## FEATURES

## RS-485 transceiver with electrical data isolation Complies with ANSI TIA/EIA-485-A and ISO 8482: 1987(E)

500 kbps data rate
Slew rate-limited driver outputs
Low power operation: $\mathbf{2 . 5} \mathbf{~ m A}$ maximum
Suitable for 5 V or 3.3 V operations (VDD1)
High common-mode transient immunity: > $\mathbf{2 5} \mathbf{~ k V / \mu s}$
True fail-safe receiver inputs
Chatter-free power-up/power-down protection 256 nodes on bus
Thermal shutdown protection
Safety and regulatory approvals (pending)
UL recognition: $\mathbf{2 5 0 0} \mathrm{V}$ rms for 1 minute per UL 1577 (pending)
VDE certificates of conformity (pending) DIN V VDE V 0884-10 (VDE V 0884-10): 2006-12 $\mathrm{V}_{\text {IORM }}=560 \mathrm{~V}$ peak
Operating temperature range: $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$

## APPLICATIONS

Low power RS-485/RS-422 networks
Isolated interfaces
Building control networks
Multipoint data transmission systems

## GENERAL DESCRIPTION

The ADM2481 differential bus transceiver is an integrated, galvanically isolated component designed for bidirectional data communication on balanced, multipoint bus transmission lines. It complies with ANSI EIA/TIA-485-A and ISO 8482: 1987(E). Using iCoupler ${ }^{\bullet}$ technology from Analog Devices, Inc., the ADM2481 combines a 3-channel isolator, a three-state differential line driver, and a differential input receiver into a single package. The logic side of the device is powered with either a 5 V or 3 V supply, and the bus side uses a 5 V supply only.
The ADM2481 is slew-limited to reduce reflections with improperly terminated transmission lines. The controlled slew rate limits the data rate to 500 kbps . The input impedance of the device is $96 \mathrm{k} \Omega$, allowing up to 256 transceivers on the bus. Its driver has an active-high enable feature. The driver differential outputs and receiver differential inputs are connected internally

## FUNCTIONAL BLOCK DIAGRAM



Figure 1.
to form a differential I/O port. When the driver is disabled or when $V_{\text {DD1 }}$ or $V_{\mathrm{DD} 2}=0 \mathrm{~V}$, this imposes minimal loading on the bus. An active-high receiver disable feature, which causes the receiver output to enter a high impedance state, is provided as well.

The receiver inputs have a true fail-safe feature that ensures a logic-high receiver output level when the inputs are open or shorted. This guarantees that the receiver outputs are in a known state before communication begins and at the point when communication ends.

Current limiting and thermal shutdown features protect against output short circuits and bus contention situations that might cause excessive power dissipation. The part is fully specified over the industrial temperature range of $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ and is available in a 16 -lead, wide body SOIC package.

Rev, 0
Information furnished by Analog Devices is believed to be accurate and reliable. However, no responsibility is assumed by Analog Devices for its use, nor for any infringements of patents or other rights of third parties that may result from its use. Specifications subject to change without notice. No license is granted by implication or otherwise under any patent or patent rights of Analog Devices. Trademarks and registered trademarks are the property of their respective owners.

## ADM2481

## TABLE OF CONTENTS

Features ..... 1
Applications. .....  1
Functional Block Diagram .....  1
General Description ..... 1
Revision History ..... 2
Specifications .....  3
Timing Specifications ..... 4
Package Characteristics ..... 4
Regulatory Information (Pending) ..... 4
Insulation and Safety-Related Specifications ..... 4
VDE 0884 Insulation Characteristics (Pending) ..... 5
Absolute Maximum Ratings ..... 6
ESD Caution ..... 6
Pin Configuration and Function Descriptions ..... 7
Typical Performance Characteristics .....  8
Test Circuits ..... 11
Switching Characteristics ..... 12
Circuit Description ..... 13
Electrical Isolation ..... 13
Truth Tables ..... 14
Thermal Shutdown ..... 14
True Fail-Safe Receiver Inputs ..... 14
Magnetic Field Immunity. ..... 14
Applications Information ..... 16
Printed Circuit Board (PCB) Layout ..... 16
Isolated Power Supply Circuit ..... 16
Outline Dimensions ..... 17
Ordering Guide ..... 17

## REVISION HISTORY

## 7/10—Revision 0: Initial Version

## SPECIFICATIONS

$3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 1} \leq 5.5 \mathrm{~V}, 4.75 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 2} \leq 5.25 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted.
Table 1.

| Parameter | Symbol | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |  |
| Differential Outputs |  |  |  |  |  |  |
| Differential Output Voltage |  |  |  | 5 | V | $\mathrm{RL}_{\mathrm{L}}=\infty$, see Figure 16 |
|  | Vod | 2.0 |  | 5 | V | $R_{L}=50 \Omega$ (RS-422), see Figure 16 |
|  | Vod | 1.5 |  | 5 | V | $\mathrm{R}_{\mathrm{L}}=27 \Omega$ (RS-485), see Figure 16 |
|  | V003 | 1.5 |  | 5 | V | $\mathrm{V}_{\text {TEST }}=-7 \mathrm{~V} \text { to }+12 \mathrm{~V}, \mathrm{~V}_{\mathrm{DD1}} \geq 4.75$ see Figure 17 |
| $\Delta\left\|V_{\text {ool }}\right\|$ for Complementary Output States |  |  |  | 0.2 | V | $\mathrm{R}_{\mathrm{L}}=27 \Omega$ or $50 \Omega$, see Figure 16 |
| Common-Mode Output Voltage | Voc |  |  | 3 | V | $\mathrm{R}_{\mathrm{L}}=27 \Omega$ or $50 \Omega$, see Figure 16 |
| $\Delta\left\|V_{\text {oc }}\right\|$ for Complementary Output States |  |  |  | 0.2 | V | $\mathrm{R}_{\mathrm{L}}=27 \Omega$ or $50 \Omega$, see Figure 16 |
| Output Short-Circuit Current, | Isc |  |  |  |  |  |
| Vout $=$ High |  | -250 |  | +250 | mA | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {Out }} \leq+12 \mathrm{~V}$ |
| $\mathrm{V}_{\text {out }}=$ Low |  | -250 |  | +250 | mA | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {Out }} \leq+12 \mathrm{~V}$ |
| Logic Inputs |  |  |  |  |  |  |
| Input High Voltage | $\mathrm{V}_{\mathrm{H}}$ | $0.7 \mathrm{~V}_{\text {DD } 1}$ |  |  | V | TxD, DE, $\overline{\mathrm{RE}}$ |
| Input Low Voltage | VIL |  | +0.01 | $0.25 \mathrm{~V}_{\text {DD } 1}$ | V | TxD, DE, $\overline{\mathrm{RE}}$ |
| CMOS Logic Input Current (TxD, DE, $\overline{\mathrm{RE}}$ ) | II | -10 |  | +10 | $\mu \mathrm{A}$ | TxD, $\mathrm{DE}, \overline{\mathrm{RE}}=\mathrm{V}_{\mathrm{DD} 1}$ or 0 V |
| RECEIVER |  |  |  |  |  |  |
| Differential Inputs |  |  |  |  |  |  |
| Differential Input Threshold Voltage | $\mathrm{V}_{\text {TH }}$ | -200 | -125 | -30 | mV | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {CM }} \leq+12 \mathrm{~V}$ |
| Input Hysteresis | $\mathrm{V}_{\text {Hrs }}$ |  | 20 |  | mV | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {cm }} \leq+12 \mathrm{~V}$ |
| Input Resistance (A, B) |  | 96 | 150 |  | $\mathrm{k} \Omega$ | $-7 \mathrm{~V} \leq \mathrm{V}_{\text {CM }} \leq+12 \mathrm{~V}$ |
| Input Current (A, B) |  |  |  | 0.125 | mA | $\mathrm{V}_{\mathrm{IN}}=12 \mathrm{~V}$ |
|  |  |  |  | -0.1 | mA | $\mathrm{V}_{\mathrm{IN}}=-7 \mathrm{~V}$ |
| RxD Logic Output |  |  |  |  |  |  |
| Output High Voltage | Vor | $V_{\text {DD } 1}-0.1$ |  |  | V | $\mathrm{l}_{\text {lout }}=20 \mu \mathrm{~A}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=0.2 \mathrm{~V}$ |
|  |  | $V_{\text {DD } 1}-0.4$ | $V_{\text {DDI }}-0.2$ |  | V | lout $=4 \mathrm{~mA}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=0.2 \mathrm{~V}$ |
| Output Low Voltage | Voı |  |  | 0.1 | V | $\mathrm{l}_{\text {out }}=-20 \mu \mathrm{~A}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=-0.2 \mathrm{~V}$ |
|  |  |  |  | 0.4 | V | lout $=-4 \mathrm{~mA}, \mathrm{~V}_{\mathrm{A}}-\mathrm{V}_{\mathrm{B}}=-0.2 \mathrm{~V}$ |
| Output Short-Circuit Current | Isc | 7 |  | 85 | mA | $\mathrm{V}_{\text {Out }}=\mathrm{GND}$ or $\mathrm{V}_{\text {cc }}$ |
| Three-State Output Leakage Current |  |  |  | $\pm 1$ | $\mu \mathrm{A}$ | $0.4 \mathrm{~V} \leq \mathrm{V}_{\text {out }} \leq 2.4 \mathrm{~V}$ |
| POWER SUPPLY CURRENT |  |  |  |  |  |  |
| Logic Side | $\mathrm{I}_{\text {DO } 1}$ |  |  | 2.5 | mA | $4.5 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 1} \leq 5.5 \mathrm{~V}$, outputs unloaded, $\overline{\mathrm{RE}}=0 \mathrm{~V}$ |
|  |  |  |  | 1.3 | mA | $3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 1} \leq 3.6 \mathrm{~V}$, outputs unloaded, $\overline{\mathrm{RE}}=0 \mathrm{~V}$ |
| Bus Side | IDD2 |  |  | 2.0 | mA | Outputs unloaded, DE $=5 \mathrm{~V}$ |
|  |  |  |  | 1.7 | mA | Outputs unloaded, DE $=0 \mathrm{~V}$ |
| COMMON-MODE TRANSIENT IMMUNITY ${ }^{1}$ | $\mathrm{V}_{\text {cm }}$ | 25 |  |  | kV/ $/ \mathrm{s}$ | $\begin{aligned} & \mathrm{TXD}=\mathrm{V}_{\mathrm{DD} 1} \text { or } 0 \mathrm{~V}, \mathrm{~V}_{\mathrm{CM}}=1 \mathrm{kV}, \\ & \text { transient magnitude }=800 \mathrm{~V} \end{aligned}$ |

[^0]
## ADM2481

## TIMING SPECIFICATIONS

$3.0 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 1} \leq 5.5 \mathrm{~V}, 4.75 \mathrm{~V} \leq \mathrm{V}_{\mathrm{DD} 2} \leq 5.25 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=\mathrm{T}_{\mathrm{MIN}}$ to $\mathrm{T}_{\mathrm{MAX}}$, unless otherwise noted.
Table 2.

| Parameter | Symbol | Min | Typ | Max | Unit | Test Conditions/Comments |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DRIVER |  |  |  |  |  |  |
| Maximum Data Rate |  | 500 |  |  | kbps |  |
| Propagation Delay | $\mathrm{t}_{\text {PLH, }}$ tPHL | 250 |  | 620 | ns | $\mathrm{R}_{\mathrm{L}}=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$, see Figure 18 and Figure 22 |
| Skew | $\mathrm{t}_{\text {skew }}$ |  |  | 40 | ns | $\mathrm{R}_{\mathrm{L}}=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{L_{2} 2}=100 \mathrm{pF}$, see Figure 18 and Figure 22 |
| Rise/Fall Time | $\mathrm{t}_{\mathrm{R}}, \mathrm{t}_{\mathrm{F}}$ | 200 |  | 600 | ns | $\mathrm{R}_{\mathrm{L}}=54 \Omega, \mathrm{C}_{\mathrm{L} 1}=\mathrm{C}_{\mathrm{L} 2}=100 \mathrm{pF}$, see Figure 18 and Figure 22 |
| Enable Time |  |  |  | 1050 | ns | $\mathrm{R}_{\mathrm{L}}=500 \Omega, C_{L}=100 \mathrm{pF}$, see Figure 19 and Figure 24 |
| Disable Time |  |  |  | 1050 | ns | $\mathrm{R}_{\mathrm{L}}=500 \Omega, \mathrm{C}_{\mathrm{L}}=15 \mathrm{pF}$, see Figure 19 and Figure 24 |
| RECEIVER |  |  |  |  |  |  |
| Propagation Delay | $\mathrm{t}_{\text {PLH, }} \mathrm{t}_{\text {PHL }}$ | 400 |  | 1050 | ns | $C_{L}=15 \mathrm{pF}$, see Figure 20 and Figure 23 |
| Differential Skew | tskew |  |  | 250 | ns | $\mathrm{C}_{L}=15 \mathrm{pF}$, see Figure 20 and Figure 23 |
| Enable Time |  |  | 25 | 70 | ns | $\mathrm{R}_{L}=1 \mathrm{k} \Omega, \mathrm{C}_{L}=15 \mathrm{pF}$, see Figure 21 and Figure 25 |
| Disable Time |  |  | 40 | 70 | ns | $\mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{C}_{L}=15 \mathrm{pF}$, see Figure 21 and Figure 25 |

## PACKAGE CHARACTERISTICS

Table 3.

| Parameter | Symbol | Min $\quad$ Typ $\quad$ Max | Unit | Test Conditions |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Resistance (Input-Output) |  |  |  |  |
| Capacitance (Input-Output) $^{1}$ | $\mathrm{R}_{1-\mathrm{O}}$ | $10^{12}$ | $\Omega$ |  |
| Input Capacitance $^{2}$ | $\mathrm{C}_{1-\mathrm{o}}$ | 3 | pF | $\mathrm{f}=1 \mathrm{MHz}$ |

${ }^{1}$ Device is considered a 2-terminal device: Pin 1 to Pin 8 are shorted together, and Pin 9 to $\operatorname{Pin} 16$ are shorted together.
${ }^{2}$ Input capacitance is from any input data pin to ground.

## REGULATORY INFORMATION (PENDING)

Table 4. ADM2481 Approvals

| Organization | Approval Type | Notes |
| :---: | :---: | :---: |
| UL | Recognized under the Component Recognition Program of Underwriters Laboratories, Inc. | In accordance with UL 1577, each ADM2481 is proof tested by applying an insulation test voltage of $\geq 3000 \mathrm{~V}$ rms for 1 second (current leakage detection limit $=5 \mu \mathrm{~A}$ ). |
| VDE | Certified according to DIN VVDE V 0884-10 (VDE V 0884-10): 2006-12 | In accordance with DIN V VDE V 0884-10, each ADM2481 is proof tested by applying an insulation test voltage of $\geq 1050 \mathrm{~V}$ peak for 1 second (partial discharge detection limit $=5 \mathrm{pC}$ ). |

## INSULATION AND SAFETY-RELATED SPECIFICATIONS

Table 5.

| Parameter | Symbol | Value | Unit | Conditions |
| :---: | :---: | :---: | :---: | :---: |
| Rated Dielectric Insulation Voltage |  | 2500 | V rms | 1-minute duration |
| Minimum External Air Gap (Clearance) | L(101) | 7.7 | mm | Measured from input terminals to output terminals, shortest distance through air |
| Minimum External Tracking (Creepage) | L(102) | 7.6 | mm | Measured from input terminals to output terminals, shortest distance along body |
| Minimum Internal Gap (Internal Clearance) |  | 0.017 min | mm | Insulation distance through insulation |
| Tracking Resistance (Comparative Tracking Index) | CTI | >175 | V | DIN IEC 112/VDE 0303 Part 1 |
| Isolation Group |  | Illa |  | Material Group (Table 1 in DIN VDE 0110,1/89) |

## ADM2481

## VDE 0884 INSULATION CHARACTERISTICS (PENDING)

This isolator is suitable for basic electrical isolation only within this safety limit data. Maintenance of this safety data shall be ensured by means of protective circuits.

Table 6.

| Description | Symbol | Characteristic | Unit |
| :---: | :---: | :---: | :---: |
| Installation Classification per DIN VDE 0110 for Rated Mains Voltage |  |  |  |
| $\leq 150 \mathrm{~V}$ rms |  | I to IV |  |
| $\leq 300 \mathrm{~V}$ rms |  | I to III |  |
| $\leq 400 \mathrm{~V}$ rms |  | I to II |  |
| Climatic Classification |  | 40/85/21 |  |
| Pollution Degree (Table 1 in DIN VDE 0110) |  | 2 |  |
| Maximum Working Insulation Voltage | VIoRM | 560 | $V_{\text {Peak }}$ |
| Input to Output Test Voltage, Method b1 | $V_{\text {PR }}$ | 1050 | $V_{\text {Peak }}$ |
| VIORM $\times 1.875=$ V $_{\text {PR, }} 100 \%$ Production Tested |  |  |  |
| $\mathrm{t}_{\mathrm{m}}=1 \mathrm{sec}$, Partial Discharge of $<5 \mathrm{pC}$ |  |  |  |
| Input-to-Output Test Voltage, Method a (After Environmental Tests, Subgroup 1) |  |  |  |
| $\mathrm{V}_{\text {Iorm }} \times 1.6=\mathrm{V}_{\text {PR, }} \mathrm{t}_{\mathrm{m}}=60 \mathrm{sec}$, Partial Discharge of $<5 \mathrm{pC}$ (After Input and/or Safety Test, Subgroup 2/3) |  | 896 | $V_{\text {peak }}$ |
| $\mathrm{V}_{\text {IORM }} \times 1.2=\mathrm{V}_{\text {PR, }} \mathrm{t}_{\mathrm{m}}=60 \mathrm{sec}$, Partial Discharge of $<5 \mathrm{pC}$ | $\mathrm{V}_{\mathrm{PR}}$ | 672 | $V_{\text {Peak }}$ |
| Highest Allowable Overvoltage <br> (Transient Overvoltage, $\mathrm{t}_{\mathrm{TR}}=10 \mathrm{sec}$ ) | $\mathrm{V}_{\text {TR }}$ | 4000 | $V_{\text {Peak }}$ |
| Safety-Limiting Values (Maximum Value Allowed in the Event of a Failure; see Figure 13) |  | 150 |  |
| Input Current | Is, INPuT | $265$ | ${ }^{\circ} \mathrm{C} A$ |
| Output Current | $\mathrm{I}_{\text {S OUTPut }}$ | 335 | mA |
| Insulation Resistance at $\mathrm{T}_{5}, \mathrm{~V}_{10}=500 \mathrm{~V}$ | Rs | $>10^{9}$ | $\Omega$ |

## ABSOLUTE MAXIMUM RATINGS

$\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}$, unless otherwise noted. All voltages are relative to their respective ground.

Table 7.

| Parameter | Rating |
| :--- | :--- |
| $\mathrm{V}_{\mathrm{DD} 1}$ | -0.5 V to +7 V |
| $\mathrm{~V}_{\mathrm{DD} 2}$ | -0.5 V to +6 V |
| Digital Input Voltage (DE, $\overline{\mathrm{RE},}, \mathrm{TxD})$ | -0.5 V to $\mathrm{V}_{\mathrm{DD} 1}+0.5 \mathrm{~V}$ |
| Digital Output Voltage (RxD) | -0.5 V to VD1 +0.5 V |
| Driver Output/Receiver Input Voltage | -9 V to +14 V |
| ESD Rating: Contact (Human Body | $\pm 2 \mathrm{kV}$ |
| $\quad$ Model) (A, B Pins) | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Operating Temperature Range | $-55^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Storage Temperature Range | -35 mA to +35 mA |
| Average Output Current per Pin | $65^{\circ} \mathrm{C} / \mathrm{W}$ |
| ӨJA Thermal Impedance |  |
| Lead Temperature | $260^{\circ} \mathrm{C}$ |
| $\quad$ Soldering (10 sec) | $215^{\circ} \mathrm{C}$ |
| Vapor Phase ( 60 sec$)$ | $220^{\circ} \mathrm{C}$ |
| Infrared (15 sec) |  |

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ESD CAUTION

|  | ESD (electrostatic discharge) sensitive device. <br> Charged devices and circuit boards can discharge <br> without detection. Although this product features <br> patented or proprietary protection circuitry, damage <br> may occur on devices subjected to high energy ESD. <br> Therefore, proper ESD precautions should be taken to <br> avoid performance degradation or loss of functionality. |
| :--- | :--- |

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Table 8. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :---: | :---: | :---: |
| 1 | $\mathrm{V}_{\mathrm{DD} 1}$ | Power Supply (Logic Side). |
| 2, 7, 8 | $\mathrm{GND}_{1}$ | Ground (Logic Side). |
| 3 | RxD | Receiver Output Data. When enabled, if $(A-B) \geq-30 \mathrm{mV}$, then $\mathrm{RxD}=$ high; if $(A-B) \leq-200 \mathrm{mV}$, then $\mathrm{RxD}=$ low. This is a tristate output when the receiver is disabled, that is, when $\overline{\mathrm{RE}}$ is driven high. |
| 4 | $\overline{\mathrm{RE}}$ | Receiver Enable Input. This is an active-low input. Driving this input low enables the receiver, and driving it high disables the receiver. |
| 5 | DE | Driver Enable Input. Driving the input high enables the driver, and driving it low disables the driver. |
| 6 | TxD | Transmit Data Input. Data to be transmitted by the driver is applied to this input. |
| 9, 10, 15 | $\mathrm{GND}_{2}$ | Ground (Bus Side). |
| 11, 14 | NC | No Connect. |
| 12 | A | Noninverting Driver Output/Receiver Input. When the driver is disabled, or when $\mathrm{V}_{\mathrm{DD} 1}$ or $\mathrm{V}_{\mathrm{DD} 2}$ is powered down, Pin A is put into a high impedance state to avoid overloading the bus. |
| 13 | B | Inverting Driver Output/Receiver Input. When the driver is disabled, or when $\mathrm{V}_{\mathrm{DD} 1}$ or $\mathrm{V}_{\mathrm{DD} 2}$ is powered down, Pin B is put into a high impedance state to avoid overloading the bus. |
| 16 | $V_{\text {DD2 }}$ | Power Supply (Bus Side). |

TYPICAL PERFORMANCE CHARACTERISTICS


Figure 3. Unloaded Supply Current vs. Temperature


Figure 4. Output Current vs. Driver Output Low Voltage


Figure 5. Output Current vs. Driver Output High Voltage


Figure 6. Receiver Output Low Voltage vs. Temperature, lout $=-4 \mathrm{~mA}$


Figure 7. Receiver Output High Voltage vs. Temperature, Iout $=4 \mathrm{~mA}$


Figure 8. Driver Output Current vs. Differential Output Voltage


Figure 9. Driver Propagation Delay vs. Temperature


Figure 10. Receiver Propagation Delay vs. Temperature


Figure 11. Driver/Receiver Propagation Delay, High to Low


Figure 12. Driver/Receiver Propagation Delay, Low to High

## ADM2481



Figure 13. Thermal Derating Curve, Dependence of Safety-Limiting Values with Case Temperature per VDE 0884


Figure 14. Output Current vs. Receiver Output Low Voltage


Figure 15. Output Current vs. Receiver Output High Voltage

## TEST CIRCUITS



Figure 17. Driver Voltage Measurement over Common-Mode Range


Figure 18. Driver Propagation Delay


Figure 19. Driver Enable/Disable


Figure 20. Receiver Propagation Delay


Figure 21. Receiver Enable/Disable

## ADM2481

## SWITCHING CHARACTERISTICS



Figure 22. Driver Propagation Delay, Rise/Fall Timing


Figure 23. Receiver Propagation Delay


Figure 24. Driver Enable/Disable Timing


Figure 25. Receiver Enable/Disable Timing

## CIRCUIT DESCRIPTION

## ELECTRICAL ISOLATION

In the ADM2481, electrical isolation is implemented on the logic side of the interface. Therefore, the part has two main sections: a digital isolation section and a transceiver section (see Figure 26). Driver input and data enable signals, applied to the TxD and DE pins, respectively, and referenced to logic ground $\left(\mathrm{GND}_{1}\right)$, are coupled across an isolation barrier to appear at the transceiver section referenced to isolated ground $\left(\mathrm{GND}_{2}\right)$.
Similarly, the receiver output, referenced to isolated ground in the transceiver section, is coupled across the isolation barrier to appear at the RxD pin referenced to logic ground $\left(\mathrm{GND}_{1}\right)$.

## iCoupler Technology

The digital signals are transmitted across the isolation barrier using iCoupler technology. This technique uses chip-scale transformer windings to couple the digital signals magnetically from one side of the barrier to the other. Digital inputs are encoded into waveforms that are capable of exciting the primary transformer winding. At the secondary winding, the induced waveforms are then decoded into the binary value that was originally transmitted.


## ADM2481

## TRUTH TABLES

The following truth tables use the abbreviations shown in Table 9.
Table 9.

| Letter | Description |
| :--- | :--- |
| H | High level |
| L | Low level |
| X | Don't care |
| Z | High impedance (off) |
| NC | Disconnected |

Table 10. Transmitting

| Supply Status |  | Inputs |  | Outputs |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| V DD $1^{\text {On }}$ | V | DD 2 | DE | TxD | A |
| B |  |  |  |  |  |
| On | On | H | H | H | L |
| On | On | H | L | L | H |
| On | On | L | X | Z | Z |
| Off | Off | X | X | Z | Z |
| Off | Off | L | L | Z | Z |

Table 11. Receiving

| Supply Status |  | Inputs |  | Outputs |
| :--- | :--- | :--- | :--- | :--- |
| $\mathbf{V}_{\mathrm{DD} 1}$ | $\mathbf{V}_{\mathrm{DD} 2}$ | $\mathbf{A}-\mathbf{B}(\mathbf{V})$ | $\overline{\mathbf{R E}}$ | $\mathbf{R x D}$ |
| On | On | $>-0.03$ | L or NC | H |
| On | On | $<-0.2$ | L or NC | L |
| On | On | $-0.2<\mathrm{A}-\mathrm{B}<-0.03$ | L or NC | Indeterminate |
| On | On | Inputs open | Lor NC | H |
| On | On | X | H | Z |
| On | Off | X | Lor NC | H |
| Off | Off | X | Lor NC | L |

## THERMAL SHUTDOWN

The ADM2481 contains thermal shutdown circuitry that protects the part from excessive power dissipation during fault conditions. Shorting the driver outputs to a low impedance source can result in high driver currents. The thermal sensing circuitry detects the increase in die temperature under this condition and disables the driver outputs. This circuitry is designed to disable the driver outputs when a die temperature of $150^{\circ} \mathrm{C}$ is reached. As the device cools, the drivers are re-enabled at a temperature of $140^{\circ} \mathrm{C}$.

## TRUE FAIL-SAFE RECEIVER INPUTS

The receiver inputs have a true fail-safe feature that ensures that the receiver output is high when the inputs are open or shorted. During line-idle conditions, when no driver on the bus is enabled, the voltage across a terminating resistance at the receiver input decays to 0 V . With traditional transceivers, receiver input thresholds specified between -200 mV and +200 mV mean that external bias resistors are required on the $A$ and B pins to ensure that the receiver outputs are in a known state. The true fail-safe receiver input feature eliminates the need for bias resistors by specifying the receiver input threshold between -30 mV and -200 mV . The guaranteed negative threshold means that when the voltage between $A$ and $B$ decays to 0 V , the receiver output is guaranteed to be high.

## MAGNETIC FIELD IMMUNITY

Because iCouplers use a coreless technology, no magnetic components are present, and the problem of magnetic saturation of the core material does not exist. Therefore, iCouplers have essentially infinite dc field immunity. The analysis that follows defines the conditions under which this might occur. The 3 V operating condition of the ADM2481 is examined because it represents the most susceptible mode of operation.
The limitation on the ac magnetic field immunity of the iCoupler is set by the condition in which the induced error voltage in the receiving coil (the bottom coil in this case) is made sufficiently large, either to falsely set or reset the decoder. The voltage induced across the bottom coil is given by

$$
V=\left(\frac{-d \beta}{d t}\right) \sum \pi r_{n}^{2} ; n=1,2, \ldots, N
$$

where, if the pulses at the transformer output are greater than 1.0 V in amplitude:
$\beta$ is the magnetic flux density (gauss).
$N$ is the number of turns in receiving coil.
$r_{n}$ is the radius of nth turn in receiving coil (cm).
The decoder has a sensing threshold of about 0.5 V ; therefore, there is a 0.5 V margin in which induced voltages can be tolerated.

Given the geometry of the receiving coil and an imposed requirement that the induced voltage is, at most, $50 \%$ of the 0.5 V margin at the decoder, a maximum allowable magnetic field is calculated, as shown in Figure 27.


Figure 27. Maximum Allowable External Magnetic Flux Density
For example, at a magnetic field frequency of 1 MHz , the maximum allowable magnetic field of 0.2 kGauss induces a voltage of 0.25 V at the receiving coil. This is about $50 \%$ of the sensing threshold and does not cause a faulty output transition. Similarly, if such an event occurs during a transmitted pulse and is the worst-case polarity, it reduces the received pulse from $>1.0 \mathrm{~V}$ to 0.75 V . This is well above the 0.5 V sensing threshold of the decoder.

These magnetic flux density values are shown in Figure 28, using more familiar quantities such as maximum allowable current flow, at given distances away from the ADM2481 transformers.


Figure 28. Maximum Allowable Current for Various Current-to-ADM2481 Spacings

At combinations of strong magnetic field and high frequency, any loops formed by printed circuit board traces could induce large enough error voltages to trigger the thresholds of succeeding circuitry. To avoid this possibility, take care in the layout of such traces.

## APPLICATIONS INFORMATION <br> PRINTED CIRCUIT BOARD (PCB) LAYOUT

The ADM2481 signal isolated RS-485 transceiver requires no external interface circuitry for the logic interfaces. Power supply bypassing is required at the input and output supply pins (see Figure 29).
Bypass capacitors are most conveniently connected between Pin 1 and Pin 2 for $V_{D D 1}$ and between Pin 15 and Pin 16 for $\mathrm{V}_{\mathrm{DD} 2}$. The capacitor value must be between $0.01 \mu \mathrm{~F}$ and $0.1 \mu \mathrm{~F}$. The total lead length between both ends of the capacitor and the input power supply pin must not exceed 20 mm .


Figure 29. Recommended Printed Circuit Board Layout

In applications involving high common-mode transients, take care to ensure that board coupling across the isolation barrier is minimized. Furthermore, the board layout must be designed such that any coupling that does occur equally affects all pins on a given component side.
Failure to ensure this can cause voltage differentials between pins that exceed the absolute maximum ratings of the device, thereby leading to latch-up or permanent damage.

## ISOLATED POWER SUPPLY CIRCUIT

The ADM2481 requires isolated power capable of 5 V at 100 mA to be supplied between the $\mathrm{V}_{\mathrm{DD} 2}$ and $\mathrm{GND}_{2}$ pins. If no suitable integrated power supply is available, a discrete circuit, such as the one in Figure 30, can be used. A centertapped transformer provides electrical isolation. The primary winding is excited with a pair of square waveforms that are $180^{\circ}$ out of phase with each other. A pair of Schottky diodes and a smoothing capacitor are used to create a rectified signal from the secondary winding. The ADP3330 linear voltage regulator provides a regulated power supply to the bus-side circuitry of the ADM2481.


## OUTLINE DIMENSIONS



## ORDERING GUIDE

| Model $^{1}$ | Data Rate (kbps) | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- | :--- |
| ADM2481BRWZ | 500 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16 -Lead, Wide Body SOIC_W | RW-16 |
| ADM2481BRWZ-RL7 | 500 | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | $16-$ Lead, Wide Body SOIC_W | RW-16 |

[^1]
## ADM2481

NOTES

NOTES

## ADM2481

## NOTES


[^0]:    ${ }^{1}$ Common-mode transient immunity is the maximum common-mode voltage slew rate that can be sustained while maintaining specification-compliant operation. $V_{\text {см }}$ is the common-mode potential difference between the logic and bus sides. The transient magnitude is the range over which the common mode is slewed. The common-mode voltage slew rates apply to both rising and falling common-mode voltage edges.

[^1]:    ${ }^{1} Z=$ RoHS Compliant Part.

