

## DS90C031

### LVDS Quad CMOS Differential Line Driver

#### General Description

The DS90C031 is a quad CMOS differential line driver designed for applications requiring ultra low power dissipation and high data rates. The device is designed to support data rates in excess of 155.5 Mbps (77.7 MHz) utilizing Low Voltage Differential Signaling (LVDS) technology.

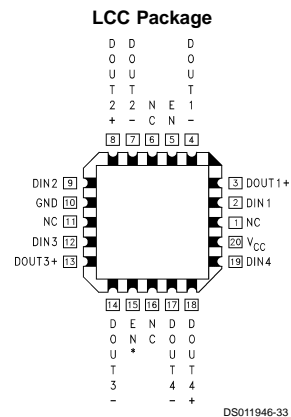
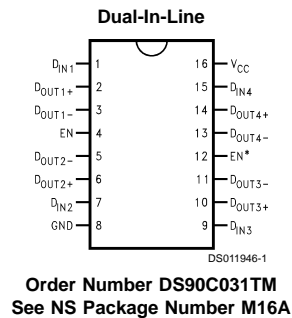
The DS90C031 accepts TTL/CMOS input levels and translates them to low voltage (350 mV) differential output signals. In addition the driver supports a TRI-STATE<sup>®</sup> function that may be used to disable the output stage, disabling the load current, and thus dropping the device to an ultra low idle power state of 11 mW typical.

The DS90C031 and companion line receiver (DS90C032) provide a new alternative to high power psuedo-ECL devices for high speed point-to-point interface applications.

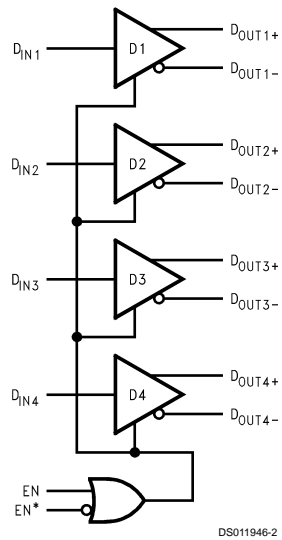
#### Features

- >155.5 Mbps (77.7 MHz) switching rates
- ±350 mV differential signaling
- Ultra low power dissipation
- 400 ps maximum differential skew (5V, 25°C)
- 3.5 ns maximum propagation delay
- Industrial operating temperature range
- Military operating temperature range option
- Available in surface mount packaging (SOIC) and (LCC)
- Pin compatible with DS26C31, MB571 (PECL) and 41LG (PECL)
- Compatible with IEEE 1596.3 SCI LVDS standard
- Conforms to ANSI/TIA/EIA-644 LVDS standard
- Available to Standard Microcircuit Drawing (SMD) 5962-95833

#### Connection Diagrams



## Functional Diagram



## Truth Table

### DRIVER

Enables		Input	Outputs	
EN	EN*	D <sub>IN</sub>	D <sub>OUT+</sub>	D <sub>OUT-</sub>
L	H	X	Z	Z
All other combinations of ENABLE inputs		L	L	H
		H	H	L

## Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

Supply Voltage ( $V_{CC}$ )	-0.3V to +6V
Input Voltage ( $D_{IN}$ )	-0.3V to ( $V_{CC} + 0.3V$ )
Enable Input Voltage (EN, EN*)	-0.3V to ( $V_{CC} + 0.3V$ )
Output Voltage ( $D_{OUT+}$ , $D_{OUT-}$ )	-0.3V to ( $V_{CC} + 0.3V$ )
Short Circuit Duration ( $D_{OUT+}$ , $D_{OUT-}$ )	Continuous
Maximum Package Power Dissipation @ +25°C	
M Package	1068 mW
E Package	1900 mW
Derate M Package	8.5 mW/°C above +25°C
Derate E Package	12.8 mW/°C above +25°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature Range	
Soldering (4 sec.)	+260°C

Maximum Junction Temperature (DS90C031T)	+150°C
Maximum Junction Temperature (DS90C031E)	+175°C
ESD Rating (Note 7)	
(HBM, 1.5 k $\Omega$ , 100 pF)	$\geq 3,500V$
(EIAJ, 0 $\Omega$ , 200 pF)	$\geq 250V$

## Recommended Operating Conditions

	Min	Typ	Max	Units
Supply Voltage ( $V_{CC}$ )	+4.5	+5.0	+5.5	V
Operating Free Air Temperature ( $T_A$ )				
DS90C031T	-40	+25	+85	°C
DS90C031E	-55	+25	+125	°C

## Electrical Characteristics

Over supply voltage and operating temperature ranges, unless otherwise specified. (Notes 2, 3)

Symbol	Parameter	Conditions	Pin	Min	Typ	Max	Units	
$V_{OD1}$	Differential Output Voltage	$R_L = 100\Omega$ (Figure 1)	$D_{OUT-}$	250	345	450	mV	
$\Delta V_{OD1}$	Change in Magnitude of $V_{OD1}$ for Complementary Output States		$D_{OUT+}$		4	35	mV	
$V_{OS}$	Offset Voltage			1.125	1.25	1.375	V	
$\Delta V_{OS}$	Change in Magnitude of $V_{OS}$ for Complementary Output States				5	25	mV	
$V_{OH}$	Output Voltage High	$R_L = 100\Omega$			1.41	1.60	V	
$V_{OL}$	Output Voltage Low			0.90	1.07		V	
$V_{IH}$	Input Voltage High		$D_{IN}$ , EN, EN*	2.0		$V_{CC}$	V	
$V_{IL}$	Input Voltage Low			GND		0.8	V	
$I_I$	Input Current	$V_{IN} = V_{CC}$ , GND, 2.5V or 0.4V		-10	$\pm 1$	+10	$\mu A$	
$V_{CL}$	Input Clamp Voltage	$I_{CL} = -18$ mA		-1.5	-0.8		V	
$I_{OS}$	Output Short Circuit Current	$V_{OUT} = 0V$ (Note 8)	$D_{OUT-}$		-3.5	-5.0	mA	
$I_{OZ}$	Output TRI-STATE Current	EN = 0.8V and EN* = 2.0V, $V_{OUT} = 0V$ or $V_{CC}$	$D_{OUT+}$	-10	$\pm 1$	+10	$\mu A$	
$I_{CC}$	No Load Supply Current Drivers Enabled	$D_{IN} = V_{CC}$ or GND $D_{IN} = 2.5V$ or 0.4V	DS90C031T	$V_{CC}$		1.7	3.0	mA
$I_{CC}$	Loaded Supply Current Drivers Enabled	$R_L = 100\Omega$ All Channels $V_{IN} = V_{CC}$ or GND (all inputs)	DS90C031T			4.0	6.5	mA
$I_{CC}$			DS90C031E			15.4	21.0	mA
$I_{CCZ}$	No Load Supply Current Drivers Disabled	$D_{IN} = V_{CC}$ or GND EN = GND, EN* = $V_{CC}$	DS90C031T			2.2	4.0	mA
$I_{CCZ}$			DS90C031E			2.2	10.0	mA

## Switching Characteristics

$V_{CC} = +5.0V$ ,  $T_A = +25^\circ C$  DS90C031T. (Notes 3, 4, 6, 9)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{PHLD}$	Differential Propagation Delay High to Low	$R_L = 100\Omega$ , $C_L = 5$ pF	1.0	2.0	3.0	ns
$t_{PLHD}$	Differential Propagation Delay Low to High	(Figure 2 and Figure 3)	1.0	2.1	3.0	ns
$t_{SKD}$	Differential Skew $ t_{PHLD} - t_{PLHD} $		0	80	400	ps
$t_{SK1}$	Channel-to-Channel Skew (Note 4)		0	300	600	ps

### Switching Characteristics (Continued)

$V_{CC} = +5.0V$ ,  $T_A = +25^\circ C$  DS90C031T. (Notes 3, 4, 6, 9)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{TLH}$	Rise Time	$R_L = 100\Omega$ , $C_L = 5\text{ pF}$ (Figure 4 and Figure 5)		0.35	1.5	ns
$t_{THL}$	Fall Time			0.35	1.5	ns
$t_{PHZ}$	Disable Time High to Z			2.5	10	ns
$t_{PLZ}$	Disable Time Low to Z			2.5	10	ns
$t_{PZH}$	Enable Time Z to High			2.5	10	ns
$t_{PZL}$	Enable Time Z to Low			2.5	10	ns

### Switching Characteristics

$V_{CC} = +5.0V \pm 10\%$ ,  $T_A = -40^\circ C$  to  $+85^\circ C$  DS90C031T. (Notes 3, 4, 5, 6, 9)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{PHLD}$	Differential Propagation Delay High to Low	$R_L = 100\Omega$ , $C_L = 5\text{ pF}$ (Figure 2 and Figure 3)	0.5	2.0	3.5	ns
$t_{PLHD}$	Differential Propagation Delay Low to High		0.5	2.1	3.5	ns
$t_{SKD}$	Differential Skew $ t_{PHLD} - t_{PLHD} $		0	80	900	ps
$t_{SK1}$	Channel-to-Channel Skew (Note 4)		0	0.3	1.0	ns
$t_{SK2}$	Chip to Chip Skew (Note 5)				3.0	ns
$t_{TLH}$	Rise Time				0.35	2.0
$t_{THL}$	Fall Time			0.35	2.0	ns
$t_{PHZ}$	Disable Time High to Z	$R_L = 100\Omega$ , $C_L = 5\text{ pF}$ (Figure 4 and Figure 5)		2.5	15	ns
$t_{PLZ}$	Disable Time Low to Z			2.5	15	ns
$t_{PZH}$	Enable Time Z to High			2.5	15	ns
$t_{PZL}$	Enable Time Z to Low			2.5	15	ns

### Switching Characteristics

$V_{CC} = +5.0V \pm 10\%$ ,  $T_A = -55^\circ C$  to  $+125^\circ C$  DS90C031E. (Notes 3, 4, 5, 6, 9, 10)

Symbol	Parameter	Conditions	Min	Typ	Max	Units
$t_{PHLD}$	Differential Propagation Delay High to Low	$R_L = 100\Omega$ , $C_L = 20\text{ pF}$ (Figure 3)	0.5	2.0	5.0	ns
$t_{PLHD}$	Differential Propagation Delay Low to High		0.5	2.1	5.0	ns
$t_{SKD}$	Differential Skew $ t_{PHLD} - t_{PLHD} $	$C_L$ Connected between each Output and GND	0	0.08	3.0	ns
$t_{SK1}$	Channel-to-Channel Skew (Note 4)		0	0.3	3.0	ns
$t_{SK2}$	Chip to Chip Skew (Note 5)			4.5	ns	
$t_{PHZ}$	Disable Time High to Z	$R_L = 100\Omega$ , $C_L = 5\text{ pF}$ (Figure 4 and Figure 5)		2.5	20	ns
$t_{PLZ}$	Disable Time Low to Z			2.5	20	ns
$t_{PZH}$	Enable Time Z to High			2.5	20	ns
$t_{PZL}$	Enable Time Z to Low			2.5	20	ns

### Parameter Measurement Information

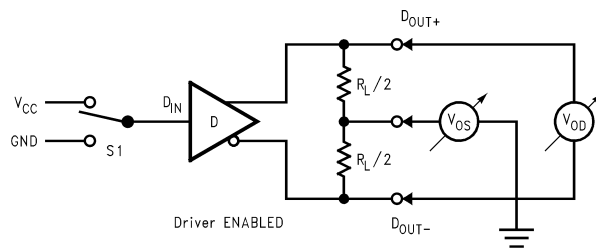
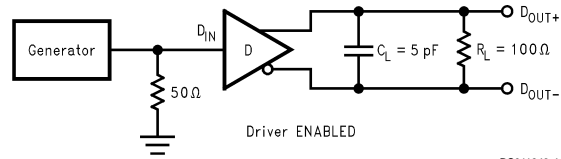


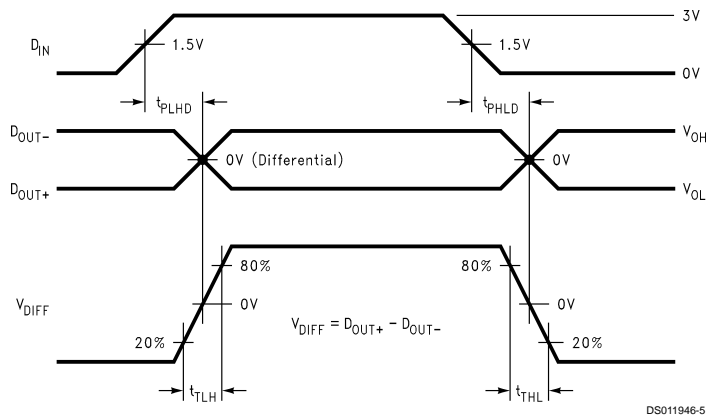
FIGURE 1. Driver  $V_{OD}$  and  $V_{OS}$  Test Circuit

## Parameter Measurement Information (Continued)



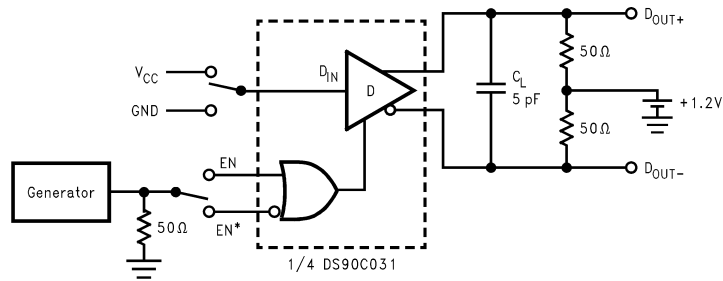
DS011946-4

FIGURE 2. Driver Propagation Delay and Transition Time Test Circuit



DS011946-5

FIGURE 3. Driver Propagation Delay and Transition Time Waveforms



DS011946-6

FIGURE 4. Driver TRI-STATE Delay Test Circuit

## Parameter Measurement Information (Continued)

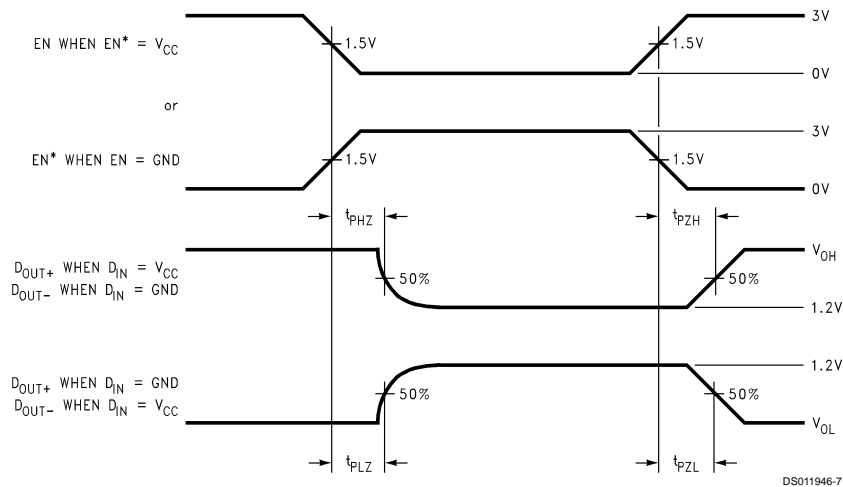


FIGURE 5. Driver TRI-STATE Delay Waveform

## Typical Application

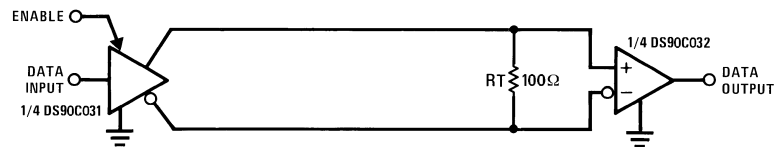


FIGURE 6. Point-to-Point Application

## Applications Information

LVDS drivers and receivers are intended to be primarily used in an uncomplicated point-to-point configuration as is shown in *Figure 6*. This configuration provides a clean signaling environment for the quick edge rates of the drivers. The receiver is connected to the driver through a balanced media which may be a standard twisted pair cable, a parallel pair cable, or simply PCB traces. Typically, the characteristic impedance of the media is in the range of  $100\Omega$ . A termination resistor of  $100\Omega$  should be selected to match the media, and is located as close to the receiver input pins as possible. The termination resistor converts the current sourced by the driver into a voltage that is detected by the receiver. Other configurations are possible such as a multi-receiver configuration, but the effects of a mid-stream connector(s), cable stub(s), and other impedance discontinuities as well as ground shifting, noise margin limits, and total termination loading must be taken into account.

The DS90C031 differential line driver is a balanced current source design. A current mode driver, generally speaking has a high output impedance and supplies a constant current for a range of loads (a voltage mode driver on the other hand supplies a constant voltage for a range of loads). Current is switched through the load in one direction to produce a logic state and in the other direction to produce the other logic state. The typical output current is mere 3.4 mA, a minimum of 2.5 mA, and a maximum of 4.5 mA. The current mode **requires** (as discussed above) that a resistive termi-

nation be employed to terminate the signal and to complete the loop as shown in *Figure 6*. AC or unterminated configurations are not allowed. The 3.4 mA loop current will develop a differential voltage of 340 mV across the  $100\Omega$  termination resistor which the receiver detects with a 240 mV minimum differential noise margin neglecting resistive line losses (driven signal minus receiver threshold ( $340\text{ mV} - 100\text{ mV} = 240\text{ mV}$ )). The signal is centered around +1.2V (Driver Offset,  $V_{OS}$ ) with respect to ground as shown in *Figure 7*. Note that the steady-state voltage ( $V_{SS}$ ) peak-to-peak swing is twice the differential voltage ( $V_{OD}$ ) and is typically 680 mV.

The current mode driver provides substantial benefits over voltage mode drivers, such as an RS-422 driver. Its quiescent current remains relatively flat versus switching frequency. Whereas the RS-422 voltage mode driver increases exponentially in most case between 20 MHz–50 MHz. This is due to the overlap current that flows between the rails of the device when the internal gates switch. Whereas the current mode driver switches a fixed current between its output without any substantial overlap current. This is similar to some ECL and PECL devices, but without the heavy static  $I_{CC}$  requirements of the ECL/PECL designs. LVDS requires 80% less current than similar PECL devices. AC specifications for the driver are a tenfold improvement over other existing RS-422 drivers.

The TRI-STATE function allows the driver outputs to be disabled, thus obtaining an even lower power state when the transmission of data is not required.

## Applications Information (Continued)

The footprint of the DS90C031 is the same as the industry standard 26LS31 Quad Differential (RS-422) Driver.

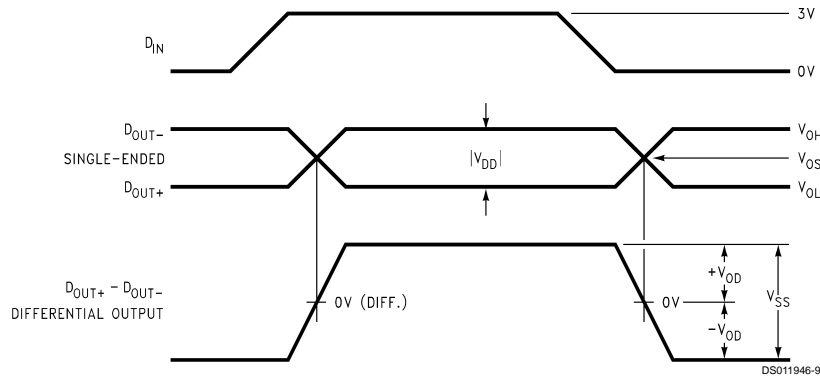


FIGURE 7. Driver Output Levels

## Pin Descriptions

Pin No. (SOIC)	Name	Description
1, 7, 9, 15	D <sub>IN</sub>	Driver input pin, TTL/CMOS compatible
2, 6, 10, 14	D <sub>OUT+</sub>	Non-inverting driver output pin, LVDS levels
3, 5, 11, 13	D <sub>OUT-</sub>	Inverting driver output pin, LVDS levels
4	EN	Active high enable pin, OR-ed with EN*
12	EN*	Active low enable pin, OR-ed with EN

Pin No. (SOIC)	Name	Description
16	V <sub>CC</sub>	Power supply pin, +5V ± 10%
8	GND	Ground pin

## Ordering Information

Operating Temperature	Package Type/ Number	Order Number
-40°C to +85°C	SOP/M16A	DS90C031TM
-55°C to +125°C	LCC/E20A	DS90C031E-QML
DS90C031E-QML	(NSID)	
5962-95833	(SMD)	

**Note 1:** "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the devices should be operated at these limits. The table of "Electrical Characteristics" specifies conditions of device operation.

**Note 2:** Current into device pins is defined as positive. Current out of device pins is defined as negative. All voltages are referenced to ground except: V<sub>OD1</sub> and ΔV<sub>OD1</sub>.

**Note 3:** All typicals are given for: V<sub>CC</sub> = +5.0V, T<sub>A</sub> = +25°C.

**Note 4:** Channel-to-Channel Skew is defined as the difference between the propagation delay of the channel and the other channels in the same chip with an event on the inputs.

**Note 5:** Chip to Chip Skew is defined as the difference between the minimum and maximum specified differential propagation delays.

**Note 6:** Generator waveform for all tests unless otherwise specified: f = 1 MHz, Z<sub>O</sub> = 50Ω, t<sub>r</sub> ≤ 6 ns, and t<sub>f</sub> ≤ 6 ns.

**Note 7:** ESD Ratings:

HBM (1.5 kΩ, 100 pF) ≥ 3,500V

EIAJ (0Ω, 200 pF) ≥ 250V

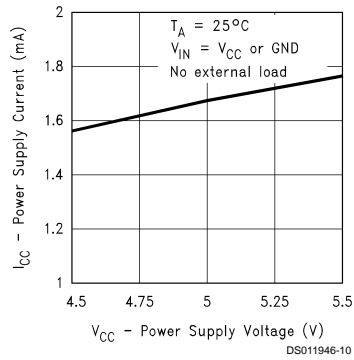
**Note 8:** Output short circuit current (I<sub>OS</sub>) is specified as magnitude only, minus sign indicates direction only.

**Note 9:** C<sub>L</sub> includes probe and jig capacitance.

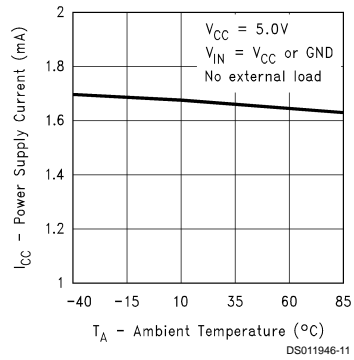
**Note 10:** Guaranteed by characterization data (DS90C031E).

## Typical Performance Characteristics

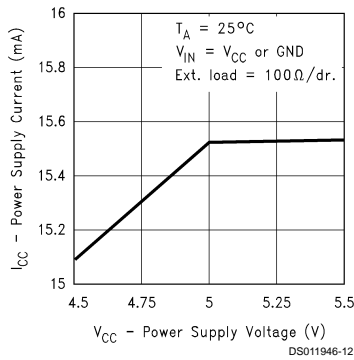
**Power Supply Current vs Power Supply Voltage**



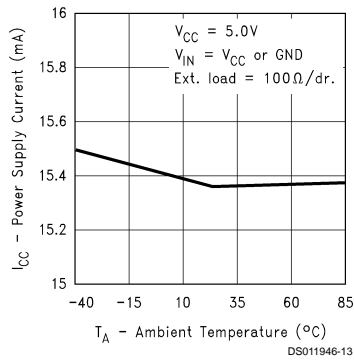
**Power Supply Current vs Temperature**



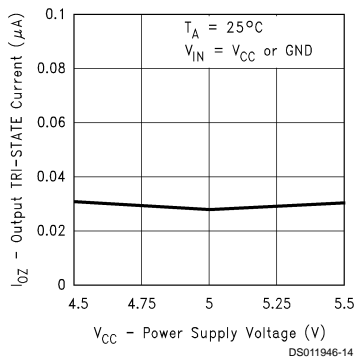
**Power Supply Current vs Power Supply Voltage (Ext. load)**



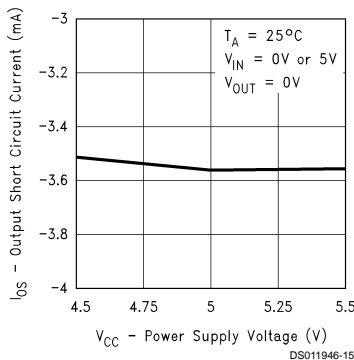
**Power Supply Current vs Temperature (Ext. load)**



**Output TRI-STATE Current vs Power Supply Voltage**



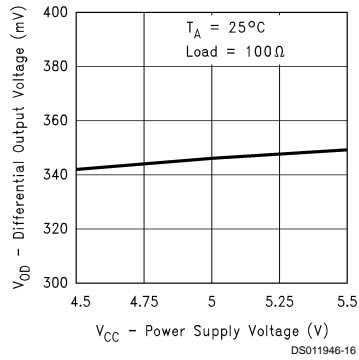
**Output Short Circuit Current vs Power Supply Voltage**



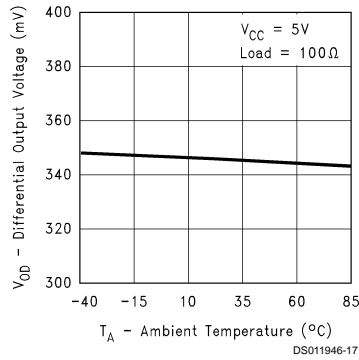


## Typical Performance Characteristics (Continued)

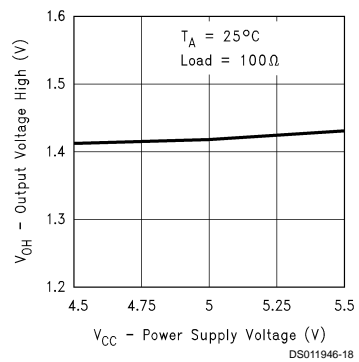
**Differential Output Voltage vs Power Supply Voltage**



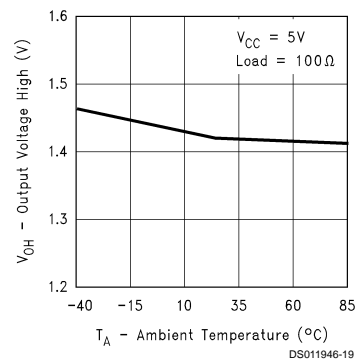
**Differential Output Voltage vs Ambient Temperature**



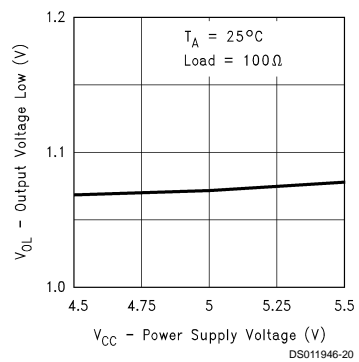
**Output Voltage High vs Power Supply Voltage**



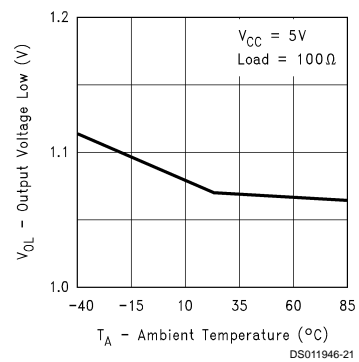
**Output Voltage High vs Ambient Temperature**



**Output Voltage Low vs Power Supply Voltage**

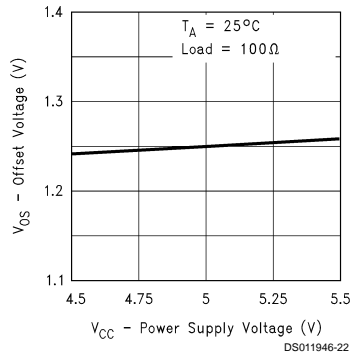


**Output Voltage Low vs Ambient Temperature**

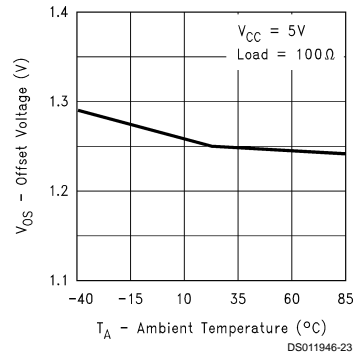


## Typical Performance Characteristics (Continued)

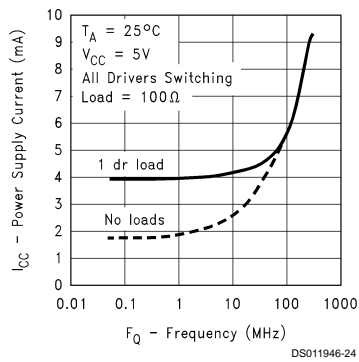
**Offset Voltage vs Power Supply Voltage**



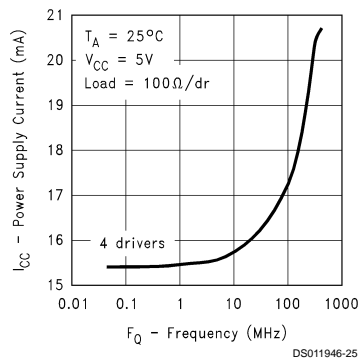
**Offset Voltage vs Ambient Temperature**



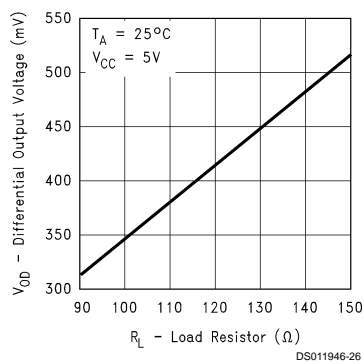
**Power Supply Current vs Frequency**



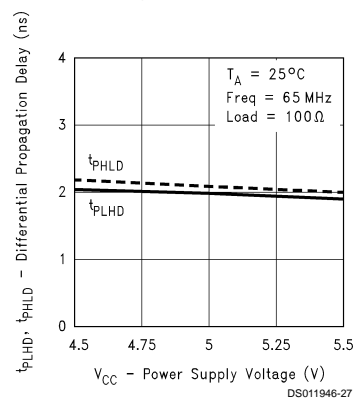
**Power Supply Current vs Frequency**



**Differential Output Voltage vs Load Resistor**

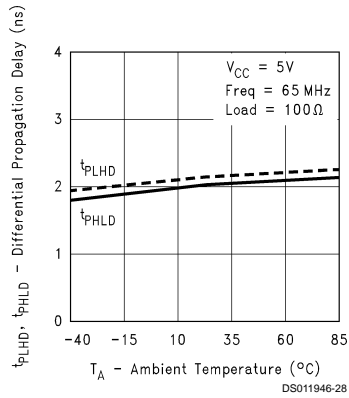


**Differential Propagation Delay vs Power Supply Voltage**

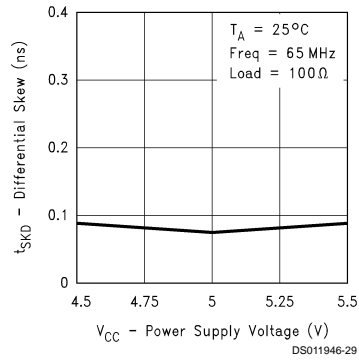


## Typical Performance Characteristics (Continued)

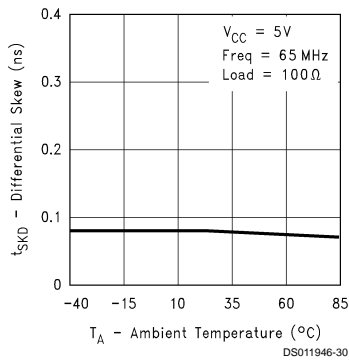
**Differential Propagation Delay vs Ambient Temperature**



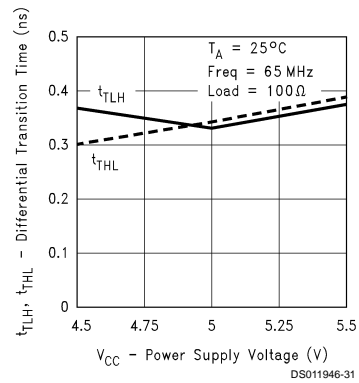
**Differential Skew vs Power Supply Voltage**



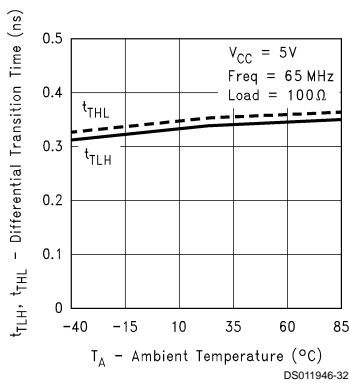
**Differential Skew vs Ambient Temperature**

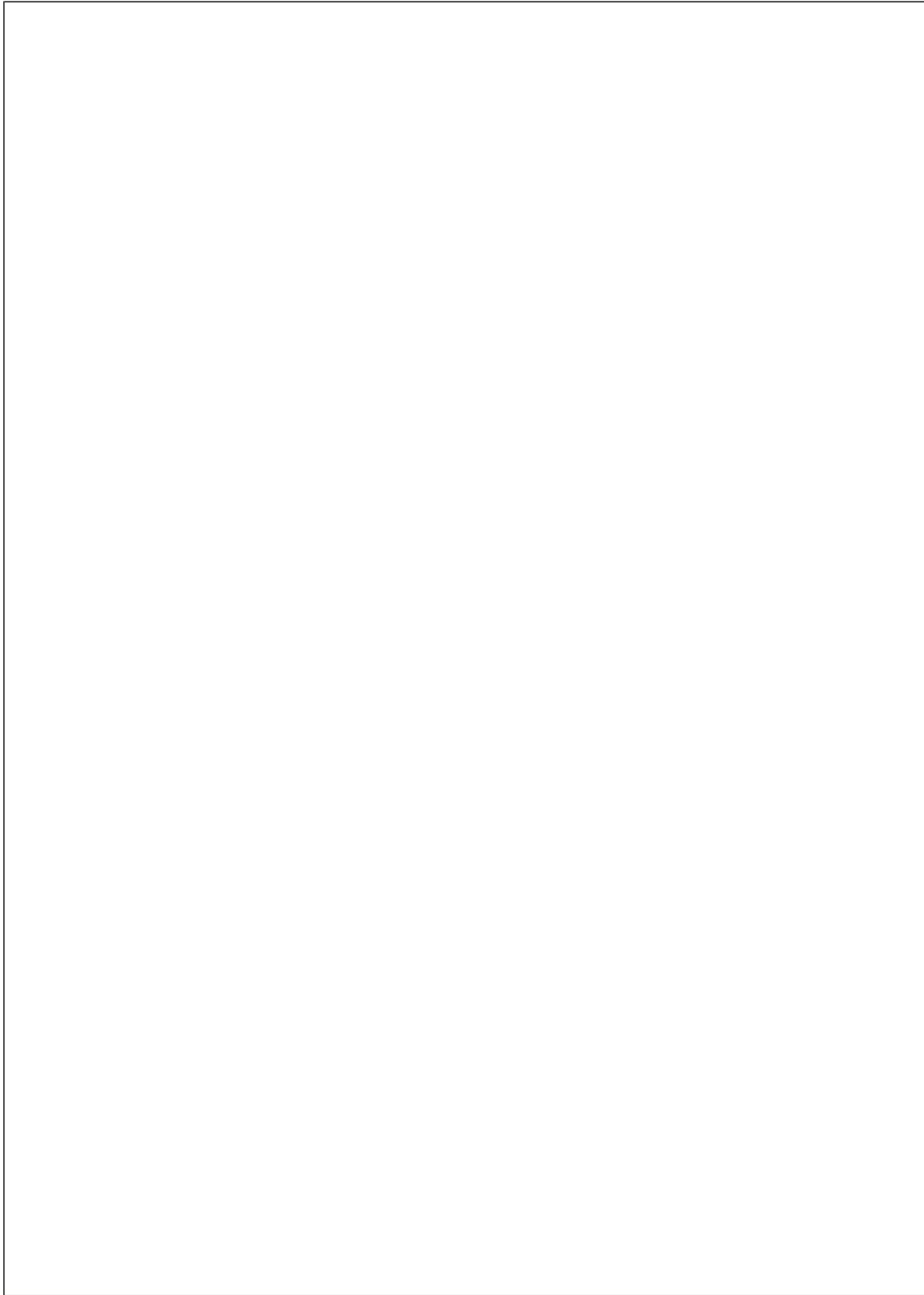


**Differential Transition Time vs Power Supply Voltage**

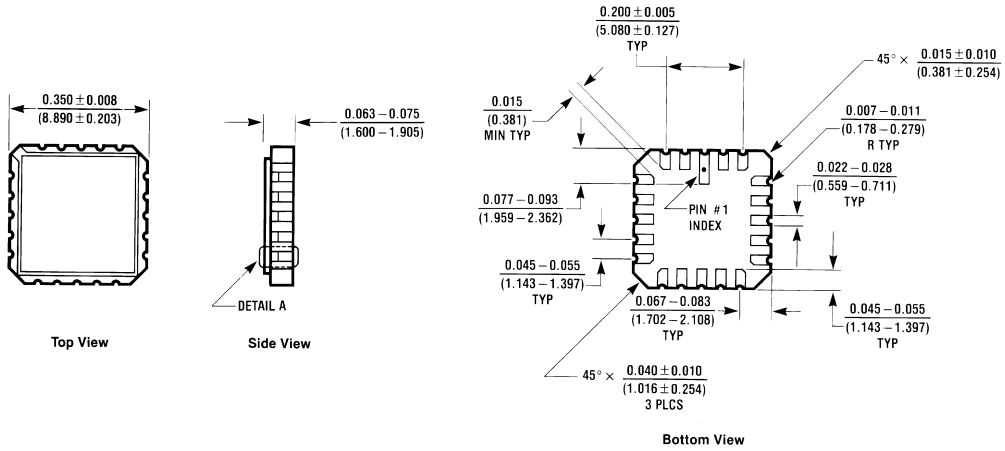


**Differential Transition Time vs Ambient Temperature**



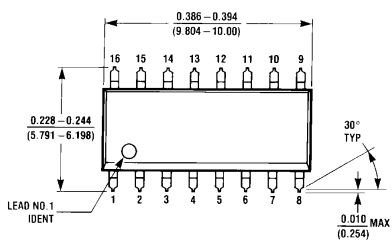


**Physical Dimensions** inches (millimeters) unless otherwise noted



**20-Lead Ceramic Leadless Chip Carrier, Type C**  
**Order Number DS90C031E-QML**  
**NS Package Number E20A**

E20A (REV D)



**16-Lead (0.150" Wide) Molded Small Outline Package, JEDEC**  
**Order Number DS90C031TM**  
**NS Package Number M16A**

M16A (REV H)

**LIFE SUPPORT POLICY**

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1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
2. A critical component in any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



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