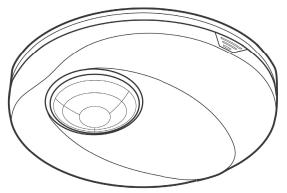




Surface Mount Presence Detector PDSM362 / PDSM361 Instructions



Models PDSM362 / PDSM361

Technical Specifications

230V~ ±10% 50Hz

Loads

Rated Voltage:

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PDSM362 (2 channels):

Load I ($L\Psi$) for Lighting: μ (contact seperation) Incandescent lamp: max. 2000W Mains halogen lamp: max. 1000W LV halogen lamp: max. 600VA

Fluorescent lamp: max. 900VA/100µF Load II (D1-D2) for HVAC:

Max. 5A (cosØ =1) 250VAC or 30VDC Max: 1/10HP (73W)

PDSM361 (1 channel):

Load I ($L\Psi$) for Lighting: μ (contact seperation) Incandescent lamp: max. 2000W Mains halogen lamp: max. 1000W LV halogen lamp: max. 600VA Fluorescent lamp: max. 900VA/100µF

Timer Adjustment (constant adjustment)

PDFM362:

TIME1 (for lighting): Adjustable from 5sec to 20min (continuously adjustable) TIME2 (for HVAC): Adjustable from 10sec to 60min (continuously adjustable)

PDFM361:

TIME: Adjustable from 5sec to 20min (continuously adjustable)

Downloaded from Floring components distributoroLUX to 2000LUX

METER Adjustment

THREE YEAR

GUARANTER

Adjustable continuously from + giving maximum detection coverage at floor level to - giving a substantially reduced detection coverage at floor level

Operating Temperature

Environmental Protection

All procedures indicated in this manual must be carried out by a professional installer.

0°C to +45°C

Class II, IP40

Package Contents

Visual I.D.		Surface Mount Prosece Detector POSM327 / FOSM251 Hosting	Commune Commune	anne anne	
Item	Sensor	Instructions	Wood screw Ø4 x 25.4mm	Self-tapping screw Ø3 x 10mm	IR-10 (optional purchase)
Quantity	1	1	2	2	

2 Product Description

2.1 Features

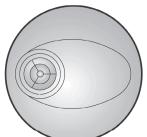
The PDSM362 / PDSM361 controller is a ceiling surface mount presence detector for indoor applications in commercial and domestic locations. PDSM361 covers lighting applications only, whereas PDSM362 can control lighting and HVAC (heating, ventilating and air conditioning) applications.

Adjustment of Time and LUX values can be made either by the dial controls on the sensor body or by the IR-10 Infrared remote control.

- PDSM362 has two relays for outputs load I and load II: load I is for lighting control and load II has voltage free contacts for HVAC control which operate at all LUX (light) levels.
- The sensor has a very high density of sensitive beams covering the detection area. These are evenly distributed ensuring no dead spots and detection of the smallest movements.
- Either side or bottom cable entry.
- Built-in red LED in sensor giving confirmation of remote control settings and easy test operation.

2.2 Dimensions (see Fig.1)





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Please disconnect power completely and read the entire instruction manual carefully before installation.

3.1 Select the required location

3.1.1 Sensor adjustment

Fig. 2 shows the way coverage alters with ceiling height and with adjustments of the METER dial setting.

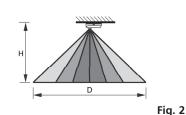
Section 4.2.3 shows how tilting and rotating the sensor can produce different fields of coverage.

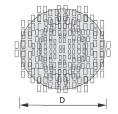
Side View

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Top View (showing individual beam pattern at floor level)





Ceiling Height (H) **Detection Coverage Diameter (D)**

	WITH MELER ON -
2m	7m
2.5m	7m
3m	10m
3.5m	12m
4m	12m
4.5m	12m

If the METER control is turned to - the coverage diameter is substantially reduced.

We do not recommend the use of these units with ceiling heights greater than 4.5m.

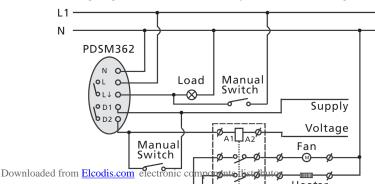
3.1.2 Helpful tips for installation

As the sensor responds to temperature change or moving heat sources, please avoid the following conditions:

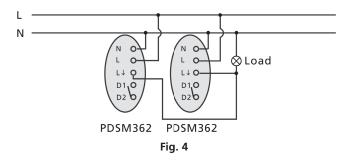
- Avoid highly reflective surfaces within the detection range.
- Avoid movable objects e.g. curtains and plants in the detection range (these may cause erronious detections when moved by air flow from fans or air conditioner).
- Avoid heat sources (e.g. heating vents, radiators, air conditioners and filament lamps) in detection range.
- · Avoid fans drawing air across the sensor lens.

3.2 Wiring

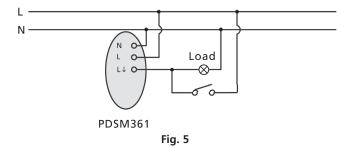
3.2.1 Lighting and HVAC are controlled by one PDSM362 (see Fig.3).



3.2.2 Lighting is controlled by two PDSM362's to enlarge detection range (see Fig.4).



3.2.3 Lighting is controlled by a PDSM361 (see Fig. 5).

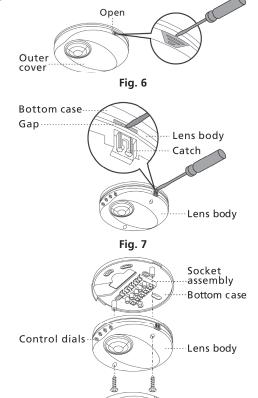


3.3 Installation procedure

3.3.1 Insert large flat blade screwdriver into the groove as shown each side in turn and twist (see Fig. 6) to remove outer cover.

3.3.2 To separate bottom case from lens body force a small flat blade screwdriver into the hidden gap shown partially exposed in Fig. 7 then push screwdriver in towards centre and lever bottom case assembly away from lens body pins.

3.3.3 Remove cardboard and screws used to assemble and fix the sensor (see Fig. 8).



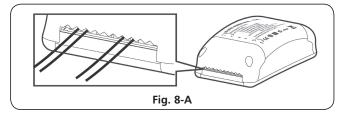
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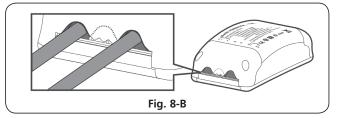
3.3.2 (cont). The protection covers have teeth (see Fig. 8-A) giving a degree of cable clamping if power and load are connected by individual wires (0.8 -1.8mm dia.)

If connection is by cable (9 - 11mm dia.) then use of a coarse rat-tailed file to open out as many of the holes as necessary using the markings on the inside of the protection cover as an approximate guide (see Fig. 8-B).

Referring it to the appropriate wiring diagram insert the wires into the correct screw terminals and tighten fully. Then plug the sensor lead into SENSOR A socket only.

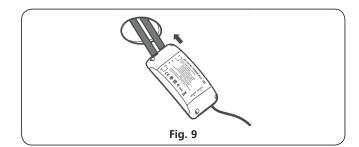
Use the coarse rat-tailed file to open a single hole (smaller than that above) in the remaining protection cover to take the sensor cable with a degree of strain relief. Secure down the protection covers.





3.3.3 Feed the wires/cables followed by the power unit through the 65mm dia. ceiling hole (see Fig. 9).

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3.3.4 Force the spring clips back until they can feed into the ceiling hole (see Fig. 10-A) and then push the sensor upwards into place so that its flange fits tightly against the ceiling (see Fig. 10-B).

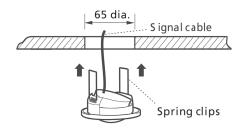


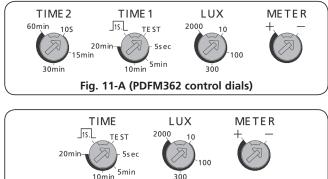
Fig. 10-A

Downloaded from Elcodis.com electronic components distributor Power Unit

4 Test and Operation

4.1 Time, LUX and Meter Controls

Following marked values (excepting TEST and Jis.L) are approximate, the values are continuously adjustable over the control range (see Fig.11-A & Fig.11-B).





4.1.1 TIME control adjustment

These are delay times between the sensor being triggered and the controller switching off assuming no further detections are made. If there are additional detections the time delay applies from the latest detection.

PDFM362:

TIME 1: Adjustable from 5sec to 20min (lighting). (Extendable to 30min and 60min when in use with the IR-10 remote controller).

TIME 2: Adjustable from 10sec to 60min (HVAC).

PDFM361:

TIME: Adjustable from 5sec to 20min (lighting). (Extendable to 30min and 60min when in use with the IR-10 remote controller).

4.1.2 LUX control adjustment

The LUX level below which the sensor will operate is adjustable from 10 LUX (operation only after dusk) to 2000 LUX (operation at any light level).

4.1.3 METER control adjustment

This control sets the diameter of detection coverage at floor level. Assuming a ceiling height of 2.5m at the + end of the scale the coverage diameter will be 7m, at the - end of the scale the coverage diameter will be 1m.

The affect of METER control at other ceiling heights is shown in section 3.1.

4.2 Test Mode

4.2.1 Sensor warm up

The detector will take a minimum of 60 seconds to warm up when the power is connected to it for the first time or if the power is being re-connected after being turned off.

During this period load I and the sensor LED will both be on. After the warm up is finished the sensor will revert to operation according to the settings of the controls on the sensor body.

4.2.2 LED function

There is a red LED (see Fig. 12) built into the sensor and visable through the PIR lens that shows the status of the loads and enables testing to be carried out without the loads being connected.



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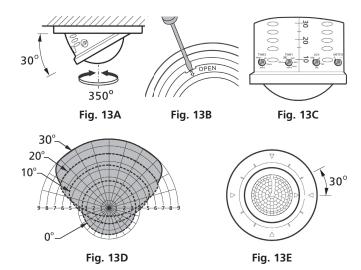
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4.2.3 Adjusting sensor head

The sensor head can be tilted by as much as 30° off axis as shown in Fig. 13A. This can be achieved by using a flat blade screwdriver as shown in Fig. 13B.

Fig. 13C shows the tilt angle markings on the sensor body. The tilt angle is read off against the edge of the mounting flange.

Fig. 13D shows the detection coverage for various tilt angles. The tilt angle can be used in conjunction with rotation of the sensor head within the flange up to 350° to give the required coverage in any direction. The markings on the sensor mounting flange (see Fig. 13E) giving 30° per division provide a useful way of adjusting angular position.



4.2.4 Walk test

3.1.

Turn supply on and wait at least 60 seconds for the system to settle down.

Turn Time 1 control to the Test position. This means that the sensor LED and load I will turn on for 2 seconds after triggering and then be off for 3 seconds after which the sensor can be re-triggered. The triggering is independent of light level.

The installer should move around in the detection area to establish that it is all covered. If necessary the tilt and rotation of the sensor should be adjusted, after which the area should be walk tested again to confirm coverage is as required.

To confirm that load 2 (HVAC) is operating correctly for a PDFM362, carry out the following:-

Turn LUX (light level) to its minimum value (10 lux) to stop load 1 (lights) from turning on. Then turn TIME 2 (HVAC) to minimum value (10s) and carry out a limited walk test to confirm correct operation of load 2.

5 Troubleshooting

When the PDFM362 / PDFM361 is not working as expected go through the troubleshooting guide below.

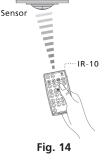
gn be	Problem	Possible Cause	Suggested Solution
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	Lights do not	1. Power is not furned on.	1. Switch on the power.

Problem	Possible Cause	Suggested Solution
Lighting or HVAC does not turn off.	 Incorrect time setting. Incorrect wiring. 	1. Check that the correct delay time is set on either TIME 1 or TIME 2 control dial. Then determine if nuisance triggering is keeping the unit turned on 2. Make sure supply and load wires are connected correctly.
LED does not turn on.	 Out of detection range. Power supply not on. "TIME" knob setting isn't on "Test". Incorrect wiring. 	 Walk within the effective detection range. Switch the power on. Turn the control position to "Test". Refer to wiring diagrams (Fig. 3 to Fig.5).
Nuisance triggering. There are heat sources, HVAC vents/fans, highly reflective surfaces or anything which may be swayed by air movement within the detection coverage.		Avoid aiming the sensor toward any heat sources, such as air conditioners, electric fans, heaters or any highly reflective surfaces. Make sure there are no swaying objects within the detection coverage.

6 Optional Remote Control - IR-10

PDFM362 / PDFM361 can also be controlled by the infrared remote controller IR-10. As well as allowing remote setting of times and light level the IR-10 also enables continuous operation for 8 hours in ON or OFF modes as well as continuously in detection mode controlled by or independent of light level.

The IR-10 is invaluable during commissioning enabling changes to be made without resorting to ladders.



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Further to this the IR-10 can download stored settings from one sensor to additional sensors in the same area.

3 Year Guarantee

In the unlikely event of this product becoming faulty due to defective material or manufacture within 3 years of the date of purchase, please return it to your supplier in the first year with proof of purchase and it will be replaced free of charge. For years 2 and 3 or any difficulty in the first year telephone the helpline on **020 8450 0515.**

For assistance with the product please contact:-

HELPLINE 020-8450-0515

or email helpline@timeguard.com

