





Small Hybride

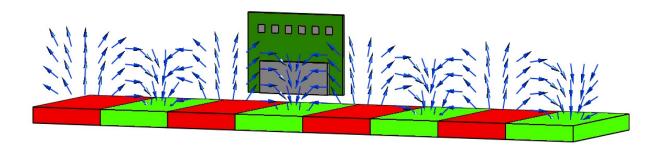
Large Hybride

- AMR gradient sensor
- Linear displacement, movements, velocities
- High precision
- Various pole pitches available

### **DESCRIPTION**

Wafer

Sliding the MLS-Sensors along a magnetic scale will produce a sine and a cosine output signal as a function of the position. In order to deliver satisfying results, this will be achieved as long as the air gap between sensor edge and magnetic scale surface does not exceed half of the pole pitch. As the sensor principle is based on the anisotropic magneto resistance effect, the signal amplitudes are nearly independent on the magnetic field strength and therefore air gap variations do not have a big effect on the accuracy. The sensor detects a magnetic gradient field and is thus almost insensitive to homogenous stray fields.



Precise displacement values will be archived by using a sine/cosine decoder. The maximal obtainable precision depends on the distance sensor – magnetic scale and on the accuracy of the magnetic scale. Values of <1% of the pole pitch are common.

### **FEATURES**

- Sin- / cos-output signals suitable for signal evaluation by standard-ASIC's
- Very high precision
- Insensitive to air gap fluctuations
- Highly reliable
- Low interference field sensitivity

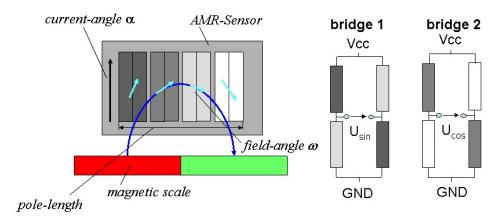
### **APPLICATIONS**

- Linear displacement, movements, velocities in dirty environments
- Very precise angular measurement using pole wheels



### **SENSOR BASICS**

The MLS-sensors consists of two magneto resistive Wheatstone bridges, generating two phase-shifted signals by means of a lateral offset. MLS-sensors will only cooperate well together with pole stripes meeting their design-pole pitch. In addition, some sensor types integrate over more than one pole in order to improve sensor performance.



### **CHARACTERISTIC VALUES**

PARAMETER	SYMBOL	CONDITION	ТүрЕ	MIN	Түр	Max	UNIT
1. Operating Limits	•	•			•	•	•
max. supply voltage	$V_{cc,max}$					10	V
max. current (both bridges)	I <sub>cc,max</sub>		MLS1000/8 MLS2000/5000			5 10	mA
operating temperature	T <sub>op</sub>			-40		+85	°C
storage temperature	$T_{st}$			-40		+125	°C
2. Sensor Specificati	2. Sensor Specifications (T=25 °C)						
Supply voltage	V <sub>cc</sub>				5		V
pole pitch *)	р		MLS1000 MLS2000 MLS5000 MLS8		1000 2000 5000 2500		μm
Resistance (both bridges)	R <sub>b</sub>		MLS1000 MLS2000/5000 MLS8	2000 1000 30000	3000 1500 40000	4000 2000 50000	Ω
Output signal range	$\Delta V_{n}/V_{cc}$	A, B		16	20		mV/V
Offset voltage	$V_{n \text{ off}}$	A, B		-1	0	+1	mV/V
3. Sensor Specifications							
TC of amplitude	TCSV	A, C		-0.36	-0.32	-0.28	%/K
TC of resistance	TCBR	A, C		+0.27	+0.32	+0.37	%/K
TC of offset	TCVoff	A, C		-4	0	+4	μV/V/K

n = 1;2 (bridge number); Stress above one or more of the limiting values may cause permanent damage to the device. Exposure to limiting values for extended periods may affect device reliability.

<sup>\*)</sup> other pole pitches on request



### **MEASUREMENT CONDITIONS**

PARAMETER	SYMBOL	Unit	CONDITION		
A. Set Up Conditions		•			
ambient temperature	Т	℃	T = 23±5 °C (unless otherwise noted)		
supply voltage	$V_{cc}$	V	Vcc = 5 V		
applied magnetic field	Н	kA/m	H > 10 kA/m		
B. Sensor Specifications (T=25 °C, 360° turn , H=25 kA/m , Vo <sub>max</sub> >0, Vo <sub>min</sub> <0)					
output signal range	$\Delta V_n / V_{cc}$	mV/V	$\Delta V_n / V_{cc} = (V_{n \text{ max}} - V_{n \text{ min}}) / V_{cc}$		
signal offset	V <sub>off n</sub>	mV/V	$V_{\text{off n}} = (V_{\text{n max}} + V_{\text{n min}}) / V_{\text{cc}}$		
C. Sensor Specifications (T=-25 °C, +125 °C)					
ambient temperatures	Т	°C	T₁ = -25 °C, T₀ = +25 °C, T₂ = +125 °C		
TC of amplitude	TCSV	%/K	$TCV = \frac{1}{(T_2 - T_1)} \cdot \frac{\frac{\Delta V_n}{V_{cc}}(T_2) - \frac{\Delta V_n}{V_{cc}}(T_1)}{\frac{\Delta V_n}{V_{cc}}(T_1)} \cdot 100\%$		
TC of resistance	TCBR	%/K	$TCR = \frac{1}{(T_2 - T_1)} \cdot \frac{R_n(T_2) - R_n(T_1)}{R_n(T_1)} \cdot 100\%$		
TC of offset	TCVoff	μV/(VK)	$TCVoff_n = \frac{Voff_n(T_2) - Voff_n(T_1)}{(T_2 - T_1)}$		

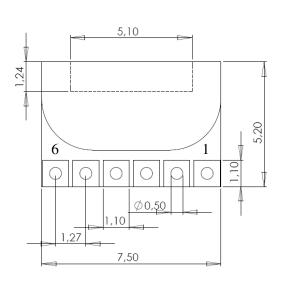
n = 1;2 (bridge number)

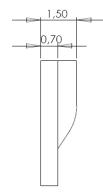




### **PACKAGES**

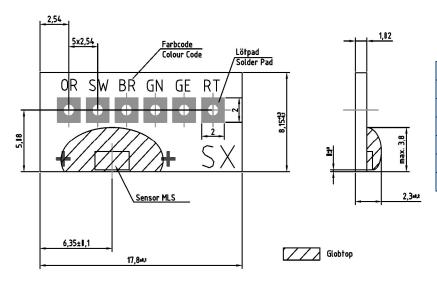
### **HK (SMALL HYBRIDE)**





Pin	Annotation	Name	
1	Output signal	V <sub>cos-</sub>	
2	Supply voltage	V <sub>cc</sub>	
3	Ground	GND	
4	Output signal	$V_{\text{sin-}}$	
5	Output signal	$V_{sin+}$	
6	Output signal	$V_{cos+}$	

### **HS (STANDARD HYBRIDE)**

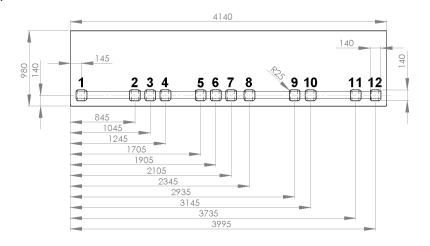


Pin	Annotation	Name
OR	Output signal	V <sub>cos-</sub>
SW	Supply voltage	V <sub>cc</sub>
BR	Ground	GND
GN	Output signal	V <sub>sin-</sub>
GE	Output signal	$V_{sin+}$
RT	Output signal	V <sub>cos+</sub>

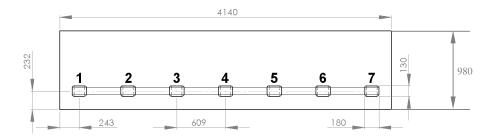


### **DIE GEOMETRIES**

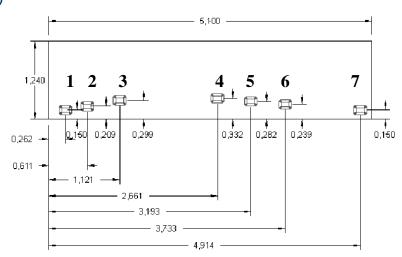
### MLS 1000 (DIE)



### MLS 2000 (DIE)



### MLS 5000/8 (DIE)

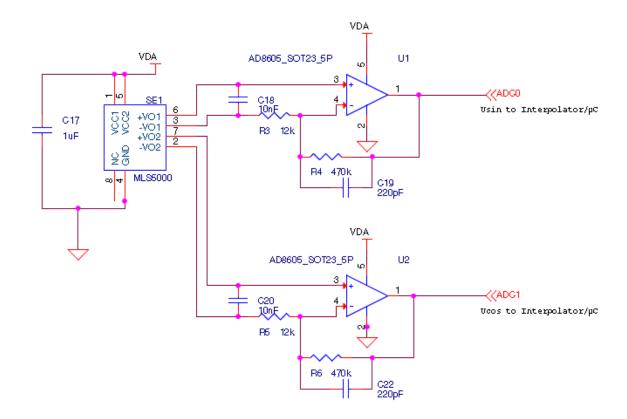




### **PIN ASSIGNMENT (DIES)**

Pin	MLS1000	MLS2000	MLS5000	MLS8
1	Vcc	-V2	Vcc (bridge 2)	+V1
2	-V1	-V1	-V2	+V2
3	+V1	-V2	-V1	GND
4	-V1	GND	GND	Vcc
5	-V2	Vcc	Vcc (bridge 1)	-V1
6	+V2	+V1	+V1	-V2
7	-V2	+V2	+V2	-
8	R1	-	-	-
9	R1	-	-	-
10	R2	-	-	-
11	R2	-	-	-
12	GND	-	-	-

### **APPLICATION EXAMPLE**



Exemplary hardware configuration using an Analog Devices AD8605 amplifier for preprocessing MLS5000 signals for usage with common Microcontroller.



eng. samples

## Magnetic Length Sensor MLS

on request

### ORDERING CODES

	MLS1000	MLS2000	MLS5000	MLS8
Wafer (diced) *)	G-MRCH-018	on request	G-MRCH-017	on request
Wafer (undiced) *)	G-MRCH-019	on request	G-MRCH-007	on request
Large hybride (HS)	on request	eng. samples	G-MRCO-012	eng. samples

eng. samples

### ORDERING INFORMATION

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Measurement Specialties China Ltd.

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Small hybride (HK) \*) MOQ is one wafer