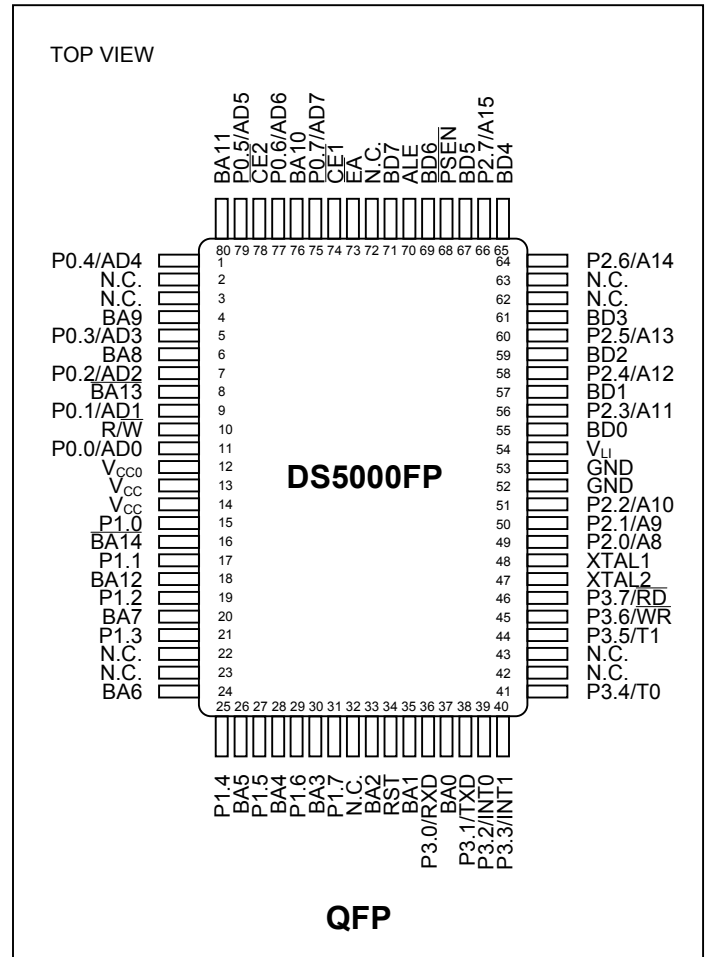


### FEATURES

- **8051-Compatible Microprocessor Adapts to Its Task**
  - Accesses between 8kB and 64kB of nonvolatile SRAM
  - In-system programming via on-chip serial port
  - Can modify its own program or data memory
  - Accesses memory on a separate byte-wide bus
- **Crash-Proof Operation**
  - Maintains all nonvolatile resources for over 10 years
  - Power-fail Reset
  - Early Warning Power-fail Interrupt
  - Watchdog Timer
  - User-supplied lithium battery backs user SRAM for program/data storage
- **Software Security**
  - Executes encrypted programs to prevent observation
  - Security lock prevents download
  - Unlocking destroys contents
- **Fully 8051 Compatible**
  - 128 bytes scratchpad RAM
  - Two timer/counters
  - On-chip serial port
  - 32 parallel I/O port pins

### PIN CONFIGURATION



This data sheet must be used in conjunction with the Secure Microcontroller User's Guide, which contains operating information. This data sheet provides ordering information, pinout, and electrical specifications. Download the Secure Microcontroller User's Guide at [www.maxim-ic.com/microcontrollers](http://www.maxim-ic.com/microcontrollers).

### ORDERING INFORMATION

PART	TEMP RANGE	MAX CLOCK SPEED (MHz)	PIN-PACKAGE
DS5000FP-16	0°C to +70°C	16	80 QFP
DS5000FP-16+	0°C to +70°C	16	80 QFP

+ Denotes a Pb-free/RoHS-compliant device.

**Note:** Some revisions of this device may incorporate deviations from published specifications known as errata. Multiple revisions of any device may be simultaneously available through various sales channels. For information about device errata, click here: [www.maxim-ic.com/errata](http://www.maxim-ic.com/errata).

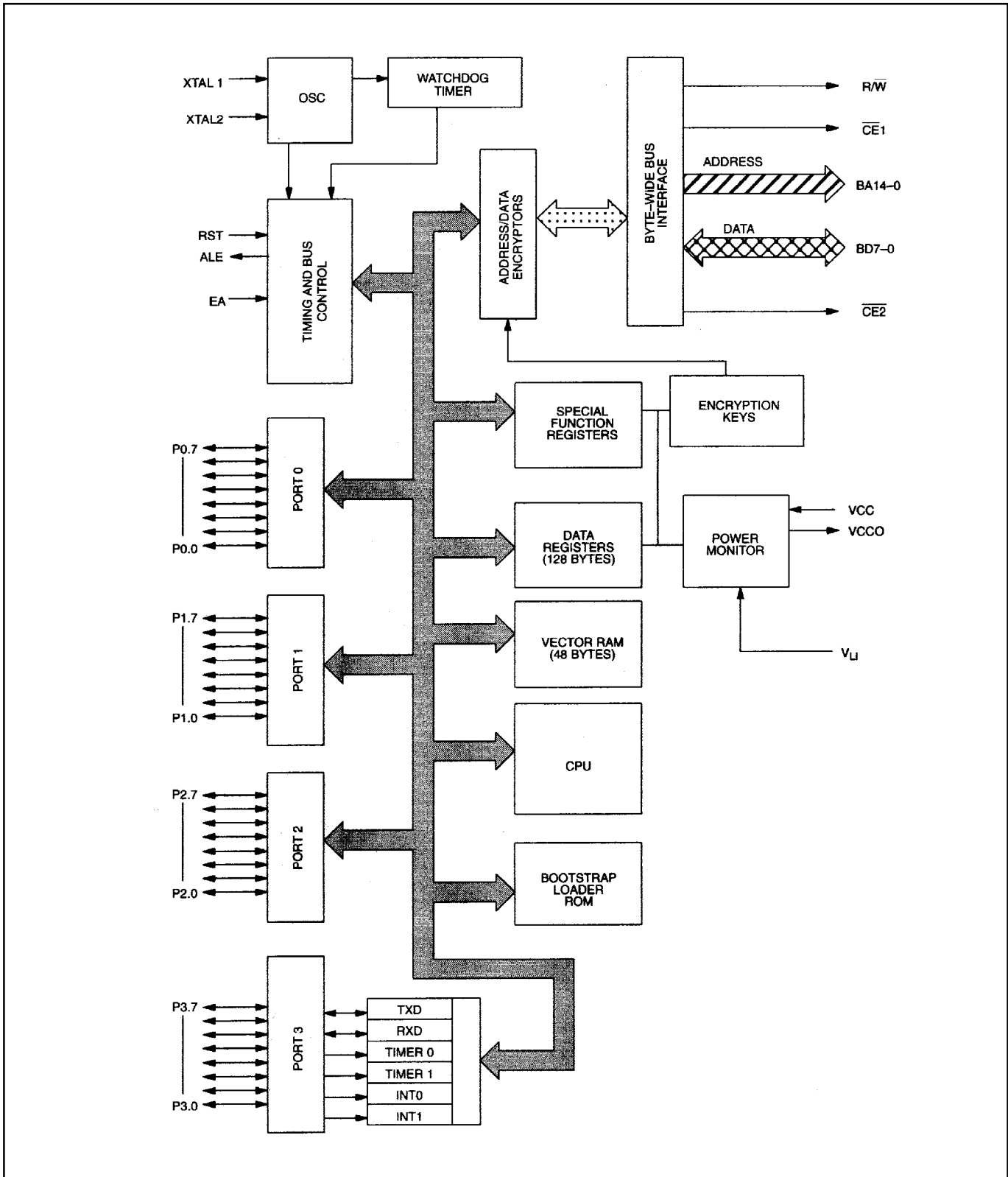
## DESCRIPTION

The DS5000FP Soft Microprocessor Chip is an 8051-compatible processor based on NV RAM technology. It is substantially more flexible than a standard 8051, yet provides full compatibility with the 8051 instruction set, timers, serial port, and parallel I/O ports. By using NV RAM instead of ROM, the user can program and then reprogram the microcontroller while in-system. The application software can even change its own operation, which allows frequent software upgrades, adaptive programs, customized systems, etc. In addition, by using NV SRAM, the DS5000FP is ideal for data-logging applications and it connects easily to a Dallas real-time clock for time stamp and date.

The DS5000FP provides the benefits of NV RAM without using I/O resources. It uses a nonmultiplexed byte-wide address and data bus for memory access. This bus can perform all memory access and provides decoded chip enables for SRAM. This leaves the 32 I/O port pins free for application use. The DS5000FP uses ordinary SRAM and battery backs the memory contents with a user's external lithium cell. Data is maintained for over 10 years with a very small lithium cell. A DS5000FP also provides crash-proof operation in portable systems or systems with unreliable power. These features include the ability to save the operating state, Power-fail Reset, Power-fail Interrupt, and Watchdog Timer.

A user loads programs into the DS5000FP via its on-chip Serial Bootstrap Loader. This function supervises the loading of code into NV RAM, validates it, and then becomes transparent to the user. Software can be stored in an 8-kbyte or 32-kbyte CMOS SRAM. Using its internal Partitioning, the DS5000FP will divide this common RAM into user programmable code and data segments. This Partition can be selected at program loading time, but can be modified anytime later. It will decode memory access to the SRAM, communicate via its byte-wide bus and write-protect the memory portion designated as ROM. Combining program and data storage in one device saves board space and cost. The DS5000FP can also access a second 32 kbytes of NV RAM but this area is restricted to data memory. The DS2250(T) and DS5000(T) are available for a user who wants a pre-constructed module using the DS5000FP, RAM, lithium cell, and optional real-time clock. Each device is described in separate data sheets, available on our website at [www.maxim-ic.com/microcontrollers](http://www.maxim-ic.com/microcontrollers). More details are contained in the *Secure Microcontroller User's Guide*.

DS5000FP BLOCK DIAGRAM Figure 1



## PIN DESCRIPTION

PIN	NAME	FUNCTION
15, 17, 19, 21, 25, 27, 29, 31	<b>P1.0–P1.7</b>	<b>General-Purpose I/O Port 1</b>
34	<b>RST</b>	<b>Active-High Reset Input.</b> A logic 1 applied to this pin activates a reset state. This pin is pulled down internally so this pin can be left unconnected if not used.
36	<b>P3.0/ RXD</b>	<b>General-Purpose I/O Port Pin 3.0.</b> Also serves as the receive signal for the on board UART. This pin should not be connected directly to a PC COM port.
38	<b>P3.1/ TXD</b>	<b>General-Purpose I/O Port Pin 3.1.</b> Also serves as the transmit signal for the on-board UART. This pin should not be connected directly to a PC COM port.
39	<b>P3.2/ INT0</b>	<b>General-Purpose I/O Port Pin 3.2.</b> Also serves as the active-low External Interrupt 0.
40	<b>P3.3/ INT1</b>	<b>General-Purpose I/O Port Pin 3.3.</b> Also serves as the active-low External Interrupt 1.
41	<b>P3.4/T0</b>	<b>General-Purpose I/O Port Pin 3.4.</b> Also serves as the Timer 0 input.
44	<b>P3.5/T1</b>	<b>General-Purpose I/O Port Pin 3.5.</b> Also serves as the Timer 1 input.
45	<b>P3.6/<math>\overline{\text{WR}}</math></b>	<b>General-Purpose I/O Port Pin.</b> Also serves as the write strobe for expanded bus operation.
46	<b>P3.7/<math>\overline{\text{RD}}</math></b>	<b>General-Purpose I/O Port Pin.</b> Also serves as the read strobe for expanded bus operation.
47, 48	<b>XTAL2, XTAL1</b>	<b>Crystal Connections.</b> Used to connect an external crystal to the internal oscillator. XTAL1 is the input to an inverting amplifier and XTAL2 is the output.
52, 53	<b>GND</b>	<b>Logic Ground</b>
49, 50, 51, 56, 58, 60, 64, 66	<b>P2.0–P2.7</b>	<b>General-Purpose I/O Port 2.</b> Also serves as the MSB of the expanded address bus.
68	<b><math>\overline{\text{PSEN}}</math></b>	<b>Program Store Enable.</b> This active-low signal is used to enable an external program memory when using the expanded bus. It is normally an output and should be unconnected if not used. $\overline{\text{PSEN}}$ is also used to invoke the Bootstrap Loader. At this time, $\overline{\text{PSEN}}$ will be pulled down externally. This should only be done once the DS5000FP is already in a reset state. The device that pulls down should be open drain since it must not interfere with $\overline{\text{PSEN}}$ under normal operation.
70	<b>ALE</b>	<b>Address Latch Enable.</b> Used to de-multiplex the multiplexed Expanded Address/Data bus on Port 0. This pin is normally connected to the clock input on a '373 type transparent latch. When using a parallel programmer, this pin also assumes the $\overline{\text{PROG}}$ function for programming pulses.
73	<b><math>\overline{\text{EA}}</math></b>	<b>External Access.</b> This pin forces the DS5000FP to behave like an 8031. No internal memory (or clock) will be available when this pin is at a logic low. Since this pin is pulled down internally, it should be connected to +5V to use NV RAM. In a parallel programmer, this pin also serves as $V_{\text{pp}}$ for super voltage pulses.

**PIN DESCRIPTION (continued)**

PIN	NAME	FUNCTION
11, 9, 7, 5, 1, 79, 77, 75	<b>P0.0–P0.7</b>	<b>General-Purpose I/O Port 0.</b> This port is open-drain and cannot drive a logic 1. It requires external pullups. Port 0 is also the multiplexed Expanded Address/Data bus. When used in this mode, it does not require pullups.
13, 14	<b>V<sub>CC</sub></b>	<b>Power Supply, +5V</b>
16, 8, 18, 80, 76, 4, 6, 20, 24, 26, 28, 30, 33, 35, 37	<b>BA14– BA0</b>	<b>Byte-Wide Address Bus Bits 14–0.</b> This 15-bit bus is combined with the nonmultiplexed data bus (BD7–BD0) to access NV SRAM. Decoding is performed on $\overline{CE1}$ and $\overline{CE2}$ . Read/write access is controlled by $R/\overline{W}$ . BA14–BA0 connect directly to an 8k or 32k SRAM. If an 8k RAM is used, BA13 and BA14 are unconnected. Note: BA13 and BA14 are inverted from the true logical address. BA14 is lithium backed.
71, 69, 67, 65, 61, 59, 57, 55	<b>BD7–BD0</b>	<b>Byte-Wide Data Bus Bits 7–0.</b> This 8-bit bidirectional bus is combined with the nonmultiplexed address bus (BA14–BA0) to access NV SRAM. Decoding is performed on $\overline{CE1}$ and $\overline{CE2}$ . Read/write access is controlled by $R/\overline{W}$ . BD7–BD0 connect directly to an 8k or 32k SRAM, and optionally to a real-time clock.
10	<b><math>R/\overline{W}</math></b>	<b>Read/Write (Active Low).</b> This signal provides the write enable to the SRAMs on the byte-wide bus. It is controlled by the memory map and partition. The blocks selected as Program (ROM) is write protected.
74	<b><math>\overline{CE1}</math></b>	<b>Active-Low Chip Enable 1.</b> This is the primary decoded chip enable for memory access on the byte-wide bus. It connects to the chip enable input of one SRAM. $\overline{CE1}$ is lithium backed. It will remain in a logic high inactive state when $V_{CC}$ falls below $V_{LI}$ .
78	<b><math>\overline{CE2}</math></b>	<b>Active-Low Chip Enable 2.</b> This chip enable is provided to bank switch to a second block of 32k bytes of nonvolatile data memory. It connects to the chip enable input of one SRAM or one lithium-backed peripheral such a real-time clock. $\overline{CE2}$ is lithium backed. It will remain in a logic high inactive state when $V_{CC}$ falls below $V_{LI}$ .
12	<b>V<sub>CCO</sub></b>	<b>V<sub>CC</sub> Output.</b> This is switched between $V_{CC}$ and $V_{LI}$ by internal circuits based on the level of $V_{CC}$ . When power is above the lithium input, power will be drawn from $V_{CC}$ . The lithium cell remains isolated from a load. When $V_{CC}$ is below $V_{LI}$ , the $V_{CCO}$ switches to the $V_{LI}$ source. $V_{CCO}$ is connected to the $V_{CC}$ pin of an SRAM.
54	<b>V<sub>LI</sub></b>	<b>Lithium Voltage Input.</b> Connect to a lithium cell greater than $V_{LImin}$ and no greater than $V_{LImax}$ as shown in the electrical specifications. Nominal value is +3V.
2, 3, 22, 23, 32, 42, 43, 62, 63, 72	<b>N.C.</b>	<b>No Connection.</b> Do not connect.

## INSTRUCTION SET

The DS5000FP executes an instruction set that is object code compatible with the industry standard 8051 microcontroller. As a result, software development packages such as assemblers and compilers that have been written for the 8051 are compatible with the DS5000FP. A complete description of the instruction set and operation are provided in the *Secure Microcontroller User's Guide*.

Also note that the DS5000FP is embodied in the DS5000(T) and DS2250(T) modules. The DS5000(T) combines the DS5000FP with one SRAM of either 8 or 32 kbytes and a lithium cell. An optional Real Time Clock is also available in the DS5000T. This is packaged in a 40-pin DIP module. The DS2250(T) is an identical function in a SIMM form factor. It also offers the option of a second 32k SRAM mapped as data on Chip Enable 2.

## MEMORY ORGANIZATION

Figure 2 illustrates the memory map accessed by the DS5000FP. The entire 64k of program and 64k of data is available. The DS5000FP maps 32k of this space into the SRAM connected to the byte-wide bus. This is the area from 0000h to 7FFFh (32k) and is reached via  $\overline{CE1}$ . Any area not mapped into the NV RAM is reached via the Expanded bus on Ports 0 & 2. Selecting  $\overline{CE2}$  provides another 32k of potential data storage. When  $\overline{CE2}$  is used, no data is available on the ports. The memory map is covered in detail in the *Secure Microcontroller User's Guide*.

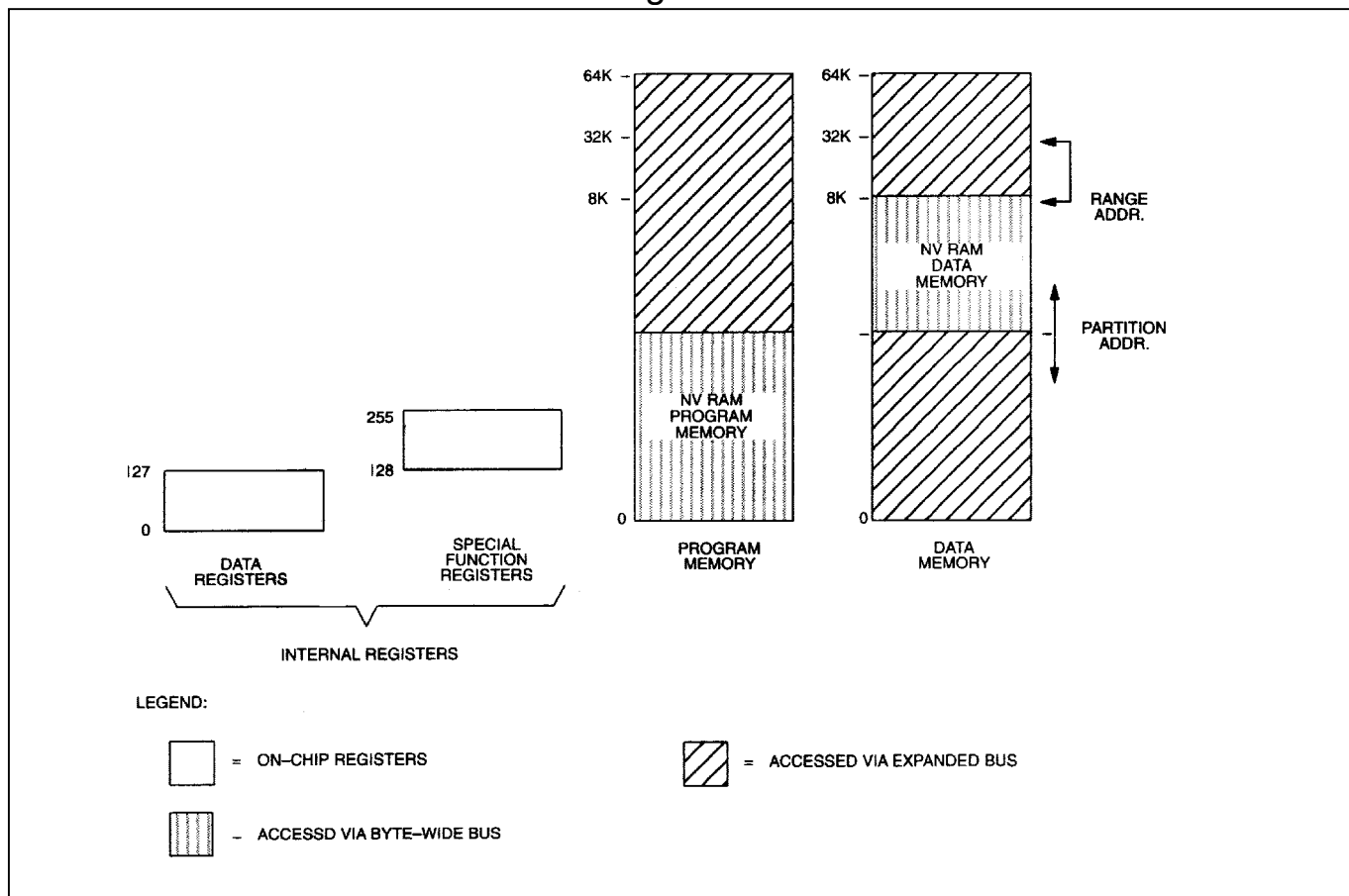
Figure 3 illustrates a typical memory connection for a system using 8k bytes of SRAM. Figure 4 shows a similar system with 32 kbytes. The byte-wide Address bus connects to the SRAM address lines. The bi-directional byte-wide data bus connects the data I/O lines of the SRAM.  $\overline{CE1}$  provides the chip enable and  $R/\overline{W}$  is the write enable. An additional RAM could be connected to  $\overline{CE2}$ , with common connections for  $R/\overline{W}$ , BA14-0, and BD7-0.

## POWER MANAGEMENT

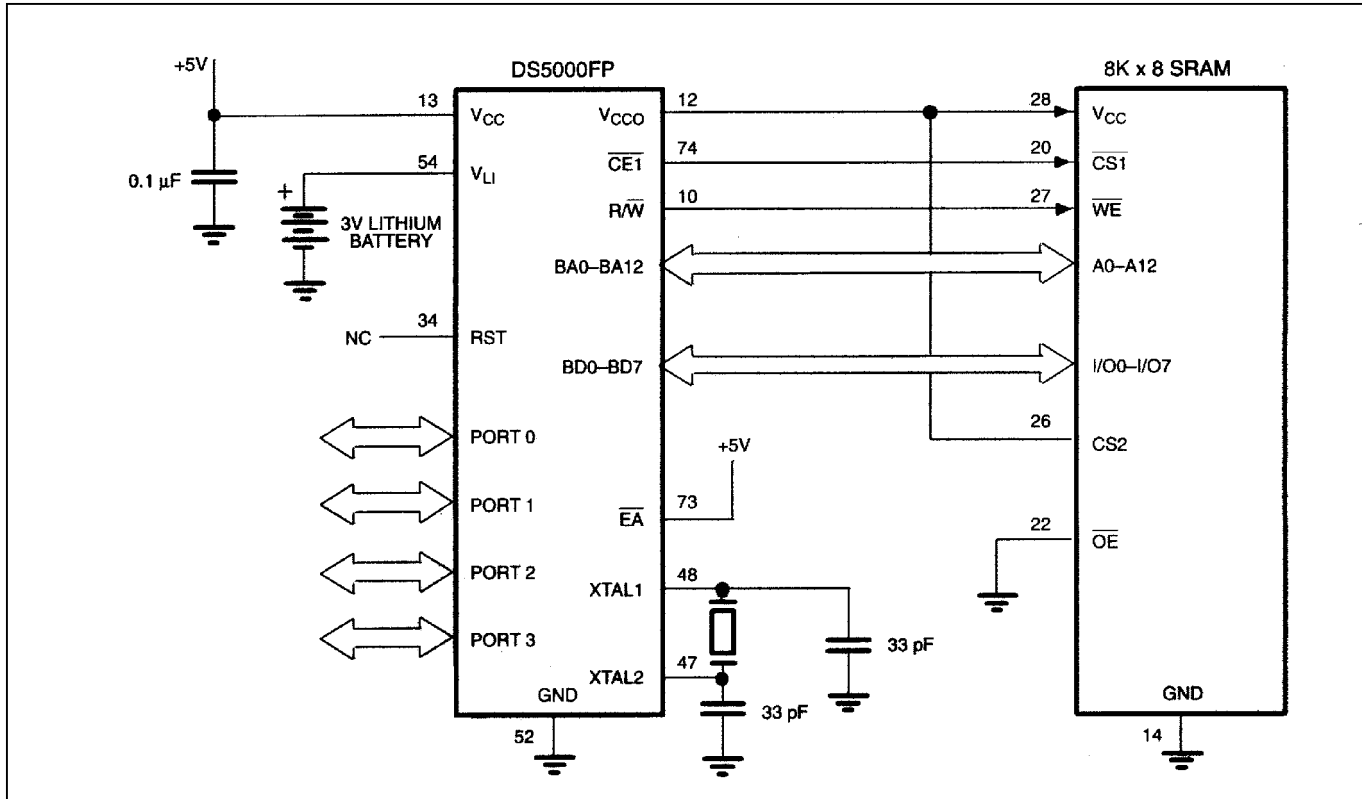
The DS5000FP monitors power to provide Power-Fail Reset, early warning Power-Fail Interrupt, and switchover to lithium backup. It uses the lithium cell at  $V_{LI}$  as a reference in determining the switch points. These are called  $V_{PFW}$ ,  $V_{CCMIN}$ , and  $V_{LI}$  respectively. When  $V_{CC}$  drops below  $V_{PFW}$ , the DS5000FP will perform an interrupt vector to location 2Bh if the power-fail warning was enabled. Full processor operation continues regardless. When power falls further to  $V_{CCMIN}$ , the DS5000FP invokes a reset state. No further code execution will be performed unless power rises back above  $V_{CCMIN}$ .  $\overline{CE1}$ ,  $\overline{CE2}$ ,  $R/\overline{W}$  go to an inactive (logic 1) state. Any address lines that are high (due to encryption) will follow  $V_{CC}$ , except for BA14, which is lithium backed.  $V_{CC}$  is still the power source at this time. When  $V_{CC}$  drops further to below  $V_{LI}$ , internal circuitry will switch to the lithium cell for power. The majority of internal circuits will be disabled and the remaining nonvolatile states will be retained. The lithium cell will power any devices connected to  $V_{CCO}$  at this time.  $V_{CCO}$  will be at the lithium battery voltage less a diode drop. This drop will vary depending on the load. Low-leakage SRAMs should be used for this reason. When a module is used, the lithium cell is selected by Dallas so absolute specifications are provided for the switch thresholds. When using the DS5000FP, the user must select the appropriate battery. The following formulas apply to the switch function:

$$\begin{aligned} V_{PFW} &= 1.45 \times V_{LI} \\ V_{CCMIN} &= 1.40 \times V_{LI} \\ V_{LI} \text{ Switch} &= 1.0 \times V_{LI} \end{aligned}$$

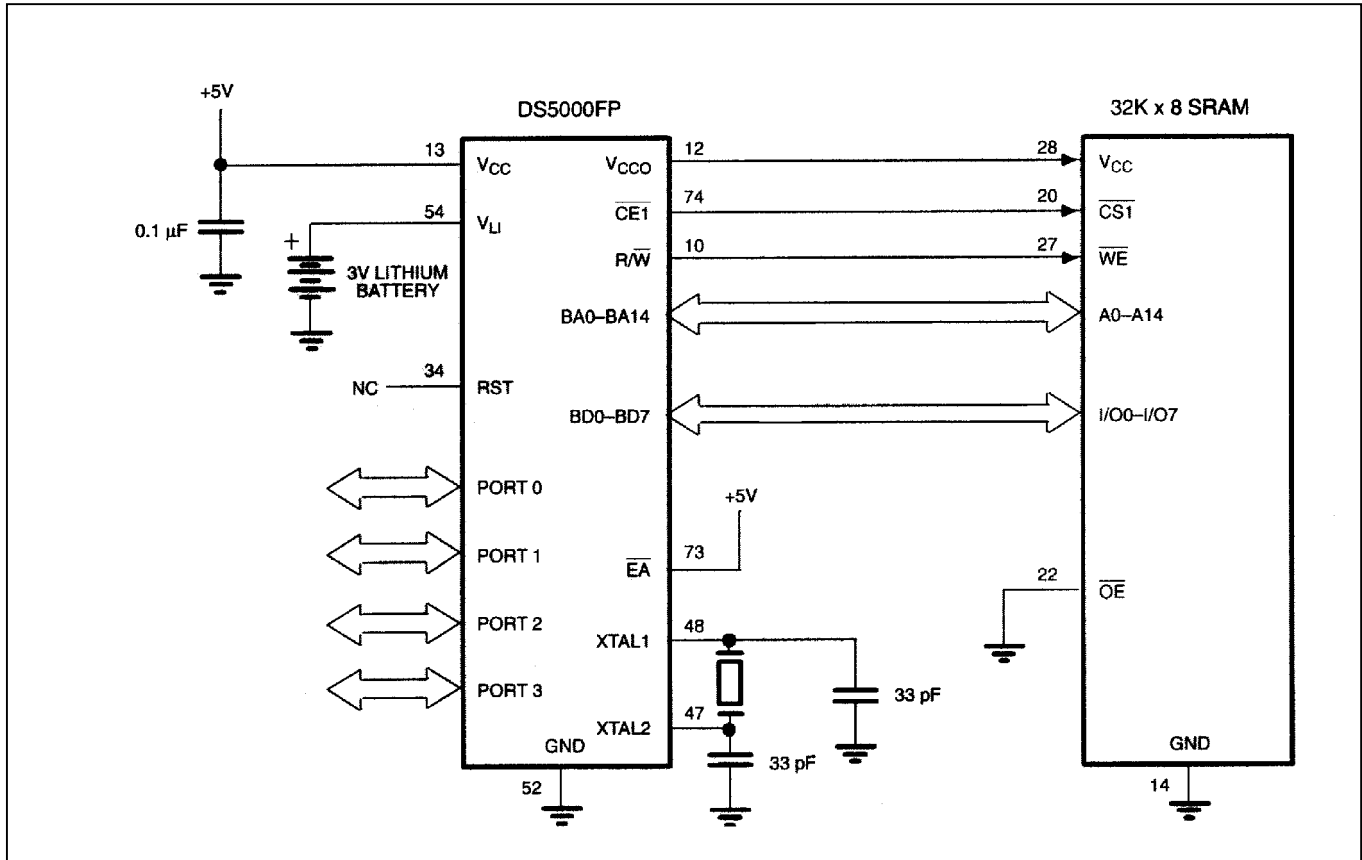
## MEMORY MAP OF THE DS5000FP Figure 2



**DS5000FP CONNECTION TO 8k X 8 SRAM Figure 3**



**DS5000FP CONNECTION TO 32k X 8 SRAM Figure 4**





## ABSOLUTE MAXIMUM RATINGS

Voltage Range on Any Pin Relative to Ground.....	-0.3V to + (V <sub>CC</sub> + 0.5V)
Voltage Range on V <sub>CC</sub> Relative to Ground.....	-0.3V to +7.0V
Operating Temperature Range.....	0°C to +70°C
Storage Temperature Range.....	-40°C to +70°C
Soldering Temperature Range.....	See IPC/JEDEC J-STD-020 Specification

*This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operation sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time can affect reliability.*

## DC CHARACTERISTICS

(V<sub>CC</sub> = 5V ±5%, T<sub>A</sub> = 0°C to +70°C.)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Input Low Voltage	V <sub>IL</sub>	-0.3		0.8	V	1
Input High Voltage	V <sub>IH1</sub>	2.0		V <sub>CC</sub> + 0.3	V	1
Input High Voltage RST, XTAL1	V <sub>IH2</sub>	3.5		V <sub>CC</sub> + 0.3	V	1
Output Low Voltage at I <sub>OL</sub> = 1.6mA (Ports 1, 2, 3)	V <sub>OL1</sub>		0.15	0.45	V	
Output Low Voltage at I <sub>OL</sub> = 3.2mA (Ports 0, ALE, $\overline{\text{PSEN}}$ , BA14–BA0, BD7–BD0, R/ $\overline{\text{W}}$ , $\overline{\text{CE}}$ 1-2)	V <sub>OL2</sub>		0.15	0.45	V	1
Output High Voltage at I <sub>OH</sub> = -80μA (Ports 1, 2, 3)	V <sub>OH1</sub>	2.4	4.8		V	1
Output High Voltage at I <sub>OH</sub> = -400μA (Ports 0, ALE, $\overline{\text{PSEN}}$ , BA14–BA0, BD7–BD0, R/ $\overline{\text{W}}$ , $\overline{\text{CE}}$ 1-2)	V <sub>OH2</sub>	2.4	4.8		V	1
Input Low Current V <sub>IN</sub> = 0.45V (Ports 1, 2, 3)	I <sub>IL</sub>			-50	μA	
Transition Current; 1 to 0 V <sub>IN</sub> = 2.0V (Ports 1, 2, 3)	I <sub>TL</sub>			-500	μA	
Input Leakage Current 0.45 < V <sub>IN</sub> < V <sub>CC</sub> (Port 0)	I <sub>L</sub>			±10	μA	
RST, $\overline{\text{EA}}$ Pulldown Resistor	R <sub>RE</sub>	40		125	kΩ	
Stop Mode Current	I <sub>SM</sub>			80	μA	4
Power-Fail Warning Voltage	V <sub>PFW</sub>	4.15	4.6	4.75	V	1, 6
Minimum Operating Voltage	V <sub>CCmin</sub>	4.05	4.5	4.65	V	1, 6
Operating Voltage	V <sub>CC</sub>	V <sub>CC(MIN)</sub>		5.5	V	1, 6
Lithium Supply Voltage	V <sub>LI</sub>	2.9		3.3	V	1
Programming Supply Voltage (Parallel Program Mode)	V <sub>PP</sub>	12.5		13	V	1
Program Supply Current	I <sub>PP</sub>		15	20	mA	

**DC CHARACTERISTICS (continued)**(V<sub>CC</sub> = 5V ±5%, T<sub>A</sub> = 0°C to +70°C.)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Operating Current at 16MHz	I <sub>CC</sub>			36	mA	2
Idle Mode Current at 12MHz	I <sub>IDLE</sub>			6.2	mA	3
Output Supply Voltage	V <sub>CCO1</sub>	V <sub>CC</sub> - 0.3			V	1
Output Supply Voltage (Battery-Backed Mode)	V <sub>CCO2</sub>	V <sub>LI</sub> - 0.65	V <sub>LI</sub> - 0.5		V	8
Output Supply Current at V <sub>CCO</sub> = V <sub>CC</sub> - 0.3V	I <sub>CCO1</sub>		80		mA	2
Battery-Backed Quiescent Current	I <sub>LI</sub>		5	75	nA	7

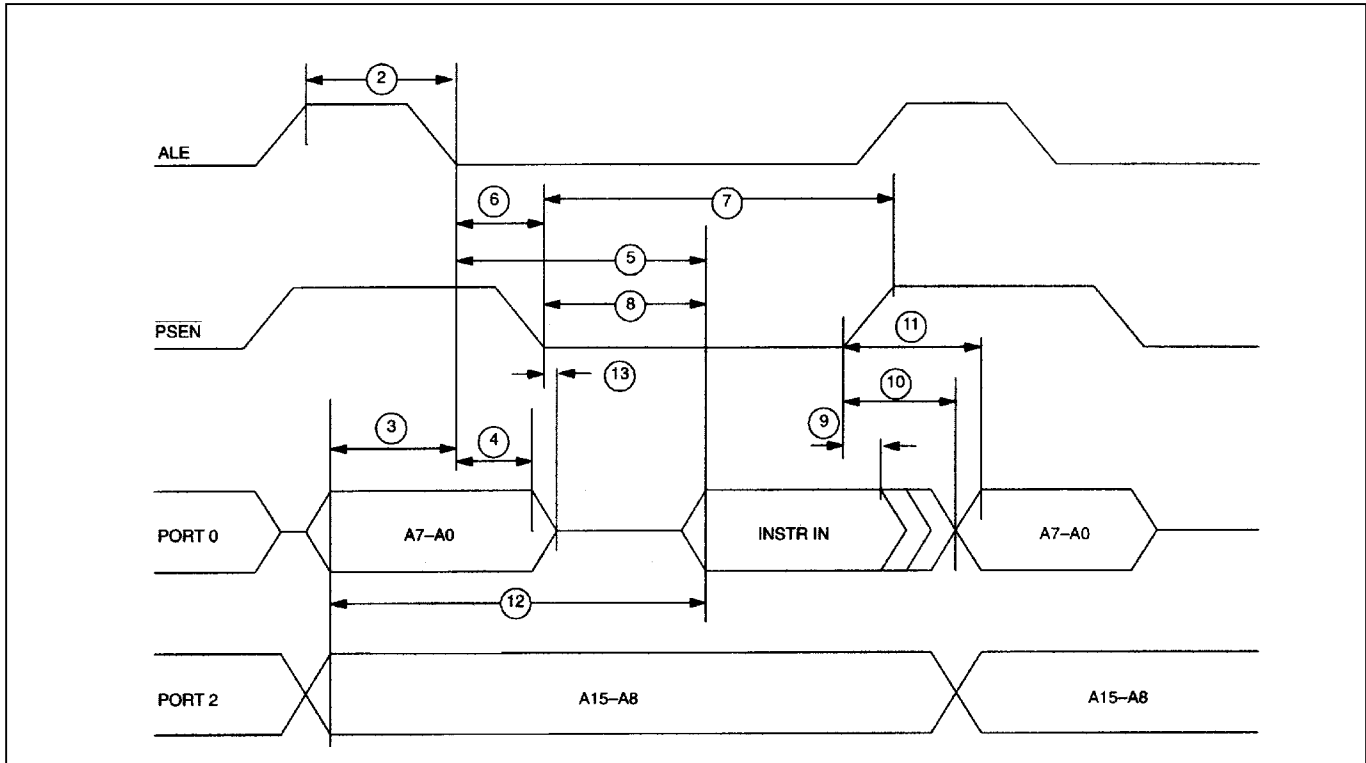
**NOTES:**

- All voltages are referenced to ground.
- Maximum operating I<sub>CC</sub> is measured with all output pins disconnected; XTAL1 driven with t<sub>CLKR</sub>, t<sub>CLKF</sub> = 10ns, V<sub>IL</sub> = 0.5V; XTAL2 disconnected;  $\overline{EA}$  = RST = PORT0 = V<sub>CC</sub>.
- Idle mode I<sub>CC</sub> is measured with all output pins disconnected; XTAL1 driven at 12MHz with t<sub>CLKR</sub>, t<sub>CLKF</sub> = 10ns, V<sub>IL</sub> = 0.5V; XTAL2 disconnected;  $\overline{EA}$  = PORT0 = V<sub>CC</sub>, RST = V<sub>SS</sub>.
- Stop mode I<sub>CC</sub> is measured with all output pins disconnected;  $\overline{EA}$  = PORT0 = V<sub>CC</sub>; XTAL2 not connected; RST = V<sub>SS</sub>.
- Crystal startup time is the time required to get the mass of the crystal into vibrational motion from the time that power is first applied to the circuit until the first clock pulse is produced by the on-chip oscillator. The user should check with the crystal vendor for the worst-case spec on this time.
- Assumes V<sub>LI</sub> = 3.3V maximum.
- I<sub>LI</sub> is the current drawn from V<sub>LI</sub> when V<sub>CC</sub> = 0V and V<sub>CCO</sub> is disconnected.
- I<sub>CCO</sub> = 10μA.

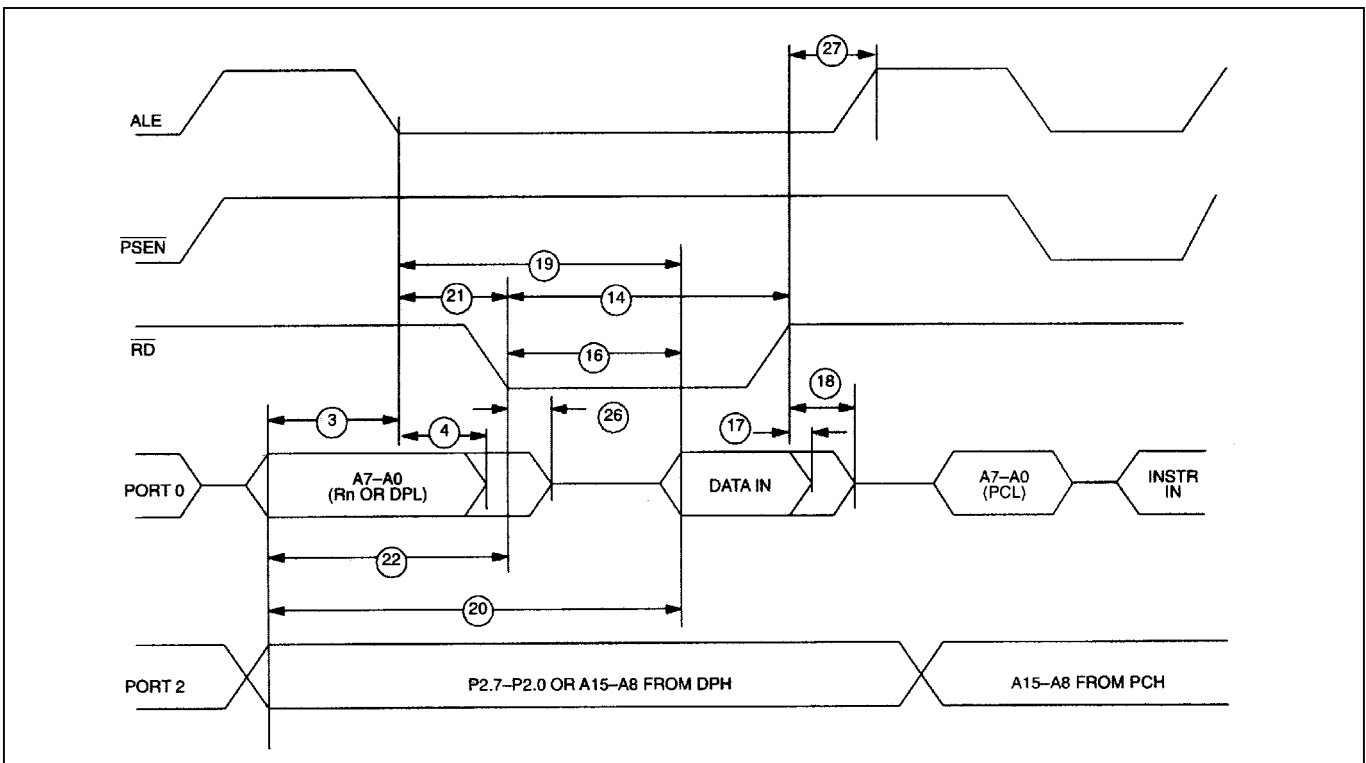
**AC CHARACTERISTICS: EXPANDED BUS MODE TIMING SPECIFICATIONS**(V<sub>CC</sub> = 5V ±5%, T<sub>A</sub> = 0°C to +70°C.)

#	PARAMETER	SYMBOL	MIN	MAX	UNITS
1	Oscillator Frequency	1/t <sub>CLK</sub>	1.0	16	MHz
2	ALE Pulse Width	t <sub>ALPW</sub>	2t <sub>CLK</sub> -40		ns
3	Address Valid to ALE Low	t <sub>AVALL</sub>	t <sub>CLK</sub> -40		ns
4	Address Hold After ALE Low	t <sub>AVAAV</sub>	t <sub>CLK</sub> -35		ns
5	ALE Low to Valid Instruction In	t <sub>ALLVI</sub>	at 12MHz	4t <sub>CLK</sub> -150	ns
			at 16MHz	4t <sub>CLK</sub> -90	
6	ALE Low to $\overline{\text{PSEN}}$ Low	t <sub>ALLPSL</sub>	t <sub>CLK</sub> -25		ns
7	$\overline{\text{PSEN}}$ Pulse Width	t <sub>PSPW</sub>	3t <sub>CLK</sub> -35		ns
8	$\overline{\text{PSEN}}$ Low to Valid Instruction In	t <sub>PSLVI</sub>	at 12MHz	3t <sub>CLK</sub> -150	ns
			at 16MHz	3t <sub>CLK</sub> -90	
9	Input Instruction Hold after $\overline{\text{PSEN}}$ Going High	t <sub>PSIV</sub>	0		ns
10	Input Instruction Float after $\overline{\text{PSEN}}$ Going High	t <sub>PSIX</sub>		t <sub>CLK</sub> -20	ns
11	Address Hold after $\overline{\text{PSEN}}$ Going High	t <sub>PSAV</sub>	t <sub>CLK</sub> -8		ns
12	Address Valid to Valid Instruction In	t <sub>AVVI</sub>	at 12MHz	5t <sub>CLK</sub> -150	ns
			at 16MHz	5t <sub>CLK</sub> -90	
13	$\overline{\text{PSEN}}$ Low to Address Float	t <sub>PSLAZ</sub>	0		ns
14	$\overline{\text{RD}}$ Pulse Width	t <sub>RDPW</sub>	6t <sub>CLK</sub> -100		ns
15	$\overline{\text{WR}}$ Pulse Width	t <sub>WRPW</sub>	6t <sub>CLK</sub> -100		ns
16	$\overline{\text{RD}}$ Low to Valid Data In	t <sub>RDLDV</sub>	at 12MHz	5t <sub>CLK</sub> -165	ns
			at 16MHz	5t <sub>CLK</sub> -105	
17	Data Hold after $\overline{\text{RD}}$ High	t <sub>RDHDV</sub>	0		ns
18	Data Float after $\overline{\text{RD}}$ High	t <sub>RDHDZ</sub>		2t <sub>CLK</sub> -70	ns
19	ALE Low to Valid Data In	t <sub>ALLVD</sub>	at 12MHz	8t <sub>CLK</sub> -150	ns
			at 16MHz	8t <sub>CLK</sub> -90	
20	Valid Address to Valid Data In	t <sub>AVDV</sub>	at 12MHz	9t <sub>CLK</sub> -165	ns
			at 16MHz	9t <sub>CLK</sub> -105	
21	ALE Low to $\overline{\text{RD}}$ or $\overline{\text{WR}}$ Low	t <sub>ALLRDL</sub>	3t <sub>CLK</sub> -50	3t <sub>CLK</sub> +50	ns
22	Address Valid to $\overline{\text{RD}}$ or $\overline{\text{WR}}$ Low	t <sub>AVRDL</sub>	4t <sub>CLK</sub> -130		ns
23	Data Valid to $\overline{\text{WR}}$ Going Low	t <sub>DVWRL</sub>	t <sub>CLK</sub> -60		ns
24	Data Valid to $\overline{\text{WR}}$ High	t <sub>DVWRH</sub>	at 12MHz	7t <sub>CLK</sub> -150	ns
			at 16MHz	7t <sub>CLK</sub> -90	
25	Data Valid after $\overline{\text{WR}}$ High	t <sub>WRHDV</sub>	t <sub>CLK</sub> -50		ns
26	$\overline{\text{RD}}$ Low to Address Float	t <sub>RDLAZ</sub>		0	ns
27	$\overline{\text{RD}}$ or $\overline{\text{WR}}$ High to ALE High	t <sub>RDHALH</sub>	t <sub>CLK</sub> -40	t <sub>CLK</sub> +50	ns

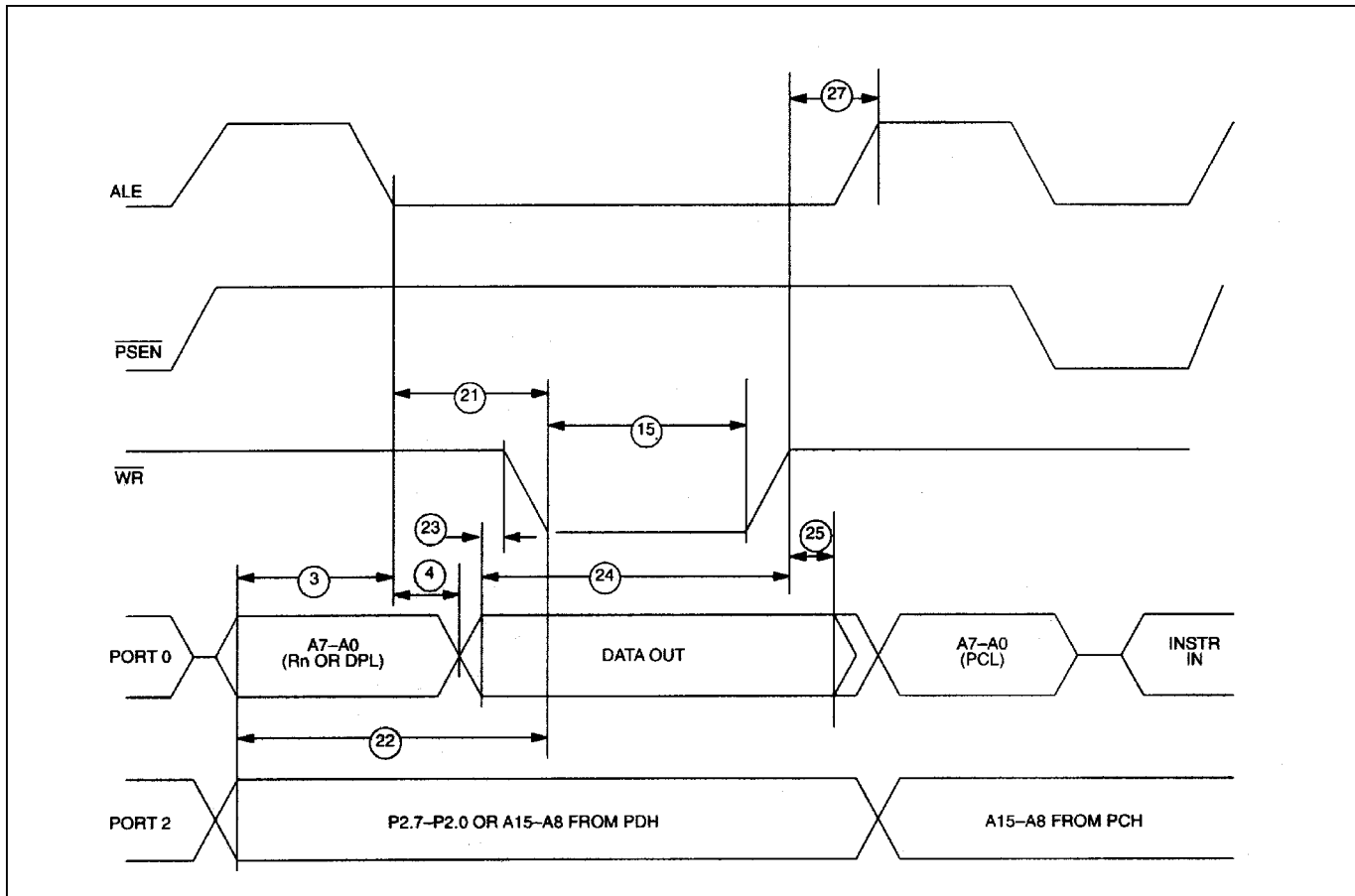
## EXPANDED PROGRAM MEMORY READ CYCLE



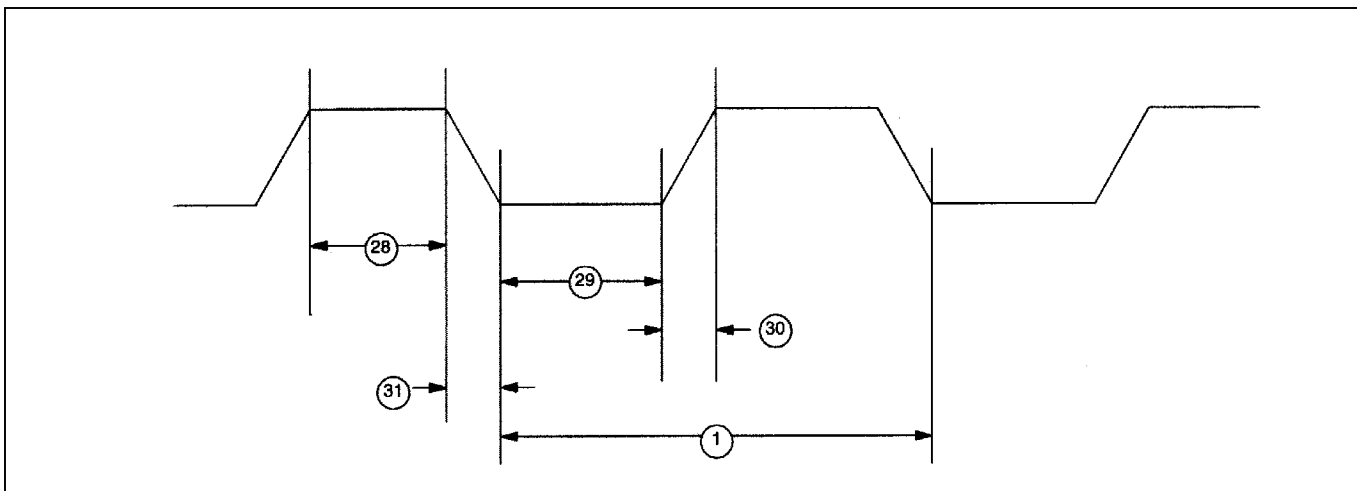
## EXPANDED DATA MEMORY READ CYCLE



## EXPANDED DATA MEMORY WRITE CYCLE



## EXTERNAL CLOCK TIMING



## AC CHARACTERISTICS: EXTERNAL CLOCK DRIVE

( $V_{CC} = 5V \pm 5\%$ ,  $T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ .)

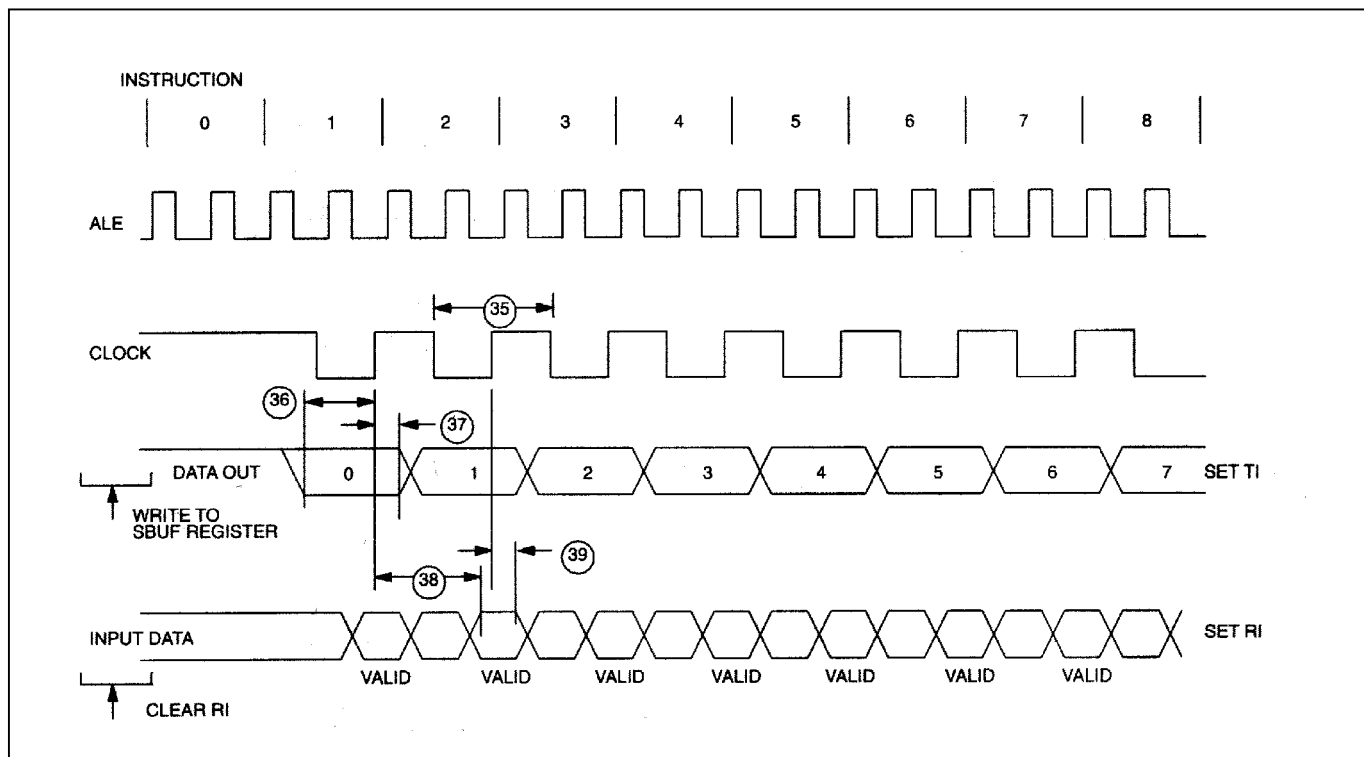
#	PARAMETER	SYMBOL	MIN	MAX	UNITS
28	External Clock High Time	$t_{CLKHPW}$	at 12MHz	20	ns
			at 16MHz	15	
29	External Clock Low Time	$t_{CLKLPW}$	at 12MHz	20	ns
			at 16MHz	15	
30	External Clock Rise Time	$t_{CLKR}$	at 12MHz	20	ns
			at 16MHz	15	
31	External Clock Fall Time	$t_{CLKF}$	at 12MHz	20	ns
			at 16MHz	15	

## AC CHARACTERISTICS: SERIAL PORT TIMING—MODE 0

( $V_{CC} = 5V \pm 5\%$ ,  $T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ .)

#	PARAMETER	SYMBOL	MIN	MAX	UNITS
35	Serial Port Cycle Time	$t_{SPCLK}$	$12t_{CLK}$		$\mu\text{s}$
36	Output Data Setup to Rising Clock Edge	$t_{DOCH}$	$10t_{CLK} - 133$		ns
37	Output Data Hold after Rising Clock Edge	$t_{CHDO}$	$2t_{CLK} - 117$		ns
38	Clock Rising Edge to Input Data Valid	$t_{CHDV}$		$10t_{CLK} - 133$	ns
39	Input Data Hold after Rising Clock Edge	$t_{CHDIV}$	0		ns

## SERIAL PORT TIMING—MODE 0

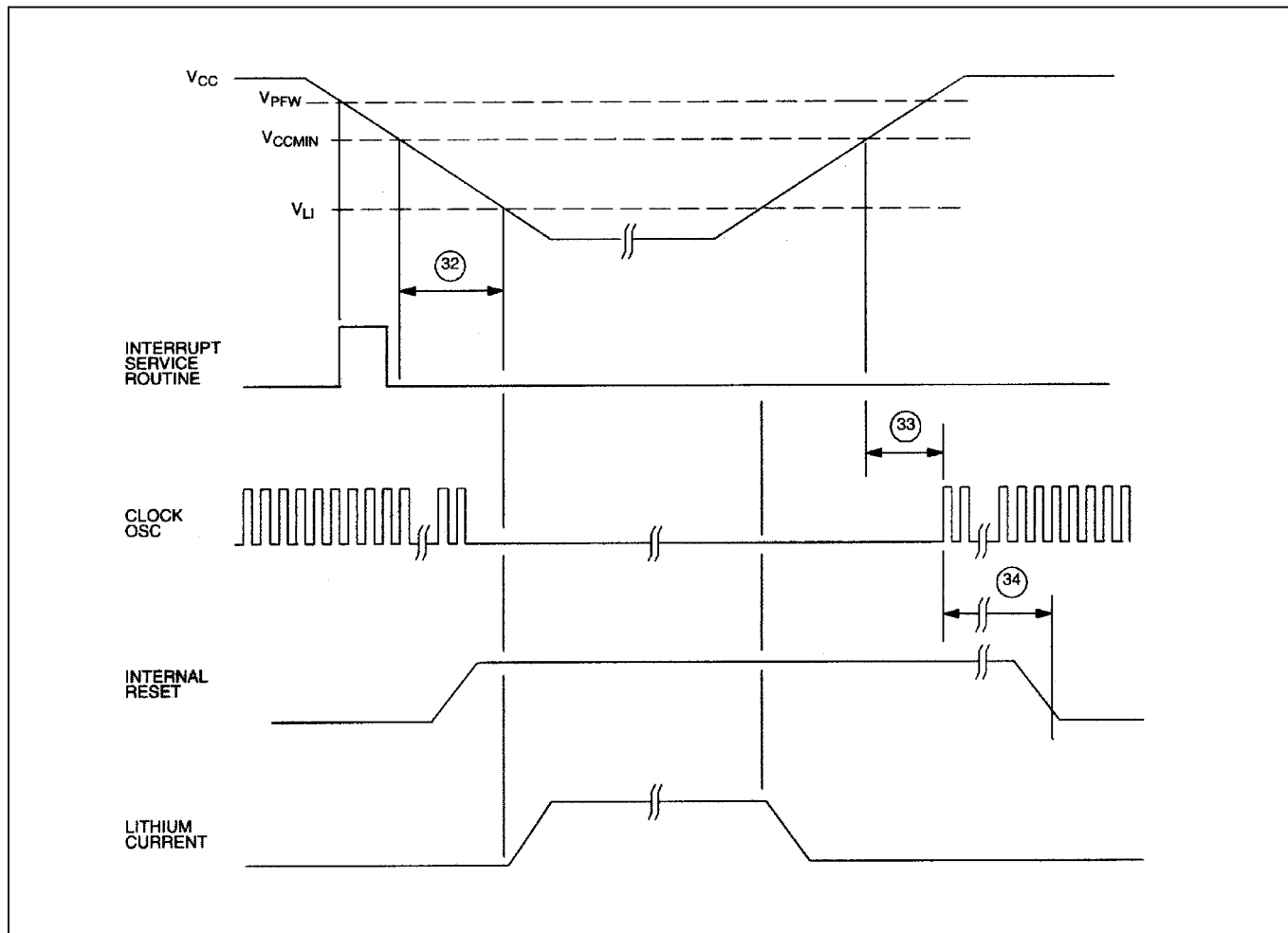


## AC CHARACTERISTICS: POWER CYCLE TIMING

( $V_{CC} = 5V \pm 5\%$ ,  $T_A = 0^\circ\text{C}$  to  $+70^\circ\text{C}$ .)

#	PARAMETER	SYMBOL	MIN	MAX	UNITS
32	Slew Rate from $V_{CCmin}$ to $V_{LImax}$	$t_F$	40		$\mu\text{s}$
33	Crystal Startup Time	$t_{CSU}$		(Note 5)	
34	Power-On Reset Delay	$t_{POR}$		21,504	$t_{CLK}$

### POWER CYCLE TIMING



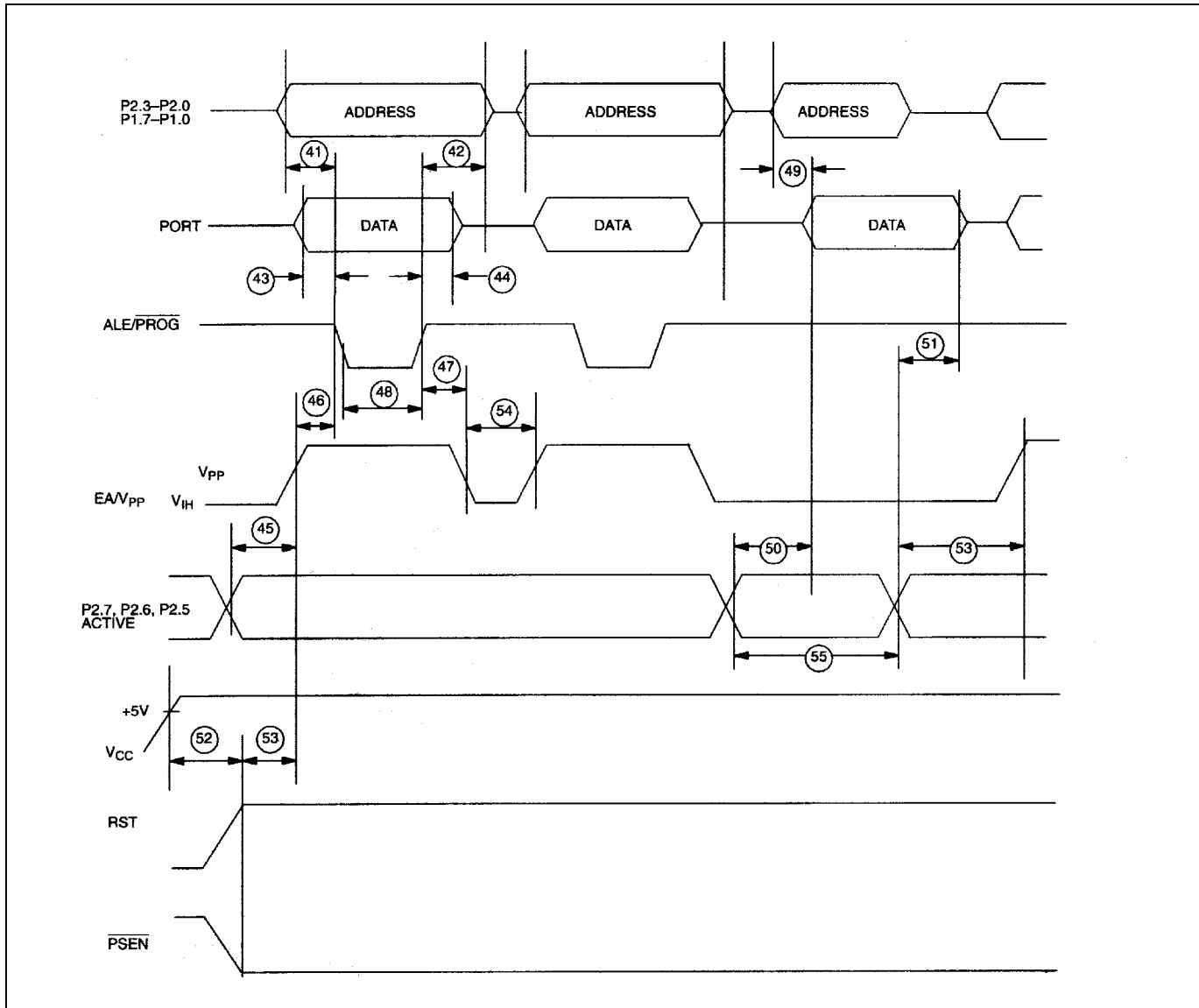
**AC CHARACTERISTICS: PARALLEL PROGRAM LOAD TIMING**(V<sub>CC</sub> = 5V ±5%, T<sub>A</sub> = 0°C to +70°C.)

#	PARAMETER	SYMBOL	MIN	MAX	UNITS
40	Oscillator Frequency	1/t <sub>CLK</sub>	1.0	12.0	MHz
41	Address Setup to $\overline{\text{PROG}}$ Low	t <sub>AVPRL</sub>	0		
42	Address Hold after $\overline{\text{PROG}}$ High	t <sub>PRHAV</sub>	0		
43	Data Setup to $\overline{\text{PROG}}$ Low	t <sub>DVPRL</sub>	0		
44	Data Hold after $\overline{\text{PROG}}$ High	t <sub>PRHDV</sub>	0		
45	P2.7, 2.6, 2.5 Setup to V <sub>PP</sub>	t <sub>P27HVP</sub>	0		
46	V <sub>PP</sub> Setup to $\overline{\text{PROG}}$ Low	t <sub>VPPRL</sub>	0		
47	V <sub>PP</sub> Hold after $\overline{\text{PROG}}$ Low	t <sub>PRHVPL</sub>	0		
48	$\overline{\text{PROG}}$ Width Low	t <sub>PRW</sub>	2400		t <sub>CLK</sub>
49	Data Output from Address Valid	t <sub>AVDV</sub>		48 (1800*)	t <sub>CLK</sub>
50	Data Output from P2.7 Low	t <sub>DVP27L</sub>		48 (1800*)	t <sub>CLK</sub>
51	Data Float after P2.7 High	t <sub>P27HDZ</sub>	0	48 (1800*)	t <sub>CLK</sub>
52	Delay to Reset/ $\overline{\text{PSEN}}$ Active after Power-On	t <sub>PORPV</sub>	21,504		t <sub>CLK</sub>
53	Reset/ $\overline{\text{PSEN}}$ Active (or Verify Inactive) to V <sub>PP</sub> High	t <sub>RAVPH</sub>	1200		t <sub>CLK</sub>
54	V <sub>PP</sub> Inactive (Between Program Cycles)	t <sub>VPPPC</sub>	1200		t <sub>CLK</sub>
55	Verify Active Time	t <sub>VFT</sub>		48 (2400*)	t <sub>CLK</sub>

\*Second set of numbers refers to expanded memory programming up to 32kBytes.



## PARALLEL PROGRAM LOAD TIMING



## CAPACITANCE

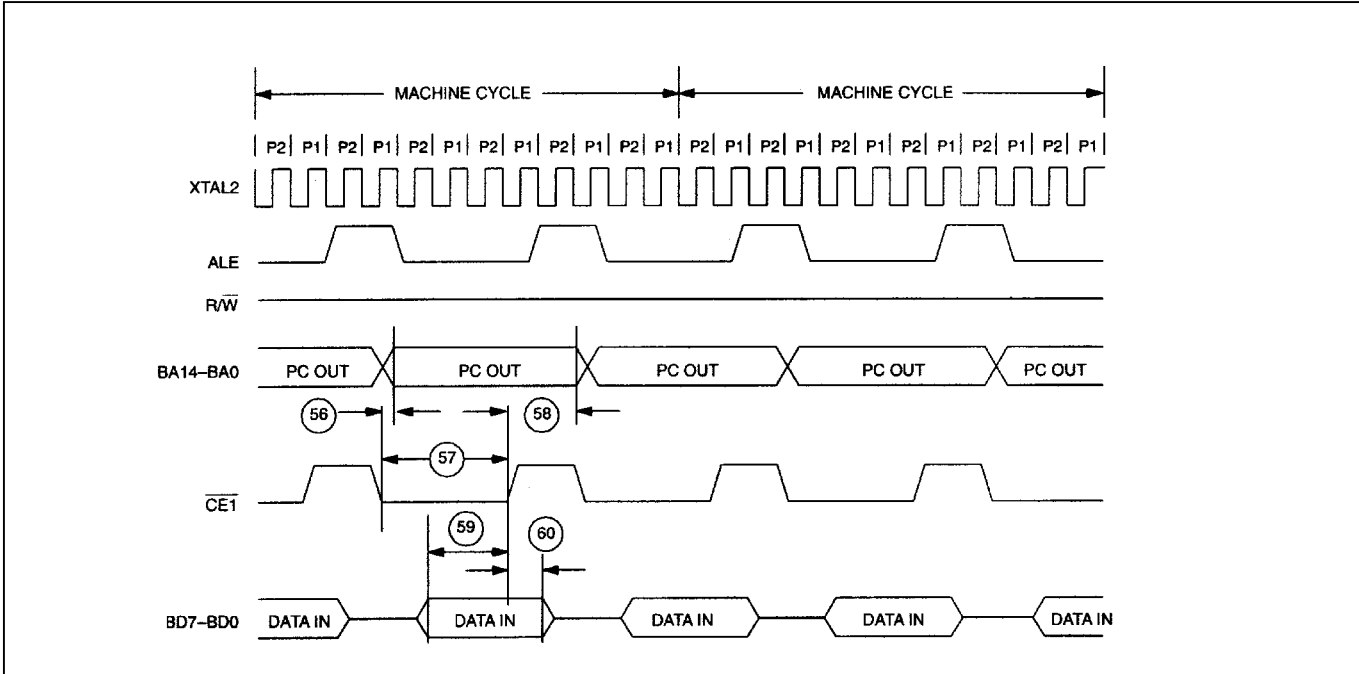
(T<sub>A</sub> = +25°C, Test Frequency = 1MHz.)

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	NOTES
Output Capacitance	C <sub>O</sub>			10	pF	
Input Capacitance	C <sub>I</sub>			10	pF	

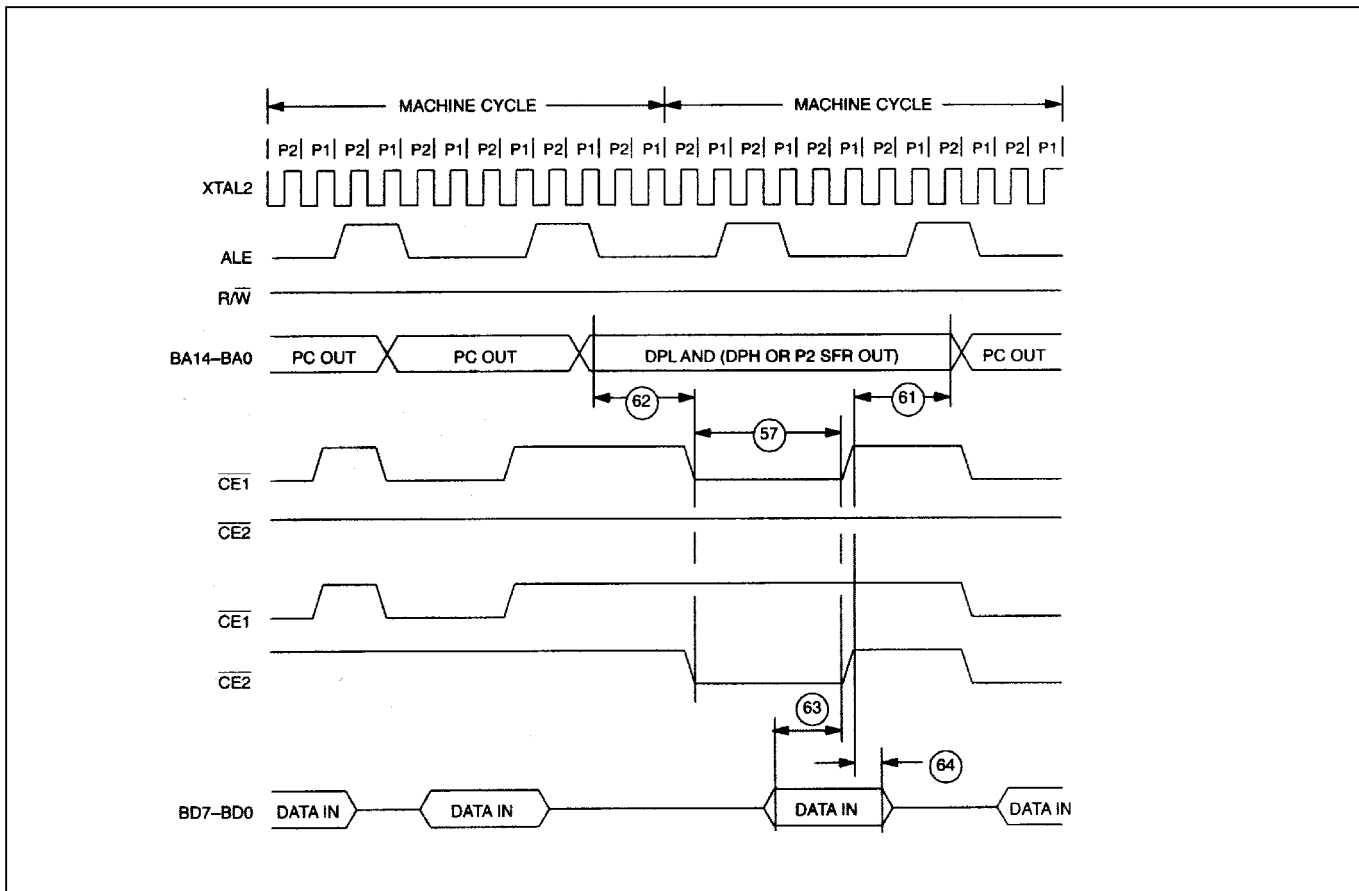
**AC CHARACTERISTICS: BYTE-WIDE ADDRESS/DATA BUS TIMING**(V<sub>CC</sub> = 5V ±5%, T<sub>A</sub> = 0°C to +70°C.)

#	PARAMETER	SYMBOL	MIN	MAX	UNITS
56	Delay to Embedded Address Valid from $\overline{\text{CE1}}$ Low During Opcode Fetch	t <sub>CE1LPA</sub>		20	ns
57	$\overline{\text{CE1}}$ or $\overline{\text{CE2}}$ Pulse Width	t <sub>CEPW</sub>	4t <sub>CLK</sub> -15		ns
58	Embedded Address Hold after $\overline{\text{CE1}}$ High During Opcode Fetch	t <sub>CE1HPA</sub>	2t <sub>CLK</sub> -20		ns
59	Embedded Data Setup to $\overline{\text{CE1}}$ High During Opcode Fetch	t <sub>OVCE1H</sub>	1t <sub>CLK</sub> +40		ns
60	Embedded Data Hold after $\overline{\text{CE1}}$ High During Opcode Fetch	t <sub>CE1HOV</sub>	10		ns
61	Embedded Address Hold after $\overline{\text{CE1}}$ or $\overline{\text{CE2}}$ High During MOVX	t <sub>CEHDA</sub>	4t <sub>CLK</sub> -30		ns
62	Delay from Embedded Address Valid to $\overline{\text{CE1}}$ or $\overline{\text{CE2}}$ Low During MOVX	t <sub>CELDA</sub>	4t <sub>CLK</sub> -25		ns
63	Embedded Data Hold Setup to $\overline{\text{CE1}}$ or $\overline{\text{CE2}}$ High During MOVX (Read)	t <sub>DACEH</sub>	1t <sub>CLK</sub> +40		ns
64	Embedded Data Hold after $\overline{\text{CE1}}$ or $\overline{\text{CE2}}$ High During MOVX (Read)	t <sub>CEHdv</sub>	10		ns
65	Embedded Address Valid to R/ $\overline{\text{W}}$ Active During MOVX (Write)	t <sub>AVRWL</sub>	3t <sub>CLK</sub> -35		ns
66	Delay from R/ $\overline{\text{W}}$ Low to Valid Data Out During MOVX (Write)	t <sub>RWLDV</sub>	20		ns
67	Valid Data Out Hold Time from $\overline{\text{CE1}}$ or $\overline{\text{CE2}}$ High	t <sub>CEHdv</sub>	1t <sub>CLK</sub> -15		ns
68	Valid Data Out Hold Time from R/ $\overline{\text{W}}$ High	t <sub>RWHDV</sub>	0		ns
69	Write Pulse Width (R/ $\overline{\text{W}}$ Low Time)	t <sub>RWLPW</sub>	6t <sub>CLK</sub> -20		ns

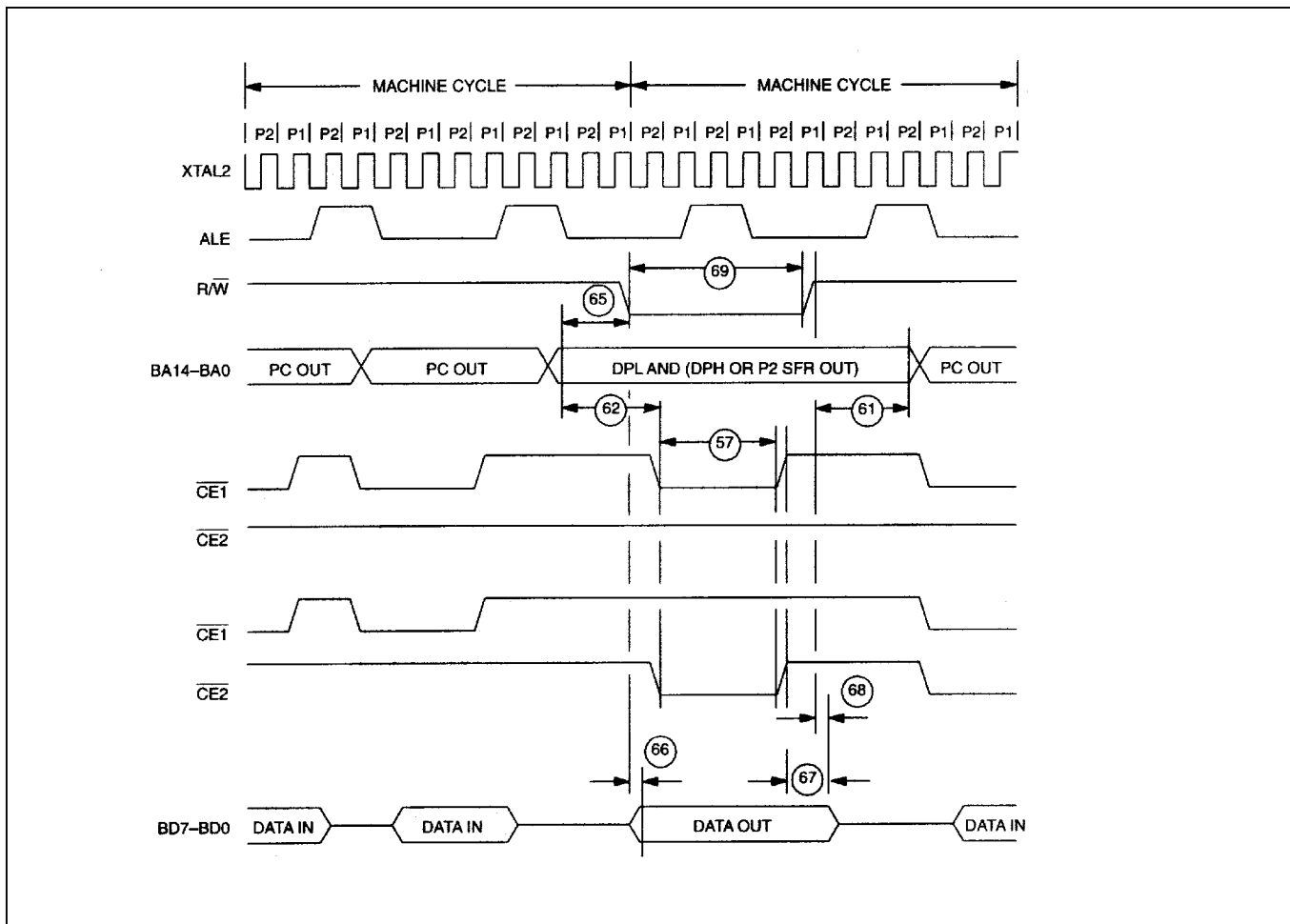
## BYTE-WIDE ADDRESS/DATA BUS OPCODE FETCH CYCLE



## BYTE-WIDE ADDRESS/DATA BUS OPCODE FETCH WITH DATA MEMORY READ



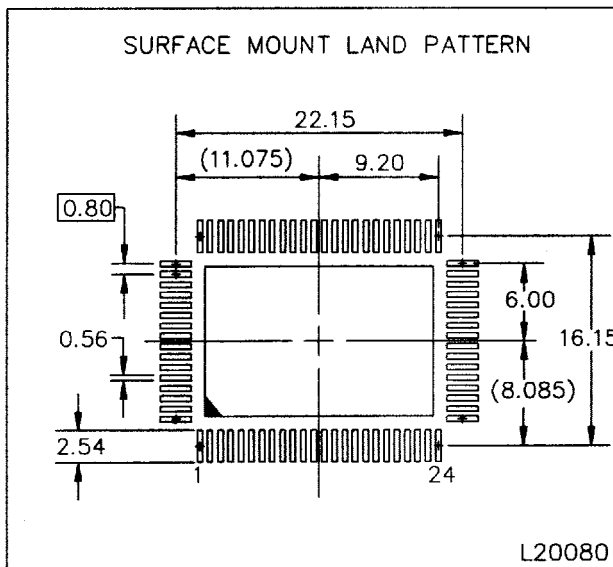
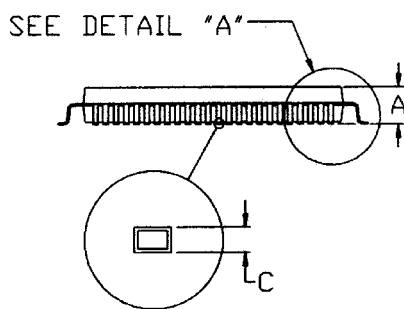
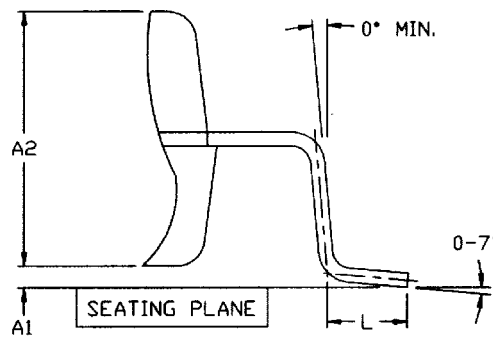
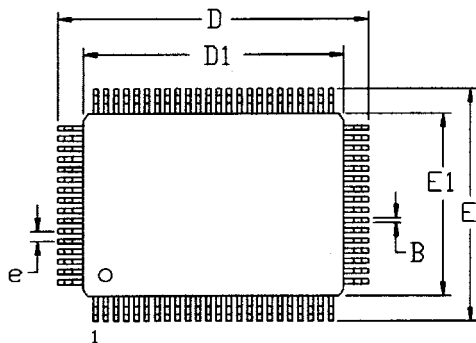
## BYTE-WIDE ADDRESS/DATA BUS OPCODE FETCH WITH DATA MEMORY WRITE



# PACKAGE INFORMATION

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to [www.maxim-ic.com/DallasPackInfo](http://www.maxim-ic.com/DallasPackInfo).)

56-G4005-001



DIM	MILLIMETERS	
	MIN	MAX
A	-	3.15
A1	0.25	-
A2	2.55	2.87
B	0.30	0.50
C	0.13	0.23
D	23.70	24.10
D1	19.90	20.10
E	17.40	18.10
E1	13.90	14.10
E	0.80 BSC	
L	0.65	0.95

**REVISION HISTORY**

<b>DATE</b>	<b>DESCRIPTION</b>
070605	<ol style="list-style-type: none"><li>1) Added Pb-free part to Ordering Information table.</li><li>2) Added operating voltage specification. (This is not a new specification because operating voltage is implied in the testing limits, but rather a clarification.)</li><li>3) Updated Absolute Maximum Ratings soldering temperature to reference JEDEC standard.</li><li>4) Added voltage rang on <math>V_{CC}</math> relative to ground specification to Absolute Maximums.</li><li>5) Changed “Secure Microcontroller Data Book” references to “Secure Microcontroller User’s Guide.”</li></ol>