Slim Incremental 50-mm-dia. Rotary Encoder

# E6C2-C

# **Tough and Easy**

- Sealed bearings with IP64 oilproof construction.
- Improved shaft loading performance. Radial: 50 N, Thrust: 30 N
- Pre-wired Models with cable connected at an angle. Side or back cable connections also possible.
- · Improved reliability with reverse connection and load short-circuit protection (except for line-driver outputs).



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Be sure to read Safety Precautions on ⚠ page 4.

# **Ordering Information**

# Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model	
5 to 24 VDC	Open-collector output (NPN)	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6C2-CWZ6C (resolution) 2M Example: E6C2-CWZ6C 10P/R 2M	
		720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		
12 to 24 VDC	Open-collector output (PNP)	100, 200, 360, 500, 600	E6C2-CWZ5B (resolution) 2M Example: E6C2-CWZ5B 100P/R 2M	
		1,000, 2,000		
5 to 12 VDC	Voltage output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6C2-CWZ3E (resolution) 2M Example: E6C2-CWZ3E 10P/R 2M	
		720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		
5 VDC	Line-driver output	10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600	E6C2-CWZ1X (resolution) 2M Example: E6C2-CWZ1X 10P/R 2M	
		720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000		

# Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks		
	E69-C06B			
Couplings	E69-C68B	Different end diameter		
Couplings	E69-C610B	Different end diameter		
	E69-C06M	Metal construction		
Florence	E69-FCA			
Flanges	E69-FCA02	E69-2 Servo Mounting Bracket provided.		
Servo Mounting Bracket	E69-2	Provided with E69-FCA02 Flange.		

Refer to Accessories for details.

# E6C2-C

# **Ratings and Specifications**

Item	Model	E6C2-CWZ6C	E6C2-CWZ5B	E6C2-CWZ3E	E6C2-CWZ1X	
Power sup voltage	ply	5 VDC -5% to 24 VDC +15%, ripple (p-p): 5% max.	12 VDC -10% to 24 VDC +15%, ripple (p-p): 5% max.	5 VDC -5% to 12 VDC +10%, ripple (p-p): 5% max.	5 VDC ±5%, ripple (p-p): 5% max.	
Current consumption*1		80 mA max.	100 mA max.		160 mA max.	
Resolution (pulses/rotation)		10, 20, 30, 40, 50, 60, 100, 200, 300, 360, 400, 500, 600, 720, 800, 1,000, 1,024, 1,200, 1,500, 1,800, 2,000	100, 200, 360, 500, 600, 1,000, 10, 20, 30, 40, 50, 60, 100, 200		, 300, 360, 400, 500, 600, 720, 800, 0, 2,000	
Output ph	ases	Phases A, B, and Z Phases A, A, B, B, Z, and Z				
Output co	nfiguration	NPN open-collector output	PNP open-collector output	Voltage output (NPN output)	Line driver output*2	
Output ca	pacity	Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 0.4 V max. (at sink current of 35 mA)	Applied voltage: 30 VDC max. Source current: 35 mA max. Residual voltage: 0.4 V max. (at source current of 35 mA)	Output resistance: 2 kΩ Output current: 20 mA max. Residual voltage: 0.4 V max. (at sink current of 20 mA)	$\begin{array}{l} \mbox{AM26LS31 equivalent} \\ \mbox{Output voltage:} \\ \mbox{High level: } lo = -20 \mbox{ mA} \\ \mbox{Low level: } ls = 20 \mbox{ mA} \\ \mbox{Output voltage: } Vo = 2.5 \mbox{ V min.} \\ \mbox{Vs} = 0.5 \mbox{ V max.} \end{array}$	
Maximum frequency		100 kHz	50 kHz	100 kHz		
Phase diff between o		90°±45° between A and B (1/4 T ± 1/8 T)				
Rise and fall times of output		1 $\mu$ s max. (Control output voltage: 5 V, Load resistance: 1 k $\Omega$ , Cable length: 2 m)	d 1 μs max. (Cable length: 2 m, Sink current: 10 mA)		0.1 μs max. (Cable length: 2 m, lo = -20 mA, ls = 20 mA)	
Starting to	orque	10 mN⋅m max.				
Moment of	f inertia	$1 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max.; } 3 \times 10^{-7} \text{ kg} \cdot \text{m}^2$	max. at 600 P/R max.			
Shaft	Radial	50 N				
loading	Thrust	30 N				
Maximum permissib	le speed	6,000 r/min				
Protection	circuits	Power supply reverse polarity prot				
Ambient te range	temperature Operating: -10 to 70°C (with no icing), Storage: -25 to 85°C (with no icing)					
Ambient h range	umidity	Operating/Storage: 35% to 85% (with no condensation)				
Insulation	resistance	20 $M\Omega$ min. (at 500 VDC) between	n current-carrying parts and case			
Dielectric	strength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case				
Vibration I	resistance	Destruction: 10 to 500 Hz, 150 m/s <sup>2</sup> or 2-mm double amplitude for 11 min 3 times each in X, Y, and Z directions				
Shock res	istance	Destruction: 1,000 m/s <sup>2</sup> 3 times each in X, Y, and Z directions				
Degree of	protection	IEC 60529 IP64, in-house standards: oilproof				
Connectio	n method	Pre-wired Models (Standard cable length: 2 m)				
Material		Case: Zinc alloy, Main unit: Aluminum, Shaft: SUS420J2				
Weight (packed st	tate)	Approx. 400 g				
	es	Instruction manual				

Note: Origin Indication

The following illustration shows the relationship between phase Z and the origin. Set cut face D to the phase Z origin as shown in the illustration.

Phase Z origin Origin Cut face D (F) 120 120° 38 dia

\*1. An inrush current of approximately 9 A will flow for approximately 0.3 ms when the power is turned ON. \*2. The line driver output is a data transmission circuit compatible with RS-422A and long-distance transmission is possible with a twisted-pair cable.(AM26LS31

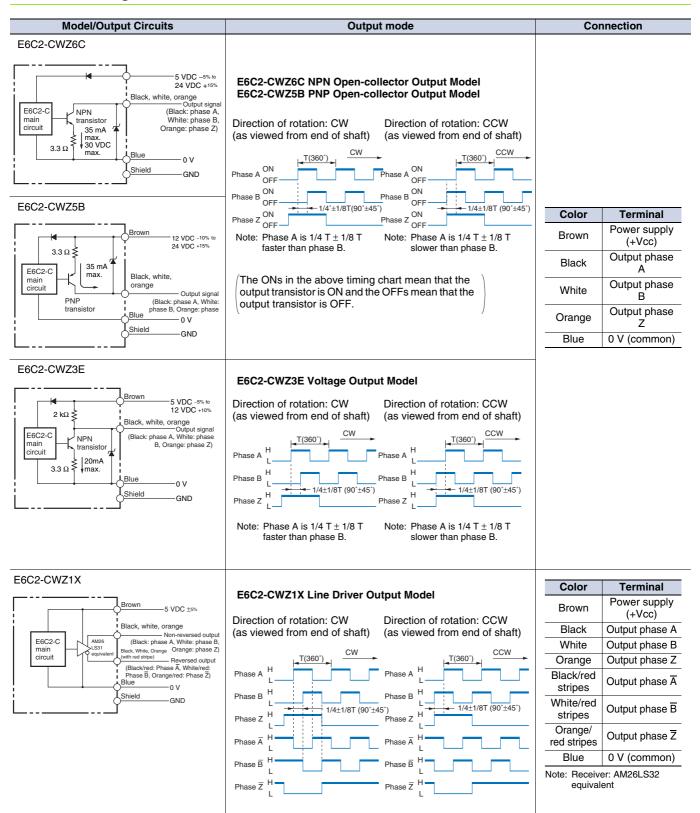
equivalent) \*3. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

Maximum electrical response speed (rpm) = <u>Maximum response frequency</u> × 60 Resolution

This means that the E6C2-C Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed.

# E6C2-C

# I/O Circuit Diagrams



Note: 1. The shielded cable outer core (shield) is not connected to the inner area or to the case.

2. The phase A, phase B, and phase Z circuits are all identical.

3. Normally, connect GND to 0 V or to an external ground.

# **Safety Precautions**

# Refer to Warranty and Limitations of Liability.

# <u> WARNING</u>

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.

# **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

# • Wiring

### **Cable Extension Characteristics**

- When the cable length is extended, the output waveform startup time is lengthened and it affects the phase difference characteristics of phases A and B. Conditions will change according to frequency, noise, and other factors. As a guideline, use a cable length of 10 m\* or less. If the cable must be more than 2 m, use a Model with a Line-driver Output (max. length for line-driver output: 100 m).
- \* Recommended Cable

Conductor cross section: 0.2 mm<sup>2</sup> Spiral shield Conductor resistance: 92 Ω/km max. (20°C) Insulation resistance: 5 Ω/km min. (20°C)

- The output waveform startup time changes not only according to the length of the cable, but also according to the load resistance and the cable type.
- Extending the cable length not only changes the startup time, but also increases the output residual voltage.

## Connection

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

# Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

# Encoder

E6C2-CWZ (60)Origin of Phase Z - (6.59) -15-<del>-</del>5 40 Three, M4 holes; Depth: 1.6 -10+ ' mm 6 .0.021 dia 25 50 d 0.021 dia Ð 20 120 38 dia 5-dia. oil-resistant PVC-insulated shielded cable with 5 conductors (line driver: 8 conductors) (Conductor cross section: 0.2 mm<sup>2</sup>, Insulator diameter: 1.0 mm), Standard length: 2 m

# Accessories (Order Separately)

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E69-C06B E69-C68B E69-C610B E69-C06M Flanges E69-FCA E69-FCA02

# Servo Mounting Bracket

E69-2 (Three brackets in a set.) Refer to *Accessories* for details.

#### **Read and Understand This Catalog**

Please read and understand this catalog before purchasing the products. Please consult your OMRON representative if you have any questions or comments.

# Warranty and Limitations of Liability

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#### Disclaimers

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#### DIMENSIONS AND WEIGHTS

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# OMRON Corporation Industrial Automation Company