

LY503ALH

MEMS motion sensor:

high performance ±30 °/s analog yaw-rate gyroscope

Preliminary data

Features

- 2.7 V to 3.6 V single-supply operation
- Wide operating temperature range (-40 °C to +85 °C)
- High stability overtemperature
- Analog absolute angular-rate output
- Two separate outputs (1x and 4x amplified)
- Integrated low-pass filters
- Low power consumption
- Embedded power-down
- Embedded self-test
- High shock and vibration survivability
- ECOPACK[®] RoHS and "Green" compliant (see Section 5)

Applications

- Image stabilization for DVC and DSC
- Image stabilization for camera phones
- Motion controlled user interface
- GPS navigation systems

Description

The LY503ALH is a low-power single-axis micromachined gyroscope capable of measuring angular rate along yaw axis.

It provides excellent temperature stability and high resolution over an extended operating temperature range (-40 °C to +85 °C).

Device summary



The LY503ALH has a full scale of ± 30 °/s and is capable of detecting rates with a -3 dB bandwidth up to 140 Hz. The gyroscope is the combination of one actuator and one accelerometer integrated in a single micromachined structure.

It includes a sensing element composed by single driving mass, kept in continuos oscillating movement and able to react when an angular rate is applied based on the Coriolis principle.

A CMOS IC provides the measured angular rate to the external world through an analog output voltage, allowing high level of integration and production trimming to better match sensing element characteristics.

ST's gyroscope family leverages on robust and mature manufacturing process already used for the production of micromachined accelerometers.

ST is already in the field with several hundreds million sensors with excellent acceptance from the market in terms of quality, reliability and performance.

LY503ALH is provided in plastic land grid array (LGA) package. Several years ago ST pioneered successfully the usage of this package for accelerometers. Today ST has the widest manufacturing capability and strongest expertise in the world for production of sensor in plastic LGA package.

Order code	Order code Temperature range (°C)		Packing
LY503ALH	-40 to +85	LGA-16 (5x5x1.5)	Tray
LY503ALHTR -40 to +85		LGA-16 (5x5x1.5)	Tape and reel

July 2009

Downloaded from Elcodis.com electronic components distributor

Table 1.

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This is preliminary information on a new product now in development or undergoing evaluation. Details are subject to change without notice.

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1 Block diagram and pin description

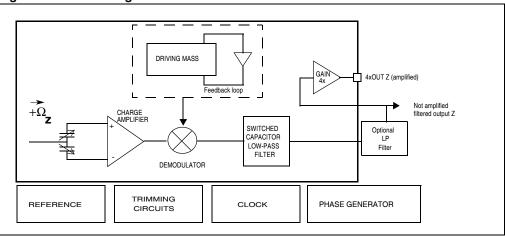
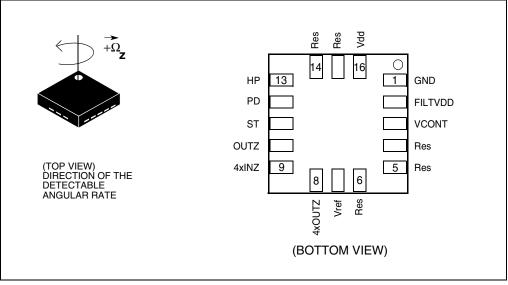


Figure 1. Block diagram

1.1 Pin description







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Pin #	Pin name	Analog function
1	GND	0V supply voltage
2	FILTVDD	PLL filter connection pin #2
3	VCONT	PLL filter connection pin #1
4	Res	Leave unconnected
5	Res	Leave unconnected
6	Res	Leave unconnected
7	Vref	Reference voltage
8	4xOUTZ	Z rate signal output voltage (amplified)
9	4xINZ	Input of 4x amplifier
10	OUTZ	Not amplified output
11	ST	Self-test (logic 0: normal mode; logic 1: self-test)
12	PD	Power-down (logic 0: normal mode; logic 1: power-down mode)
13	HP	High pass filter reset (logic 0: normal operation mode; logic1: external high pass filter is reset)
14,15	Res	Reserved. Connect to Vdd
16	Vdd	Power supply
-		

Table 2.Pin description



2 Mechanical and electrical specifications

2.1 Mechanical characteristics

Table 5.	mechanical characteristics @ vdd = 5 v, 1 = 25 °C unless otherwise hoted v						
Symbol	Parameter	Test condition	Min.	Typ. ⁽²⁾	Max.	Unit	
FSA	Maggurament renge	4x OUT (amplified)		±30		°/s	
FS	Measurement range	OUT (not amplified)		±120		°/s	
SoA	Sensitivity ⁽³⁾	4x OUT (amplified)		33.3		mV/ °/s	
So	Sensitivity	OUT (not amplified)		8.3		mV/ °/s	
SoDr	Sensitivity change vs temperature	Delta from 25°C		0.05		%/°C	
Voff	Zero-rate level ⁽³⁾			1.23		V	
Vref	Reference voltage			1.23		V	
OffDr	Zero-rate level change Vs temperature	Delta from 25°C		0.01		°/s/°C	
NL	Non linearity	Best fit straight line		±1		% FS	
BW	Bandwidth ⁽⁴⁾			140		Hz	
Rn	Rate noise density			0.014		°/s / $\sqrt{\text{Hz}}$	
Тор	Operating temperature range		-40		+85	°C	

Table 3. Mechanical characteristics @ Vdd = 3 V, T = 25 °C unless otherwise noted⁽¹⁾

1. The product is factory calibrated at 3 V. The operational power supply range is specified in Table 4.

2. Typical specifications are not guaranteed

3. Sensitivity and zero-rate level are not ratiometric to supply voltage

4. The product is capable of measuring angular rates extending from DC to the selected BW.



Supply current

Self-test input

Supply current in

power-down mode

Power-down input

Operating temperature

ldd

IddPdn

Vst

VPD

Тор

mA

μΑ

V

V

°C

5.5

5

0.2*Vdd

Vdd

0.2*Vdd

Vdd

+85

5

1

-40 to +125

2 (HBM)

0

0.8*Vdd

0

0.8*Vdd

-40

2.2 **Electrical characteristics**

Symbol	Parameter	Test condition	Min.	Тур. ⁽²⁾	Max.	Unit
Vdd	Supply voltage		2.7	3	3.6	V

PD pin connected to GND

PD pin connected to Vdd

Logic 0 level

Logic 1 level

Logic 0 level

Logic 1 level

Electrical characteristics @ Vdd =3 V, T=25 °C unless otherwise noted⁽¹⁾ Table 4.

1. The product is factory calibrated at 3 V

range

2. Typical specifications are not guaranteed

Absolute maximum ratings 2.3

Storage temperature range

Electrostatic discharge protection

Stresses above those listed as "Absolute maximum ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device under these conditions is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

Table 5.	Absolute maximum ratings	ute maximum ratings				
Symbol	Ratings	Maximum value	Unit			
Vdd	Supply voltage	-0.3 to 6	V			
Vin	Input voltage on any control pin (PD, ST)	-0.3 to Vdd +0.3	V			
А	Acceleration	3000 <i>g</i> for 0.5 ms				
А		10000 <i>g</i> for 0.1 ms				



T_{STG} ESD

> This is a mechanical shock sensitive device, improper handling can cause permanent damage to the part



This is an ESD sensitive device, improper handling can cause permanent damage to the part



°C

kV

3 Terminology

3.1 Sensitivity

An angular rate gyroscope is a device that produces a positive-going output voltage for counterclockwise rotation around the sensitive axis considered. Sensitivity describes the gain of the sensor and can be determined by applying a defined angular velocity to it. This value changes very little over temperature and time.

3.2 Zero-rate level

Zero-rate level describes the actual output signal if there is no angular rate present. The zero-rate level of precise MEMS sensors is, to some extent, a result of stress to the sensor and therefore zero-rate level can slightly change after mounting the sensor onto a printed circuit board or after exposing it to extensive mechanical stress. This value changes very little over temperature and time.

3.3 Self-test

Self-test allows testing of the mechanical and electrical part of the sensor, allowing the seismic mass to be moved by means of an electrostatic test-force. The self-test function is off when the ST pin is connected to GND. When the ST pin is tied to Vdd, an actuation force is applied to the sensor, emulating a definite Coriolis force. In this case the sensor output will exhibit a voltage change in its DC level which is also dependent on the supply voltage. When ST is active, the device output level is given by the algebraic sum of the signals produced by the velocity acting on the sensor and by the electrostatic test-force. If the output signals change within the amplitude specified in *Table 3*, then the mechanical element is working properly and the parameters of the interface chip are within the defined specifications.

3.4 High pass filter reset (HP)

The LY503ALH provides the possibility to reset the optional external high pass filter by applying a high logic value to the HP pad. This procedure ensures faster response, especially during overload conditions. Moreover, this operation is suggested each time the device is powered.



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4 Application hints

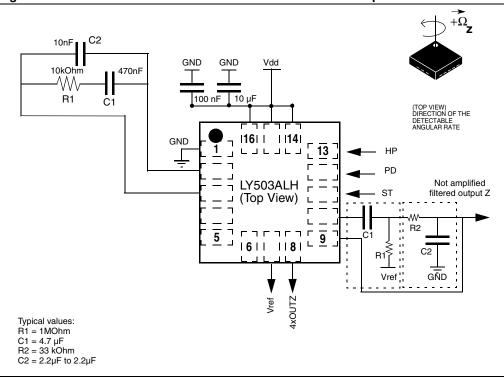


Figure 3. LY503ALH electrical connections and external component values

Power supply decoupling capacitors (100 nF ceramic or polyester + 10 μ F aluminum) should be placed as near as possible to the device (common design practice).

The LY503ALH allows band limiting of the output rate response through the use of an external low pass filter (suggested) and/or high pass filter (optional) in addition to the embedded low pass filter ($f_t = 140 \text{ Hz}$).

4xOUTZ is OUTZ amplified outputs line, internally buffered to ensure low output impedance.

If external high pass or low pass filtering is not applied it is mandatory to short-circuit pad 9 to pad 10 when amplified outputs are used.

When only non-amplified output is used (OUTZ), it is suggested to set pad 9 to fixed reference voltage (Vref).

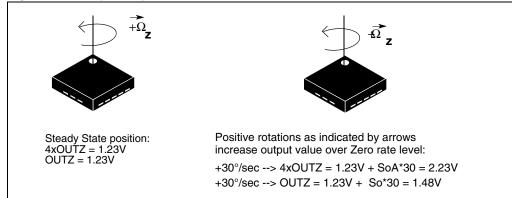
When high pass filter is applied to not amplified output (OUTx), it is recommended to buffer the line before entering ADC for performance optimization.

The LY503ALH IC includes a PLL (phase locked loop) circuit to synchronize driving and sensing interfaces. Capacitors and resistors must be added at the **FILTVDD** and **VCONT** pins (as shown in *Figure 3*) to implement a low-pass filter.



4.1 Output response vs. rotation

Figure 4. Output response vs. rotation



4.2 Soldering information

The LGA package is compliant with the ECOPACK[®], RoHS and "Green" standard. It is qualified for soldering heat resistance according to JEDEC J-STD-020C.

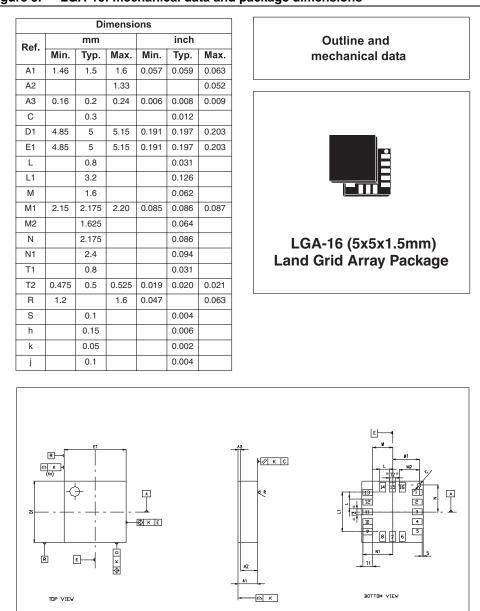
Leave "pin 1 indicator" unconnected during soldering.

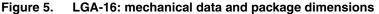
Land pattern and soldering recommendations are available at <u>www.st.com.</u>



5 Package information

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK[®] packages, depending on their level of environmental compliance. ECOPACK[®] specifications, grade definitions and product status are available at: www.st.com. ECOPACK is an ST trademark.







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6 Revision history

Table 6.Document revision history

Date	Revision	Changes
09-Jun-2009	1	Initial release
06-Jul-2009	2	Small text changes to improve readability. Updated <i>Table 4</i> .



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