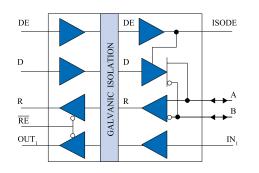


# IL485W

# Isolated RS485 Interface With Handshake

# **Functional Diagram**



# **Function Table**

V <sub>ID</sub> (A-B)	DE	RE	ISODE	R	D	MODE
≥ 0.2V	L	L	L	Н	Х	Receive
≤ -0.2V	L	L	L	L	Х	Receive
-7 <v<sub>ID&lt;12</v<sub>	Х	Н	Х	Ζ	Х	Receive/Drive
≥ 1.5	Н	L	Н	Н	Н	Drive
≤-1.5	Н	L	Н	L	L	Drive
Open	L	L	L	Н	Х	Receive

RE1	IN <sub>1</sub>	OUT <sub>1</sub>	H=
L	L	L	L=
L	Н	Н	X=
Н	Х	Z	Z=

H= High Level
L= Low Level
X= Irrelevant
Z= High Impedance

### **Ordering Information**

IL485W	Standard Part Number
IL485WE	Lead Free
IL485WTR	Tape and Reel
IL485WETR	Lead Free/Tape and Reel

## Features

- 2500 V<sub>RMS</sub> Isolation (1 min)
- 25 ns Maximum Propagation Delay
- 35 MBaud Data Rate
- 1 ns Pulse Skew (typ.)
- · Designed for Multi-point Transmission
- on Long Bus Lines in Noisy Environments
- ±60 mA Driver Output Capability
- Thermal Shutdown Protection
- · Meets or Exceeds ANSI RS-485 and ISO 8482:1987 (E)
- · -40°C to +85°C Temperature Range
- · 16 Pin SOIC Package
- · PROFIBUS International Component Recognition
- UL1577 Approval (pending)
- IEC 61010-1 Approval (pending)

## Applications

- · PROFIBUS/RS485
- · RS-485 Systems
- · Multiple Data Point Transmission

### Description

The IL485W is a galvanically isolated, high speed differential bus transceiver, designed for bidirectional data communication on balanced transmission lines. The IL485W uses patented\* IsoLoop® technology and is the first isolated RS-485 interface available in a standard 16 pin SOIC package, which meets the ANSI Standards EIA/TIA-422-B and RS485.

The IL485W has current limiting and thermal shutdown features to protect against output short circuits and bus contention situations where these may cause excessive power dissipation.

With a 1 nsec pulse skew and 16 nsec propagation delay, the IL485W is ideal for PROFIBUS applications. Use of DE/ISODE and  $IN_1/OUT_1$  allows the IL485W to perform the handshaking operations of RTSAS and DTSAS of PROFIBUS.

 $\mathit{Isoloop}^{\circledast}$  is a registered trademark of NVE Corporation

\* US Patent number 5,831,426; 6,300,617 and others



#### **Absolute Maximum Ratings**

Parameters	Symbol	Min.	Max.	Units
Storage Temperature	Τ <sub>S</sub>	-65	150	°C
Ambient Operating Temperature	T <sub>A</sub>	-40	85	°C
Voltage Range at A or B Bus Pins		-7	12	Volts
Supply Voltage <sup>(1)</sup>	$V_{DD1}, V_{DD2}$	-0.5	7	Volts
Digital Input Voltage		-0.5	5.5	Volts
Digital Output Voltage		-0.5	$V_{DD}^{+} 0.1$	Volts
Continuous Total Power Dissipation			725	mWatts (25°C)
			377	mWatts (85°C)
Maximum Output Current	I <sub>O</sub>		95	mA
Lead Solder Temperature (10s)			260	°C
ESD	2kV H	uman Body	Model	

#### **Insulation Specifications**

Parameter	Condition	Min.	Тур.	Max.	Units
Creepage Distance (External)		8.077			mm
Barrier Impedance			>1014  7		$\Omega \parallel pF$
Leakage Current	240 V <sub>RMS</sub>		0.2		μΑ
	60Hz				

#### **Recommended Operating Conditions**

Parameters	Symbol	Min.	Max.	Units
Supply Voltage	$V_{DD1}, V_{DD2}$	4.5	5.5	Volts
Input Voltage at any bus terminal	VI		12	Volts
(separately or common mode)	VIC		-7	
High-level Digital Input Voltage	V <sub>IH</sub>	3		Volts
Low-Level Digital Input Voltage	V <sub>IL</sub>		0.8	Volts
Differential Input Voltage <sup>(2)</sup>	V <sub>ID</sub>		+12/-7	Volts
High-Level Output Current (Driver)	I <sub>OH</sub>		-60	mA
High-Level Digital Output Current (Receiver)	I <sub>OH</sub>		8	mA
Low-Level Output Current (Driver)	I <sub>OL</sub>		60	mA
Low-Level Digital Output Current (Receiver)	I <sub>OL</sub>		8	mA
Operating Free Air Temperature	T <sub>A</sub>	-40	85	°C
Digital Input Signal Rise and Fall Times	t <sub>IR</sub> ,t <sub>IF</sub>	DC Stable		

#### IEC61010-1

TUV Certificate Numbers: Pending

Classification as Table 1.

Model	Pollution	Material	Max Working	Package Type
	Degree	Group	Voltage	16–SOIC (0.3")
IL485W	II	III	300 Vrms	$\checkmark$

#### <u>UL 1577</u>

Component Recognition program. File #: *Pending* Rated 2500Vrms for 1min.

# IL485W

#### **Driver Section**

All Specifications are  $T_{\mbox{min}}$  to  $T_{\mbox{max}}$  unless otherwise stated.

Parameter	Symbol	Min.	Typ. <sup>(5)</sup>	Max.	Units	Test Conditions
Input Clamp Voltage	V <sub>IK</sub>			-1.5	V	I <sub>L</sub> =-18mA
Output Voltage	V <sub>0</sub>	0		6	V	I <sub>O</sub> =0
Differential Output Voltage	V <sub>OD1</sub>	1.5		6	V	I <sub>O</sub> =0
Differential Output Voltage <sup>(6)</sup>	V <sub>OD2</sub>	1.5	2.5	5	V	$R_{L}=54\Omega$
Differential Output Voltage	V <sub>OD3</sub>	1.5		5	V	V <sub>test</sub> =-7 to 12V
Change in Magnitude of (7)	$\Delta  V_{OD} $			±0.2	V	$R_{\rm L}=54 \text{ or } 100\Omega$
Differential Output Voltage						_
Common Mode Output Voltage	V <sub>OC</sub>			3 -1	V	$R_L = 54 \text{ or } 100\Omega$
Change in Magnitude of (7)	$\Delta  V_{OC} $			±0.2	V	$R_{I} = 54 \text{ or } 100\Omega$
Common Mode Output Voltage						L
Output Current <sup>(4)</sup>	I <sub>O</sub>			1	mA	Output Disabled V <sub>0</sub> =12
-	0			-0.8	mA	V <sub>0</sub> =-7
High Level Input Current	I <sub>IH</sub>			10	μΑ	V <sub>1</sub> =3.5 V
Low Level Input Current	IL			-10	μΑ	V <sub>1</sub> =0.4 V
Short-Circuit Output Current	I <sub>OS</sub>			-250	mA	$V_0 = -6$
	00			-150		$V_0 = 0$
				250		$V_0 = 8$
Supply Current $(V_{DD2} = +5V)$	I <sub>DD2</sub>		27	34	mA	No Load (Outputs Enabled)
$(V_{DD1} = +5V)$	I <sub>DD1</sub>		5	10	mA	
Switching Characteristics	551					
Parameter	Symbol	Min.	Typ. <sup>(5)</sup>	Max.	Units	Test Conditions
Maximum Data Rate		35			Mbd	$R_L = 54\Omega, C_L = 50 pF$
Differential Output Delay Time	t <sub>D</sub> (OD)		16	25	ns	$R_{\rm L} = 54\Omega, C_{\rm L} = 50 \text{pF}$
Pulse Skew <sup>(10)</sup>	t <sub>SK(P)</sub>		1	6	ns	$R_L = 54\Omega, C_L = 50 pF$
Differential Output Transition Time	t <sub>T</sub> (OD)		8	10	ns	$R_L = 54\Omega, C_L = 50 pF$
Output Enable Time To High Level	t <sub>PZH</sub>		31	65	ns	$R_L = 54\Omega, C_L = 50 pF$
Output Enable Time To Low Level	t <sub>PZL</sub>		22	35	ns	$R_L = 54\Omega, C_L = 50 pF$
Output Disable Time From High Level	t <sub>PHZ</sub>		28	50	ns	$R_L = 54\Omega, C_L = 50 pF$
Output Disable Time From Low Level	t <sub>PLZ</sub>		16	32	ns	$R_L = 54\Omega, C_L = 50 pF$
Skew Limit <sup>(3)</sup>	t <sub>SK</sub> (LIM)		2	8	ns	$R_{\rm L}=54\Omega, C_{\rm L}=50 {\rm pF}$



# **Receiver Section**

	пил					
Parameter	Symbol	Min.	<b>Typ.</b> <sup>(5)</sup>	Max.	Units	Test Conditions
Positive-going Input Threshold Voltage	$V_{IT+}$			0.2	V	$V_0 = 2.7V, I_0 = -0.4mA$
Negative-going Input Threshold Voltage	V <sub>IT</sub> -	-0.2			V	$V_0 = 0.5V, I_0 = 8mA$
Hysteresis Voltage (V <sub>IT+</sub> - V <sub>IT-</sub> )	V <sub>hvs</sub>		60		mV	
High Level Digital Output Voltage	V <sub>OH</sub>	$V_{DD} - 0.2$			V	$V_{\rm ID}$ = 200mV, $I_{\rm OH}$ = -20 $\mu$ A
Low Level Digital Output Voltage	V <sub>OL</sub>			0.2	V	$V_{ID}$ = -200mV, $I_{OL}$ = 20 $\mu$ A
High-impedance-state output current	I <sub>OZ</sub>			±20	μΑ	$V_0 = 0.4$ to $(V_{DD2} - 0.5)$ V
Line Input Current <sup>(8)</sup>	II			1	mA	Other Input <sup>(11)</sup> = 0V $V_I$ = 12V
				-0.8		$V_I = -7V$
Input Resistance	r <sub>I</sub>		50		kΩ	
Supply Current $(V_{DD2} = +5)$	I <sub>DD2</sub>		27	34	mA	No Load (Outputs Enabled)
$(V_{DD1} = +5)$	I <sub>DD1</sub>		5	10	mA	
Switching Characteristics						
Parameter	Symbol	Min.	<b>Typ.</b> <sup>(5)</sup>	Max.	Units	Test Conditions
Maximum Data Rate	•	35	• •		Mbd	$R_L=54\Omega, C_L=50pF$
Propagation Time <sup>(9)</sup>	t <sub>PD</sub>		24	32	ns	$V_0$ =-1.5 to 1.5V, C <sub>L</sub> =15pF
Pulse Skew <sup>(10)</sup>	t <sub>SK(P)</sub>		1	6	ns	$V_0$ =-1.5 to 1.5V, C <sub>L</sub> =15pF
Skew Limit <sup>(3)</sup>	t <sub>sk(lim)</sub>		2	8	ns	$R_L=54\Omega, C_L=50pF$
Output Enable Time To High Level	t <sub>PZH</sub>		17	24	ns	C <sub>L</sub> =15pF
Output Enable Time To Low Level	t <sub>PZL</sub>		30	45	ns	C <sub>L</sub> =15pF
Output Disable Time From High Level	t <sub>PHZ</sub>		30	45	ns	C <sub>L</sub> =15pF
Output Disable Time From Low Level	t <sub>PLZ</sub>		18	27	ns	C <sub>L</sub> =15pF

All Specifications are  $T_{min}$  to  $T_{max}$  unless otherwise stated.

# **Electrostatic Discharge Sensitivity**

This product has been tested for electrostatic sensitivity to the limits stated in the specifications. However, NVE recommends that all integrated circuits be handled with appropriate care to avoid damage. Damage caused by inappropriate handling or storage could range from performance degradation to complete failure.

# ISOLOOP® **IL485W**

#### Notes:

- All Voltage values are with respect to network ground 1. except differential I/O bus voltages.
- 2. Differential input/output voltage is measured at the noninverting terminal A with respect to the inverting terminal B.
- Skew limit is the maximum difference in any two channels 3. in one device.
- 4. The power-off measurement in ANSI Standard EIA/TIA-422-B applies to disabled outputs only and is not applied to combined inputs and outputs.
- 5.
- All typical values are at  $V_{DD1}$ ,  $V_{DD2} = 5V$  and  $T_A = 25^{\circ}C$ . The minimum  $V_{OD2}$  with a 100 $\Omega$  load is either  $\frac{1}{2}V_{OD1}$  or 6. 2V, whichever is greater.
- $\Delta |V_{OD}|$  and  $\Delta |V_{OC}|$  are the changes in magnitude of  $V_{OD}$ 7. and  $V_{OC}$ , respectively, that occur when the input is changed form one logic state to the other.
- 8. This applies for both power on and power off, refer to ANSI standard RS-485 for exact condition. The EIA/TIA-422-B limit does not apply for a combined driver and receiver terminal.
- 9. Includes 8 ns read enable time. Maximum propagation delay is 25 ns after read assertion.
- 10. Pulse skew is defined as the  $|t_{PLH} t_{PHL}|$  of each channel.

#### **Application Notes:**

#### **Power Consumption**

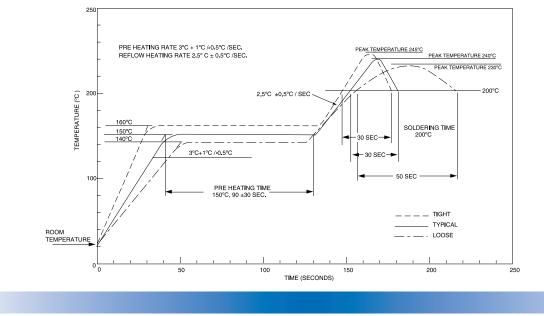
Isoloop<sup>®</sup> devices achieve their low power consumption from the manner by which they transmit data across the isolation barrier. By detecting the edge transitions of the input logic signal and converting these to narrow current pulses a magnetic field is created around the GMR Wheatstone bridge. Depending on the direction of the magnetic field, the bridge causes the output comparator to switch following the input logic signal. Since the current pulses are narrow, about 2.5ns wide, the power consumption is independent of mark-to-space ratio and solely dependent on frequency. This has obvious advantages over optocouplers whose power consumption is heavily dependent on its on-state and frequency.

The approximate power supply current per channel for

Isoloop<sup>®</sup> is: I(input) = 40  $\left(\frac{f}{fmax}\right)\left(\frac{1}{4}\right)$  mA where f = operating frequency fmax = 50 MHz

#### **Power Supplies**

It is recommended that low ESR ceramic capacitors be used to decouple the supplies. Both  $V_{DD1}$  and  $V_{DD2}$  should be bypassed with 47 nF capacitors. These should be placed no further than 1 cm from the device pins for proper operation. In addition,  $V_{\text{DD2}}$  should have a 10  $\mu F$  tantalum capacitor connected in parallel with the 47 nF capacitor.

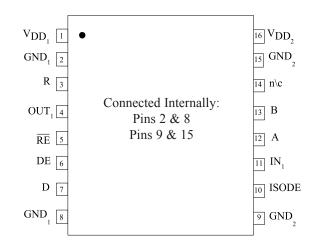


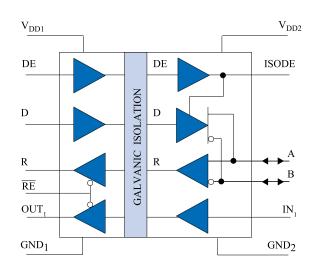
#### NVE Corporation 11409 Valley View Road Eden Prairie, MN 55344-3617 USA Telephone: (952) 829-9217 Fax: (952) 829-9189 Internet: www.isoloop.com

**Soldering Profile** 



# **Pin Configuration**





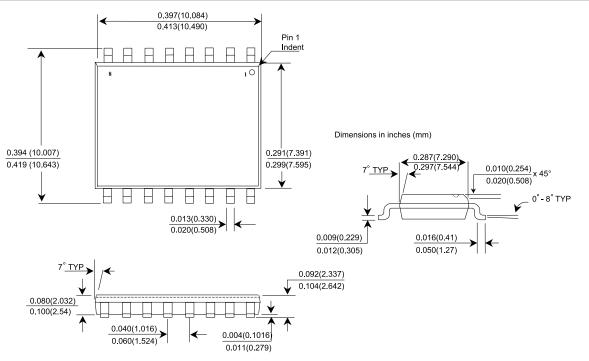
# **Pin Description**

Pin	Mnemonic	Description
1	V <sub>DD1</sub>	Input Power Supply
2	GND <sub>1</sub>	Input Power Supply Ground Return
3	R	Output Data from Bus
4	OUT <sub>1</sub>	Output From Auxiliary Isolation Channel
5	RE	Read Data Enable (if $\overline{RE}$ is high, R is high Impedence)
6	DE	Drive Enable
7	D	Data Input to Bus
8	GND1	Input Power Supply Ground Return
9	GND <sub>2</sub>	Output Power Supply Ground Return
10	ISODE	Isolated DE Output for use in Profibus applications where the state of the drive enable node needs to be monitored
11	IN <sub>1</sub>	Input to the Auxiliary Isolation Channel
12	А	'A' Bus Connection to RS485 (True)
13	В	'B' Bus Connection to RS485 (Inverse)
14	nc	No Internal Connection
15	GND <sub>2</sub>	Output Power Supply Return
16	V <sub>DD2</sub>	Output Power Supply

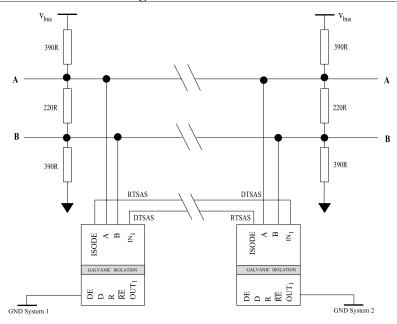
# IL485W

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# 0.3" SOIC-16 Package



**Application: PROFIBUS Fault Interrogation** 



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#### **About NVE**

An ISO 9001 Certified Company

NVE Corporation is a high technology components manufacturer having the unique capability to combine leading edge Giant Magnetoresistive (GMR) materials with integrated circuits to make high performance electronic components. Products include Magnetic Field Sensors, Magnetic Field Gradient Sensors (Gradiometer), Digital Magnetic Field Sensors, Digital Signal Isolators and Isolated Bus Transceivers.

NVE is a leader in GMR research and in 1994 introduced the world's first products using GMR material, a line of GMR magnetic field sensors that can be used for position, magnetic media, wheel speed and current sensing.

NVE is located in Eden Prairie, Minnesota, a suburb of Minneapolis. Please visit our Web site at www.nve.com or call 952-829-9217 for information on products, sales or distribution.

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#### Specifications shown are subject to change without notice.

ISB-DS-001-IL485W-E June 1, 2005