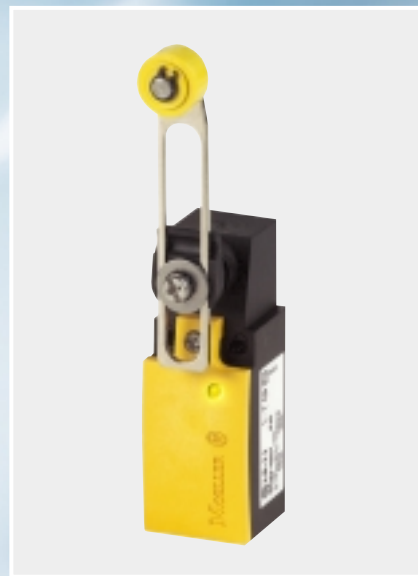
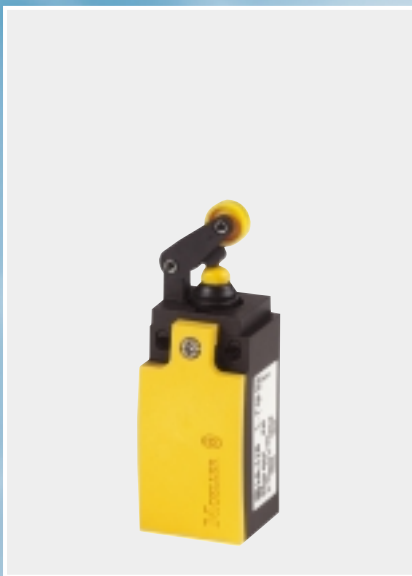


Safety and Reliability – Monitoring and Indication LS-Titan® Position Switches



xCommand

Command and signalling –
ergonomic shape,
attractive design.
Switching control
circuit currents reliably
and precisely.

RMQ command and
signalling devices

FAK foot and palm
switches

SL signal towers

**LS-Titan
position switches**

T/P rotary switches

ETR timing relays

EMR measuring
relays

ESR safety relays

Selection Guide

LS-Titan® position switch

LSE-Titan® position switch

MOELLER



Think future. Switch to green.

LS-Titan® Position Switch

Quick and Flexible

Metal or plastic versions




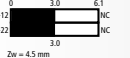

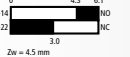

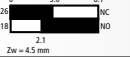







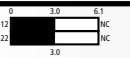



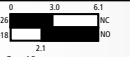

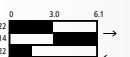



The LS-Titan position switches are optionally available in robust metal enclosures or in light insulated enclosures. Exchangeable metal or plastic operating heads make the LS-Titan position switch particularly flexible. Modular design, vibration proof and maintenance-free Cage-Clamp terminations guarantee extremely fast installation.

Electronic position switch with programmable operating point

The highlight is the world's first electronic position switch, the LSE-Titan. Its freely programmable operating point can be set individually at any time:

Move to the operating point – press the Set key – ready!

The devices are suitable for use with safety applications designed to protect persons or processes.

| LS-Titan® Position Switch UL/CSA 4X, 13 IP 66 | | Contacts M = Make B = Break ⊕ = Safety function with positively opening contacts to IEC/EN 60947-5-1 | Contact sequence diagram for plunger and roller plunger | Contact sequence contact ■ closed □ open Zw = Positive opening clearance | Plunger EN 50 047 | Roller plunger EN 50 047 | Contact sequence diagram for spring rod |
|---|----|---|---|---|----------------------|---|---|
| | | | | | |  | |
| plastic version  | – | 2B⊕ |  |  | LS-02 | | |
| | 1M | 1B⊕ |  |  | LS-11 | LS-11/P | |
| | 1M | 1B⊕ |  |  | LS-11D | | |
| | 1M | 1B⊕ |  |  | LS-11S* | LS-11S/P* |  |
| | 2M | – |  |  | LS-20 | | |
| metal version  | – | 2B⊕ |  |  | LSM-02 | | |
| | 1M | 1B⊕ |  |  | LSM-11 | LSM-11/P | |
| | 1M | 1B⊕ |  |  | LSM-11D | | |
| | 1M | 1B⊕ |  |  | LSM-11S* | LSM-11S/P* |  |
| | 2M | – |  |  | LSM-20 | | |

* LS/LSM-...S = Snap-Action contact






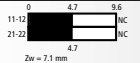
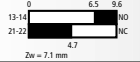
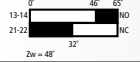

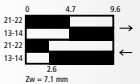

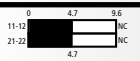
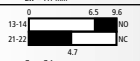
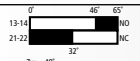
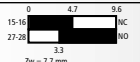
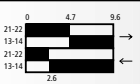

LSE-Titan® electronic position switch

Setting a variable operating point

The LSE electronic position switch has an operating point that can be set variably. Two fast and bounce-free PNP switch outputs enable high switching frequencies. They are protected against short-circuit and overload and are equipped with an abrupt switching behaviour. This guarantees a defined and reproducible operating point. The actual operation point is in a range between 0.5 mm to 5.5 mm (supplied ex-works = 3 mm).

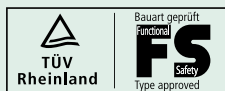
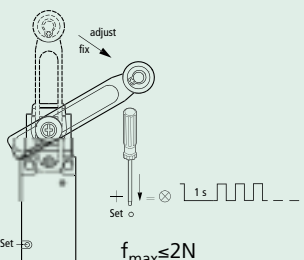
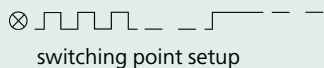
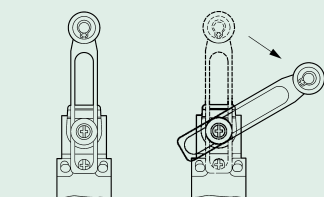
The setting to the "new" operating point is performed as follows: The plunger must be moved from the "old" to the "new" operating position. Now the set button should be pressed for a duration of 1 sec. The LED now flashes with a higher pulse frequency and the new operation point is set retentively.



| Spring-Rod | Contact sequence diagram for roller lever | Roller lever EN 50 047 | Contact sequence diagram for rotary lever, adjustable roller lever and actuating rod | Rotary lever EN 50 047 | Adjustable roller lever | Actuating rod |
|--|---|---|--|---|---|---|
|  | |  | |  |  |  |
| |  | LS-02/L | | | | |
| |  | LS-11/L |  | LS-11/RL | LS-11/RLA | |
| |  | LS-11D/L | | | | |
| LS-11S/S* |  | LS-11S/L* |  | LS-11S/RL* | LS-11S/RLA* | LS-11S/RR* |
| | | | | | | |
| |  | LSM-02/L | | | | |
| |  | LSM-11/L |  | LSM-11/RL | LSM-11/RLA | |
| |  | LSM-11D/L | | | | |
| LSM-11S/S* |  | LSM-11S/L* |  | LSM-11S/RL* | LSM-11S/RLA* | LSM-11S/RR* |
| | | | | | | |

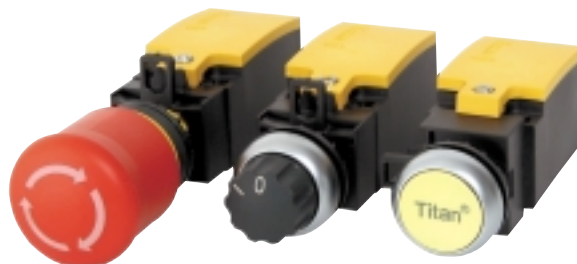
**Limit switch
electronic
-LSE-**


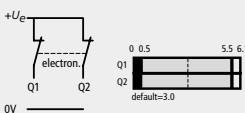

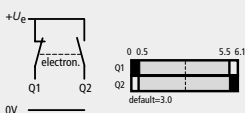
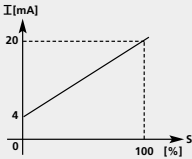

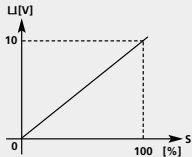
Individual adjustment of switching point









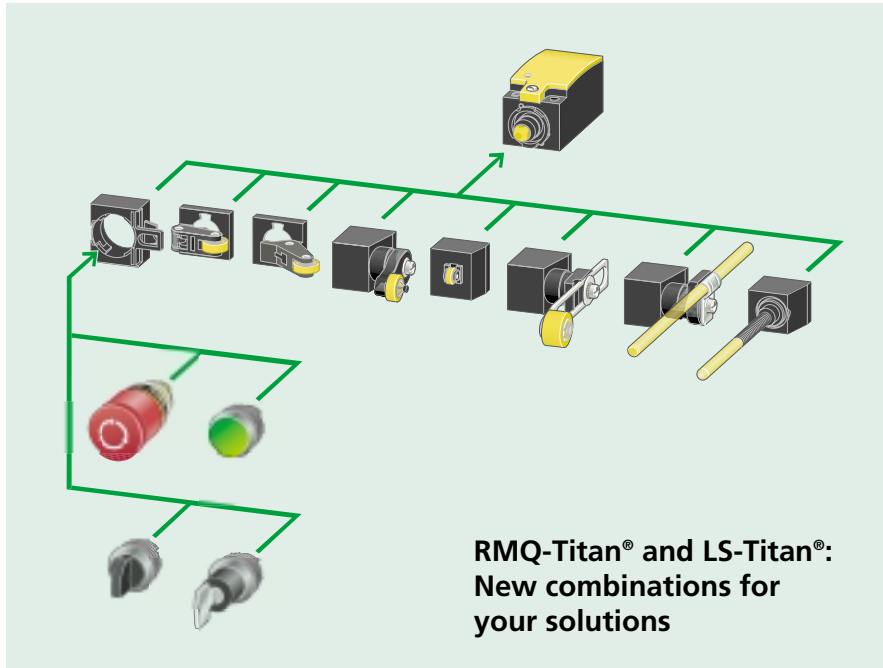
Simply snap on the RMQ-Titan command device

A further unique feature is the ability to combine a control circuit device from the RMQ-Titan range with the LS-Titan position switches. Pushbutton actuators, selector switches or emergency-stop buttons can be simply snapped on directly as the operating heads on each position switch. The combined unit maintains the degree of protection IP66 on both the front and rear.



| LSE-Titan® Position Switch | Contact sequence diagram for plunger | Optical status display |
|---|---|-----------------------------|
| <p>Plastic version</p>  |  | LSE-02 |
|  |  | LSE-11 |
| <p>Plastic version</p>  |  | LSE-AI 4 - 20 mA |
|  |  | LSE-AU 0 - 10 V |















| LS-Titan® operating heads, accessories | Roller lever | Angled roller lever | Roller plunger |
|--|---|---|---|
| <p>Plastic version</p> |  |  |  |
| | LS-XL | LS-XLA | LS-XP |
| <p>Metal version</p> |  |  |  |
| | LSM-XL | LSM-XLA | LSM-XP |



**RMQ-Titan® and LS-Titan®:
New combinations for
your solutions**

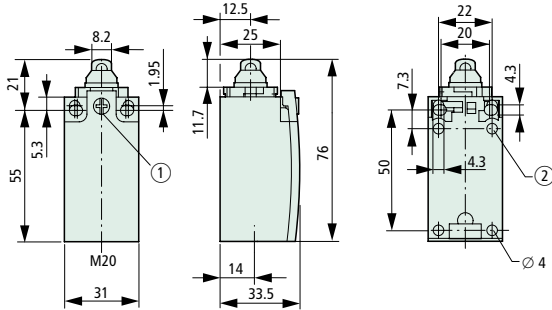


The operating head can be attached in all four directions (4 x 90°) and can be installed quickly and securely with a bayonet fitting.

| Rotary lever | Adjustable roller lever d=18mm | Adjustable roller lever d=30mm | Adjustable roller lever d=40mm | Adjustable roller lever d=40mm (Rubber) | Plastic actuating rod | Metal actuating rod | Spring rod actuator | RMQ-Titan fixing adapter |
|--|---|---|---|---|---|--|---|---|
|  |  |  |  |  |  |  |  |  |
| LS-XRL | LS-XRLA | LS-XRLA30 | LS-XRLA40 | LS-XRLA40R | LS-XRR | LS-XRRM | LS-XS | M22-LS |
|  |  | | | |  |  |  | |
| LSM-XRL | LSM-XRLA | | | | LSM-XRR | LSM-XRRM | LSM-XS | |

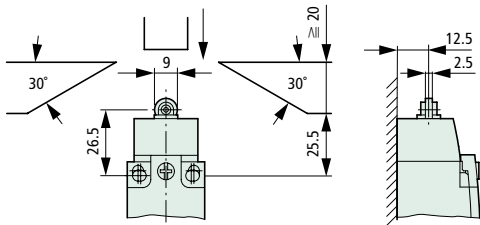
Dimensions LS-Titan® Position Switches

Position switches
LS-..., LSM-..., LSE-..

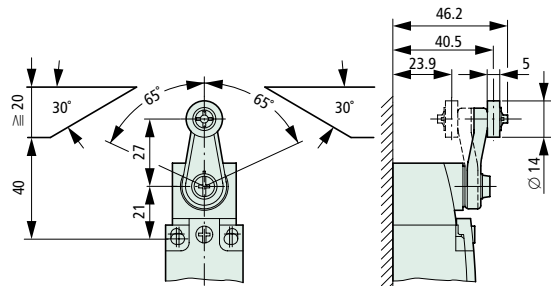


① Tightening torque of cover screw: 1.0 Nm ± 0.2 Nm ② Only with LS (plastic design)

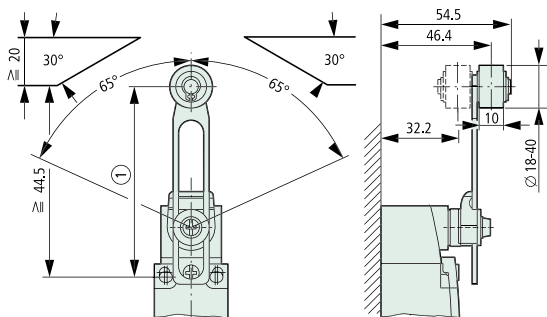
LS-11 (S)/P



LS(M)-11(S)/RL

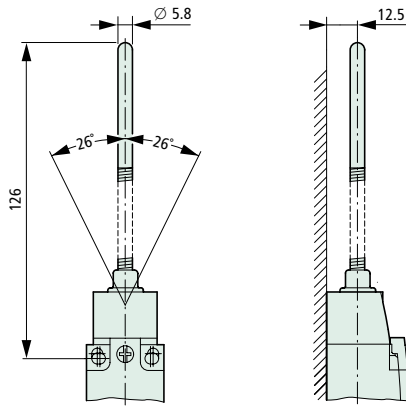


LS(M)-11(S)/RLA

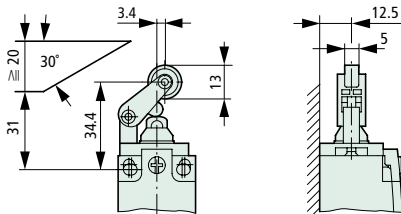


① Setting range from 54.5 to 97

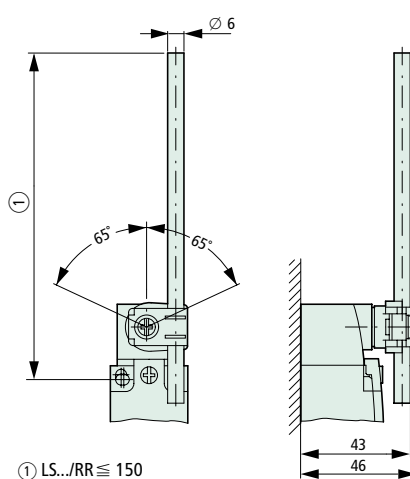
LS(M)-11S/S



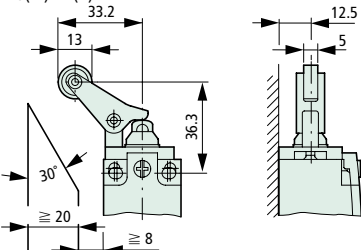
LS(M)-.../L



LS(M)-11S/RR



LS(M)-XL(A)



① LS.../RR ≅ 150
LS.../RRM ≅ 210

Technical Data

Complete unit to IP66
LS, LSM

LSE-11, LSE-11

LSE-AI

LSE-AU

General

| | | | | | |
|---------------------------|----|--|-----------------------------|-----------------------------|-----------------------------|
| Standards and regulations | | IEC/EN 60947 | IEC/EN 60947, EN 61000-4 | IEC/EN 60947, EN 61000-4 | IEC/EN 60947, EN 61000-4 |
| Climatic proofing | | Damp heat, constant to IEC 60068-2-3, Damp heat, cyclic to IEC 60068-2-30 | | | |
| Ambient temperature | °C | -25/+70 | -25/+70 | -25/+70 | -25/+70 |
| Mounting position | | as required | as required | as required | as required |
| Degree of protection | | IP66 | IP66 | IP66 | IP66 |

Cage Clamp terminal capacity

| | | | | | |
|-----------------------|-----------------|-----------------|-----------------|-----------------|-----------------|
| solid | mm ² | 1 x (0.5 – 2.5) | 1 x (0.5 – 2.5) | 1 x (0.5 – 2.5) | 1 x (0.5 – 2.5) |
| flexible with ferrule | mm ² | 1 x (0.5 – 1.5) | 1 x (0.5 – 1.5) | 1 x (0.5 – 1.5) | 1 x (0.5 – 1.5) |

DIN 46228

Power Supply

| | | | | | | |
|---------------------------|-------|------|---|---------|----------------|----------------|
| Rated voltage | U_e | V DC | – | 12 – 30 | 24 (–15%/+20%) | 24 (–15%/+20%) |
| Rated operational current | | | | | | |
| 12 V | I | mA | – | 15 | – | – |
| 24 V | I | mA | – | 18 | 28 – 45 | 24 |
| 30 V | I | mA | – | 19 | – | – |

Conductors/Switching capacity

| | | | | | | |
|---|-----------|------|-------|-------|-------|-------|
| Rated impulse withstand voltage | U_{imp} | V AC | 4000 | – | – | – |
| Rated isolation | U_i | V | 400 | – | – | – |
| Overvoltage category/ pollution degree | | | III/3 | III/3 | III/3 | III/3 |

Rated operational current

| | | | | | | | |
|-------|-------------|-------|---|-----|-----|---|---|
| AC-15 | 24 V | I_e | A | 6 | – | – | – |
| | 230 V/240 V | I_e | A | 6 | – | – | – |
| | 400 V/415 V | I_e | A | 4 | – | – | – |
| DC-13 | 24 V | I_e | A | 10 | 0.2 | – | – |
| | 110 V | I_e | A | 1 | – | – | – |
| | 220 V | I_e | A | 0.5 | – | – | – |

Analog output Q1

| | | | | | | |
|--------------------------------|--|-------|---|---|--------|--------|
| Output voltage | | V DC | – | – | – | 0 – 10 |
| Output current | | mA | – | – | 4 – 20 | – |
| Resolution | | Steps | – | – | 100 | 100 |
| Step tolerance | | Step | – | – | < 1 | < 1 |
| Load impedance, resistive load | | Ω | – | – | < 400 | > 1000 |

Digital diagnostic output Q2

| | | | | | | |
|------------------|--|-----|---|---|---------------|---------------|
| Normal operation | | V | – | – | approx. U_e | approx. U_e |
| | | m A | – | – | < 200 | < 200 |
| Fault scenario | | V | – | – | 0 | 0 |

Control circuit reliability

| | | | | | | |
|-----------------|-------|-----------------|--|---|---|---|
| at 24 V DC/5 mA | H_f | Fault-frequency | < 10 ⁻⁷ , < 1 fault in 10 ⁷ operations | – | – | – |
| at 5 V DC/1 mA | H_f | Fault-frequency | < 10 ⁻⁶ , < 1 fault in 5 x 10 ⁶ operations | – | – | – |

Mains frequency

| | | | | | | |
|--|--|----|----------|---|---|---|
| | | Hz | max. 400 | – | – | – |
|--|--|----|----------|---|---|---|

Short-circuit rating in closed state (IEC/EN 60947-5-1)

| | | | | | |
|-----------|---------|-----------------------|--|--|--|
| Fuseless | Type | PKZM 0-10 PXL-B6/1 | non-inherently short-circuit proof, after reset switch back on | non-inherently short-circuit proof, after reset switch back on | non-inherently short-circuit proof, after reset switch back on |
| Max. fuse | A gG/gI | 10 | – | – | – |

Short-circuit rating to IEC/EN 60947-5-1

| | | | | | |
|-----------|---------|---|---|---|---|
| Max. fuse | A gG/gI | 6 | – | – | – |
|-----------|---------|---|---|---|---|

| | | | | | |
|---------------------|----|--------|--------|--------|--------|
| Repetition accuracy | mm | ± 0.02 | ± 0.02 | ± 0.02 | ± 0.02 |
|---------------------|----|--------|--------|--------|--------|

Note

The following applies for LSE-11, LSE-02: Ensure that the voltage supply is not interrupted when setting the switching point. Cage-Clamp is a registered trademark of Wago Kontakttechnik, 32423 Minden, Germany. Accessories and actuation tools for the Cage-Clamp connection available from Wago: Actuation tool, 2-way, Wago article no. 280-432 Screwdriver short, angled, Wago article no. 210-258 Jumper insert, grey, Wago article no. 264-402

Technical Data

Complete unit to IP66

LS, LSM

LSE-11, LSE-02

LSE-AI

LSE-AU

Mechanical Features

| | | | | | | |
|---|--------------|-------------------|--------|-----------------------------|--------|--------|
| Life | | | | | | |
| Slow action contact | operations | x 10 ⁶ | 3 | – | – | – |
| Snap-action contact | operations | x 10 ⁶ | 3 | 3 (electronic) | – | – |
| Contact temperature of the roller head | | °C | ≤ 100 | ≤ 100 | ≤ 100 | ≤ 100 |
| Mechanical shock resistance (half-sinusoidal shock 20 ms) | | | | | | |
| Slow action contact | | g | 25 | – | – | – |
| Snap-action contact | | g | 2 | – | – | – |
| Basic unit | | g | – | 30 | 30 | 30 |
| Operating frequency | operations/h | | ≤ 6000 | ≤ 3000 | ≤ 3000 | ≤ 3000 |
| Switching point | | | | 0.5 – 5.5 mm, adjustable | – | – |
| Hysteresis | | mm | – | 0.4 | 0.4 | 0.4 |
| Resolution | | mm | – | 0.04 | 0.06 | 0.06 |

Drive

| | | | | | | |
|--|---|-----|---------|---------|---------|---------|
| Mechanical | | | | | | |
| Actuating force travel start/end | | | | | | |
| Basic unit | | N | 1.0/8.0 | 3.5/8.0 | 3.5/8.0 | 3.5/8.0 |
| LS(M)-XP | | N | 1.0/8.0 | 1.0/8.0 | 1.0/8.0 | 1.0/8.0 |
| LS(M)-XL | | N | 1.0/8.0 | 1.0/8.0 | 1.0/8.0 | 1.0/8.0 |
| LS(M)-XLA | | N | 1.0/8.0 | 1.0/8.0 | 1.0/8.0 | 1.0/8.0 |
| Rotary drive actuation torque | | Nm | 0.2 | 0.2 | 0.2 | 0.2 |
| Max. operating speed with DIN cams | | | | | | |
| Basic unit with angle speed of operation | $\alpha = 0^\circ/30^\circ$ | m/s | 1/0.5 | 1/0.5 | 1/0.5 | 1/0.5 |
| LS(M)-XRL with angle speed of operation | $\alpha = 0^\circ$ | m/s | 1.5 | 1.5 | 1.5 | 1.5 |
| LS(M)-XRLA with angle speed of operation | $\alpha = 30^\circ, L = 125 \text{ mm}$ | m/s | 1.5 | 1.5 | 1.5 | 1.5 |
| LS(M)-XRR with | $L = 130 \text{ mm}$ | m/s | 1.5 | 1.5 | 1.5 | 1.5 |
| LS(M)-XL with angle speed of operation | $\alpha = 30^\circ/45^\circ$ | m/s | 1 | 1 | 1 | 1 |
| LS(M)-XLA with angle speed of operation | $\alpha = 30^\circ/45^\circ$ | m/s | 1 | 1 | 1 | 1 |
| LS(M)-XP with angle speed of operation | $\alpha = 0^\circ/30^\circ$ | m/s | 1/1 | 1/1 | 1/1 | 1/1 |

Electromagnetic Compatibility (EMC)

| | | | | | | |
|--|--|-----|---|-----|-----|-----|
| Electrostatic discharge (IEC/EN 61000-4-2, Level 3, ESD) | | | | | | |
| Air discharge | | kV | – | 8 | 8 | 8 |
| Contact discharge | | kV | – | 4 | 4 | 4 |
| Electromagnetic fields (IEC/EN 61000-4-3, Level 3, RFI) | | V/m | – | 10 | 10 | 10 |
| Burst Impulse (IEC/EN 61000-4-4, Level 3) | | | | | | |
| Supply lines | | kV | – | 2 | 2 | 2 |
| Signal lines | | kV | – | 2 | 2 | 2 |
| Surge (IEC/EN 61000-4-5) | | kV | – | 0.5 | 0.5 | 0.5 |
| Immunity to line-conducted interference (IEC/EN 61000-4-6) | | V | – | 10 | 10 | 10 |

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Moeller addresses worldwide:
www.moeller.net/address
E-Mail: info@moeller.net

