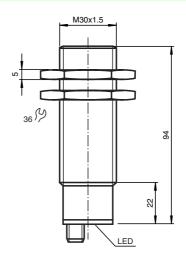
# Ultrasonic sensor UB500-30GM-E5-V15



# **Features**

- Switch output
- 5 different output functions can be set
- TEACH-IN input
- · Synchronisation options
- · Deactivation option
- Temperature compensation
- · Insensitive to compressed air

# **Dimensions**



 $\epsilon$ 

# **Technical data**

#### General specifications

Sensing range Adjustment range 30 ... 500 mm 50 ... 500 mm Unusable area 0 ... 30 mm 100 mm x 100 mm approx. 380 kHz Standard target plate Transducer frequency Response delay approx. 50 ms

Indicators/operating means

LED green

LED yellow

LED red

**Electrical specifications** 

Operating voltage No-load supply current I<sub>0</sub>

Input/Output

Synchronisation

bi-directional 0 level -U<sub>B</sub>...+1 V 1 level: +4 V...+U<sub>B</sub> input impedance: > 12 KOhm synchronisation pulse:  $\geq$  100  $\mu$ s, synchronisation interpulse period:  $\geq$  2 ms

≤ 50 mA

≤ 95 Hz

Synchronisation frequency

Common mode operation Multiplex operation

Input

Input type

Output Output type

Repeat accuracy Rated operational current I<sub>e</sub>

Voltage drop U<sub>d</sub> Switching frequency f

Range hysteresis H Temperature influence ≤ 10 Hz

 $\leq$  0,5 % of switching point

1 % of the set operating distance

< 2 % of full-scale value

< 2.5 V

Standard conformity Standards

**Ambient conditions** 

Ambient temperature Storage temperature Mechanical specifications

Protection degree Connection Material Housing

Transducer Mass

EN 60947-5-2

-25 ... 70 °C (248 ... 343 K) -40 ... 85 °C (233 ... 358 K)

IP65

connector V15 (M12 x 1), 5 pin

brass, nickel-plated, plastic components PBT

permanent: Power-on flashing: TEACH-IN function object detected

permanent: switching state switch output flashing: TEACH-IN function normal operation: "fault"
TEACH-IN function: no object detected

10 ... 30 V DC , ripple 10 %SS

 $\leq$  95/n Hz, n = number of sensors

epoxy resin/hollow glass sphere mixture; polyurethane foam

1 TEACH-IN input, operating range 1: -U<sub>B</sub> ... +1 V, operating range 2: +4 V ... +U<sub>B</sub> input impedance: > 4.7 k $\Omega$ ; TEACH-IN pulse:  $\geq$  1 s

1 switch output E5, pnp NO/NC, parameterisable

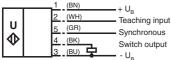
200 mA, short-circuit/overload protected

135 q

# Electrical connection

## Standard symbol/Connections:

(version E5, pnp)



Core colours in accordance with EN 60947-5-2

#### Connector V15



#### Description of the sensor functions

# **Synchronisation**

The sensor features a synchronisation input for the suppression of mutual interference. If this input is not used, the sensor will operate using an internally generated clock rate. The synchronisation of multiple sensors can be realised as follows:

#### External synchronisation:

The sensor can be synchronised by the external application of a square wave voltage. A synchronisation pulse at the synchronisation input starts a measuring cycle. The pulse must have a duration greater than 100  $\mu$ s. The measuring cycle starts with the falling edge of a synchronisation pulse. Two operating modes are available:

- Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised
- 2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

## Internal synchronisation:

The synchronisation connections of up to 5 sensors capable of internal synchronisation are connected to one another. When power is applied, these sensors will operate in multiplex mode.

The state of the switch output will not change until the switching threshold has been exceeded five times as an average of the five measurements is determined internally. A low level > 1 s or an open synchronisation input will result in the normal operation of the sensor.

Synchronisation cannot be performed during TEACH-IN and vice versa. The sensors must be operated in an unsynchronised manner to teach the switching point.

A high level at the synchronisation input disables the sensor.

#### Note:

If the option for synchronization is not used, the synchronization input has to be connected to ground (0V) or the sensor has to be operated via a V1 cable connector (4-pin).

# Adjusting the switching points

The ultrasonic sensor features an analogue output with two teachable evaluation limits. These are set by applying the supply voltage -U $_{\rm B}$  or +U $_{\rm B}$  to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s. LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. Evaluation limit A1 is taught with -U $_{\rm B}$ , A2 with +U $_{\rm B}$ . For simple setting the switching point and the output functions the programming unit UB-PROG2 can be used.

Five different output functions can be set:

- 1. Window mode, normally-open function
- 2. Window mode, normally-closed function
- 3. One switching point, normally-open function
- 4. One switching point, normally-closed function
- 5. Detection of object presence

#### **TEACH-IN** window mode, normally-open function

- Set target to near switching point
- TEACH-IN switching point A1 with -U<sub>R</sub>
- Set target to far switching point
- TEACH-IN switching point A2 with +U<sub>B</sub>

# **TEACH-IN** window mode, normally-closed function

- Set target to near switching point
- TEACH-IN switching point A2 with +UB
- Set target to far switching point
- TEACH-IN switching point A1 with -U<sub>B</sub>

## **TEACH-IN** one switching point, normally-open function

- Set target to near switching point
- TEACH-IN switching point A2 with +UB
- Cover sensor with hand or remove all objects from sensing range
- TEACH-IN switching point A1 with -UB

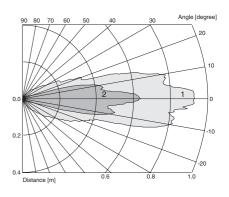
# TEACH-IN one switching point, normally-closed function

- Set target to near switching point
- TEACH-IN switching point A1 with -UB

# UB500-30GM-E5-V15

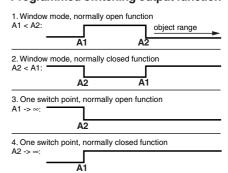
# Characteristic curves/additional information

# Characteristic response curve



Curve 1: flat surface 100 mm x 100 mm Curve 2: round bar, Ø 25 mm

## Programmed switching output function



 A1 -> ∞, A2 -> ∞: Detection of object presence Object detected: Switch output closed No object detected: Switch output open

## **Accessories**

#### Mounting aid

BF30

BF30F

BF5-30

M-105

# Sound deflectors

UVW90-M30 UVW90-K30

#### **Programming Unit**

**UB-PROG2** 

# Cable sockets \*)

V15-G-2M-PVC V15-W-2M-PUR

\*) For additional cable sockets see section "Accessories".

# UB500-30GM-E5-V15

- Cover sensor with hand or remove all objects from sensing range
- TEACH-IN switching point A2 with  $+ U_B$

# **TEACH-IN** detection of object presence

- Cover sensor with hand or remove all objects from sensing range
- TEACH-IN switching point A1 with - $U_{\rm B}$
- TEACH-IN switching point A2 with +UB

# **Default setting**

A1: unusable area

A2: nominal sensing range

# **LED Displays**

Displays in dependence on operating mode	Green LED	Red LED	Yellow LED
TEACH-IN switching point			
Object detected	flashes	off	flashes
No object detected	off	flashes	flashes
Object uncertain (TEACH-IN invalid)	off	flashes	off
Normal operation	on	off	switching state
Interference	off	flashes	previous state

# **LED-Window**

