F10-S15R, or F10-S05R	
Indicators	Result indicator: 1 orange LED Level indicators: 8 green LEDs Threshold indicators: 7 red LEDs Status indicators: 3 on the C20/C25, or 7 on the C50/C55	
Operation interface	Teach/display button (TEACH/DISPLAY), UP/DOWN selection buttons, mode selector (TEACH/MON/RUN), 5 DIP switch pins: Automatic teaching (OFF/ON), model size (NORMAL/WIDE), OFF-delay timer (OFF/ON), matching/not matching (output ON for matching object/non-matching object), and external input (C50/C55 only) (LINE: To use the input line for external inputs in RUN mode; RS-232C/RS-422: To use serial communications for external inputs in RUN mode)	

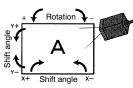
General Specifications

Item		Specification	
Ambient Operating		0°C to 50°C (32°F to 122°F) with no icing or condensation	
temperature	Storage	-25°C to 65°C (-13°F to 149°F) with no icing or condensation	
Ambient	Operating	35% to 85% (with no condensation)	
humidity	Storage	35% to 85% (with no condensation)	
Operating enviro	onment	With no corrosive gas	
Input power sup	ply	21.6 to 26.4 VDC (with ripple)	
Current consum	ption	300 mA max.	
Insulation resistance		20 MΩ min. (at 500 VDC)	
Dielectric strength		1,000 VAC at 50/60 Hz for 1 min	
Degree of protection IEC 60		IEC 60529 IP40	
Vibration resista	nce	10 Hz to 150 Hz, half-amplitude of 0.75 mm max. or 100 m/s ² max. for 32 min each in X, Y, and Z directions	
Shock resistance	е	Peak acceleration: 300 m/s ² 3 times each in X, Y, and Z directions	
Connection Prew		Prewired (standard cable length: 2 m)	
Casing material		ABS	
Weight (when packed)		Approx. 300 g (Unit: approx. 200 g (including cable))	
Accessories provided In		Instruction manual	

Engineering Data

DATA CHARACTERISTICS

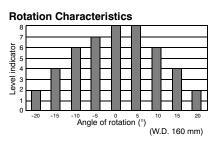
F10-S50R





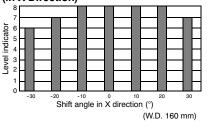
The following data is obtained on the basis of sample sensing objects, each of which is as large as this size (A). (Typical example)

The Head is inclined 15° to the sensing object.

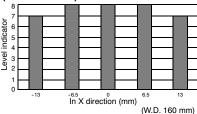


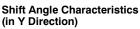
Shift Angle Characteristics (in X Direction)

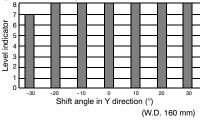
-15



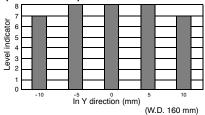
Area Position Characteristics (in X Direction)



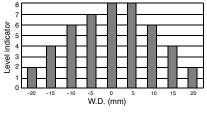


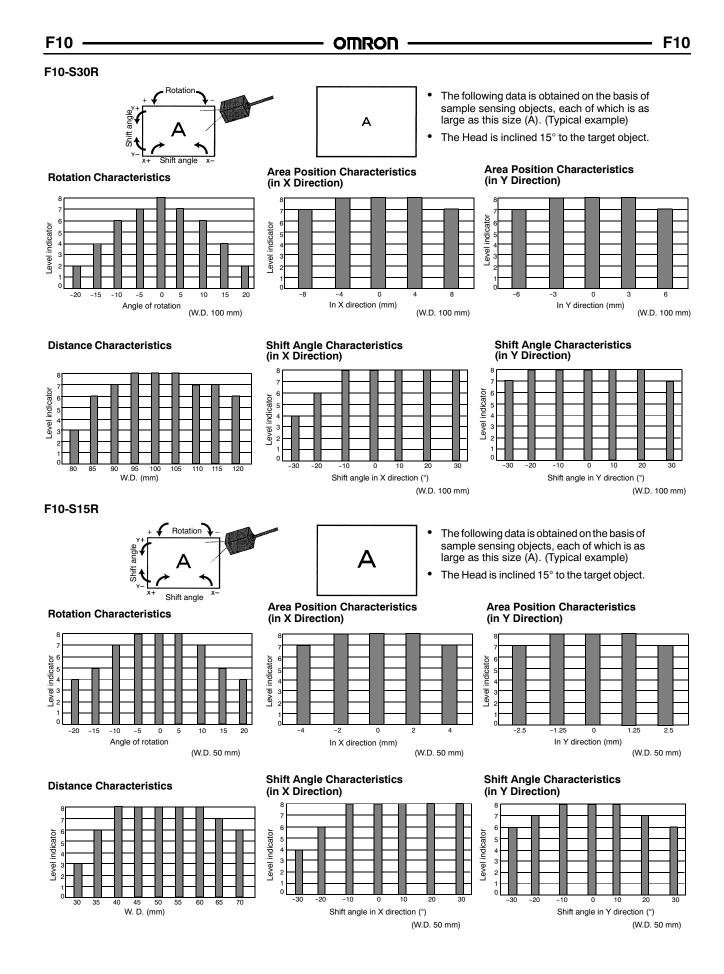


Area Position Characteristics (in Y Direction)



Distance Characteristics



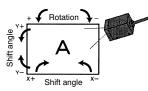


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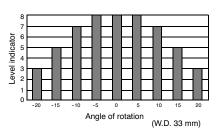
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(W.D. 33 mm)

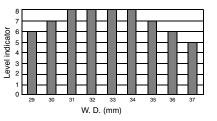
F10-S05R



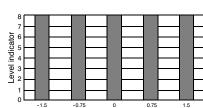
Rotation Characteristics



Distance Characteristics

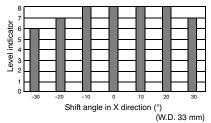


Area Position Characteristics (in X Direction)



-0.75 0 0.75 In X direction (mm)

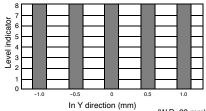
Shift Angle Characteristics (in X Direction)



The following data is obtained on the basis of sample sensing objects, each of which is as large as this size (Å). (Typical example)

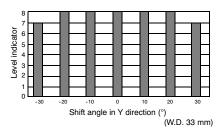
The Head is inclined 15° to the target object.

Area Position Characteristics (in Y Direction)



(W.D. 33 mm)

Shift Angle Characteristics (in Y Direction)

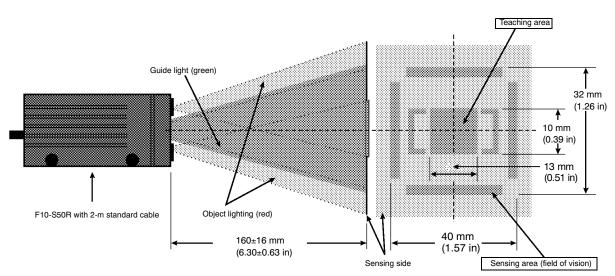


Nomenclature

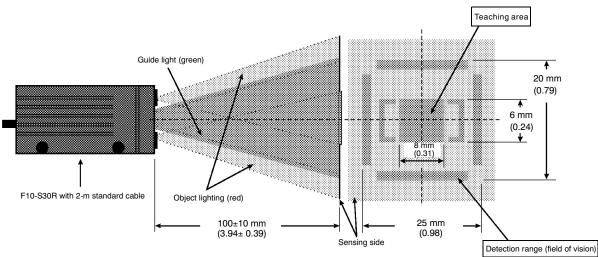
Unit: mm (inch)

■ HEADS

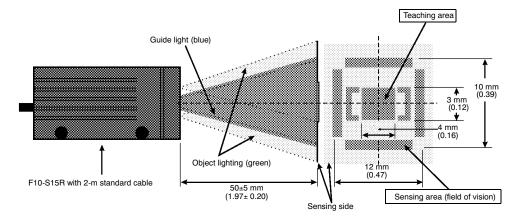
F10-S50R



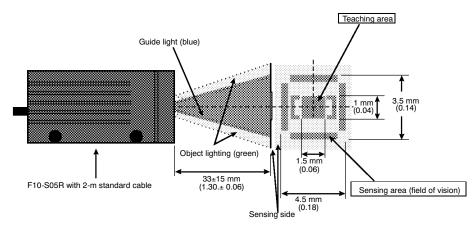
F10-S30R



F10-S15R



F10-S05R



AMPLIFIERS

F10-C20/C25 (2) Result (2) Result (1) Level (1) Level indicators **37**77 indicator indicators 3102(8-50 indicator 67 LL OUT ΟUT 5653 (4) Status (3) Threshold-(3)Threshold (4)Status indiindicators indicators cator/bank indicators number LEV(E) THRESHOLD **BEVE**I THREESHOLD (5) Teach/ display Teach/ (5) TEACH/ DISPLAY TEACH/ DISPLAY display ^ display (6) UP/DOWN button (6) UP/DOWN SELECT SELECT button selection selection buttons buttons MON MON TEACH - KUN TFACH RUN Mode (7)(7) Mode selector selector Measurement (8) Measurement TATTOLI 🐼 🖬 PATTIBA BATT-PLN 🗰 🚽 🕬 (8) (TEACH/ (TEACH/ item selection item/bank num-ND THE P ____WD TMB # _____UN MON/RUN) а т ок MON/RUN) switch ber selection 8 8 8 8 switch de in jai MADE IN JAPA (9) DIP switch (9) DIP switch (1) Displays measurement values (degree of conformity with the (8) • Changing Measurement Items registered model). PATT Automatically switches PATT•PLN (2) ON: Lit PATT/BANK between pattern mea-

- OFF: Not lit
- (3) Displays the threshold.
- (4) Displays type of value displayed on the level indicator.

F10-C20/C25

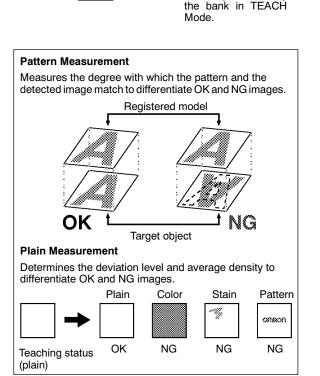
PATT (Pattern measurement): Degree of conformity with model PLN (Plain measurement)-DEV: Deviation level AVE: Average density

F10-C50/C55

- p Pattern measurement: Degree of conformity model
- *d*: Plain measurement: Deviation level
- R: Plain measurement: Difference from average density

Also displays bank number for F10-C50/C55

- (5) Starts teaching. Switches display item.
- (6)Changes the threshold value. Changes measurement item selection level for plain measurement. Changes bank number for F10-C50/C55.
- (7) TEACH: Teaching Mode MON: Monitor Mode RUN: Run Mode



PATT

PATT/BANK

PATT•PLN

PATT•PLN

• Bank Selection Mode

(F10-C50/C55)

surement and plain measurement depend-

Executes pattern

PATT/BANK measurement only.

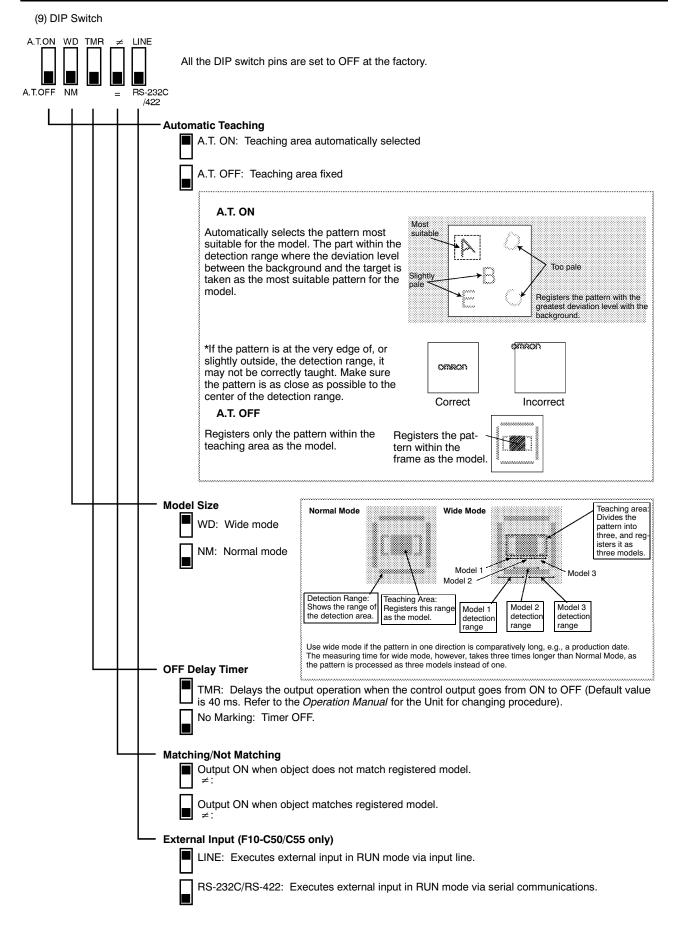
ing on the taught model.

Enters the mode for

selecting and setting

F10-C50/C55

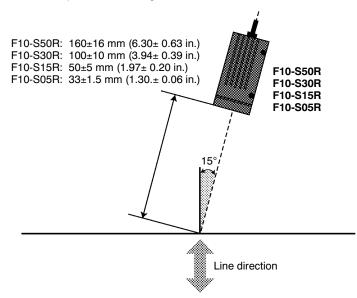
F10



Installation

MOUNTING ANGLE

- Incline the Head by 15° and mount the Head so that no regular reflection light affects the Sensor.
- Use the provided Mounting Bracket to mount the Head.



Sensor direction

Simulation

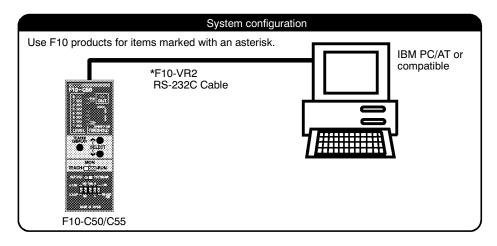
F10

Note: Position the sensor perpendicular to the direction of motion of the target object.

■ CONNECTION WITH PERIPHERALS (F10-C50/C55 ONLY)

You can input the measurement trigger and output the measurement results via an RS-232C port. You can also back up the settings in an IBM PC/AT or compatible. Refer to the *F10 Operation Manual* for details on communications commands.

1:1 Connection



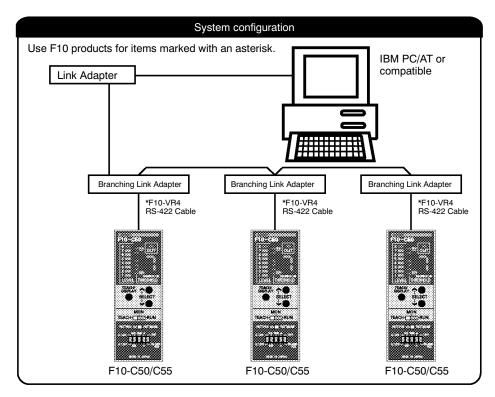
MULTIDROP CONNECTIONS

A maximum of 31 F10-C50/C55 Sensors can communicate with an IBM PC/AT or compatible by connecting though RS-232C/RS-422 converters.

Recommended Link Adapters (manufactured by OMRON) Link Adapter: B500-AL004 Branching Link Adapter: B500-AL001

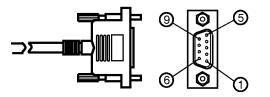
Note: When using a B500-AL004 Link Adapter, be sure to enable terminating resistance and include a terminating resistance in the last link adapter according to the following:

Between RDA(-) and RDB(+): 220 Ω (1/2 W min.) Between SDA(-) and SDB(+): 220 Ω (1/2 W min.)



F10-VR2

RS-232C Cable: D-sub 9-pin connector (2 m)

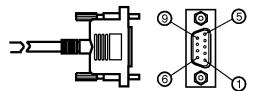


Pin No.	Signal	Name
2	SD (TXD)	Send data
3	RD (RXD)	Receive data
5	SG (GND)	Signal ground

Note: 1. Signal and name are in reference to the F10.

2. Secure the connector with, for example, binding tape.

F10-VR4 RS-422 Cable: D-sub 9-pin connector (2 m)



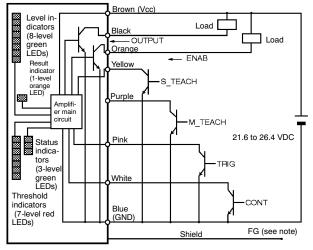
Pin No.	Signal	Name
1	RDB (+)	Receive data (+)
3	SG (GND)	Signal ground
5	SDB (+)	Send data (+)
6	RDA (-)	Receive data (-)
9	SDA (-)	Send data (-)

Operation

■ I/O CIRCUIT DIAGRAM

F10-C20 NPN Models

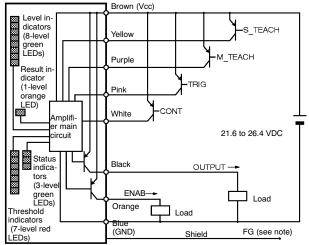
There are gray, green, and red input lines, but they are not used with this model. Take steps to ensure that these lines will not be short-circuited with other lines.



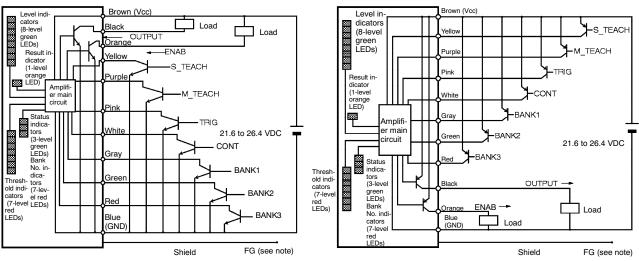
F10-C50 NPN Models

F10-C25 PNP Models

There are gray, green, and red input lines, but they are not used with this model. Take steps to ensure that these lines will not be short-circuited with other lines.



F10-C55 PNP Models



Note: For normal operation, ground or connect the shielded cable to 0 V. The shield is not connected to the interior or casing.

I/O Signals

Signal	Function
OUTPUT	Control output
ENAB	Enabled output
S_TEACH	Stationary object teaching input
M_TEACH	Moving object teaching input
TRIG	Measurement trigger input
CONT	Continuous measurement input
BANK1	Bank switching input (F10-C50/C55)
BANK2	
BANK3	

Note: All input signals are enabled in RUN mode only.

Switching Banks (F10-C50/C55)

You can switch banks by connecting BANK1 to BANK3 as shown below.

Bank No.	BANK1	BANK2	BANK3
Bank 0	OFF	OFF	OFF
Bank 1	ON	OFF	OFF
Bank 2	OFF	ON	OFF
Bank 3	ON	ON	OFF
Bank 4	OFF	OFF	ON
Bank 5	ON	OFF	ON
Bank 6	OFF	ON	ON
Bank 7	ON	ON	ON

SETTING PROCEDURE

Pattern Registration (TEACH Mode)

Use the following procedure to register measurement criteria.

- (1) Set the mode selector to TEACH.
- Make the automatic teaching and model size settings on the DIP switch.
 If using an F10-C50/C55, go to step (3) to set the bank number. If using an F10-C20/C25, go to step (5).
- (3) Set the measurement item/bank number selection switch to PATT/BANK. Bank No. 0 will be displayed.



Indicator Example

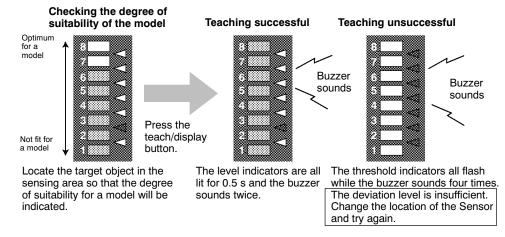
Banks Each F10-C50/C55 Sensor has eight banks for storing data, and a different threshold value can be stored in each of the eight banks. Use this function to take measurements under various conditions. You can switch operation simply by switching banks.

(4) Press the UP/DOWN select buttons to set the bank number.

TIP

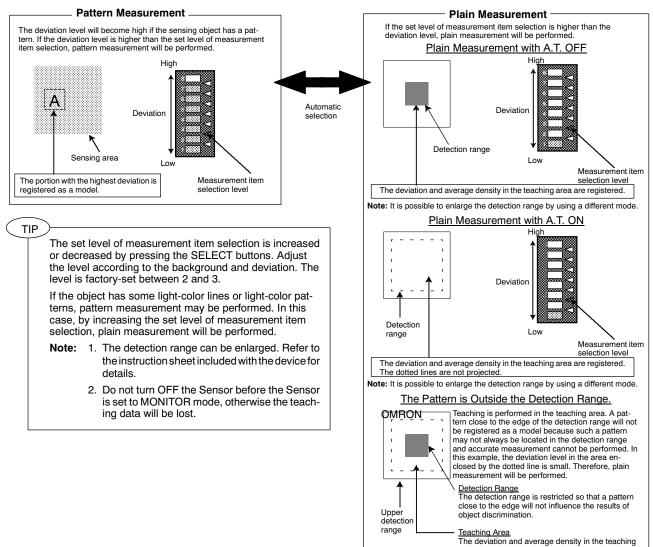
- (5) Use the measurement item (bank number for F10-C50/C55) selection switch to set the measurement method.
- (6) Press the teach/display button after locating the sensing object in the sensing area.

Measurement Items: PATT/BANK



Measurement Item: PATT-PLN

Whether measurement is patterned or plain is determined automatically by comparing the deviation level with the background within the detection range. When teaching is finished, all the level indicators will light for 0.5 s, and the buzzer will sound twice.



Note: Do not turn OFF the Sensor before the Sensor is set to MONITOR mode, otherwise the teaching data will be lost.

F10

area are registered in the above example.

F10

OMRON

Threshold Adjustment/Sample Test (MONITOR Mode)

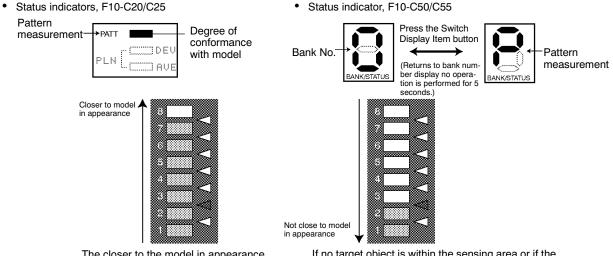
The Sensor operates in MONITOR mode for threshold level adjustments and desktop sample tests for object discrimination with no signal output. No external output operation signal or external input signal is accepted in MONITOR mode.

(1) Set the mode selector to MON.

Measurement continues as long as the selector is set to MON.

Pattern Measurement

On the basis of the registered model, the level indicator indicates the degree of conformity of the target object.

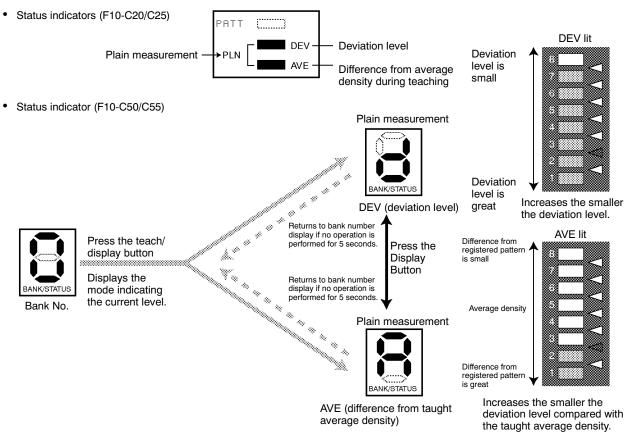


The closer to the model in appearance, the higher the level.

If no target object is within the sensing area or if the target object is greatly different from the model, the level will be lower.

Plain Measurement

Press the teach/display button to change the display (DEV-AVE).



(2) Press the UP/DOWN selection buttons to adjust the threshold. Adjust the threshold to the most suitable level by monitoring the level indicator. Altered threshold values will not be sound unless the mode selector is changed area to either PUN or TEAC

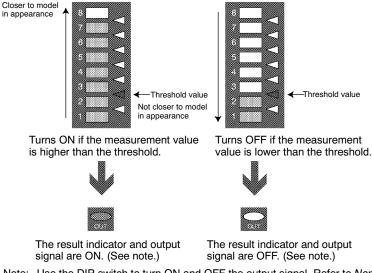
Altered threshold values will not be saved unless the mode selector is changed once to either RUN or TEACH.

Pattern Measurement

In wide mode, the pattern with the lowest degree of conformance among the three models is selected.

Plain Measurement

Set the threshold values for both DEV (deviation level) and AVE (average density). If either is lower than the threshold value, the discrimination result will be set to OFF.



Note: Use the DIP switch to turn ON and OFF the output signal. Refer to Nomenclature for details.

Performing Measurement in Response to External Input Signals (RUN Mode)

(1) Set the mode selector to RUN.

When the switch is set to RUN mode, measurements are made in response to external input signals.

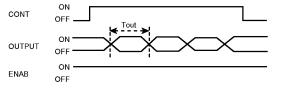
Relationship between the F10 I/O terminal operations and ON/OFF indications in the timing charts are as shown in the following table.

Signal	Indication in timing charts	NPN (F10-C20/C50)	PNP (F10-C25/C55)
Input TRIG (pink) CONT (white) S_TEACH (yellow) M_TEACH (purple) BANK1 (gray) (see note) BANK2 (green) (see note) BANK3 (red) (see note)	ON	GND	Vcc
	OFF	OPEN	OPEN
Output OUTPUT (black) ENAB (orange)	ON	GND	Vcc
	OFF	Vcc	GND

Note: F10-C20/C25 do not have banks 1 to 3.

CONT Mode

In CONT mode, the Sensor is in sensing operation repeatedly while the CONT signal is ON. The measurement result is renewed once per measurement cycle, and output.



Measurement cycle: Tout

Normal mode: 3.6 ms Wide mode: 10.8 ms Plain measurement: 7.2 ms

TRIG Mode

The Sensor in TRIG mode is used for object measurement only TIP once in synchronization with the rising edge of the TRIG signal and Turning the Guide Light ON and OFF: the result is output. In RUN mode, even when synchronous measurement is not being executed, the guide light ON TRIG will normally be ON. It is possible to turn the OFF guide light OFF (and ON again) by pressing Normal mode the UP selection button as required. ON OUTPUT OFF While the guide light is being turned ON or OFF, the ENAB signal is turned OFF, and no 10ms 3.6 ms max. external inputs can be received. ON The OUTPUT signal is turned OFF when the ENAB OFF UP selection button is pressed. Wide mode (plain measurement) Tout Press and hold ON OUTPUT down the UP selection button. OFF ON OFF 3.6 ms max. ON ON ENAB OFF OUTPUT OFF 0.7 s max ON **ENAB** OFF Minimum ON width for the trigger signal is 0 1 ms. OFF Guide light The OUTPUT signal is stored until the ON: Lit measurement results are refreshed. OFF: Unlit

ENAB signal:

OFF width is 10 ms in normal mode.

Turns ON when the OUTPUT signal is refreshed. Measurement cycle: Tout

Normal mode: 7.2 ms max. Wide mode: 14.4 ms max. Plain measurement: 10.8 ms max. In RUN mode, a model can be registered by external signal input using either of the following methods.

Note: The data of the model is stored in the EEPROM when the teaching process of the Sensor completes. Therefore, do not turn OFF the Sensor during the teaching process.

If the Sensor is turned OFF, an EEPROM data error will result when the Sensor is turned ON again. In this case, perform proper teaching and threshold level adjustments again.

Stationary Object Teaching (S_TEACH)

Stationary object teaching is performed with the TRIG signal input or CONT signal input after external S_TEACH signal input. Therefore, do not move the object until teaching is completed.

- (1) Provide S_TEACH signal input.
- (2) Check that the ENAB signal is OFF.
- (3) Check that the stationary object is in the teaching area (or in the sensing area if A.TEACH is set to ON).
- (4) Provide external CONT or TRIG signal input.
- (5) After teaching is completed, the ENAB signal will turn ON. At that time, check the status of the OUTPUT signal.
- (6) The OUTPUT signal will be ON if teaching is successfully completed.
- (7) The OUTPUT signal will be OFF if teaching is unsuccessful.
- (8) Turn the S_TEACH signal OFF to complete the teaching process. If teaching has been unsuccessful, the Sensor will remain in the previous status. Therefore, perform teaching again.

Moving Object Teaching (M_TEACH)

Moving object teaching is performed by using more than one object. Perform this teaching if the sensing objects cannot be stopped. After M_TEACH signal input, this teaching requires six processes in synchronization with external trigger input. The Sensor will not be in detection operation during the teaching process. External trigger input will be ignored after it is turned ON six times.

- (1) Provide external M_TEACH signal input.
- (2) Check that the ENAB signal is OFF.
- (3) Provide TRIG signal input in synchronization with the measurement timing of the sensing objects used for teaching.
- (4) Repeat step 3 six times.
- (5) After teaching is completed, the ENAB signal will turn ON. At that time, check the status of the OUTPUT signal.
- (6) The OUTPUT signal will be ON if teaching is successfully completed.
- (7) The OUTPUT signal will be OFF if teaching is unsuccessful.
- (8) Turn the M_TEACH signal OFF to complete the teaching process. If the teaching has been unsuccessful, the Sensor will remain in the previous status. Therefore, perform teaching again. The teaching operation will be disabled if the M_TEACH signal is turned OFF during the teaching process.

ENABLE

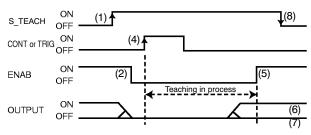
Enable output turns ON when the Sensor is ready to be in sensing operation. Therefore, enable output will turn OFF if the mode selector is set to TEACH or MON.

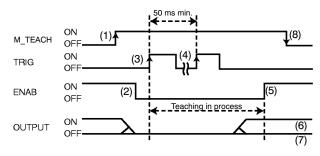
Enable output is OFF in the following cases in RUN mode.

- 1. The Sensor is in teaching process with external teaching input.
- 2. The Sensor is in sensing operation with TRIG signal input.
- 3. No teaching data has been registered.
- 4. The hardware fails.
- 5. The bank is being switched.
- 6. The guide light is being turned ON or OFF.

RS-232C/RS-422 COMMAND INPUTS (F10-C50/C55 ONLY)

Communications with external devices, such as an IBM PC/AT or compatible, is possible via the RS-232C/RS-422 port. Refer to the *Operation Manual* for the unit for details on the communications commands.





Troubleshooting _____

Problem	Probable cause	Remedy
Buzzer sounds This LED of the threshold indicators flashes and the buzzer sounds.	Head disconnection error The Head is not connected properly and no image signal is obtainable.	Connect the Head and turn the Sensor OFF and ON. Note: 1. If the same error occurs again, the Head may be broken. Con- sult your OMRON representa- tive.
Buzzer sounds This LED of the threshold indicators flashes and the buzzer sounds.	Hardware error A hardware failure, such as CPU runaway, has resulted.	Consult your OMRON representative.
Buzzer sounds This LED of the threshold indicators flashes and the buzzer sounds.	Head data read error1. The EEPROM data of the Head is not readable.2. The data is illegal.	
Buzzer sounds This LED of the threshold indicators flashes and the buzzer sounds.	Amplifier data read error1. The EEPROM data of the Amplifier is not readable.2. The data is illegal.	 Turn the Sensor OFF and ON. 2. All internal data of the Amplifier may be cleared. 3. If the same error occurs again after turning the Sensor OFF and ON, consult your OMRON representative.
Buzzer sounds This LED of the threshold indicators flashes and the buzzer sounds.	Amplifier data write error1.No EEPROM data is written to the Amplifier.2.The data is illegal.	
Buzzer sounds This threshold indicator flashes and the buzzer sounds.	Detection range mode error The detection range mode currently set is different from that set in teaching.	Perform teaching again in TEACH mode or change the detection range mode.

(This table continues on the next page.)

Troubleshooting (continued)

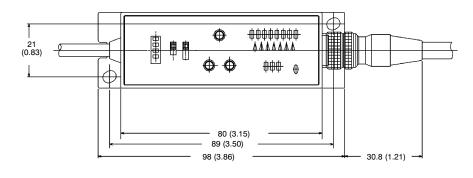
Problem	Probable cause	Remedy
Buzzer sounds This LED of the threshold indicators flashes and the buzzer sounds.	Head type error An F10-S30/S15 is connected to the head.	Connect an F10-S30R/S15R/S05R to the head.
Buzzer sounds	Teaching data setting error The Sensor was set to MONITOR or RUN mode before teaching completed.	Perform the teaching of the Sensor in TEACH mode. Refer to 1. Pattern Registration (TEACH Mode) within the Operation Section under the head SETTING PROCEDURE.
Buzzer sounds These LEDs of the threshold indicators flashes and the buzzer sounds three times.	Serial buffer overflow error Either the send buffer or receive buffer has become full during communications.	Send buffer overflow Change the communications settings. Receive buffer overflow Wait for a response from the F10, then send the command.
Control output (OUTPUT) and enable output are OFF, and will not turn ON.	A current exceeding the rated value has flowed to the output transistor and the overcurrent protective circuit has been triggered.	Reduce the current so that it will not exceed the rated value. Note: If the output does not turn ON even after reducing the current below the rated value, contact your OMRON representative.

Dimensions

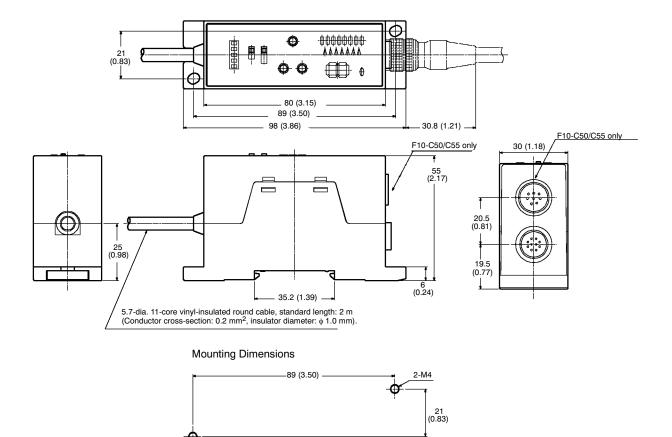
AMPLIFIERS

Unit: mm (inch)

F10-C20 F10-C25

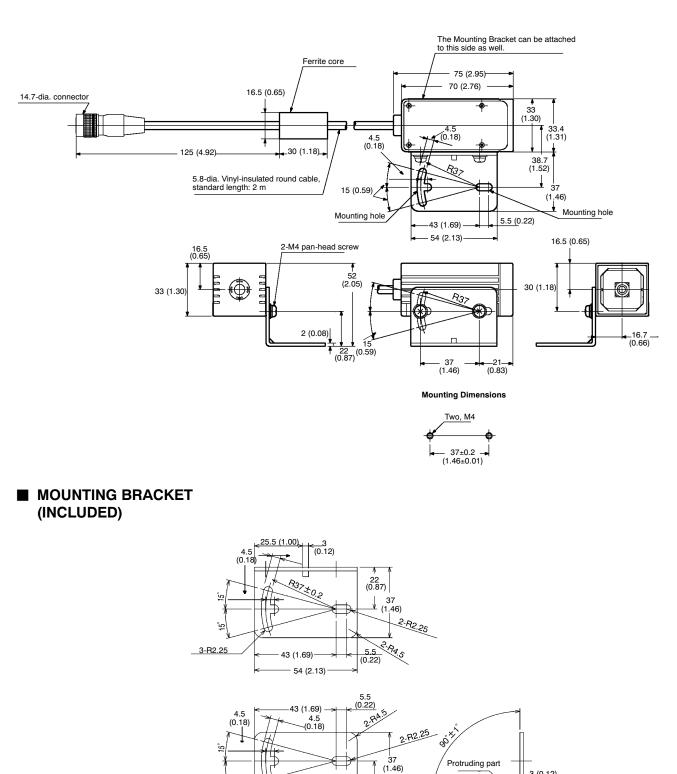


F10-C50 F10-C55



HEADS

Unit: mm (inch) F10-S R



22 (0.87)

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3-R2.25

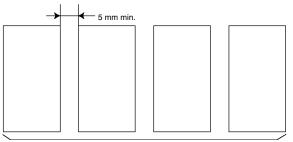
3 (0.12)

3 (0.12)

R1 max.

SETUP AND MOUNTING

The F10-C \square Amplifier radiates heat. If more than one Unit is installed side-by-side, make sure that there is a minimum space of 5 mm between adjacent Units as shown below.



Amplifiers

- Do not disconnect or connect the Head while the Sensor is turned ON.
- The F10-S30R/S50R cannot detect red objects with white backgrounds. Use the F10-S15R instead.
- The F10-S15R/S05R cannot detect green objects with white backgrounds. Use the F10-S30R/S50R instead.
- Make sure that the length of the cable of the Amplifier is no longer than 20 m.
- Make sure that the tightening torque of each screw on the Head and Amplifier is no greater than 1.2 N m.
- The connector on the Amplifier and the metal screws on the bottom of the Amplifier are connected internally to 0-V terminal of the Amplifier.
- The operating ambient temperature range of the Amplifier is between 0°C and 50°C under the following conditions.
- Provide enough ventilation to the Amplifier. If more than one Unit is installed side-by-side, provide a ventilation fan for efficient ventilation.
- Do not install the Amplifier close to heat-radiating devices such as heaters, transformers, and high-capacity resistors.
- If power lines with high current for motors are wired close to the Amplifier, make sure that the Amplifier operates normally and take proper measures so that the power lines will not have a bad influence on the operation of the Amplifier.

APPLICATION PRECAUTIONS

- /ı̯\- Caution -

- Do not make mistakes in wiring, such as mistakes in polarity. Doing so may cause Sensor damage or malfunction.
- Do not apply voltage exceeding the rated range. Doing so may cause Sensor damage or malfunction.
- Do not short-circuit the load. Doing so may cause Sensor damage or malfunction.
- Organic solvents may damage the casing of the Amplifier, which is made of ABS resin and the transparent front panel of the Head, which is made of acrylic resin. Do not use paint thinner or any other organic solvent to clean the product.
- Be sure to set the locking mechanism on the cables and units before use.
- Do not use the Sensor in an environment where the degree of protection is not satisfied.
- Do not disassemble the Sensor. Doing so may cause malfunction or breakdown.

GENERAL PRECAUTIONS

The user must operate the product according to the performance specifications described in the brochure.

Consult your OMRON representative before using the product under conditions which are not described in the brochure or applying the product to nuclear control systems, railroad systems, aviation systems, vehicles, combustion systems, medical equipment, amusement machines, safety equipment, and other systems, machines, and equipment that may have a serious influence on lives and property if used improperly.

NOTE: DIMENSIONS SHOWN ARE IN MILLIMETERS. To convert millimeters to inches divide by 25.4.



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Specifications subject to change without notice.

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