## Slim Rectangular Inductive Prox

## Miniature, Slim-styled Type Proximity

- Space-saving prox ideal for timing cam and dog detection
- Four mounting holes provided: two from the side and two from the rear of the housing
- Ganged mounting possible for multiple
 pulse generation
- Alternate frequency models available to avoid mutual interference


## Ordering Information

| Type | Sensing Distance | Part number |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | DC 3-wire switching type |  |  |  | AC switching type |  |
|  |  | NPN-NO | NPN-NC | PNP-NO | PNP-NC | SCR-NO | SCR-NC |
| Shielded | 2 mm (0.08 in) | TL-T2E1 | TL-T2E2 | TL-T2F1 | TL-T2F2 | TL-T2Y1 | TL-T2Y2 |
| Unshielded | 5 mm (0.20 in) | TL-T5ME1 | TL-T5ME2 | TL-T5MF1 | TL-T5MF2 | TL-T5MY1 | TL-T5MY2 |
| $\square$ |  |  |  |  |  |  |  |

Note: 1. To avoid mutual interference, this sensor can be ordered with a different oscillating frequency. Add a " 5 " to the end of the part number (e.g. TL-N2E15).
2. Add suffix " $G$ " to the model number when placing your order for European models with color-coded cables conforming to CENELEC standard (EN50044). Refer to the color code table in the "Output Stage Circuit Diagram" for the cable color codes of the European models.

## Specifications

RATINGS/CHARACTERISTICS

| Part number |  | TL-T2E1, TL-T2E2, TL-T2F1, TL-T2F2 | TL-T2Y1, TL-T2Y2 | TL-T5ME1, TL-T5ME2, TL-T5MF1, TL-T5MF2 | TL-T5MY1, TL-T5MY2 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply voltage (operating voltage range) |  | E and F models: 12 to 24 VDC ( 10 to 30 VDC), ripple (p-p): $20 \%$ max. Y models: 100 to 220 VAC ( 90 to 250 VAC), $50 / 60 \mathrm{~Hz}$ |  |  |  |
| Current consumption |  | E and F models: 15 mA max. at 24 VDC |  |  |  |
| Leakage current |  | Y models: 2.5 mA max. at 200 VAC |  |  |  |
| Sensing object |  | Magnetic metal (The sensing distance decreases with non-magnetic metal.) |  |  |  |
| Sensing distance |  | $2 \mathrm{~mm} \pm 10 \%$ (0.08 $\pm 10 \%$ ) |  | $5 \mathrm{~mm} \pm 10 \%$ (0.19 $\pm 10 \%$ ) |  |
| Sensing distance (standard object) |  | 0 to 1.6 mm (iron, $12 \times 12 \times 1 \mathrm{~mm}$ ) 0 to 0.06 in (iron $0.47,47 \times 0.04$ in) |  | 0 to 4 mm (iron, $15 \times 15 \times 1 \mathrm{~mm}$ ) <br> 0 to 0.157 in (iron $0.59 \times 0.59 \times 0.39 \mathrm{in}$ ) |  |
| Differential travel |  | 10\% max. of sensing distance |  |  |  |
| Response frequency |  | E and F models: <br> Y models: | $\begin{aligned} & 800 \mathrm{~Hz}, \\ & 20 \mathrm{~Hz} \end{aligned}$ | $\begin{array}{ll}\text { E and F models: } & 250 \mathrm{~Hz}, \\ \text { Y models: } & 20 \mathrm{~Hz}\end{array}$ |  |
| Operating status (with sensing object approaching) |  | E1 models: L output signal with load ON <br> E2 models: H output signal with load OFF <br> F1 models: H output signal with load ON <br> Y1 models: Load ON <br> Y2 models: Load OFF |  |  |  |
| Control output | Type | E1: NPN-NO Y1: SCR-NO <br> E2: NPN-NC Y2: SCR-NC <br> F1: PNP-NO <br> F2: PNP-NC |  |  |  |
|  | Switching capacity | $\begin{array}{ll}\text { E and F models: } 100 \mathrm{~mA} \text { max. at } 12 \mathrm{VDC} \text { and } 200 \mathrm{~mA} \text { max. at } 24 \text { VDC } \\ \text { Y models: } & 10 \text { to } 200 \mathrm{~mA}\end{array}$ |  |  |  |
| Circuit protection |  | E and F models: Reverse connection protection and surge absorber <br> Y models: Surge absorber |  |  |  |
| Indicator |  | Operation indicator (red LED) |  |  |  |
| Ambient temperature | Operating | $-25^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}\left(-13^{\circ} \mathrm{F}\right.$ to $\left.158^{\circ} \mathrm{F}\right)$ with no icing |  |  |  |
| Ambient humidity | Operating | 35\% to 95\% |  |  |  |
| Temperature influence |  | $\pm 10 \%$ max. of sensing distance at $23^{\circ} \mathrm{C}\left(73.4^{\circ} \mathrm{F}\right)$ in the temperature range of $-25^{\circ} \mathrm{C}$ to $70^{\circ} \mathrm{C}\left(-13^{\circ} \mathrm{F}\right.$ to $\left.158^{\circ} \mathrm{F}\right)$ |  |  |  |
| Voltage influence |  | $E$ and $F$ models: $\pm 2.5 \%$ max. of sensing distance within a range of $\pm 15 \%$ of the rated power supply voltage <br> Y models: $\pm 2.5 \%$ max. of sensing distance within a range of $\pm 10 \%$ of the rated power supply voltage |  |  |  |
| Residual voltage |  | $\begin{array}{ll}\text { E and F models: } & 1.0 \mathrm{~V} \text { max. with a load current of } 100 \mathrm{~mA} \text { and a cord length of } 2 \mathrm{~m} \\ \text { Y models: } & \text { Refer to Residual Load Voltage (Typical) on page } 4 .\end{array}$ |  |  |  |
| Insulation resistance |  | $50 \mathrm{M} \Omega$ min. (at 500 VDC ) between case and current carry parts |  |  |  |
| Dielectric strength |  | DC switching models: $\quad 1,000 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}$ for 1 min between case and current carry parts AC switching models: $\quad 2,000 \mathrm{VAC}, 50 / 60 \mathrm{~Hz}$ for 1 min between case and current carry parts |  |  |  |
| Vibration resistance |  | 10 to 55 Hz , 1.5-mm (0.06 in)double amplitude for 2 hours each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Shock resistance |  | $500 \mathrm{~m} / \mathrm{s}^{2}\left(1640 \mathrm{ft} / \mathrm{s}^{2}\right)$ approx. 50G for 10 times each in $\mathrm{X}, \mathrm{Y}$, and Z directions |  |  |  |
| Enclosure rating |  | IEC IP67 |  |  |  |
| Weight (with 2-m cord) |  | Approx. $70 \mathrm{~g} \mathrm{(2.47} \mathrm{oz)}$ |  |  |  |
| Material | Case | Heat-resistant ABS resin |  |  |  |
|  | Sensing surface | Heat-resistant ABS resin |  |  |  |

## Operation

## OUTPUT CIRCUITS



Note: 1. 200 mA max. (load current)
2. When a transistor is connected

## Y Models

(AC 2-wire)


## TIMING CHARTS



F Models
PNP (DC 3-wire)


Note: 1. 200 mA max. (load current)
2. When a transistor is connected

## F Models

PNP (DC 3-wire)

Y Models (DC 2-wire)
Target
object $\quad$ Yes

## Engineering Data

## - OPERATING RANGE (TYPICAL)



## LEAKAGE CURRENT

 (TYPICAL)

SENSING OBJECT SIZE AND MATERIAL VS. SENSING DISTANCE (TYPICAL)

TL-T2


TL-T5M


## RESIDUAL LOAD VOLTAGE (TYPICAL)

(at constant 100 VAC)

(at constant 200 VAC)


## Dimensions

Unit: mm (inch)


DC switching model: Three, $0.2-\mathrm{mm}(0.007 \mathrm{in})$ conductors AC switching model: Two, $0.3-\mathrm{mm}$ ( 0.012 in ) conductors Oil- and vibration-resistant, vinyl-insulated round cord, 4 external dia.; standard length: 2 m ( 6.56 ft )

## Precautions

## CONNECTION TO THE LOAD

Be sure to connect the Proximity Sensor to the power source through a load. Direct connection of the Sensor may damage the Sensor.


## MOUNTING

At the time of rear mounting, be sure that the tightening torque does not exceed $6 \mathrm{kgf} \cdot \mathrm{cm}(0.59 \mathrm{~N} \cdot \mathrm{~m}) 5.22 \mathrm{in} \cdot \mathrm{lbf}$.


At the time of side mounting, be sure that the tightening torque does not exceed $8 \mathrm{kgf} \cdot \mathrm{cm}(0.78 \mathrm{~N} \cdot \mathrm{~m}) 2.02 \mathrm{in} \cdot \mathrm{lbf}$.


## EFFECT OF SURROUNDING METALS

If the TL-T5M is embedded in metal, keep at least the following distances between the TL-T and the metal.


If the TL-T2 is embedded in metal, the TL-T2 will not be influenced by metal.

## MUTUAL INTERFERENCE

When two or more TL-T sensors are mounted face-to-face or side-by-side, separate them as shown below. The table below indicates the minimum distances $A$ and $B$.


| Distance | A | B |
| :--- | :--- | :--- |
| TL-T5 $\square \square$ | $120 \mathrm{~mm}(4.72 \mathrm{in})$ | $80 \mathrm{~mm}(3.15 \mathrm{in})$ |
| TL-T5 $\square \square 5$ | $60 \mathrm{~mm}(2.36 \mathrm{in})$ | $40 \mathrm{~mm}(1.57 \mathrm{in})$ |
| TL-T2 $\square \square$ | $40 \mathrm{~mm}(1.57 \mathrm{in})$ | $12 \mathrm{~mm}(0.47 \mathrm{in})$ |
| TL-T2 $\square \square 5$ | $10 \mathrm{~mm}(0.39 \mathrm{in})$ | 0 mm |

Note: Figures in parentheses will apply if the Sensors in use are different from each other in response frequency.

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