

## UB2000-30GM-E2-V15

## Features

- Switch output
- 5 different output functions can be set
- TEACH-IN input
- Synchronisation options
- Deactivation option
- Watchdog


## Note

Model number

## Function

## Synchronisation

The sensor features a synchronisation input for the suppression of mutual interference. It can be synchronised by applying a square wave voltage. The falling edge of a synchronisation pulse at the synchronisation input starts a measuring cycle. A low level $>1 \mathrm{~s}$ or an open synchronisation input will result in the non-synchronised normal operation of the sensor. A high level at the synchronisation input disables the sensor. Synchronisation cannot be performed during TEACH-IN and vice versa. Two operating modes are possible:

1. Multiple sensors can be controlled by the same synchronisation signal. The sensors are synchronised.
2. The synchronisation pulses are sent cyclically to individual sensors. The sensors operate in multiplex mode.

## Setting the switching points

The ultrasonic sensor features a switch output with two teachable switching points. These are set by applying the supply voltage -UB or +UB to the TEACH-IN input. The supply voltage must be applied to the TEACH-IN input for at least 1 s . LEDs indicate whether the sensor has recognised the target during the TEACH-IN procedure. Switching point A1 is taught with -UB, A2 with +UB.

Five different output functions can be set:

| Function | TEACH-IN procedure |
| :---: | :---: |
| Window mode, close function | - Set object to near switching point <br> - Teach switching point A1 with -UB <br> - Set object to far switching point <br> - Teach switching point A2 with +UB |
| Window mode, open function | - Set object to near switching point <br> - Teach switching point A2 with +UB <br> - Set object to far switching point <br> - Teach switching point A1 with -UB |
| 1 switching point, close function | - Set object to near switching point <br> - Teach switching point A2 with +UB <br> - Cover sensor or remove all objects from sensing range <br> - Teach switching point A1 with -UB |
| 1 switching point, open function | - Set object to near switching point <br> - Teach switching point A1 with -UB <br> - Cover sensor or remove all objects from sensing range <br> - Teach switching point A2 with +UB |
| Detection of object presence | - Cover sensor or remove all objects from sensing range <br> - Teach switching point A1 with -UB <br> - Teach switching point A2 with +UB |

Default setting of switching points: $\mathrm{A} 1=$ blind range, $\mathrm{A} 2=$ nominal distance

| Displays in dependence on operat- <br> ing mode | Green LED | Red LED | Yellow LED |
| :--- | :---: | :---: | :---: |
| Teach switching point | Flashing | Off | Off |
| Object detected | Off | On |  |
| No object detected |  |  |  |
| Object uncertain (TEACH-IN invalid) | Off | Flashing | Off |
| Normal operation | On | Off | Switching state |
| Interference (e.g. compressed air) | Off | Flashing | Previous state |

## Characteristic curves/ Additional information

One switch point, normally open function


A1 $\rightarrow \infty$, A2 $->\infty$ : Detection of presence of object
Object detected: Switch output closed
No object detected: Switch output open

## LED-Window



## Programmed switching output function



