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# 1GHz, Low-Power, SOT23, Current-Feedback Amplifiers with Shutdown

### General Description

The MAX4223-MAX4228 current-feedback amplifiers combine ultra-high-speed performance, low distortion, and excellent video specifications with low-power operation. The MAX4223/MAX4224/MAX4226/MAX4228 have a shutdown feature that reduces power-supply current to 350µA and places the outputs into a highimpedance state. These devices operate with dual supplies ranging from ±2.85V to ±5.5V and provide a typical output drive current of 80mA. The MAX4223/ MAX4225/MAX4226 are optimized for a closed-loop gain of +1 (0dB) or more and have a -3dB bandwidth of 1GHz, while the MAX4224/MAX4227/MAX4228 are compensated for a closed-loop gain of +2 (6dB) or more, and have a -3dB bandwidth of 600MHz (1.2GHz gain-bandwidth product).

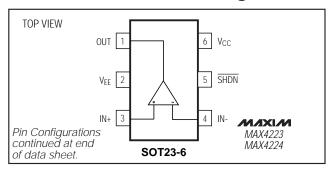
The MAX4223-MAX4228 are ideal for professional video applications, with differential gain and phase errors of 0.01% and 0.02°, 0.1dB gain flatness of 300MHz, and a 1100V/µs slew rate. Total harmonic distortion (THD) of -60dBc (10MHz) and an 8ns settling time to 0.1% suit these devices for driving high-speed analog-to-digital inputs or for data-communications applications. The lowpower shutdown mode on the MAX4223/MAX4224/ MAX4226/MAX4228 makes them suitable for portable and battery-powered applications. Their high output impedance in shutdown mode is excellent for multiplexing applications.

The single MAX4223/MAX4224 are available in spacesaving 6-pin SOT23 packages. All devices are available in the extended -40°C to +85°C temperature range.

## Applications

**ADC Input Buffers Data Communications** Video Cameras Video Line Drivers Video Switches Video Multiplexing Video Editors **XDSL Drivers RF** Receivers Differential Line Drivers

### Pin Configurations



**Features** 

- ♦ Ultra-High Speed and Fast Settling Time: 1GHz -3dB Bandwidth (MAX4223, Gain = +1) 600MHz - 3dB Bandwidth (MAX4224, Gain = +2)1700V/µs Slew Rate (MAX4224) 5ns Settling Time to 0.1% (MAX4224)
- **♦** Excellent Video Specifications (MAX4223): Gain Flatness of 0.1dB to 300MHz 0.01%/0.02° DG/DP Errors
- **♦** Low Distortion:
  - -60dBc THD (f<sub>c</sub> = 10MHz) 42dBm Third-Order Intercept (f = 30MHz)
- ♦ 6.0mA Quiescent Supply Current (per amplifier)
- ♦ Shutdown Mode:
  - 350µA Supply Current (per amplifier) 100k $\Omega$  Output Impedance
- **♦** High Output Drive Capability: **80mA Output Current**

Drives up to 4 Back-Terminated 75 $\Omega$  Loads to ±2.5V while Maintaining Excellent Differential **Gain/Phase Characteristics** 

♦ Available in Tiny 6-Pin SOT23 and 10-Pin µMAX **Packages** 

## Ordering Information

PART	PART TEMP. RANGE		SOT TOP MARK
MAX4223EUT-T	-40°C to +85°C	6 SOT23	AAAD
MAX4223ESA	-40°C to +85°C	8 SO	_

Ordering Information continued at end of data sheet.

### Selector Guide

PART	MIN. GAIN	AMPS PER PKG.	SHUT- DOWN MODE	PIN- PACKAGE
MAX4223	1	1	Yes	6 SOT23, 8 SO
MAX4224	2	1	Yes	6 SOT23, 8 SO
MAX4225	1	2	No	8 SO
MAX4226	1	2	Yes	10 μMAX, 14 SO
MAX4227	2	2	No	8 SO
MAX4228	2	2	Yes	10 μMAX, 14 SO

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#### **ABSOLUTE MAXIMUM RATINGS**

Supply Voltage (V <sub>CC</sub> to V <sub>EE</sub> )	12V
Analog Input Voltage	(VEE - 0.3V) to (VCC + 0.3V)
Analog Input Current	±25mA
SHDN Input Voltage	
Short-Circuit Duration	
OUT to GND	Continuous
OUT to V <sub>CC</sub> or V <sub>EE</sub>	5sec

Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
6-Pin SOT23 (derate 7.1mW/°C above +70°C)571mW
8-Pin SO (derate 5.9mW/°C above +70°C)471mW
10-Pin μMAX (derate 5.6mW/°C above +70°C)444mW
14-Pin SO (derate 8.3mW/°C above +70°C)667mW
Operating Temperature Range40°C to +85°C
Storage Temperature Range65°C to +150°C
Lead Temperature (soldering, 10sec)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### DC ELECTRICAL CHARACTERISTICS

(V<sub>CC</sub> = +5V, V<sub>EE</sub> = -5V,  $\overline{SHDN}$  = 5V, V<sub>CM</sub> = 0V, R<sub>L</sub> =  $\propto$  T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.) (Note 1)

PARAMETER	SYMBOL	CONI	DITIONS	MIN	TYP	MAX	UNITS	
		T25°C	MAX4223/MAX4224		±0.5	±4		
Innut Offeet Veltage	\/	T <sub>A</sub> = +25°C	MAX4225-MAX4228		±0.5	±5	ma\/	
Input Offset Voltage	Vos		MAX4223/MAX4224			±6	mV	
		TA = TMIN to TMAX	MAX4225-MAX4228			±7		
Input Offset Voltage Drift	TCVos				±2		μV/°C	
Input Bias Current	I <sub>B+</sub>	T <sub>A</sub> = +25°C			±2	±10	μА	
(Positive Input)	I IB+	$T_A = T_{MIN}$ to $T_{MAX}$				±15	μΑ	
		T <sub>A</sub> = +25°C	MAX4223/MAX4224		±4	±20		
Input Bias Current	I <sub>B-</sub>	1A - +23 C	MAX4225-MAX4228		±4	±25	μA	
(Negative Input)	IB-	TA = TMIN to TMAX	MAX4223/MAX4224			±30	μΑ	
		TA - TMIN TO TMAX	MAX4225-MAX4228			±35		
Input Resistance (Positive Input)	R <sub>IN+</sub>				700		kΩ	
Input Resistance (Negative Input)	R <sub>IN</sub> -				45		Ω	
Input Common-Mode Voltage Range	Vсм	Inferred from CMRR to	est	±2.5	±3.2		V	
Cammon Mada Daigatian Datia	CMRR	V 2 FV	T <sub>A</sub> = +25°C	55	61		dB	
Common-Mode Rejection Ratio	CIVIRR	$V_{CM} = \pm 2.5V$	TA = TMIN to TMAX	50				
Operating Supply Voltage Range	VCC/VEE	Inferred from PSRR te	st	±2.85		±5.5	V	
Dawar Cupply Dalaction Datio	DCDD	$V_{CC} = 2.85V \text{ to } 5.5V,$	T <sub>A</sub> = +25°C	68	74		-10	
Power-Supply Rejection Ratio	PSRR	$V_{EE} = -2.85V \text{ to } -5.5V$	TA = TMIN to TMAX	63			– dB	
Quiescent Supply Current	Isy	Normal mode (SHDN	= 5V)		6.0	9.0	mA	
(per Amplifier)	ISY	Shutdown mode (SHE	$\overline{ON} = OV)$		0.35	0.55	IIIA	
Open-Loop Transresistance	T <sub>R</sub>	V <sub>OUT</sub> = ±2.5V	R <sub>L</sub> = ∞	0.7	1.5		MO	
Open-Loop Transfesistance	I IR	VOUT = ±2.5V	$R_L = 50\Omega$	0.3	0.8		- MΩ	
Output Voltage Swing	Vout	$R_L = 50\Omega$		±2.5	±2.8		V	
Output Current (Note 2)	lout	$V_{OUT} = \pm 2.5V$		60	80		mA	
Short-Circuit Output Current	I <sub>SC</sub>	R <sub>L</sub> = short to ground			140		mA	
SHDN Logic Low	VIL					0.8	V	
SHDN Logic High	VIH			2.0			V	

### DC ELECTRICAL CHARACTERISTICS (continued)

 $(V_{CC} = +5V, V_{EE} = -5V, \overline{SHDN} = 5V, V_{CM} = 0V, R_L = T_{MIN} to T_{MAX}, unless otherwise noted. Typical values are at T_A = +25°C.) (Note 1)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SHDN Input Current	liL/liH	SHDN = 0V or 5V		25	70	μA
Shutdown Mode Output Impedance		SHDN = 0V, V <sub>OUT</sub> = -2.5V to +2.5V (Note 3)	10	100		kΩ

#### **AC ELECTRICAL CHARACTERISTICS**

 $(V_{CC}=+5V,V_{EE}=-5V,\overline{SHDN}=5V,V_{CM}=0V,A_V=+1V/V \text{ for MAX4223/MAX4225/MAX4226, } A_V=+2V/V \text{ for MAX4224/MAX4227/MAX4228, } R_L=100\Omega$ ,  $T_A=+25^{\circ}C$ , unless otherwise noted.) (Note 4)

PARAMETER	SYMBOL		CONDITIONS		MIN	TYP	MAX	UNITS												
-3dB Small-Signal Bandwidth	DW	\/ 20m\/m		MAX4223/5/6	750	1000		NAL I-												
(Note 5)	BW	$V_{OUT} = 20 \text{mVp-}_{I}$	)	MAX4224/7/8	325	600		- MHz												
Bandwidth for ±0.1dB	DWs . Is	\/a.i= 20m\/n.i		MAX4223/5/6	100	300		MHz												
Gain Flatness (Note 5)	BW <sub>0.1dB</sub>	$V_{OUT} = 20 \text{mVp-}_{I}$	J	MAX4224/7/8	60	200		IVITZ												
Gain Peaking		MAX4223/5/6				1.5		dB												
Gairreaking		MAX4224/7/8				0.1		ub												
Large-Signal Bandwidth	BWLS	V <sub>OUT</sub> = 2Vp-p		MAX4223/5/6		250		MHz												
Large-Signal Bandwidth	DWLS	v001 = 5vb-b		MAX4224/7/8		330		IVITZ												
			Rising edge	MAX4223/5/6	850	1100														
Slow Data (Note E)	SR	Vout = 4V step	Rising eage	MAX4224/7/8	1400	1700		Muc												
Slew Rate (Note 5)	SK	VOUT = 4V Step	Folling odgo	MAX4223/5/6	625	800		V/µs												
			Falling edge		1100	1400														
Settling Time to 0.1%	ts	Vour = 2V step		MAX4223/5/6		8		ns												
Settling Time to 0.1%	ıs	VOUT = 2V Step		MAX4224/7/8		5		115												
Rise and Fall Time	t tc	)/ = t===		MAX4223/5/6		1.5		nc												
Rise and Fall Time	t <sub>r</sub> , t <sub>f</sub>	VOUT = 2V Step	V <sub>OUT</sub> = 2V step MAX			1.0		ns												
Off Isolation		SHDN = 0V, f =	10MHz, MAX42	23/4/6/8		65		dB												
Crosstalk	V	f = 30MHz,		MAX4225/6		-68		- dB												
Clossidik	XTALK	$R_S = 50\Omega$		MAX4227/8		-72		aB												
Turn-On Time from Shutdown	ton	MAX4223/4/6/8				2		μs												
Turn-Off Time to Shutdown	toff	MAX4223/4/6/8				300		ns												
Power-Up Time	tup	V <sub>CC</sub> , V <sub>EE</sub> = 0V to	±5V step			100		ns												
Differential Gain Error	DG	$R_{\rm I} = 150\Omega$ (Note	. 4)	MAX4223/5/6		0.01		%												
Differential Gain Entit	DG	KL = 13022 (NOTE	: 0)	MAX4224/7/8		0.02		%												
Differential Phase Error	DP	D. 1500 (Note	. 4)	MAX4223/5/6		0.02		dograca												
Differential Friase Effor	Error DP $R_L = 150\Omega$ (Note 6)		: 0)	MAX4224/7/8		0.01		degrees												
			$R_L = 100\Omega$	MAX4223/5/6		-60														
Total Harmonic Distortion	THD	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$					$V_{OUT} = 2V_{p-p},$ $f_{C} = 10MHz$	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$	$V_{OUT} = 2V_{p-p},$ $f_{C} = 10MHz$	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$	$V_{OUT} = 2Vp-p,$ $f_{C} = 10MHz$	11 - 10022	MAX4224/7/8		-61		dBc
Total Halffloriic Distortion	טווו														fc = 10MHz	fc = 10MHz	Di = 1k0	MAX4223/5/6		-65
		$R_L = 1k\Omega$		MAX4224/7/8		-78														



### **AC ELECTRICAL CHARACTERISTICS (continued)**

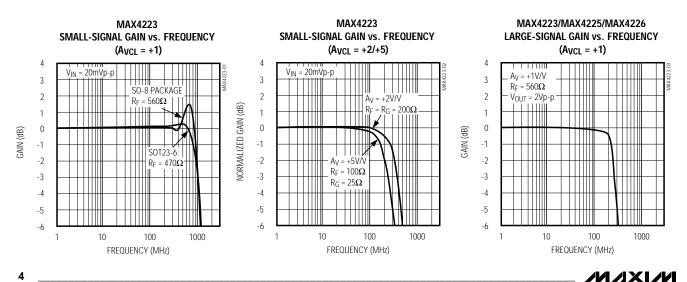
 $(V_{CC} = +5V, V_{EE} = -5V, \overline{SHDN} = 5V, V_{CM} = 0V, A_V = +1V/V \text{ for MAX4223/MAX4225/MAX4226, } A_V = +2V/V \text{ for MAX4224/MAX4227/MAX4228, } R_L = 100\Omega$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.) (Note 4)

PARAMETER	SYMBOL	CONDITIO	CONDITIONS		TYP	MAX	UNITS	
Output Impedance	Z <sub>OUT</sub>	f = 10kHz			2		Ω	
Third-Order Intercept	IP3	f = 30kHz	MAX4223/5/6		42		dBm	
mild-Order intercept	IP3	$f_Z = 30.1MHz$	MAX4224/7/8		36		UDIII	
Spurious Frag Dynamic Dange	SEDR	f = 10kHz	MAX4223/5/6		-61		4D	
Spurious-Free Dynamic Range	SFUR	I = IUKMZ	MAX4224/7/8		-62		- dB	
1dB Gain Compression		f = 10kHz	•		20		dBm	
Input Noise Voltage Density	en	f = 10kHz			2		nV/√Hz	
Input Noise Current Density	1	f = 10kHz	IN+		3		pA/√Hz	
input Noise Current Density	i <sub>n+</sub> , i <sub>n</sub> -	I = IUKMZ	IN-		20		PA/VHZ	
		SO-8, SO-14	Pin to pin		0.3		pF	
Input Capacitance (Note 7)	CINI	packages	Pin to GND		1.0			
	CIN	SOT23-6, 10-pin µMAX	Pin to pin		0.3			
		packages	Pin to GND		0.8		1	

- Note 1: The MAX422\_EUT is 100% production tested at T<sub>A</sub> = +25°C. Specifications over temperature limits are guaranteed by design.
- Note 2: Absolute Maximum Power Dissipation must be observed.
- Note 3: Does not include impedance of external feedback resistor network.
- **Note 4:** AC specifications shown are with optimal values of R<sub>F</sub> and R<sub>G</sub>. These values vary for product and package type, and are tabulated in the *Applications Information* section of this data sheet.
- **Note 5:** The AC specifications shown are not measured in a production test environment. The minimum AC specifications given are based on the combination of worst-case design simulations along with a sample characterization of units. These minimum specifications are for design guidance only and are not intended to guarantee AC performance (see *AC Testing/Performance*). For 100% testing of these parameters, contact the factory.
- Note 6: Input Test Signal: 3.58MHz sine wave of amplitude 40IRE superimposed on a linear ramp (0IRE to 100IRE). IRE is a unit of video signal amplitude developed by the International Radio Engineers. 140IRE = 1V.
- Note 7: Assumes printed circuit board layout similar to that of Maxim's evaluation kit.

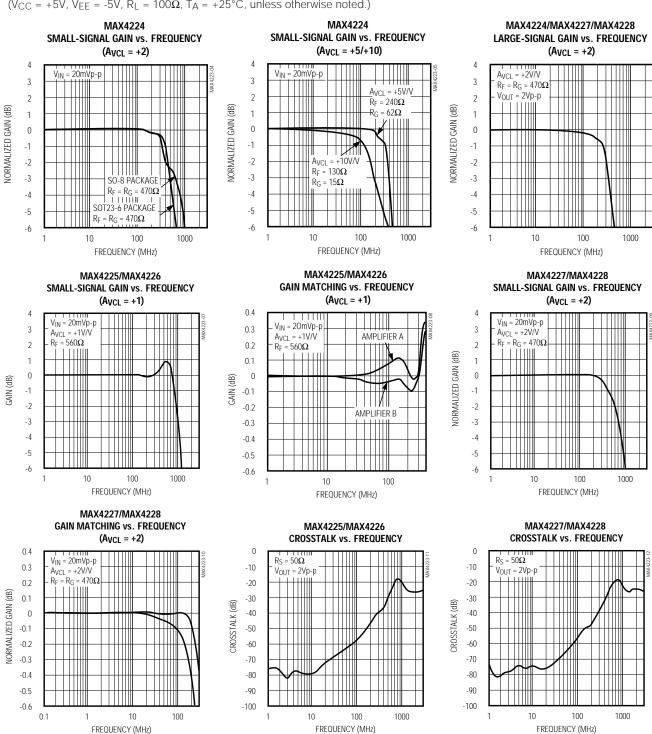
## \_Typical Operating Characteristics

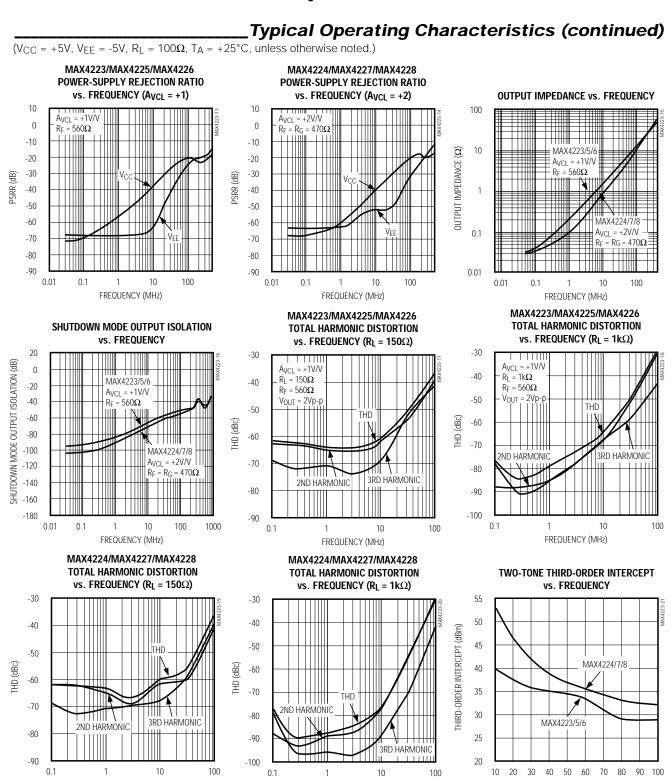
(V<sub>CC</sub> = +5V, V<sub>EE</sub> = -5V, R<sub>L</sub> =  $100\Omega$ , T<sub>A</sub> =  $+25^{\circ}$ C, unless otherwise noted.)



## Typical Operating Characteristics (continued)

 $(V_{CC} = +5V, V_{FF} = -5V, R_{I} = 100\Omega, T_{A} = +25^{\circ}C, \text{ unless otherwise noted.})$ 





FREQUENCY (MHz)

FREQUENCY (MHz)

MIXIM

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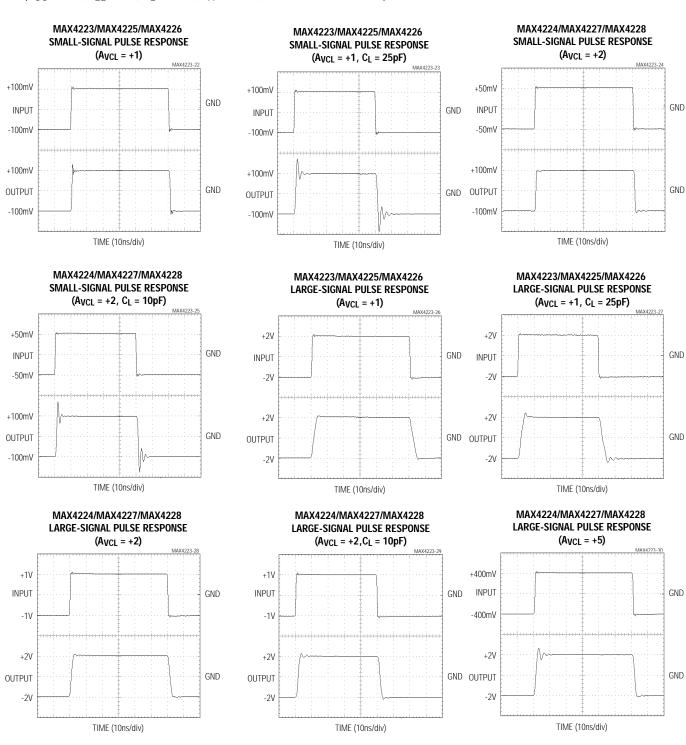
FREQUENCY (MHz)

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# 1GHz, Low-Power, SOT23, Current-Feedback Amplifiers with Shutdown

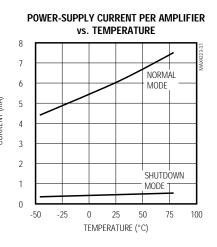
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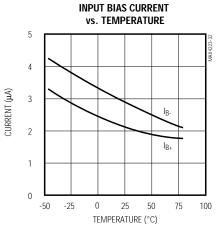
 $(V_{CC} = +5V, V_{FF} = -5V, R_1 = 100\Omega, T_A = +25^{\circ}C, \text{ unless otherwise noted.})$ 

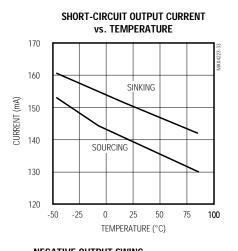


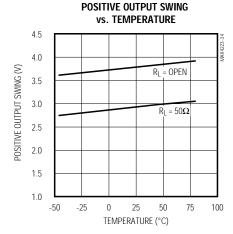
## \_Typical Operating Characteristics (continued)

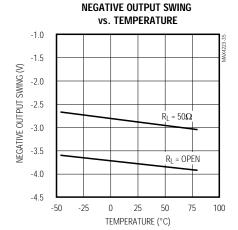
(V<sub>CC</sub> = +5V, V<sub>EE</sub> = -5V, R<sub>L</sub> =  $100\Omega$ , T<sub>A</sub> =  $+25^{\circ}$ C, unless otherwise noted.)











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Pin Description

		PIN				
MAX4223	/MAX4224	MAX4225 MAX4227	MAX422	6/MAX4228	NAME	FUNCTION
SOT23	so	so	μΜΑΧ	so	]	
	1,5	_	_	5, 7, 8, 10	N.C.	No Connect. Not internally connected. Tie to GND for optimum AC performance.
1	6	_	_	_	OUT	Amplifier Output
2	4	4	4	4	VEE	Negative Power-Supply Voltage. Connect to -5V.
3	3	_	_	_	IN+	Amplifier Noninverting Input
4	2	_	_	_	IN-	Amplifier Inverting Input
5	8	_	_	_	SHDN	Amplifier Shutdown. Connect to +5V for normal operation. Connect to GND for low-power shutdown.
6	7	8	10	14	V <sub>C</sub> C	Positive Power-Supply Voltage. Connect to +5V.
_	_	1	1	1	OUTA	Amplifier A Output
_	_	2	2	2	INA-	Amplifier A Inverting Input
_	_	3	3	3	INA+	Amplifier A Noninverting Input
_	_	5	7	11	INB+	Amplifier B Noninverting Input
_	_	6	8	12	INB-	Amplifier B Inverting Input
_	_	7	9	13	OUTB	Amplifier B Output
_	_	_	5	6	SHDNA	Amplifier A Shutdown Input. Connect to +5V for normal operation. Connect to GND for low-power shutdown mode.
_	_	_	6	9	SHDNB	Amplifier B Shutdown Input. Connect to +5V for normal operation. Connect to GND for low-power shutdown mode.

### Detailed Description

The MAX4223–MAX4228 are ultra-high-speed, low-power, current-feedback amplifiers featuring -3dB bandwidths up to 1GHz, 0.1dB gain flatness up to 300MHz, and very low differential gain and phase errors of 0.01% and 0.02°, respectively. These devices operate on dual ±5V or ±3V power supplies and require only 6mA of supply current per amplifier. The MAX4223/MAX4225/MAX4226 are optimized for closed-loop gains of +1 (0dB) or more and have -3dB bandwidths of 1GHz. The MAX4224/MAX4227/MAX4228 are optimized for closed-loop gains of +2 (6dB) or more, and have -3dB bandwidths of 600MHz (1.2GHz gain-bandwidth product).

The current-mode feedback topology of these amplifiers allows them to achieve slew rates of up to 1700V/ $\mu$ s with corresponding large signal bandwidths up to 330MHz. Each device in this family has an output that is capable of driving a minimum of 60mA of output current to  $\pm 2.5$ V.

#### **Theory of Operation**

Since the MAX4223–MAX4228 are current-feedback amplifiers, their open-loop transfer function is expressed as a transimpedance:

$$\frac{\Delta V_{OUT}}{\Delta I_{IN-}}$$
 or  $T_Z$ 

The frequency behavior of this open-loop transimpedance is similar to the open-loop gain of a voltage-feedback amplifier. That is, it has a large DC value and decreases at approximately 6dB per octave.

Analyzing the current-feedback amplifier in a gain configuration (Figure 1) yields the following transfer function:

$$\frac{V_{OUT}}{V_{IN}} = G \times \frac{T_Z(S)}{T_Z(S) + G \times R_{IN-} + R_F}$$
 where G = A<sub>V</sub> = 1 +  $\frac{R_F}{R_G}$ .

At low gains, (G x R<sub>IN-</sub>) << R<sub>F</sub> . Therefore, unlike traditional voltage-feedback amplifiers, the closed-loop bandwidth is essentially independent of the closed-loop gain. Note also that at low frequencies, T<sub>Z</sub> >> [(G x R<sub>IN-</sub>) + R<sub>F</sub>], so that:

$$\frac{V_{OUT}}{V_{IN}} = G = 1 + \frac{R_F}{R_G}$$

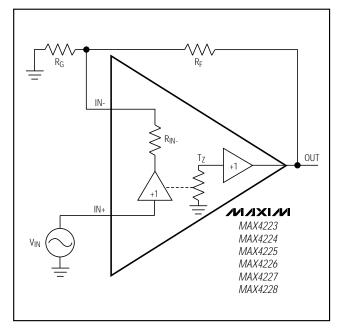


Figure 1. Current-Feedback Amplifier

#### Low-Power Shutdown Mode

The MAX4223/MAX4224/MAX4226/MAX4228 have a shutdown mode that is activated by driving the SHDN input low. When powered from ±5V supplies, the SHDN input is compatible with TTL logic. Placing the amplifier in shutdown mode reduces quiescent supply current to 350µA typical, and puts the amplifier output into a highimpedance state (100k $\Omega$  typical). This feature allows these devices to be used as multiplexers in wideband systems. To implement the mux function, the outputs of multiple amplifiers can be tied together, and only the amplifier with the selected input will be enabled. All of the other amplifiers will be placed in the low-power shutdown mode, with their high output impedance presenting very little load to the active amplifier output. For gains of +2 or greater, the feedback network impedance of all the amplifiers used in a mux application must be considered when calculating the total load on the active amplifier output.

## \_Applications Information

#### Layout and Power-Supply Bypassing

The MAX4223–MAX4228 have an extremely high bandwidth, and consequently require careful board layout, including the possible use of constant-impedance microstrip or stripline techniques.

To realize the full AC performance of these high-speed amplifiers, pay careful attention to power-supply bypassing and board layout. The PC board should have at least two layers: a signal and power layer on one side and a large, low-impedance ground plane on the other. The ground plane should be as free of voids as possible, with one exception: the inverting input pin (IN-) should have as low a capacitance to ground as possible. This means that there should be no ground plane under IN- or under the components (RF and RG) connected to it. With multilayer boards, locate the ground plane on a layer that incorporates no signal or power traces.

Whether or not a constant-impedance board is used, it is best to observe the following guidelines when designing the board:

- Do not use wire-wrapped boards (they are too inductive) or breadboards (they are too capacitive).
- Do not use IC sockets. IC sockets increase reactance.
- 3) Keep signal lines as short and straight as possible. Do not make 90° turns; round all corners.
- Observe high-frequency bypassing techniques to maintain the amplifier's accuracy and stability.
- In general, surface-mount components have shorter bodies and lower parasitic reactance, giving better high-frequency performance than through-hole components.

The bypass capacitors should include a 10nF ceramic, surface-mount capacitor between each supply pin and the ground plane, located as close to the package as possible. Optionally, place a 10µF tantalum capacitor at the power-supply pins' point of entry to the PC board to ensure the integrity of incoming supplies. The power-supply trace should lead directly from the tantalum capacitor to the  $V_{CC}$  and  $V_{EE}$  pins. To minimize parasitic inductance, keep PC traces short and use surface-mount components. The N.C. pins should be connected to a common ground plane on the PC board to minimize parasitic coupling.

If input termination resistors and output back-termination resistors are used, they should be surface-mount types, and should be placed as close to the IC pins as possible. Tie all N.C. pins to the ground plane to minimize parasitic coupling.

#### Choosing Feedback and Gain Resistors

As with all current-feedback amplifiers, the frequency response of these devices depends critically on the value of the feedback resistor R<sub>F</sub>. R<sub>F</sub> combines with an internal compensation capacitor to form the dominant pole in the feedback loop. Reducing R<sub>F</sub>'s value increases the pole frequency and the -3dB bandwidth, but also increases peaking due to interaction with other nondominant poles. Increasing R<sub>F</sub>'s value reduces peaking and bandwidth.

Table 1 shows optimal values for the feedback resistor (R<sub>F</sub>) and gain-setting resistor (R<sub>G</sub>) for the MAX4223–MAX4228. Note that the MAX4224/MAX4227/MAX4228 offer superior AC performance for all gains except unity gain (0dB). These values provide optimal AC response using surface-mount resistors and good layout techniques. Maxim's high-speed amplifier evaluation kits provide practical examples of such layout techniques.

Stray capacitance at IN- causes feedback resistor decoupling and produces peaking in the frequency-response curve. Keep the capacitance at IN- as low as possible by using surface-mount resistors and by avoiding the use of a ground plane beneath or beside these resistors and the IN- pin. Some capacitance is unavoidable; if necessary, its effects can be counteracted by adjusting R<sub>F</sub>. Use 1% resistors to maintain consistency over a wide range of production lots.

Table 1. Optimal Feedback Resistor Networks

GAIN (V/V)	GAIN (dB)	R <sub>F</sub> (Ω)	R <sub>G</sub> (Ω)	-3dB BW (MHz)	0.1dB BW (MHz)		
MAX4223/MAX4225/MAX4226							
1	0	560*	Open	1000	300		
2	6	200	200	380	115		
5	14	100	25	235	65		
MAX422	24/MAX422	7/MAX422	28				
2	6	470	470	600	200		
5	14	240	62	400	90		
10	20	130	15	195	35		

<sup>\*</sup>For the MAX4223EUT, this optimal value is  $470\Omega$ .

#### DC and Noise Errors

The MAX4223–MAX4228 output offset voltage, Vout (Figure 2), can be calculated with the following equation:

$$V_{OUT} = V_{OS} x \left(1 + R_F/R_G\right) + I_{B+} x R_S$$
$$x \left(1 + \frac{R_F}{R_G}\right) + I_{B-} x R_F$$

where:

Vos = input offset voltage (in volts)

1 + R<sub>F</sub> / R<sub>G</sub> = amplifier closed-loop gain (dimensionless)

IB+ = input bias current (in amps)

IB- = inverting input bias current (in amps)

 $R_G$  = gain-setting resistor (in  $\Omega$ )

 $R_F$  = feedback resistor (in  $\Omega$ )

 $R_S = source resistor (in \Omega)$ 

The following equation represents output noise density:

$$e_{n(OUT)} = \left(1 + \frac{R_F}{R_G}\right) x$$

$$\sqrt{(i_{n+} \times R_S)^2 + [i_{n-} \times (R_F || R_G)]^2 + (e_n)^2}$$

where:

 $i_n$  = input noise current density (in pA/ $\sqrt{Hz}$ )

 $e_n$  = input noise voltage density (in  $nV/\sqrt{Hz}$ )

The MAX4223–MAX4228 have a very low,  $2nV/\sqrt{Hz}$  noise voltage. The current noise at the noninverting input (i<sub>n+</sub>) is  $3pA/\sqrt{Hz}$ , and the current noise at the inverting input (i<sub>n-</sub>) is  $20pA/\sqrt{Hz}$ .

An example of DC-error calculations, using the MAX4224 typical data and the typical operating circuit with RF = RG = 470 $\Omega$  (RF || RG = 235 $\Omega$ ) and RS = 50 $\Omega$ , gives:

$$V_{OUT} = [5 \times 10^{-4} \times (1 + 1)] + [2 \times 10^{-6} \times 50 \times (1 + 1)] + [4 \times 10^{-6} \times 470]$$

 $V_{OUT} = 3.1 \text{mV}$ 

Calculating total output noise in a similar manner yields the following:

$$e_{n(OUT)} = (1 + 1) \times \left[ (3 \times 10^{-12}) \times 50 \right]^{2} + \left[ (20 \times 10^{-12}) \times 235 \right]^{2} + (2 \times 10^{-9})^{2}$$

$$e_{n(OUT)} = 10.2 \text{nV} / \sqrt{\text{Hz}}$$

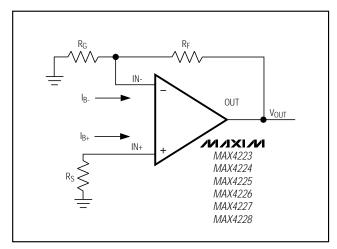


Figure 2. Output Offset Voltage

With a 600MHz system bandwidth, this calculates to  $250\mu V_{RMS}$  (approximately 1.5mVp-p, using the six-sigma calculation).

#### **Communication Systems**

Nonlinearities of components used in a communication system produce distortion of the desired output signal. Intermodulation distortion (IMD) is the distortion that results from the mixing of two input signals of different frequencies in a nonlinear system. In addition to the input signal frequencies, the resulting output signal contains new frequency components that represent the sum and difference products of the two input frequencies. If the two input signals are relatively close in frequency, the third-order sum and difference products will fall close to the frequency of the desired output and will therefore be very difficult to filter. The third-order intercept (IP3) is defined as the power level at which the amplitude of the largest third-order product is equal to the power level of the desired output signal. Higher third-order intercept points correspond to better linearity of the amplifier. The MAX4223-MAX4228 have a typical IP3 value of 42dBm, making them excellent choices for use in communications systems.

#### **ADC Input Buffers**

Input buffer amplifiers can be a source of significant errors in high-speed ADC applications. The input buffer is usually required to rapidly charge and discharge the ADC's input, which is often capacitive (see the section *Driving Capacitive Loads*). In addition, a high-speed ADC's input impedance often changes very rapidly during the conversion cycle, requiring an amplifier with

very low output impedance at high frequencies to maintain measurement accuracy. The combination of high speed, fast slew rate, low noise, and low distortion makes the MAX4223–MAX4228 ideally suited for use as buffer amplifiers in high-speed ADC applications.

#### **Video Line Driver**

The MAX4223–MAX4228 are optimized to drive coaxial transmission lines when the cable is terminated at both ends, as shown in Figure 3. Note that cable frequency response may cause variations in the signal's flatness.

#### **Driving Capacitive Loads**

A correctly terminated transmission line is purely resistive and presents no capacitive load to the amplifier. Although the MAX4223–MAX4228 are optimized for AC performance and are not designed to drive highly capacitive loads, they are capable of driving up to 25pF without excessive ringing. Reactive loads decrease phase margin and may produce excessive ringing and oscillation (see *Typical Operating Characteristics*). Figure 4's circuit reduces the effect of large capacitive loads. The small (usually  $5\Omega$  to  $20\Omega$ ) isolation resistor R<sub>ISO</sub>, placed before the reactive load, prevents ringing and oscillation at the expense of a

small gain error. At higher capacitive loads, AC performance is limited by the interaction of load capacitance with the isolation resistor.

#### Maxim's High-Speed Evaluation Board Layout

Figures 7 and 8 show a suggested layout for Maxim's high-speed, single-amplifier evaluation boards. These boards were developed using the techniques described above. The smallest available surface-mount resistors were used for the feedback and back-termination resistors to minimize the distance from the IC to these resistors, thus reducing the capacitance associated with longer lead lengths.

SMA connectors were used for best high-frequency performance. Because distances are extremely short, performance is unaffected by the fact that inputs and outputs do not match a  $50\Omega$  line. However, in applications that require lead lengths greater than 1/4 of the wavelength of the highest frequency of interest, constant-impedance traces should be used.

Fully assembled evaluation boards are available for the MAX4223 in an SO-8 package.

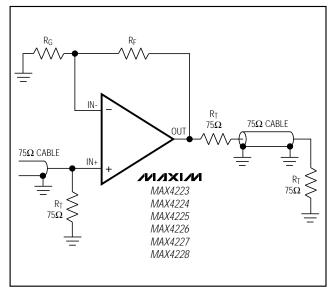


Figure 3. Video Line Driver

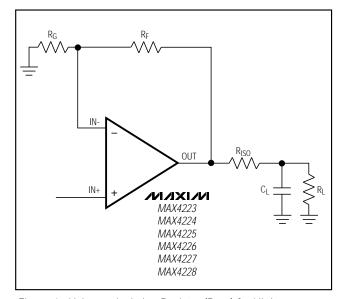


Figure 4. Using an Isolation Resistor (R<sub>ISO</sub>) for High Capacitive Loads

### AC Testing/Performance

AC specifications on high-speed amplifiers are usually guaranteed without 100% production testing. Since these high-speed devices are sensitive to external parasitics introduced when automatic handling equipment is used, it is impractical to guarantee AC parameters through volume production testing. These parasitics are greatly reduced when using the recommended PC board layout (like the Maxim evaluation kit). Characterizing the part in this way more accurately represents the amplifier's true AC performance. Some

manufacturers guarantee AC specifications without clearly stating how this guarantee is made. The MAX4223–MAX4228 AC specifications are derived from worst-case design simulations combined with a sample characterization of 100 units. The AC performance distributions along with the worst-case simulation limits are shown in Figures 5 and 6. These distributions are repeatable provided that proper board layout and power-supply bypassing are used (see *Layout and Power-Supply Bypassing* section).

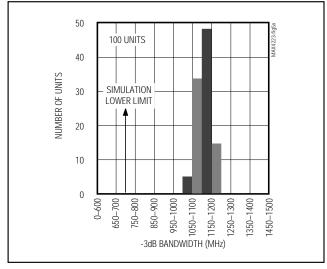


Figure 5a. MAX4223 -3dB Bandwidth Distribution

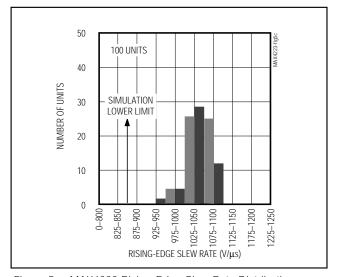


Figure 5c. MAX4223 Rising-Edge Slew-Rate Distribution

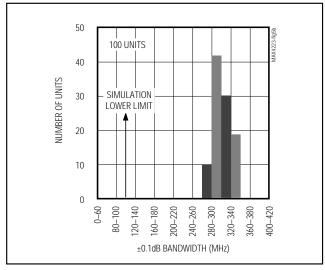


Figure 5b. MAX4223 ±0.1dB Bandwidth Distribution

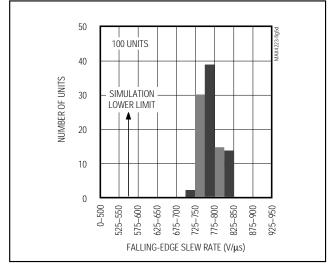


Figure 5d. MAX4223 Falling-Edge Slew-Rate Distribution

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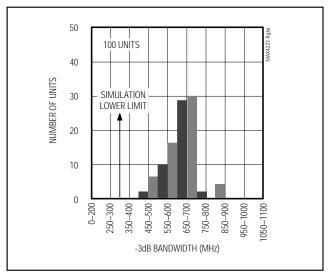


Figure 6a. MAX4224 -3dB Bandwidth Distribution

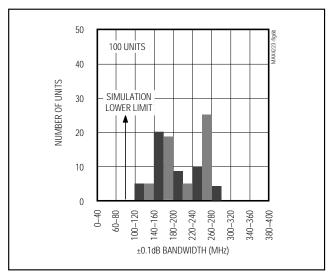


Figure 6b. MAX4224 ±0.1dB Bandwidth Distribution

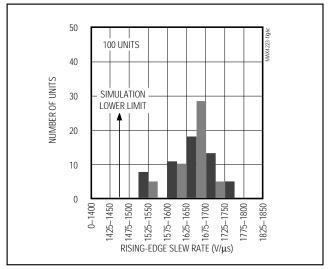


Figure 6c. MAX4224 Rising-Edge Slew-Rate Distribution

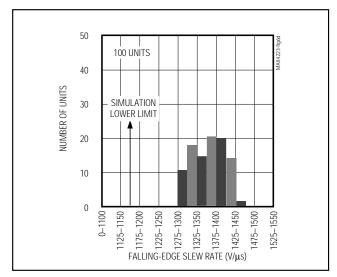


Figure 6d. MAX4224 Falling-Edge Slew-Rate Distribution

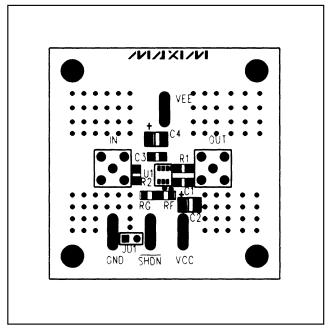


Figure 7a. Maxim SOT23 High-Speed Evaluation Board Component Placement Guide—Component Side

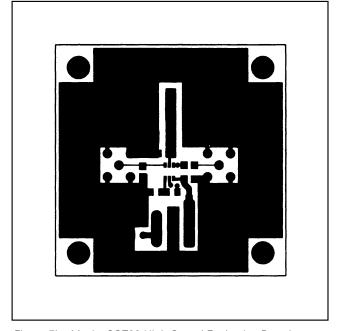


Figure 7b. Maxim SOT23 High-Speed Evaluation Board PC Board Layout—Component Side

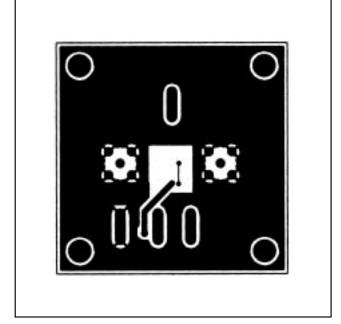


Figure 7c. Maxim SOT23 High-Speed Evaluation Board PC Board Layout—Back Side

16

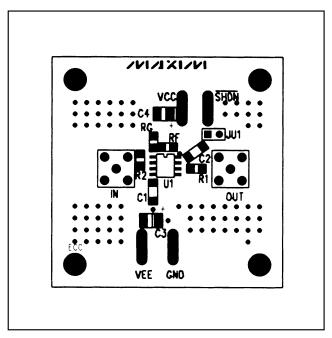


Figure 8a. Maxim SO-8 High-Speed Evaluation Board Component Placement Guide—Component Side

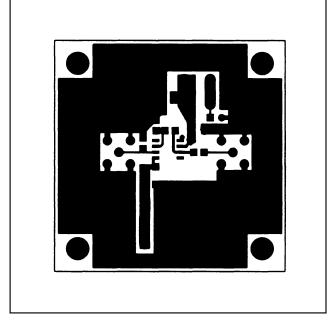


Figure 8b. Maxim SO-8 High-Speed Evaluation Board PC Board Layout—Component Side

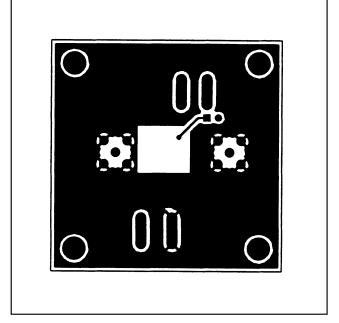
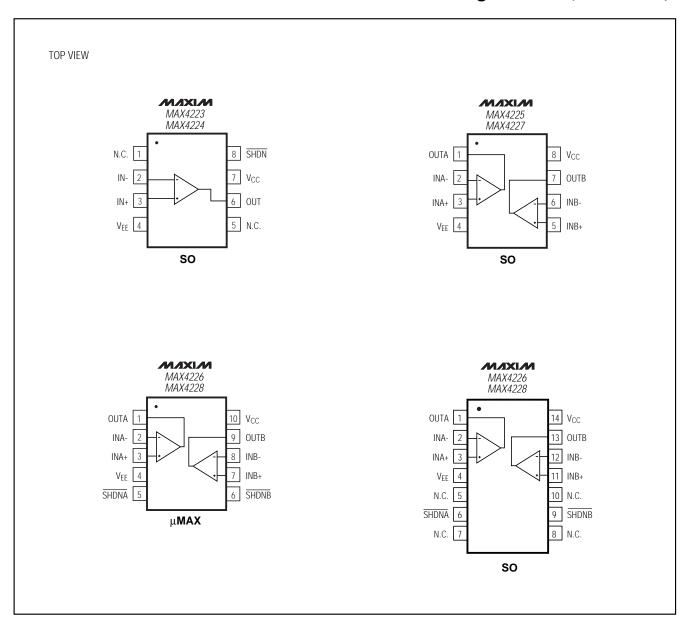


Figure 8c. Maxim SO-8 High-Speed Evaluation Board PC Board Layout—Back Side

Pin Configurations (continued)



18 \_\_\_\_\_\_ /N/XI/N

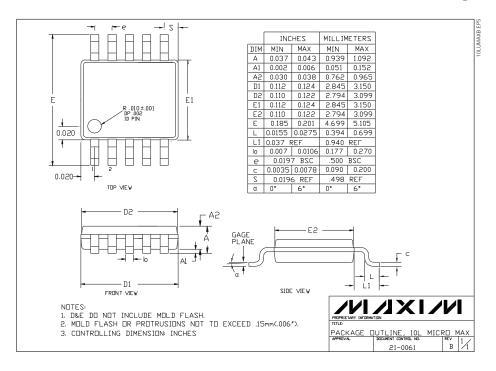
### \_Ordering Information (continued)

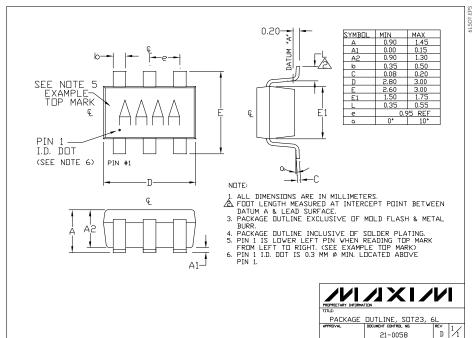
PART	TEMP. RANGE	PIN- PACKAGE	SOT TOP MARK
MAX4224EUT-T	-40°C to +85°C	6 SOT23	AAAE
MAX4224ESA	-40°C to +85°C	8 SO	_
MAX4225ESA	-40°C to +85°C	8 SO	_
MAX4226EUB	-40°C to +85°C	10 μMAX	_
MAX4226ESD	-40°C to +85°C	14 SO	_
MAX4227ESA	-40°C to +85°C	8 SO	_
MAX4228EUB	-40°C to +85°C	10 μMAX	_
MAX4228FSD	-40°C to +85°C	14 SO	_

\_\_\_\_Chip Information

MAX4223/MAX4224 TRANSISTOR COUNT: 87 MAX4225-MAX4228 TRANSISTOR COUNT: 171 SUBSTRATE CONNECTED TO VEE

Package Information





Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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