

# MC10198

## Monostable Multivibrator

The MC10198 is a retriggerable monostable multivibrator. Two enable inputs permit triggering on any combination of positive or negative edges as shown in the accompanying table. The trigger input is buffered by Schmitt triggers making it insensitive to input rise and fall times.

The pulse width is controlled by an external capacitor and resistor. The resistor sets a current which is the linear discharge rate of the capacitor. Also, the pulse width can be controlled by an external current source or voltage (see applications information).

For high-speed response with minimum delay, a hi-speed input is also provided. This input bypasses the internal Schmitt triggers and the output responds within 2 nanoseconds typically.

Output logic and threshold levels are standard MECL 10,000. Test conditions are per Table 2. Each "Precondition" referred to in Table 2 is per the sequence of Table 1.

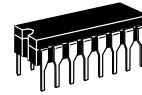
- $P_D = 415 \text{ mW typ/pkg (No Load)}$
- $t_{pd} = 4.0 \text{ ns typ Trigger Input to Q}$
- $2.0 \text{ ns typ Hi-Speed Input to Q}$
- Min Timing Pulse Width  $PW_{Qmin}$   $10 \text{ ns typ}^1$
- Max Timing Pulse Width  $PW_{Qmax}$   $>10 \text{ ms typ}^2$
- Min Trigger Pulse Width  $PW_T$   $2.0 \text{ ns typ}$
- Min Hi-Speed Trigger Pulse Width  $PW_{HS}$   $3.0 \text{ ns typ}$
- Enable Setup Time  $t_{set}$   $1.0 \text{ ns typ}$
- Enable Hold Time  $t_{hold}$   $1.0 \text{ ns typ}$
- $^1 C_{Ext} = 0 \text{ (Pin 4 open), } R_{Ext} = 0 \text{ (Pin 6 to } V_{EE})$
- $^2 C_{Ext} = 10 \text{ mF, } R_{Ext} = 2.7 \text{ kW}$



ON Semiconductor

<http://onsemi.com>

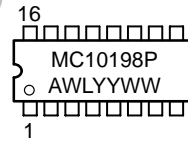
### MARKING DIAGRAMS



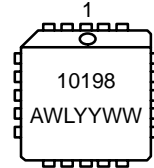
CDIP-16  
L SUFFIX  
CASE 620



PDIP-16  
P SUFFIX  
CASE 648



PLCC-20  
FN SUFFIX  
CASE 775



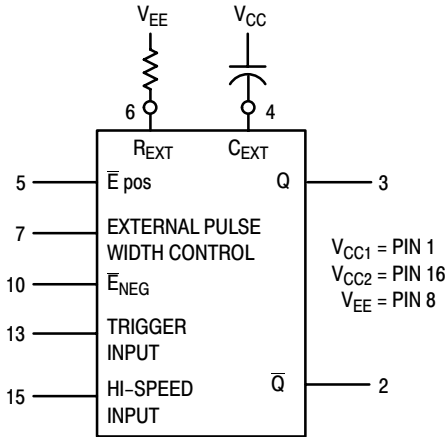
A = Assembly Location  
WL = Wafer Lot  
YY = Year  
WW = Work Week

### ORDERING INFORMATION

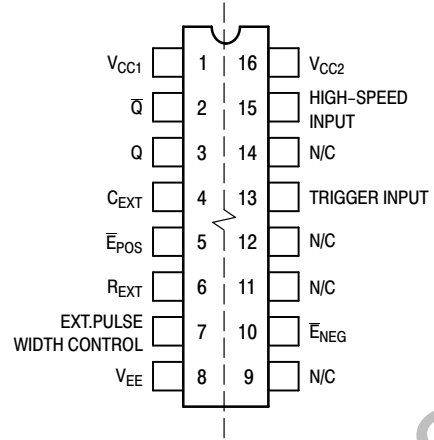
Device	Package	Shipping
MC10198L	CDIP-16	25 Units / Rail
MC10198P	PDIP-16	25 Units / Rail
MC10198FN	PLCC-20	46 Units / Rail

# MC10198

## LOGIC DIAGRAM



## DIP PIN ASSIGNMENT

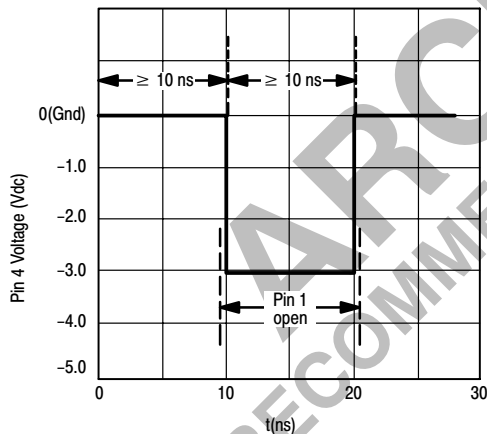


Pin assignment is for Dual-in-Line Package. For PLCC pin assignment, see the Pin Conversion Tables on page 18 of the ON Semiconductor MECL Data Book (DL122/D).

## TRUTH TABLE

INPUT		OUTPUT
$\bar{E}_{Pos}$	$\bar{E}_{Neg}$	
L	L	Triggers on both positive & negative input slopes
L	H	Triggers on positive input slope
H	L	Triggers on negative input slope
H	H	Trigger is disabled

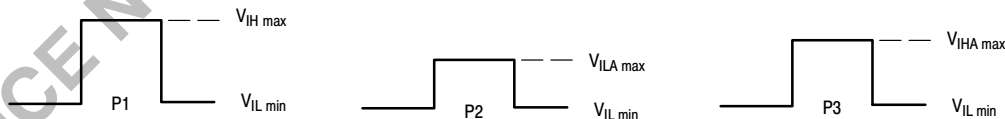
TABLE 1 — PRECONDITION SEQUENCE



- At  $t = 0$ 
  - Apply  $V_{IHmax}$  to Pin 5 and 10.
  - Apply  $V_{ILmin}$  to Pin 15.
  - Ground Pin 4.
- At  $t \geq 10$  ns
  - Open Pin 1.
  - Apply  $-3.0$  Vdc to Pin 4. Hold these conditions for  $\geq 10$  ns.
- Return Pin 4 to Ground and perform test as indicated in Table 2.

TABLE 2 — CONDITIONS FOR TESTING OUTPUT LEVELS

(See Table 1 for Precondition Sequence)



Pins 1, 16 =  $V_{CC}$  = Ground  
 Pins 6, 8 =  $V_{EE}$  =  $-5.2$  Vdc  
 Outputs loaded  $50 \Omega$  to  $-2.0$  Vdc

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Test	P.U.T.	Pin Conditions			
		5	10	13	15
Precondition					
V <sub>OH</sub>	2			V <sub>IL min</sub>	
V <sub>OH</sub>	3			P1	
Precondition					
V <sub>OL</sub>	3			V <sub>IL min</sub>	
V <sub>OL</sub>	2			P1	
Precondition					
V <sub>OHA</sub>	2				V <sub>ILA max</sub>
V <sub>OHA</sub>	3				V <sub>IHA min</sub>
Precondition					
V <sub>OHA</sub>	2			V <sub>IL min</sub>	
V <sub>OHA</sub>	3			P3	
Precondition					
V <sub>OHA</sub>	2			P2	
V <sub>OHA</sub>	3			P3	
Precondition					
V <sub>OHA</sub>	2		V <sub>IH max</sub>	P2	
V <sub>OHA</sub>	3		V <sub>IH max</sub>	P3	
Precondition					
V <sub>OHA</sub>	2		V <sub>IH max</sub>	P1	
V <sub>OHA</sub>	3		V <sub>IH max</sub>	P1	

Test	P.U.T.	Pin Conditions			
		5	10	13	15
Precondition					
V <sub>OHA</sub>	2		V <sub>IHA min</sub>	P1	
V <sub>OHA</sub>	3		V <sub>ILA max</sub>	P1	
Precondition					
V <sub>OLA</sub>	3				V <sub>ILA max</sub>
V <sub>OLA</sub>	2				V <sub>IHA min</sub>
Precondition					
V <sub>OLA</sub>	2			V <sub>IL min</sub>	
V <sub>OLA</sub>	3			V <sub>IL min</sub>	
Precondition					
V <sub>OLA</sub>	3			P2	
V <sub>OLA</sub>	2			P3	
Precondition					
V <sub>OLA</sub>	3		V <sub>IH max</sub>	P2	
V <sub>OLA</sub>	2		V <sub>IH max</sub>	P3	
Precondition					
V <sub>OLA</sub>	3	V <sub>IHA min</sub>	V <sub>IH max</sub>	P1	
V <sub>OLA</sub>	2	V <sub>ILA max</sub>	V <sub>IH max</sub>	P1	
Precondition					
V <sub>OLA</sub>	3	V <sub>IH max</sub>	V <sub>IHA min</sub>	P1	
V <sub>OLA</sub>	2	V <sub>IH max</sub>	V <sub>ILA max</sub>	P1	

ARCHIVED FOR NEW DESIGN

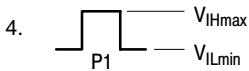
DEVICE NOT RECOMMENDED FOR NEW DESIGN

# MC10198

## ELECTRICAL CHARACTERISTICS

Characteristic	Symbol	Pin Under Test	Test Limits						Unit	
			-30°C		+25°C		+85°C			
			Min	Max	Min	Typ	Max	Min		Max
Power Supply Drain Current	$I_E$	8		110		80	100		110	mAdc
Input Current	$I_{inH}$	5, 10		415			260		260	$\mu$ Adc
		13 15		350 560			220 350		220 350	
	$I_{inL}$	5	0.5		0.5			0.3		$\mu$ Adc
Output Voltage Logic 1	$V_{OH}$	2	-1.060	-0.890	-0.960		-0.810	-0.890	-0.700	Vdc
		3	-1.060	-0.890	-0.960		-0.810	-0.890	-0.700	
Output Voltage Logic 0	$V_{OL}$	2	-1.890	-1.675	-1.850		-1.650	-1.825	-1.615	Vdc
		3	-1.890	-1.675	-1.850		-1.650	-1.825	-1.615	
Threshold Voltage Logic 1	$V_{OHA}$	2	-1.080		-0.980			-0.910		Vdc
		3	-1.080		-0.980			-0.910		
Threshold Voltage Logic 0	$V_{OLA}$	2		-1.655			-1.630		-1.595	Vdc
		3		-1.655			-1.630		-1.595	
Switching Times (50 $\Omega$ Load)										
Trigger Input	$t_{T+Q+}$	3	2.5	6.5	2.5	4.0	5.5	2.5	6.5	ns
		3	2.5	6.5	2.5	4.0	5.5	2.5	6.5	
High Speed Trigger Input	$t_{HS+Q+}$	3	1.5	3.2	1.5	2.0	2.8	1.5	3.2	ns
Minimum Timing Pulse Width	$PW_{Qmin}$	3				10.0				ns
Maximum Timing Pulse Width	$PW_{Qmax}$	3				>10				ms
Min Trigger Pulse Width	$PW_T$	3				2.0				ns
Min Hi-Spd Trig Pulse Width	$PW_{HS}$	3				3.0				ns
Rise Time (20 to 80%)		3	1.5	4.0	1.5		3.5	1.5	4.0	ns
Fall Time (20 to 80%)		3	1.5	4.0	1.5		3.5	1.5	4.0	ns
Enable Setup Time	$t_{setup}(E)$	3				1.0				ns
Enable Hold Time	$t_{hold}(E)$	3				1.0				ns

1. The monostable is in the timing mode at the time of this test.
2.  $C_{EXT} = 0$  (Pin 4 Open);  $R_{EXT} = 0$  (Pin 6 tied to  $V_{EE}$ ).
3.  $C_{EXT} = 10\mu F$  (Pin);  $R_{EXT} = 2.7k$  (Pin 6).

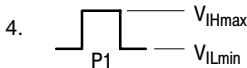


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## ELECTRICAL CHARACTERISTICS (continued)

			TEST VOLTAGE VALUES (Volts)						
			V <sub>IHmax</sub>	V <sub>ILmin</sub>	V <sub>IHAmin</sub>	V <sub>ILAmax</sub>	V <sub>EE</sub>		
@ Test Temperature									
			-30°C	-0.890	-1.890	-1.205	-1.500	-5.2	
			+25°C	-0.810	-1.850	-1.105	-1.475	-5.2	
			+85°C	-0.700	-1.825	-1.035	-1.440	-5.2	
Characteristic	Symbol	Pin Under Test	TEST VOLTAGE APPLIED TO PINS LISTED BELOW					(V <sub>CC</sub> ) Gnd	
			V <sub>IHmax</sub>	V <sub>ILmin</sub>	V <sub>IHAmin</sub>	V <sub>ILAmax</sub>	V <sub>EE</sub>		
Power Supply Drain Current	I <sub>E</sub>	8					6, 8	1, 4, 16	
Input Current	I <sub>inH</sub>	5, 10	5,10				6, 8	1, 4, 16	
		13	13				6, 8	1, 4, 16	
15		15				6, 8	1, 4, 16		
Output Voltage	Logic 1	V <sub>OH</sub>	2		13			6, 8	1, 4, 16
			3	13 (4.)			6, 8	1, 4, 16	
Output Voltage	Logic 0	V <sub>OL</sub>	2					6, 8	1, 4, 16
			3	13 (4.)	13		6, 8	1, 4, 16	
Threshold Voltage	Logic 1	V <sub>OHA</sub>	2				15	6, 8	1, 16, 4
			3			15	6, 8	1, 16, 4	
Threshold Voltage	Logic 0	V <sub>OLA</sub>	2				15	6, 8	1, 16, 4
			3			15	6, 8	1, 16, 4	
Switching Times (50Ω Load)			+1.11V		Pulse In	Pulse Out	-3.2 V	+2.0 V	
Trigger Input	t <sub>T+Q+</sub>	3	10		13	3	6, 8	1, 16, 4	
		3	5		13	3	6, 8	1, 16, 4	
High Speed Trigger Input	t <sub>HS+Q+</sub>	3			15	3	6, 8	1, 16, 4	
Minimum Timing Pulse Width	PW <sub>Qmin</sub>	3				Note 2.	6, 8	1, 16, 4	
Maximum Timing Pulse Width	PW <sub>Qmax</sub>	3				Note 3.	6, 8	1, 16, 4	
Minimum Trigger Pulse Width	PW <sub>T</sub>	3			13	3	6, 8	1, 16, 4	
Minimum Hi-Spd Trigger Pulse Width	PW <sub>HS</sub>	3			15	3	6, 8	1, 16, 4	
Rise Time (20 to 80%)		3					6, 8	1, 16, 4	
Fall Time (20 to 80%)		3					6, 8	1, 16, 4	
Enable Setup Time	t <sub>setup</sub> (E)	3			5	3	6, 8	1, 16, 4	
Enable Hold Time	t <sub>hold</sub> (E)	3			5	3	6, 8	1, 16, 4	

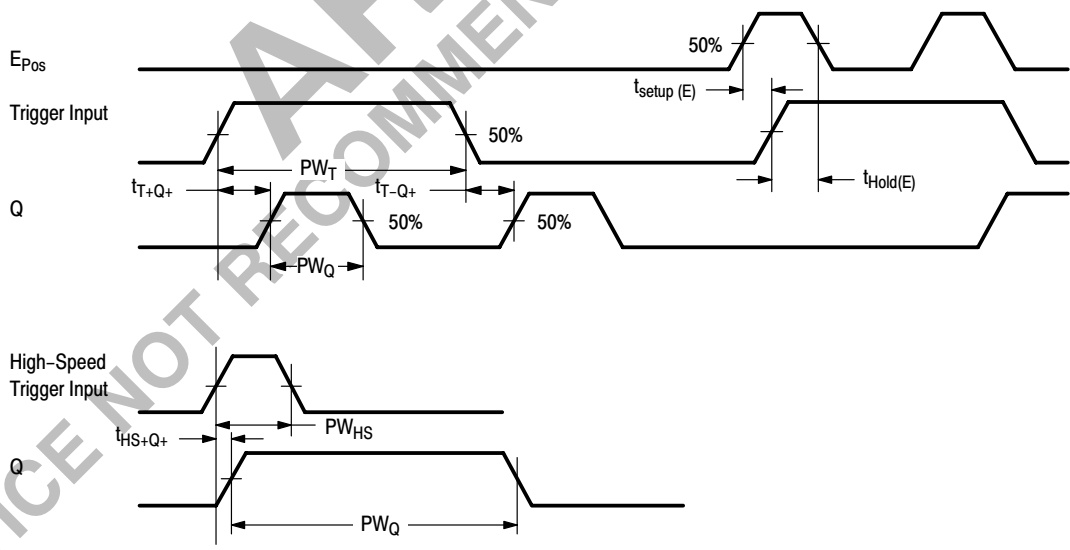
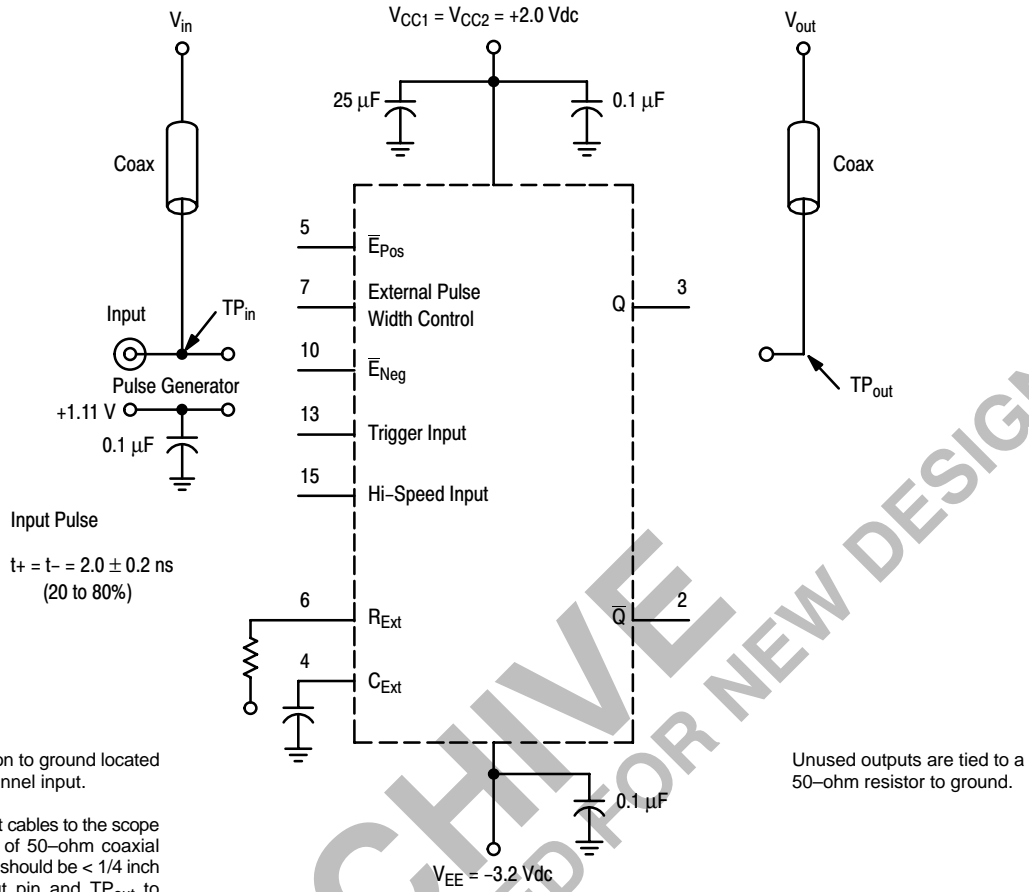
- The monostable is in the timing mode at the time of this test.
- C<sub>EXT</sub> = 0 (Pin 4 Open); R<sub>EXT</sub> = 0 (Pin 6 tied to V<sub>EE</sub>).
- C<sub>EXT</sub> = 10μF (Pin); R<sub>EXT</sub> = 2.7k (Pin 6).



Each MECL 10,000 series circuit has been designed to meet the dc specifications shown in the test table, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow greater than 500 linear fpm is maintained. Outputs are terminated through a 50-ohm resistor to -2.0 volts. Test procedures are shown for only one gate. The other gates are tested in the same manner.

# MC10198

## SWITCHING TIME TEST CIRCUIT AND WAVEFORMS @ 25°C



APPLICATIONS INFORMATION

**Circuit Operation:**

1. PULSE WIDTH TIMING — The pulse width is determined by the external resistor and capacitor. The MC10198 also has an internal resistor (nominally 284 ohms) that can be used in series with  $R_{Ext}$ . Pin 7, the external pulse width control, is a constant voltage node (-3.60 V nominally). A resistance connected in series from this node to  $V_{EE}$  sets a constant timing current  $I_T$ . This current determines the discharge rate of the capacitor:

where

$$\Delta T = \text{pulse width}$$

$$\Delta V = 1.9 \text{ V change in capacitor voltage}$$

$$\text{Then: } I_T = C_{Ext} \frac{\Delta V}{\Delta T}$$

If  $R_{Ext} + R_{Int}$  are in series to  $V_{EE}$ :

$$I_T = [(-3.60 \text{ V}) - (-5.2 \text{ V})] \div [R_{Ext} + 284 \Omega]$$

$$I_T = 1.6 \text{ V} / (R_{Ext} + 284)$$

$$\text{The timing equation becomes: } \Delta T = C_{Ext} \frac{1.9 \text{ V}}{I_T}$$

$$\Delta T = [(C_{Ext})(1.9 \text{ V})] \div [1.6 \text{ V} / (R_{Ext} + 284)]$$

$$\Delta T = C_{Ext} (R_{Ext} + 284) 1.19$$

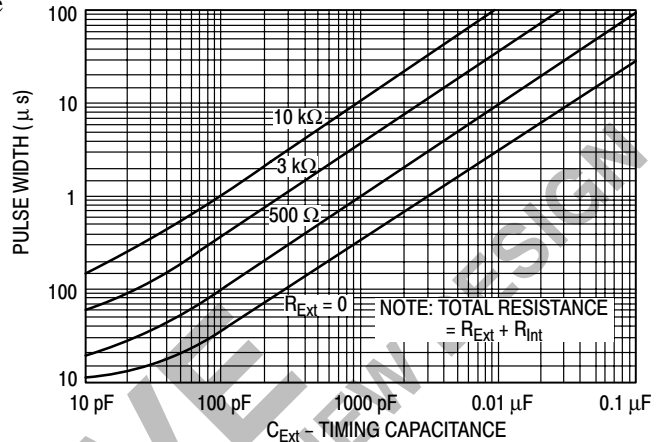
where  $\Delta T = \text{Sec}$

$$R_{Ext} = \text{Ohms}$$

$$C_{Ext} = \text{Farads}$$

Figure 2 shows typical curves for pulse width versus  $C_{Ext}$  and  $R_{Ext}$  (total resistance includes  $R_{Int}$ ). Any low leakage capacitor can be used and  $R_{Ext}$  can vary from 0 to 16 k-ohms.

FIGURE 2 – TIMING PULSE WIDTH versus  $C_{Ext}$  and  $R_{Ext}$



2. TRIGGERING — The  $\bar{E}_{Pos}$  and  $\bar{E}_{Neg}$  inputs control the trigger input. The MC10198 can be programmed to trigger on the positive edge, negative edge, or both. Also, the trigger input can be totally disabled. The truth table is shown on the first page of the data sheet.

The device is totally retriggerable. However, as duty cycle approaches 100%, pulse width jitter can occur due to the recovery time of the circuit. Recovery time is basically dependent on capacitance  $C_{Ext}$ . Figure 3 shows typical recovery time versus capacitance at  $I_T = 5 \text{ mA}$ .

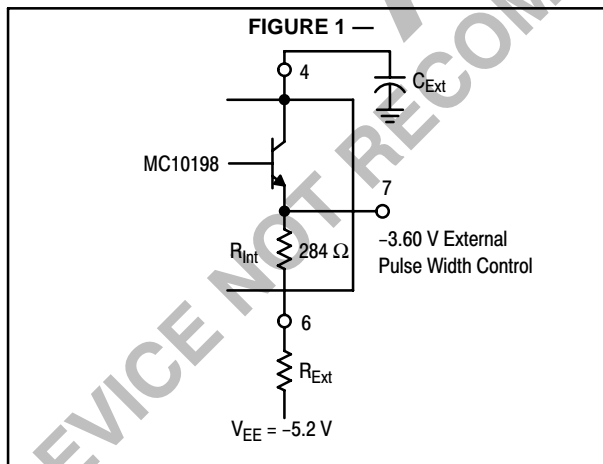
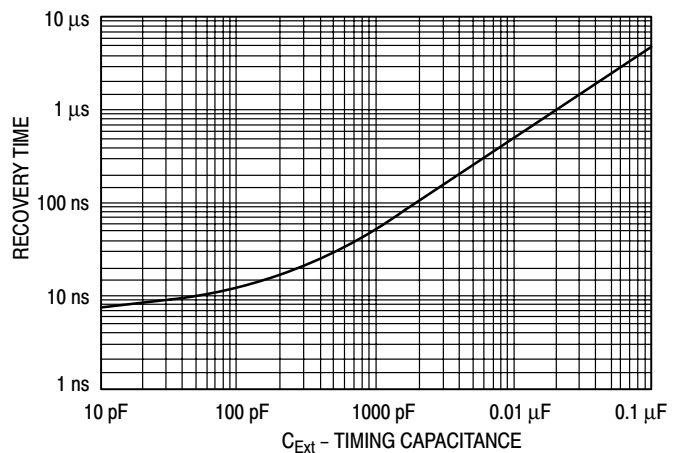


FIGURE 3 — RECOVERY TIME versus  $C_{Ext}$  @  $I_T = 5 \text{ mA}$



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3. **HI-SPEED INPUT** — This input is used for stretching very narrow pulses with minimum delay between the output pulse and the trigger pulse. The trigger input should be disabled when using the high-speed input. The MC10198 triggers on the rising edge, using this input, and input pulse width should narrow, typically less than 10 nanoseconds.

## USAGE RULES:

1. Capacitor lead lengths should be kept very short to minimize ringing due to fast recovery rise times.
2. The  $\bar{E}$  inputs should not be tied to ground to establish a high logic level. A resistor divider or diode can be used to establish a  $-0.7$  to  $-0.9$  voltage level.
3. For optimum temperature stability;  $0.5$  mA is the best timing current  $I_T$ . The device is designed to have a constant voltage at the EXTERNAL PULSE WIDTH CONTROL over temperature at this current value.
4. Pulse Width modulation can be attained with the EXTERNAL PULSE WIDTH CONTROL. The timing current can be altered to vary the pulse width. Two schemes are:
  - a. The internal resistor is not used. A dependent current source is used to set the timing current as shown in Figure 4. A graph of pulse width versus timing current ( $C_{Ext} = 13$  pF) is shown in Figure 5.
  - b. A control voltage can also be used to vary the pulse width using an additional resistor (Figure 6). The current ( $I_T + I_C$ ) is set by the voltage drop across  $R_{Int} + R_{Ext}$ . The control current  $I_C$  modifies  $I_T$  and alters the pulse width. Current  $I_C$  should never force  $I_T$  to zero.  $R_C$  typically  $1$  k $\Omega$ .

FIGURE 4 —

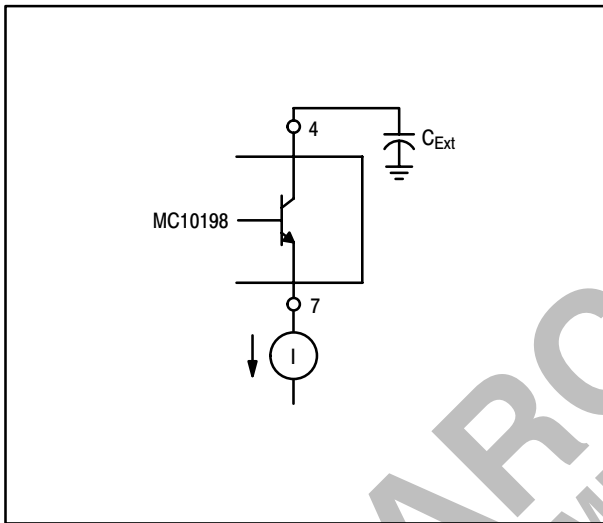


FIGURE 5 — PULSE WIDTH versus  $I_T$  @  $C_{Ext} = 13$  pF

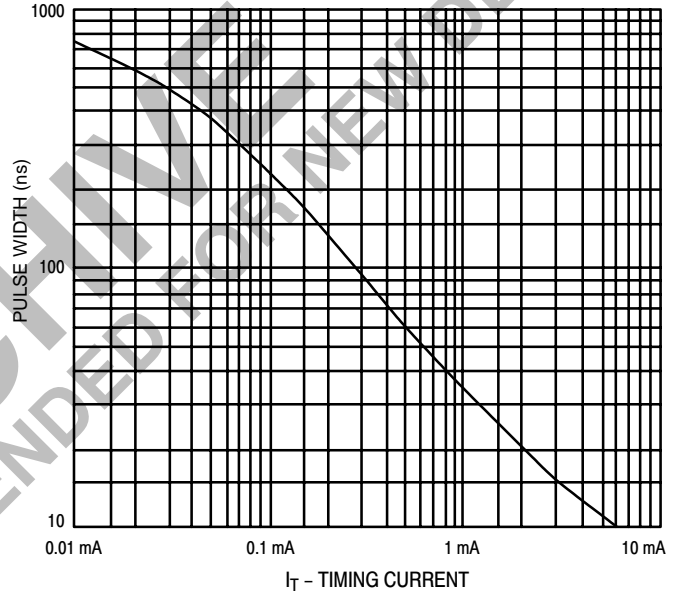
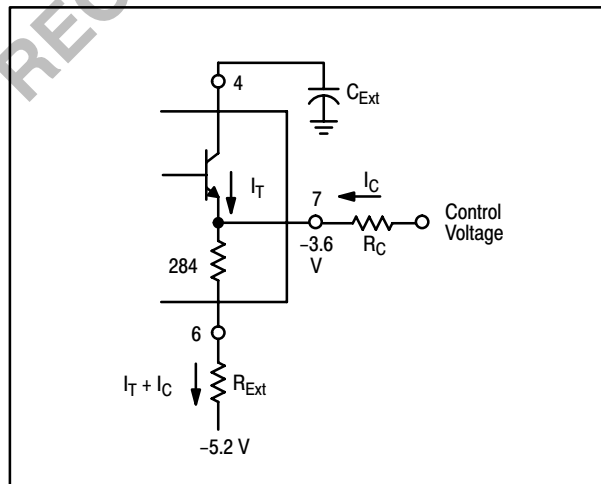


FIGURE 6 —

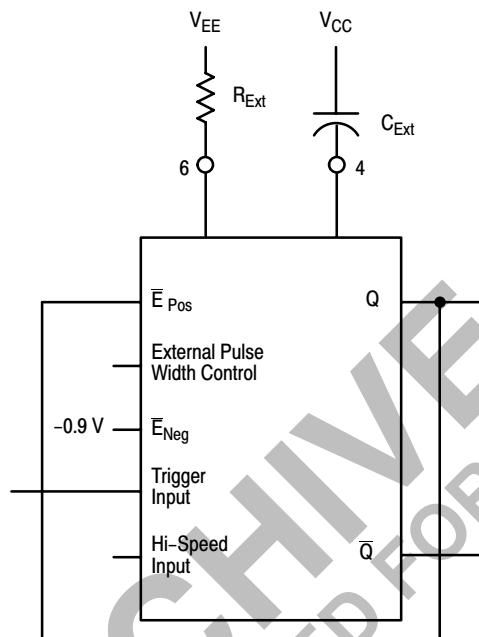




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5. The MC10198 can be made non-retriggerable. The Q output is fed back to disable the trigger input during the triggered state (Logic Diagram). Figure 7 shows a positive triggered configuration; a similar configuration can be made for negative triggering.

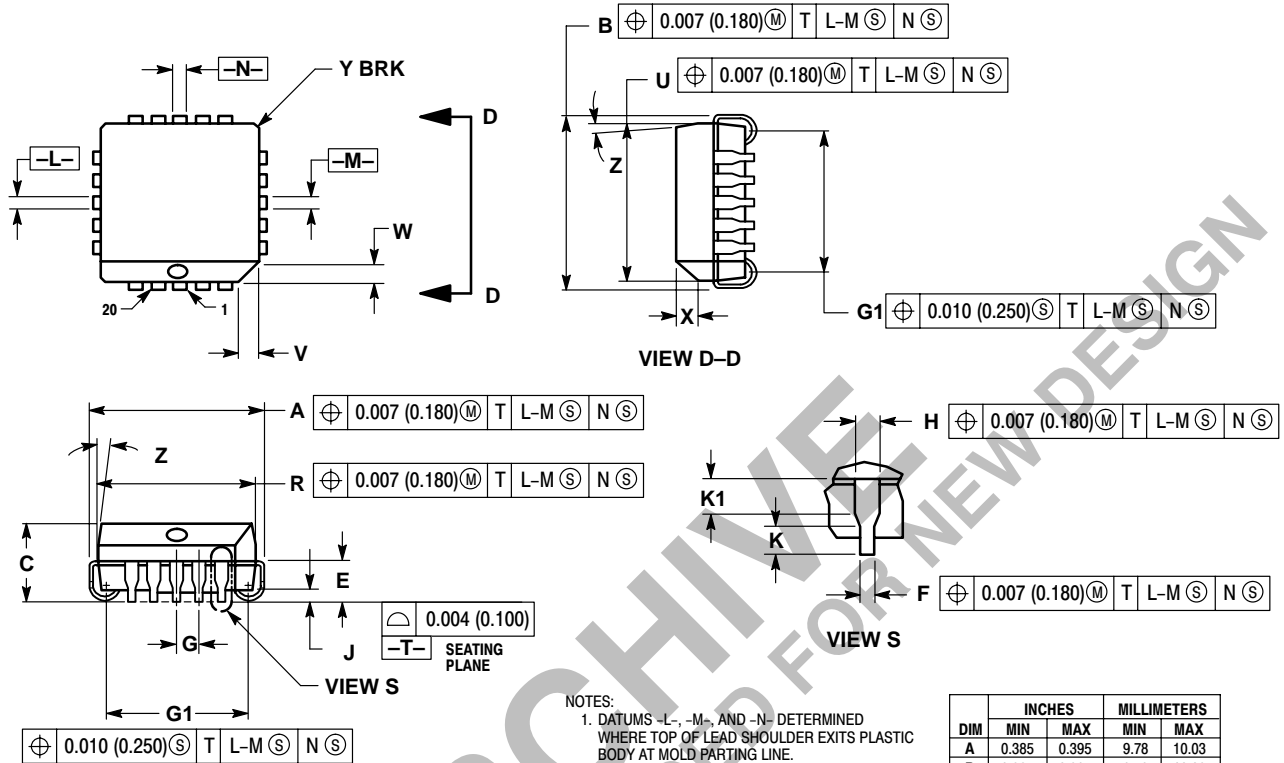
FIGURE 7 —



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## PACKAGE DIMENSIONS

PLCC-20  
FN SUFFIX  
PLASTIC PLCC PACKAGE  
CASE 775-02  
ISSUE C



### NOTES:

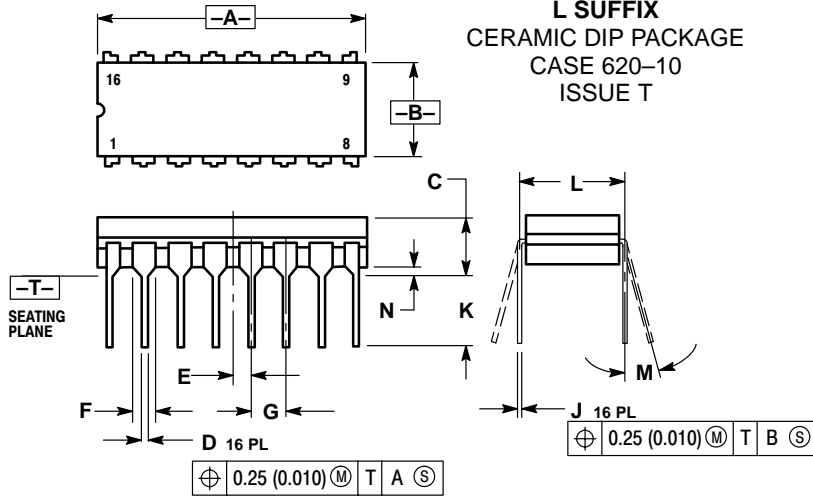
- DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD PARTING LINE.
- DIMENSION G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, SEATING PLANE.
- DIMENSIONS R AND U DO NOT INCLUDE MOLD FLASH. ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE.
- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: INCH.
- THE PACKAGE TOP MAY BE SMALLER THAN THE PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS R AND U ARE DETERMINED AT THE OUTERMOST EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.037 (0.940). THE DAMBAR INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.385	0.395	9.78	10.03
B	0.385	0.395	9.78	10.03
C	0.165	0.180	4.20	4.57
E	0.090	0.110	2.29	2.79
F	0.013	0.019	0.33	0.48
G	0.050 BSC		1.27 BSC	
H	0.026	0.032	0.66	0.81
J	0.020	---	0.51	---
K	0.025	---	0.64	---
R	0.350	0.356	8.89	9.04
U	0.350	0.356	8.89	9.04
V	0.042	0.048	1.07	1.21
W	0.042	0.048	1.07	1.21
X	0.042	0.056	1.07	1.42
Y	---	0.020	---	0.50
Z	2°	10°	2°	10°
G1	0.310	0.330	7.88	8.38
K1	0.040	---	1.02	---

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## PACKAGE DIMENSIONS

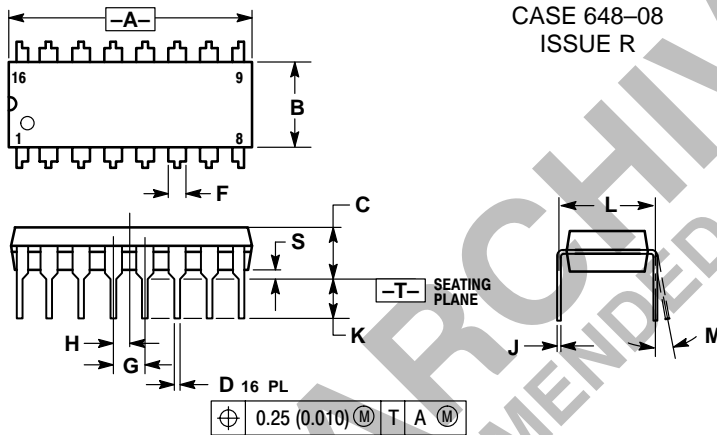
### CDIP-16 L SUFFIX CERAMIC DIP PACKAGE CASE 620-10 ISSUE T



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
  4. DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC BODY.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.750	0.785	19.05	19.93
B	0.240	0.295	6.10	7.49
C	---	0.200	---	5.08
D	0.015	0.020	0.39	0.50
E	0.050 BSC		1.27 BSC	
F	0.055	0.065	1.40	1.65
G	0.100 BSC		2.54 BSC	
H	0.008	0.015	0.21	0.38
K	0.125	0.170	3.18	4.31
L	0.300 BSC		7.62 BSC	
M	0°	15°	0°	15°
N	0.020	0.040	0.51	1.01


### PDIP-16 P SUFFIX PLASTIC DIP PACKAGE CASE 648-08 ISSUE R



- NOTES:
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
  4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
  5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01

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