**EXAMALOG
DEVICES**

Video Encoder with Six 10-Bit DACs, 54 MHz Oversampling and Progressive Scan Inputs

ADV7192

FEATURES

Six High-Quality 10-Bit Video DACs 10-Bit Internal Digital Video Processing Multistandard Video Input Multistandard Video Output 4 Oversampling with Internal 54 MHz PLL Programmable Video Control Includes: Digital Noise Reduction Gamma Correction Black Burst LUMA Delay CHROMA Delay Multiple Luma and Chroma Filters Luma SSAF™ (Super Subalias Filter) Average Brightness Detection Field Counter Macrovision Rev. 7.1 CGMS (Copy Generation Management System) WSS (Wide Screen Signaling) Closed Captioning Support. Teletext Insertion Port (PAL-WST) 2-Wire Serial MPU Interface (I2C®-Compatible and Fast I2C) I 2 C Interface Supply Voltage 5 V and 3.3 V Operation 80-Lead LQFP Package

APPLICATIONS

DVD Playback Systems PC Video/Multimedia Playback Systems Progressive Scan Playback Systems

GENERAL DESCRIPTION

The ADV7192 is part of the new generation of video encoders from Analog Devices. The device builds on the performance of previous video encoders and provides new features like interfacing progressive scan devices, Digital Noise Reduction, Gamma Correction, 4× Oversampling and 54 MHz operation, Average Brightness Detection, Black Burst Signal Generation, Chroma Delay, an additional Chroma Filter, and other features.

The ADV7192 supports NTSC-M, NTSC-N (Japan), PAL N, PAL M, PAL-B/D/G/H/I and PAL-60 standards. Input standards supported include ITU-R.BT656 4:2:2 YCrCb in 8-bit or 16-bit format and 3×10 -Bit YCrCb progressive scan format.

The ADV7192 can output Composite Video (CVBS), S-Video (Y/C), Component YUV or RGB and analog progressive scan in YPrPb format. The analog component output is also compatible with Betacam, MII, and SMPTE/EBU N10 levels, SMPTE 170 M NTSC, and ITU–R.BT 470 PAL.

Please see Detailed Description of Features for more information about the ADV7192.

SIMPLIFIED FUNCTIONAL BLOCK DIAGRAM

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I²C is a registered trademark of Philips Corporation. Throughout the document YUV refers to digital or analog component video.

REV. A

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 $\bf 5~V~SPECIFICATIONS^{1 (V_{AA} = 5 V, V_{REF} = 1.235 V, R_{SET1,2} = 1200 ~\Omega}$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}² **unless otherwise noted.)**

NOTES

¹All measurements are made in $4 \times$ Oversampling Mode unless otherwise specified.

 2 Temperature range ${\rm T_{MIN}}$ to ${\rm T_{MAX}}$: 0°C to 70°C.

³Guaranteed by characterization.

4 For all inputs but PAL_NTSC and ALSB.

⁵For PAL_NTSC and ALSB inputs.

6 For all outputs but *VSO*/TTX/CLAMP.

7 For *VSO*/TTX/CLAMP output.

 8 Measurement made in $2 \times$ Oversampling Mode.

 $^{9}I_{\mathrm{DAC}}$ is the total current required to supply all DACs including the $\rm V_{REF}$ Circuitry.

¹⁰All six DACs ON.

 ${}^{11}I_{CCT}$ or the circuit current, is the continuous current required to drive the digital core without I_{PLL} .

ADV7192–SPECIFICATIONS

 $\bf 3.3~V~SPECIFICATIONS$ ¹ (V_{AA} = 3.3 V, V_{REF} = 1.235 V, R_{SET1,2} = 1200 Ω unless otherwise noted. All specifications T_{MIN} to T_{MAX}² **unless otherwise noted.)**

NOTES

¹All measurements are made in $4\times$ Oversampling Mode unless otherwise specified and are guaranteed by characterization. In $2\times$ Oversampling Mode, power requirement for the ADV7192 is typically 3.0 V.

²Temperature range $\rm T_{MIN}$ to $\rm T_{MAX:}$ 0°C to 70°C.

³For all inputs but PAL_NTSC and ALSB.

4 For PAL_NTSC and ALSB inputs.

5 For all outputs but *VSO*/TTX/CLAMP.

6 For *VSO*/TTX/CLAMP output.

 7 Measurement made in $2 \times$ Oversampling Mode.

 ${}^{8}I_{\mathrm{DAC}}$ is the total current required to supply all DACs including the $\rm V_{REF}$ Circuitry.

9 All six DACs ON.

 $^{10}I_{\text{CCT}}$ or the circuit current, is the continuous current required to drive the digital core without I_{PLL} .

5 V DYNAMIC—SPECIFICATIONS^{1 (V_{AA} = 5 V \pm 250 mV, V_{REF} = 1.235 V, R_{SET1,2} = 1200 Ω unless otherwise noted. All
5 V DYNAMIC—SPECIFICATIONS¹ specifications T_{MIN} to T_{MAX}² unless otherwise noted.)} spec ifications T_{MIN} to T_{MAX}² unless otherwise noted.)

NOTES

¹All measurements are made in 4× Oversampling Mode unless otherwise specified and are guaranteed by characterization.

²Temperature range T_{MIN} to T_{MAX} : 0°C to 70°C.

³Values in parentheses apply to $2 \times$ Oversampling Mode.

Specifications subject to change without notice.

3.3 **V** DYNAMIC—SPECIFICATIONS¹ specifications T_{MIN} to T_{MAX}² unless otherwise noted.) **specifications TMIN to TMAX 2 unless otherwise noted.)**

NOTES

¹All measurements are made in 4× Oversampling Mode unless otherwise specified and are guaranteed by characterization.

²Temperature range $\rm T_{MIN}$ to $\rm T_{MAX:}$ 0°C to 70°C.

³Values in parentheses apply to $2\times$ Oversampling Mode.

$\bf 5~V~TIMING~CHARACTERISTICS~$ ^{(V_{AA} = 5 V \pm 250 mV, V_{REF} = 1.235 V, R_{SET1,2} = 1200 V unless otherwise noted. All
 $\bf 5~V$} spec ifications T_{MIN} to T_{MAX}¹ unless otherwise noted.)

NOTES

¹Temperature range T_{MIN} to T_{MAX}: 0°C to 70°C.
²Guaranteed by characterization. ³Pixel Port consists of: Data: P7–P0, Y0/P8–Y7/P15 Pixel Inputs Control: *HSYNC*, *VSYNC*, *BLANK* Clock: CLKIN 4 Teletext Port consists of: Digital Output: TTXREQ Data: TTX

3.3 **V** TIMING CHARACTERISTICS $\frac{(V_{AA}=3.3 \text{ V }\pm\text{ 150 mV, V}_{REF}=1.235 \text{ V, R}_{SET1,2}=1200 \text{ }\Omega}$ unless otherwise noted. All specifications T_{MIN} to T_{MAX}¹ unless otherwise noted.)²

NOTES

¹Temperature range T_{MIN} to T_{MAX} : 0°C to 70°C. ²Guaranteed by characterization. 3 Pixel Port consists of: Data: P7–P0, Y0/P8–Y7/P15 Pixel Inputs Control: *HSYNC*, *VSYNC*, *BLANK* Clock: CLKIN 4 Teletext Port consists of: Digital Output: TTXREQ Data: TTX

Figure 1. MPU Port Timing Diagram

Figure 2. Pixel and Control Data Timing Diagram

Figure 3. Teletext Timing Diagram

Figure 4. Progressive Scan Input Timing

ABSOLUTE MAXIMUM RATINGS¹

NOTES

¹Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those listed in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

²Analog Output Short Circuit to any Power Supply or Common can be of an indefinite duration.

PACKAGE THERMAL PERFORMANCE

The 80-lead package is used for this device. The junction-toambient (θ_{IA}) thermal resistance in still air on a four-layer PCB is 24.7°C.

To reduce power consumption when using this part the user can run the part on a 3.3 V supply, turn off any unused DACs.

The user must at all times stay below the maximum junction temperature of 110°C. The following equation shows how to calculate this junction temperature:

Junction Temperature = $(V_{AA} \times (I_{DAC} + I_{CCT}) \times \theta_{JA} + 70^{\circ}C T_{AMB}$

IDAC = 10 *mA* + (*sum of the average currents consumed by each powered-on DAC*)

Average current consumed by each powered-on DAC =

 $(V_{REF} \times K)/R_{SET}$ V_{REF} = 1.235 *V* $K = 4.2146$

PIN CONFIGURATION

ORDERING GUIDE

CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although the ADV7192 features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

PIN FUNCTION DESCRIPTIONS

DETAILED DESCRIPTION OF FEATURES Clocking: Single 27 MHz Clock Required to Run the Device 4 Oversampling with Internal 54 MHz PLL Square Pixel Operation Advanced Power Management Programmable Video Control Features: Digital Noise Reduction Black Burst Signal Generation Pedestal Level Hue, Brightness, Contrast, and Saturation Clamping Output Signal VBI (Vertical Blanking Interval) Subcarrier Frequency and Phase LUMA Delay CHROMA Delay Gamma Correction Luma And Chroma Filters Luma SSAF (Super Subalias Filter) Average Brightness Detection Field Counter Interlaced/Noninterlaced Operation Complete On-Chip Video Timing Generator Programmable Multimode Master/Slave Operation Macrovision Rev 7.1 CGMS (Copy Generation Management System) WSS (Wide Screen Signaling) Closed Captioning Support Teletext Insertion Port (PAL-WST) 2-Wire Serial MPU Interface (I2C-Compatible and Fast I2 C) I 2C Registers Synchronized to VSYNC

GENERAL DESCRIPTION

The ADV7192 is an integrated Digital Video Encoder that converts digital CCIR-601/656 4:2:2 8-bit or 16-bit component video data into a standard analog baseband television signal compatible with worldwide standards. Additionally, it is possible to input video data in 3×10 -bit YCrCb progressive scan format to facilitate interfacing devices such as progressive scan systems.

Six DACs are available on the ADV7192, each of which is capable of providing 4.33 mA of current. In addition to the composite output signal there is the facility to output S-Video (Y/C Video), RGB Video and YUV Video. All YUV formats (SMPTE/EBU N10, MII or Betacam) are supported.

The on-board SSAF (Super Subalias Filter) with extended luminance frequency response and sharp stopband attenuation enables studio quality video playback on modern TVs, giving optimal horizontal line resolution. An additional sharpness control feature allows high-frequency enhancement on the luminance signal.

Figure 6. Block Diagram for DNR Mode and DNR Sharpness **Mode**

SCRESET/RTC/TR Figure 5. Detailed Functional Block Diagram

Digital Noise Reduction allows improved picture quality in removing low amplitude, high frequency noise. Figure 6 shows the DNR functionality in the two modes available.

Programmable gamma correction is also available. The figure below shows the response of different gamma values to a ramp signal.

Figure 7. Signal Input (Ramp) and Selectable Gamma Output Curves

The device is driven by a 27 MHz clock. Data can be output at 27 MHz or 54 MHz (on-board PLL) when $4 \times$ oversampling is enabled. Also, the output filter requirements in $4\times$ oversampling and $2 \times$ oversampling differ, as can be seen in Figure 8.

Figure 8. Output Filter Requirements in 4× Oversampling Mode

Figure 9. PLL and 4× Oversampling Block Diagram

The ADV7192 also supports both PAL and NTSC square pixel operation. In this case the encoder requires a 24.5454 MHz Clock for NTSC or 29.5 MHz Clock for PAL square pixel mode operation. All internal timing is generated on-chip.

An advanced power management circuit enables optimal control of power consumption in normal operating modes or sleep modes.

The Output Video Frames are synchronized with the incoming data Timing Reference Codes. Optionally, the Encoder accepts (and can generate) *HSYNC*, *VSYNC,* and FIELD timing signals. These timing signals can be adjusted to change pulsewidth and position while the part is in master mode.

HSO/*CSO* and *VSO* TTL outputs are also available and are timed to the analog output video.

A separate teletext port enables the user to directly input teletext data during the vertical blanking interval.

The ADV7192 also incorporates WSS and CGMS-A data control generation.

The ADV7192 modes are set up over a 2-wire serial bidirectional port ($I²C$ -compatible) with two slave addresses, and the device is register-compatible with the ADV7172.

The ADV7192 is packaged in an 80-lead LQFP package.

DATA PATH DESCRIPTION

For PAL B, D, G, H, I, M, N, and NTSCM, N modes, YCrCb 4:2:2 data is input via the CCIR-656/601-compatible Pixel Port at a 27 MHz Data Rate. The Pixel Data is demultiplexed to form three data paths. Y typically has a range of 16 to 235, Cr and Cb typically have a range of 128 ± 112 ; however, it is possible to input data from 1 to 254 on both Y, Cb, and Cr. The ADV7192 supports PAL (B, D, G, H, I, N, M) and NTSCM, N (with and without Pedestal) and PAL60 standards.

Digital noise reduction can be applied to the Y signal. Programmable gamma correction can also be applied to the Y signal if required.

The Y data can be manipulated for contrast control and a setup level can be added for brightness control. The Cr, Cb data can be scaled to achieve color saturation control. All settings become effective at the start of the next field when double buffering is enabled.

The appropriate sync, blank, and burst levels are added to the YCrCb data. Macrovision antitaping, closed-captioning and teletext levels are also added to Y and the resultant data is interpolated to 54 MHz $(4 \times$ Oversampling Mode). The interpolated data is filtered and scaled by three digital FIR filters.

The U and V signals are modulated by the appropriate Subcarrier Sine/Cosine waveforms and a phase offset may be added onto the color subcarrier during active video to allow hue adjustment. The resulting U and V signals are added together to make up the Chrominance signal. The Luma (Y) signal can be delayed by up to six clock cycles (at 27 MHz) and the Chroma signal can be delayed by up to eight clock cycles (at 27 MHz).

The Luma and Chroma signals are added together to make up the Composite Video Signal. All timing signals are controlled.

The YCrCb data is also used to generate RGB data with appropriate sync and blank levels. The YUV levels are scaled to output the suitable SMPTE/EBU N10, MII, or Betacam levels.

Each DAC can be individually powered off if not required. A complete description of DAC output configurations is given in the Mode Register 2 section.

Video output levels are illustrated in Appendix 9.

When to used to interface progressive scan systems, the ADV7192 allows to input YCrCb signals in Progressive Scan format $(3 \times 10$ -bit) before these signals are routed to the interpolation filters and the DACs.

INTERNAL FILTER RESPONSE

The Y Filter supports several different frequency responses including two low-pass responses, two notch responses, an Extended (SSAF) response with or without gain boost/attenuation, a CIF response, and a QCIF response. The UV filters support

several different frequency responses including five low-pass responses, a CIF response, and a QCIF response, as can be seen in the following figures. All filter plots show the $4\times$ Oversampling responses.

In Extended Mode there is the option of 12 responses in the range from –4 dB to +4 dB. The desired response can be chosen by the user by programming the correct value via the $I²C$. The variation of frequency responses can be seen in the Tables I and II. For more detailed filter plots refer to Analog Devices' Application Note AN-562.

NOTES

¹Passband Ripple is defined as the fluctuations from the 0 dB response in the passband, measured in (dB). The passband is defined to have 0–fc frequency limits for a low-pass filter, 0–f1 and f2–infinity for a notch filter, where fc, f1, f2 are the -3 dB points.

 23 dB bandwidth refers to the -3 dB cutoff frequency.

Filter Type		Filter Selection		Passband Ripple ¹ (dB)	3 dB Bandwidth ² (MHz)
	MR07	MR06	MR05		
1.3 MHz Low-Pass	0	0	Ω	0.09	1.395
0.65 MHz Low-Pass	Ω	0		Monotonic	0.65
1.0 MHz Low-Pass	Ω		Ω	Monotonic	1.0
2.0 MHz Low-Pass	0			0.048	2.2
3.0 MHz Low-Pass				Monotonic	3.2
CIF		Ω		Monotonic	0.65
OCIF			Ω	Monotonic	0.5

Table II. Chrominance Internal Filter Specifications (4× Oversampling)

NOTES

¹Passband Ripple is defined as the fluctuations from the 0 dB response in the passband, measured in (dB). The passband is defined to have 0–fc frequency limits for a low-pass filter, 0–f1 and f2–infinity for a notch filter, where fc, f1, f2 are the -3 dB points.

²3 dB bandwidth refers to the -3 dB cutoff frequency.

ADV7192–Typical Performance Characteristics

TPC 1. NTSC Low-Pass Luma Filter

TPC 2. PAL Low-Pass Luma Filter

TPC 3. NTSC Notch Luma Filter

TPC 4. PAL Notch Luma Filter

TPC 5. Extended Mode (SSAF) Luma Filter

TPC 6. Extended SSAF Luma Filter and Programmable Gain/Attenuation Showing +4 dB/–12 dB Range

TPC 7. Extended SSAF and Programmable Attenuation, Showing Range 0 dB/–4 dB

TPC 8. Extended SSAF and Programmable Gain, Showing Range 0 dB/+4 dB

TPC 9. Luma CIF Filter

TPC 10. Luma QCIF Filter

TPC 11. Chroma 0.65 MHz Low-Pass Filter

TPC 12. Chroma 1.0 MHz Low-Pass Filter

TPC 13. Chroma 1.3 MHz Low-Pass Filter

TPC 14. Chroma 2 MHz Low-Pass Filter

TPC 15. Chroma 3 MHz Low-Pass Filter

TPC 16. Chroma CIF Filter

TPC 17. Chroma QCIF Filter

FEATURES: FUNCTIONAL DESCRIPTION BLACK BURST OUTPUT

It is possible to output a black burst signal from two DACs. This signal output is very useful for professional video equipment since it enables two video sources to be locked together. (Mode Register 9.)

Figure 10. Possible Application for the Black Burst Output **Signal**

BRIGHTNESS DETECT

This feature is used to monitor the average brightness of the incoming Y video signal on a field by field basis. The information is read from the $I²C$ and based on this information the color saturation, contrast and brightness controls can be adjusted (for example to compensate for very dark pictures). (Brightness Detect Register.)

CHROMA/LUMA DELAY

The luminance data can be delayed by maximum of six clock cycles. Additionally the Chroma can be delayed by a maximum of eight clock cycles (one clock cycle at 27 MHz). (Timing Register 0 and Mode Register 9.)

Figure 11. Chroma Delay Figure 12. Luma Delay

CLAMP OUTPUT

The ADV7192 has a programmable clamp TTL output signal. This clamp signal is programmable to the front and back porch. The clamp signal can be varied by one to three clock cycles in a positive and negative direction from the default position. (Mode Register 5, Mode Register 7.)

Figure 13. Clamp Output Timing

CSO, HSO, AND VSO OUTPUTS

The ADV7192 supports three output timing signals, *CSO* (composite sync signal), *HSO* (Horizontal Sync Signal) and *VSO* (Vertical Sync Signal). These output TTL signals are aligned with the analog video outputs. See Figure 14 for an example of these waveforms. (Mode Register 7.)

Figure 14. CSO, HSO, VSO Timing Diagram

COLOR BAR GENERATION

The ADV7192 can be configured to generate 100/7.5/75/7.5 color bars for NTSC or 100/0/75/0 color bars for PAL. (Mode Register 4.)

COLOR BURST SIGNAL CONTROL

The burst information can be switched on and off the composite and chroma video output. (Mode Register 4.)

COLOR CONTROLS

The ADV7192 allows the user to control the brightness, contrast, hue and saturation of the color. The control registers may be double-buffered, meaning that any modification to the registers will be done outside the active video region and, therefore, changes made will not be visible during active video.

Contrast Control

Contrast adjustment is achieved by scaling the Y input data by a factor programmed by the user. This factor allows the data to be scaled between 0% and 150%. (Contrast Control Register.)

Brightness Control

The brightness is controlled by adding a programmable setup level onto the scaled Y data. This brightness level may be added onto the Y data. For NTSC with pedestal, the setup can vary from 0 IRE to 22.5 IRE. For NTSC without pedestal and PAL, the setup can vary from –7.5 IRE to +15 IRE. (Brightness Control Register.)

Color Saturation

Color adjustment is achieved by scaling the Cr and Cb input data by a factor programmed by the user. This factor allows the data to be scaled between 0% and 200%. (U Scale Register and V Scale Register.)

Hue Adjust Control

The hue adjustment is achieved on the composite and chroma outputs by adding a phase offset onto the color subcarrier in the active video but leaving the color burst unmodified, i.e., only the phase between the video and the colorburst is modified and hence the hue is shifted. The ADV7192 provides a range of $\pm 22^{\circ}$ in increments of 0.17578125°. (Hue Adjust Register.)

CHROMINANCE CONTROL

The color information can be switched on and off the composite, chroma and color component video outputs. (Mode Register 4.)

UNDERSHOOT LIMITER

A limiter is placed after the digital filters. This prevents any synchronization problems for TVs. The level of undershoot is programmable between -1.5 IRE, -6 IRE, -11 IRE when operating in 4× Oversampling Mode. In 2× Oversampling Mode the limits are –7.5 IRE and 0 IRE. (Mode Register 9 and Timing Register 0.)

DIGITAL NOISE REDUCTION

DNR is applied to the Y data only. A filter block selects the high frequency, low amplitude components of the incoming signal (DNR Input Select). The absolute value of the filter output is compared to a programmable threshold value (DNR Threshold Control). There are two DNR modes available: DNR Mode and DNR Sharpness Mode.

In DNR Mode, if the absolute value of the filter output is smaller than the threshold, it is assumed to be noise. A programmable amount (Coring Gain Control) of this noise signal will be subtracted from the original signal.

In DNR Sharpness Mode, if the absolute value of the filter output is less than the programmed threshold, it is assumed to be noise, as before. Otherwise, if the level exceeds the threshold, now being identified as a valid signal, a fraction of the signal (Coring Gain Control) will be added to the original signal in order to boost high frequency components and to sharpen the video image.

In MPEG systems it is common to process the video information in blocks of 8×8 pixels for MPEG2 systems, or 16×16 pixels for MPEG1 systems ('Block Size Control'). DNR can be applied to the resulting block transition areas that are known to contain noise. Generally the block transition area contains two pixels. It is possible to define this area to contain four pixels (Border Area Control).

It is also possible to compensate for variable block positioning or differences in YCrCb pixel timing with the use of the Block Offset Control. (Mode Register 8, DNR Registers 0–2.)

DOUBLE BUFFERING

Double buffering can be enabled or disabled on the following registers: Closed Captioning Registers, Brightness Control Register, V-Scale, U-Scale Contrast Control Register, Hue Adjust Register, Macrovision Registers, and the Gamma Curve Select bit. These registers are updated once per field on the falling edge of the *VSYNC* signal. Double Buffering improves the overall performance of the ADV7192, since modifications to register settings will not be made during active video, but take effect on the start of the active video. (Mode Register 8.)

GAMMA CORRECTION CONTROL

Gamma correction may be performed on the luma data. The user has the choice to use either of two different gamma curves, A or B. At any one time one of these curves is operational if gamma correction is enabled. Gamma correction allows the mapping of the luma data to a user-defined function. (Mode Register 8, Gamma Correction Registers 0–13.)

NTSC PEDESTAL CONTROL

In NTSC mode it is possible to have the pedestal signal generated on the output video signal. (Mode Register 2.)

POWER-ON RESET

After power-up, it is necessary to execute a *RESET* operation. A reset occurs on the falling edge of a high-to-low transition on the *RESET* pin. This initializes the pixel port such that the data on the pixel inputs pins is ignored. See Appendix 8 for the register settings after *RESET* is applied.

PROGRESSIVE SCAN INPUT

It is possible to input data to the ADV7192 in progressive scan format. For this purpose the input pins Y0/P8–Y7/P15, Y8–Y9, Cr0–Cr9 and Cb0–Cb9 accept 10-bit Y data, 10-bit Cb data and 10-bit Cr data. The data is clocked into the part at 27 MHz. The data is then filtered and sinc corrected in an $2\times$ Interpolation filter and then output to three video DACs at 54 MHz (to interface to a progressive scan monitor).

Figure 15. Plot of the Interpolation Filter for the Y Data

Figure 16. Plot of the Interpolation Filter for the CrCb Data

It is assumed that there is no color space conversion or any other such operation to be performed on the incoming data. Thus if these DAC outputs are to drive a TV, all relevant timing and synchronization data should be contained in the incoming digital *Y* data. An FPGA can be used to achieve this,

The block diagram below shows a possible configuration for progressive scan mode using the ADV7192.

Figure 17. Block Diagram Using the ADV7192 in Progressive Scan Mode

The progressive scan decoder deinterlaces the data from the MPEG2 decoder. This now means that there are 525 video lines per field in NTSC mode and 625 video lines per field in PAL mode. The duration of the video line is now 32 μ s.

It is important to note that the data from the MPEG2 decoder is in 4:2:2 format. The data output from the progressive scan decoder is in 4:4:4 format. Thus it is assumed that some form of interpolation on the color component data is performed in the progressive scan decoder IC. (Mode Register 8.)

REAL-TIME CONTROL, SUBCARRIER RESET, AND TIMING RESET

Together with the SCRESET/RTC/TR pin and Mode Register 4 (Genlock Control), the ADV7192 can be used in (a) Timing Reset Mode, (b) Subcarrier Phase Reset Mode or (c) RTC Mode.

- (a) A TIMING RESET is achieved in holding this pin high. In this state the horizontal and vertical counters will remain reset. On releasing this pin (set to low), the internal counters will commence counting again. The minimum time the pin has to be held high is 37 ns (1 clock cycle at 27 MHz), otherwise the reset signal might not be recognized.
- (b) The SUBCARRIER PHASE will reset to that of Field 0 at the start of the following field when a low to high transition occurs on this input pin.
- (c) In RTC MODE, the ADV7192 can be used to lock to an external video source.

The real-time control mode allows the ADV7192 to automatically alter the subcarrier frequency to compensate for line length variations. When the part is connected to a device that outputs a digital datastream in the RTC format (such as a ADV7185 video decoder, see Figure 21), the part will automatically change to the compensated subcarrier frequency on a line-by-line basis. This digital datastream is 67 bits wide and the subcarrier is contained in Bits 0 to 21. Each bit is two clock cycles long. 00Hex should be written into all four Subcarrier Frequency registers when using this mode. (Mode Register 4.)

SCH PHASE MODE

The SCH phase is configured in default mode to reset every four (NTSC) or eight (PAL) fields to avoid an accumulation of SCH phase error over time. In an ideal system, zero SCH phase

error would be maintained forever, but in reality, this is impossible to achieve due to clock frequency variations. This effect is reduced by the use of a 32-bit DDS, which generates this SCH.

Resetting the SCH phase every four or eight fields avoids the accumulation of SCH phase error, and results in very minor SCH phase jumps at the start of the four or eight field sequence.

Resetting the SCH phase should not be done if the video source does not have stable timing or the ADV7192 is configured in RTC mode. Under these conditions (unstable video) the Subcarrier Phase Reset should be enabled but no reset applied. In this configuration the SCH Phase will never be reset; this means that the output video will now track the unstable input video. The Subcarrier Phase Reset when applied will reset the SCH phase to Field 0 at the start of the next field (e.g., Subcarrier Phase Reset applied in Field 5 (PAL) on the start of the next field SCH phase will be reset to Field 0). (Mode Register 4.)

SLEEP MODE

If, after *RESET*, the SCRESET/RTC/TR and NTSC_PAL pins are both set high, the ADV7192 will power up in Sleep Mode to facilitate low power consumption before all registers have been initialized.

If Power-up in Sleep Mode is disabled, Sleep Mode control passes to the Sleep Mode control in Mode Register 2 (i.e., control via $I²C$). (Mode Register 2 and Mode Register 6.)

SQUARE PIXEL MODE

The ADV7192 can be used to operate in square pixel mode. For NTSC operation an input clock of 24.5454 MHz is required. Alternatively, for PAL operation, an input clock of 29.5 MHz is required. The internal timing logic adjusts accordingly for square pixel mode operation. Square pixel mode is not available in 4× Oversampling mode. (Mode Register 2.)

VERTICAL BLANKING DATA INSERTION AND BLANK INPUT

It is possible to allow encoding of incoming YCbCr data on those lines of VBI that do not have line sync or pre-/post-equalization pulses . This mode of operation is called *Partial Blanking*. It allows the insertion of any VBI data (Opened VBI) into the encoded output waveform, this data is present in digitized incoming YCbCr data stream (e.g., WSS data, CGMS, VPS etc.). Alternatively the entire VBI may be blanked (no VBI data inserted) on these lines. VBI is available in all timing modes.

It is possible to allow control over the *BLANK* signal using Timing Register 0. When the *BLANK* input is enabled (TR03 = 0 and input pin tied low), the *BLANK* input can be used to input externally generated blank signals in Slave Mode 1, 2, or 3. When the \overline{BLANK} input is disabled (TR03 = 1 and input pin tied low or tied high) the *BLANK* input is not used and the ADV7192 automatically blanks all normally blank lines as per CCIR-624. (Timing Register 0.)

YUV LEVELS

This functionality allows the ADV7192 to output SMPTE levels or Betacam levels on the Y output when configured in PAL or NTSC mode.

As the data path is branched at the output of the filters, the luma signal relating to the CVBS or S-Video Y/C output is unaltered. Only the Y output of the YCrCb outputs is scaled. This control allows color component levels to have a peak-peak amplitude of 700 mV, 1000 mV or the default values of 934 mV in NTSC and 700 mV in PAL. (Mode Register 5.)

16-BIT INTERFACE

It is possible to input data in 16-bit format. In this case, the interface only operates if the data is accompanied by separate *HSYNC*/*VSYNC*/*BLANK* signals. Sixteen-bit mode is not available in Slave Mode 0 since EAV/SAV timing codes are used. (Mode Register 8.)

4 OVERSAMPLING AND INTERNAL PLL

It is possible to operate all six DACs at 27 MHz (2× Oversampling) or 54 MHz $(4 \times$ Oversampling).

The ADV7192 is supplied with a 27 MHz clock synced with the incoming data. Two options are available: to run the device throughout at 27 MHz or to enable the PLL. In the latter case, even if the incoming data runs at 27 MHz, 4× Oversampling and the internal PLL will output the data at 54 MHz.

NOTE

In 4× Oversampling Mode the requirements for the optional output filters are different from those in 2× Oversampling. (Mode Register 1, Mode Register 6.) See Appendix 6.

Figure 18. PLL and $4 \times$ Oversampling Block Diagram

Figure 19. Output Filter Requirements in $2x$ and $4x$ Oversampling Mode

VIDEO TIMING DESCRIPTION

The ADV7192 is intended to interface to off-the-shelf MPEG1 and MPEG2 Decoders. As a consequence, the ADV7192 accepts 4:2:2 YCrCb Pixel Data via a CCIR-656 Pixel Port and has several Video Timing Modes of operation that allow it to be configured as either System Master Video Timing Generator or a Slave to the System Video Timing Generator. The ADV7192 generates all of the required horizontal and vertical timing periods and levels for the analog video outputs.

The ADV7192 calculates the width and placement of analog sync pulses, blanking levels, and color burst envelopes. Color bursts are disabled on appropriate lines and serration and equalization pulses are inserted where required.

In addition the ADV7192 supports a PAL or NTSC square pixel operation. The part requires an input pixel clock of 24.5454 MHz for NTSC square pixel operation and an input pixel clock of 29.5 MHz for PAL square pixel operation. The internal horizontal line counters place the various video waveform sections in the correct location for the new clock frequencies.

The ADV7192 has four distinct Master and four distinct Slave timing configurations. Timing Control is established with the bidirectional *HSYNC*, *BLANK* and *VSYNC* pins. Timing Register 1 can also be used to vary the timing pulsewidths and where they occur in relation to each other. (Mode Register 2, Timing Register 0, 1.)

RESET SEQUENCE

When *RESET* becomes active the ADV7192 reverts to the default output configuration (see Appendix 8 for register settings). The ADV7192 internal timing is under the control of the logic level on the NTSC_PAL pin.

When *RESET* is released Y, Cr, Cb values corresponding to a black screen are input to the ADV7192. Output timing signals are still suppressed at this stage. DACs A, B, C are switched off and DACs D, E, F are switched on.

When the user requires valid data, Pixel Data Valid Control is enabled ($MR26 = 1$) to allow the valid pixel data to pass through the encoder. Digital output timing signals become active and the encoder timing is now under the control of the Timing Registers. If at this stage, the user wishes to select a different video standard to that on the NTSC_PAL pin, Standard I²C Control should be enabled ($MR25 = 1$) and the video standard required is selected by programming Mode Register 0 (Output Video Standard Selection). Figure 20 illustrates the *RESET* sequence timing.

Figure 21. RTC Timing and Connections

Mode 0 (CCIR–656): Slave Option

(Timing Register $0 \text{ TR}0 = \text{X} \text{X} \text{X} \text{X} \text{X} \text{0} \text{0}$)

The ADV7192 is controlled by the SAV (Start Active Video) and EAV (End Active Video) Time Codes in the Pixel Data. All timing information is transmitted using a 4-byte Synchronization Pattern. A synchronization pattern is sent immediately before and after each line during active picture and retrace. Mode 0 is illustrated in Figure 22. The *HSYNC*, *VSYNC* and *BLANK* (if not used) pins should be tied high during this mode. Blank output is available.

Figure 22. Timing Mode 0, Slave Mode

Mode 0 (CCIR–656): Master Option

(Timing Register 0 TR $0 =$ X X X X X 0 0 1)

The ADV7192 generates H, V, and F signals required for the SAV (Start Active Video) and EAV (End Active Video) Time Codes in the CCIR656 standard. The H bit is output on the *HSYNC* pin, the V bit is output on the *BLANK* pin and the F bit is output on the *VSYNC* pin. Mode 0 is illustrated in Figure 23 (NTSC) and Figure 24 (PAL). The H, V, and F transitions relative to the video waveform are illustrated in Figure 25.

Figure 23. Timing Mode 0, NTSC Master Mode

Figure 24. Timing Mode 0, PAL Master Mode

Figure 25. Timing Mode 0 Data Transitions, Master Mode

Mode 1: Slave Option HSYNC, BLANK, FIELD

(Timing Register 0 TR $0 =$ X X X X X 0 1 0)

In this mode the ADV7192 accepts Horizontal SYNC and Odd/ Even FIELD signals. A transition of the FIELD input when *HSYNC* is low indicates a new frame, i.e., Vertical Retrace. The *BLANK* signal is optional. When the *BLANK* input is disabled the ADV7192 automatically blanks all normally blank lines as per CCIR-624. Mode 1 is illustrated in Figure 26 (NTSC) and Figure 27 (PAL).

Figure 27. Timing Mode 1, PAL

Mode 1: Master Option HSYNC, BLANK, FIELD

(Timing Register $0 \text{ TR}0 =$ X X X X X 0 1 1)

In this mode the ADV7192 can generate Horizontal SYNC and Odd/Even FIELD signals. A transition of the FIELD input when *HSYNC* is low indicates a new frame i.e., Vertical Retrace. The *BLANK* signal is optional. When the *BLANK* input is disabled the ADV7192 automatically blanks all normally blank lines as per CCIR-624. Pixel data is latched on the rising clock edge following the timing signal transitions. Mode 1 is illustrated in Figure 26 (NTSC) and Figure 27 (PAL). Figure 28 illustrates the *HSYNC*, *BLANK* and FIELD for an odd or even field transition relative to the pixel data.

Figure 28. Timing Mode 1 Odd/Even Field Transitions Master/Slave

Mode 2: Slave Option HSYNC, VSYNC, BLANK

(Timing Register $0 \text{ TR}0 =$ X X X X X 1 0 0)

In this mode the ADV7192 accepts Horizontal and Vertical SYNC signals. A coincident low transition of both *HSYNC* and *VSYNC* inputs indicates the start of an Odd Field. A *VSYNC* low transition when *HSYNC* is high indicates the start of an Even Field. The *BLANK* signal is optional. When the *BLANK* input is disabled the ADV7192 automatically blanks all normally blank lines as per CCIR-624. Mode 2 is illustrated in Figure 29 (NTSC) and Figure 30 (PAL).

Figure 29. Timing Mode 2, NTSC

Figure 30. Timing Mode 2, PAL

Mode 2: Master Option HSYNC,VSYNC , BLANK

(Timing Register $0 \text{ TR}0 = \text{X} \text{X} \text{X} \text{X} \text{X} 1 0 1$)

In this mode the ADV7192 can generate Horizontal and Vertical SYNC signals. A coincident low transition of both *HSYNC* and *VSYNC* inputs indicates the start of an Odd Field. A *VSYNC* low transition when *HSYNC* is high indicates the start of an Even Field. The *BLANK* signal is optional. When the *BLANK* input is disabled the ADV7192 automatically blanks all normally blank lines as per CCIR-624. Mode 2 is illustrated in Figure 29 (NTSC) and Figure 30 (PAL). Figure 31 illustrates the *HSYNC*, *BLANK* and *VSYNC* for an even-to-odd field transition relative to the pixel data. Figure 32 illustrates the *HSYNC*, *BLANK* and *VSYNC* for an odd-to-even field transition relative to the pixel data.

Figure 31. Timing Mode 2, Even-to-Odd Field Transition Master/Slave

Figure 32. Timing Mode 2, Odd-to-Even Field Transition Master/Slave

Mode 3: Master/Slave Option HSYNC, **BLANK**, **FIELD**

(Timing Register 0 TR0 = X X X X X 1 1 0 or X X X X X 1 1 1)

In this mode the ADV7192 accepts or generates Horizontal SYNC and Odd/Even FIELD signals. A transition of the FIELD input when *HSYNC* is high indicates a new frame i.e., Vertical Retrace. The *BLANK* signal is optional. When the *BLANK* input is disabled the ADV7192 automatically blanks all normally blank lines as per CCIR-624. Mode 3 is illustrated in Figure 33 (NTSC) and Figure 34 (PAL).

Figure 34. Timing Mode 3, PAL

MPU PORT DESCRIPTION

The ADV7192 support a two-wire serial $(I²C$ -compatible) microprocessor bus driving multiple peripherals. Two inputs, Serial Data (SDA) and Serial Clock (SCL), carry information between any device connected to the bus. Each slave device is recognized by a unique address. The ADV7192 has four possible slave addresses for both read and write operations. These are unique addresses for each device and are illustrated in Figure 35 and Figure 37. The LSB sets either a read or write operation. Logic Level 1 corresponds to a read operation while Logic Level 0 corresponds to a write operation. A1 is set by setting the ALSB pin of the ADV7192 to Logic Level 0 or Logic Level 1. When ALSB is set to 0, there is greater input bandwidth on the $I²C$ lines, which allows high speed data transfers on this bus. When ALSB is set to 1, there is reduced input bandwidth on the I^2C lines, which means that pulses of less than 50 ns will not pass into the $I²C$ internal controller. This mode is recommended for noisy systems.

Figure 35. Slave Address

To control the various devices on the bus the following protocol must be followed. First, the master initiates a data transfer by establishing a start condition, defined by a high-to-low transition on SDA while SCL remains high. This indicates that an address/ data stream will follow. All peripherals respond to the start condition and shift the next eight bits (7-bit address + R/*W* bit). The bits are transferred from MSB down to LSB. The peripheral that recognizes the transmitted address responds by pulling the data line low during the ninth clock pulse. This is known as an acknowledge bit. All other devices withdraw from the bus at this point and maintain an idle condition. The idle condition is where the device monitors the SDA and SCL lines waiting for the start condition and the correct transmitted address. The R/*W* bit determines the direction of the data.

A Logic 0 on the LSB of the first byte means that the master will write information to the peripheral. A Logic 1 on the LSB of the first byte means that the master will read information from the peripheral.

The ADV7192 acts as a standard slave device on the bus. The data on the SDA pin is eight bits long supporting the 7-bit addresses plus the R/\overline{W} bit. It interprets the first byte as the device address and the second byte as the starting subaddress. The subaddresses autoincrement allowing data to be written to or read from the starting subaddress. A data transfer is always terminated by a stop condition. The user can also access any unique subaddress register on a one-by-one basis without having to update all the registers. There is one exception. The Subcarrier Frequency Registers should be updated in sequence, starting with Subcarrier Frequency Register 0. The autoincrement function should be then used to increment and access Subcarrier Frequency Registers 1, 2, and 3. The Subcarrier Frequency Registers should not be accessed independently.

Stop and start conditions can be detected at any stage during the data transfer. If these conditions are asserted out of sequence with normal read and write operations, then, these cause an immediate jump to the idle condition. During a given SCL high period the user should issue only one start condition, one stop condition, or a single stop condition followed by a single start condition. If an invalid subaddress is issued by the user, the ADV7192 will not issue an acknowledge and will return to the idle condition. If, in autoincrement mode, the user exceeds the highest subaddress, then the following action will be taken:

- 1. In Read Mode, the highest subaddress register contents will continue to be output until the master device issues a no-acknowledge. This indicates the end of a read. A no-acknowledge condition is where the SDA line is not pulled low on the ninth pulse.
- 2. In Write Mode, the data for the invalid byte will be not be loaded into any subaddress register, a no-acknowledge will be issued by the ADV7192 and the part will return to the idle condition.

Figure 36. Bus Data Transfer

Figure 36 illustrates an example of data transfer for a read sequence and the start and stop conditions.

Figure 37 shows bus write and read sequences.

Figure 37. Write and Read Sequences

REGISTER ACCESSES

The MPU can write to or read from all of the registers of the ADV7192 with the exception of the Subaddress Registers which are write only registers. The Subaddress Register determines which register the next read or write operation accesses. All communications with the part through the bus start with an access to the Subaddress Register. Then a read/write operation is performed from/to the target address which then increments to the next address until a stop command on the bus is performed.

REGISTER PROGRAMMING

The following section describes each register. All registers can be read from as well as written to.

Subaddress Register (SR7–SR0)

The Communications Register is an eight bit write-only register. After the part has been accessed over the bus and a read/write operation is selected, the subaddress is set up. The Subaddress Register determines to/from which register the operation takes place.

Figure 38 shows the various operations under the control of the Subaddress Register 0 should always be written to SR7.

Register Select (SR6–SR0)

These bits are set up to point to the required starting address.

SR7	SR6 SR ₅		SR4		SR ₃		SR ₂	SR1 SR ₀
SR7								ADV7192 SUBADDRESS REGISTER
ZERO SHOULD BE WRITTEN	ADDRESS	SR6	SR ₅ SR4	SR3	SR ₂	SR ₁	SR ₀	
HERE	00H 01H	0 0	0 0 0 0	0 0	0 0	0 0	0 1	MODE REGISTER 0 MODE REGISTER 1
	02H	0	0 0	0	0	1	0	MODE REGISTER 2
	03H 04H	0 0	0 0 0 0	0 0	0 1	1 0	1 0	MODE REGISTER 3 MODE REGISTER 4
	05H	0	0 0	0	1	0	1	MODE REGISTER 5
	06H 07H	0 0	0 0 0 0	0 0	1 1	1 1	0 1	MODE REGISTER 6 MODE REGISTER 7
	08H	0	0 0	1	0	0	0	MODE REGISTER 8
	09H 0AH	0 $\mathbf{0}$	0 0 0 0	1 1	0 Ω	0 1	1 0	MODE REGISTER 9 TIMING REGISTER 0
	0BH	0	0 0	1	0	1	1	TIMING REGISTER 1
	0CH 0DH	0 0	O 0 0 0	1 1	1 1	O 0	0 1	SUBCARRIER FREQUENCY REGISTER 0 SUBCARRIER FREQUENCY REGISTER 1
	0EH	0	0 0	1	1	1	0	SUBCARRIER FREQUENCY REGISTER 2
	0FH 10H	Ω 0	O 0 0 1	1 0	1 0	1 0	1 0	SUBCARRIER FREQUENCY REGISTER 3 SUBCARRIER PHASE REGISTER
	11H	0	0 1	0	0	0	1	CLOSED CAPTIONING EXTENDED DATA BYTE 0
	12H 13H	0 0	0 1 0 1	0 0	0 0	1 1	0 1	CLOSED CAPTIONING EXTENDED DATA BYTE 1 CLOSED CAPTIONING DATA BYTE 0
	14H	0	O 1	0	1	O	0	CLOSED CAPTIONING DATA BYTE 1
	15H 16H	0 0	0 1 0 1	0 0	1 1	0 1	1 0	NTSC PEDESTAL/TELETEXT CONTROL REGISTER 0 NTSC PEDESTAL/TELETEXT CONTROL REGISTER 1
	17H	0	0 1	0	1	1	1	NTSC PEDESTAL/TELETEXT CONTROL REGISTER 2
	18H 19H	0 0	0 1 0 1	1 1	0 0	0 O	0 1	NTSC PEDESTAL/TELETEXT CONTROL REGISTER 3 CGMS/WSS 0
	1AH	0	0 1	1	0	1	0	CGMS/WSS1
	1BH 1CH	0 0	0 1 0 1	1 1	0 1	1 0	1 0	CGMS/WSS 2 TELETEXT REQUEST CONTROL REGISTER
	1DH	0	0 1	1	1	0	1	CONTRAST CONTROL REGISTER
	1EH 1FH	0 0	0 1 0 1	1 1	1 1	1 1	0 1	U SCALE REGISTER V SCALE REGISTER
	20H 21H	0 $\mathbf{0}$	1 0 0 1	0 0	0 $\mathbf{0}$	0 O	0 1	HUE ADJUST CONTROL REGISTER BRIGHTNESS CONTROL REGISTER
	22H	0	0 1	0	0	1	0	SHARPNESS RESPONSE REGISTER
	23H 24H	0 0	1 0 0 1	0 0	O 1	1 0	1 0	DNR REGISTER 0 DNR REGISTER 1
	25H	0	1 0	0	1	0	1	DNR REGISTER 2
	26H 27H	$\mathbf{0}$ 0	0 1 0 1	O 0	1 1	1 1	0 1	GAMMA CORRECTION REGISTER 0 GAMMA CORRECTION REGISTER 1
	28H	0	1 0	1	0	0	0	GAMMA CORRECTION REGISTER 2
	29H 2AH	0 0	0 1 1 0	1 1	0 0	0 1	1 0	GAMMA CORRECTION REGISTER 3 GAMMA CORRECTION REGISTER 4
	2BH	Ω	0 1	1	0	1	1	GAMMA CORRECTION REGISTER 5
	2CH 2DH	0 0	1 0 1 0	1 1	1 1	0 0	0 1	GAMMA CORRECTION REGISTER 6 GAMMA CORRECTION REGISTER 7
	2EH	0	0 1	1	1	1	0	GAMMA CORRECTION REGISTER 8
	2FH 30H	0 0	0 1 1 1	1 0	1 0	1 0	1 0	GAMMA CORRECTION REGISTER 9 GAMMA CORRECTION REGISTER 10
	31H	0	1 1	0	0	0	1	GAMMA CORRECTION REGISTER 11
	32H 33H	0 0	1 1 1 1	0 ŋ	0 O	1 1	0 1	GAMMA CORRECTION REGISTER 12 GAMMA CORRECTION REGISTER 13
	34H	0	1 1	0	1	0	0	BRIGHTNESS DETECT REGISTER
	35H 36H	0 0	1 1 1 1	0 0	1 1	0 1	1 0	OUTPUT CLOCK REGISTER RESERVED
	37H 38H	0 Ω	1 1 1 1	0 1	1 Ω	1 Ω	1	RESERVED RESERVED
	39H	0	1 1	1	0	0	0 1	RESERVED
	ЗАН 3BH	0 0	1 1 1 1	1 1	0 0	1 1	0 1	MACROVISION REGISTER MACROVISION REGISTER
	зсн	0	1 1	1	1	0	0	MACROVISION REGISTER
	3DH 3EH	Ω	1 1	1	1 1	0	1	MACROVISION REGISTER MACROVISION REGISTER
	3FH	0 1	1 1 1 1	1 1	1	1 1	0 1	MACROVISION REGISTER
	40H 41 H	1 1	0 0 0 0	0 0	0 0	0 0	0 1	MACROVISION REGISTER MACROVISION REGISTER
	42H	1	0 ŋ	0	ŋ	1	0	MACROVISION REGISTER
	43H 44H	1 1	0 0 0 0	0 0	0 1	1 0	1 0	MACROVISION REGISTER MACROVISION REGISTER
	45H	1	0 0	0	1	0	1	MACROVISION REGISTER
	46H 47H	1 1	0 0 0 0	0 1	1 1	1 1	0 1	MACROVISION REGISTER MACROVISION REGISTER
	48H	1	0 0	1	0	1	0	MACROVISION REGISTER
	49H 4AH	1 1	0 0 0 O	1 1	0 0	0 Ω	1 0	MACROVISION REGISTER MACROVISION REGISTER
	4BH	1	0 0	1	0		1	MACROVISION REGISTER

Figure 38. Subaddress Register for the ADV7192

MODE REGISTER 0

MR0 (MR07–MR00)

(Address (SR4–SR0) = 00H)

Figure 39 shows the various operations under the control of Mode Register 0.

MR0 BIT DESCRIPTION

Output Video Standard Selection Control (MR00–MR01)

These bits are used to set up the encoder mode. The ADV7192 can be set up to output NTSC, PAL (B, D, G, H, I), PAL M or PAL N standard video.

Luminance Filter Select (MR02–MR04)

These bits specify which luma filter is to be selected. The filter selection is made independent of whether PAL or NTSC is selected.

Chrominance Filter Select (MR05–MR07)

These bits select the chrominance filter. A low-pass filter can be selected with a choice of cutoff frequencies (0.65 MHz, 1.0 MHz, 1.3 MHz, 2 MHz, or 3 MHz) along with a choice of CIF or QCIF filters.

MODE REGISTER 1 MR1 (MR17–MR10)

(Address (SR4–SR0) = 01H)

Figure 40 shows the various operations under the control of Mode Register 1.

MR1 BIT DESCRIPTION

DAC Control (MR10–MR15)

Bits MR15–MR10 can be used to power-down the DACs. This are used to reduce the power consumption of the ADV7192 or if any of the DACs are not required in the application.

4 Oversampling Control (MR16)

To enable 4× Oversampling this bit has to be set to 1. When enabled, the data is output at a frequency of 54 MHz.

Note that PLL Enable Control has to be enabled $(MR61 = 0)$ in $4\times$ Oversampling mode. An external V_{REF} is not recommended in that mode.

Reserved (MR17)

A Logical 0 must be written to this bit.

Figure 39. Mode Register 0, MR0

Figure 40. Mode Register 1, MR1

MODE REGISTER 2 MR2 (MR27–MR20) (Address (SR4–SR0) = 02H)

Mode Register 2 is an 8-bit-wide register.

Figure 41 shows the various operations under the control of Mode Register 2.

MR2 BIT DESCRIPTION—RGB/YUV Control (MR20)

This bit enables the output from the DACs to be set to YUV or RGB output video standard.

DAC Output Control (MR21)

This bit controls the output from DACs A, B, and C. When this bit is set to 1, Composite, Luma and Chroma Signals are output from DACs A, B, and C (respectively). When this bit is set to 0, RGB or YUV may be output from these DACs.

SCART Enable Control (MR22)

This bit is used to switch the DAC outputs from SCART to a EUROSCART configuration. A complete table of all DAC output configurations is shown below.

Pedestal Control (MR23)

This bit specifies whether a pedestal is to be generated on the NTSC composite video signal. This bit is invalid when the device is configured in PAL mode.

Square Pixel Control (MR24)

This bit is used to set up square pixel mode. This is available in Slave Mode only. For NTSC, a 24.54 MHz clock must be supplied. For PAL, a 29.5 MHz clock must be supplied. Square pixel operation is not available in 4× Oversampling mode.

Standard I² C Control (MR25)

This bit controls the video standard used by the ADV7192. When this bit is set to 1 the video standard is as programmed in Mode Register 0 (Output Video Standard Selection). When it is set to 0, the ADV7192 is forced into the standard selected by the NTSC_PAL pin. When NTSC_PAL is low, the standard is NTSC, when the NTSC_PAL pin is high, the standard is PAL.

Pixel Data Valid Control (MR26)

After resetting the device this bit has the value 0 and the pixel data input to the encoder is blanked such that a black screen is output from the DACs. The ADV7192 will be set to Master Mode timing. When this bit is set to 1 by the user (via the $I²C$), pixel data passes to the pins and the encoder reverts to the timing mode defined by Timing Register 0.

Sleep Mode Control (MR27)

When this bit is set (1), Sleep Mode is enabled. With this mode enabled, the ADV7192 current consumption is reduced to typically 0.1 μ A. The I²C registers can be written to and read from when the ADV7192 is in Sleep Mode.

When the device is in Sleep Mode and 0 is written to MR27, the ADV7192 will come out of Sleep Mode and resume normal operation. Also, if a *RESET* is applied during Sleep Mode the ADV7192 will come out of Sleep Mode and resume normal operation.

For this to operate Power up in Sleep Mode control has to be enabled (MR60 is set to a Logic 0), otherwise Sleep Mode is controlled by the PAL_NTSC and SCRESET/RTC/TR pins.

Figure 41. Mode Register 2, MR2

NOTE

In Progressive Scan Mode (MR80 = 1) the DAC output configuration is stated in the brackets.

MODE REGISTER 3 MR3 (MR37–MR30)

(Address (SR4–SR0) = 03H)

Mode Register 3 is an 8-bit-wide register. Figure 42 shows the various operations under the control of Mode Register 3.

MR3 BIT DESCRIPTION

Revision Code (MR30–MR31)

This bit is read only and indicates the revision of the device.

VBI Open (MR32)

This bit determines whether or not data in the Vertical Blanking Interval (VBI) is output to the analog outputs or blanked. Note that this condition is also valid in Timing Slave Mode 0. For further information see Vertical Blanking Data Insertion and *BLANK* Input section.

Teletext Enable (MR33)

This bit must be set to 1 to enable teletext data insertion on the TTX pin. Note: TTX functionality is shared with *VSO* and CLAMP on Pin 62. CLAMP/*VSO* Select (MR77) and TTX Input/CLAMP–*VSO* Output (MR76) have to be set accordingly.

Teletext Bit Request Mode Control (MR34)

This bit enables switching of the teletext request signal from a continuous high signal ($MR34 = 0$) to a bitwise request signal $(MR34 = 1).$

Closed Captioning Field Selection (MR35–MR36)

These bits control the fields that closed captioning data is displayed on, closed captioning information can be displayed on an odd field, even field or both fields.

Reserved (MR37)

A Logic 0 must be written to this bit.

MODE REGISTER 4 MR4 (MR47–MR40)

(Address (SR4–SR0) = 04H)

Mode Register 4 is an 8-bit-wide register. Figure 43 shows the various operations under the control of Mode Register 4.

MR4 BIT DESCRIPTION

VSYNC_3H Control (MR40)

When this bit is enabled (1) in Slave Mode, it is possible to drive the *VSYNC* input low for 2.5 lines in PAL mode and three lines in NTSC mode. When this bit is enabled in Master Mode the ADV7192 outputs an active low *VSYNC* signal for three lines in NTSC mode and 2.5 lines in PAL mode.

Genlock Control (MR41–MR42)

These bits control the Genlock feature and timing reset of the ADV7192. Setting MR41 and MR42 to Logic 0 disables the SCRESET/RTC/TR pin and allows the ADV7192 to operate in normal mode.

1. By setting MR41 to zero and MR42 to one, a timing reset is applied, resetting the horizontal and vertical counters. This has the effect of resetting the Field Count to Field 0.

If the SCRESET/RTC/TR pin is held high, the counters will remain reset. Once the pin is released the counters will commence counting again. For correct counter reset, the SCRESET/RTC/TR pin has to remain high for at least 37 ns (one clock cycle at 27 MHz).

- 2. If MR41 is set to one and MR42 is set to zero, the SCRESET/ RTC/TR pin is configured as a subcarrier reset input and the subcarrier phase will reset to Field 0 whenever a low-tohigh transition is detected on the SCRESET/RTC/TR pin (SCH phase resets at the start of the next field).
- 3. If MR41 is set to one and MR42 is set to one, the SCRESET/ RTC/TR pin is configured as a real time control input and the ADV7192 can be used to lock to an external video source working in RTC mode. See Real-Time Control, Subcarrier Reset and Timing Reset section.

Active Video Line Duration (MR43)

This bit switches between two active video line durations. A zero selects CCIR Rec. 601 (720 pixels PAL/NTSC) and a one selects ITU-R BT. 470 standard for active video duration (710 pixels NTSC, 702 pixels PAL).

Chrominance Control (MR44)

This bit enables the color information to be switched on and off the chroma, composite and color component outputs.

Burst Control (MR45)

This bit enables the color burst to be switched on and off the chroma and composite outputs.

Color Bar Control (MR46)

This bit can be used to generate and output an internal color bar test pattern. The color bar configuration is 100/7.5/75/7.5 for NTSC and 100/0/75/0 for PAL. It is important to note that when color bars are enabled the ADV7192 is configured in a Master Timing mode. The output pins *VSYNC*, *HSYNC* and *BLANK* are three-state during color bar mode.

Interlaced Mode Control (MR47)

This bit is used to setup the output to interlaced or noninterlaced mode.

Figure 42. Mode Register 3, MR3

Figure 43. Mode Register 4, MR4

MODE REGISTER 5 MR5 (MR57–MR50)

(Address (SR4–SR0) = 05H)

Mode Register 5 is a 8-bit-wide register. Figure 44 shows the various operations under the control of Mode Register 5.

MR5 BIT DESCRIPTION

Y-Level Control (MR50)

This bit controls the component Y output level on the ADV7192 If this bit is set (0), the encoder outputs Betacam levels when configured in PAL or NTSC mode. If this bit is set (1), the encoder outputs SMPTE levels when configured in PAL or NTSC mode.

UV-Levels Control (MR51–MR52)

These bits control the component U and V output levels on the ADV7192. It is possible to have UV levels with a peak-to-peak amplitude of either 700 mV (MR52 + MR51 = 01) or 1000 mV $(MR52 + MR51 = 10)$ in NTSC and PAL. It is also possible to have default values of 934 mV for NTSC and 700 mV for PAL $(MR52 + MR51 = 00).$

RGB Sync (MR53)

This bit is used to set up the RGB outputs with the sync information encoded on all RGB outputs.

Clamp Delay (MR54–MR55)

These bits control the delay or advance of the CLAMP signal in the front or back porch of the ADV7192. It is possible to delay or advance the pulse by zero, one, two or three clock cycles.

Note: TTX functionality is shared with *VSO* and CLAMP on Pin 62. CLAMP/*VSO* Select (MR77) and TTX Input/CLAMP–*VSO* Output (MR76) have to be set accordingly.

Clamp Delay Direction (MR56)

This bit controls a positive or negative delay in the CLAMP signal. If this bit is set (1), the delay is negative. If it is set (0), the delay is positive.

Clamp Position (MR57)

This bit controls the position of the CLAMP signal. If this bit is set (1), the CLAMP signal is located in the back porch position. If this bit is set (0), the CLAMP signal is located in the front porch position.

Figure 44. Mode Register 5, MR5

MR63 MR60 MR67 MR66 MR65 MR64 MR62 MR61										
MR67 MR66 MR65	MR64 MR63 MR62 ZERO MUST		PLL ENABLE CONTROL		POWER-UP SLEEP MODE CONTROL					
FIELD COUNTER	BE WRITTEN	MR61		MR60						
	TO THESE BITS		ENABLED DISABLED		ENABLED DISABLED					

Figure 45. Mode Register 6, MR6

Mode Register 6 MR6 (MR67–MR60) (Address (SR4–SR0) = 06H)

Mode Register 6 is a 8-bit-wide register. Figure 45 shows the various operations under the control of Mode Register 6.

MR6 BIT DESCRIPTION

Power-Up Sleep Mode Control (MR60)

After $\overline{\text{RESET}}$ is applied this control is enabled ($\text{MR60} = 0$) if both SCRESET/RTC/TR and NTSC_PAL pins are tied high. The ADV7192 will then power up in Sleep Mode to facilitate low power consumption before the I^2C is initialized. When this control is disabled (MR60 = 1, via the I^2C) Sleep Mode control passes to Sleep Mode Control, MR27.

PPL Enable Control (MR61)

The PLL control should be enabled (MR61 = 0) when $4\times$ Oversampling is enabled $(MR16 = 1)$. When this bit is toggled, it is also used to reset the PLL.

Reserved (MR62, MR63, MR64)

A Logical 0 must be written to these bits.

Field Counter (MR65, MR66, MR67)

These three bits are read only bits. The field count can be read back over the I^2C interface. In NTSC mode the field count goes from 0–3, in PAL Mode from 0–7.

MODE REGISTER 7

MR7 (MR77–MR70)

(Address (SR4–SR0) = 07H)

Mode Register 7 is a 8-bit-wide register. Figure 46 shows the various operations under the control of Mode Register 7.

MR7 BIT DESCRIPTION

Color Control Enable (MR70)

This bit is used to enable control of contrast and saturation of color. If this bit is set (1) color controls are enabled (Contrast Control Register, U-Scale Register, V-Scale Register). If this bit is set (0), the color control features are disabled.

Luma Saturation Control (MR71)

When this bit is set (1), the luma signal will be clipped if it reaches a limit that corresponds to an input luma value of 255 (after scaling by the Contrast Control Register). This prevents the chrominance component of the composite video signal being clipped if the amplitude of the luma is too high. When this bit is set (0), this control is disabled.

Hue Adjust Control (MR72)

This bit is used to enable hue adjustment on the composite and chroma output signals of the ADV7192. When this bit is set (1), the hue of the color is adjusted by the phase offset described in the Hue Adjust Control Register. When this bit is set (0), hue adjustment is disabled.

Brightness Enable Control (MR73)

This bit is used to enable brightness control on the ADV7192. The actual brightness level is programmed in the Brightness Control Register. This value or set-up level is added to the scaled Y data. When this bit is set (1), brightness control is enabled. When this bit is set (0), brightness control is disabled.

Sharpness Filter Enable (MR74)

This bit is used to enable the sharpness control of the luminance signal on the ADV7192 (Luma Filter Select has to be set to Extended, $MR04-MR02 = 100$. The various responses of the filter are determined by the Sharpness Control Register. When this bit is set (1), the luma response is altered by the amount described in the Sharpness Control Register. When this bit is set (0), the sharpness control is disabled. See Internal Filter Response section for luma signal responses.

CSO_HSO Output Control (MR75)

This bit is used to determine whether *HSO* or *CSO* TTL output signal is output at the $\overline{CSO$ HSO pin. If this bit is set (1), the *CSO* TTL signal is output. If this bit is set (0), the *HSO* TTL signal is output.

TTX Input/CLAMP–VSO Output (MR76)

This bit controls whether Pin 62 is configured as an output or as an input pin. A 1 selects Pin 62 to be an output for CLAMP or *VSO* functionality. A 0 selects this pin as a TTX input pin.

Figure 46. Mode Register 7, MR7

Figure 47. Mode Register 8, MR8

CLAMP/VSO Select (MR77)

This bit is used to select the functionality of Pin 62. Setting this bit to 1 selects CLAMP as the output signal. A 0 selects *VSO* as the output signal. Since this pin is also shared with the TTX functionality, TTX Input/CLAMP–*VSO* Output has to be set accordingly (MR76).

MODE REGISTER 8

MR8 (MR87–MR80)

(Address (SR4–SR0) = 08H)

Mode Register 8 is an 8-bit-wide register. Figure 47 shows the various operations under the control of Mode Register 8.

MR8 BIT DESCRIPTION

Progressive Scan Control (MR80)

This control enables the progressive scan inputs on pins Y(0)/P8–Y(7)/P15, Y(8)–Y(9), Cr(0)–Cr(9), Cb(0)–Cb(9)*.* To enable this control MR80 has to be set to 1. It is assumed that the incoming *Y* data contains all necessary sync information.

Note: Simultaneous progressive scan input and 16-bit pixel input is not possible.

Reserved (MR81)

A 0 must be written to this bit.

Double Buffer Control (MR82)

Double Buffering can be enabled or disabled on the Contrast Control Register, U Scale Register, V Scale Register, Hue Adjust Control Register, Closed Captioning Register, Brightness Control Register, Gamma Curve Select Bit and the Macrovision Registers. Double Buffer is not available in Master Mode.

16-Bit Pixel Port (MR83)

This bit controls if the ADV7192 is operated in 8-bit or 16-bit mode. In 8-bit mode the input data will be set up on Pins P0–P7. In 16-bit mode the first eight bits are set up on Pin 3–10, with LSB on Pin 3. The second eight bits are set up on Pin 13–20.

Reserved (MR84)

A Logic 0 must be written to this bit.

DNR Enable Control (MR85)

To enable the DNR process this bit has to be set to 1. If this bit is set to other DNR processing is bypassed. For further information on DNR controls see DNR Mode Control section.

Gamma Enable Control (MR86)

To enable the programmable gamma correction this bit has to be set to enabled $(MR86 = 1)$. For further information on Gamma Correction controls see Gamma Correction Registers section.

Gamma Curve Select Control (MR87)

This bit selects which of the two programmable gamma curves is to be used. When setting MR87 to 0, the gamma correction curve selected is Curve A. Otherwise, Curve B is selected. Each curve will have to be programmed by the user. For further information on Gamma Correction controls see Gamma Correction Registers section.

MODE REGISTER 9

MR9 (MR97–MR90) (Address (SR4–SR0) = 09H)

Mode Register 9 is an 8-bit-wide register. Figure 49 shows the various operations under the control of Mode Register 9.

MR9 BIT DESCRIPTION

Undershoot Limiter (MR90–MR91)

This control ensures that no luma video data will go below a programmable level. This prevents any synchronization problems due to luma signals going below the blanking level. Available limit levels are –1.5 IRE, –6 IRE, –11 IRE. Note that this facility is only available in $4 \times$ Oversampling mode (MR16 = 1). When the device is operated in $2 \times$ Oversampling mode (MR16 = 0) or RGB output without RGB sync are selected, the minimum luma level is set in Timing Register 0, TR06 (Min Luma Control).

Black Burst Y DAC (MR92)

It is possible to output a Black Burst signal from the DAC which is selected to be the Luma DAC (MR22, MR21, MR20). This signal can be useful for locking two video sources together using professional video equipment. See also Black Burst Output section.

Black Burst Luma (MR93)

It is possible to output a Black Burst signal from the DAC which is selected to be the Y-DAC (MR22, MR21, MR20). This signal can be useful for locking two video sources together using professional video equipment. See also Black Burst Output section.

Figure 48. Black Burst Signals for PAL and NTSC Standards

Figure 49. Mode Register 9 (MR9)

Chroma Delay Control (MR94–MR95)

The Chroma signal can be delayed by up to 8 clock cycles at 27 MHz using MR94–95. For further information see also Chroma/Luma Delay Section.

TIMING REGISTER 0 (TR07–TR00)

(Address (SR4–SR0) = 0AH)

Figure 50 shows the various operations under the control of Timing Register 0. This register can be read from as well as written to.

TR0 BIT DESCRIPTION

Master/Slave Control (TR00)

This bit controls whether the ADV7192 is in master or slave mode.

Timing Mode Selection (TR01–TR02)

These bits control the timing mode of the ADV7192. These modes are described in more detail in the Video Timing Description section of the data sheet.

BLANK Input Control (TR03)

This bit controls whether the *BLANK* input is used to accept blank signals or whether blank signals are internally generated.

Note: When this input pin is tied high (to 5 V), the input is disabled regardless of the register setting. It, therefore, should be tied low (to Ground) to allow control over the $I²C$ register.

Luma Delay (TR04–TR05)

The luma signal can be delayed by up to 222 ns (or six clock cycles at 27 MHz) using TR04–TR05. For further information see Chroma/Luma Delay section.

Min Luminance Value (TR06)

This bit is used to control the minimum luma output value by the ADV7192 in $2\times$ Oversampling mode and $4\times$ Oversampling mode. When this bit is set to a Logic 1, the luma is limited to 7IRE below the blank level. When this bit is set to (0), the luma value can be as low as the sync bottom level.

Timing Register Reset (TR07)

Toggling TR07 from low to high and low again resets the internal timing counters. This bit should be toggled after power-up, reset or changing to a new timing mode.

TIMING REGISTER 1 (TR17–TR10) (Address (SR4–SR0) = 0BH)

Timing Register 1 is a 8-bit-wide register.

Figure 51 shows the various operations under the control of Timing Register 1. This register can be read from as well written to. This register can be used to adjust the width and position of the master mode timing signals.

TR1 BIT DESCRIPTION

HSYNC Width (TR10–TR11)

These bits adjust the *HSYNC* pulsewidth.

 T_{PCLK} = one clock cycle at 27 MHz.

HSYNC to VSYNC Delay (TR13–TR12)

These bits adjust the position of the *HSYNC* output relative to the VSYNC output.

 T_{PCLK} = one clock cycle at 27 MHz.

HSYNC to VSYNC Rising Edge Delay (TR14–TR15)

When the ADV7192 is in Timing Mode 1, these bits adjust the position of the HSYNC output relative to the VSYNC output rising edge.

 T_{PCLK} = one clock cycle at 27 MHz.

VSYNC Width (TR14–TR15)

When the ADV7192 is configured in Timing Mode 2, these bits adjust the *VSYNC* pulsewidth.

 T_{PCLK} = one clock cycle at 27 MHz.

HSYNC to Pixel Data Adjust (TR16–TR17)

This enables the *HSYNC* to be adjusted with respect to the pixel data. This allows the Cr and Cb components to be swapped.

Figure 50. Timing Register 0

Figure 51. Timing Register 1

This adjustment is available in both master and slave timing modes.

 T_{PCLK} = one clock cycle at 27 MHz.

SUBCARRIER FREQUENCY REGISTERS 3–0 (FSC31–FSC0) (Address (SR4–SR0) = 0CH–0FH)

These 8-bit-wide registers are used to set up the Subcarrier Frequency. The value of these registers are calculated by using the following equation:

Subcarrier Frequency Register =
$$
\frac{(2^{32} - 1) \times f_{SCF}}{f_{CLK}}
$$

Example: *NTSC Mode,* $f_{CLK} = 27 MHz$ *,* $f_{SCF} = 3.5795454 MHz$

$$
Subcarrier Frequency Value = \frac{(2^{32} - 1) \times 3.5795454 \times 10^6}{27 \times 10^6}
$$

Subcarrier Register Value =
$$
21F07C16
$$
 Hex

Figure 52 shows how the frequency is set up by the four registers.

Figure 52. Subcarrier Frequency Registers

SUBCARRIER PHASE REGISTER (FPH7–FPH0) (Address (SR4–SR0) = 10H)

This 8-bit-wide register is used to set up the Subcarrier Phase. Each bit represents 1.41°. For normal operation this register is set to 00Hex.

FPH7 FPH6 FPH5 FPH4 FPH3 FPH2 FPH1 FPH0 SUBCARRIER PHASE REGISTER

Figure 53. Subcarrier Phase Register

CLOSED CAPTIONING EVEN FIELD DATA REGISTER 1–0 (CCD15–CCD0)

(Address (SR4–SR0) = 11–12H)

These 8-bit-wide registers are used to set up the closed captioning extended data bytes on Even Fields. Figure 54 shows how the high and low bytes are set up in the registers.

Figure 54. Closed Captioning Extended Data Register

CLOSED CAPTIONING ODD FIELD DATA REGISTER 1–0 (CED15-CED0) (Subaddress (SR4–SR0) = 13–14H)

These 8-bit-wide registers are used to set up the closed captioning data bytes on Odd Fields. Figure 55 shows how the high and low bytes are set up in the registers.

NTSC PEDESTAL/PAL TELETEXT CONTROL REGISTERS 3–0

(PCE15–0, PCO15–0)/(TXE15–0, TXO15–0) (Subaddress (SR4–SR0) = 15–18H)

These 8-bit-wide registers are used to enable the NTSC pedestal/ PAL Teletext on a line-by-line basis in the vertical blanking interval for both odd and even fields. Figures 56 and 57 show the four control registers. A Logic 1 in any of the bits of these

registers has the effect of turning the Pedestal OFF on the equivalent line when used in NTSC. A Logic 1 in any of the bits of these registers has the effect of turning Teletext ON on the equivalent line when used in PAL.

Figure 56. Pedestal Control Registers

Figure 57. Teletext Control Registers

TELETEXT REQUEST CONTROL REGISTER TC07 (TC07–TC00)

(Address (SR4–SR0) = 1CH)

Teletext Control Register is an 8-bit-wide register. See Figure 58.

TTXREQ Falling Edge Control (TC00–TC03)

These bits control the position of the falling edge of TTXREQ. It can be programmed from zero clock cycles to a maximum of 15 clock cycles. This controls the active window for Teletext data. Increasing this value reduces the amount of Teletext bits below the default of 360. If Bits TC00–TC03 are 00Hex when Bits TC04– TC07 are changed then the falling edge of TTREQ will track that of the rising edge (i.e., the time between the falling and rising edge remains constant).

PCLK = clock cycle at 27 MHz.

TTXREQ Rising Edge Control (TC04–TC07)

These bits control the position of the rising edge of TTXREQ. It can be programmed from zero clock cycles to a maximum of 15 clock cycles.

PCLK = clock cycle at 27 MHz.

CGMS_WSS REGISTER 0 C/W0 (C/W07–C/W00)

(Address (SR4–SR0) = 19H)

CGMS_WSS register 0 is an 8-bit-wide register. Figure 59 shows the operations under control of this register.

C/W0 BIT DESCRIPTION

CGMS Data Bits (C/W00–C/W03)

These four data bits are the final four bits of CGMS data output stream. Note it is CGMS data ONLY in these bit positions, i.e., WSS data does not share this location.

CGMS CRC Check Control (C/W04)

When this bit is enabled (1), the last six bits of the CGMS data, i.e., the CRC check sequence, is internally calculated by the ADV7192. If this bit is disabled (0) the CRC values in the register are output to the CGMS data stream.

CGMS Odd Field Control (C/W05)

When this bit is set (1), CGMS is enabled for odd fields. Note this is only valid in NTSC mode.

CGMS Even Field Control (C/W06)

When this bit is set (1), CGMS is enabled for even fields. Note this is only valid in NTSC mode.

WSS Control (C/W07)

When this bit is set (1), wide screen signalling is enabled. Note this is only valid in PAL mode.

CGMS_WSS REGISTER 1 C/W1 (C/W17–C/W10) (Address (SR4–SR0) = 1AH)

CGMS_WSS register 1 is an 8-bit-wide register. Figure 60 shows the operations under control of this register.

C/W1 BIT DESCRIPTION

CGMS/WSS Data (C/W10–C/W15)

These bit locations are shared by CGMS data and WSS data. In NTSC mode these bits are CGMS data. In PAL mode these bits are WSS data.

	C/W07		C/W06		C/W05		C/W04	C/W03	C/W02	C/W01	C/W00
		WSS CONTROL			CONTROL	CGMS ODD FIELD				$C/W03 - C/W00$	
C/W07	C/W05									CGMS DATA BITS	
ŋ		DISABLE ENABLE		O		DISABLE ENABLE					
	CGMS EVEN FIELD CONTROL						CGMS CRC CHECK CONTROL				
		C/W06				C/W04					
		DISABLE 0 ENABLE				ŋ	DISABLE ENABLE				

Figure 59. CGMS_WSS Register 0

CGMS Data (C/W16–C/W17)

These bits are CGMS data bits only.

Figure 60. CGMS_WSS Register 1

CGMS_WSS REGISTER 2 C/W1 (C/W27–C/W20) (Address (SR4–SR0) = 1BH)

CGMS_WSS Register 2 is an 8-bit-wide register. Figure 61 shows the operations under control of this register.

C/W2 BIT DESCRIPTION

CGMS/WSS Data (C/W20–C/W27)

These bit locations are shared by CGMS data and WSS data. In NTSC mode these bits are CGMS data. In PAL mode these bits are WSS data.

C/W27	C/W26	C/W25	C/W24	C/W23	C/W22	C/W21	C/W20
				$C/W27 - C/W20$			
				CGMS/WSS DATA			

Figure 61. CGMS_WSS Register 2

CONTRAST CONTROL REGISTER (CC00–CC07) (Address (SR4–SR0) = 1DH)

The contrast control register is an 8-bit-wide register used to scale the Y output levels. Figure 62 shows the operation under control of this register.

Y Scale Value (CC00–CC07)

These eight bits represent the value required to scale the Y pixel data from 0.0 to 1.5 of its initial level. The value of these eight bits is calculated using the following equation:

$$
Y
$$
 Scale Value = Scale Factor \times 128

Example:

Scale Factor = 1.18

Y Scale Value = $1.18 \times 128 = 151.04$

Y Scale Value = 151 (rounded to the nearest integer)

Y Scale Value = 10010111_b

Y Scale Value = 97_h

Figure 62. Contrast Control Register

COLOR CONTROL REGISTERS 1–2 (CC1–CC2) (Address (SR4–SR0) = 1EH–1FH)

The color control registers are 8-bit-wide registers used to scale the U and V output levels. Figure 63 shows the operations under control of these registers.

Figure 63. Color Control Registers

CC1 BIT DESCRIPTION

U Scale Value (CC10–CC17)

These eight bits represent the value required to scale the U level from 0.0 to 2.0 of its initial level. The value of these eight bits is calculated using the following equation:

$$
U
$$
 Scale Value = Scale Factor × 128

Example:

Scale Factor = 1.18

U Scale Value = $1.18 \times 128 = 151.04$

U Scale Value = 151 (rounded to the nearest integer)

U Scale Value = 10010111_b

U Scale Value = 97_h

CC2 BIT DESCRIPTION

V Scale Value (CC20–CC27)

These eight bits represent the value required to scale the V pixel data from 0.0 to 2.0 of its initial level. The value of these eight bits is calculated using the following equation:

V Scale Value = *Scale Factor* × 128

Example:

Scale Factor = 1.18

- V Scale Value = $1.18 \times 128 = 151.04$
- V Scale Value = 151 (rounded to the nearest integer)
- V Scale Value = 10010111_b
- V Scale Value = 97_h

HUE ADJUST CONTROL REGISTER (HCR)

(Address (SR5–SR0) = 20H)

The hue control register is an 8-bit-wide register used to adjust the hue on the composite and chroma outputs. Figure 64 shows the operation under control of this register.

HCR7	HCR6	HCR ₅	HCR4	HCR3	HCR ₂	HCR ₁	HCR ₀
				HCR7 - HCR0			
				HUE ADJUST VALUE			

Figure 64. Hue Control Register

HCR BIT DESCRIPTION

Hue Adjust Value (HCR0–HCR7)

These eight bits represent the value required to vary the hue of the video data, i.e., the variance in phase of the subcarrier during active video with respect to the phase of the subcarrier during the colorburst. The ADV7192 provides a range of $\pm 22.5^{\circ}$ increments of 0.17578125°. For normal operation (zero adjustment), this register is set to 80Hex. FFHex and 00Hex represent the upper and lower limit (respectively) of adjustment attainable.

Hue Adjust [°] = $0.17578125^{\circ} \times (HCR_d - 128)$; for positive Hue Adjust Value

Example:

To adjust the hue by 4° write 97_h to the Hue Adjust Control Register:

 $(4/0.17578125) + 128 = 151_d * = 97_h$

To adjust the hue by (-4°) write 69_h to the Hue Adjust Control Register:

 $(-4/0.17578125) + 128 = 105_d * = 69_h$

*Rounded to the nearest integer.

EXAMPLE

1. Standard: NTSC with Pedestal. To add 20 IRE brightness level write 28_h into the Brightness Control Register:

 $[Brightness Control Register Value]$ ^{*h*} = [*IRE Value* \times 2.015631]^{*h*} = [20 \times 2.015631]^{*h*} = [40.31262]^{*h*} = 28*h*

2. Standard: PAL. To add -7 IRE brightness level write 72_h into the Brightness Control Register:

 $[|IRE Value| \times 2.015631] = [7 \times 2.015631] = [14.109417] = 0001110_b$

[0001110] *into two's complement* = 1110010_b = 72_h

Figure 65. Brightness Control Register

BRIGHTNESS CONTROL REGISTER (BCR)

(Address (SR5–SR0) = 21H)

The brightness control register is an 8-bit-wide register which allows brightness control. Figure 65 shows the operation under control of this register.

BCR BIT DESCRIPTION

Brightness Value (BCR0–BCR6)

Seven bits of this 8-bit-wide register are used to control the brightness level. The brightness is controlled by adding a programmable setup level onto the scaled Y data. This brightness level can be a positive or negative value.

The programmable brightness levels in NTSC, without pedestal, and PAL are max 15 IRE and min –7.5 IRE, in NTSC pedestal max 22.5 IRE and min 0 IRE.

NOTE

Values in the range from $3F_h$ to 44_h might result in an invalid output signal.

SHARPNESS RESPONSE REGISTER (PR)

(Address (SR5–SR0) = 22H)

The sharpness response register is an 8-bit-wide register. The four MSBs are set to 0. The four LSBs are written to in order to select a desired filter response. Figure 66 shows the operation under control of this register.

PR BIT DESCRIPTION

Sharpness Response Value (PR3–PR0)

These four bits are used to select the desired luma filter response. The option of twelve responses is given supporting a gain boost/ attenuation in the range -4 dB to $+4$ dB. The value 12 (1100) written to these four bits corresponds to a boost of +4 dB while the value $0(0000)$ corresponds to -4 dB. For normal operation these four bits are set to 6 (0110). Note: Luma Filter Select has to be set to Extended Mode and Sharpness Filter Control has to be enabled for settings in the Sharpness Control Register to take effect (MR02–04 = 100; MR74 = 1).

Reserved (PR4–PR7)

A Logical 0 must be written to these bits.

Figure 66. Sharpness Response Register

DNR REGISTERS 2–0

(DNR2–DNR0)

(Address (SR5–SR0) = 23H–25H)

The Digital Noise Reduction Registers are three 8-bit-wide register. They are used to control the DNR processing. See Digital Noise Register section.

Coring Gain Border (DNR00–DNR03)

These four bits are assigned to the gain factor applied to border areas.

In DNR Mode the range of gain values is 0–1, in increments of 1/8. This factor is applied to the DNR filter output which lies below the set threshold range. The result is then subtracted from the original signal.

In DNR Sharpness Mode the range of gain values is 0–0.5, in increments of 1/16. This factor is applied to the DNR filter output which lies above the threshold range.

The result is added to the original signal.

Coring Gain Data (DNR04–DNR07)

These four bits are assigned to the gain factor applied to the luma data inside the MPEG pixel block.

In DNR Mode the range of gain values is 0–1, in increments of 1/8. This factor is applied to the DNR filter output which lies below the set threshold range. The result is then subtracted from the original signal.

In DNR Sharpness Mode the range of gain values is 0–0.5, in increments of 1/16. This factor is applied to the DNR filter output which lies above the threshold range. The result is added to the original signal.

Figures 67 and 68 show the various operations under the control of DNR Register 0.

DNR07		DNR06		DNR05		DNR04	(DNR03)		$($ DNR02 $)$		DNR01		DNR00
				CORING GAIN DATA							CORING GAIN BORDER		
		DNR DNR DNR DNR									DNR DNR DNR DNR		
	07	06	05	04				03	02	01	00		
	0	0	n	0				O	0	0	0		
	0	0	ŋ		$+1/16$			ŋ	O	0		$+1/16$	
	0	0		0	$+2/16$			0	0		0	$+2/16$	
	0	O			$+3/16$			0				$+3/16$	
	0		ŋ	0	$+4/16$			O		ŋ	0	$+4/16$	
	0				$+5/16$			0		0		$+5/16$	
	0			0	$+6/16$			0			0	$+6/16$	
	0				$+7/16$			ŋ				$+7/16$	
		ŋ	n	0	$+8/16$				0	0	0	$+8/16$	

Figure 67. DNR Register 0 in DNR Sharpness Mode

DNR07			DNR06	DNR05		DNR04	DNR03			DNR02	DNR01		DNR00	
				CORING GAIN DATA							CORING GAIN BORDER			
				DNR DNR DNR DNR							DNR DNR DNR DNR			
	07	06	05	04				03	02	01	00			
	0	Ω	0	0	0			0	n	0	0			
	0	0	0		$-1/8$			ŋ	0	0		-1/8		
	0	0		O	$-2/8$				0		0	-2/8		
	0	0			$-3/8$							$-3/8$		
	0		n	n	$-4/8$					0	ŋ	-4/8		
	0		n		$-5/8$					O		-5/8		
	0			n	$-6/8$						ŋ	-6/8		
	ŋ				$-7/8$							$-7/8$		
		0	n	0	-1				ŋ	0		-1		

Figure 68. DNR Register 0 in DNR Mode

DNR1 BIT DESCRIPTION

DNR Threshold (DNR10–DNR15)

These six bits are used to define the threshold value in the range of 0 to 63. The range is an absolute value.

Border Area (DNR16)

In setting DNR16 to a Logic 1 the block transition area can be defined to consist of four pixels. If this bit is set to a Logic 0 the border transition area consists of two pixels, where one pixel refers to two clock cycles at 27 MHz.

Block Size Control (DNR17)

This bit is used to select the size of the data blocks to be processed (see Figure 69). Setting the block size control function to a Logic 1 defines a 16×16 pixel data block, a Logic 0 defines an 8×8 pixel data block, where one pixel refers to two clock cycles at 27 MHz.

Figure 69. MPEG Block Diagram

Figure 70. DNR Register 1

DNR2 BIT DESCRIPTION

DNR Input Select (DNR20–DNR22)

Three bits are assigned to select the filter which is applied to the incoming Y data. The signal which lies in the passband of the selected filter is the signal which will be DNR processed. Figure 71 shows the filter responses selectable with this control.

DNR Mode Control (DNR23)

This bit controls the DNR mode selected. A Logic 0 selects DNR mode, a Logic 1 selects DNR Sharpness mode.

DNR works on the principle of defining low amplitude, highfrequency signals as probable noise and subtracting this noise from the original signal.

In DNR mode, it is possible to subtract a fraction of the signal which lies below the set threshold, assumed to be noise, from the original signal. The threshold is set in DNR Register 1.

When DNR Sharpness mode is enabled it is possible to add a fraction of the signal which lies above the set threshold to the original signal, since this data is assumed to be valid data and not noise. The overall effect being that the signal will be boosted (similar to using Extended SSAF Filter).

Figure 71. Filter Response of Filters Selectable

Figure 72. Block Diagram for DNR Mode and DNR Sharpness Mode

Block Offset (DNR24–DNR27)

Four bits are assigned to this control which allows a shift of the data block of 15 pixels maximum. Consider the coring gain positions fixed. The block offset shifts the data in steps of one pixel such that the border coring gain factors can be applied at the same position regardless of variations in input timing of the data.

Figure 73. DNR27–DNR24 Block Offset Control

Figure 74. DNR Register 2

GAMMA CORRECTION REGISTERS 0–13 (GAMMA CORRECTION 0–13)

(Address (SR5–SR0) = 26H–32H)

The Gamma Correction Registers are fourteen 8-bit wide register. They are used to program the gamma correction Curves A and B.

Generally gamma correction is applied to compensate for the nonlinear relationship between signal input and brightness level output (as perceived on the CRT). It can also be applied wherever nonlinear processing is used.

Gamma correction uses the function:

$$
Signal_{OUT} = (Signal_{IN})^{\gamma}
$$

where

$$
\gamma
$$
 = gamma power factor

Gamma correction is performed on the luma data only. The user has the choice to use two different curves, Curve A or Curve B. At any one time only one of these curves can be used.

The response of the curve is programmed at seven predefined locations. In changing the values at these locations the gamma curve can be modified. Between these points linear interpolation is used to generate intermediate values. Considering the curve to have a total length of 256 points, the seven locations are at: 32, 64, 96, 128, 160, 192, and 224.

Location 0, 16, 240 and 255 are fixed and can not be changed.

For the length of 16 to 240 the gamma correction curve has to be calculated as below:

 $y = x^{\gamma}$

y = gamma corrected output

 $x =$ linear input signal

 $γ =$ gamma power factor

To program the gamma correction registers, the seven values for y have to be calculated using the following formula:

$$
y_n = \left[x_{(n-16)} / (240 - 16) \right]^\gamma \times (240 - 16) + 16
$$

where

where

- $x_{(n-16)}$ = Value for x along x-axis at points n = 32, 64, 96, 128, 160, 192, or 224
- y_n = Value for y along the y-axis, which has to be written into the gamma correction register

Example:

 y_{32} = $[(16/224)^{0.5} \times 224]$ + 16 = 76^{*} $y_{64} = [(48/224)^{0.5} \times 224] + 16 = 120*$

REV. A $-43-$

 y_{96} = $[(80/224)^{0.5} \times 224] + 16 = 150*$ $y_{128} = [(112/224)^{0.5} \times 224] + 16 = 174*$

*Rounded to the nearest integer.

The above will result in a gamma curve shown below, assuming a ramp signal as an input.

Figure 75. Signal Input (Ramp) and Signal Output for Gamma 0.5

Figure 76. Signal Input (Ramp) and Selectable Gamma Output Curves

The gamma curves shown above are examples only, any user defined curve is acceptable in the range of 16–240.

BRIGHTNESS DETECT REGISTER

(Address (SR5–SR0) = 34H)

The Brightness Detect Register is an 8-bit-wide register used only to read back data in order to monitor the brightness/darkness of the incoming video data on a field-by-field basis. The brightness information is read from the I^2C and based on this information, the color controls or the gamma correction controls may be adjusted.

The luma data is monitored in the active video area only. The average brightness I^2C register is updated on the falling edge of every *VSYNC* signal.

OUTPUT CLOCK REGISTER (OCR 9–0) (Address (SR4–SR0) = 35H)

The Output Clock Register is an 8-bit-wide register. Figure 76 shows the various operations under the control of this register.

OCR BIT DESCRIPTION

Reserved (OCR00)

A Logic 0 must be written to this bit.

CLKOUT Pin Control (OCR01)

This bit enables the CLKOUT pin when set to 1 and, therefore, outputs a 54 MHz clock generated by the internal PLL. The PLL and $4 \times$ Oversampling have to be enabled for this control to take effect, $(MR61 = 0; MR16 = 1)$.

Reserved (OCR02–03)

A Logic 0 must be written to this bit.

Reserved (OCR04–06)

A Logic 1 must be written to these bits.

Reserved (OCR07)

A Logic 0 must be written to this bit.

Figure 77. Output Clock Register

APPENDIX 1

BOARD DESIGN AND LAYOUT CONSIDERATIONS

The ADV7192 is a highly integrated circuit containing both precision analog and high-speed digital circuitry. It has been designed to minimize interference effects on the integrity of the analog circuitry by the high-speed digital circuitry. It is imperative that these same design and layout techniques be applied to the system level design such that high-speed, accurate performance is achieved. The Recommended Analog Circuit Layout shows the analog interface between the device and monitor.

The layout should be optimized for lowest noise on the ADV7192 power and ground lines by shielding the digital inputs and providing good decoupling. The lead length between groups of V_{AA} and AGND and V_{DD} and DGND pins should by minimized so as to minimize inductive ringing.

Ground Planes

The ground plane should encompass all ADV7192 ground pins, voltage reference circuitry, power supply bypass circuitry for the ADV7192, the analog output traces, and all the digital signal traces leading up to the ADV7192. This should be as substantial as possible to maximize heat spreading and power dissipation on the board.

Power Planes

The ADV7192 and any associated analog circuitry should have its own power plane, referred to as the analog power plane (V_{AA}) . This power plane should be connected to the regular PCB power plane (V_{CC}) at a single point through a ferrite bead. This bead should be located within three inches of the ADV7192.

The metallization gap separating device power plane and board power plane should be as narrow as possible to minimize the obstruction to the flow of heat from the device into the general board.

The PCB power plane should provide power to all digital logic on the PC board, and the analog power plane should provide power to all ADV7192 power pins and voltage reference circuitry.

Plane-to-plane noise coupling can be reduced by ensuring that portions of the regular PCB power and ground planes do not overlay portions of the analog power plane, unless they can be arranged such that the plane-to-plane noise is common-mode.

Supply Decoupling

For optimum performance, bypass capacitors should be installed using the shortest leads possible, consistent with reliable operation, to reduce the lead inductance. Best performance is obtained with 0.1 μ F ceramic capacitor decoupling. Each group of V_{AA} pins on the ADV7192 must have at least one 0.1 µF decoupling capacitor to AGND. The same applies to groups of V_{DD} and DGND. These capacitors should be placed as close as possible to the device.

It is important to note that while the ADV7192 contains circuitry to reject power supply noise, this rejection decreases with frequency. If a high frequency switching power supply is used, the designer should pay close attention to reducing power supply noise and consider using a three-terminal voltage regulator for supplying power to the analog power plane.

Digital Signal Interconnect

The digital inputs to the ADV7192 should be isolated as much as possible from the analog outputs and other analog circuitry. Also, these input signals should not overlay the analog power plane.

Due to the high clock rates involved, long clock lines to the ADV7192 should be avoided to reduce noise pickup.

Any active termination resistors for the digital inputs should be connected to the regular PCB power plane (V_{CC}) , and not the analog power plane.

Analog Signal Interconnect

The ADV7192 should be located as close as possible to the output connectors to minimize noise pickup and reflections due to impedance mismatch.

The video output signals should overlay the ground plane, and not the analog power plane, to maximize the high frequency power supply rejection.

Digital inputs, especially pixel data inputs and clocking signals should never overlay any of the analog signal circuitry and should be kept as far away as possible.

For best performance, the outputs should each have a 300 Ω load resistor connected to AGND. These resistors should be placed as close as possible to the ADV7192 so as to minimize reflections.

The ADV7192 should have no inputs left floating. Any inputs that are not required should be tied to ground.

Figure 78. Recommended Analog Circuit Layout

APPENDIX 2 CLOSED CAPTIONING

The ADV7192 supports closed captioning conforming to the standard television synchronizing waveform for color transmission. Closed captioning is transmitted during the blanked active line time of Line 21 of the odd fields and Line 284 of even fields.

Closed captioning consists of a seven-cycle sinusoidal burst that is frequency and phase locked to the caption data. After the clock run-in signal, the blanking level is held for two data bits and is followed by a Logic Level 1 start bit. Sixteen bits of data follow the start bit. These consist of two eight-bit bytes, seven data bits, and one odd parity bit. The data for these bytes is stored in Closed Captioning Data Registers 0 and 1.

The ADV7192 also supports the extended closed captioning operation which is active during even fields and is encoded on Scan Line 284. The data for this operation is stored in Closed Captioning Extended Data Registers 0 and 1.

All clock run-in signals and timing to support Closed Captioning on Lines 21 and 284 are generated automatically by the ADV7192 All pixels inputs are ignored during Lines 21 and 284 if closed captioning is enabled.

FCC Code of Federal Regulations (CFR) 47 Section 15.119 and EIA608 describe the closed captioning information for Lines 21 and 284.

The ADV7192 uses a single buffering method. This means that the closed captioning buffer is only one byte deep, therefore, there will be no frame delay in outputting the closed captioning data unlike other two byte deep buffering systems. The data must be loaded one line before (Line 20 or Line 283) it is outputted on Line 21 and Line 284. A typical implementation of this method is to use *VSYNC* to interrupt a microprocessor, which in turn will load the new data (two bytes) every field. If no new data is required for transmission, 0s must be inserted in both data registers, this is called NULLING. It is also important to load *control codes* all of which are double bytes on Line 21 or a TV will not recognize them. If there is a message like *Hello World* which has an odd number of characters, it is important to pad it out to even in order to get *end of caption* 2-byte control code to land in the same field.

Figure 79. Closed Captioning Waveform (NTSC)

APPENDIX 3

COPY GENERATION MANAGEMENT SYSTEM (CGMS)

The ADV7192 supports Copy Generation Management System (CGMS) conforming to the standard. CGMS data is transmitted on Line 20 of the odd fields and Line 283 of even fields. Bits C/W05 and C/W06 control whether or not CGMS data is outputed on ODD and EVEN fields. CGMS data can only be transmitted when the ADV7192 is configured in NTSC mode. The CGMS data is 20 bits long, the function of each of these bits is as shown below. The CGMS data is preceded by a reference pulse of the same amplitude and duration as a CGMS bit, see Figure 79. These bits are outputed from the configuration registers in the following order: $C/W00 = C16$, $C/W01 = C17$, $C/W02 = C18$, $C/W03 = C19$, $C/W10 = C8$, $C/W11 = C9$, $C/W12 = C10$, $C/W13 = C11$, $C/W14 = C12$, $C/W15 = C13$, $C/W16 = C14$, $C/W17 = C15$, $C/W20 = C0$, $C/W21 = C1$, $C/W22 = C2$, $C/W23 = C3$, $C/W24 = C4$, $C/W25 = C5$, $C/W26 = C6$, $C/W27 = C7$. If the bit $C/W04$ is set to a Logic 1, the last six bits C19–C14 which comprise the 6-bit CRC check sequence are calculated automatically on the ADV7192 based on the lower 14 bits (C0–C13) of the data in the data registers and output with the remaining 14-bits to form the complete 20-bits of the CGMS data. The calculation of the CRC sequence is based on the polynomial $X^6 + X + 1$ with a preset value of 111111. If C/W04 is set to a Logic 0 then all 20-bits (C0–C19) are output directly from the CGMS registers (no CRC calculated, must be calculated by the user).

Function of CGMS Bits

Figure 80. CGMS Waveform Diagram

APPENDIX 4

WIDE SCREEN SIGNALING

The ADV7192 supports Wide Screen Signaling (WSS) conforming to the standard. WSS data is transmitted on Line 23. WSS data can only be transmitted when the ADV7192 is configured in PAL mode. The WSS data is 14-bits long, the function of each of these bits is as shown below. The WSS data is preceded by a run-in sequence and a Start Code, see Figure 80. The bits are output from the configuration registers in the following order: $C/W20 = W0$, $C/W21 = W1$, $C/W22 = W2$, $C/W23 = W3$, $C/W24 = W4$, $C/W25 = W5$, $C/W26 = W6$, $C/W27 = W7$, $C/W10 = W8$, $C/W11 = W9$, $C/W12 = W10$, $C/W13 = W11$, $C/W14 = W12$, $C/W15 = W13$. If the bit $C/W07$ is set to a Logic 1, it enables the WSS data to be transmitted on Line 23. The latter portion of Line 23 (42.5 µs from the falling edge of *HSYNC*) is available for the insertion of video.

Function of CGMS Bits

- B4
- 0 Camera Mode
- 1 Film Mode
- $B₅$
- 0 Standard Coding
- 1 Motion Adaptive Color Plus
- B6
- 0 No Helper
- 1 Modulated Helper
- B7 RESERVED
- B9 B10
- 0 0 No Open Subtitles
- 1 0 Subtitles in Active Image Area
- 0 1 Subtitles Out of Active Image Area
- 1 1 RESERVED
- B11
- 0 No Surround Sound Information
- 1 Surround Sound Mode
- B12 RESERVED
- B13 RESERVED

Figure 81. WSS Waveform Diagram

APPENDIX 5

TELETEXT INSERTION

Time, t_{PD} , is the time needed by the ADV7192 to interpolate input data on TTX and insert it onto the CVBS or Y outputs, such that it appears $t_{SYNTTXOUT}$ = 10.2 µs after the leading edge of the horizontal signal. Time TTX_{DEL} is the pipeline delay time by the source that is gated by the TTXREQ signal in order to deliver TTX data.

With the programmability that is offered with TTXREQ signal on the Rising/Falling edges, the TTX data is always inserted at the correct position of 10.2 µs after the leading edge of Horizontal Sync pulse, thus this enables a source interface with variable pipeline delays.

The width of the TTXREQ signal must always be maintained such that it allows the insertion of 360 (in order to comply with the Teletext Standard PAL-WST) teletext bits at a text data rate of 6.9375 Mbits/s, this is achieved by setting TC03–TC00 to 0. The insertion window is not open if the Teletext Enable bit (MR33) is set to 0.

Teletext Protocol

The relationship between the TTX bit clock (6.9375 MHz) and the system CLOCK (27 MHz) for 50 Hz is given as follows:

$$
(27 MHz/4) = 6.75 MHz
$$

$$
(6.9375 \times 10^{6}/6.75 \times 10^{6} = 1.027777
$$

Thus 37 TTX bits correspond to 144 clocks (27 MHz), each bit has a width of almost four clock cycles. The ADV7192 uses an internal sequencer and variable phase interpolation filter to minimize the phase jitter and thus generate a bandlimited signal which can be output on the CVBS and Y outputs.

At the TTX input the bit duration scheme repeats after every 37 TTX bits or 144 clock cycles. The protocol requires that TTX Bits 10, 19, 28, 37 are carried by three clock cycles, all other bits by four clock cycles. After 37 TTX bits, the next bits with three clock cycles are Bits 47, 56, 65, and 74. This scheme holds for all following cycles of 37 TTX bits, until all 360 TTX bits are completed. All teletext lines are implemented in the same way. Individual control of teletext lines are controlled by Teletext Setup Registers.

Figure 82. Teletext VBI Line

Figure 83. Teletext Functionality Diagram

APPENDIX 6 OPTIONAL OUTPUT FILTER

If an output filter is required for the CVBS, Y, UV, Chroma and RGB outputs of the ADV7192, the following filter in Figure 84 can be used in $2 \times$ Oversampling Mode. In $4 \times$ Oversampling Mode the filter in Figure 86 is recommended. The plot of the filter characteristics are shown in Figures 85 and 87. An output filter

22H 68pF 22pF 56pF 22H FILTER I/P \rightarrow \overline{m} \rightarrow \overline{m} \rightarrow \overline{m} \rightarrow \overline{m} \rightarrow \overline{m} \rightarrow FILTER O/P **6.8H** $600\Omega \pm$ 22pF \pm 68pF \pm 56pF \leq 600 Ω

Figure 84. Output Filter for $2x$ Oversampling Mode

Figure 85. Output Filter Plot for $2\times$ Oversampling Filter

is not required if the outputs of the ADV7192 are connected to most analog monitors or TVs, however, if the output signals are applied to a system where sampling is used, (e.g., Digital TVs) then a filter is required to prevent aliasing.

Figure 86. Output Filter for 4× Oversampling Mode

Figure 87. Output Filter Plot for 4× Oversampling Filter

Figure 88. Output Filter Requirements in 4× Oversampling Mode

APPENDIX 7

DAC BUFFERING

External buffering is needed on the ADV7192 DAC outputs. The configuration in Figure 89 is recommended.

When calculating absolute output full-scale current and voltage use the following equations:

$$
V_{OUT} = I_{OUT} \times R_{LOAD}
$$

$$
I_{OUT} = (V_{REF} \times K)/R_{SET}
$$

$$
K = 4.2146 constant, V_{REF} = 1.235 V
$$

Figure 89. Output DAC Buffering Configuration

Figure 90. Recommended DAC Output Buffer Using an Op Amp

APPENDIX 8

RECOMMENDED REGISTER VALUES

The ADV7192 registers can be set depending on the user standard required. The following examples give the various register formats for several video standards.

NTSC (F_{SC} = 3.5795454 MHz)

PAL B, D, G, H, I (F_{SC} = 4.43361875 MHz)

PAL N (F_{SC} = 4.43361875 MHz)

PAL 60 (F_{SC} = 4.43361875 MHz)

PAL M (F_{SC} = 3.57561149 MHz)

POWER-ON RESET REGISTER VALUES

POWER-ON RESET REG VALUES (PAL_NTSC = 0, NTSC Selected)

POWER-ON RESET REG VALUES (PAL_NTSC = 1, PAL Selected)

APPENDIX 9 NTSC WAVEFORMS (WITH PEDESTAL)

Figure 94. NTSC RGB Video Levels

NTSC WAVEFORMS (WITHOUT PEDESTAL)

PAL WAVEFORMS

VIDEO MEASUREMENT PLOTS

Figure 104. PAL Color Bar Measurement

Figure 105. NTSC DG DP Measurement

Figure 109. NTSC Chrominance Nonlinearity

CHROMINANCE AM/PM (NTSC) WFM RED FIELD FIELD = 2, LINE = 217

–95 –90 –85 –80 –75 –70 –65 –60

PM NOISE –82.7dB RMS

AM NOISE –86.5dB RMS

BANDWIDTH 10kHz TO 100kHz

–95 –90 –85 –80 –75 –70 –65 –60

(0dB = 714mV p-p WITH AGC FOR 100% CHROMINANCE LEVEL)

Figure 110. NTSC Chrominance AM/PM

Figure 112. PAL Chrominance AM/PM

dB RMS

dB RMS

Figure 113. NTSC Noise Spectrum: Pedestal

Figure 114. NTSC Noise Spectrum: Ramp

Figure 116. PAL Noise Spectrum: Ramp

UV WAVEFORMS

Figure 117. NTSC 100% Color Bars No Pedestal U Levels

Figure 118. NTSC 100% Color Bars with Pedestal U Levels

Figure 120. NTSC 100% Color Bars No Pedestal V Levels

Figure 121. NTSC 100% Color Bars with Pedestal V

Figure 122. PAL 100% Color Bars V Levels

OUTPUT WAVEFORMS

Figure 124. 100/0/75/0 PAL Color Bars Luminance

Figure 127. 100/7.5/75/7.5 NTSC Color Bars Luminance

Figure 128. 100/7.5/75/7.5 NTSC Color Bars Chrominance

APPENDIX 10 VECTOR PLOTS

OUTLINE DIMENSIONS

Dimensions shown in inches and (mm).

C00229-0-12/00 (rev. A) C00229–0–12/00 (rev. A)