

# General Purpose, Low Voltage, Rail-to-Rail Output **Operational Amplifiers**

# **General Description**

The LMV358/LMV324 are low voltage (2.7-5.5V) versions of the dual and quad commodity op amps, LM358/LMV324, which currently operate at 5-30V. The LMV321 is the single version.

The LMV321/LMV358/LMV324 are the most cost effective solutions for the applications where low voltage operation, space saving and low price are needed. They offer specifications that meet or exceed the familiar LM358/LMV324. The LMV321/LMV358/LMV324 have rail-to-rail output swing capability and the input common-mode voltage range includes ground. They all exhibit excellent speed to power ratio, achieving 1 MHz of bandwidth and 1 V/µs of slew rate with low supply current.

The LMV321 is available in the space saving 5-Pin SC70, which is approximately half the size of the 5-Pin SOT23. The small package saves space on PC boards, and enables the design of small portable electronic devices. It also allows the designer to place the device closer to the signal source to reduce noise pickup and increase signal integrity.

The chips are built with National's advanced submicron silicon-gate BiCMOS process. The LMV321/LMV358/LMV324 have bipolar input and output stages for improved noise performance and higher output current drive.

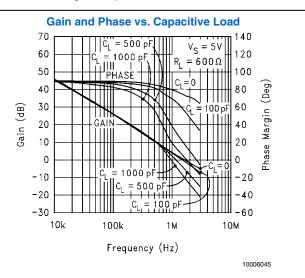
# Features

(For  $V^+ = 5V$  and  $V^- = 0V$ , unless otherwise specified)

- Guaranteed 2.7V and 5V performance
- -No crossover distortion
- Industrial temperature range -40°C to +85°C 1 MHz
- Gain-bandwidth product -Low supply current — LMV321 130 µA - LMV358 210 µA - LMV324 410 µA Rail-to-rail output swing @ 10 kΩ V+ -10 mV V- +65 mV -0.2V to V+-0.8V V<sub>CM</sub>

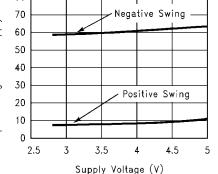
# Applications

- Active filters
- General purpose low voltage applications
- General purpose portable devices



Output Voltage from Supply Voltage (mV) 100  $R_{\rm I} = 10 \, \rm k \, \Omega$ 90 80 70 Negative Swing 60

Output Voltage Swing vs. Supply Voltage



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100060 © 2009 National Semiconductor Corporation

ESD Tolerance (*Note 2*) Human Body Model LMV358/LMV324

Supply Voltage (V+-V -) Output Short Circuit to V + Output Short Circuit to V -Soldering Information

LMV321 Machine Model Differential Input Voltage

Input Voltage

# Absolute Maximum Ratings (Note 1)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

atings (Note 1)	Infrared or Convection (30 sec)	260°C	
vices are required,	Storage Temp. Range	–65°C to 150°C	
onductor Sales Office/ ecifications.	Junction Temperature ( <i>Note 5</i> )	150°C	
ecilications.	<b>Operating Ratings</b> (Note 1)		
	Supply Voltage	2.7V to 5.5V	
2000V	Temperature Range (Note 5)		
900V	LMV321/LMV358/LMV324	–40°C to +85°C	
100V	Thermal Resistance (θ <sub>JA</sub> ) ( <i>Note 10</i> )		
±Supply Voltage	5-pin SC70	478°C/W	
-0.3V to +Supply Voltage	5-pin SOT23	265°C/W	
5.5V	8-Pin SOIC	190°C/W	
( <i>Note 3</i> )	8-Pin MSOP	235°C/W	
( <i>Note 4</i> )	14-Pin SOIC	145°C/W	

155°C/W

# **2.7V DC Electrical Characteristics**

Unless otherwise specified, all limits guaranteed for  $T_J = 25^{\circ}C$ ,  $V^+ = 2.7V$ ,  $V^- = 0V$ ,  $V_{CM} = 1.0V$ ,  $V_O = V^+/2$  and  $R_L > 1$  M $\Omega$ .

14-Pin TSSOP

Symbol	Parameter	Conditions	Min	Тур	Max	Units
			( <i>Note 7</i> )	(Note 6)	(Note 7)	
V <sub>OS</sub>	Input Offset Voltage			1.7	7	mV
TCV <sub>OS</sub>	Input Offset Voltage Average Drift			5		µV/°C
I <sub>B</sub>	Input Bias Current			11	250	nA
I <sub>OS</sub>	Input Offset Current			5	50	nA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 1.7V$	50	63		dB
PSRR	Power Supply Rejection Ratio	2.7V ≤ V+ ≤ 5V	50	60		dB
		$V_{O} = 1V$				
V <sub>CM</sub>	Input Common-Mode Voltage Range	For CMRR ≥ 50 dB	0	-0.2		V
				1.9	1.7	V
Vo	Output Swing	$R_L = 10 \text{ k}\Omega \text{ to } 1.35 \text{V}$	V+ -100	V+ –10		mV
				60	180	mV
I <sub>S</sub>	Supply Current	LMV321		80	170	μA
		LMV358		140	340	μA
		Both amplifiers				μΑ
		LMV324		260	680	μA
		All four amplifiers				μ-

# **2.7V AC Electrical Characteristics**

Unless otherwise specified, all limits guaranteed for T  $_{\rm J}$  = 25°C, V<sup>+</sup> = 2.7V, V<sup>-</sup> = 0V, V<sub>CM</sub> = 1.0V, V<sub>O</sub> = V<sup>+</sup>/2 and R<sub>L</sub> > 1 M $\Omega$ .

Symbol	Parameter	Conditions	Min	Тур	Max	Units
			(Note 7)	( <i>Note 6</i> )	(Note 7)	
GBWP	Gain-Bandwidth Product	C <sub>L</sub> = 200 pF		1		MHz
Φ <sub>m</sub>	Phase Margin			60		Deg
G <sub>m</sub>	Gain Margin			10		dB
e <sub>n</sub>	Input-Referred Voltage Noise	f = 1 kHz		46		<u>nV</u> √Hz
i <sub>n</sub>	Input-Referred Current Noise	f = 1 kHz		0.17		<u>pA</u> √Hz

Symbol	Parameter	Conditions	Min ( <i>Note 7</i> )	Typ ( <i>Note 6</i> )	Max ( <i>Note 7</i> )	Units
V <sub>OS</sub>	Input Offset Voltage			1.7	7 9	mV
rcv <sub>os</sub>	Input Offset Voltage Average Drift			5		μV/°C
В	Input Bias Current			15	250 <b>500</b>	nA
I <sub>os</sub>	Input Offset Current			5	50 <b>150</b>	nA
CMRR	Common Mode Rejection Ratio	$0V \le V_{CM} \le 4V$	50	65		dB
PSRR	Power Supply Rejection Ratio	$2.7V \le V^+ \le 5V$ $V_0 = 1V, V_{CM} = 1V$	50	60		dB
V <sub>CM</sub>	Input Common-Mode Voltage	For CMRR ≥ 50 dB	0	-0.2		V
-	Range			4.2	4	V
A <sub>V</sub>	Large Signal Voltage Gain ( <i>Note 8</i> )	$R_L = 2 k\Omega$	15 <b>10</b>	100		V/mV
V <sub>o</sub> C	Output Swing	$R_L = 2 k\Omega$ to 2.5V	V+ -300 <b>V+ -400</b>	V+ -40		mV
				120	300 <b>400</b>	mV
		$R_L = 10 \text{ k}\Omega \text{ to } 2.5 \text{V}$	V+ -100 V+ -200	V+ -10		mV
				65	180 <b>280</b>	mV
I <sub>O</sub>	Output Short Circuit Current	Sourcing, V <sub>O</sub> = 0V	5	60		mA
		Sinking, V <sub>O</sub> = 5V	10	160		IIIA
I <sub>S</sub>	Supply Current	LMV321		130	250 <b>350</b>	μA
		LMV358 Both amplifiers		210	440 <b>615</b>	μA
		LMV324 All four amplifiers		410	830 1160	μA

# **5V AC Electrical Characteristics**

**5V DC Electrical Characteristics** 

Unless otherwise specified, all limits guaranteed for  $T_J = 25^{\circ}C$ ,  $V^+ = 5V$ ,  $V^- = 0V$ ,  $V_{CM} = 2.0V$ ,  $V_O = V^+/2$  and  $R_L > 1 M\Omega$ . **Boldface** limits apply at the temperature extremes.

Symbol	Parameter	Conditions	Min ( <i>Note 7</i> )	Typ ( <i>Note 6</i> )	Max ( <i>Note 7</i> )	Units
SR	Slew Rate	(Note 9)		1		V/µs
GBWP	Gain-Bandwidth Product	C <sub>L</sub> = 200 pF		1		MHz
Φ <sub>m</sub>	Phase Margin			60		Deg
G <sub>m</sub>	Gain Margin			10		dB
e <sub>n</sub>	Input-Referred Voltage Noise	f = 1 kHz		39		nV 1√Hz
i <sub>n</sub>	Input-Referred Current Noise	f = 1 kHz		0.21		<u>pA</u> √Hz

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not guaranteed. For guaranteed specifications and the test conditions, see the Electrical Characteristics. Note 2: Human Body Model, applicable std. MIL-STD-883, Method 3015.7. Machine Model, applicable std. JESD22-A115-A (ESD MM std. of JEDEC) Field-Induced Charge-Device Model, applicable std. JESD22-C101-C (ESD FICDM std. of JEDEC)

Note 3: Shorting output to V+ will adversely affect reliability.

Note 4: Shorting output to V- will adversely affect reliability.

Note 5: The maximum power dissipation is a function of  $T_{J(MAX)}$ ,  $\theta_{JA}$ . The maximum allowable power dissipation at any ambient temperature is  $P_D = (T_{J(MAX)} - T_A)/\theta_{JA}$ . All numbers apply for packages soldered directly onto a PC Board.

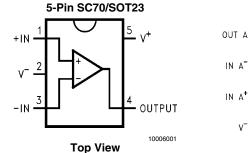
Note 6: Typical values represent the most likely parametric norm as determined at the time of characterization. Actual typical values may vary over time and will also depend on the application and configuration. The typical values are not tested and are not guaranteed on shipped production material.

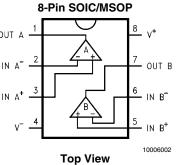
Note 7: All limits are guaranteed by testing or statistical analysis.

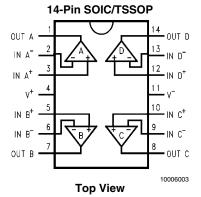
Note 8:  $R_L$  is connected to V<sup>-</sup>. The output voltage is 0.5V  $\leq V_O \leq$  4.5V.

**Note 9:** Connected as voltage follower with 3V step input. Number specified is the slower of the positive and negative slew rates. **Note 10:** All numbers are typical, and apply for packages soldered directly onto a PC board in still air.

## **Connection Diagrams**





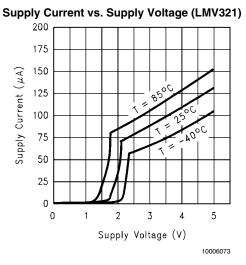


# **Ordering Information**

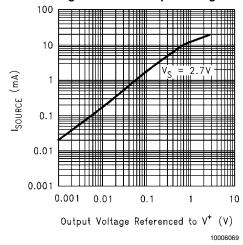
	Temperature Range				
Package	Industrial	Packaging Marking	Transport Media	NSC Drawing	
	–40°C to +85°C				
5-Pin SC70	Pin SC70 LMV321M7 A12		1k Units Tape and Reel		
5-PIII 5070	LMV321M7X	AI2	3k Units Tape and Reel	MAA05A	
5-Pin SOT23	LMV321M5	A13	1k Units Tape and Reel		
5-PIII 50125	LMV321M5X	AIS	3k Units Tape and Reel	MF05A	
	LMV358M		Rails	M08A	
8-Pin SOIC	LMV358MX	LMV358M	2.5k Units Tape and Reel		
	LMV358MM	1 N0/050	1k Units Tape and Reel	MUADOA	
8-Pin MSOP	LMV358MMX	LMV358	3.5k Units Tape and Reel	MUA08A	
	LMV324M	1.00/00/00/	Rails		
14-Pin SOIC	LMV324MX	LMV324M	2.5k Units Tape and Reel	M14A	
	LMV324MT		Rails	MTO14	
14-Pin TSSOP	LMV324MTX	LMV324MT	2.5k Units Tape and Reel	MTC14	

4

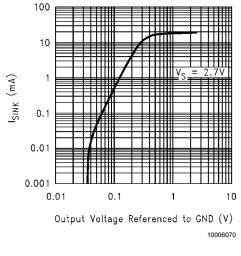
# Typical Performance Characteristics Unless otherwise specified, V<sub>s</sub> = +5V, single supply, T<sub>A</sub> = 25°C.

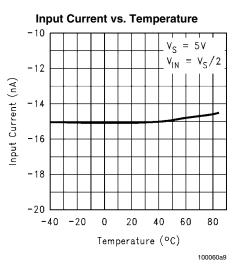


Sourcing Current vs. Output Voltage

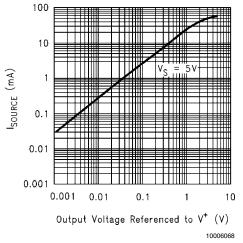


Sinking Current vs. Output Voltage

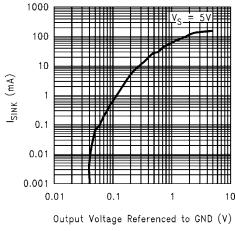




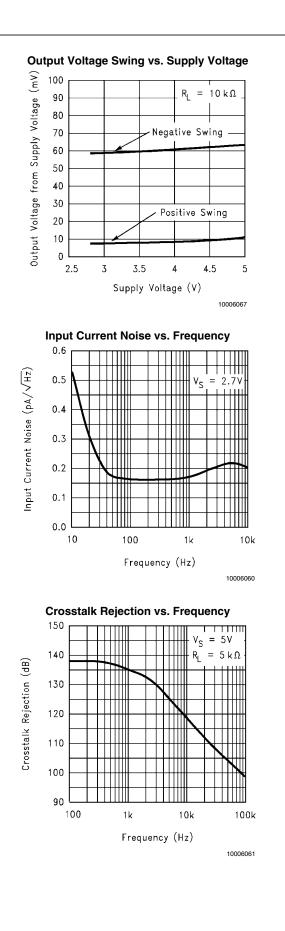
Sourcing Current vs. Output Voltage

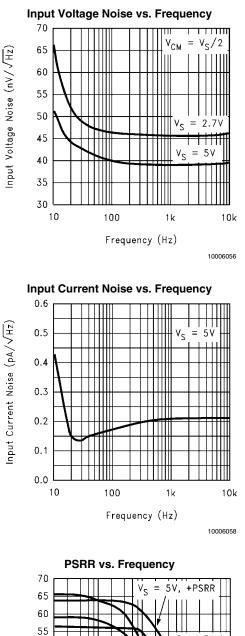


Sinking Current vs. Output Voltage



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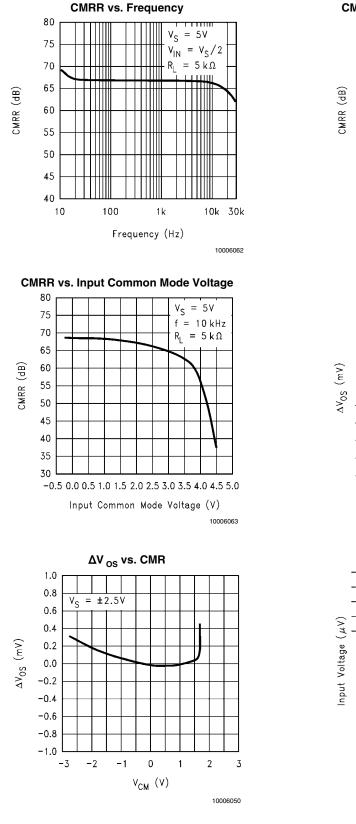
R = 5kΩ 50 45 40 = 2.7V, +PSRR 35 ٧<sub>S</sub> 5V, -PSRR 30 = 25 2 7V. -PSRF = 20 100 10k 100k 1k 1M Frequency (Hz)

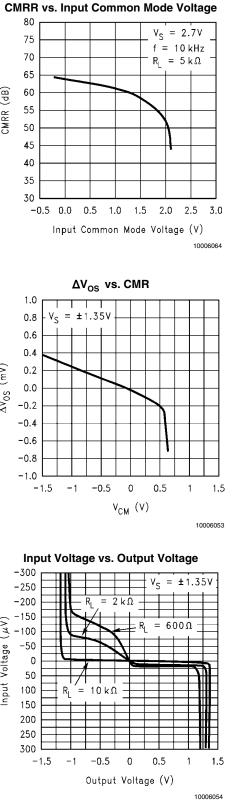
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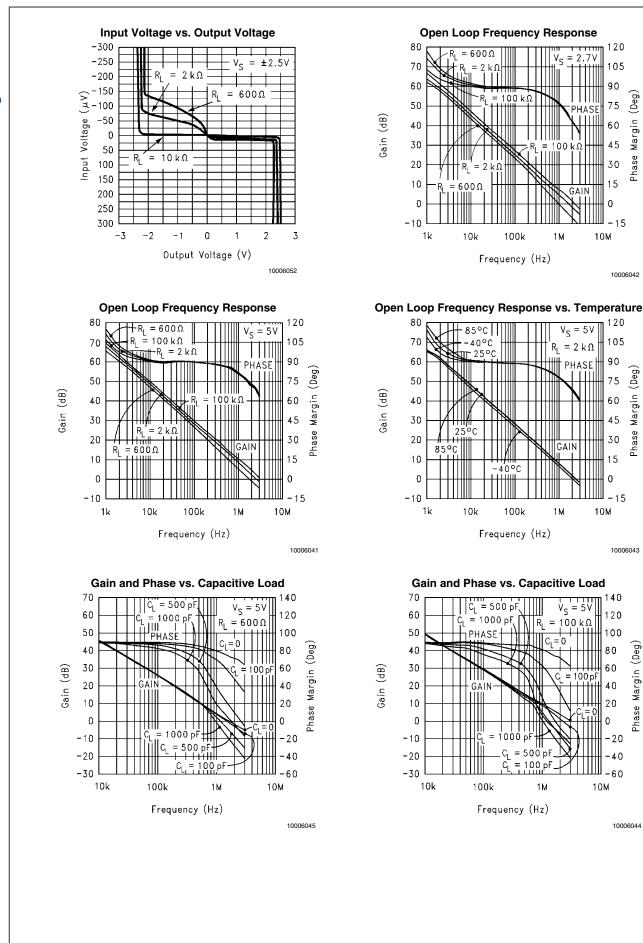
www.national.com

PSRR (dB)









120

105

90

75

45

30

15

0

10M

-15

10006042

120

105

90

75

60

45

30

15

-15

10006043

140

120

100

80

60

40

20

-20

40

-60

10006044

10M

0

Phase Margin (Deg

0

10M

Margin (Deg

Phase

(Deg)

Margin 60

Phase

2.7V

100 k.0

1 M

٧<sub>S</sub> = 5\

IGAIN

1 M

ν<sub>s</sub>

= 0

R =

= 500 p

= 100 pF

1M

= 5 V

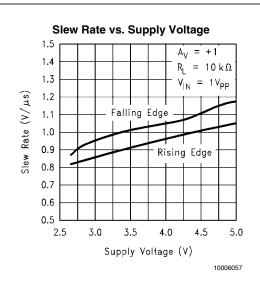
100

100 kΩ

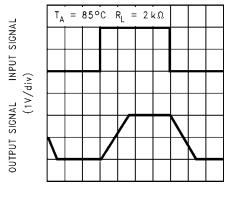
= 2 k Ω RL

PHASE

GAIN



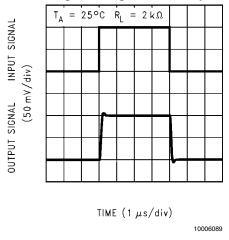
Non-Inverting Large Signal Pulse Response



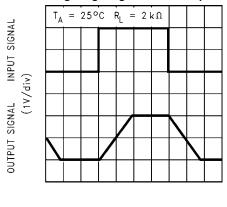
TIME (1μs/div)

100060a1

Non-Inverting Small Signal Pulse Response



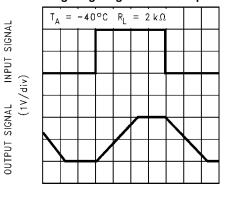
Non-Inverting Large Signal Pulse Response



TIME (1μs/div)

10006088

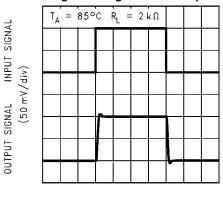
Non-Inverting Large Signal Pulse Response



TIME (1  $\mu$ s/div)

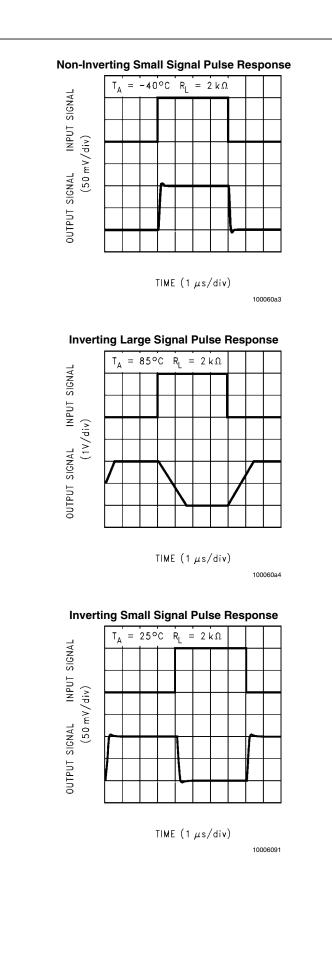




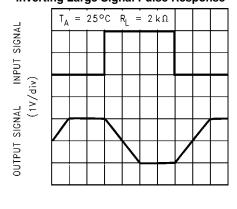


TIME (1  $\mu$ s/div)

### 100060a2



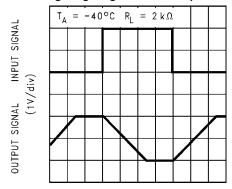
Inverting Large Signal Pulse Response



TIME (1  $\mu$ s/div)

10006090

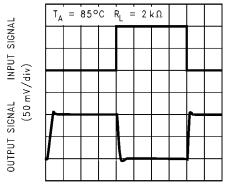
**Inverting Large Signal Pulse Response** 



TIME (1  $\mu$ s/div)

100060a5

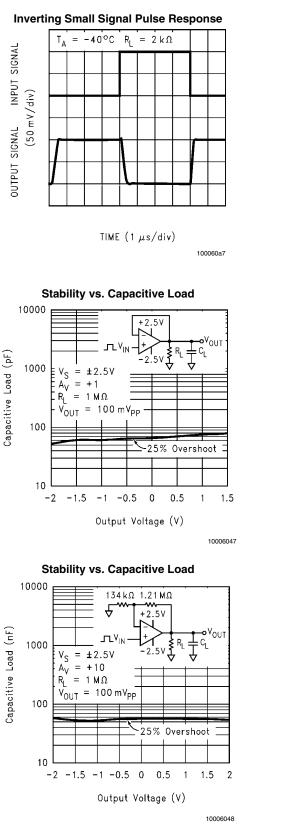
### Inverting Small Signal Pulse Response



TIME (1  $\mu$ s/div)

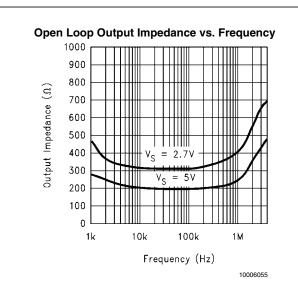
100060a6



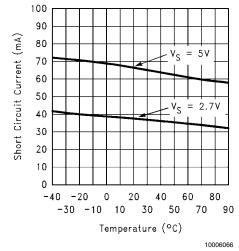


Stability vs. Capacitive Load 10000 +2.5V ΟU Ţ CL Capacitive Load (pF) 1000 25% Overshoot 100  $= \pm 2.5 V$ ۷<sub>s</sub> = +1 2kΩ R =  $= 100 \text{ mV}_{PP}$ Voui 10 0 -2 -1.5 -1 -0.5 0.5 1 1.5 Output Voltage (V) 10006046 Stability vs. Capacitive Load 10000 134kΩ 1.21MΩ . 2 Capacitive Load (nF) ΟU л٧ 1000 C ₹ Ŷ = ±2.5V ٧<sub>S</sub> = +10 Av 2kΩ R =  $= 100 \, mV_{PP}$ VOUT 100 25% Overshoot 10 -2 -1.5 -1 -0.5 0 0.5 1.5 2 1 Output Voltage (V) 10006049 THD vs. Frequency 5 0.5 THD (%) = + 10, V<sub>OUT</sub> 2.7V, A<sub>V</sub>  $= 1 V_{p_1}$ = 5V, A<sub>V</sub> = +10, V<sub>OUT</sub> = 2.5V<sub>P</sub> 0.05 = 2.7V, A<sub>V</sub> = +1, V<sub>OUT</sub>  $= 1V_{PF}$  $= 5V, A_V = +1, V_{OUT} = 1V_{PF}$ 0.005 20 100 1k 10k 100k Frequency (Hz)

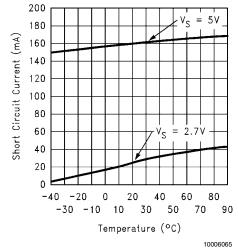
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Short Circuit Current vs. Temperature (Sinking)



# **Application Information**

## BENEFITS OF THE LMV321/LMV358/LMV324

### Size

The small footprints of the LMV321/LMV358/LMV324 packages save space on printed circuit boards, and enable the design of smaller electronic products, such as cellular phones, pagers, or other portable systems. The low profile of the LMV321/LMV358/LMV324 make them possible to use in PCMCIA type III cards.

### Signal Integrity

Signals can pick up noise between the signal source and the amplifier. By using a physically smaller amplifier package, the LMV321/LMV358/LMV324 can be placed closer to the signal source, reducing noise pickup and increasing signal integrity.

### Simplified Board Layout

These products help you to avoid using long PC traces in your PC board layout. This means that no additional components, such as capacitors and resistors, are needed to filter out the unwanted signals due to the interference between the long PC traces.

### Low Supply Current

These devices will help you to maximize battery life. They are ideal for battery powered systems.

### Low Supply Voltage

National provides guaranteed performance at 2.7V and 5V. These guarantees ensure operation throughout the battery lifetime.

### **Rail-to-Rail Output**

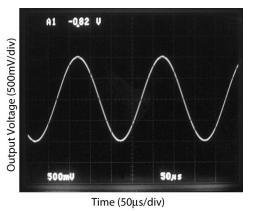
Rail-to-rail output swing provides maximum possible dynamic range at the output. This is particularly important when operating on low supply voltages.

### **Input Includes Ground**

Allows direct sensing near GND in single supply operation. Protection should be provided to prevent the input voltages from going negative more than -0.3V (at 25°C). An input clamp diode with a resistor to the IC input terminal can be used.

### Ease of Use and Crossover Distortion

The LMV321/LMV358/LMV324 offer specifications similar to the familiar LM324. In addition, the new LMV321/LMV358/LMV324 effectively eliminate the output crossover distortion. The scope photos in *Figure 1* and *Figure 2* compare the output swing of the LMV324 and the LM324 in a voltage follower configuration, with V<sub>S</sub> = ± 2.5V and R<sub>L</sub> (= 2 kΩ) connected to GND. It is apparent that the crossover distortion has been eliminated in the new LMV324.



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FIGURE 1. Output Swing of LMV324

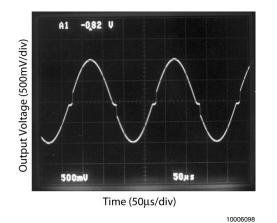


FIGURE 2. Output Swing of LM324

### CAPACITIVE LOAD TOLERANCE

The LMV321/LMV358/LMV324 can directly drive 200 pF in unity-gain without oscillation. The unity-gain follower is the most sensitive configuration to capacitive loading. Direct capacitive loading reduces the phase margin of amplifiers. The combination of the amplifier's output impedance and the capacitive load induces phase lag. This results in either an underdamped pulse response or oscillation. To drive a heavier capacitive load, the circuit in *Figure 3* can be used.

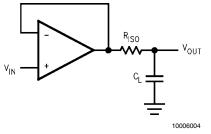
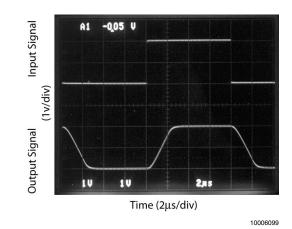


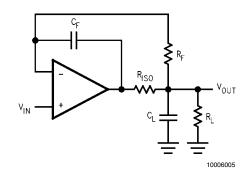
FIGURE 3. Indirectly Driving a Capacitive Load Using Resistive Isolation

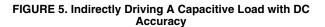
In *Figure 3*, the isolation resistor R<sub>ISO</sub> and the load capacitor C<sub>L</sub> form a pole to increase stability by adding more phase margin to the overall system. The desired performance depends on the value of R<sub>ISO</sub>. The bigger the R<sub>ISO</sub> resistor value, the more stable V<sub>OUT</sub> will be. *Figure 4* is an output waveform of *Figure 3* using 620 $\Omega$  for R<sub>ISO</sub> and 510 pF for C<sub>L</sub>.



### FIGURE 4. Pulse Response of the LMV324 Circuit in Figure 3

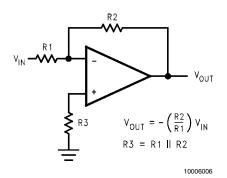
The circuit in *Figure 5* is an improvement to the one in *Figure 3* because it provides DC accuracy as well as AC stability. If there were a load resistor in *Figure 3*, the output would be voltage divided by  $R_{ISO}$  and the load resistor. Instead, in *Figure 5*,  $R_F$  provides the DC accuracy by using feed-forward techniques to connect  $V_{IN}$  to  $R_L$ . Caution is needed in choosing the value of  $R_F$  due to the input bias current of theLMV321/LMV358/LMV324.  $C_F$  and  $R_{ISO}$  serve to counteract the loss of phase margin by feeding the high frequency component of the output signal back to the amplifier's inverting input, thereby preserving phase margin in the overall feedback loop. Increased capacitive drive is possible by increasing the value of  $C_F$ . This in turn will slow down the pulse response.





### INPUT BIAS CURRENT CANCELLATION

The LMV321/LMV358/LMV324 family has a bipolar input stage. The typical input bias current of LMV321/LMV358/LMV324 is 15 nA with 5V supply. Thus a 100 k $\Omega$  input resistor will cause 1.5 mV of error voltage. By balancing the resistor values at both inverting and non-inverting inputs, the error caused by the amplifier's input bias current will be reduced. The circuit in *Figure 6* shows how to cancel the error caused by input bias current.



### FIGURE 6. Cancelling the Error Caused by Input Bias Current

### **TYPICAL SINGLE-SUPPLY APPLICATION CIRCUITS**

### **Difference Amplifier**

The difference amplifier allows the subtraction of two voltages or, as a special case, the cancellation of a signal common to two inputs. It is useful as a computational amplifier, in making a differential to single-ended conversion or in rejecting a common mode signal.

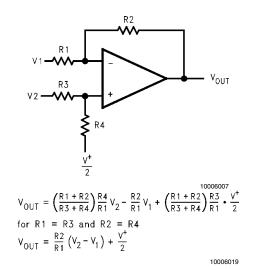


FIGURE 7. Difference Amplifier

### **Instrumentation Circuits**

The input impedance of the previous difference amplifier is set by the resistors  $R_1$ ,  $R_2$ ,  $R_3$ , and  $R_4$ . To eliminate the problems of low input impedance, one way is to use a voltage follower ahead of each input as shown in the following two instrumentation amplifiers.

### **Three-Op-Amp Instrumentation Amplifier**

The quad LMV324 can be used to build a three-op-amp instrumentation amplifier as shown in *Figure 8*.

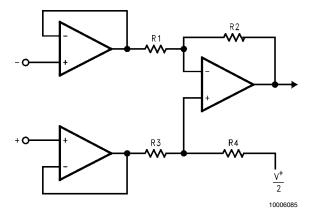
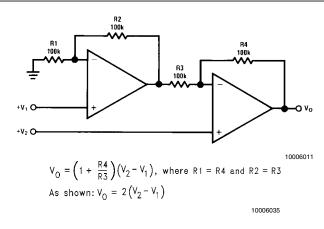


FIGURE 8. Three-Op-Amp Instrumentation Amplifier

The first stage of this instrumentation amplifier is a differentialinput, differential-output amplifier, with two voltage followers. These two voltage followers assure that the input impedance is over 100 MΩ. The gain of this instrumentation amplifier is set by the ratio of R<sub>2</sub>/R<sub>1</sub>. R<sub>3</sub> should equal R<sub>1</sub>, and R<sub>4</sub> equal R<sub>2</sub>. Matching of R<sub>3</sub> to R<sub>1</sub> and R<sub>4</sub> to R<sub>2</sub> affects the CMRR. For good CMRR over temperature, low drift resistors should be used. Making R<sub>4</sub> slightly smaller than R<sub>2</sub> and adding a trim pot equal to twice the difference between R<sub>2</sub> and R<sub>4</sub> will allow the CMRR to be adjusted for optimum performance.

### **Two-Op-Amp Instrumentation Amplifier**

A two-op-amp instrumentation amplifier can also be used to make a high-input-impedance DC differential amplifier (*Figure 9*). As in the three-op-amp circuit, this instrumentation amplifier requires precise resistor matching for good CMRR. R<sub>4</sub> should equal R<sub>1</sub> and, R<sub>3</sub> should equal R<sub>2</sub>.



### FIGURE 9. Two-Op-Amp Instrumentation Amplifier

### **Single-Supply Inverting Amplifier**

There may be cases where the input signal going into the amplifier is negative. Because the amplifier is operating in single supply voltage, a voltage divider using R<sub>3</sub> and R<sub>4</sub> is implemented to bias the amplifier so the input signal is within the input common-mode voltage range of the amplifier. The capacitor C<sub>1</sub> is placed between the inverting input and resistor R<sub>1</sub> to block the DC signal going into the AC signal source, V<sub>IN</sub>. The values of R<sub>1</sub> and C<sub>1</sub> affect the cutoff frequency, fc =  $1/2\pi R_1 C_1$ .

As a result, the output signal is centered around mid-supply (if the voltage divider provides V+/2 at the non-inverting input). The output can swing to both rails, maximizing the signal-tonoise ratio in a low voltage system.

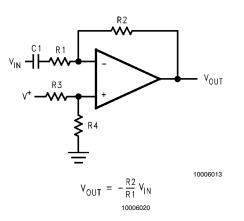


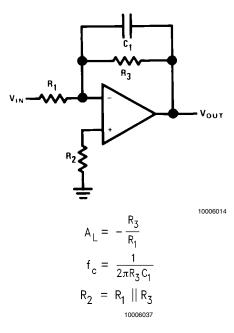
FIGURE 10. Single-Supply Inverting Amplifier

### **ACTIVE FILTER**

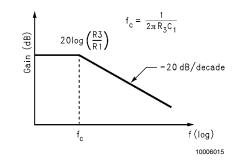
LMV321/LMV358/LMV324 Single/Dual/Quad

### **Simple Low-Pass Active Filter**

The simple low-pass filter is shown in *Figure 11*. Its low-frequency gain ( $\omega \rightarrow 0$ ) is defined by  $-R_3/R_1$ . This allows low-frequency gains other than unity to be obtained. The filter has a -20 dB/decade roll-off after its corner frequency fc.  $R_2$  should be chosen equal to the parallel combination of  $R_1$  and  $R_3$  to minimize errors due to bias current. The frequency response of the filter is shown in *Figure 12*.



### FIGURE 11. Simple Low-Pass Active Filter



### FIGURE 12. Frequency Response of Simple Low-Pass Active Filter in Figure 11

Note that the single-op-amp active filters are used in the applications that require low quality factor,  $Q(\leq 10)$ , low frequency ( $\leq 5 \text{ kHz}$ ), and low gain ( $\leq 10$ ), or a small value for the product of gain times  $Q (\leq 100)$ . The op amp should have an open loop voltage gain at the highest frequency of interest at least 50 times larger than the gain of the filter at this frequency. In addition, the selected op amp should have a slew rate that meets the following requirement:

Slew Rate  $\geq 0.5 \times (\omega_H V_{OPP}) \times 10^{-6} V/\mu sec$ 

where  $\omega_{H}$  is the highest frequency of interest, and  $V_{OPP}$  is the output peak-to-peak voltage.

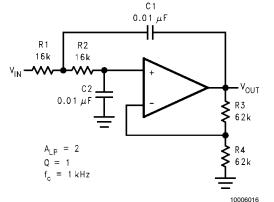
### Sallen-Key 2nd-Order Active Low-Pass Filter

The Sallen-Key 2nd-order active low-pass filter is illustrated in *Figure 13*. The DC gain of the filter is expressed as

$$A_{LP} = \frac{R_3}{R_4} + 1$$
 (1)

Its transfer function is

$$\frac{V_{\text{OUT}}}{V_{\text{IN}}}(S) = \frac{\frac{1}{C_1 C_2 R_1 R_2} A_{\text{LP}}}{S^2 + S\left(\frac{1}{C_1 R_1} + \frac{1}{C_1 R_2} + \frac{1}{C_2 R_2} - \frac{A_{\text{LP}}}{C_2 R_2}\right) + \frac{1}{C_1 C_2 R_1 R_2}}$$
(2)



### FIGURE 13. Sallen-Key 2nd-Order Active Low-Pass Filter

The following paragraphs explain how to select values for  $R_1$ ,  $R_2$ ,  $R_3$ ,  $R_4$ ,  $C_1$ , and  $C_2$  for given filter requirements, such as  $A_{LP}$ , Q, and  $f_c$ .

The standard form for a 2nd-order low pass filter is

$$\frac{V_{OUT}}{V_{IN}}(S) = \frac{A_{LP} \omega_c^2}{S^2 + \left(\frac{\omega_c}{Q}\right)S + \omega_c^2}$$
(3)

where

Q: Pole Quality Factor

ω<sub>C</sub>: Corner Frequency

A comparison between Equation 2 and Equation 3 yields

$$\omega_{\rm c}^2 = \frac{1}{C_1 C_2 R_1 R_2} \tag{4}$$

$$\frac{\omega_{c}}{Q} = \frac{1}{C_{1}R_{1}} + \frac{1}{C_{1}R_{2}} + \frac{1}{C_{2}R_{2}} - \frac{A_{LP}}{C_{2}R_{2}}$$
(5)

To reduce the required calculations in filter design, it is convenient to introduce normalization into the components and design parameters. To normalize, let  $\omega_{\rm C} = \omega_{\rm n} = 1$  rad/s, and  $C_1 = C_2 = C_{\rm n} = 1$ F, and substitute these values into *Equation 4* and *Equation 5*. From *Equation 4*, we obtain

$$R_1 = \frac{1}{R_2} \tag{6}$$

From *Equation 5*, we obtain

$$R_{2} = \frac{1 \pm \sqrt{1 - 4Q^{2}(2 - A_{LP})}}{2Q}$$
(7)

For minimum DC offset,  $\mathsf{V}^{\scriptscriptstyle +}=\mathsf{V}^{\scriptscriptstyle -},$  the resistor values at both inverting and non-inverting inputs should be equal, which means

$$R_1 + R_2 = \frac{R_3 R_4}{R_3 + R_4}$$
(8)

From Equation 1 and Equation 8, we obtain

$$R_3 = (R_1 + R_2)A_{LP}$$
 (9)

$$R_4 = \left(\frac{A_{LP}}{A_{LP}-1}\right)(R_1 + R_2)$$
(10)

The values of  $C_1$  and  $C_2$  are normally close to or equal to

$$C = \frac{10}{f_c} \mu F$$

As a design example:

Require:  $A_{LP} = 2$ , Q = 1, fc = 1 kHz Start by selecting  $C_1$  and  $C_2$ . Choose a standard value that is close to

$$C = \frac{10}{f_c} \mu F$$
$$= C_2 = \frac{10}{1 \times 10^3} \mu F = 0.01 \mu F$$

From Equations 6, 7, 9, 10,

 $C_1$ 

$$R_{1} = 1\Omega$$
$$R_{2} = 1\Omega$$
$$R_{3} = 4\Omega$$
$$R_{4} = 4\Omega$$

The above resistor values are normalized values with  $\omega_n = 1$  rad/s and  $C_1 = C_2 = C_n = 1F$ . To scale the normalized cutoff frequency and resistances to the real values, two scaling factors are introduced, frequency scaling factor  $(k_f)$  and impedance scaling factor  $(k_m)$ .

$$k_{f} = \frac{\omega_{c}}{\omega_{n}} = \frac{2\pi \times 1 \times 10^{3}}{1} = 2\pi \times 10^{3}$$
$$k_{m}k_{f} = \frac{Cn}{C1}$$
$$k_{m} = 1.59 \times 10^{4}$$

Scaled values:

$$R_2 = R_1 = 15.9 \text{ k}\Omega$$
  
 $R_3 = R_4 = 63.6 \text{ k}\Omega$   
 $C_1 = C_2 = 0.01 \text{ μF}$ 

An adjustment to the scaling may be made in order to have realistic values for resistors and capacitors. The actual value used for each component is shown in the circuit.

### 2nd-Order High Pass Filter

A 2nd-order high pass filter can be built by simply interchanging those frequency selective components  $(R_1, R_2, C_1, C_2)$  in the Sallen-Key 2nd-order active low pass filter. As shown in *Figure 14*, resistors become capacitors, and capacitors become resistors. The resulted high pass filter has the same corner frequency and the same maximum gain as the previous 2nd-order low pass filter if the same components are chosen.

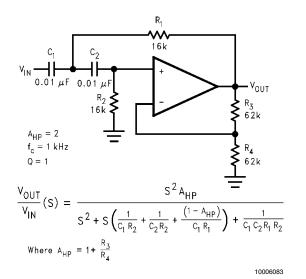


FIGURE 14. Sallen-Key 2nd-Order Active High-Pass Filter

### **State Variable Filter**

A state variable filter requires three op amps. One convenient way to build state variable filters is with a quad op amp, such as the LMV324 (*Figure 15*).

This circuit can simultaneously represent a low-pass filter, high-pass filter, and bandpass filter at three different outputs. The equations for these functions are listed below. It is also called "Bi-Quad" active filter as it can produce a transfer function which is quadratic in both numerator and denominator.

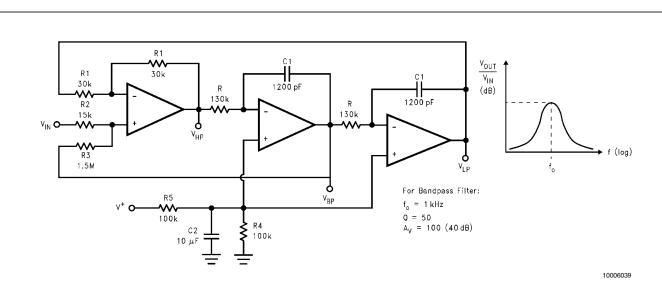


FIGURE 15. State Variable Active Filter

$$V_{LP} = \left(\frac{2R_3}{R_2 + R_3}\right) \frac{\frac{1}{R^2 C^2}}{S^2 + \frac{1}{\left(\frac{R_2 + R_3}{2R_2}\right)RC}} S + \frac{1}{R^2 C^2} V_{IN}$$

$$V_{HP} = \left(\frac{2R_3}{R_2 + R_3}\right) \frac{S^2}{S^2 + \frac{1}{\left(\frac{R_2 + R_3}{2R_2}\right)RC}} S + \frac{1}{R^2C^2} V_{IN}$$

$$V_{BP} = \left(\frac{2R_{3}}{R_{2} + R_{3}}\right) \frac{\left(\frac{1}{RC}\right)S}{S^{2} + \frac{1}{\left(\frac{R_{2} + R_{3}}{2R_{2}}\right)RC}S + \frac{1}{R^{2}C^{2}}} V_{IN}$$

where for all three filters,

$$Q = \frac{R_2 + R_3}{2R_2}$$
(11)

$$\omega_0 = \frac{1}{RC}$$
 (resonant frequency) (12)

A design example for a bandpass filter is shown below: Assume the system design requires a bandpass filter with f<sub>O</sub> = 1 kHz and Q = 50. What needs to be calculated are capacitor and resistor values.

First choose convenient values for C<sub>1</sub>, R<sub>1</sub> and R<sub>2</sub>:

$$2R_2 = R_1 = 30 \text{ k}\Omega$$

Then from Equation 11,

$$R_3 = R_2(2Q-1)$$
  

$$R_3 = 15 k\Omega \times (2 \times 50-1)$$
  
= 1.5 M\Omega

From Equation 12,

$$R = \frac{1}{\omega_0 C_1}$$

$$R = \frac{1}{(2\pi x 10^3)(1.2 \times 10^{-9})}$$

$$= 132.7 \text{ k}\Omega$$

From the above calculated values, the midband gain is  $H_0 = R_3/R_2 = 100$  (40 dB). The nearest 5% standard values have been added to *Figure 15*.

### PULSE GENERATORS AND OSCILLATORS

A pulse generator is shown in *Figure 16*. Two diodes have been used to separate the charge and discharge paths to capacitor C.

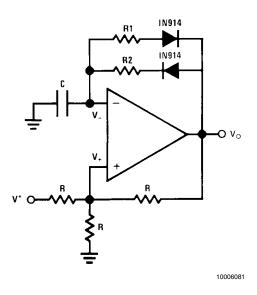
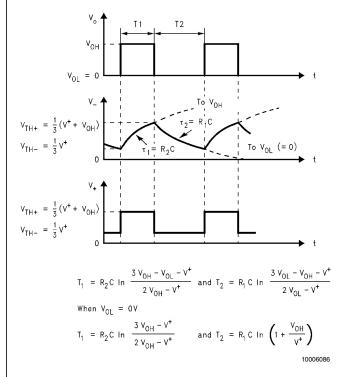


FIGURE 16. Pulse Generator

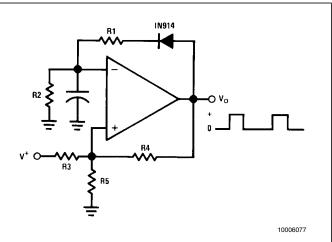
When the output voltage  $V_{O}$  is first at its high,  $V_{OH}$ , the capacitor C is charged toward  $V_{OH}$  through  $R_2$ . The voltage across C rises exponentially with a time constant  $\tau = R_2C$ , and this voltage is applied to the inverting input of the op amp. Meanwhile, the voltage at the non-inverting input is set at the positive threshold voltage  $(V_{TH+})$  of the generator. The capacitor voltage continually increases until it reaches  $V_{TH+}$ , at which point the output of the generator will switch to its low,  $V_{OL}$  which 0V is in this case. The voltage at the non-inverting input is switched to the negative threshold voltage  $(V_{TH-})$  of the generator. The capacitor then starts to discharge toward  $V_{OL}$  exponentially through  $R_1$ , with a time constant  $\tau = R_1C$ . When the capacitor voltage reaches  $V_{TH-}$ , the output of the pulse generator switches to  $V_{OH}$ . The capacitor starts to charge, and the cycle repeats itself.



### FIGURE 17. Waveforms of the Circuit in Figure 16

As shown in the waveforms in *Figure 17*, the pulse width (T<sub>1</sub>) is set by R<sub>2</sub>, C and V<sub>OH</sub>, and the time between pulses (T<sub>2</sub>) is set by R<sub>1</sub>, C and V<sub>OL</sub>. This pulse generator can be made to have different frequencies and pulse width by selecting different capacitor value and resistor values.

*Figure 18* shows another pulse generator, with separate charge and discharge paths. The capacitor is charged through  $R_1$  and is discharged through  $R_2$ .



### **FIGURE 18. Pulse Generator**

*Figure 19* is a squarewave generator with the same path for charging and discharging the capacitor.

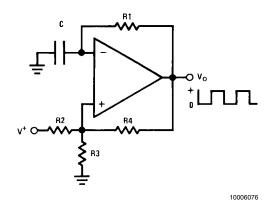


FIGURE 19. Squarewave Generator

### **CURRENT SOURCE AND SINK**

The LMV321/LMV358/LMV324 can be used in feedback loops which regulate the current in external PNP transistors to provide current sources or in external NPN transistors to provide current sinks.

### **Fixed Current Source**

A multiple fixed current source is shown in *Figure 20*. A voltage ( $V_{REF} = 2V$ ) is established across resistor  $R_3$  by the voltage divider ( $R_3$  and  $R_4$ ). Negative feedback is used to cause the voltage drop across  $R_1$  to be equal to  $V_{REF}$ . This controls the emitter current of transistor  $Q_1$  and if we neglect the base current of  $Q_1$  and  $Q_2$ , essentially this same current is available out of the collector of  $Q_1$ .

Large input resistors can be used to reduce current loss and a Darlington connection can be used to reduce errors due to the  $\beta$  of  $Q_1.$ 

The resistor,  $R_2$ , can be used to scale the collector current of  $Q_2$  either above or below the 1 mA reference value.

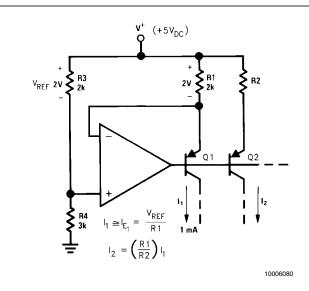


FIGURE 20. Fixed Current Source

### **High Compliance Current Sink**

A current sink circuit is shown in *Figure 21*. The circuit requires only one resistor ( $R_E$ ) and supplies an output current which is directly proportional to this resistor value.

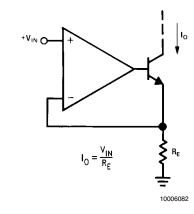
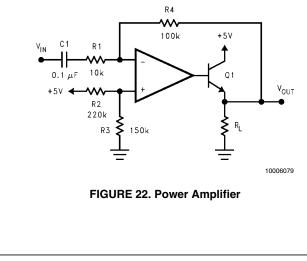


FIGURE 21. High Compliance Current Sink

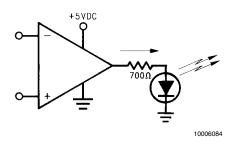
### **POWER AMPLIFIER**

A power amplifier is illustrated in *Figure 22*. This circuit can provide a higher output current because a transistor follower is added to the output of the op amp.



### LED DRIVER

The LMV321/LMV358/LMV324 can be used to drive an LED as shown in *Figure 23*.



### FIGURE 23. LED Driver

### **COMPARATOR WITH HYSTERESIS**

The LMV321/LMV358/LMV324 can be used as a low power comparator. *Figure 24* shows a comparator with hysteresis. The hysteresis is determined by the ratio of the two resistors.

$$V_{TH+} = V_{REF} / (1+R_1/R_2) + V_{OH} / (1+R_2/R_1)$$
  

$$V_{TH-} = V_{REF} / (1+R_1/R_2) + V_{OL} / (1+R_2/R_1)$$
  

$$V_{H} = (V_{OH-}V_{OL}) / (1+R_2/R_1)$$

where

V<sub>TH+</sub>: Positive Threshold Voltage

V<sub>TH</sub>.: Negative Threshold Voltage

V<sub>OH</sub>: Output Voltage at High

V<sub>OI</sub>: Output Voltage at Low

V<sub>H</sub>: Hysteresis Voltage

Since LMV321/LMV358/LMV324 have rail-to-rail output, the (V\_{OH}\_V\_{OL}) is equal to V\_S, which is the supply voltage.

$$V_{\rm H} = V_{\rm S} / (1 + R_2 / R_1)$$

The differential voltage at the input of the op amp should not exceed the specified absolute maximum ratings. For real comparators that are much faster, we recommend you use National's LMV331/LMV93/LMV339, which are single, dual and quad general purpose comparators for low voltage operation.

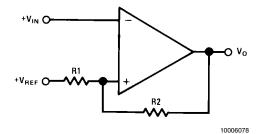
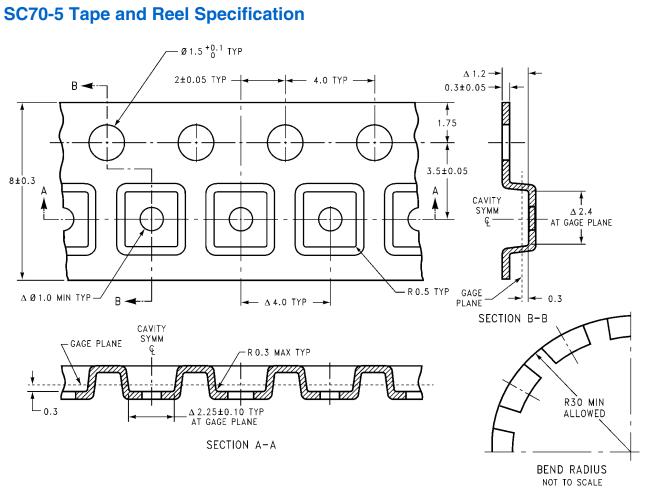


FIGURE 24. Comparator with Hysteresis



100060b3

# **SOT-23-5 Tape and Reel Specification**

### TAPE FORMAT

Tape Section	# Cavities	Cavity Status	Cover Tape Status
Leader	0 (min)	Empty	Sealed
(Start End)	75 (min)	Empty	Sealed
Carrier	3000	Filled	Sealed
	250	Filled	Sealed
Trailer	125 (min)	Empty	Sealed
(Hub End)	0 (min)	Empty	Sealed

# **TAPE DIMENSIONS**

Tape Size

DIM A

DIM Ao

DIM B

DIM Bo

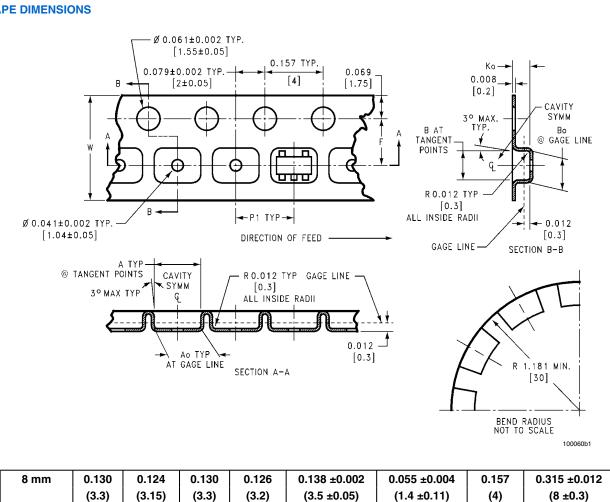
DIM F

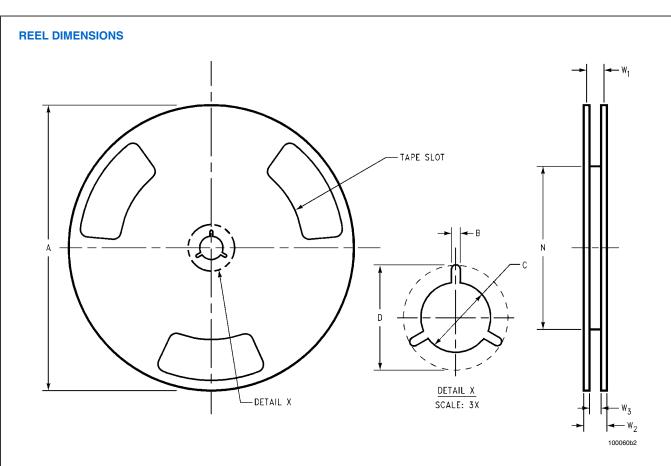
DIM Ko

DIM P1

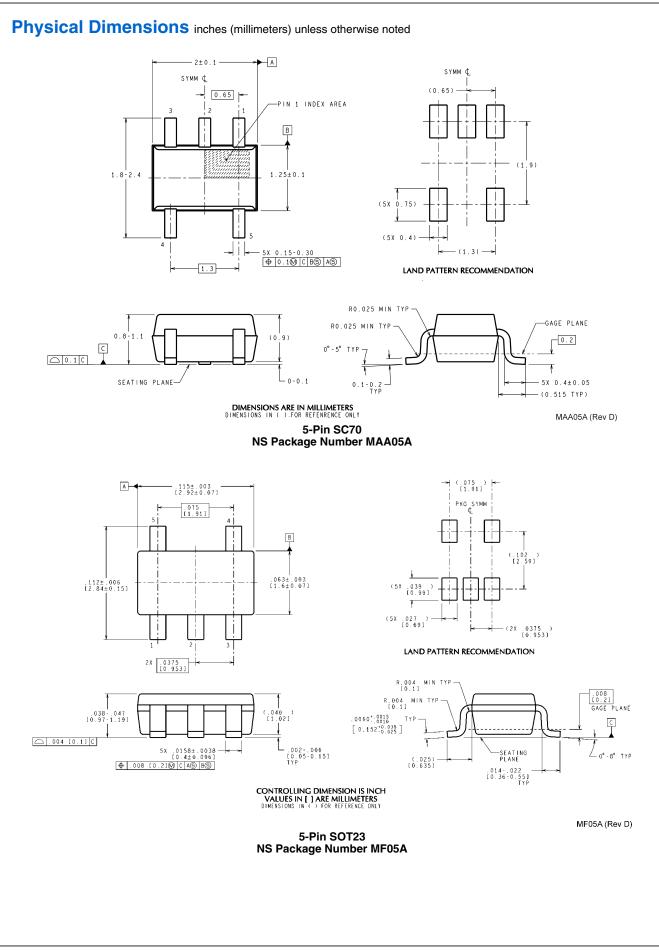
DIM W



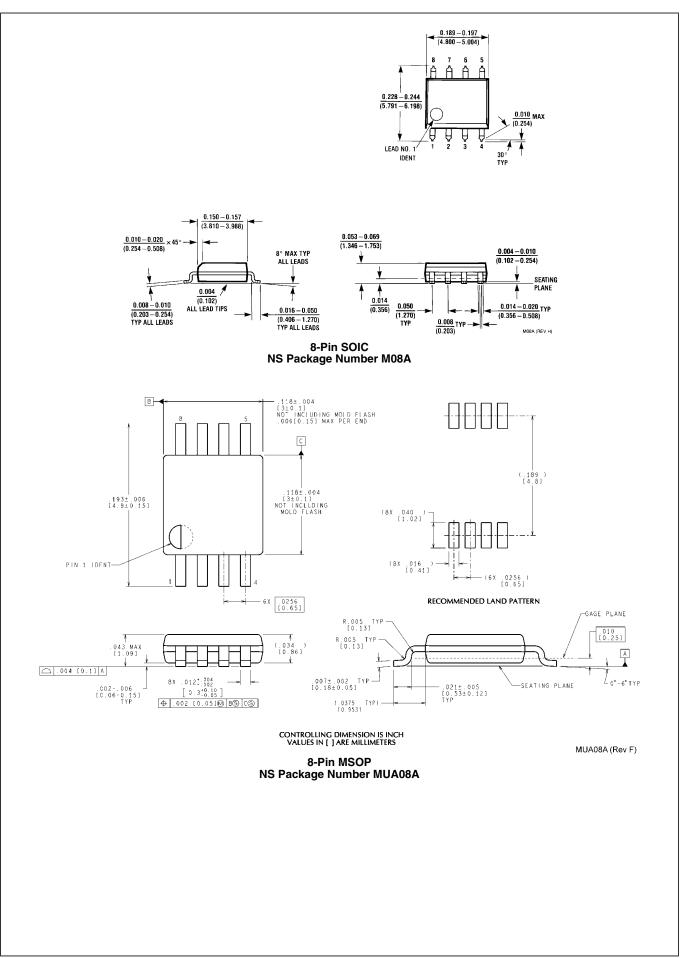




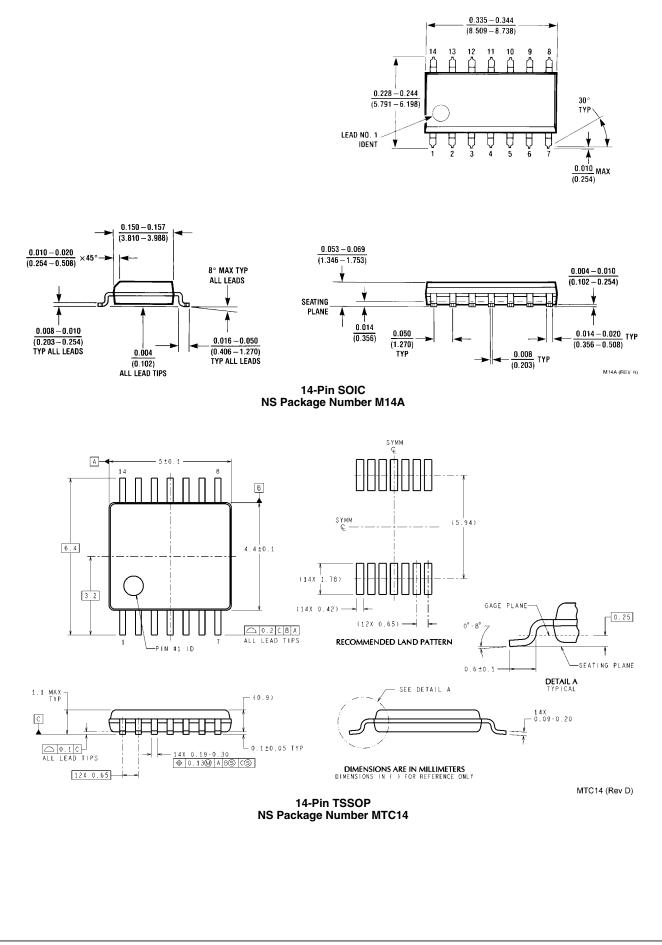
8 mm	7.00	0.059	0.512	0.795	2.165	0.331 + 0.059/-0.000	0.567	W1+ 0.078/-0.039
	330.00	1.50	13.00	20.20	55.00	8.40 + 1.50/-0.00	14.40	W1 + 2.00/-1.00
Tape Size	A	В	С	D	Ν	W1	W2	W3



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# **Notes**

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Switching Regu	
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LED Lighting	www.national.com/led
Voltage Referer	
PowerWise® Solutio	· · · · ·
Serial Digital Interfac	
Temperature Sensor	
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Power Management	www.national.com/power	Green Compliance	www.national.com/quality/green
Switching Regulators	www.national.com/switchers	Distributors	www.national.com/contacts
LDOs	www.national.com/ldo	Quality and Reliability	www.national.com/quality
LED Lighting	www.national.com/led	Feedback/Support	www.national.com/feedback
Voltage Reference	www.national.com/vref	Design Made Easy	www.national.com/easy
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