# Dual Monostable Multivibrators with Schmitt-Trigger Inputs

Each multivibrator of the LS221 features a negative-transition-triggered input and a positive-transition-triggered input either of which can be used as an inhibit input.

Pulse triggering occurs at a voltage level and is not related to the transition time of the input pulse. Schmitt-trigger input circuitry for B input allows jitter-free triggering for inputs as slow as 1 volt/second, providing the circuit with excellent noise immunity. A high immunity to  $V_{CC}$  noise is also provided by internal latching circuitry.

Once triggered, the outputs are independent of further transitions of the inputs and are a function of the timing components. The output pulses can be terminated by the overriding clear. Input pulse width may be of any duration relative to the output pulse width. Output pulse width may be varied from 35 nanoseconds to a maximum of 70 s by choosing appropriate timing components. With  $R_{ext} = 2.0 \text{ k}\Omega$  and  $C_{ext} = 0$ , a typical output pulse of 30 nanoseconds is achieved. Output rise and fall times are independent of pulse length.

Pulse width stability is achieved through internal compensation and is virtually independent of  $V_{CC}$  and temperature. In most applications, pulse stability will only be limited by the accuracy of external timing components.

Jitter-free operation is maintained over the full temperature and  $V_{CC}$  ranges for greater than six decades of timing capacitance (10 pF to 10  $\mu F$ ), and greater than one decade of timing resistance (2.0 to 100  $k\Omega$  for the SN74LS221). Pulse width is defined by the relationship:  $t_w(\text{out}) = C_{ext}R_{ext}$  ln 2.0  $\approx$   $\boxed{0}$ .7  $C_{ext}$   $R_{ext}$ ; where  $t_W$  is in ns if  $C_{ext}$  is in pF and  $R_{ext}$  is in  $k\Omega$ . If pulse cutoff is not critical, capacitance up to 1000  $\mu F$  and resistance as low as 1.4  $k\Omega$  may be used. The range of jitter-free pulse widths is extended if  $V_{CC}$  is 5.0 V and 25°C temperature.

- SN74LS221 is a Dual Highly Stable One-Shot
- Overriding Clear Terminates Output Pulse
- Pin Out is Identical to SN74LS123

# **GUARANTEED OPERATING RANGES**

Symbol	Symbol Parameter		Тур	Max	Unit
V <sub>CC</sub>	Supply Voltage	4.75	5.0	5.25	V
T <sub>A</sub>	T <sub>A</sub> Operating Ambient Temperature Range		25	70	°C
I <sub>OH</sub>	I <sub>OH</sub> Output Current – High			-0.4	mA
l <sub>OL</sub>	Output Current – Low			8.0	mA



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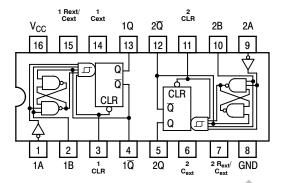


SOIC D SUFFIX CASE 751B

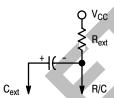
#### **ORDERING INFORMATION**

Device	Package	Shipping		
SN74LS221N	16 Pin DIP	2000 Units/Box		
SN74LS221D	SOIC-16	38 Units/Rail		
SN74LS221DR2	SOIC-16	2500/Tape & Reel		

### (TOP VIEW)



Positive logic: Low input to clear resets Q low and  $\overline{\mathbb{Q}}$  high regardless of dc levels at A or B inputs.



# FUNCTION TABLE (EACH MONOSTABLE)

	INP	UTS	OUTP	UTS	
	CLEAR	Α	В	ø	Q
	L	Χ	X	10	HO
1	X	Н	X	L	Н
	X	X	L	Ľ	H
	Н	L	1		7_
	Н	$\downarrow$	Н	Ŋ	
	*1	$\Box$	Н	L	디

\*See operational notes — Pulse Trigger Modes

TYPICAL MAXIMUM
TYPE POWER OUTPUT PULSE
DISSIPATION LENGTH
\$N74LS221 23 mW 70 s

#### **OPERATIONAL NOTES**

Once in the pulse trigger mode, the output pulse width is determined by  $t_W = R_{ext}C_{ext}In2$ , as long as  $R_{ext}$  and  $C_{ext}$  are within their minimum and maximum valves and the duty cycle is less than 50%. This pulse width is essentially independent of V<sub>CC</sub> and temperature variations. Output pulse widths varies typically no more than ±0.5% from device to device.

If the duty cycle, defined as being  $100 \cdot \frac{^tW}{T}$  where T is the period of the input pulse, rises above 50%, the output pulse width will become shorter. If the duty cycle varies between low and high valves, this causes the output pulse width to vary in length, or jitter. To reduce jitter to a minimum, Rext should be as large as possible. (Jitter is independent of C<sub>ext</sub>). With  $R_{ext} = 100K$ , jitter is not appreciable until the duty cycle approaches 90%.

Although the LS221 is pin-for-pin compatible with the LS123, it should be remembered that they are not functionally identical. The LS123 is retriggerable so that the output is dependent upon the input transitions once it is high. This is not the case for the LS221. Also note that it is recommended to externally ground the LS123 Cext pin. However, this cannot be done on the LS221

The SN74LS221 is a dual, monolithic, non-retriggerable, high-stability one shot. The output pulse width, tw can be varied over 9 decades of timing by proper selection of the external timing components, Rext and Cext.

Pulse triggering occurs at a voltage level and is, therefore, independent of the input slew rate. Although all three inputs have this Schmitt-trigger effect, only the B input should be used for very long transition triggers (≥1.0 µV/s). High immunity to V<sub>CC</sub> noise (typically 1.5 V) is achieved by internal latching circuitry. However, standard bypassing is strongly recommended.

The LS221 has four basic modes of operation.

Clear Mode: If the clear input is held low, irregardless of

the previous output state and other input

states, the Q output is low.

Inhib-If either the A input is high or the B input is it Mode:

low, once the Q output goes low, it cannot

be retriggered by other inputs.

Pulse Trigger Mode:

A transition of the A or B inputs as indicated in the functional truth table will trigger the Q output to go high for a duration determined by the  $t_W$  equation described above;  $\overline{Q}$  will go low for a corresponding length of time.

The Clear input may also be used to trigger an output pulse, but special logic preconditioning on the A or B inputs must be done as follows:

Following any output triggering action using the A or B inputs, the A input must be set high OR the B input must be set low to allow Clear to be used as a trigger. Inputs should then be set up per the truth table (without triggering the output) to allow Clear to be used a trigger for the output pulse.

If the Clear pin is routinely being used to trigger the output pulse, the A or B inputs must be toggled as described above before and between each Clear trigger event.

Once triggered, as long as the output remains high, all input transitions (except overriding Clear) are ignored.

Overriding

Clear Mode: If the Q output is high, it may be forced low

by bringing the clear input low.

### DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

			Limits			
Symbol	Parameter	Min	Тур	Max	Unit	Test Conditions
V <sub>T+</sub>	Positive-Going Threshold Voltage at C Input		1.0	2.0	V	V <sub>CC</sub> = MIN
V <sub>T-</sub>	Negative-Going Threshold Voltage at C Input	0.7	0.8		V	V <sub>CC</sub> = MIN
$V_{T+}$	Positive-Going Threshold Voltage at B Input		1.0	2.0	٧	V <sub>CC</sub> = MIN
$V_{T-}$	Negative-Going Threshold Voltage at B Input	0.8	0.9		V	V <sub>CC</sub> = MIN
V <sub>IH</sub>	Input HIGH Voltage	2.0			٧	Guaranteed Input HIGH Voltage for A Input
V <sub>IL</sub>	Input LOW Voltage			0.8	٧	Guaranteed Input LOW Voltage for A Input
V <sub>IK</sub>	Input Clamp Voltage			-1.5	V	V <sub>CC</sub> = MIN, I <sub>IN</sub> = -18 mA
V <sub>OH</sub>	Output HIGH Voltage	2.7	3.4		V	V <sub>CC</sub> = MIN, I <sub>OH</sub> = MAX
V <sub>OL</sub>	Output LOW Voltage		0.35	0.5	V	I <sub>OL</sub> = 8.0 mA V <sub>CC</sub> = MIN
	Input HIGH Current			20	μΑ	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 2.7 V
I <sub>IH</sub>				0.1	mA	V <sub>CC</sub> = MAX, V <sub>IN</sub> = 7.0 V
I <sub>IL</sub>	Input LOW Current Input A Input B Clear			-0.4 -0.8 -0.8	mA	$V_{CC} = MAX$ , $V_{IN} = 0.4 V$
los	Short Circuit Current (Note 1)	-20		-100	mA	V <sub>CC</sub> = MAX
I <sub>CC</sub>	Power Supply Current Quiescent		4.7	11	mA	V <sub>CC</sub> = MAX
	Triggered bre than one output should be shorted		19	27	·O.	
	Power Supply Current Quiescent Triggered ore than one output should be shorted	SOL	MA			

# AC CHARACTERISTICS ( $V_{CC} = 5.0 \text{ V}, T_A = 25^{\circ}\text{C}$ )

	From	То	Limits		Limits				
Symbol	(Input)	(Output)	Min	Тур	Max	Unit	Test Conditions		
	Α	Q		45	70				
t <sub>PLH</sub>	В	Q		35	55	ns			
	Α	Q		50	80			0 00 = 5 0 000	
t <sub>PHL</sub>	В	Q		40	65	ns		$C_{\text{ext}}$ = 80 pF, $R_{\text{ext}}$ = 2.0 $\Omega$	
t <sub>PHL</sub>	Clear	Q		35	55	ns	C <sub>L</sub> = 15 pF,		
t <sub>PLH</sub>	Clear	Q		44	65	ns	See Figure 1		
			70	120	150			$C_{\text{ext}}$ = 80 pF, $R_{\text{ext}}$ = 2.0 $\Omega$	
	A or B	A or B Q or Q	20	47	70	ns	ns		$C_{ext} = 0$ , $R_{ext} = 2.0 \text{ k}\Omega$
t <sub>W(out)</sub>			600	670	750			$C_{ext}$ = 100 pF, $R_{ext}$ = 10 k $\Omega$	
			6.0	6.9	7.5	ms		$C_{ext}$ = 1.0 μF, $R_{ext}$ = 10 kΩ	

# AC SETUP REQUIREMENTS ( $V_{CC} = 5.0 \text{ V}, T_A = 25^{\circ}\text{C}$ )

				Limits		
Symbol	Parameter		Min	Тур	Max	Unit
	Rate of Rise or Fall of Input Pulse		. (			
dv/dt		Schmitt, B	1.0	0		V/s
		Logic Input, A	1.0	, ,		V/μs
	Input Pulse Width	C		100		
$t_W$		A or B, t <sub>W(in)</sub>	40	Or.		ns
		Clear, t <sub>W</sub> (clear)	40	),		
t <sub>s</sub>	Clear-Inactive-State Setup Time	50	15			ns
R <sub>ext</sub>	External Timing Resistance		1.4		100	kΩ
C <sub>ext</sub>	External Timing Capacitance	40,714,0	0		1000	μF
	Output Duty Cycle	10 K				
		$RT = 2.0 \text{ k}\Omega$			50	%
	.6	$R_T = MAX R_{ext}$			90	
	PIERSE PERRE	SENIK				

#### **AC WAVEFORMS**

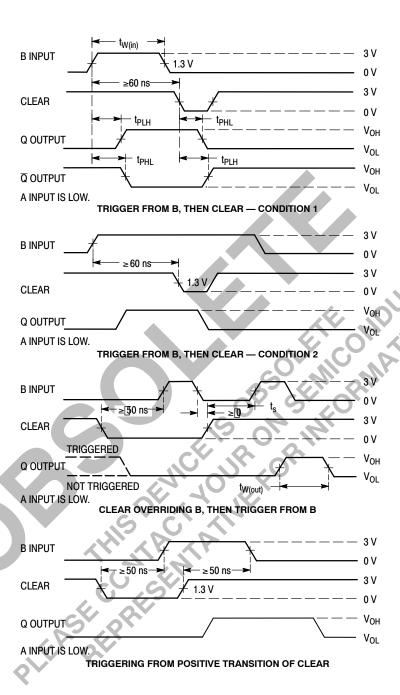
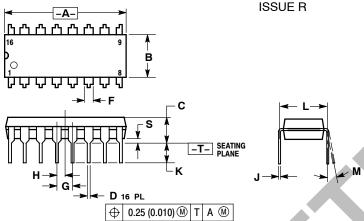


Figure 1.

#### PACKAGE DIMENSIONS

#### **N SUFFIX**

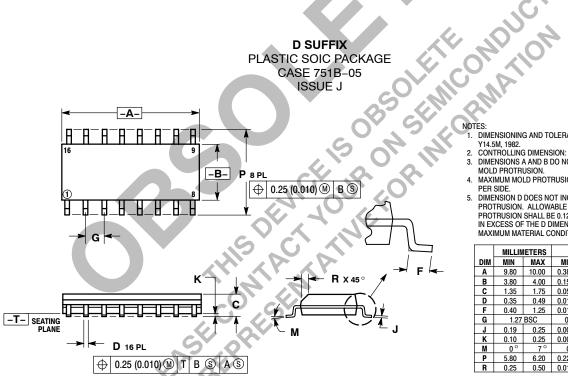
PLASTIC PACKAGE CASE 648-08



- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982. CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
- DIMENSION B DOES NOT INCLUDE MOLD FLASH.
- ROUNDED CORNERS OPTIONAL

	INC	HES	MILLIMETERS		
DIM	MIN	MAX	MIN	MAX	
Α	0.740	0.770	18.80	19.55	
В	0.250	0.270	6.35	6.85	
C	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100	BSC	2.54 BSC		
H	0.050	BSC	1.27 BSC		
7	0.008	0.015	0.21	0.38	
K	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
M	0°	10°	0 %	10°	
S	0.020	0.040	0.51	1.01	

#### **D SUFFIX** PLASTIC SOIC PACKAGE CASE 751B-05 **ISSUE J**



- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M. 1982.
- T14.3M, 1962. CONTROLLING DIMENSION: MILLIMETER. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006)
- DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INCHES		
DIM	MIN	MIN MAX		MAX	
Α	9.80	10.00	0.386	0.393	
В	3.80	4.00	0.150	0.157	
ဂ	1.35	1.75	0.054	0.068	
D	0.35	0.49	0.014	0.019	
F	0.40	1.25	0.016	0.049	
G	1.27	BSC	0.050 BSC		
_	0.19	0.25	0.008	0.009	
K	0.10	0.25	0.004	0.009	
M	0°	7°	0°	7°	
Р	5.80	6.20	0.229	0.244	
R	0.25	0.50	0.010	0.019	

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