# **AEDA-3200-Txx Series**

# Ultra Miniature, High Resolution Incremental Encoders



# **Data Sheet**



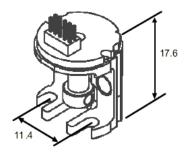
# **Description**

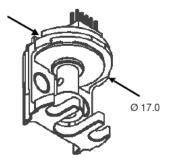
The AEDA-3200-T series (top mounting type) are high performance, cost effective, three-channel optical incremental encoder modules.

AEDA-3200-T series emphasize high reliability, high resolution and easy assembly, using transmissive encoder technology to sense rotary position. Outputs of the AEDA-3200 encoders are two channel quadrature outputs and a third channel gated index output. These encoder modules can be easily mounted to customer specific applications with the specially designed mechanical alignment tool.

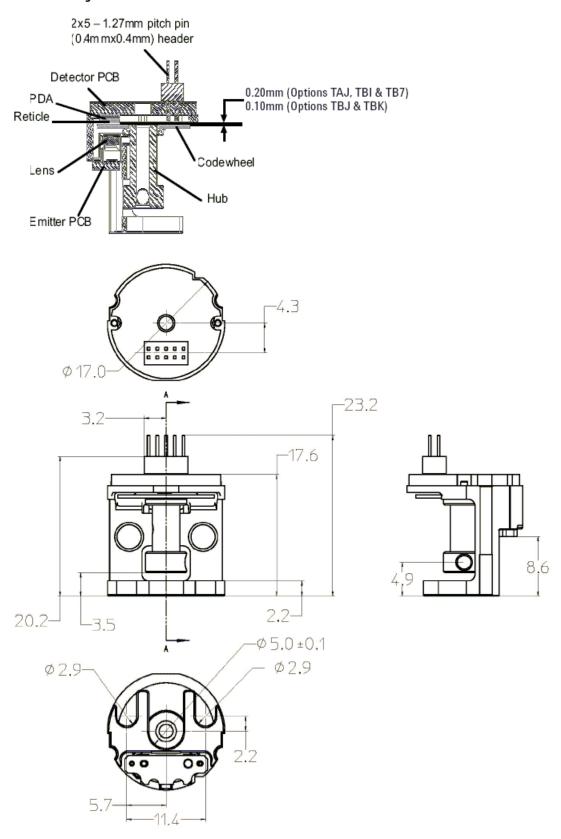
#### **Features**

- · Two channel quadrature output with index
- · Quick and easy assembly with alignment tool
- · Cost-effective
- Ultra miniature size (ø17 mm)
- Resolution options from 2500 to 7500 Cycles Per Revolution (CPR), up to 30000 counts with 4X decodina
- Integrated RS 422 differential line driver





# **Outline Drawing**



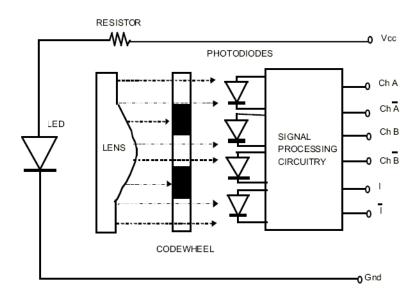
### **Theory of Operation**

The AEDA-3200 translates rotary motion of a shaft into a three channel digital output. The AEDA-3200 series has five key parts: a single light emitting diode (LED) light source, a photodetector IC with a set of uniquely configured photodiodes, an interpolator IC, a line driver IC and a pair of lenses.

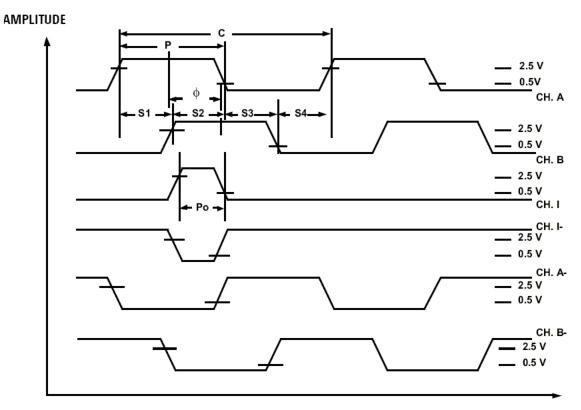
This light is used to produce internal signals A and A<sup>-</sup>, and B and B<sup>-</sup>.

As part of the "push-pull" detector system, these signals are fed through comparators and line driver that are part of the signal processing circuitry to produce the final outputs for channels A.

The AEDA-3200 is available for cycles per revolution (CPR) of 2500 to 7500. This translates to a maximum resolution of 30000 counts after quadrature decode (4X).



## **Output Waveforms**



CODEWHEEL ROTATION (Clockwise)

#### **Definitions**

**Count (N):** N refers to the cycles per revolution (CPR) of the encoder output.

**One Cycle (C):** 360 electrical degrees (°e).

**One Shaft Rotation:** 360 mechanical degrees, N cycles (rotary motion only).

**Phase** ( $\phi$ ): The number of electrical degrees between the center of the high state on the channel A and the center of the high state of channel B. This value is nominally 90°e.

**Pulse Width (P):** The number of the electrical degrees that an output is a high-level during one cycle, nominally 180°e or 1/2 a cycle.

**Pulse Width Error** ( $\Delta$ **P):** The deviation in electrical degrees of the pulse width from its ideal value of 180°e.

**Index Pulse Width (Po):** The number of electrical degrees that an index is high during one full shaft rotation. This value is nominally 90°e or 1/4 cycle.

**State Width (S):** The number of the electrical degrees between a transition in the output of the channel B. There are 4 states per cycle, each nominally 90°e.

**State Width Error** ( $\Delta$ **S):** The deviation in electrical degrees of each state width from its ideal value of 90°e.

#### **Direction of Motor Rotation**

When the codewheel rotates in a clockwise direction, channel A will lead channel B (Figure 1 illustrates the definition of clockwise direction of codewheel rotation). When the codewheel rotates in a counter-clockwise direction, channel B will lead channel A.

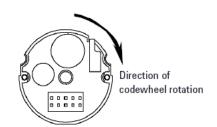


Figure 1. Viewed from the PCB encoder end.

#### **Absolute Maximum Ratings**

Storage Temperature	-40°C to 125°C
Operating Temperature	-40°C to 125°C
Supply Voltage	4.5 V to 5.5 V
Output Voltage	-0.5 V to V <sub>cc</sub>
Output Current per Channel	20 mA
Frequency	750 kHz

#### **Recommended Operating Conditions**

Parameter	Symbol	Min.	Typical	Max.	Units	Notes
Temperature	T <sub>A</sub>	-40	25	125	°C	
Supply Voltage	V <sub>cc</sub>	4.5	5.0	5.5	Volts	Ripple < 100 mVp-p
Frequency	f		125	750	kHz	$f = RPM \times CPR$
						60

### **Maximum Frequency and RPM**

CPR	Maximum Frequency (kHz)	Maximum RPM <sup>2</sup>
2500	750 ¹	12000
5000	750	9000
6000	750	7500
7200	750	6250
7500	750	6000

#### Note:

- 1. Maximum frequency will be lower due to limitation in maximum RPM.
- 2. Maximum mechanical limit is 12000 RPM, operating limit is dependent on the maximum operating frequency.

# **Electrical Characteristics**

Electrical characteristics over recommended operating conditions. Typical values at 25°C.

Parameter	Symbol	Min.	Typical	Max.	Units
Supply Current	I <sub>cc</sub>		55	80	mA
High level Output Voltage	V <sub>OH</sub>	2.5	3.4		V
Low level Output Voltage	V <sub>OL</sub>		0.3	0.5	V

# **Encoding Characteristics**

Encoding characteristics over recommended operating conditions. Typical values at 25°C.

Parameter	Symbol	Typical	Max.	Units
Pulse Width Error	ΔΡ	5	85	°e
State Width Error	ΔS	5	60	°e
Phase Error	Δφ	1	40	°e

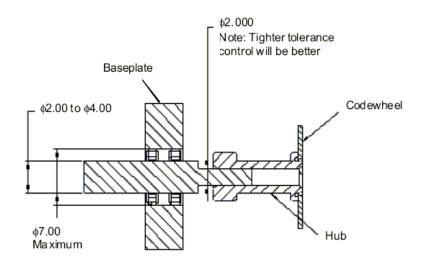
# **Mechanical Characteristics**

(Refer to page 2 for details.)

Parameter	Dimension/Details	Tolerance	Units
Standard Shaft Diameters	2 mm diameter maximum *	002/007 (0001/0003)	mm (in)
Mounting Screw Size:	M2.5 x 0.45 (Recommended Length 6 mm)		mm

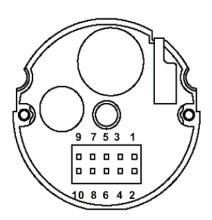
<sup>\*</sup> Note:

<sup>1.</sup> Using a step shaft, maximum shaft diameter is 4 mm.



### **Pin Assignments**

Pin	Signal	Description
Pin 1	A+	Digital Output
Pin 2	A-	Digital Output
Pin 3	Gnd	Ground Pin
Pin 4	Gnd	Ground Pin
Pin 5	B+	Digital Output
Pin 6	B-	Digital Output
Pin 7	Vcc	Input Voltage
Pin 8	Vcc	Input Voltage
Pin 9	l+	Digital Output
Pin 10	-	Digital Output



#### Notes:

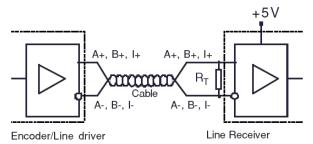
- 1. Both Pin 7 and Pin 8 must be connected to Vcc.
- 2. Either Pin 3 or Pin 4 must be connected to Gnd.

# **Mating Connector**

AEDA-3200 requires a 5 x 2 (1.27 mm x 1.27 mm) female IDC Connector. An example of the suggested mating connectors is Samtec (www.samtec.com) part number: FFSD-05-D-x-01-N. The cable used is 0.635 mm pitch flat ribbon cable.

### **Electrical Interface**

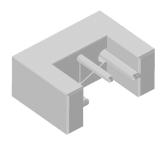
Avago recommends National Semiconductor DS26C32AM Quad Differential Line Receiver or compatible as line receiver. Unused pin should be grounded for noise reduction.



# **Alignment Considerations**

The mechanical alignment tool is intended to absorb normal installation misalignment and runouts. To achieve the optimum performance, user should minimize misalignment.

Complete instructions for AEDA-3200 installation can be found in Application Note 5080, Avago AEDA-3200-T Mechanical Mounting and Installation Consideration. AEDA-3200 Mechanical Alignment tool part number is HEDS-8940.



**HEDS-8940 Mechanical Alignment Tool.** 

# **Ordering Information**

A E D A - 3 2 0 0 - <u>T</u>\_\_\_\_

Resol	ution Options (CPR)	Counts After 4x Decoding
ΑJ	2,500	10,000
B 1	5,000	20,000
B 7	6,000	24,000
BJ	7,200	28,800
BK	7,500	30,000

Alignment Tool	Remark
HEDS-8940	Mechanical Alignment Tool

For product information and a complete list of distributors, please go to our web site: **www.avagotech.com** 

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