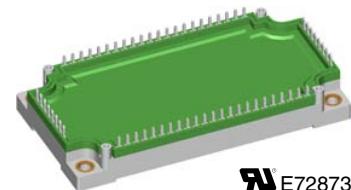
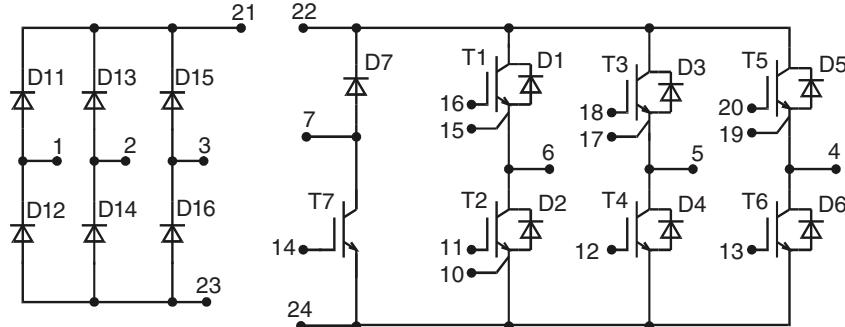
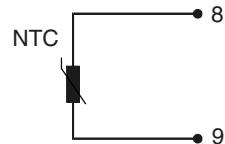


Converter - Brake - Inverter Module (CBI3)



See outline drawing for pin arrangement

Preliminary data



Three Phase Rectifier	Brake Chopper	Three Phase Inverter
$V_{RRM} = 1600 \text{ V}$	$V_{CES} = 600 \text{ V}$	$V_{CES} = 600 \text{ V}$
$I_{FAVM} = 90 \text{ A}$	$I_{C25} = 50 \text{ A}$	$I_{C25} = 125 \text{ A}$
$I_{FSM} = 850 \text{ A}$	$V_{CE(\text{sat})} = 1.9 \text{ V}$	$V_{CE(\text{sat})} = 1.9 \text{ V}$

Input Rectifier D11 - D16

Symbol	Conditions	Maximum Ratings		
V_{RRM}		1600		V
I_{FAV}	$T_c = 80^\circ\text{C}; \text{sine } 180^\circ$	65		A
I_{DAVM}	$T_c = 80^\circ\text{C}; \text{rectangular; } d = 1/3; \text{bridge}$	180		A
I_{FSM}	$T_{vj} = 25^\circ\text{C}; t = 10 \text{ ms; sine } 50 \text{ Hz}$	850		A
P_{tot}	$T_c = 25^\circ\text{C}$	170		W

Application: AC motor drives with

- € Input from single or three phase grid
- € Three phase synchronous or asynchronous motor
- € Electric braking operation

Features

- € High level of integration - only one power semiconductor module required for the whole drive
- € NPT IGBT technology with low saturation voltage, low switching losses, high RBSOA and short circuit ruggedness
- € Epitaxial free wheeling diodes with Hiperfast and soft reverse recovery
- € Industry standard package with insulated copper base plate and soldering pins for PCB mounting
- € Temperature sense included

Symbol	Conditions	Characteristic Values			
		($T_{vj} = 25^\circ\text{C}$, unless otherwise specified)	min.	typ.	max.
V_F	$I_F = 100 \text{ A}; T_{vj} = 25^\circ\text{C}$ $T_{vj} = 125^\circ\text{C}$		1.3	1.5	V
I_R	$V_R = V_{RRM}; T_{vj} = 25^\circ\text{C}$ $T_{vj} = 125^\circ\text{C}$		1	0.05	mA mA
R_{thJC}	(per diode)			0.73	K/W

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Output Inverter T1 - T6

Symbol	Conditions	Maximum Ratings		
V_{CES}	$T_{VJ} = 25^\circ\text{C}$ to 150°C	600	V	
V_{GES}	Continuous	± 20	V	
I_{C25}	$T_C = 25^\circ\text{C}$	125	A	
I_{C80}	$T_C = 80^\circ\text{C}$	85	A	
RBSOA	$V_{GE} = \pm 15 \text{ V}$; $R_G = 2.2 \Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 200$ $V_{CEK} \leq V_{CES}$	A	
t_{sc} (SCSOA)	$V_{CE} = V_{CES}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 2.2 \Omega$; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10	μs	
P_{tot}	$T_C = 25^\circ\text{C}$	410	W	

Symbol	Conditions	Characteristic Values			
		($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)	min.	typ.	max.
$V_{CE(sat)}$	$I_C = 100 \text{ A}$; $V_{GE} = 15 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.9 2.2	2.5	V	
$V_{GE(th)}$	$I_O = 1.5 \text{ mA}$; $V_{GE} = V_{CE}$	4.5		6.5	V
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.5	1.4	mA	mA
I_{GES}	$V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$		400	nA	
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	Inductive load, $T_{VJ} = 125^\circ\text{C}$ $V_{CE} = 300 \text{ V}$; $I_C = 100 \text{ A}$ $V_{GE} = \pm 15 \text{ V}$; $R_G = 2.2 \Omega$	25 11 150 30 1.0 2.9		ns ns ns ns mJ mJ	
C_{ies}		4.3		nF	
Q_{Gon}		340		nC	
R_{thJC}	(per IGBT)		0.3	K/W	

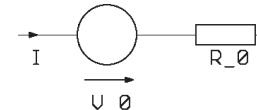
Output Inverter D1 - D6

Symbol	Conditions	Maximum Ratings		
I_{F25}	$T_C = 25^\circ\text{C}$	140	A	
I_{F80}	$T_C = 80^\circ\text{C}$	85	A	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
V_F	$I_F = 100 \text{ A}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.9 1.4	2.2	V
I_{RM} t_r	$I_F = 60 \text{ A}$; $dI_F/dt = -500 \text{ A}/\mu\text{s}$; $T_{VJ} = 125^\circ\text{C}$ $V_R = 300 \text{ V}$; $V_{GE} = 0 \text{ V}$	28 100		A ns
R_{thJC}			0.61	K/W

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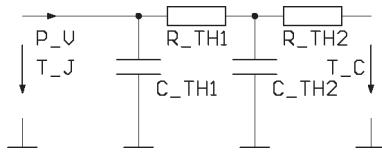
Equivalent Circuits for Simulation**Conduction**IGBT (typ. at $V_{GE} = 15 \text{ V}$; $T_J = 125^\circ\text{C}$)
T1-T6

$V_0 = 1.05 \text{ V}; R_0 = 11.5 \text{ m}\Omega$

T7
 $V_0 = 1.05 \text{ V}; R_0 = 21.5 \text{ m}\Omega$ Diode (typ. at $T_J = 125^\circ\text{C}$)

D1-D6

$V_0 = 1.15 \text{ V}; R_0 = 2.5 \text{ m}\Omega$

D7
 $V_0 = 1.15 \text{ V}; R_0 = 12.5 \text{ m}\Omega$ D11-D16
 $V_0 = 0.85 \text{ V}; R_0 = 4 \text{ m}\Omega$ **Thermal Response**

IGBT (typ.)

T1-T6

$C_{th1} = 0.232 \text{ J/K}; R_{th1} = 0.223 \text{ K/W}$
 $C_{th2} = 1.504 \text{ J/K}; R_{th2} = 0.077 \text{ K/W}$

T7
 $C_{th1} = 0.123 \text{ J/K}; R_{th1} = 0.419 \text{ K/W}$
 $C_{th2} = 0.944 \text{ J/K}; R_{th2} = 0.131 \text{ K/W}$

Diode (typ.)

D1-D6

$C_{th1} = 0.138 \text{ J/K}; R_{th1} = 0.48 \text{ K/W}$
 $C_{th2} = 0.957 \text{ J/K}; R_{th2} = 0.13 \text{ K/W}$

D7
 $C_{th1} = 0.038 \text{ J/K}; R_{th1} = 1.74 \text{ K/W}$
 $C_{th2} = 0.435 \text{ J/K}; R_{th2} = 0.36 \text{ K/W}$ D11-D16
 $C_{th1} = 0.112 \text{ J/K}; R_{th1} = 0.568 \text{ K/W}$
 $C_{th2} = 0.745 \text{ J/K}; R_{th2} = 0.162 \text{ K/W}$

Brake Chopper T7

Symbol	Conditions	Maximum Ratings		
V_{CES}	$T_{VJ} = 25^\circ\text{C}$ to 150°C	600		V
V_{GES}	Continuous	± 20		V
I_{C25}	$T_C = 25^\circ\text{C}$	75		A
I_{C80}	$T_C = 80^\circ\text{C}$	50		A
RBSOA	$V_{GE} = \pm 15 \text{ V}$; $R_G = 22 \Omega$; $T_{VJ} = 125^\circ\text{C}$ Clamped inductive load; $L = 100 \mu\text{H}$	$I_{CM} = 100$ $V_{CEK} \leq V_{CES}$		A
t_{sc} (SCSOA)	$V_{CE} = V_{CES}$; $V_{GE} = \pm 15 \text{ V}$; $R_G = 22 \Omega$; $T_{VJ} = 125^\circ\text{C}$ non-repetitive	10		μs
P_{tot}	$T_C = 25^\circ\text{C}$	225		W
Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^\circ\text{C}$, unless otherwise specified)		
		min.	typ.	max.
$V_{CE(sat)}$	$I_C = 50 \text{ A}$; $V_{GE} = 15 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	1.9 2.1	2.3 V	V
$V_{GE(th)}$	$I_C = 1 \text{ mA}$; $V_{GE} = V_{CE}$	4.5		6.5 V
I_{CES}	$V_{CE} = V_{CES}$; $V_{GE} = 0 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.5	0.5 mA mA	
I_{GES}	$V_{CE} = 0 \text{ V}$; $V_{GE} = \pm 20 \text{ V}$		200 nA	
$t_{d(on)}$ t_r $t_{d(off)}$ t_f E_{on} E_{off}	$\left. \begin{array}{l} \text{Inductive load, } T_{VJ} = 125^\circ\text{C} \\ V_{CE} = 300 \text{ V}; I_C = 50 \text{ A} \\ V_{GE} = \pm 15 \text{ V}; R_G = 22 \Omega \end{array} \right\}$	50 55 300 30 2.3 1.7	ns ns ns ns mJ mJ	
C_{ies} Q_{Gon}		2.8 120	nF nC	
R_{thJC}			0.55 K/W	

Brake Chopper D7

Symbol	Conditions	Maximum Ratings		
V_{RRM}	$T_{VJ} = 25^\circ\text{C}$ to 150°C	600		V
I_{F25}	$T_C = 25^\circ\text{C}$	35		A
I_{F80}	$T_C = 80^\circ\text{C}$	24		A
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
V_F	$I_F = 50 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	2.2 1.8	2.5 V	V
I_R	$V_R = V_{RRM}$; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = 125^\circ\text{C}$	0.1	0.1 mA mA	
I_{RM} t_{rr}	$\left. \begin{array}{l} I_F = 15 \text{ A}; di_F/dt = -400 \text{ A}/\mu\text{s} \\ V_R = 300 \text{ V} \end{array} \right\}$	13 90	A ns	
R_{thJC}			2.1 K/W	

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Temperature Sensor NTC

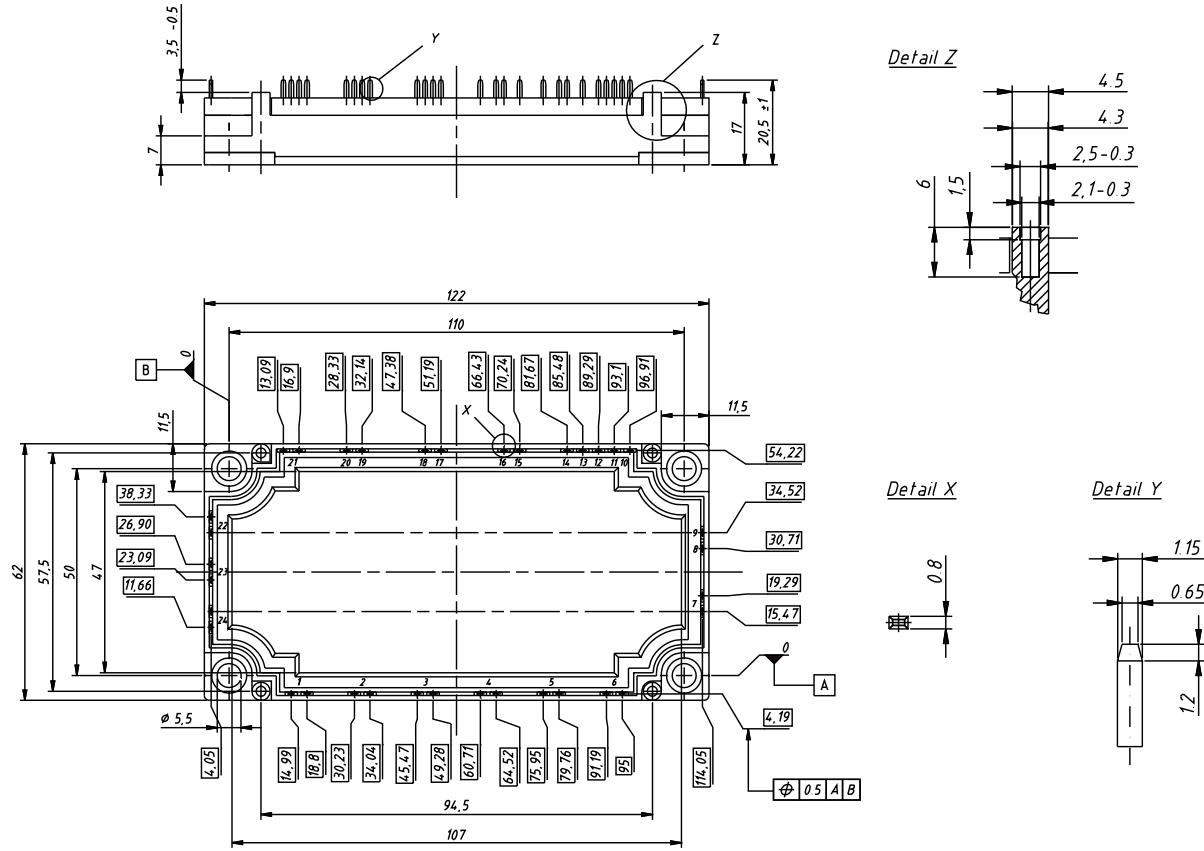
Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
R_{25}	$T = 25^\circ\text{C}$	4.75	5.0	5.25 k Ω
$B_{25/50}$			3375	K

Module

Symbol	Conditions	Maximum Ratings		
T_{VJ}	operating	-40...+125	$^\circ\text{C}$	
T_{JM}		+150	$^\circ\text{C}$	
T_{stg}		-40...+125	$^\circ\text{C}$	
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}; 50/60 \text{ Hz}$	2500	V~	
M_d	Mounting torque (M5)	3 - 6	Nm	

Symbol	Conditions	Characteristic Values		
		min.	typ.	max.
$R_{pin-chip}$			5	m Ω
d_s	Creepage distance on surface	6		mm
d_A	Strike distance in air	6		mm
R_{thCH}	with heatsink compound	0.01		K/W
Weight		300		g

Dimensions in mm (1 mm = 0.0394")



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