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# MOS INTEGRATED CIRCUIT $\mu PD8871$

# 10680 PIXELS $\times\,3$ COLOR CCD LINEAR IMAGE SENSOR

# DESCRIPTION

The  $\mu$ PD8871 is a color CCD (Charge Coupled Device) linear image sensor which changes optical images to electrical signal and has the function of color separation.

The  $\mu$ PD8871 has 3 rows of 10680 pixels, and each row has a single-sided readout type of charge transfer register. And it has reset feed-through level clamp circuits and voltage amplifiers. Therefore, it is suitable for 1200 dpi/A4 color image scanners, color facsimiles and so on.

#### **FEATURES**

- Valid photocell : 10680 pixels × 3
- Photocell pitch : 4  $\mu$ m
- Photocell size  $: 4 \times 4 \mu m^2$
- Line spacing : 32  $\mu$ m (8 lines) Red line Green line, Green line Blue line
- Color filter : Primary colors (red, green and blue), pigment filter (with light resistance 10<sup>7</sup> lx•hour)
- Resolution : 48 dot/mm A4 ( $210 \times 297$  mm) size (shorter side)
  - 1200 dpi US letter (8.5"  $\times$  11") size (shorter side)
- Drive clock level : CMOS output under 5 V operation
- Data rate : 10 MHz Max.
- Power supply : +12 V
- On-chip circuits : Reset feed-through level clamp circuits Voltage amplifiers

# ORDERING INFORMATION

Part Number	Package
μPD8871CY-A	CCD linear image sensor 32-pin plastic DIP (10.16 mm (400))

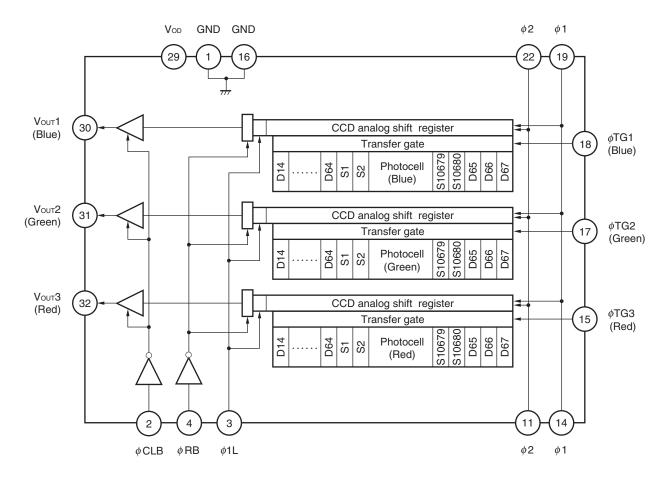
<R> **Remark** The  $\mu$  PD8871CY-A is a lead-free product.

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Document No. S15329EJ3V0DS00 (3rd edition) Date Published February 2006 NS CP (N) Printed in Japan C NEC Electronics Corporation 2001

The revised points can be easily searched by copying an "<R>" in the PDF file and specifying it in the "Find what:" field.

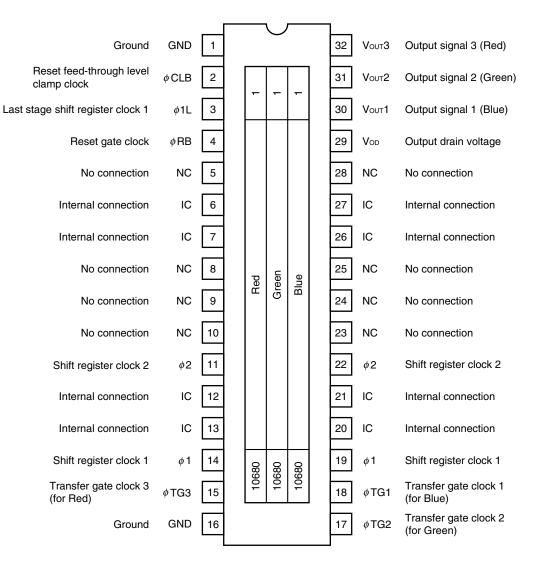
# **BLOCK DIAGRAM**



#### PIN CONFIGURATION (Top View)

#### CCD linear image sensor 32-pin plastic DIP (10.16 mm (400))

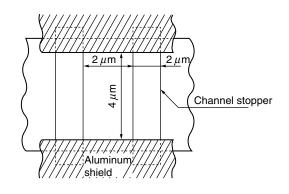
• *µ*PD8871CY-A



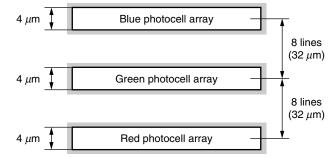
Cautions 1. Leave pins 6, 7, 12, 13, 20, 21, 26, 27 (IC) unconnected.

2. Connect the No connection pins (NC) to GND.

# PHOTOCELL STRUCTURE DIAGRAM



# PHOTOCELL ARRAY STRUCTURE DIAGRAM (Line spacing)



# ABSOLUTE MAXIMUM RATINGS (TA = $+25^{\circ}$ C)

Parameter	Symbol	Ratings	Unit
Output drain voltage	Vod	-0.3 to +15	V
Shift register clock voltage	$V_{\phi 1}, V_{\phi 2}, V_{\phi 1L}$	-0.3 to +8	V
Reset gate clock voltage	Vørb	-0.3 to +8	V
Reset feed-through level clamp	Vøclb	-0.3 to +8	V
clock voltage			
Transfer gate clock voltage	<b>V</b> <i>ø</i> тg1 <b>to V</b> <i>ø</i> тg3	-0.3 to +8	V
Operating ambient temperature Note	TA	0 to +60	°C
Storage temperature	Tstg	-40 to +70	°C

Note Use at the condition without dew condensation.

Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

#### **RECOMMENDED OPERATING CONDITIONS (TA = +25°C)**

Parameter	Symbol	Min.	Тур.	Max.	Unit
Output drain voltage	Vod	11.4	12.0	12.6	V
Shift register clock high level	Vø1H, Vø2H, Vø1LH	4.75	5.0	5.5	V
Shift register clock low level	$V_{\phi 1L}, V_{\phi 2L}, V_{\phi 1LL}$	-0.3	0	+0.25	V
Reset gate clock high level	Vørbh	4.5	5.0	5.5	V
Reset gate clock low level	Vørbl	-0.3	0	+0.5	V
Reset feed-through level clamp clock	Vøclbh	4.5	5.0	5.5	V
high level					
Reset feed-through level clamp clock	Vøclbl	-0.3	0	+0.5	V
low level					
Transfer gate clock high level	Vøтg1н to Vøтg3н	4.75	V∉1H Note	V ∉ 1H Note	V
Transfer gate clock low level	Vøtg1l to Vøtg3l	-0.3	0	+0.15	V
Data rate	førв	-	2.0	10.0	MHz

Note When Transfer gate clock high level ( $V_{\phi TG1H}$  to  $V_{\phi TG3H}$ ) is higher than Shift register clock high level ( $V_{\phi 1H}$ ), Image lag can increase.

# **ELECTRICAL CHARACTERISTICS**

			2 MHz, storage time = 5.5 ms, in $00S$ (infrared cut filter, t = 1 mm)				- = 3 mm)
Parameter	5	Symbol	Test Conditions	Min.	Тур.	Max.	ر، Unit
Saturation voltage		Vsat		2.5	3.2	_	V
Saturation exposure	Red	SER		_	0.889	_	lx•s
	Green	SEG		_	0.970	_	lx•s
	Blue	SEB		-	1.455	-	lx•s
Photo response non-unifo	rmity	PRNU	Vout = 1.0 V	-	6	20	%
Average dark signal		ADS	Light shielding	-	0.2	4.0	mV
Dark signal non-uniformity	,	DSNU	Light shielding	-	1.0	4.0	mV
Power consumption	Power consumption			-	360	540	mW
Output impedance		Zo		-	0.30	1.00	kΩ
Response	Red	R <sub>R</sub>		2.52	3.60	4.68	V/Ix•s
	Green	Rg		2.31	3.30	4.29	V/lx•s
	Blue	RΒ		1.54	2.20	2.86	V/lx•s
Image lag		IL	Vout = 1.0 V	-	1.0	7.0	%
Offset level Note 1		Vos		4.5	6.0	7.5	V
Output fall delay time Note 2		ta	Vout = 1.0 V, (t1') = 5 ns	-	25	-	ns
Total transfer efficiency		TTE	Vout = 1.0 V, data rate = 10 MHz	92	98	-	%
Response peak	Red			-	630	-	nm
	Green			-	540	-	nm
	Blue			_	460	-	nm
Dynamic range		DR1	Vsat/DSNU	_	3200	-	times
		DR2	Vsat/ $\sigma$ CDS	_	3200	-	times
Reset feed-through noise	Note 1	RFTN	Light shielding	-2000	+100	+1000	mV
Random noise (CDS)		$\sigma { m CDS}$	Light shielding	-	1.0	-	mV

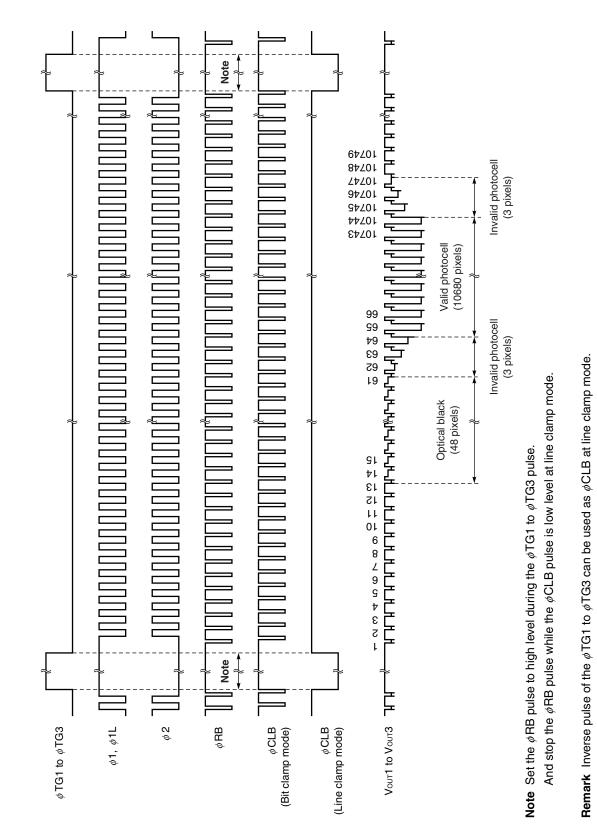
Notes 1. Refer to TIMING CHART 2, 3.

**2.** When the fall time of  $\phi$ 1L (t1') is the Typ. value (refer to **TIMING CHART 2, 3**).

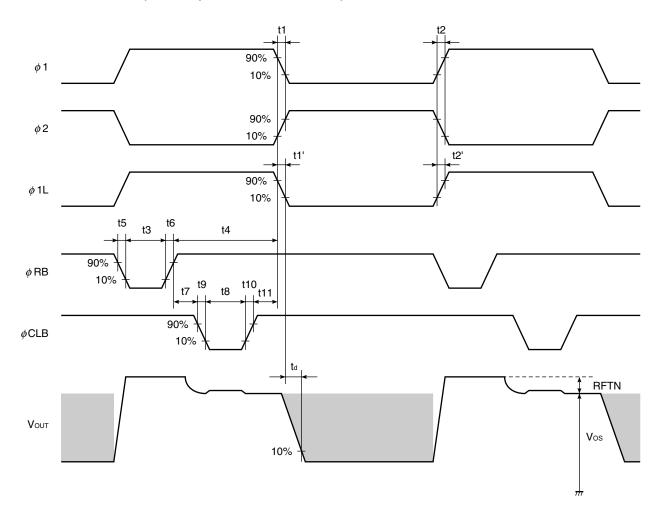
# INPUT PIN CAPACITANCE $(T_A = +25^{\circ}C, V_{OD} = 12 V)$

Parameter	Symbol	Pin	Pin No.	Min.	Тур.	Max.	Unit
Shift register clock pin capacitance 1	<b>C</b> <i>ϕ</i> 1	<i>φ</i> 1	14	-	450	_	pF
			19	_	450	-	pF
Shift register clock pin capacitance 2	Cø2	<i>ø</i> 2	11	_	450	_	pF
			22	_	450	_	pF
Last stage shift register clock pin capacitance	CøL	<i>ø</i> 1L	3	_	10	_	pF
Reset gate clock pin capacitance	Cørb	φRB	4	_	10	_	pF
Reset feed-through level clamp clock pin capacitance	Cøclb	¢CLB	2	-	10	-	pF
Transfer gate clock pin capacitance	Сøтg	¢TG1	18	-	100	-	pF
		¢TG2	17	-	100	-	pF
		¢TG3	15	_	100	-	pF

**Remark** Pin 14 and 19 ( $\phi$ 1), 11 and 22 ( $\phi$ 2) are each connected inside of the device.



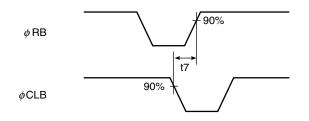
TIMING CHART 1 (for each color)

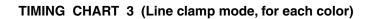


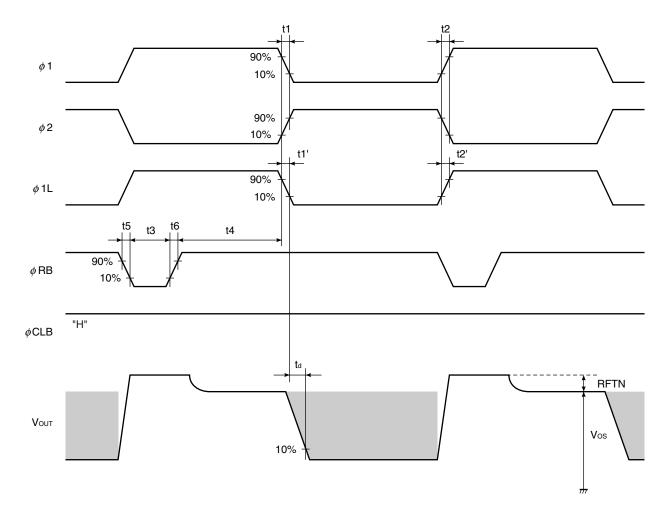
# TIMING CHART 2 (Bit clamp mode, for each color)

Symbol	Min.	Тур.	Max.	Unit
t1, t2	0	25	_	ns
t1', t2'	0	5	-	ns
t3	20	100	-	ns
t4	40	150	_	ns
t5, t6	0	25	_	ns
t7	-5 <sup>Note</sup>	25	_	ns
t8	20	100	_	ns
t9, t10	0	25	_	ns
t11	10	25	-	ns

**Note** Min. of t7 shows that the  $\phi$  RB and  $\phi$  CLB overlap each other.

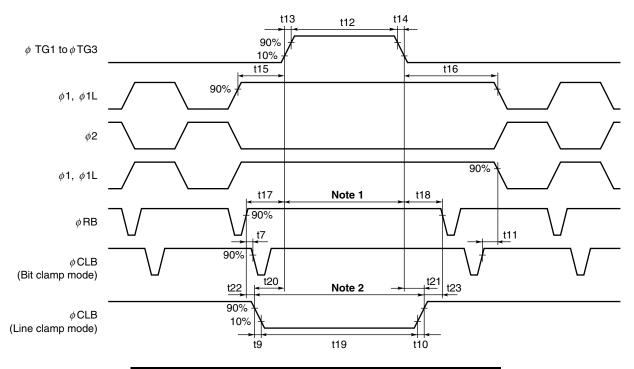






Symbol	Min.	Тур.	Max.	Unit
t1, t2	0	25	_	ns
t1', t2'	0	5	-	ns
t3	20	100	-	ns
t4	40	150	_	ns
t5, t6	0	25	_	ns

# $\phi$ TG1 to $\phi$ TG3, $\phi$ 1, $\phi$ 2 TIMING CHART



Symbol	Min.	Тур.	Max.	Unit
t7	-5 Note 3	25	-	ns
t9, t10	0	25	-	ns
t11	10	25	-	ns
t12	5000	10000	50000	ns
t13, t14	0	50	-	ns
t15, t16	900	1000	-	ns
t17, t18	200	400	I	ns
t19	t12	t12	50000	ns
t20, t21	0	50	_	ns
t22, t23	0	350	-	ns

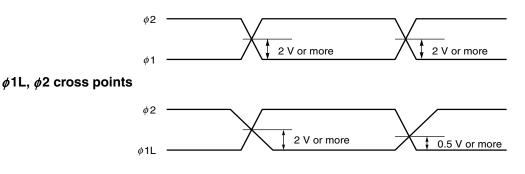
**Notes 1.** Set the  $\phi$ RB pulse to high level during this period.

**2.** Stop the  $\phi$ RB pulse during this period.

**3.** Min. of t7 shows that the  $\phi$ RB and  $\phi$ CLB overlap each other.

**Remark** Inverse pulse of the  $\phi$ TG1 to  $\phi$ TG3 can be used as  $\phi$ CLB.

#### $\phi$ 1, $\phi$ 2 cross points



**Remark** Adjust cross points ( $\phi 1$ ,  $\phi 2$ ) and ( $\phi 1L$ ,  $\phi 2$ ) with input resistance of each pin.

# NEC

# DEFINITIONS OF CHARACTERISTIC ITEMS

1. Saturation voltage : Vsat

Output signal voltage at which the response linearity is lost.

2. Saturation exposure : SE

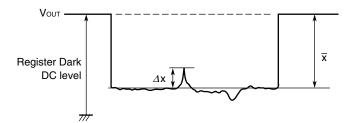
Product of intensity of illumination (lx) and storage time (s) when saturation of output voltage occurs.

# 3. Photo response non-uniformity : PRNU

The output signal non-uniformity of all the valid pixels when the photosensitive surface is applied with the light of uniform illumination. This is calculated by the following formula.

PRNU (%) = 
$$\frac{\Delta x}{\overline{x}} \times 100$$
  
 $\Delta x$  : maximum of  $|x_j - \overline{x}|$   
 $\overline{x} = \frac{\underset{j=1}{\overset{j=1}{10680}}}{10680}$ 

x<sub>j</sub> : Output voltage of valid pixel number j



#### 4. Average dark signal : ADS

Average output signal voltage of all the valid pixels at light shielding. This is calculated by the following formula.

$$ADS (mV) = \frac{\displaystyle\sum_{j=1}^{10680} d_j}{\displaystyle10680} \\ d_j: Dark \mbox{ signal of valid pixel number } j$$

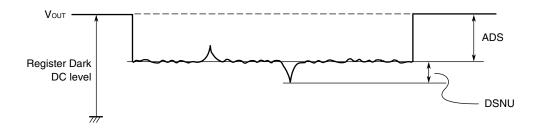
Data Sheet S15329EJ3V0DS

#### 5. Dark signal non-uniformity : DSNU

Absolute maximum of the difference between ADS and voltage of the highest or lowest output pixel of all the valid pixels at light shielding. This is calculated by the following formula.

DSNU (mV) : maximum of  $|d_j - ADS|_{j=1 \text{ to } 10680}$ 

dj : Dark signal of valid pixel number j



6. Output impedance : Zo

Impedance of the output pins viewed from outside.

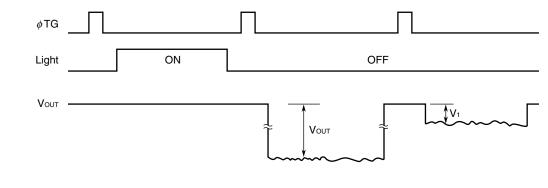
7. Response : R

Output voltage divided by exposure (lx•s).

Note that the response varies with a light source (spectral characteristic).

8. Image lag : IL

The rate between the last output voltage and the next one after read out the data of a line.



$$\mathsf{IL}(\%) = \frac{\mathsf{V}_1}{\mathsf{V}_{\mathsf{OUT}}} \times 100$$

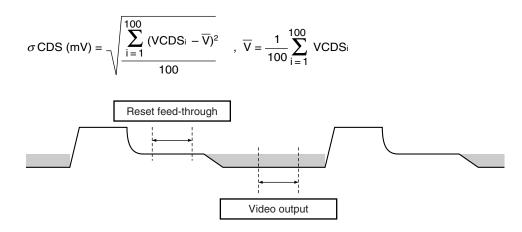
9. Random noise (CDS) :  $\sigma$ CDS

Random noise  $\sigma$ CDS is defined as the standard deviation of a valid pixel output signal with 100 times (=100 lines) data sampling at dark (light shielding).  $\sigma$ CDS is calculated by the following procedure.

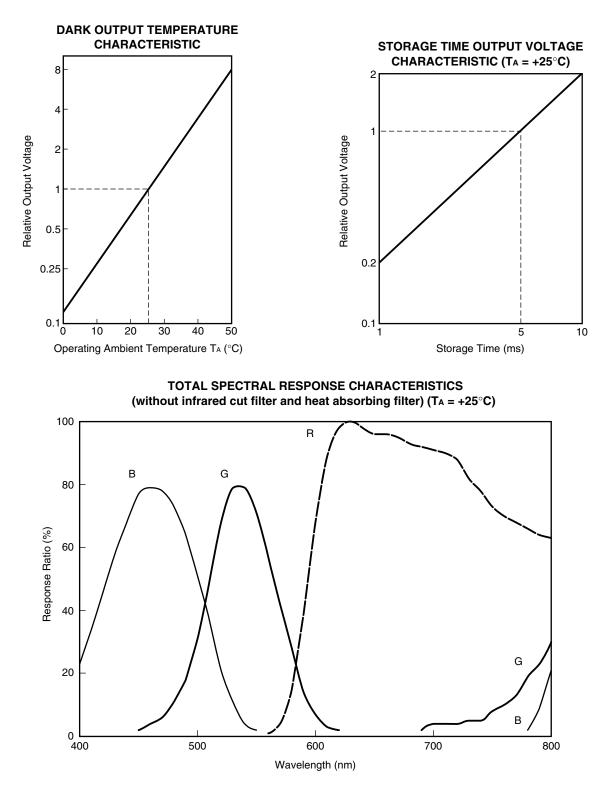
- 1. One valid photocell in one reading is fixed as measurement point.
- 2. The output level is measured during the reset feed-through period which is averaged over 100 ns to get "VDi".
- 3. The output level is measured during the video output time averaged over 100 ns to get "VOi".
- 4. The correlated double sampling output is defined by the following formula.

 $VCDS_i = VD_i - VO_i$ 

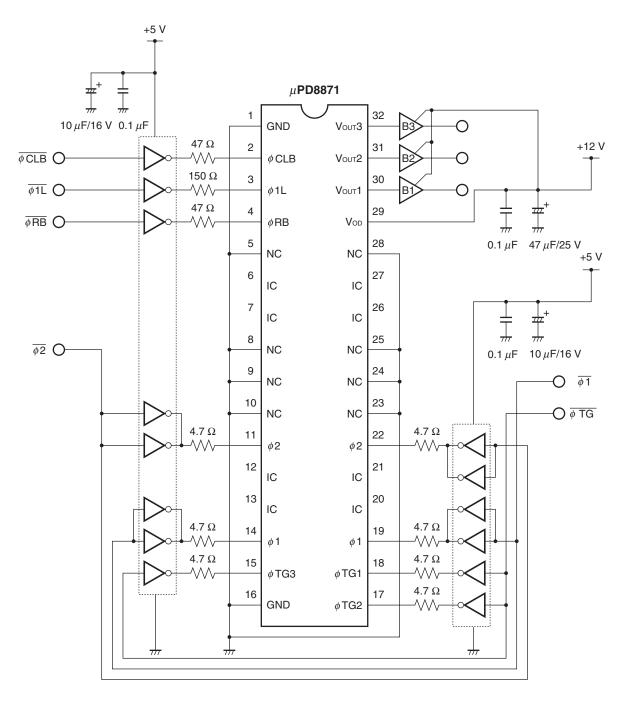
- 5. Repeat the above procedure (1 to 4) for 100 times (= 100 lines).
- 6. Calculate the standard deviation  $\sigma$ CDS using the following formula equation.



# STANDARD CHARACTERISTIC CURVES (Reference Value)

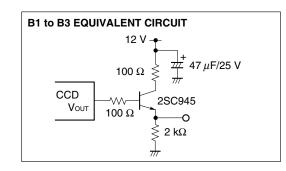


# APPLICATION CIRCUIT EXAMPLE



Cautions 1. Leave pins 6, 7, 12, 13, 20, 21, 26, 27 (IC) unconnected.

2. Connect the No connection pins (NC) to GND.



Remarks 1. B1 to B3 in the application circuit example are shown in the figure below.

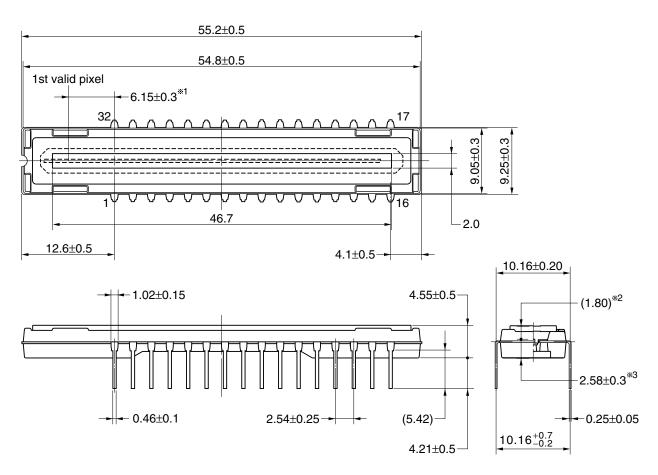
**2.** Number and type of inverters in the application circuit example are different by data rate. The following table shows the recommended number and type of inverters for data rate.

Pin Name	Pin No.	Data Rate (MHz) Inverter		erter
			Туре	Number (each pin)
φCLB	2	(data rate) < 10	74HC04	1
¢1L	3	(data rate) < 2	74HC04	1
		$2 \leq (data rate) < 10$	74AC04	1
φRB	4	(data rate) < 10	74HC04	1
<i>ø</i> 1, <i>ø</i> 2	14, 19, 11, 22	(data rate) < 2	74HC04	1
		$2 \leq (data rate) < 6$	74AC04	1
		$6 \leq$ (data rate) < 10	74AC04	3
$\phi$ TG1 to $\phi$ TG3	18, 17, 15	(data rate) < 10	74HC04	1

# PACKAGE DRAWING

# μ**PD8871CY** CCD LINEAR IMAGE SENSOR 32-PIN PLASTIC DIP (10.16 mm (400))

(Unit : mm)



Name	Dimensions	Refractive index
Plastic cap	52.2×6.4×0.7	1.5

%1 1st valid pixel → The center of the pin1

%2 The surface of the CCD chip → The top of the cap
%3 The bottom of the package → The surface of the CCD chip

32C-1CCD-PKG5-1

## **RECOMMENDED SOLDERING CONDITIONS**

When soldering this product, it is highly recommended to observe the conditions as shown below.

If other soldering processes are used, or if the soldering is performed under different conditions, please make sure to consult with our sales offices.

#### Type of Through-hole Device

#### µPD8871CY-A : CCD linear image sensor 32-pin plastic DIP (10.16 mm (400))

Process	Conditions
Partial heating method	Pin temperature : 300°C or below, Heat time : 3 seconds or less (per pin)

Cautions 1. During assembly care should be taken to prevent solder or flux from contacting the plastic cap. The optical characteristics could be degraded by such contact.

2. Soldering by the solder flow method may have deleterious effects on prevention of plastic cap soiling and heat resistance. So the method cannot be guaranteed.

# NOTES ON HANDLING THE PACKAGES

# **1** DUST AND DIRT PROTECTING

The optical characteristics of the CCD will be degraded if the cap is scratched during cleaning. Don't either touch plastic cap surface by hand or have any object come in contact with plastic cap surface. Should dirt stick to a plastic cap surface, blow it off with an air blower. For dirt stuck through electricity ionized air is recommended. And if the plastic cap surface is grease stained, clean with our recommended solvents.

#### **O CLEANING THE PLASTIC CAP**

Care should be taken when cleaning the surface to prevent scratches.

We recommend cleaning the cap with a soft cloth moistened with one of the recommended solvents below. Excessive pressure should not be applied to the cap during cleaning. If the cap requires multiple cleanings it is recommended that a clean surface or cloth be used.

#### **O RECOMMENDED SOLVENTS**

The following are the recommended solvents for cleaning the CCD plastic cap.

Use of solvents other than these could result in optical or physical degradation in the plastic cap. Please consult your sales office when considering an alternative solvent.

Symbol
EtOH
MeOH
IPA
NMP

# **② MOUNTING OF THE PACKAGE**

The application of an excessive load to the package may cause the package to warp or break, or cause chips to come off internally. Particular care should be taken when mounting the package on the circuit board. Don't have any object come in contact with plastic cap. You should not reform the lead frame. We recommended to use a IC-inserter when you assemble to PCB.

Also, be care that the any of the following can cause the package to crack or dust to be generated.

- 1. Applying heat to the external leads for an extended period of time with soldering iron.
- 2. Applying repetitive bending stress to the external leads.
- 3. Rapid cooling or heating

# **③ OPERATE AND STORAGE ENVIRONMENTS**

Operate in clean environments. CCD image sensors are precise optical equipment that should not be subject to mechanical shocks. Exposure to high temperatures or humidity will affect the characteristics. So avoid storage or usage in such conditions.

Keep in a case to protect from dust and dirt. Dew condensation may occur on CCD image sensors when the devices are transported from a low-temperature environment to a high-temperature environment. Avoid such rapid temperature changes.

For more details, refer to our document "Review of Quality and Reliability Handbook" (C12769E)

# **④** ELECTROSTATIC BREAKDOWN

CCD image sensor is protected against static electricity, but destruction due to static electricity is sometimes detected. Before handling be sure to take the following protective measures.

- 1. Ground the tools such as soldering iron, radio cutting pliers of or pincer.
- 2. Install a conductive mat or on the floor or working table to prevent the generation of static electricity.
- 3. Either handle bare handed or use non-chargeable gloves, clothes or material.
- 4. Ionized air is recommended for discharge when handling CCD image sensor.
- 5. For the shipment of mounted substrates, use box treated for prevention of static charges.
- Anyone who is handling CCD image sensors, mounting them on PCBs or testing or inspecting PCBs on which CCD image sensors have been mounted must wear anti-static bands such as wrist straps and ankle straps which are grounded via a series resistance connection of about 1 MΩ.

[MEMO]

[MEMO]

#### NOTES FOR CMOS DEVICES -

#### **1** VOLTAGE APPLICATION WAVEFORM AT INPUT PIN

Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between  $V_{IL}$  (MAX) and  $V_{IH}$  (MIN).

# (2) HANDLING OF UNUSED INPUT PINS

Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.

#### **③** PRECAUTION AGAINST ESD

A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.

# **④** STATUS BEFORE INITIALIZATION

Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.

#### **⑤** POWER ON/OFF SEQUENCE

In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current.

The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.

#### 6 INPUT OF SIGNAL DURING POWER OFF STATE

Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.

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