

GPS Smart Receiver

User's Manual

GENERAL DESCRIPTION

The GPS smart receiver is a total solution GPS receiver, designed based on high sensitivity SiRF Star III architecture. This complete enabled GPS smart receiver provides high position, velocity and time accuracy performances as well as high sensitivity and tracking capabilities.

The GPS smart receiver is ideal for many applications such as car navigation, mapping, surveying, security and so on.

APPLICATIONS

- Automotive
- Asset tracking
- Personal/Portable Navigation
- Location Based Services enabled devices
- Sports and Recreation
- Geographic Surveying

KEY PRODUCT FEATURES

- Built-in SiRF Star III chipset
- 200,000 effective correlators for fast TTFF
- 20 channels "All-In-View" tracking
- Cold/Warm/Hot start time: 42/38/1 sec. (average)
- Superior sensitivity: -159dBm tracking
- Reacquisition time: 0.1 sec.
- Low power design (75mA, tracking)
- Build-in low noise, high gain active antenna
- Super-cohesive magnetic for installation
- Apply to host devices with TTL/RS232
- Size: 47.0 (L) X 39.0 (W) X 16 (H) mm
- Weight: 66.6g

SPECIFICATIONS

Key Technology	SiRF Star III chipset	Dimensions	
Performance		W x L x H (mm)	39 x 47 x 16
Receiver		W x L x H (inch)	1.54 x 1.85 x 0.63
Fraguanav		Moight	66.6g (2m, cable included)
Frequency	L1, 1575.42MHz	Weight	112.2g (5m, cable included)
C/A Code	1.023MHz chip rate	Power	DC 3.7 ~ 6V, typical 5V
Channel	20 channels all in view	Internal Back-up battery	3.0V, 5.5mAh, Lithium battery
Tracking Sensitivity	-159dBm	Back-up Current	7μA typ.
Acquisition Rate		Environmental	
Cold Start	42 sec. (average)	Operating Temperature	-40 °C ~ +85 °C
Warm Start	38 sec. (average)	Storage Temperature	-55 °C ~ +85 °C
Hot Start	1 sec. (average)	Relative Humidity	5% to 90% non-condensing
Reacquisition	0.1sec. (average)		
Update Rate	1 Hz (max.)		
Accuracy			
Position	5 - 25m CEP without SA		
Velocity	0.1m/sec, without SA		
Time	1μs synchronized to GPS time		
Dynamic Condition			
Altitude	<18,000m (60,000 feet)		
Velocity	<515m/sec (1,000 knots)		
Acceleration	<4G		
Motional Jerk	20m/sec ³ max.		
GPS Protocol	NMEA0183		
Interface			
TTL	Yes		

RS232

Yes

General NMEA Format

\$GPGGA

This message transfers global positioning system fix data. The \$GPGGA message structure is shown below:

Field	Format	Min chars	Max chars	Notes
Message ID	\$GPGGA	6	6	GGA protocol header.
UTC Time	hhmmss.sss	2,2,2.3	2,2,2.3	Fix time to 1ms accuracy.
Latitude	float	3,2.4	3,2.4	Degrees * 100 + minutes.
N/S	char	1	1	N=north or S=south
Indicator				
Longitude	float	3,2.4	3,2.4	Degree * 100 + minutes.
E/W	Char	1	1	E=east or W=west
indicator				
Position Fix	Int	1	1	0: Fix not available or invalid.
Indictor				1: GPS SPS mode. Fix available.
Satellites	Int	2	2	Number of satellites used to calculate fix.
Used				
HDOP	Float	1.1	3.1	Horizontal Dilution of Precision.
MSL Altitude	Float	1.1	5.1	Altitude above mean seal level
Units	Char	1	1	M Stands for "meters".
Geoid	Int	(0) 1	4	Separation from Geoid, can be blank.
Separation				
Units	Char	1	1	M Stands for "meters".
Age of	int	(0) 1	5	Age in seconds Blank (Null) fields when DGPS is not
Differential				used.
Corrections				
Diff	int	4	4	0000.
Reference				
Corrections				
Checksum	*xx	(0) 3	3	2 digits.
Message	<cr> <lf></lf></cr>	2	2	ASCII 13, ASCII 10.
terminator				

\$GPGLL

This message transfers Geographic position, Latitude, Longitude, and time. The \$GPGLL message structure is shown below:

Field	Format	Min chars	Max chars	Notes
Message ID	\$GPGLL	6	6	GLL protocol header.
Latitude	Float	1,2.1	3,2.4	Degree * 100 + minutes.
N/S Indicator	Char	1	1	N=north or S=south.
Longitude	Float	1,2.1	3,2.4	Degree * 100 + minutes.
E/W indicator	Character	1	1	E=east or W=west.
UTC Time	hhmmss.sss	1,2,2.1	2,2,2.3	Fix time to 1ms accuracy.
Status	Char	1	1	A Data Valid.
				V Data invalid.
Mode Indicator	Char	1	1	A Autonomous
Checksum	*хх	(0) 3	3	2 digits.
Message terminator	<cr><lf></lf></cr>	2	2	ASCII 13, ASCII 10.

\$GPGSA

This message transfers DOP and active satellites information. The \$GPGSA message structure is shown below:

Field	Format	Min	Max chars	Notes
		chars		
Message ID	\$GPGSA	6	6	GSA protocol header.
Mode	Char	1	1	M Manual, forced to operate in selected
				mode.
				A Automatic switching between modes.
Mode	Int	1	1	1 Fix not available.
				2 2D position fix.
				3 3D position fix.
Satellites Used	Int	2	2	SV on channel 1.
Satellites Used	Int	2	2	SV on channel 2.
Satellites Used	Int	2	2	SV on channel 12.
PDOP	Float	1.1	3.1	
HDOP	Float	1.1	3.1	
VDOP	Float	1.1	3.1	
Checksum	*xx	0	3	2 digits
Message terminator	<cr> <lf></lf></cr>	2	2	ASCII 13, ASCII 10

\$GPGSV

This message transfers information about satellites in view. The \$GPGSV message structure is shown below. Each record contains the information for up to 4 channels, allowing up to 12 satellites in view. In the final record of the sequence the unused channel fields are left blank with commas to indicate that a field has been omitted.

Field	Format	Min	Max chars	Notes
		chars		
Message ID	\$GPGSV	6	6	GSA protocol header.
Number of	Int	1	1	Number of messages in the message
messages				sequence from 1 to 3.
Message number	Int	1	1	Sequence number of this message in current
				sequence, form 1 to 3.
Satellites in view	Int	1	2	Number of satellites currently in view.
Satellite Id	Int	2	2	Satellite vehicle 1.
Elevation	Int	1	3	Elevation of satellite in degrees.
Azimuth	Int	1	3	Azimuth of satellite in degrees.
SNR	Int	(0) 1	2	Signal to noise ration in dBHz, null if the sv is
				not in tracking.
Satellite Id	Int	2	2	Satellite vehicle 2.
Elevation	Int	1	3	Elevation of satellite in degrees.
Azimuth	Int	1	3	Azimuth of satellite in degrees.
SNR	Int	(0) 1	2	Signal to noise ration in dBHz, null if the sv is
				not in tracking.
Satellite Id	Int	2	2	Satellite vehicle 3.
Elevation	Int	1	3	Elevation of satellite in degrees.
Azimuth	Int	1	3	Azimuth of satellite in degrees.
SNR	Int	(0) 1	2	Signal to noise ration in dBHz, null if the sv is
				not in tracking.
Satellite Id	Int	2	2	Satellite vehicle 4.
Elevation	Int	1	3	Elevation of satellite in degrees.
Azimuth	Int	1	3	Azimuth of satellite in degrees.
SNR	Int	(0) 1	2	Signal to noise ration in dBHz, null if the sv is
				not in tracking.
Checksum	*xx	(0) 3	3	2 digits.
Message terminator	<cr> <lf></lf></cr>	2	2	ASCII 13, ASCII 10.
		+	-	

\$GPRMC

This message transfers recommended minimum specific GNSS data. The \$GPRMC message format is shown below.

Field	Format	Min chars	Max chars	Notes
Message ID	\$GPRMC	6	6	RMC protocol header.
UTC Time	hhmmss.sss	1,2,2.1	2,2,2.3	Fix time to 1ms accuracy.
Status	char	1	1	A Data Valid.
				V Data invalid.
Latitude	Float	1,2.1	3,2.4	Degrees * 100 + minutes.
N/S Indicator	Char	1	1	N=north or S=south.
Longitude	Float	1,2.1	3,2.4	Degrees * 100 + minutes.
E/W indicator	Char	1	1	E=east or W=west.
Speed over ground	Float	1,1	5.3	Speed over ground in knots.
Course over ground	Float	1.1	3.2	Course over ground in degrees.
Date	ddmmyy	2,2,2	2,2,2	Current date.
Magnetic variation	Blank	(0)	(0)	Not used.
E/W indicator	Blank	(0)	(0)	Not used.
Mode	Char	1	1	A Autonomous
Checksum	*xx	(0) 3	3	2 digits.
Message terminator	<cr> <lf></lf></cr>	2	2	ASCII 13, ASCII 10.

\$GPVTG

This message transfers Velocity, course over ground, and ground speed. The \$GPVTG message format is shown below.

Field	Format	Min chars	Max	Notes
			chars	
Message ID	\$GPVTG	6	6	VTG protocol header.
Course (true)	Float	1.1	3.2	Measured heading in degrees.
Reference	Char	1	1	T = true heading.
Course (magnetic)	Float	1.1	3.2	Measured heading (blank).
Reference	Char	1	1	M = magnetic heading.
Speed	Float	1.1	4.2	Speed in knots.
Units	Char	1	1	N = knots.
Speed	Float	1.1	4.2	Speed
units	Char	1	1	K = Km/h.
Mode	Char	1	1	A Autonomous
Checksum	*xx	(0) 3	3	2 digits.
Message	<cr> <lf></lf></cr>	2	2	ASCII 13, ASCII 10.
terminator				

\$GPZDA

This message transfers UTC Time and Date. Since the latency of preparing and transferring the message is variable, and the time does not refer to a particular position fix, the seconds precision is reduced to 2 decimal places. The \$GPZGA message format is shown below.

Field	Format	Min chars	Max	Notes
			chars	
Message ID	\$GPZDA	6	6	ZDA protocol header.
UTC time	hhmmss.ss	2,2,2.2	2,2,2.2	0000000.00 to 235959.99
UTC day	dd	2	2	01 to 31, day of month.
UTC month	mm	2	2	01 to 12.
UTC Year	уууу	4	4	1989-9999.
Local zone hours	Int	(-)2	(-)2	Offset of local time zone (-13) to 13.
Local zone	Unsigned	2	2	
minutes				
Checksum	*хх	(0) 3	3	2 digits.
Message	<cr> <lf></lf></cr>	2	2	ASCII 13, ASCII 10.
terminator				

