



The Continuing Evolution of Smart Sensors Presenting a New Laser-type ZX-LDA -N Amplifier Unit

Smart Style!









a Smart Sensor!!

What's Style?

Top Priority Placed on Easy Operation

OMRON Offers Sensor Users New Choices



Downloaded from Elcodis an electron





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A Full Complement of Practical Functions Patent ling By simply fitting a Calculating Unit between two Amplifiers, the processing results of two Sensors can be displayed on a single Amplifier. Setting parameters need to be input only on one Amplifier.

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to Smart Style!



Advanced to

Advanced Functions Respond to Evolving Needs

More User Friendly New Function

Zero Reset Time Display

A reference value other than zero can be set as the zero reset value.



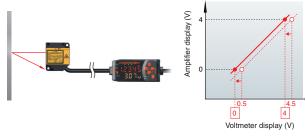
Present Value Display

The sub-digital display shows present values when the hold function is enabled. This makes it easy to check whether a measurement is within range.



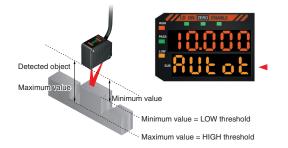
Linear Output Correction

Various factors, such as conversion errors occurring with connected devices, may cause the output value displayed on the Amplifier to differ from the actual output from a voltmeter. Adjusting the Amplifier display while monitoring the actual output on a voltmeter can eliminate the difference between the two values.



Automatic Teaching

Maximum and minimum measurement values can be set as thresholds when automatic teaching is executed. It is useful for setting threshold values from actual measurements while the workpiece is moving.





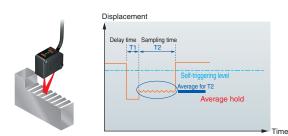
Enhanced Hold Function New Function



Average hold and delay hold functions were added to enable accurate assessment of changes and the desired measurement position.

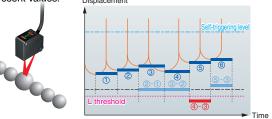
Delay Hold/Average Hold

The delay hold function measures only signals within the desired sampling time after a specified time delay from the trigger. The newly added average hold function is especially useful for measuring large workpieces with uneven surfaces.



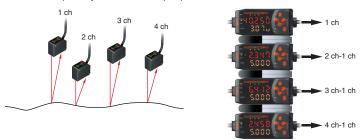
Previous Value Comparison Function

Gradual changes in measurements due to machine temperature changes or other factors can be ignored in certain situations, such as when detecting foreign matter around bearings. The previous value comparison function effectively detects any changes between previous and present values. Displacement



Multiple-point Measurements Computed Using 1 Point

The result computed for one point can be used as a basis for the output for every other point. This is especially useful for multiple-point measurements.





Sensors

Sensor Heads (Reflective)

| Optical system | Beam shape | Sensing distance | Resolution* | Model |
|--------------------|------------|------------------|-------------|-----------|
| Diffuse reflective | Spot beam | 40±10 mm | 2 μm | ZX-LD40 |
| | | 100±40 mm | 16 μm | ZX-LD100 |
| | | 300±200 mm | 300 µm | ZX-LD300 |
| | Line beam | 40±10 mm | 2 μm | ZX-LD40L |
| | | 100±40 mm | 16 μm | ZX-LD100L |
| | | 300±200 mm | 300 μm | ZX-LD300L |
| Regular reflective | Spot beam | 30±2 mm | 0.25 μm | ZX-LD30V |
| | Line beam | | | ZX-LD30VL |

* For an average count of 4,096.

Sensor Heads (Through-beam)

| Optical system | Measuring width | Sensing distance | Resolution* | Model |
|----------------|-----------------|------------------|-------------|----------|
| Through-beam | 1-mm dia. | 0 to 2000 mm | 4 μm | ZX-LT001 |
| | 5 mm | 0 to 500 mm | | ZX-LT005 |
| | 10 mm | | | ZX-LT010 |

* For an average count of 64.

Amplifier Units

| Appearance | Power supply | Output type | Model |
|------------|--------------|-------------|------------|
| | DC | NPN | ZX-LDA11-N |
| | | PNP | ZX-LDA41-N |

Note: Compatible connection with the Sensor Head.

Accessories (Order Separately) Calculating Unit

| Appearance | Model |
|------------|---------|
| | ZX-CAL2 |

Side-view Attachments

| Appearance | Applicable Sensor Head | Model |
|------------|---------------------------|---------|
| | ZX-LT1001/ LT005 | ZX-XF12 |
| s Q | ZX-LT010 | ZX-XF22 |

Cables with Connectors on Both Ends (for Extension)*1

| Cable length | Model | Quantity |
|--------------|---------|----------|
| 1 m | ZX-XC1A | 1 |
| 4 m | ZX-XC4A | |
| 8 m | ZX-XC8A | |
| 9 m *2 | ZX-XC9A | |

*1. ZX-XC \Box R robot cable type also available.

 $^{\ast}2.$ For use only with Reflective Sensors.

12 ZX Series (ZX-L-N) Smart Sensors

Smart Monitor Sensor Setup Tool for Personal Computer Connection

| Appearance | Name | Model |
|------------|---|----------------------|
| | ZX-series Communi- cations Interface Unit | ZX-SF11 |
| CD-ROM | ZX-series Communi- cations Interface Unit + ZX-series Sensor Setup Soft- ware Basic | ZX-SFW11V3 *1, *2 |
| CD-ROM | ZX-series Sensor Setup Software | ZX-SW11EV3 *1 |

 The ZX-SFW11V3 or ZX-SW11V3 is required to use Smart Monitor with the ZX-LDA11-N/41-N. Earlier versions cannot be used.

*2. The ZX-SFW11EV3 SmartMonitor can be used only to set functions and monitor waveforms.

Specifications

Sensor Heads (Reflective)

| Item Model | ZX-LD40 | ZX-LD100 | ZX-LD300 | ZX-LD30V | ZX-LD40L | ZX-LD100L | ZX-LD300L | Z3X-LD30VL |
|------------------------------------|--|---|---------------------------|----------------------------|---------------------------|---|---------------------------|----------------------------|
| Optical system | Diffuse reflective | Diffuse reflective | | | Diffuse reflective | | | Regular reflective |
| Light source (wave length) | Visible-light sem | iconductor laser w | ith a wavelength c | of 650 nm and an | output of 1 mW m | ax.; class 2 | | |
| Measurement point | 40 mm | 100 mm | 300 mm | 30 mm | 40 mm | 100 mm | 300 mm | 30 mm |
| Measurement range | ±10 mm | ±40 mm | ±200 mm | ±2 mm | ±10 mm | ±40 mm | ±200 mm | ±2 mm |
| Beam shape | Spot | | | | Line | | | |
| Beam size*1 | 50-µm dia. | 100-µm dia. | 300-µm dia. | 75-µm dia. | 75 µm x 2 mm | 150 µm x 2 mm | 450 µm x 2 mm | 100 µm x 1.8 mm |
| Resolution*2 | 2 μm | 16 µm | 300 µm | 0.25 μm | 2 μm | 16 µm | 300 µm | 0.25 μm |
| Linearity*3 | ±0.2% FS (entire range) | ±0.2% FS (80 to 120 mm) | ±2% FS (200 to 400 mm) | ±0.2% FS (entire range) | ±0.2% FS (32 to 48 mm) | ±0.2% FS (80 to 120 mm) | ±2% FS (200 to 400 mm) | ±0.2% FS (entire range) |
| Temperature characteristic*4 | ±0.03% FS/°C (I | 0.03% FS/°C (Except for ZX-LD300 and ZX-LD300L, which are ±0.1% FS/°C.) | | | | | | |
| Ambient illumination | Incandescent la | ncandescent lamp: 3,000 lx max. (on light receiving side) | | | | | | |
| Ambient temperature | Operating: 0 to 5 | Dperating: 0 to 50°C, Storage: -15 to 60°C (with no icing or condensation) | | | | | | |
| Ambient humidity | Operating and s | Operating and storage: 35% to 85% (with no condensation) | | | | | | |
| Insulation resistance | 20 MΩ min. at 5 | 20 MΩ min. at 500 VDC | | | | | | |
| Dielectric strength | 1,000 VAC, 50/6 | 1,000 VAC, 50/60 Hz for 1 min | | | | | | |
| Vibration resistance (destruction) | 10 to 150 Hz, 0. | 10 to 150 Hz, 0.7-mm double amplitude 80 min each in X, Y, and Z directions | | | | | | |
| Shock resistance (destruction) | 300 m/s ² 3 times | 300 m/s ² 3 times each in six directions (up/down, left/right, forward/backward) | | | | | | |
| Degree of protection | IEC60529, IP50 | | | IEC60529, IP40 | IEC60529, IP50 | | | IEC60529, IP40 |
| Connection method | Connector relay | (standard cable le | ngth: 500 mm) | | | | | |
| Weight (packed state) | Approx. 150 g | | | Approx. 250 g | Approx. 150 g | | | Approx. 250 g |
| Materials | Case: PBT (polybutylene terephthalate), Cover: Alu- minum, Lens: Glass Case: PBT (polybutylene terephthalate), Cover: Aluminum, Lens: Case: PBT (polybutylene terephthalate), Cover: Aluminum, Lens: Case: PBT (polybutylene terephthalate), Cover: Alumi | | | | alate), Cover: Alu- | Case and cover: Aluminum, Lens: Glass | | |
| Accessories | Instruction shee | t, Laser warning la | bel (English) | | | | | |

*1. Beam size: The beam size is defined by 1/e² (13.5%) of the strength of the beam at the beam center (measured value). Incorrect detection may occur if there is light leakage outside the defined spot and the material around the sensing object is more reflective than the sensing object.

outside the defined spot and the material around the sensing object is more reflective than the sensing object.
*2. Resolution: The resolution is the deviation (±3\u03c6) in the linear output when connected to the ZX-LDA Amplifier Unit. (The resolution is measured with the standard reference object (white ceramic), at the measurement point with the ZX-LDA set for an average count of 4.096 per period.) The resolution is given at the repeat accuracy for a stationary workpiece, and is not an indication of the distance accuracy. The resolution may be adversely affected under strong electromagnetic fields.
*3. Linearity: The linearity is given as the error in an ideal straight line displacement output when measuring the standard reference object. The linearity and measurement values vary with the object being measured.
*4. Temperature characteristic: The temperature characteristic is measured at the measurement point with the Sensor and reference object (OMRON's standard reference object) secured with an aluminum jig.

Note: Highly reflective objects can result in incorrect detection by causing out-of-range measurements.

Sensor Heads (Through-beam)

| ltem Mo | del Z | ZX-LT001 | | ZX-LT010 | | |
|-------------------------------|-------------------------|--|------------------------------------|----------------------|--|--|
| Optical system | Through-beam | | • | · | | |
| Light source (wave length) | Visible-light semicondu | sible-light semiconductor laser with a wavelength of 650 nm; JIS class1 | | | | |
| Maximum output | 0.2 mW max. | | 0.35 mW max. | | | |
| Measurement width | 1-mm dia. | 1- to 2.5-mm dia. | 5 mm | 10 mm | | |
| Measurement distance | 0 to 500 mm | 500 to 2,000 mm | 0 to 500 mm | | | |
| Minimum sensing object | 8-μm dia. (opaque) | 8- to 50-μm dia. (opaque) | 0.05-mm dia. (opaque) | 0.1-mm dia. (opaque) | | |
| Resolution*1 | 4 μm *2 | μm *2 4 μm *3 | | | | |
| Temperature characteristic | 0.2% FS/°C | .2% FS/°C | | | | |
| Ambient illumination | Incandescent lamp: 10, | ncandescent lamp: 10,000 🖄 max. (on light-receiving side) | | | | |
| Ambient temperature | Operating: 0 to 50°C, S | Dperating: 0 to 50°C, Storage: -25 to 70°C (with no icing or condensation) | | | | |
| Degree of protection | IEC60529, IP40 | EC60529, IP40 | | | | |
| Connection method | Connector relay (standa | ard cable length: 500 mm) | | | | |
| Weight (packed state) | Approx. 220 g | | | | | |
| Cable length | Extendable up to 10 m | Extendable up to 10 m with special extension cable. | | | | |
| Materials | Case: Polyetherimide, 0 | Case: Polyetherimide, Case cover: Polycarbonate, Unit cover: Glass | | | | |
| Tightening torque | 0.3 N·m max. | 0.3 N·m max. | | | | |
| Accessories | Optical axis adjustment | seal, sensor head-amplifier co | nnection cable (1.5 m), instructio | n sheet | | |

*1. This value is obtained by converting the deviation (±3\sigma) in the linear output that results when the sensor head is connected to the amplifier unit, into the measurement width.

*2. For an average count of 64. The value is 5 μm for an average count of 32. This is the value that results when a minimum sensing object blocks the light near the center of the 1-mm measurement width.

*3. For an average count of 64. The value is 5 μm for an average count of 32.

■ Amplifier Units

| Item Model | ZX-LDA11-N | ZX-LDA41-N | |
|--|--|---|--|
| Measurement period | 150 μs | | |
| Possible average count settings*1 | 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1,024, 2,048, or 4,096 | | |
| Temperature characteristic | When connected to a Reflective Sensor Head: 0.01% FS/°C, When connected to a Through-beam Sensor Head: 0.1% FS/°C | | |
| Linear output*2 | 4 to 20 mA/FS, Max. load resistance: 300 $\Omega,$ ± 4 V (\pm 5 V, 1 to 5 V *3), | Output impedance: 100 Ω | |
| Judgement outputs (3 outputs: HIGH/PASS/LOW)*1 | NPN open-collector outputs, 30 VDC, 50 mA max. Residual voltage: 1.2 V max. | PNP open-collector outputs, 30 VDC, 50 mA max. Residual voltage: 2 V max. | |
| Laser OFF input, zero reset input, timing input, reset input | ON: Short-circuited with 0-V terminal or 1.5 V or less OFF: Open (leakage current: 0.1 mA max.) | ON: Supply voltage short-circuited or supply voltage within 1.5 V OFF: Open (leakage current: 0.1 mA max.) | |
| Functions | Measurement value display, set value/light level/resolution display, sca digit changes, sample hold, peak hold, bottom hold, peak-to-peak hol reset, ON-delay timer, OFF-delay timer, one-shot timer, deviation, paut direct threshold value setting, position teaching, 2-point teaching, aut monitor focus, (A-B) calculations*4, (A+B) calculations*4, mutual inter | ing, display reverse, display OFF mode, ECO mode, number of display d, self-peak hold, self-bottom hold, intensity mode, zero reset, initial vious value comparison, sensitivity adjustment, keep/clamp switch, matic teaching, hysteresis width setting, timing inputs, reset input, ference*4, laser deterioration detection, zero reset memory, key lock | |
| Indications | Operation indicators: High (orange), pass (green), low (yellow), 7-segment main display (red), 7-segment subdisplay (yellow), laser ON (green), zero reset (green), enable (green) | | |
| Power supply voltage | 12 to 24 VDC ±10%, Ripple (p-p): 10% max. | | |
| Current consumption | 140 mA max. with power supply voltage of 24 VDC (with Sensor connected) | | |
| Ambient temperature | Operating: 0 to 50°C, Storage: -15 to 60°C (with no icing or condensation) | | |
| Ambient humidity | Operating and storage: 35% to 85% (with no condensation) | | |
| Insulation resistance | 20 MΩ min. at 500 VDC | | |
| Dielectric strength | 1,000 VAC, 50/60 Hz for 1 min | | |
| Vibration resistance (destruction) | 10 to 150 Hz, 0.7-mm double amplitude 80 min each in X, Y, and Z di | rections | |
| Shock resistance (destruction) | 300 m/s ² 3 times each in six directions (up/down, left/right, forward/backward) | | |
| Connection method | Prewired (standard cable length: 2 m) | | |
| Weight (packed state) | Approx. 350 g | | |
| Materials | Case: PBT (polybutylene terephthalate), Cover: Polycabonate | | |
| Accessories | Instruction sheet | | |

*1. The response speed of the linear output is calculated as the measurement period × (average count setting + 1) (with fixed sensitivity). The response speed of the judgement outputs is calculated as the measurement period × (average count setting + 1) (with fixed sensitivity).
*2. The output can be switched between a current output and voltage output using a switch on the bottom of the Amplifier Unit.
*3. Setting is possible via the monitor focus function.
*4. A Calculating Unit (ZX-CAL2) is required.
Note: For operating details, refer to the operation manual (Cat. No. Z157).

■ Calculating Unit

| Item | ZX-CAL2 |
|---------------------------------------|---|
| Applicable Amplifier Units | ZX-LD11-N/41-N, ZX-EDA11/41, ZX-TDA11/41 |
| Current consumption | 12 mA max. (supplied from the Smart Sensor Amplifier Unit) |
| Ambient temperature | Operating: 0 to 50°C, Storage: -15 to 60°C (with no icing or condensation) |
| Ambient humidity | Operating and storage: 35% to 85% (with no condensation) |
| Connection method | Connector |
| Dielectric strength | 1,000 VAC, 50/60 Hz for 1 min |
| Insulation resistance | 100 MΩ (at 500 VDC) |
| Vibration resistance (destructive) | 10 to 150 Hz, 0.7-mm double amplitude 80 min each in X, Y, and Z directions |
| Shock resistance (destructive) | $300\mbox{ m/s}^2$ 3 times each in six directions (up/down, left/right, forward/backward) |
| Materials | Display: Acrylic, Case: ABS resin |
| Weight (packed state) | Approx. 50 g |
| Accessories | Instruction sheet |

ZX-series Communications **Interface Unit**

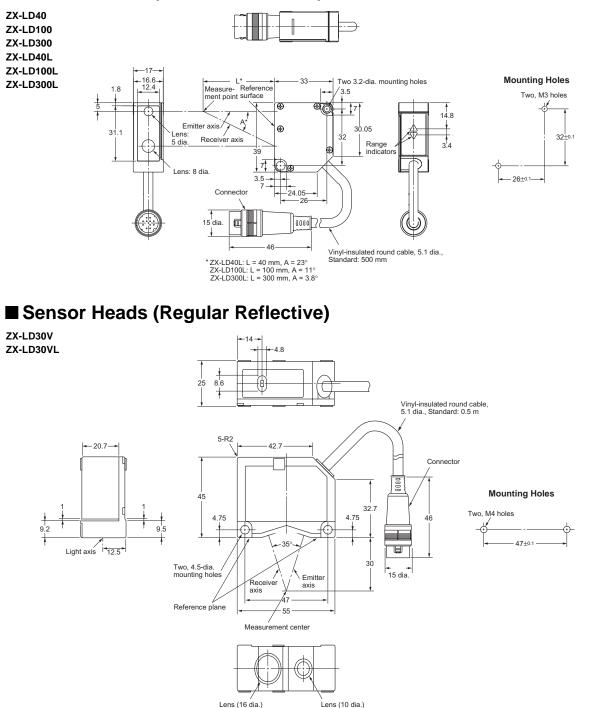
| | Item | ZX-SF11 | | |
|---------------------------------------|------------------------------|---|--|--|
| Current co | onsumption | 60 mA max. (supplied by the Amplifier Unit) | | |
| Applicable | Amplifier Units | ZX Series | | |
| Applicable Amplifier Unit versions | | ZX-LDA⊟1-N Ver. 1.000 or higher ZX-EDA⊟1 Ver. 1.100 or higher ZX-TDA⊡1 Ver. 1.000 or higher | | |
| Max. No. o | f Amplifier Units | 5 | | |
| Commu- nications | Communica- tions port | RS-232C port (9-pin D-Sub Connector) | | |
| functions | Communica- tions protocol | CompoWay/F* | | |
| | Baud rate | 38,400 bps | | |
| | Data configura- tion | Data bits: 8, Parity: none, Start bits: 1, Stop bits: 1, Flow con- trol: none | | |
| Indicators | | Power supply: green, Sensor communications: green, Sen- sor communications error: red, External terminal communi- cations: green, External terminal communications error: red | | |
| Protective | circuits | Reverse polarity protection | | |
| Ambient te | emperature | Operating: 0 to 50°C, storage: -15 to 60°C (with no icing or condensation) | | |
| Ambient h | umidity | Operating and storage: 35% to 85% (with no condensation) | | |
| Insulation | resistance | 20 MΩ min. (at 500 VDC) | | |
| Dielectric : | strength | 1,000 VAC, 50/60 Hz for 1 min, Leakage current: 10 mA max. | | |
| Materials | | Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | | |
| Accessorie | es | Instruction sheet, 2 clamps | | |

* Contact your OMRON representative for CompoWay/F communications specifications.

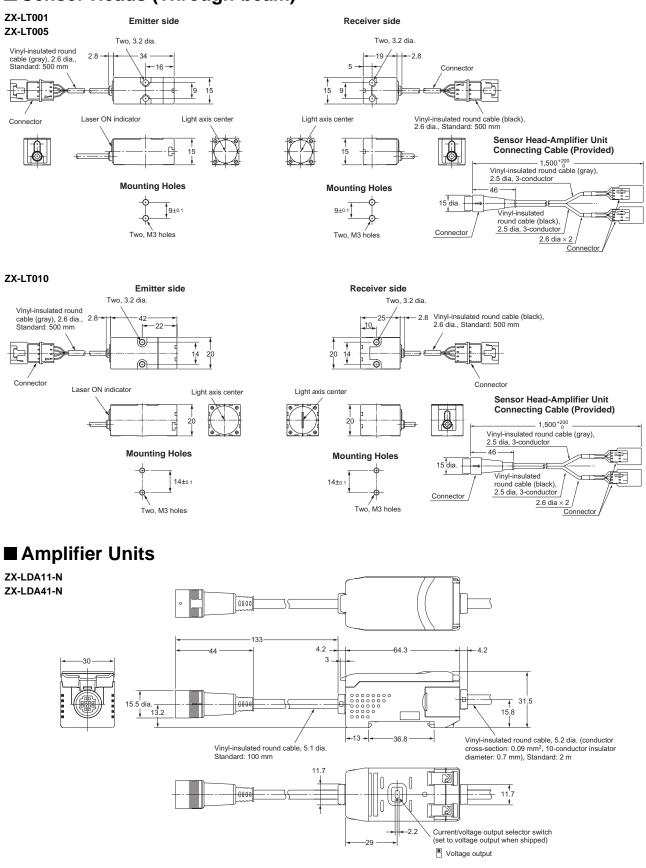
ZX Series (ZX-L-N) Smart Sensors 14

(Unit: mm)

Sensor Heads (Diffuse Reflective)

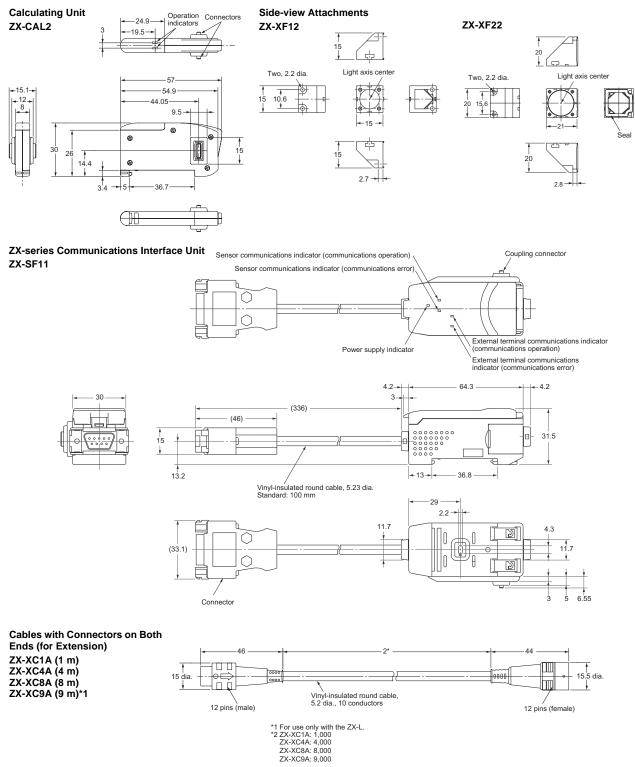


Sensor Heads (Through-beam)



16 **ZX Series (ZX-L-N)** Smart Sensors

■ Accessories (Order Separately)



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Sensors

Sensor Heads

| Shape | Dimensions | Sensing distance | Resolution *1 | Model |
|-----------------------------|------------------|------------------|---------------|----------------|
| Cylindrical | 3 dia. x 18 mm | 0.5 mm | 1 μm | ZX-EDR5T |
| | 5.4 dia. x 18 mm | 1 mm | | ZX-ED01T *2 |
| | 8 dia. x 22 mm | 2 mm | | ZX-ED02T *2 |
| Screw-shaped | M10 x 22 mm | | | ZX-EM02T *2 |
| | M18 x 46.3 mm | 7 mm | | ZX-EM07MT *2 |
| Flat | 30 x 14 x 4.8 mm | 4 mm | | ZX-EV04T *2 *3 |
| Heat-resistant, cylindrical | M12 x 22 mm | 2 mm | | ZX-EM02HT *4 |

*1. For an average count of 4096.

*2. Models with Protective Spiral Tubes are also available. Add a suffix of "-S" to the above model numbers when ordering. (Example: ZX-ED01-S)

*3. Be sure to use ZX-EDA \Box Amplifier Unit version 1,200 or later with the ZX-EV04T.

*4. Be sure to use ZX-EDA Amplifier Unit version 1,300 or later with the ZX-EM02HT.

Amplifier Units

| Appearance | Power supply | Output type | Model |
|------------|--------------|-------------|----------|
| | DC | NPN | ZX-EDA11 |
| | | PNP | ZX-EDA41 |

Note: Compatible connection with the Sensor Head.

Accessories (Order Separately)

Amplifier Mounting Brackets

| Appearance | Model | Remarks |
|------------|---------|------------------------------------|
| S | ZX-XBE1 | Attached to each Sensor Head |
| | ZX-XBE2 | For DIN track mounting |

ZX-CAL2 Calculating Unit

Refer to pages 12 and 14 for details.

ZX-SF11 ZX-series Communications Interface Unit

Refer to pages 12 and 14 for details.

ZX-XC A Cable with Connectors on Both

Ends (for Extension)

Refer to page 12 for details.

ZX-SW11V3 Smart Monitor Sensor Setup Tool for Personal Computer Connection

Refer to page 12 for details.

Specifications

Sensor Heads

| | | Model | ZX-EDR5T | ZX-ED01T | ZX-ED02T/ EM02T | ZX-EM07MT | ZX-EV04T | ZX-EM02HT |
|---|----------------|--------------------|---|---|--------------------|----------------------|--------------------------|------------------------------------|
| Measurement rang | je | | 0 to 0.5 mm | 0 to 1 mm | 0 to 2 mm | 0 to 7 mm | 0 to 4 mm | 0 to 2 mm |
| Sensing object | | | Magnetic metals (| Measurement ra | nges and linearit | ies are different fo | or non-magnetic | metals.) |
| Standard reference | e object | | $18 \times 18 \times 3$ mm | $30 \times 30 \times 3$ mm $60 \times 60 \times 3$ mm | | | | $45 \times 45 \times 3 \text{ mm}$ |
| | | | Material: ferrous (| S50C) | • | • | | • |
| Resolution *1 | | | 1 μm | | | | | |
| Linearity *2 | | | ±0.5% F.S. | | | | | ±1.0% F.S. *5 |
| Linear output rang | je | | Same as measure | ement range. | | | | |
| Temperature characteristic *3 (including Amplifier Unit) | | | 0.15% F.S./°C | 0.07% F.S./°C | | | | 0.1% F.S./°C |
| Ambient temper- Operating *4 | | ig *4 | 0 to 50°C (with no | -10 to 60°C (wit | h no icing or con | densation) | | -10 to 200°C |
| ature Storage *4 | | | icing or conden- sation) | nden20 to 70°C (with no icing or condensation) | | | | |
| Ambient humidity | | | Operating and storage: 35% to 85% (with no condensation) | | | | | |
| Insulation resistar | ice | | 50 MΩ min. (at 500 DC) | | | | | |
| Dielectric strength | 1 | | 1,000 VAC, 50/60 Hz for 1 min between charged parts and case | | | | | |
| Vibration resistant | ce (dest | ruction) | 10 to 55 Hz with 1.5-mm double amplitude for 2 h each in X, Y, and Z directions | | | | | |
| Shock resistance | (destruc | tion) | 500 m/s ² , 3 times each in X, Y, and Z directions | | | | | |
| Degree of protection | on (Sen | sor Head) | IEC60529, IP65 | IEC60529, IP67 | | | | IEC60529, IP60 *6 |
| Connection metho | d | | Connector relay (s | standard cable le | ngth: 2 m) | | | |
| Weight (packed sta | ate) | | Approx. 120 g | Approx. 140 g | | Approx. 160 g | Approx. 130 g | Approx. 160 g |
| Materials | Sensor Head | Case | Brass | Stainless steel | Brass | | Zinc (nickel- plated) | Brass |
| | | Sensing surface | Heat-resistant ABS | | | | PEEK | |
| | Preampl | ifier | PES | | | | | |
| Accessories | | | Amplifier Mounting | Mounting Brackets (ZX-XBE1), Instruction Manual | | | | |

*1. Resolution: The resolution is the deviation (±3 s) in the linear output when connected to the ZX-EDA Amplifier Unit. The above values indicate the deviations observed 30 minutes after the power is turned ON.

(The resolution is measured with OMRON's standard reference object at 1/2 of the measurement range with the ZX-EDA set for the maximum average count of 4096.)

The resolution is given at the repeat accuracy for a stationary workpiece, and is not an indication of the distance accuracy. The resolution may be adversely affected under strong electromagnetic fields.

*2. Linearity: The linearity is given as the error in an ideal straight line displacement output when measuring the standard reference object. The linearity and measurement values vary with the object being measured.

*3. Temperature characteristic: The temperature characteristic is measured with OMRON's standard reference object at 1/2 of the measurement range.

*4. The ambient temperature given is only for the sensor head. It is -10 to 60°C for the preamp.

*5. The value given is for an ambient temperature of 25°C.

*6. Do not use in moist environments because the case is not waterproof.

■ Amplifier Units

| Model | ZX-EDA11 | ZX-EDA41 | | | |
|--|---|--|--|--|--|
| Measurement period | 150 μs | | | | |
| Possible average count settings *1 | 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1,024, 2,048, or 4,096 | | | | |
| Linear output *2 | Current output: 4 to 20 mA/F.S., Max. load resistance: 300 Ω | | | | |
| | Voltage output: \pm 4 V (\pm 5 V, 1 to 5 V *3), Output impe | edance: 100 Ω | | | |
| Judgement outputs | NPN open-collector outputs, 30 VDC, 50 mA max. | PNP open-collector outputs, 30 VDC, 50 mA max. | | | |
| (3 outputs: HIGH/PASS/LOW) | Residual voltage: 1.2 V max. | Residual voltage: 2 V max. | | | |
| Zero reset input, timing input, reset input, judgement output hold input | ON: Short-circuited with 0-V terminal or 1.5 V or less | ON: Supply voltage short-circuited or supply volt- age within 1.5 V | | | |
| input, judgement output noid input | OFF: Open (leakage current: 0.1 mA max.) | OFF: Open (leakage current: 0.1 mA max.) | | | |
| Function | Measurement value display Present value/set value/output value/resolution display Linearity adjustment (materials selection) Display reverse Display OFF mode Number of display digit changes Sample hold Self-bottom Self-bottom | | | | |
| Indications | Judgement indicators: High (orange), pass (green), low (yellow), 7-segment main digital display (red), 7-segment sub-digital display (yellow), power ON (green), zero reset (green), enable (green) | | | | |
| Voltage influence (including Sensor) | 0.5% F.S. of linear output value at $\pm 20\%$ of power supply voltage | | | | |
| Power supply voltage | 12 to 24 VDC ±10%, Ripple (p-p): 10% max. | | | | |
| Current consumption | 140 mA max. with power supply voltage of 24 VDC (| , , , , , , , , , , , , , , , , , , , | | | |
| Ambient temperature | Operating and storage: 0 to 50°C (with no icing or co | , | | | |
| Ambient humidity | Operating and storage: 35% to 85% (with no conder | nsation) | | | |
| Insulation resistance | 20 MΩ min. (at 500 DC) | | | | |
| Dielectric strength | 1,000 VAC, 50/60 Hz for 1 min | | | | |
| Vibration resistance (destruction) | 10 to 150 Hz with 0.7-mm double amplitude for 80 m | | | | |
| Shock resistance (destruction) | 300 m/s ² , 3 times each in 6 directions (up, down, left | t, right, forward, backward) | | | |
| Connection method | Prewired (standard cable length: 2 m) | | | | |
| Weight (packed state) | Approx. 350 g | | | | |
| Materials | Case: PBT (polybutylene terephthalate), Cover: Poly | ycarbonate | | | |
| Accessories | Instruction Manual | | | | |

*1. The response speed of the linear output is calculated as the measurement period × (average count setting + 1).

The response speed of the judgement outputs is calculated as the measurement period imes (average count setting + 1).

*2. The output can be switched between a current output and voltage output using a switch on the bottom of the Amplifier Unit.

*3. A Calculating Unit (ZX-CAL2) is required. Setting is possible via the monitor focus function.

*4. A Calculating Unit (ZX-CAL2) is required.

Note: For operating details, refer to the operation manual (Cat. No. Z166).

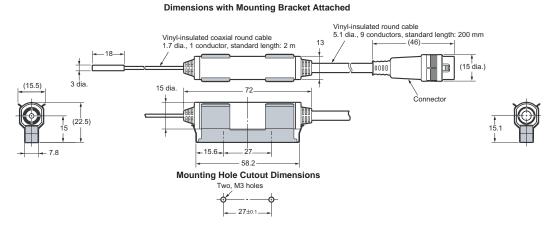
22 ZX Series (ZX-E) Smart Sensors (Inductive Displacement Type)

Dimensions

Sensors

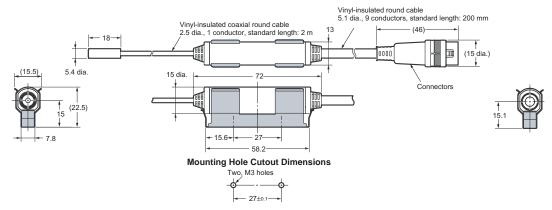
Sensor Heads

ZX-EDR5T



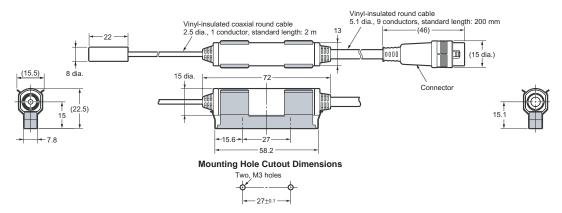
ZX-ED01T

Dimensions with Mounting Bracket Attached



ZX-ED02T

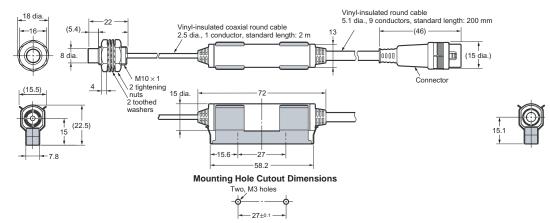
Dimensions with Mounting Bracket Attached



ZX Series (ZX-E) Smart Sensors (Inductive Displacement Type) 23

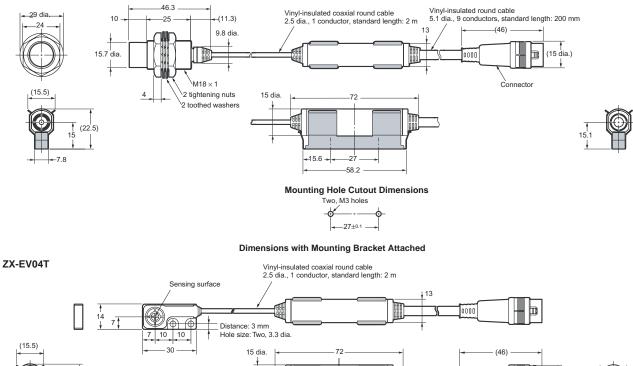
Dimensions with Mounting Bracket Attached

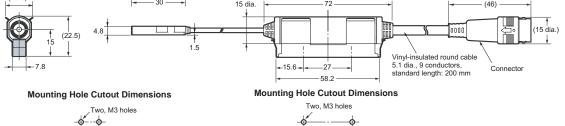
15 1



ZX-EM07MT

Dimensions with Mounting Bracket Attached

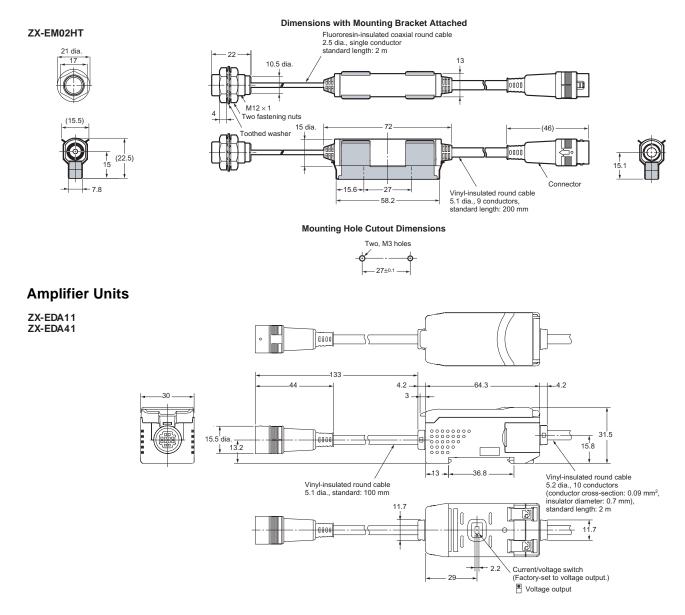




27±0.1

24 **ZX Series (ZX-E)** Smart Sensors (Inductive Displacement Type)

10±0.1

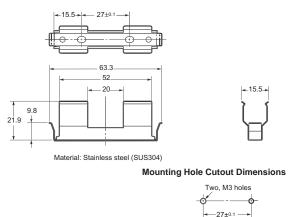


ZX Series (ZX-E) Smart Sensors (Inductive Displacement Type) 25

Accessories (Sold Separately)

Preamplifier Mounting Brackets

ZX-XBE1



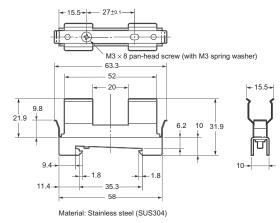
ZX-CAL2 Calculating Unit

Refer to page 17 for details.

ZX-SF11 ZX-series Communications Interface Unit

Refer to page 17 for details.

ZX-XBE2



ZX-XC1A (1 m), ZX-XC4A (4 m), ZX-XC8A (8 m) Cables with Connectors on Both Ends (for Extension)

Refer to page 17 for details.

26 ZX Series (ZX-E) Smart Sensors (Inductive Displacement Type)

-

Sensors

Sensor Heads

| Size | Туре | Sensing distance | Resolution (See note.) | Model |
|--------|----------------------|------------------|------------------------|-------------|
| 6 dia. | Short type | 1 mm | 0.1 μm | ZX-TDS01T |
| 6 dia. | Standard type | 4 mm | 0.1 μm | ZX-TDS04T |
| 6 dia. | Low measurement type | 4 mm | 0.1 μm | ZX-TDS04T-L |

Note: The resolution refers to the minimum value that can be read when a ZX-TDA 1 Amplifier Unit is connected.

■ Amplifier Units

| Appearance | Power supply | Output type | Model |
|------------|--------------|-------------|----------|
| TE STATE | DC | NPN | ZX-TDA11 |
| | | PNP | ZX-TDA41 |

■ Accessories (Order Separately)

Preamplifier Mounting Brackets

| Appearance | Model | Remarks |
|------------|---------|---------------------------------|
| | ZX-XBT1 | Attached to each Sensor Head |
| | ZX-XBT2 | For DIN track mount- ing |

ZX-CAL2 Calculating Unit

Refer to pages 12 and 14 for details.

ZX-SF11 ZX-series Communications Interface Unit

Refer to pages 12 and 14 for details.

ZX-XC A Cable with Connectors on Both

Ends (for Extension)

Refer to page 12 for details.

ZX-SW11V3 Smart Monitor Sensor Setup Tool for Personal Computer Connection

Refer to page 12 for details.

Sensor Heads

| lte | m | ZX-TDS01T | ZX-TDS04T | ZX-TDS04T-L | | |
|--------------------------------------|-------------------|--|-----------------------------|----------------|--|--|
| Measurement rang | je | 1 mm | 4 mm | | | |
| Maximum actuator | r travel distance | Approx. 1.5 mm | Approx. 5 mm | | | |
| Resolution *1 | | 0.1 μm | | | | |
| Linearity *2 | | 0.3% F.S. | | | | |
| Operating force *3 | | Approx. 0.7 N | | Approx. 0.25 N | | |
| Degree of protecti | on (Sensor Head) | IEC60529, IP67 | | IEC60529, IP54 | | |
| Mechanical durabi | lity | 10,000,000 operations min. | | | | |
| Ambient temperate | ure | Operating: 0°C to 50°C (with no icing or condensation) Storage: –15°C to 60°C (with no icing or condensation) | | | | |
| Ambient humidity | | Operating and storage: 35% to 85% (with no icing or condensation) | | | | |
| Temperature | Sensor Head | 0.03% F.S./°C | 0.03% F.S./°C 0.01% F.S./°C | | | |
| characteristic *4 | Preamplifier | 0.01% F.S./°C | | | | |
| Vibration resistand (destruction) | ce | 10 to 55 Hz with 0.35-mm single amplitude in the X, Y, and Z directions | | | | |
| Shock resistance (destruction) | | 150 m/s ² , 3 times each in the X, Y, and Z directions | | | | |
| Connection metho | d | Connector relay (standard cable length: 2 m) | | | | |
| Isolation | | Isolated (Sensor Head enclosure and I/O lines) | | | | |
| Weight (packed st | ate) | Approx. 100 g | | | | |
| Materials | Sensor Head | Stainless steel | | | | |
| | Rubber boot | Fluorocarbon rubber | Silicon rubber | | | |
| | Preamplifier | Polycarbonate | | | | |
| Accessories | | Instruction manual, Preamplifier Mounting Brackets (ZX-XBT1) | | | | |

*1. The resolution is given as the minimum value that can be read when a ZX-TDA
1 Amplifier Unit is connected. This value is taken 15 minutes after turning ON the power with the average number of operations set to 256.

*2. The linearity is given as the error in an ideal straight line displacement output.

*3. These figures are representative values that apply for the measurement mid-point, and are for when the provided actuator is used, with the actuator moving downwards. If the actuator moves horizontally or upwards, the operating force will be reduced. Also, if an actuator other than the standard one is used, the operating force will vary with the weight of the actuator itself.

*4. These figures are representative values that apply for the mid-point of the measurement range.

ZX Series (ZX-T) Smart Sensors (High-precision Contact Type) 31

■ Amplifier Units

| ZX-TDA11 | | ZX-TDA41 | | | |
|--|--|--|--|--|--|
| 1 ms | | | | | |
| 2, 4, 8, 16, 32, 64, 128, 256, 512, or 1,024 | | | | | |
| Current output: 4 to 20 mA/F.S., Max. load resistance: 300 Ω Voltage output: ±4 V (±5 V, 1 to 5 V), Output impedance: 100 \pm | 2 | | | | |
| NPN open-collector outputs, 30 VDC, 30 mA max. Residual voltage: 1.2 V max. | | PNP open-collector outputs, 30 VDC, 30 mA max. Residual voltage: 2 V max. | | | |
| ON: Short-circuited with 0-V terminal or 1.5 V or less OFF: Open (leakage current: 0.1 mA max.) | | ON: Supply voltage short-circuited or supply voltage of 1.5 V or less OFF: Open (leakage current: 0.1 mA max.) | | | |
| Display reverse - ECO mode - Number of display digit changes Sample hold - Peak hold - Bottom hold, peak-to-peak hold Self-peak hold - Self-bottom hold - Zero reset Initial reset - Direct threshold value setting - Position teaching Hysteresis width setting - Timing inputs - Reset input Judgement output hold input - Monitor focus - (A-B) calculations *4 Carbor set memory - Function lock - Non-measurement setting Clamp value setting - Sele inversion - Zero reset indicator | | | | | |
| Judgement indicators: High (orange), pass (green), low (yellow), 7-segment main digital display (red), 7-segment sub-digital display (yellow), power ON (green), zero reset (green), enable (green) | | | | | |
| 12 to 24 VDC ±10%, Ripple (p-p): 10% max. | | | | | |
| 140 mA max. (with Sensor connected), For 24-VDC power sup | ply: 140 m | A max. (with Sensor connected) | | | |
| Operating and storage: 0 to 50°C (with no icing or condensation | n) | | | | |
| Operating and storage: 35% to 85% (with no icing or condensation | ition) | | | | |
| 0.03% F.S./°C | | | | | |
| 20 MΩ min. at 500 VDC | | | | | |
| 1,000 VAC, 50/60 Hz for 1 min | | | | | |
| 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in | X, Y, and Z | Z directions | | | |
| 300 m/s², 3 times each in six directions (up, down, left, right, forward, backward) | | | | | |
| Prewired (standard cable length: 2 m) | | | | | |
| Approx. 350 g | Approx. 350 g | | | | |
| Case: PBT (polybutylene terephthalate), Cover: Polycarbonate | | | | | |
| Instruction sheet | | | | | |
| | 1 ms 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, or 1,024 Current output: 4 to 20 mA/F.S., Max. load resistance: 300 Ω Voltage output: ±4 V (±5 V, 1 to 5 V), Output impedance: 100 Ω NPN open-collector outputs, 30 VDC, 30 mA max. Residual voltage: 1.2 V max. ON: Short-circuited with 0-V terminal or 1.5 V or less OFF: Open (leakage current: 0.1 mA max.) • Measurement value display - Present value • Display reverse - ECO mode • Sample hold - Peak hold • Self-peak hold - Self-bottom f • Hysteresis width setting - Timing inputs • Judgement output hold input - Monitor focus • Zero reset memory - Function lock • Zero reset memory - Scale inversit • Judgement indicators: High (orange), pass (green), low (yellow ON (green), zero reset (green), enable (green) ON (green), zero reset (green), enable (green) 12 to 24 VDC ±10%, Ripple (p-p): 10% max. 140 mA max. (with Sensor connected), For 24-VDC power sup Operating and storage: 35% to 85% (with no icing or condensatio 0.03% F.S./*C 20 MΩ min. at 500 VDC 1,000 VAC, 50/60 Hz for 1 min 10 to 150 Hz with 0.7-mm double amplitude for 80 min each in 300 m/s | 1 ms 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, or 1,024 Current output: 4 to 20 mA/F.S., Max. load resistance: 300 Ω Voltage output: ±4 V (±5 V, 1 to 5 V), Output impedance: 100 Ω NPN open-collector outputs, 30 VDC, 30 mA max. Residual voltage: 1.2 V max. ON: Short-circuited with 0-V terminal or 1.5 V or less OFF: Open (leakage current: 0.1 mA max.) • Measurement value display - Present value/set value - Display reverse - ECO mode - Sample hold - Self-bottom hold - Initial reset - Direct threshold value set - Judgement output hold input - Monitor focus - Zero reset memory - Function lock - Clamp value setting - Scale inversion - Sudjustment - Warming-up display Judgement indicators: High (orange), pass (green), low (yellow), 7-segmed ON (green), zero reset (green), enable (green) VON (green), zero reset (green), enable (green) 12 to 24 VDC ±10%, Ripple (p-p): 10% max. 140 mA max. (with Sensor connected), For 24-VDC power supply: 140 m Operating and storage: 0 to 50°C (with no icing or condensation) 0.03% F.S./°C 20 MΩ min. at 500 VDC 1,000 VAC, 50/60 Hz for 1 min 1 | | | |

*1. The response speed of the linear output is calculated as the measurement period × (average count setting + 1). The response speed of the judgement outputs is calculated as the measurement period × (average count setting + 1).

*2. The output can be switched between a current output and voltage output using a switch on the bottom of the Amplifier Unit.

*3. Setting is possible via the monitor focus function.

*4. A Calculating Unit (ZX-CAL2) is required.

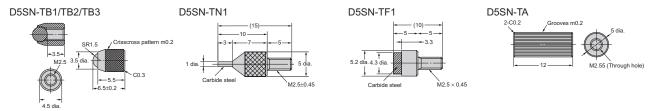
Note: For operating details, refer to the operation manual (Cat. No. E346) provided by OMRON.

Options (Actuators)

| м | odel | Type (material) | Screw section | Appearance | Application | Applicable Sensor * ZX-TDS□T |
|-------|------|---|---|------------|---|---------------------------------|
| D5SN- | TB1 | Ball type (steel) Female screw M2.5 x 0.45 | | | Measuring ordinary flat surfaces (standard actuator supplied with the ZX-TDS Series) | \bigcirc |
| | TB2 | Ball type (carbide steel) | Female screw M2.5 x 0.45 | | Measurements where abrasion resistance is critical Measured objects: Carbide (HR90) or lower. | \bigcirc |
| | ТВ3 | Ball type (ruby) | Female screw M2.5 x 0.45 | | Measurements where abrasion resistance is critical Measured objects: Carbide (HR90) or higher. | \bigcirc |
| | TN1 | Needle type (carbide steel) | Male screw M2.5 x 0.45 | | Measuring the bottom of grooves and holes | \triangle |
| | TF1 | Flat (carbide steel) | Male screw M2.5 x 0.45 | | Measuring spherical objects | \triangle |
| | ТА | Conversion Adapter (stainless steel) | Through-hole fe- male screw M2.5 x 0.45 | | Mounting D5SN-TN1/-TF1 or commercially available actuators on ZX-TDS-series Sensors | \bigcirc |

Note: For optional Actuator combinations, the circle means the Actuator is replaceable and the triangle means that a Conversion Adapter is required.

Dimensions

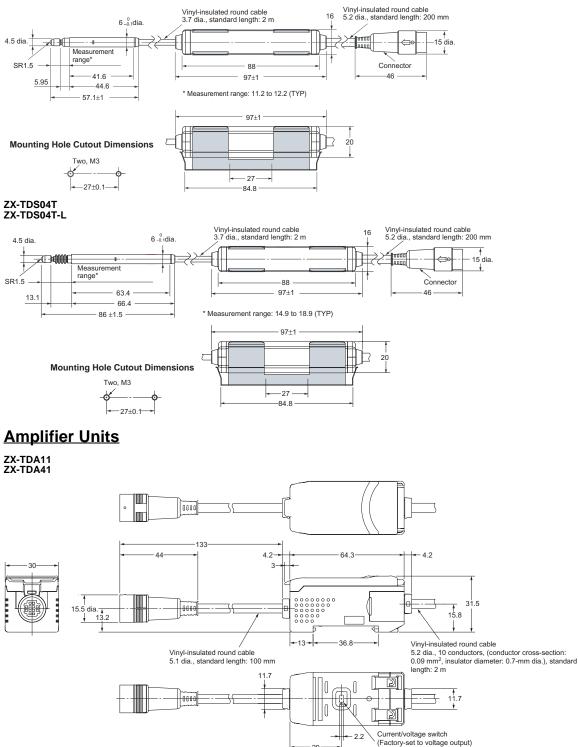


32 **ZX Series (ZX-T)** Smart Sensors (High-precision Contact Type)

Dimensions

Sensors

ZX-TDS01T



ZX Series (ZX-T) Smart Sensors (High-precision Contact Type) 33

Voltage output

2.2

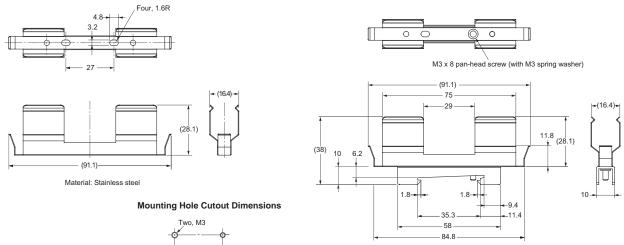
■ Accessories (Order Separately)

Preamplifier Mounting Bracket (Supplied with Each Sensor)

ZX-XBT1



Material: Stainless steel



ZXCAL2 Calculating Unit

Refer to page 17 for details.

ZX-SF11 ZX-series Communications Interface Unit

Refer to page 17 for details.

ZX-XC1A (1 m), ZX-XC4A (4 m), ZX-XC8A (8 m) Cables with Connectors on Both Ends (for Extension)

Refer to page 17 for details.

34 **ZX Series (ZX-T)** Smart Sensors (High-precision Contact Type)

Precautions

Design Precautions

Conform to the specified ratings and performance. Refer to the *Specifications* for each product on the following pages.

ZX-L: Pages 13 and 14

ZX-E: Pages 21 and 22

ZX-T: Pages 31 and 32

Environment

Do not operate the product in locations subject to flammable or explosive gases.

In order to ensure safe operation and maintenance, do not install the product in the vicinity of high-voltage devices or power equipment.

Correct Use

This product consists of precision parts that may fail if it is dropped.

Design Precautions

Compatibility

Sensors and Amplifier Units are mutually compatible. Sensors can be added or replaced individually.

Influence of High-frequency Electromagnetic Fields

Using the product in the vicinity of devices that generate high-frequency electromagnetic fields, such as ultrasonic cleaning equipment, high-frequency generators, transceivers, mobile phones, and inverters, may result in malfunction.

Wiring

Wiring Check

After wiring is completed, before turning ON the power, confirm that the power supply is connected correctly, that there are no faulty connections, such as load short-circuits, and that the load current is correct. Incorrect wiring may result in failure.

Cable Extension

Do not extend the cable for the Sensor and the Amplifier Unit to a length exceeding 10 m. Use a ZX-XC A Extension Cable (sold separately) to extend the Sensor's cable. Extend the Amplifier Unit's cable using a shielded cable of the same type.

Wiring

Do not use the product at voltages exceeding the rated values. Doing so may result in damage.

Do not connect the product to an AC power supply or connect the power supply in reverse.

Do not short loads connected to open-collector outputs.

Do not lay the cable for the product together with or in the same duet as high-voltage lines or power lines. Doing so may result in incorrect operation or damage due to induction.

Other Precautions

Do not attempt to disassemble, repair, or modify the product.

Dispose of the product using standard procedures for industrial waste.

Do not connect combinations of ZX-L -, ZX-E -, and ZX-T -series Smart Sensors.

Power Supply

When using a commercially available switching regulator, ground the FG (frame ground) terminal.

If the power supply line is subject to surges, connect a surge absorber that meets the conditions of the operating environment.

Calculating Unit

When using a Calculating Unit, connect the linear output ground of the corresponding Amplifier Unit.

Connectors

Do not connect or disconnect connectors while the power is ON.

Be sure hold to connectors by the cover when connecting or disconnecting.

Installation Location

Do not install the product in the following locations.

- Locations subject to temperatures outside the specified range
 Locations subject to condensation due to sudden temperature
- changesLocations subject to humidity levels outside range 35% to 85%
- Locations subject to corrosive or flammable gases
- Locations subject to dust, salts, or metallic powder.
- · Locations directly subject to vibrations and shocks
- Locations subject to splashes of water, oil, or chemicals
- · Locations subject to strong electromagnetic or electrical fields

Maintenance and Inspection

- Be sure to turn OFF the power supply before adjusting or removing the Sensor Head.
- Cleaning: Do not use thinners, benzine, acetone, or kerosene for cleaning.

Terms and Conditions of Sale

- Offer: Acceptance. These terms and conditions (these "Terms") are deemed part of all quotes, agreements, purchase orders, acknowledgments, price lists, catalogs, manuals, brochures and other documents, whether electronic or in writing, relating to the sale of products or services (collectively, the "<u>Products</u>") by Omron Electronics LLC and its subsidiary companies ("<u>Omron</u>"). Omron objects to any terms or conditions proposed in Buyer's purchase order or other
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- Governmental Approvals. Buyer shall be responsible for, and shall bear all 6 costs involved in, obtaining any government approvals required for the impor-tation or sale of the Products.
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 a. Shipments shall be by a carrier selected by Omron; Omron will not drop ship except in "break down" situations.
 - b. Such carrier shall act as the agent of Buyer and delivery to such carrier shall constitute delivery to Buyer; c. All sales and shipments of Products shall be FOB shipping point (unless of
 - erwise stated in writing by Omron), at which point title and risk of loss shall pass from Omron to Buyer; provided that Omron shall retain a security interest in the Products until the full purchase price is paid; d. Delivery and shipping dates are estimates only; and e. Omron will package Products as it deems proper for protection against nor-
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- Warranties. (a) Exclusive Warranty. Omron's exclusive warranty is that the Products will be free from defects in materials and workmanship for a period of twelve months from the date of sale by Omron (or such other period expressed 13 (b) <u>Limitations</u>. OMRON MAKES NO WARRANTY OR REPRESENTATION, EXPRESS OR IMPLIED, ABOUT NON-INFRINGEMENT, MERCHANTABIL-

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 (ii) Outdoor use, uses involving potential chemical contamination or electrical interference, or conditions or uses not described in this document.

 (ii) Use in consumer products or any use in significant quantities.
 (iii) Energy control systems, combustion systems, railroad systems, aviation systems, medical equipment, amusement machines, vehicles, safety equip-(iv) Systems, machines and equipment that could present a risk to life or prop-erty. Please know and observe all prohibitions of use applicable to this Product

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ALL DIMENSIONS SHOWN ARE IN MILLIMETERS. To convert millimeters into inches, multiply by 0.03937. To convert grams into ounces, multiply by 0.03527.

OMRON.

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