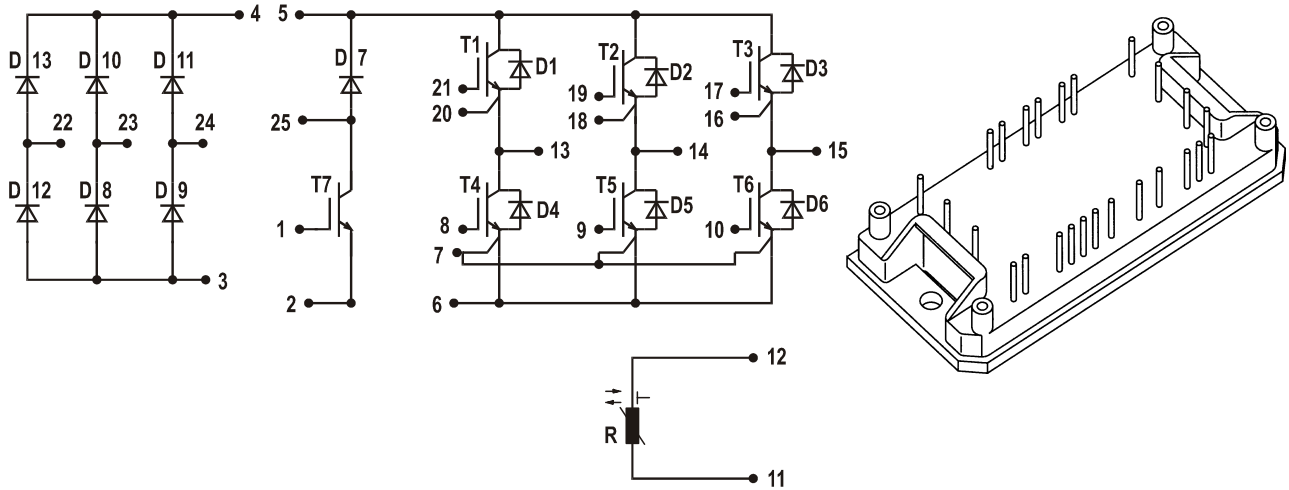


Converter - Brake - Inverter Module (CBI1)



Rectifier	Brake	Inverter
$V_{RRM} = 1200V$	$V_{CES} = 600 V$	$V_{CES} = 600 V$
$I_{FAVM} = 11 A$	$I_{C25} = 7 A$	$I_{C25} = 7 A$
$I_{FSM} = 250 A$	$V_{CE(sat)} = 2.0 V$	$V_{CE(sat)} = 2.0 V$

Input Rectifier Bridge D8 - D13		
Symbol	Conditions	Maximum Ratings
V_{RRM}		1200 V
I_F	$T_{VJ} = 25^{\circ}C$	36 A
I_{FAVM}	$T_{VJ} = 150^{\circ}C; T_K = 70^{\circ}C$	11 A
I_{FSM}	$T_{VJ} = 45^{\circ}C; t = 10 \text{ ms sine } 50 \text{ Hz}$	250 A
i^2t	$T_{VJ} = 125^{\circ}C$	310 A ² s
T_{VJ}		+150 $^{\circ}C$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}C$, unless otherwise specified)		
		min.	typ.	max.
I_R	$V_{RRM} = 1200 V; T_{VJ} = 25^{\circ}C$ $T_{VJ} = 125^{\circ}C$			10 μA 3 mA
V_F	$I_F = 36 A$		1.15	1.4 V
R_{thJC}	per die		1.4	$^{\circ}C/W$

Features

- NPT IGBT technology Square RBSOA, no latchup
- Free wheeling diodes with Hiperfast and soft recovery behaviour
- Isolation voltage 2500 V~
- Built in temperature sense
- High level of integration: one module for complete drive system
- **Direct Copper Bonded** Al_2O_3 ceramic base plate

Applications

- AC motor control
- AC servo and robot drives

Advantages

- No need of external isolation
- Easy to mount with two screws
- Package designed for wave soldering
- High temperature and power cycling capability

IXYS reserves the right to change limits, test conditions and dimensions.

Output Inverter T1 - T6, D1 - D6

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$	600	V
V_{CGR}	$T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$	600	V
V_{GE}	$T_{VJ} = 25^{\circ}\text{C}$	± 20	V
I_C	$T_C = 25^{\circ}\text{C}$	7	A
	$T_C = 90^{\circ}\text{C}$	4.5	A
I_{CM}	$t_p = 1 \text{ ms} = 1\% \text{ duty cycle};$ $T_C = 25^{\circ}\text{C}$ $T_C = 90^{\circ}\text{C}$	14	A
		9	A
t_{SC}	IGBT $V_{CE} = 600 \text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	38	W
T_{VJ}	Free-Wheeling Diode	+150	$^{\circ}\text{C}$
T_{VJ}	IGBT	+150	$^{\circ}\text{C}$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)		
		min.	typ.	max.
I_{CES}	$V_{GE} = 0 \text{ V}; V_{CE} = 600 \text{ V}$			10 μA
I_{GES}	$V_{CE} = 0 \text{ V}; V_{GE} = 25 \text{ V}$			100 nA
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_C = 0.2 \text{ mA}$	3	4	5 V
$V_{(BR)CES}$	$V_{GE} = 0 \text{ V}; I_C = 0.5 \text{ mA}; T_{VJ} = -40^{\circ}\text{C}$	600		V
$V_{CE(sat)}$	$V_{GE} = 15 \text{ V}; I_C = 4 \text{ A};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$	2.0	2.5	V
		2.3	2.8	V
t_f t_r	Inductive load, $T_{VJ} = 150^{\circ}\text{C}$	100	150	ns
		20	30	ns
$t_{d(on)}$ $t_{d(off)}$	$V_{CC} = 400 \text{ V}; I_C = 4 \text{ A}$ $R_G = 50 \Omega; V_{GE} = \pm 15 \text{ V}$	20	30	ns
		260	390	ns
E_{off} E_{on}		0.1	0.13	mJ
		0.2	0.26	mJ
C_{iss} C_{oss} C_{rss}	$V_{GE} = 0 \text{ V}$ $V_{CE} = 25 \text{ V}$ $f = 1 \text{ MHz}$	270	340	pF
		30	40	pF
		18	23	pF
g_{fs}	$V_{CE} = 20 \text{ V}; I_C = 4 \text{ A}$	0.8	3.2	S
Q_g	$V_{CC} = 400 \text{ V}; I_C = 6 \text{ A pulse}; V_{GE} = 15 \text{ V}$	24		nC
V_F	$I_F = 10 \text{ A}; V_{GE} = 0 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$	2		V
		1.8		V
t_{rr}	$I_F = 10 \text{ A}; V_R = -300 \text{ V}; V_{GE} = 0 \text{ V}$ $di_F/dt = -350 \text{ A}/\mu\text{s}; T_{VJ} = 100^{\circ}\text{C}$	0.2		μs
Q_r	$I_F = 10 \text{ A}; V_R = -300 \text{ V};$ $di_F/dt = -350 \text{ A}/\mu\text{s}; V_{GE} = 0 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.3		μC
		0.9		μC
I_r			250	μA
R_{thJC}	IGBT (per die)	2.7		$^{\circ}\text{C}/\text{W}$
	Diode (per die)	2.3		$^{\circ}\text{C}/\text{W}$

Brake Chopper T7, D7

Symbol	Conditions	Maximum Ratings	
V_{CES}	$T_{VJ} = 25^{\circ}\text{C}$	600	V
V_{CGR}	$T_{VJ} = 25^{\circ}\text{C}; R_{GE} = 20\text{k}\Omega$	600	V
V_{GE}	$T_{VJ} = 25^{\circ}\text{C}$	± 20	V
I_C	$T_C = 25^{\circ}\text{C}$	7	A
	$T_C = 90^{\circ}\text{C}$	4.5	A
I_{CM}	$t_p = 1 \text{ ms} = 1\% \text{ duty cycle};$ $T_C = 25^{\circ}\text{C}$ $T_C = 90^{\circ}\text{C}$	14	A
		9	A
t_{SC}	IGBT $V_{CE} = 600 \text{ V}; T_{VJ} = 125^{\circ}\text{C}$ non-repetitive	10	μs
P_{tot}	$T_C = 25^{\circ}\text{C}$	38	W
T_{VJ}	Free-Wheeling Diode	+150	$^{\circ}\text{C}$
T_{VJ}	IGBT	+150	$^{\circ}\text{C}$

Symbol	Conditions	Characteristic Values ($T_{VJ} = 25^{\circ}\text{C}$, unless otherwise specified)		
		min.	typ.	max.
I_{CES}	$V_{GE} = 0 \text{ V}; V_{CE} = 600 \text{ V}$			20 μA
I_{GES}	$V_{CE} = 0 \text{ V}; V_{GE} = 25 \text{ V}$			100 nA
$V_{GE(th)}$	$V_{GE} = V_{CE}; I_C = 0.2 \text{ mA}$	3	4	5 V
$V_{(BR)CES}$	$V_{GE} = 0 \text{ V}; I_C = 0.5 \text{ mA}; T_{VJ} = -40^{\circ}\text{C}$	600		V
$V_{CE(sat)}$	$V_{GE} = 15 \text{ V}; I_C = 4 \text{ A};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$	2.0	2.5	V
		2.3	2.8	V
t_f t_r $t_{d(on)}$ $t_{d(off)}$ E_{off} E_{on}	Inductive load, $T_{VJ} = 150^{\circ}\text{C}$ $V_{CC} = 400 \text{ V}; I_C = 4 \text{ A}$ $R_G = 50 \Omega; V_{GE} = \pm 15 \text{ V}$	100	150	ns
		20	30	ns
		20	30	ns
		260	390	ns
		0.1	0.13	mJ
		0.2	0.26	mJ
C_{iss} C_{oss} C_{rss}	$V_{GE} = 0 \text{ V}$ $V_{CE} = 25 \text{ V}$ $f = 1 \text{ MHz}$	270	340	pF
		30	40	pF
		18	23	pF
g_{fs}	$V_{CE} = 20 \text{ V}; I_C = 4 \text{ A}$	0.8	3.2	S
Q_g	$V_{CC} = 400 \text{ V}; I_C = 6 \text{ A pulse}; V_{GE} = 15 \text{ V}$	24		nC
V_F	$I_F = 10 \text{ A}; V_{GE} = 0 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 150^{\circ}\text{C}$	2		V
		1.8		V
t_{rr}	$I_F = 10 \text{ A}; V_R = -300 \text{ V}; V_{GE} = 0 \text{ V}$ $di_F/dt = -350 \text{ A}/\mu\text{s}; T_{VJ} = 100^{\circ}\text{C}$	0.2		μs
Q_r	$I_F = 10 \text{ A}; V_R = -300 \text{ V};$ $di_F/dt = -350 \text{ A}/\mu\text{s}; V_{GE} = 0 \text{ V};$ $T_{VJ} = 25^{\circ}\text{C}$ $T_{VJ} = 125^{\circ}\text{C}$	0.3		μC
		0.9		μC
I_r			250	μA
R_{thJC}	IGBT (per die)	2.7		$^{\circ}\text{C}/\text{W}$
	Diode (per die)	2.3		$^{\circ}\text{C}/\text{W}$

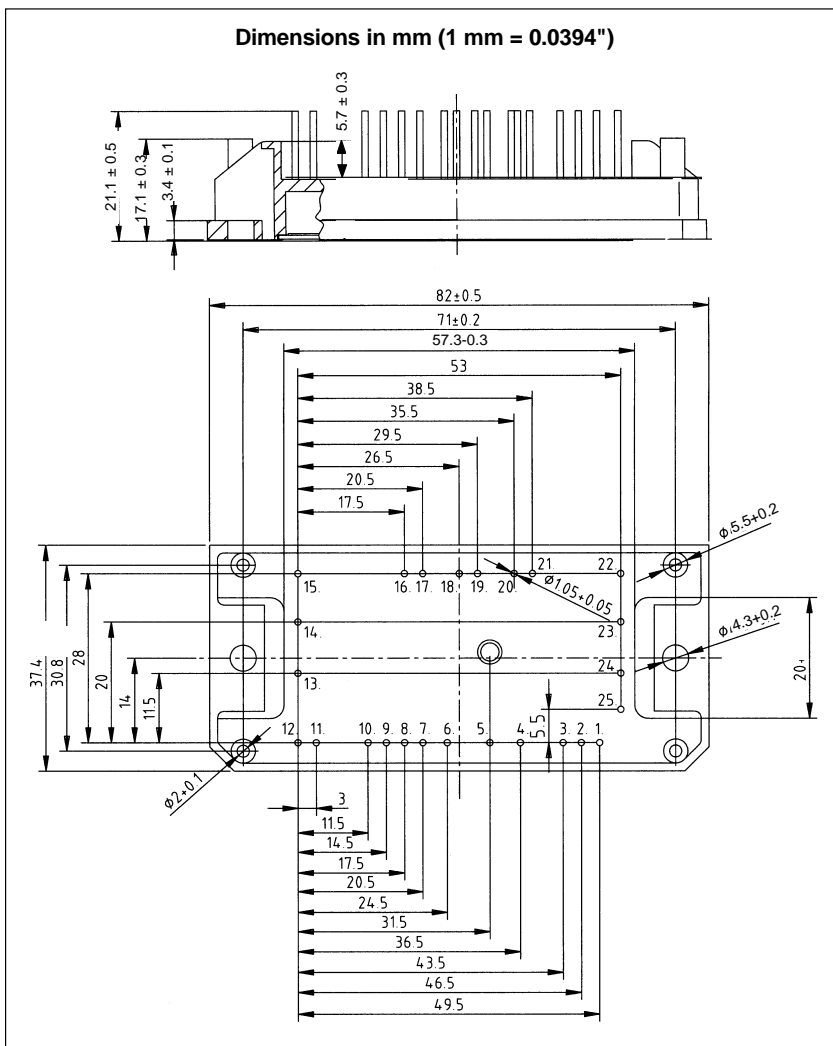
Module

Symbol	Conditions	Maximum Ratings	
T_{stg}		-40...+125	°C
V_{ISOL}	$I_{ISOL} \leq 1 \text{ mA}$; 50/60 Hz; $t = 1 \text{ min}$	2500	V~
M_d	Mounting torque (M4)	2.0 - 2.2 18 - 20	Nm lb.in.
d_s	Creepage distance on surface	12.7	mm
d_A	Strike distance in air	12.7	mm
Weight	typ.	42	g

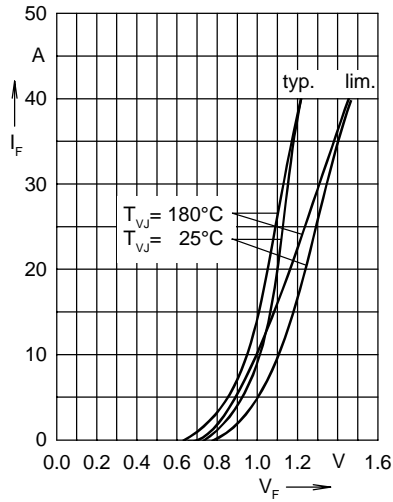
Temperature Sensor R

Symbol	Conditions	Maximum Ratings	
R	$T_{amb} = 20^\circ\text{C}$	4.7	k Ω

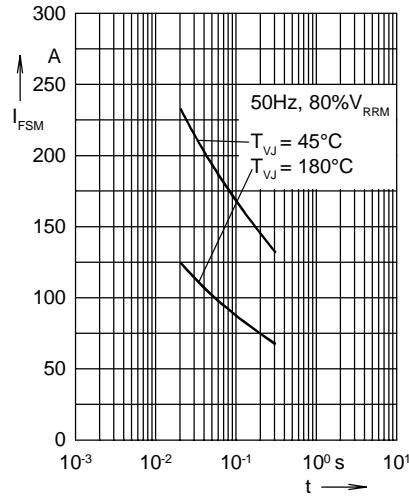
For additional data see C620/4.7k 5% S+M NTC thermistor catalog



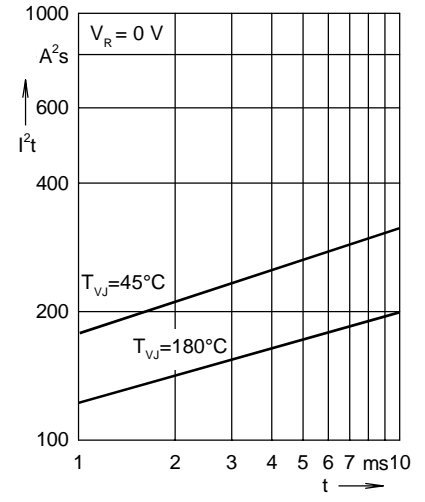
Input Rectifier Bridge D8 - D13



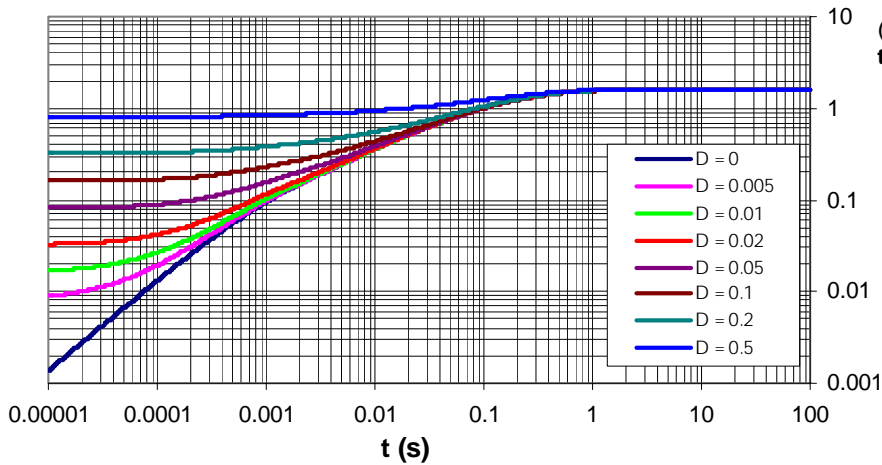
Forward characteristics



Surge overload current
 I_{FSM} : crest value, t: duration



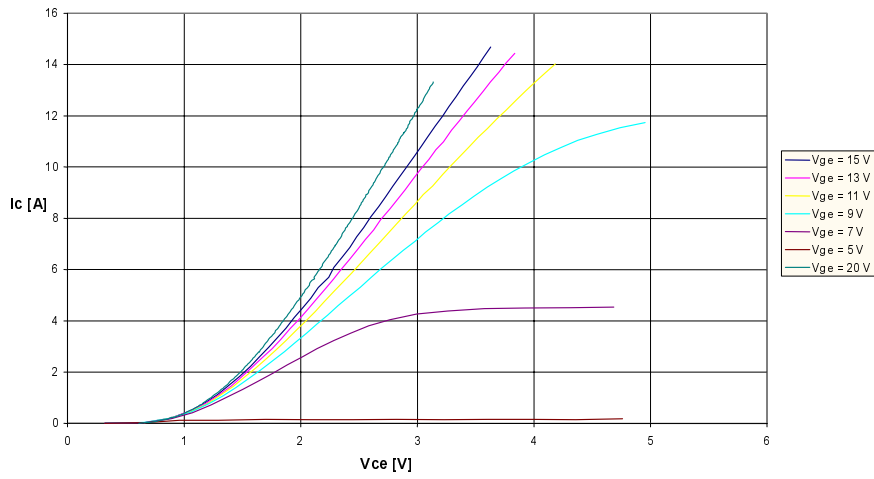
I^2t versus time (1-10 ms)



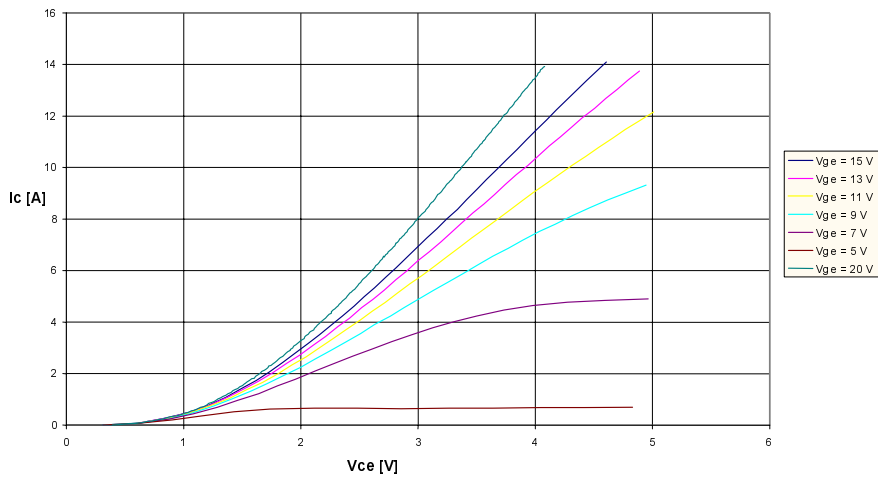
Transient thermal resistance junction to heatsink

Output Inverter T1 - T6, D1 - D6

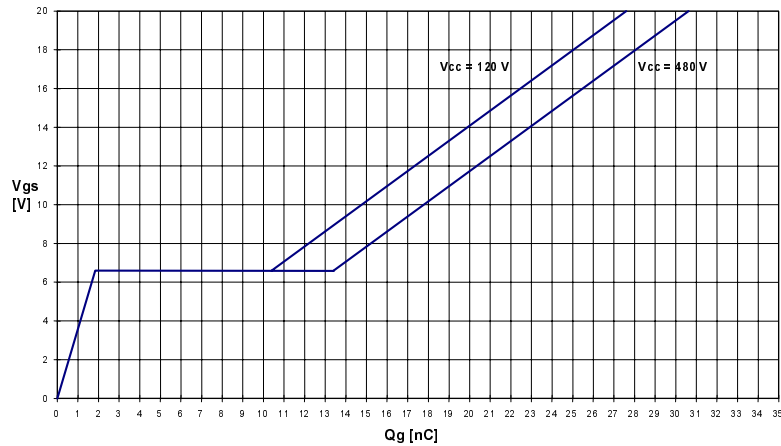
Typ. Output characteristics, 25°C



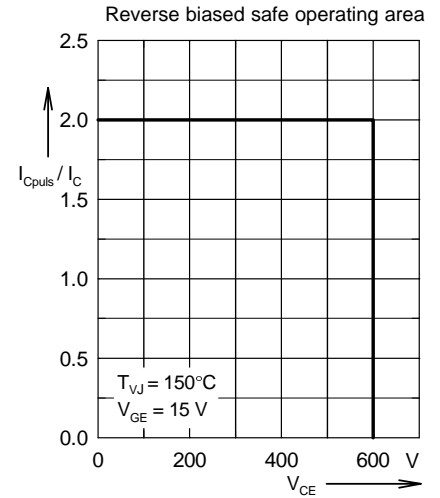
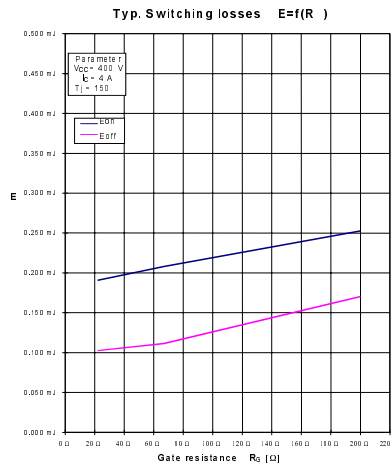
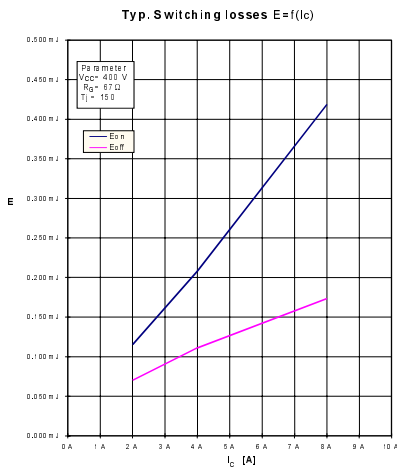
Typ. Output characteristics, 125°C



Typ. Gate-Charge

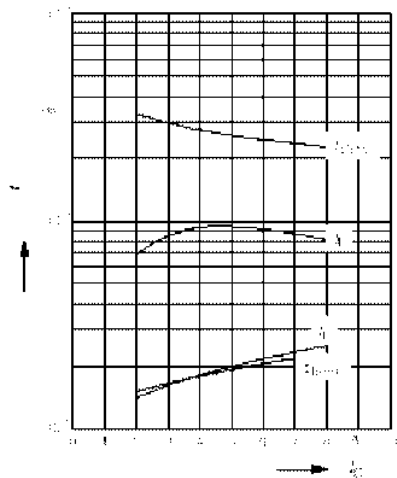


Output Inverter T1 - T6, D1 - D6



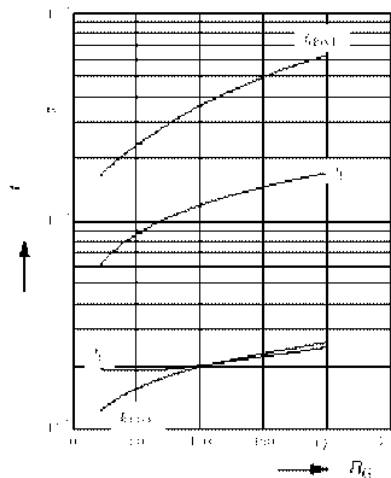
Typ. switching time

$t_{tr}(I_{C1})$ inductive load, $T_J = 150\text{ }^\circ\text{C}$
 par: $V_{GE} = 400\text{ V}$, $V_{GE_L} = 0$, $V_{CE_L} = 15\text{ V}$, $R_G = 67\ \Omega$

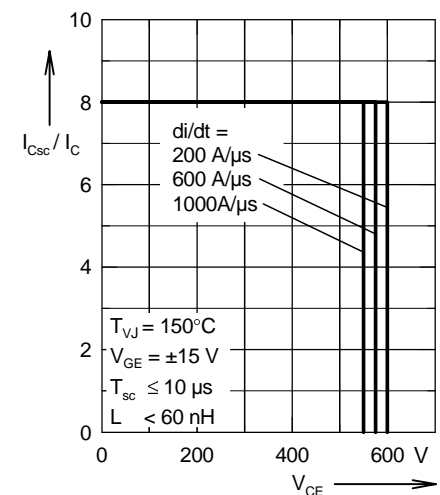


Typ. switching time

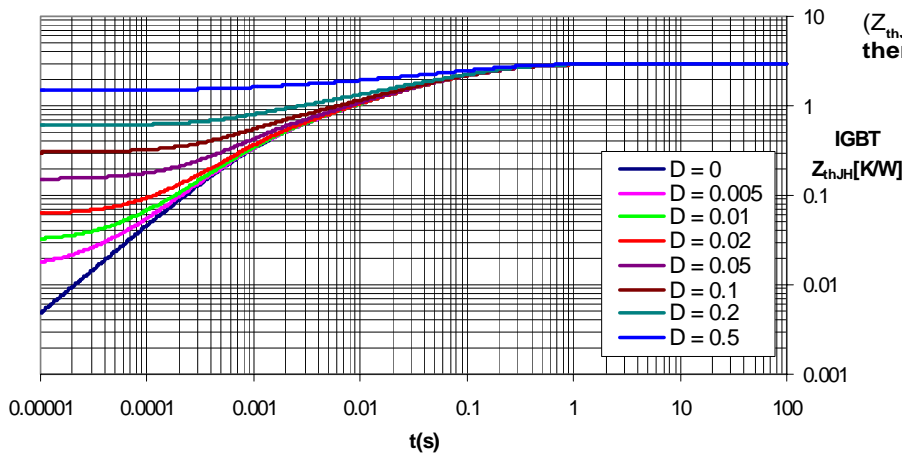
$t_{tr}(I_{C2})$ inductive load, $T_J = 150\text{ }^\circ\text{C}$
 par: $V_{GE} = 400\text{ V}$, $V_{GE_L} = 0$, $V_{CE_L} = 15\text{ V}$, $I_c = 4\text{ A}$



Short circuit safe operating area



Transient thermal resistance junction to heatsink



Output Inverter D1 - D6

