

# XR21B1411 USER'S MANUAL WEB CONFIGURATION TOOL USER'S MANUAL

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#### 1.0 OVERVIEW

The XR21B1411 Enhanced 1-Channel Full-Speed USB UART has internal One-Time-Programmable (OTP) memory that can be used to customize the default settings of the XR21B1411. The web configuration tool for the XR21B1411 from Exar I/O Lab is shown above and can be accessed from a link on the XR21B1411 product page on Exar's website. This tool shows a visual representation of how the device will behave upon power-up such as the GPIO settings, UART settings and USB parameters (ie. Vendor ID, Product ID, Device Maximum Power, etc.). Once the XR21B1411 has been configured using this tool, the design configuration can be downloaded and used as an input file for Exar's OTP programming tool (also available from Exar's website) to program the XR21B1411 device.

This manual provides instruction for configuring the XR21B1411 and provides notes/tips for the various settings that are available. Note that once the XR21B1411 is programmed, no further changes or modifications can be made to the OTP.

#### 2.0 GPIO PIN CONFIGURATIONS

There are 4 modes available for the GPIO pins. Details of these 4 modes can be found in the XR21B1411 datasheet on **Exar's website**. The 4 modes that can be selected are:

- GPIO Mode
- Auto RTS/CTS HW Flow Control
- Auto DTR/DSR HW Flow Control
- Auto Half-Duplex Transceiver Enable (typically used for RS-485)

#### 2.1 Configuring the GPIO pins in GPIO Mode

There are 6 GPIO pins on the XR21B1411. By default, they are General Purpose I/Os that can be configured either as inputs or outputs. In this mode, the defaults for the GPIOs are:

- Inputs
- Internal pull-up and pull-down resistors disabled
- Interrupts are enabled for GPIOs configured as inputs

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## 2.1.1 Configuring GPIO inputs

#### 2.1.1.1 Enabling internal pull-up or pull-down resistors

As an input, a GPIO can have either an internal pull-up or pull-down resistor enabled. The pull-up or pull-down resistor for an input can be configured by clicking on "PU" or "PD" for the desired GPIO input pins (shown in the green circles in the image above). If enabled, the "PU" or "PD" will turn yellow for "enabled". Note that the configuration tool will not allow both to be enabled at the same time. The last block clicked, "PU" or "PD", will determine if the GPIO has an internal pull-up or pull-down resistor enabled. Clicking on the "PU" and "PD" blocks will not have any effects if the GPIO is an output. Also, changing an input to an output will clear any "PU" or "PD" block that has been enabled for that GPIO.

#### 2.1.1.2 Enabling GPIO interrupts

By default, the GPIO interrupts are enabled. Any GPIO that is an input will generate an interrupt when its input state changes. The GPIO interrupt can be disabled by clicking on the GPIOs in the purple circle in the image above. If a GPIO is configured as an output, the interrupt will automatically be disabled for that GPIO.



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#### 2.1.2 Configuring GPIO outputs

By clicking on the arrows highlighted with the red circle above, the GPIOs will change from inputs to outputs as shown in the image below. Once the GPIO is an output, the block next to the output arrow will turn yellow and display "0" indicating that the default output state will be low upon power-up. Clicking on the this block will change it to a "1" indicating that the default output state will be high upon power-up. An example of this is shown below for GPIO2.





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#### 2.2 Configuring the GPIO Pins in Auto RTS/CTS Flow Control Mode

In Auto RTS/CTS flow control mode, GPIO5/RTS# becomes an output pin and GPIO4/CTS# becomes an input pin. GPIO5/RTS# can not be changed to an input and, similarly, GPIO4/CTS# can not be changed to an output. The configuration is shown below.

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In this mode, GPIO3-GPIO0 can still be configured as described in "Section 2.1, Configuring the GPIO pins in GPIO Mode" on page 1.



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## 2.3 Configuring the GPIO Pins in Auto DTR/DSR Flow Control Mode

Auto DTR/DSR Flow Control Mode is similar to Auto RTS/CTS Flow Control Mode. In this mode, GPIO3/DTR# is configured as an output and GPIO2/DSR# is configured as an input and their direction can not be changed. The Auto DTR/DSR Flow Control configuration is shown below.

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Pull Up Enabled       Interrupt Enabled         PUI Up Disabled       Interrupt Disabled         PUI Up Grayed       Interrupt Grayed         PUI Up Grayed       Active Low         PD       Pull Down Enabled         PD       Pull Down Grayed         PUI Down Grayed       Output Pin (Editable)	<ul> <li>Input Pin (Editable)</li> <li>Output Pin (Locked)</li> <li>Input Pin (Locked)</li> <li>Default Logic Level High (Editable)</li> <li>Default Logic Level Low (Editable)</li> <li>Default Logic Level (Disabled)</li> </ul>				

In this mode, GPIO5, GPIO4, GPIO1, and GPIO0 can still be configured as described in "Section 2.1, Configuring the GPIO pins in GPIO Mode" on page 1.



#### 2.4 Configuring the GPIO Pins in Auto Half-Duplex Transceiver Enable Mode

The Auto Half-Duplex Transceiver enable mode is typically used in half-duplex RS-485 applications. In this mode the GPIO5/RTS# pin is used to control the driver enable of an RS-485 transceiver. When this mode is selected, the polarity will also need to be selected as active high or active low.

- Active High The GPIO5/RTS# pin will be low when the UART is not transmitting data and the GPIO5/ RTS# pin will be high when the UART is transmitting data.
- Active Low The GPIO5/RTS# pin will be high when the UART is not transmitting data and the GPIO5/ RTS# pin will be low when the UART is transmitting data.

An example of how the Auto Half-Duplex Transceiver enable mode is shown below. The block next to the "TX EN" also shows whether the selected polarity is active high or active low.



In this mode, GPIO4-GPIO0 can still be configured as described in "Section 2.1, Configuring the GPIO pins in GPIO Mode" on page 1.



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#### 3.0 USB CONFIGURATIONS

By clicking on the "USB" block, an additional configuration window will appear on the right hand side of the screen, as shown below.



#### 3.1 Entering a Valid Vendor ID and Product ID

In this new window, the USB parameters can be entered. The configuration tool will have defaults of 0x0000 in the Vendor ID (VID) and Product ID (PID) field. A VID or PID of 0x0000 is not an acceptable and will reported later as an error when the "Check Design" button is pressed if valid IDs have not been entered. If using Exar's VID (0x04E2) and PID (0x1411), these values will need to be entered. A unique range of PIDs can be requested from Exar by sending an e-mail request to uarttechsupport@exar.com.





#### 3.2 USB Manufacturer, Product, Serial Number Strings

The default Manufacturer String is "Exar" and Product String is "XR21B1411" if no string values have been entered. There is no default value for the Serial Number String. If one string is entered, then all three strings need to be updated or they will not have a value when the OTP is programmed. Entering a value for the Serial Number String is optional.

#### 3.3 Remote Wake-up Support

By default, remote wake-up support is enabled. This can be disabled by unchecking the box. Note that if the software driver does not have the remote wake-up feature enabled, then the XR21B1411 will not issue a remote wake-up signal when a remote wake-up event occurs. Note that the standard CDC-ACM driver does not support the Remote Wake-up feature.

#### 3.4 Selecting the Power Mode

By default, bus-powered mode is enabled. The XR21B1411 can be configured for self-powered mode by checking the box next to "Self Powered". For self-power mode, it is recommended that the box next to "Enable VBUS Sense" also be checked. The VBUS Sense feature disables the internal pull-up resistor on the USBD+ pin when there is no power on the VBUS pin. This is required for USB compliance. If the VBUS Sense feature is not available, then an external mechanism is required to disable the power supply to the XR21B1411.

#### 3.5 USB Max Power

By default, the USB maximum power is configured as 100 mA. This is the maximum for a low power device, as described in the USB specifications. Any board that requires more than 100 mA from VBUS will be considered a high power device. The maximum allowable supply current is 500 mA for a high power device. The USB max power can be changed by clicking on the arrows on either end of the scroll bar or by dragging the horizontal scroll bar.

#### 3.6 LOWPOWER Pin Polarity

The default polarity of the LOWPOWER pin (pin 1) is active high as shown in the drawing. The polarity can be changed by clicking on the box below the USB block in the drawing. The inner circle will become yellow to indicate that the LOWPOWER pin is now active low.



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#### 4.0 UART SETTING CONFIGURATIONS

Clicking on the "UART" block will remove the USB Configuration window and display the "UART Configuration Window" as shown below.





#### 4.1 Selecting the Core Clock Frequency

The available core clock frequencies are 6 MHz, 12 MHz, 24 MHz and 48 MHz. The selection of the core clock frequency will affect the maximum baud rate and the power consumption. The maximum baud rate can be calculated by dividing the core clock frequency by 4.

- 6 MHz core clock frequency => 1.5 Mbps maximum baud rate
- 12 MHz core clock frequency => 3 Mbps maximum baud rate
- 24 MHz core clock frequency => 6 Mbps maximum baud rate
- 48 MHz core clock frequency => 12 Mbps maximum baud rate

For details of how much power the XR21B1411 consumes with each core clock frequency, refer to the XR21B1411 datasheet on Exar's website. Note that the higher the core clock frequency, the more power it consumes. If an application is battery-powered, it will be beneficial to use a 6 MHz core clock frequency if baud rates above 1.5 Mbps do not need to be supported.

#### 4.2 Selecting the UART default settings

Default baud rates and character formats can be entered and selected. Most standard software drivers and applications will typically initialize the UART settings. However, this may be helpful for custom software drivers and/or software applications that do not initialize/configure the UART settings.

#### 5.0 CHECK DESIGN AND GENERATE CONFIGURATION FILE

Once all of the desired configurations have been entered or selected, click on the "Check Design" button. This will check to see if there are any errors. If there are errors, then a pop-up message, as shown below, will appear indicating the error and a button to go back to the correct page to fix it.





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In this example, the VID and PID were not entered. Clicking on "Back to USB" will bring up the "USB Configuration" block where the VID and PIDs can be entered. Once the error has been fixed, click "Check Design" again. If there are no errors, then a pop-up window similar to the one below will appear.



Click on "Download Design File" to view and save the generated file. The file will have a ".xml" extension. This saved file can be used at a later date by loading it using the "Load an Existing Design" block.

## 6.0 XR21B1411 SOFTWARE DRIVER AND OTP PROGRAMMING TOOL

The XR21B1411 Software Driver and OTP Programming Tool can be downloaded from **Exar's website**. The software driver needs to be installed before the OTP Programming Tool can be used. It is recommended that the configuration be carefully reviewed before programming the OTP memory. <u>Once the OTP memory has been programmed, it can not be un-programmed.</u> It is also recommended that samples be programmed and tested before programming in volume.

#### 7.0 TECHNICAL SUPPORT

If there are any questions about the web configuration tool, configuration file or the XR21B1411, send your questions to <u>uarttechsupport@exar.com</u>.

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