### **Freescale Semiconductor**

Data Sheet: Technical Data

Document Number: MC9S08QA4 Rev. 3, 1/2009

8-Pin NB-SOIC

Case 751-07

# MC9S08QA4

# MC9S08QA4 Series

#### Covers: **MC9S08QA4 MC9S08QA2**

#### Features:

- 8-bit HCS08 Central Processor Unit (CPU)
  - Up to 20 MHz CPU at 3.6 V to 1.8 V across temperature range of -40°C to 85°C
  - HC08 instruction set with added BGND instruction
  - Support for up to 32 interrupt/reset sources
- On-Chip Memory
  - Flash read/program/erase over full operating voltage and temperature
  - Random-access memory (RAM)
  - Security circuitry to prevent unauthorized access to RAM and flash contents
- Power-Saving Modes
  - Two very low power stop modes
  - Peripheral clock enable register can disable clocks to unused modules, thereby reducing currents
  - Very low power real time counter for use in run, wait, and stop modes with internal clock sources
- Clock Source Options
  - Internal Clock Source (ICS) Internal clock source module containing a frequency-locked-loop (FLL) controlled by internal reference; precision trimming of internal reference allows 0.2% resolution and 2% deviation over temperature and voltage; supports bus frequencies from 1 MHz to 10 MHz
- System Protection
  - Watchdog computer operating properly (COP) reset with option to run from dedicated 1 kHz internal clock source or bus clock
  - Low-voltage detection with reset or interrupt
  - Selectable trip points
  - Illegal opcode detection with reset
  - Illegal address detection with reset
  - Flash block protection
- Development Support
  - Single-wire background debug interface



8-Pin PDIP Case 626-06

- Breakpoint capability to allow single breakpoint setting during in-circuit debugging
- · Peripherals
  - ADC 4-channel, 10-bit resolution; 1.7 mV/°C temperature sensor; automatic compare function; internal bandgap reference channel; operation in stop3; fully functional from 3.6 V to 1.8 V
  - ACMP Analog comparator with selectable interrupt on rising, falling, or either edge of comparator output; compare option to fixed internal bandgap reference voltage; output can be tied internally to TPM input capture
  - TPM One 1-channel timer/pulse-width modulator (TPM) module; selectable input capture, output compare, or buffered edge- or center-aligned PWM on each channel; ACMP output can be tied internally to input capture
  - MTIM 8-bit modulo timer module with 8-bit prescaler
  - KBI 4-pin keyboard interrupt module with software selectable polarity on edge or edge/level modes
- Input/Output
  - Four GPIOs, one input-only pin and one output-only pin.
  - Hysteresis and configurable pullup device on all input pins; configurable slew rate and drive strength on all output pins except PTA5
- Package Options
  - 8-pin SOIC, PDIP, and DFN

This document contains information on a product under development. Freescale reserves the right to change or discontinue this product without notice.

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8-Pin DFN Case 1452-02

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# **Revision History**

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

#### http://freescale.com/

The following revision history table summarizes changes contained in this document.

Revision	Date	Description of Changes
1	1/2008	Initial public release
2	2/2008	Changed the designator of the device in Table 15.
3	1/2009	Changed the condition of Run supply current measured to f <sub>Bus</sub> = 1 MHz in Table 7. Fixed the error of inconsistent table number.

### **Related Documentation**

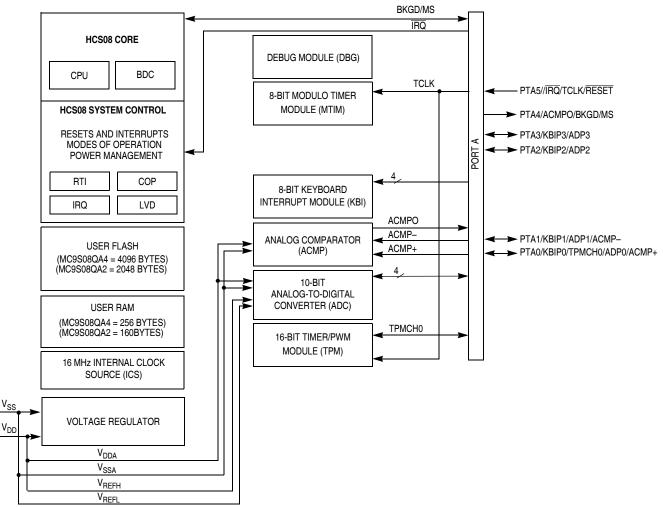
Find the most current versions of all documents at: http://www.freescale.com

#### Reference Manual (MC9S08QA4RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

# 1 MCU Block Diagram

The block diagram, Figure 1, shows the structure of the MC9S08QA4 MCU.



NOTES:

- <sup>1</sup> Port pins are software configurable with pullup device if input port.
- <sup>2</sup> Port pins are software configurable for output drive strength.
- <sup>3</sup> Port pins are software configurable for output slew rate control.
- <sup>4</sup> IRQ contains a software configurable (IRQPDD) pullup device if PTA5 enabled as IRQ pin function (IRQPE = 1).
- <sup>5</sup> RESET contains integrated pullup device if PTA5 enabled as reset pin function (RSTPE = 1).
- <sup>6</sup> PTA4 contains integrated pullup device if BKGD enabled (BKGDPE = 1).
- <sup>7</sup> When pin functions as KBI (KBIPEn = 1) and associated pin is configured to enable the pullup device, KBEDGn can be used to reconfigure the pullup as a pulldown device.

### Figure 1. MC9S08QA4 Series Block Diagram

# 2 Pin Assignments

This section shows the pin assignments in the packages available for the MC9S08QA4 series.

MC9S08QA4 Series MCU Data Sheet, Rev. 3

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DIN	-		Priority		
PIN	Lowest				Highest
8-Pin	Port Pin	Alt 1	Alt 2	Alt 3	Alt 4
1	PTA5 <sup>1</sup>	ĪRQ	TCLK		RESET
2	PTA4		ACMPO	BKGD	MS
3					V <sub>DD</sub>
4					V <sub>SS</sub>
5	PTA3	KBIP3	ADP3		
6	PTA2	KBIP2	ADP2		
7	PTA1	KBIP1		ADP1 <sup>2</sup>	ACMP-2
8	PTA0	KBIP0	TPMCH0	ADP0 <sup>2</sup>	ACMP+ <sup>2</sup>

#### Table 1. Pin Sharing Priority

<sup>1</sup> Pin does not contain a clamp diode to  $V_{DD}$  and must not be driven above  $V_{DD}$ . The voltage measured on the internally pulled-up RESET pin will not be pulled to  $V_{DD}$ . The internal gates connected to this pin are pulled to  $V_{DD}$ .

 $^2\,$  If ACMP and ADC are both enabled, both will have access to the pin.

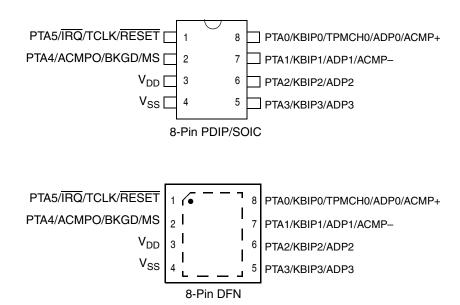


Figure 2. MC9S08QA4 Series in 8-Pin Packages

### 3.1 Introduction

This chapter contains electrical and timing specifications for the MC9S08QA4 series of microcontrollers available at the time of publication.

### 3.2 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in Table 2 may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pullup resistor associated with the pin is enabled.

Rating	Symbol	Value	Unit
Supply voltage	V <sub>DD</sub>	-0.3 to 3.8	V
Maximum current into V <sub>DD</sub>	I <sub>DD</sub>	120	mA
Digital input voltage	V <sub>In</sub>	-0.3 to V <sub>DD</sub> + 0.3	V
Instantaneous maximum current Single pin limit (applies to all port pins) <sup>1, 2, 3</sup>	Ι <sub>D</sub>	±25	mA
Storage temperature range	T <sub>stg</sub>	–55 to 150	°C

Table 2	Absolute	Maximum	Ratings
		waxiiiuiii	пашуэ

<sup>1</sup> Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive (V<sub>DD</sub>) and negative (V<sub>SS</sub>) clamp voltages, then use the larger of the two resistance values.

- $^2\,$  All functional non-supply pins are internally clamped to V\_{SS} and V\_{DD}
- <sup>3</sup> Power supply must maintain regulation within operating V<sub>DD</sub> range during instantaneous and operating maximum current conditions. If positive injection current (V<sub>In</sub> > V<sub>DD</sub>) is greater than I<sub>DD</sub>, the injection current may flow out of V<sub>DD</sub> and could result in external power supply going out of regulation. Ensure external V<sub>DD</sub> load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

### 3.3 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  will be very small.

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T <sub>A</sub>	T <sub>L</sub> to T <sub>H</sub> 40 to 85	°C
Thermal resistance Single-layer board			
8-pin PDIP		113	
8-pin NB SOIC	$\theta_{JA}$	150	°C/W
8-pin DFN		179	
Thermal resistance Four-layer board			
8-pin PDIP		72	
8-pin NB SOIC	$\theta_{JA}$	87	°C/W
8-pin DFN	1	41	1

**Table 3. Thermal Characteristics** 

The average chip-junction temperature  $(T_J)$  in °C can be obtained from:

$$T_{J} = T_{A} + (P_{D} \times \theta_{JA})$$
 Eqn. 1

where:

—  $T_A =$  Ambient temperature, °C

—  $\theta_{JA}$  = Package thermal resistance, junction-to-ambient, °C/W

- P<sub>D</sub> = P<sub>int</sub> + P<sub>I/O</sub>

—  $P_{int} = I_{DD} \times V_{DD}$ , Watts — chip internal power

—  $P_{I/O}$  = Power dissipation on input and output pins — user-determined

For most applications,  $P_{I/O} \ll P_{int}$  and can be neglected. An approximate relationship between  $P_D$  and  $T_J$  (if  $P_{I/O}$  is neglected) is:

$$P_{D} = K \div (T_{J} + 273^{\circ}C)$$
 Eqn. 2

Solving Equation 1 and Equation 2 for K gives:

$$\mathbf{K} = \mathbf{P}_{\mathbf{D}} \times (\mathbf{T}_{\mathbf{A}} + 273^{\circ}\mathbf{C}) + \theta_{\mathbf{J}\mathbf{A}} \times (\mathbf{P}_{\mathbf{D}})^{2} \qquad \qquad Eqn. 3$$

where K is a constant pertaining to the particular part. K can be determined from Equation 3 by measuring  $P_D$  (at equilibrium) for a known  $T_A$ . Using this value of K, the values of  $P_D$  and  $T_J$  can be obtained by solving Equation 1 and Equation 2 iteratively for any value of  $T_A$ .

### 3.4 ESD Protection and Latch-Up Immunity

Although damage from electrostatic discharge (ESD) is much less common on these devices than on early CMOS circuits, normal handling precautions should be used to avoid exposure to static discharge. Qualification tests are performed to ensure that these devices can withstand exposure to reasonable levels of static without suffering any permanent damage.

All ESD testing is in conformity with AEC-Q100 Stress Test Qualification for Automotive Grade Integrated Circuits. During the device qualification ESD stresses were performed for the human body model (HBM), the machine model (MM) and the charge device model (CDM).

A device is defined as a failure if after exposure to ESD pulses the device no longer meets the device specification. Complete DC parametric and functional testing is performed per the applicable device specification at room temperature followed by hot temperature, unless specified otherwise in the device specification.

Model	Description	Symbol	Value	Unit
	Series resistance	R1	1500	Ω
Human Body	Storage capacitance	С	100	pF
	Number of pulses per pin		3	
	Series resistance	R1	0	Ω
Machine	Storage capacitance	С	200	pF
	Number of pulses per pin		3	
Latch-up	Minimum input voltage limit		-2.5	V
Laton-up	Maximum input voltage limit		7.5	V

Table 4. ESD and Latch-up Test Conditions

#### Table 5. ESD and Latch-Up Protection Characteristics

No.	Rating <sup>1</sup>	Symbol	Min	Max	Unit
1	Human body model (HBM)	V <sub>HBM</sub>	±2000	_	V
2	Machine model (MM)	V <sub>MM</sub>	±200		V
3	Charge device model (CDM)	V <sub>CDM</sub>	±500	—	V
4	Latch-up current at $T_A = 85^{\circ}C$	I <sub>LAT</sub>	±100		mA

<sup>1</sup> Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

### 3.5 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

Table 6. DC Characteristics (Temperature Range = -40 to 85°C Ambient)

Parameter	Symbol	Min	Typical	Max	Unit
Supply voltage (run, wait, and stop modes)					
(V <sub>DD</sub> falling)	$V_{DD}$	1.8	—	3.6	v
(V <sub>DD</sub> rising)		V <sub>LVDL</sub> (rising)	_	3.6	
Minimum RAM retention supply voltage applied to $\mathrm{V}_{\mathrm{DD}}$	V <sub>RAM</sub>	V <sub>por</sub> <sup>1,2</sup>	_	_	V
Low-voltage detection threshold (V <sub>DD</sub> falling) (V <sub>DD</sub> rising)	V <sub>LVD</sub>	1.80 1.88	1.82 1.90	1.91 1.99	v
Low-voltage warning threshold (V <sub>DD</sub> falling)	V <sub>LVW</sub>	2.08	2.1	2.2	v

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Parameter	Symbol	Min	Typical	Мах	Unit		
(V <sub>DD</sub> rising)		2.16	2.19	2.27			
Power on reset (POR) re-arm voltage	V <sub>por</sub>	—	1.4	—	V		
Bandgap voltage reference	V <sub>BG</sub>	1.18	1.20	1.21	V		
Input high voltage ( $V_{DD} > 2.3 V$ ) (all digital inputs)	М	$0.70 \times V_{DD}$	_	_	V		
Input high voltage (1.8 V $\leq$ V_{DD} $\leq$ 2.3 V) (all digital inputs)	V <sub>IH</sub>	$0.85  imes V_{DD}$	_	_	v		
Input low voltage (V <sub>DD</sub> > 2.3 V) (all digital inputs)	V	—	_	$0.35\times V_{DD}$	V		
Input low voltage (1.8 V $\leq$ V_{DD} $\leq$ 2.3 V) (all digital inputs)	V <sub>IL</sub>	—	_	$0.30\times V_{DD}$	v		
Input hysteresis (all digital inputs)	V <sub>hys</sub>	$0.06 \times V_{DD}$	_	—	V		
Input leakage current (per pin) $V_{In} = V_{DD}$ or $V_{SS}$ , all input-only pins	<sub>In</sub>	_	0.025	1.0	μA		
High impedance (off-state) leakage current (per pin) $V_{In} = V_{DD}$ or $V_{SS}$ , all input/output	I <sub>OZ</sub>	_	0.025	1.0	μA		
Internal pullup resistors <sup>3,4</sup>	R <sub>PU</sub>	17.5	_	52.5	kΩ		
Internal pulldown resistor (KBI)	R <sub>PD</sub>	17.5	_	52.5	kΩ		
Output high voltage — low drive (PTxDSn = 0) $I_{OH} = -2 \text{ mA} (V_{DD} \ge 1.8 \text{ V})$		V <sub>DD</sub> – 0.5		_			
	V <sub>OH</sub>	V <sub>DD</sub> – 0.5			V		
Maximum total I <sub>OH</sub> for all port pins	I <sub>OHT</sub>	—	_	60	mA		
Output low voltage — low drive (PTxDSn = 0) I <sub>OL</sub> = 2.0 mA (V <sub>DD</sub> $\ge$ 1.8 V)		_	_	0.5	V		
$ \begin{array}{l} Output \ \text{low voltage} & \ \text{high drive (PTxDSn = 1)} \\ I_{OL} = 10.0 \ \text{mA} \ (V_{DD} \geq 2.7 \ \text{V}) \\ I_{OL} = 6 \ \text{mA} \ (V_{DD} \geq 2.3 \ \text{V}) \\ I_{OL} = 3 \ \text{mA} \ (V_{DD} \geq 1.8 \ \text{V}) \end{array} $	V <sub>OL</sub>		 	0.5 0.5 0.5	v		
Maximum total I <sub>OL</sub> for all port pins	I <sub>OLT</sub>	_		60	mA		
DC injection current <sup>2, 5, 6, 7</sup> $V_{ln} < V_{SS}, V_{ln} > V_{DD}$ Single pin limit Total MCU limit, includes sum of all stressed pins	I <sub>IC</sub>	-0.2 -5		0.2 5	mA mA		
Input capacitance (all non-supply pins)	C <sub>In</sub>	—		7	pF		
		1			ł		

Table 6. DC Characteristics (Temperature Range = -40 to 85°C Ambient) (continued)

<sup>1</sup> RAM will retain data down to POR voltage. RAM data not guaranteed to be valid following a POR.

<sup>2</sup> This parameter is characterized and not tested on each device.

 $^3~$  Measurement condition for pull resistors:  $V_{In}$  =  $V_{SS}$  for pullup and  $V_{In}$  =  $V_{DD}$  for pulldown.

<sup>4</sup> PTA5/IRQ/TCLK/RESET pullup resistor may not pull up to the specified minimum V<sub>IH</sub>. However, all ports are functionally tested to guarantee that a logic 1 will be read on any port input when the pullup is enabled and no DC load is present on the pin.

 $^5\,$  All functional non-supply pins are internally clamped to  $V_{SS}$  and  $V_{DD}$ 

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- <sup>6</sup> Input must be current-limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive and negative clamp voltages, then use the larger of the two values.
- <sup>7</sup> Power supply must maintain regulation within operating  $V_{DD}$  range during instantaneous and operating maximum current conditions. If positive injection current ( $V_{In} > V_{DD}$ ) is greater than  $I_{DD}$ , the injection current may flow out of  $V_{DD}$  and could result in external power supply going out of regulation. Ensure external  $V_{DD}$  load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if clock rate is very low (which would reduce overall power consumption).

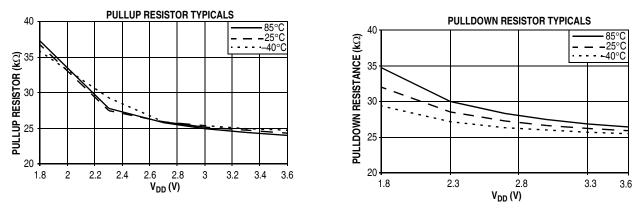


Figure 3. Pullup and Pulldown Typical Resistor Values (V<sub>DD</sub> = 3.0 V)

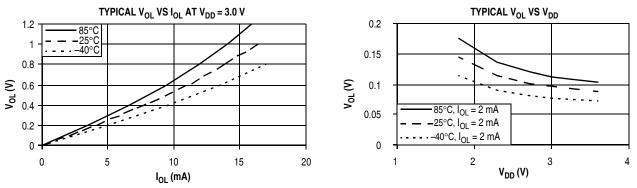


Figure 4. Typical Low-Side Driver (Sink) Characteristics — Low Drive (PTxDSn = 0)

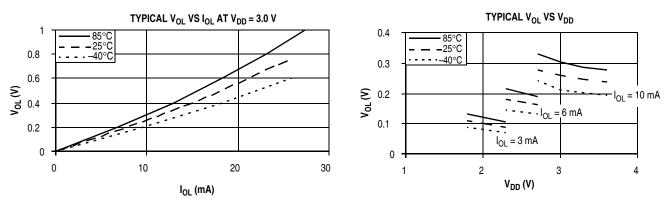
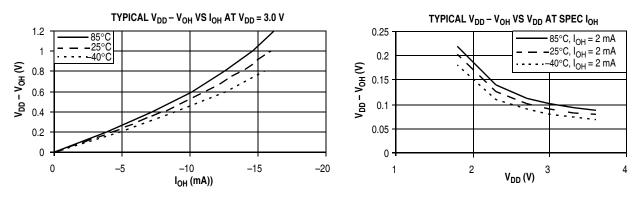
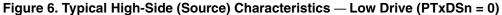


Figure 5. Typical Low-Side Driver (Sink) Characteristics — High Drive (PTxDSn = 1)

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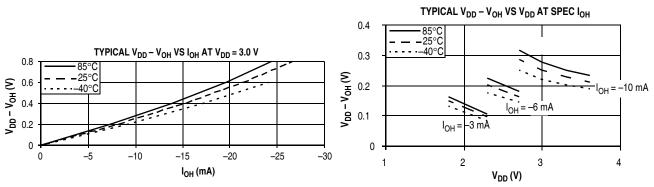


Figure 7. Typical High-Side (Source) Characteristics — High Drive (PTxDSn = 1)

### 3.6 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

Parameter	Symbol	V <sub>DD</sub> (V) <sup>1</sup>	Typical <sup>2</sup>	Max	T (°C)
Run supply current <sup>3</sup> measured in FBE mode at	RI <sub>DD</sub>	3	3.5 mA	5 mA	85
f <sub>Bus</sub> = 8 MHz	DD	2	2.6 mA		85
Run supply current <sup>3</sup> measured in FBE mode at	RI <sub>DD</sub>	3	490 μA	1 mA	85
f <sub>Bus</sub> = 1 MHz	I NDD	2	370 μA	_	85
Wait mode supply current <sup>4</sup> measured in FBE at 8 MHz	WI <sub>DD</sub>	3	1 mA	1.5 mA	85
Stop1 mode supply current	Q1I	3	475 nA	1.2 μA	85
	S1I <sub>DD</sub>	2	470 nA	_	85
Stop2 mode supply current	521	3	600 nA	2 μΑ	85
	S2I <sub>DD</sub>	2	550 nA	_	85
Stop3 mode supply current	ଟସା	3	750 nA	6 μΑ	85
	S3I <sub>DD</sub>	2	680 nA	_	85
RTI adder to stop1, stop2, or stop3 <sup>4</sup>		3	300 nA	_	85
		2	300 nA	_	85
LVD adder to stop3 (LVDE = LVDSE = $1$ ) <sup>4</sup>	_	3	70 μA	_	85
		2	60 μA	_	85

Table 7. Supply Current Characteristics

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- <sup>1</sup> 3 V values are 100% tested; 2 V values are characterized but not tested.
- $^2~$  Typicals are measured at 25 °C.
- <sup>3</sup> Does not include any DC loads on port pins.

<sup>4</sup> Most customers are expected to find that auto-wakeup from a stop mode can be used instead of the higher current wait mode.

### 3.7 Internal Clock Source (ICS) Characteristics

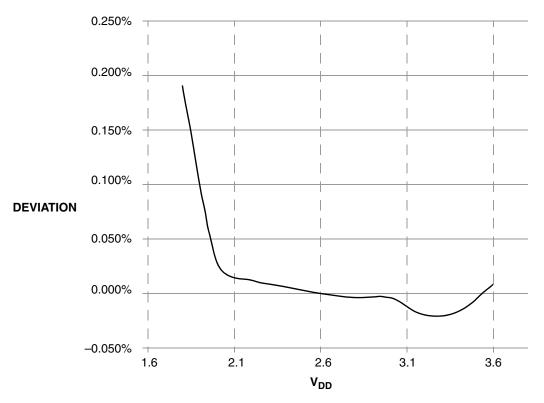
### Table 8. ICS Specifications (Temperature Range = -40 to 85°C Ambient)

Characteristic	Symbol	Min	Typical <sup>1</sup>	Max	Unit
Internal reference start-up time	t <sub>IRST</sub>		60	100	μs
Average internal reference frequency — untrimmed	f <sub>int_ut</sub>	25	32.7	41.66	kHz
Average internal reference frequency — trimmed	f <sub>int_t</sub>	31.25	—	39.06	kHz
DCO output frequency range — untrimmed	f <sub>dco_ut</sub>	12.8	16.8	21.33	MHz
DCO output frequency range — trimmed	f <sub>dco_t</sub>	16	—	20	MHz
Resolution of trimmed DCO output frequency at fixed voltage and temperature <sup>2</sup>	$\Delta f_{dco\_res\_t}$	_	±0.1	±0.2	%f <sub>dco</sub>
Total deviation of DCO output from trimmed frequency <sup>2</sup> At 8 MHz over full voltage and temperature range At 8 MHz and 3.6 V from 0 to 70 °C	$\Delta f_{dco_t}$	_	−1.0 to 0.5 ±0.5	±2 ±1	%f <sub>dco</sub>
FLL acquisition time <sup>2,3</sup>	t <sub>Acquire</sub>	_	—	1.5	ms
Long term jitter of DCO output clock (averaged over 2 ms interval)	C <sub>Jitter</sub>	_	0.02	0.2	%f <sub>dco</sub>

<sup>1</sup> Data in Typical column was characterized at 3.0 V, 25 °C, or is typical recommended value.

<sup>2</sup> This parameter is characterized and not tested on each device.

<sup>3</sup> This specification applies to any time the FLL reference source or reference divider is changed, trim value changed.





### 3.8 AC Characteristics

This section describes timing characteristics for each peripheral system.

### 3.8.1 Control Timing

Parameter	Symbol	Min	Typical <sup>1</sup>	Мах	Unit
Bus frequency (t <sub>cyc</sub> = 1/f <sub>Bus</sub> )	f <sub>Bus</sub>	0	_	10	MHz
Real-time interrupt internal oscillator period (see Table 9)	t <sub>RTI</sub>	700	1000	1300	μs
External reset pulse width <sup>2</sup>	t <sub>extrst</sub>	100	—	—	ns
IRQ pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>3</sup>	tı∟ıн	100 1.5 t <sub>cyc</sub>	_	_	ns
KBIPx pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>3</sup>	t <sub>ILIH,</sub> t <sub>IHIL</sub>	100 1.5 t <sub>cyc</sub>	_	_	ns
Port rise and fall time (load = 50 pF) <sup>4</sup> Slew rate control disabled (PTxSE = 0) Slew rate control enabled (PTxSE = 1)	t <sub>Rise</sub> , t <sub>Fall</sub>		3 30		ns
BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	t <sub>MSSU</sub>	500	_	_	ns
BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>5</sup>	t <sub>MSH</sub>	100	_	_	μs

### Table 9. Control Timing

<sup>1</sup> Data in Typical column was characterized at 3.0 V, 25°C.

<sup>2</sup> This is the shortest pulse that is guaranteed to be recognized.

<sup>3</sup> This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized in that case.

 $^4~$  Timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$  levels. Temperature range –40°C to 85°C.

<sup>5</sup> To enter BDM mode following a POR, BKGD/MS should be held low during the power-up and for a hold time of  $t_{MSH}$  after  $V_{DD}$  rises above  $V_{LVD}$ .

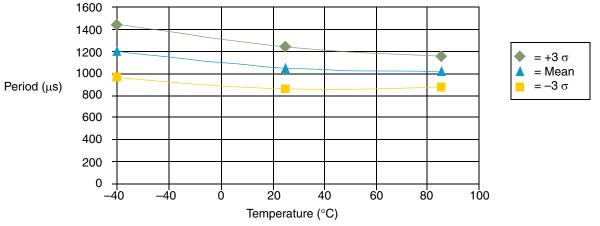


Figure 9. Typical RTI Clock Period vs. Temperature

#### MC9S08QA4 Series MCU Data Sheet, Rev. 3

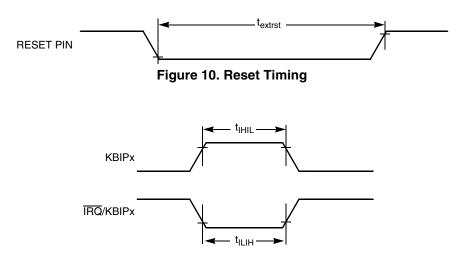


Figure 11. IRQ/KBIPx Timing

### 3.8.2 TPM/MTIM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Function	Symbol	Min	Мах	Unit
External clock frequency	f <sub>TCLK</sub>	0	f <sub>Bus</sub> /4	Hz
External clock period	t <sub>TCLK</sub>	4	—	t <sub>cyc</sub>
External clock high time	t <sub>clkh</sub>	1.5	—	t <sub>cyc</sub>
External clock low time	t <sub>clkl</sub>	1.5	—	t <sub>cyc</sub>
Input capture pulse width	t <sub>ICPW</sub>	1.5	—	t <sub>cyc</sub>

Table 10. TPM/MTIM Input Timing

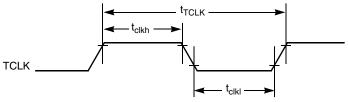


Figure 12. Timer External Clock

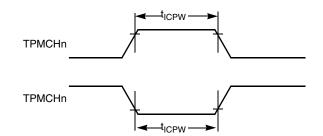


Figure 13. Timer Input Capture Pulse

### 3.9 Analog Comparator (ACMP) Electricals

Characteristic	Symbol	Min	Typical	Max	Unit
Supply voltage	V <sub>DD</sub>	1.80	_	3.60	V
Supply current (active)	IDDAC	—	20	_	μA
Analog input voltage	V <sub>AIN</sub>	V <sub>SS</sub> – 0.3	_	V <sub>DD</sub>	V
Analog input offset voltage	V <sub>AIO</sub>	—	20	40	mV
Analog comparator hysteresis	V <sub>H</sub>	3.0	9.0	15.0	mV
Analog input leakage current	I <sub>ALKG</sub>	—	—	1.0	μA
Analog comparator initialization delay	t <sub>AINIT</sub>	—	—	1.0	μs

### 3.10 ADC Characteristics

Characteristic	Conditions	Symbol	Min	Typical <sup>1</sup>	Мах	Unit	Comment
Supply voltage	Absolute	V <sub>DD</sub>	1.8	—	3.6	V	
Input voltage		V <sub>ADIN</sub>	V <sub>SS</sub>	—	V <sub>DD</sub>	V	
Input capacitance		C <sub>ADIN</sub>	—	4.5	5.5	pF	
Input resistance		R <sub>ADIN</sub>	—	5	7	kΩ	
Analog source resistance	10 bit mode f <sub>ADCK</sub> > 4 MHz f <sub>ADCK</sub> < 4 MHz	R <sub>AS</sub>	_	_	5 10	kΩ	External to MCU
	8 bit mode (all valid f <sub>ADCK</sub> )			—	10		
ADC conversion	High Speed (ADLPC=0)	f	0.4	— 8.0	8.0	MHz	
clock frequency	Low Power (ADLPC=1)	f <sub>ADCK</sub>	0.4	—	4.0	IVIHZ	

Typical values assume  $V_{DD}$  = 3.0 V, Temp = 25°C,  $f_{ADCK}$  =1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

### MC9S08QA4 Series MCU Data Sheet, Rev. 3

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1

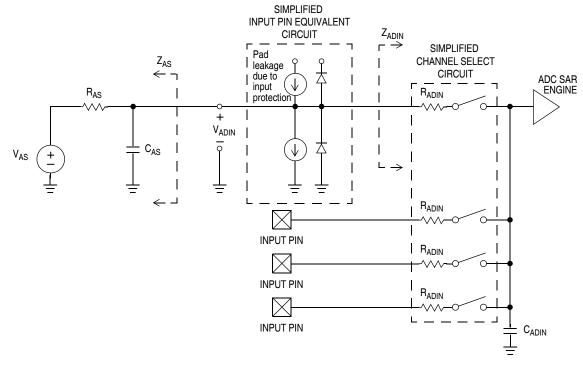


Figure 14. ADC Input Impedance Equivalency Diagram

Characteristic	Conditions	Symbol	Min	Typical <sup>1</sup>	Max	Unit	Comment
Supply current ADLPC = 1 ADLSMP = 1 ADCO = 1		I <sub>DDAD</sub>	_	120	_	μA	
Supply current ADLPC = 1 ADLSMP = 0 ADCO = 1		I <sub>DDAD</sub>	_	202	_	μA	
Supply current ADLPC = 0 ADLSMP = 1 ADCO = 1		I <sub>DDAD</sub>	_	288	_	μA	
Supply current ADLPC = 0 ADLSMP = 0 ADCO = 1		I <sub>DDAD</sub>	_	532	646	μA	
ADC asynchronous	High speed (ADLPC=0)	f	2	3.3	5	MHz	t <sub>ADACK</sub> =
clock source	Low power (ADLPC=1)	f <sub>ADACK</sub>	1.25	2	3.3		1/f <sub>ADACK</sub>

Table 13.	3 V 10-Bit ADC	Characteristics
-----------	----------------	-----------------

Characteristic	Conditions	Symbol	Min	Typical <sup>1</sup>	Max	Unit	Comment
Conversion time	Short sample (ADLSMP=0)		_	20	_	ADCK	See
(including sample time)	Long sample (ADLSMP=1)	t <sub>ADC</sub>	_	40	_	cycles	MC9S08QA4 Series
	Short sample (ADLSMP=0)			3.5		ADCK	Reference Manual for
Sample time	Long sample (ADLSMP=1)	t <sub>ADS</sub>		23.5		cycles	conversion time variances
<b></b>	10-bit mode	_		±1.5	±3.5	1.0.02	Includes
Total unadjusted error	8-bit mode	E <sub>TUE</sub>	_	±0.7	±1.5	LSB <sup>2</sup>	quantization
<b>D</b> ''	10-bit mode			±0.5	±1.0		Monotonicity
Differential non-linearity	8-bit mode	DNL	_	±0.3	±0.5	LSB <sup>2</sup>	and no missing codes guaranteed
	10-bit mode	- INL		±0.5	±1.0	LSB <sup>2</sup>	
Integral non-linearity	8-bit mode		_	±0.3	±0.5		
Zero-scale error	10-bit mode	– E <sub>ZS</sub>	_	±1.5	±2.1	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>SS</sub>
	8-bit mode			±0.5	±0.7		
Full-scale error	10-bit mode	E <sub>FS</sub>	0	±1.0	±1.5	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>DD</sub>
	8-bit mode	FS	0	±0.5	±0.5	LOD	VADIN − VDD
Quantization error	10-bit mode	EQ	_	—	±0.5	LSB <sup>2</sup>	
Quantization entri	8-bit mode	LQ		_	±0.5	LOD	
Input leakage error	10-bit mode	Ε <sub>IL</sub>	0	±0.2	±4	LSB <sup>2</sup>	Pad leakage <sup>3 *</sup>
input leakage error	8-bit mode		0	±0.1	±1.2	LSB-	R <sub>AS</sub>
Temp sensor	−40°C − 25°C	m	—	1.646	_	mV/°C	
slope	25°C – 85°C		_	1.769			
Temp sensor voltage	25°C	V <sub>TEMP25</sub>	_	701.2	_	mV	

Table 13. 3 V 10-Bit ADC Chara	acteristics (continued)
--------------------------------	-------------------------

<sup>1</sup> Typical values assume V<sub>DD</sub> = 3.0 V, Temp = 25°C, f<sub>ADCK</sub> = 1.0 MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>2</sup> 1 LSB =  $(V_{\text{REFH}} - V_{\text{REFL}})/2^N$ 

<sup>3</sup> Based on input pad leakage current. Refer to pad electricals.

### 3.11 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the flash memory.

MC9S08QA4 Series MCU Data Sheet, Rev. 3

Program and erase operations do not require any special power sources other than the normal V<sub>DD</sub> supply. For more detailed information about program/erase operations, see *MC9S08QA4 Series Reference Manual*.

Characteristic	Symbol	Min	Typical	Max	Unit
Supply voltage for program/erase -40°C to 85°C	V <sub>prog/erase</sub>	1.8	_	3.6	V
Supply voltage for read operation	V <sub>Read</sub>	1.8	—	3.6	V
Internal FCLK frequency <sup>1</sup>	f <sub>FCLK</sub>	150	—	200	kHz
Internal FCLK period (1/FCLK)	t <sub>Fcyc</sub>	5	—	6.67	μS
Byte program time (random location) <sup>2</sup>	t <sub>prog</sub>	9		t <sub>Fcyc</sub>	
Byte program time (burst mode) <sup>2</sup>	t <sub>Burst</sub>		4		t <sub>Fcyc</sub>
Page erase time <sup>2</sup>	t <sub>Page</sub>		4000		t <sub>Fcyc</sub>
Mass erase time <sup>2</sup>	t <sub>Mass</sub>		20,000		t <sub>Fcyc</sub>
Program/erase endurance <sup>3</sup> T <sub>L</sub> to T <sub>H</sub> = -40°C to + 85°C T = 25°C		10,000			cycles
Data retention <sup>4</sup>	t <sub>D_ret</sub>	15	100		years

#### Table 14. Flash Characteristics

<sup>1</sup> The frequency of this clock is controlled by a software setting.

<sup>2</sup> These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.

<sup>3</sup> **Typical endurance for flash** was evaluated for this product family on the 9S12Dx64. For additional information on how Motorola defines typical endurance, please refer to Engineering Bulletin EB619/D, *Typical Endurance for Nonvolatile Memory*.

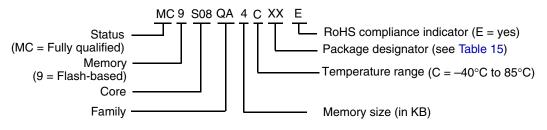
<sup>4</sup> Typical data retention values are based on intrinsic capability of the technology measured at high temperature and de-rated to 25°C using the Arrhenius equation. For additional information on how Freescale defines typical data retention, please refer to Engineering Bulletin EB618/D, *Typical Data Retention for Nonvolatile Memory.* 

# 4 Ordering Information

This section contains ordering numbers for MC9S08QA4 series devices. See below for an example of the device numbering system.

Device Number	Device Number		Package		
Device Number	Flash	RAM	Туре	Designator	Document No.
MC9S08QA4	4 KB	256 bytes	8 DFN 8 PDIP	FQ PA	98ARL10557D 98ASB42420B
MC9S08QA2	2 KB	160 bytes	8 NB SOIC	DN	98ASB42564B

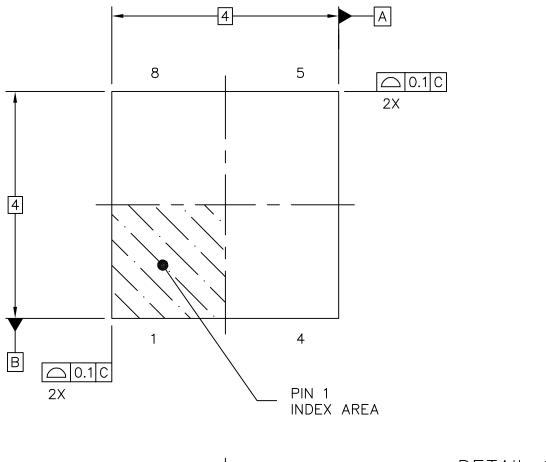
### Table 15. Device Numbering System

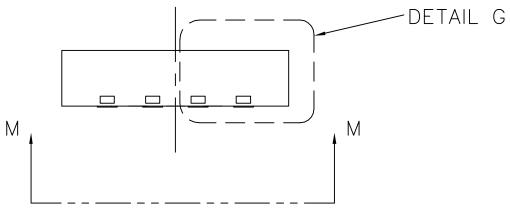


# 5 Mechanical Drawings

The following pages contain mechanical specifications for MC9S08QA4 series package options.

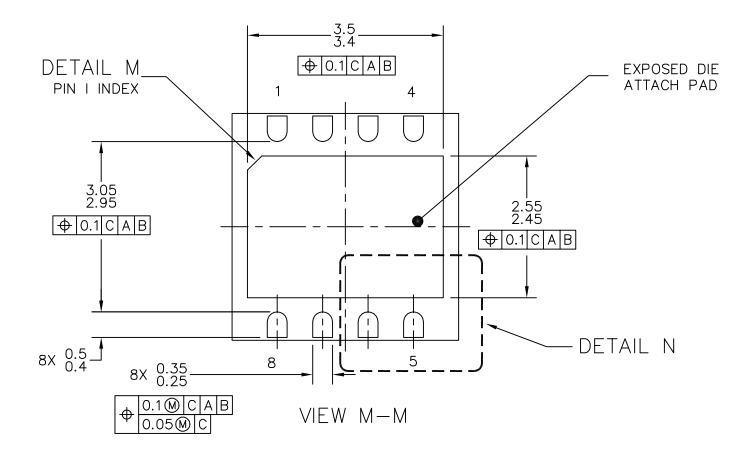
- 8-pin DFN (plastic dual in-line pin)
- 8-pin NB SOIC (narrow body small outline integrated circuit)
- 8-pin PDIP (plastic dual in-line pin)

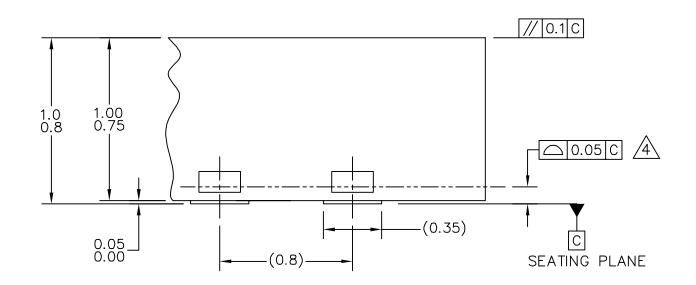




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TITLE: THERMALLY ENHANCED DUAL FLAT NO LEAD PACKAGE (DFN) 8 TERMINAL, 0.8 PITCH (4 X 4 X 1)		DOCUMENT NO	): 98ARL10557D	REV: B
		CASE NUMBER	: 1452–02	28 DEC 2005
		STANDARD: NO	N-JEDEC	

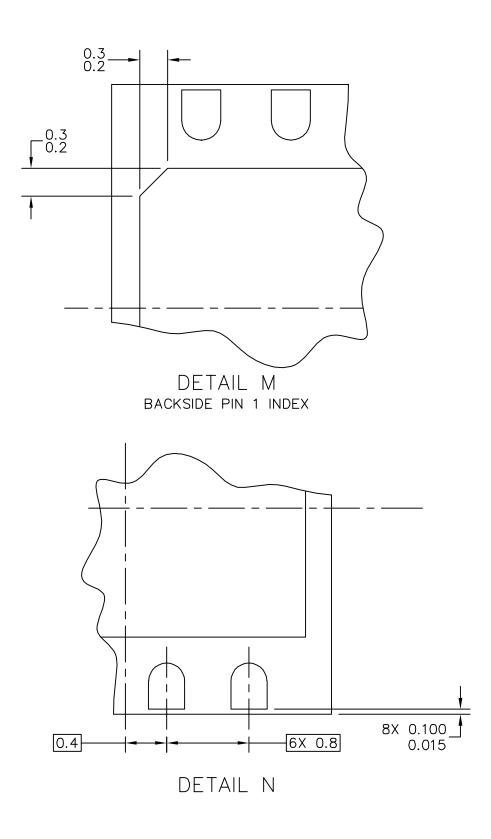
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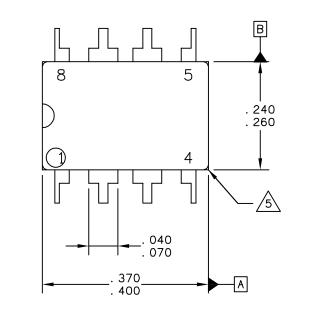
2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14. 5M-1994.

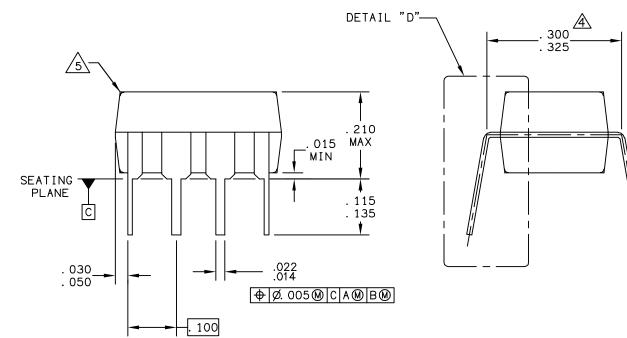
3. THE COMPLETE JEDEC DESIGNATOR FOR THIS PACKAGE IS: HP-VFDFP-N.

4. COPLANARITY APPLIES TO LEADS AND DIE ATTACH PAD.

5. MIN. METAL GAP SHOULD BE 0.2MM.

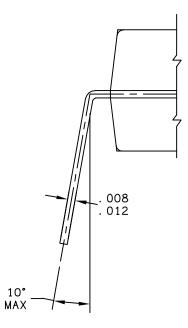
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FLAT NO LEAD PACKAGE (DFN)		CASE NUMBER	: 1452–02	28 DEC 2005
8 TERMINAL, O. 8 PITCH(4	× 4 × 1)	STANDARD: NC	N-JEDEC	





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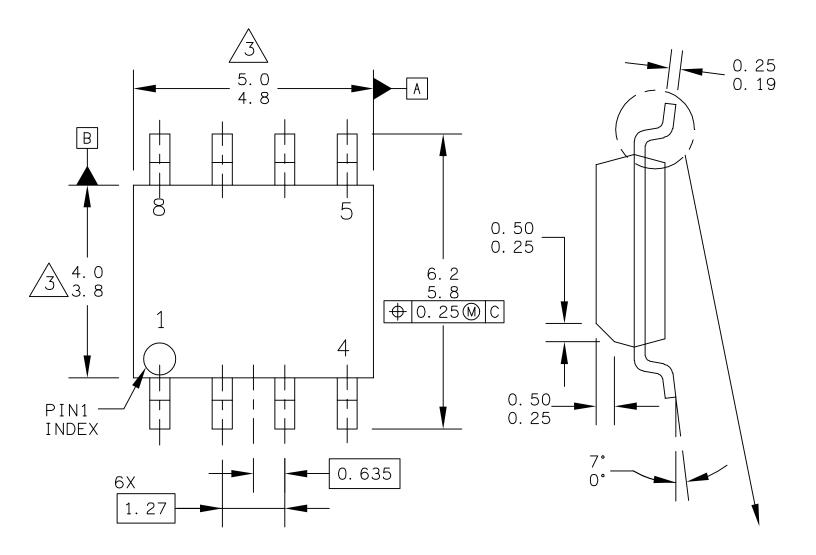
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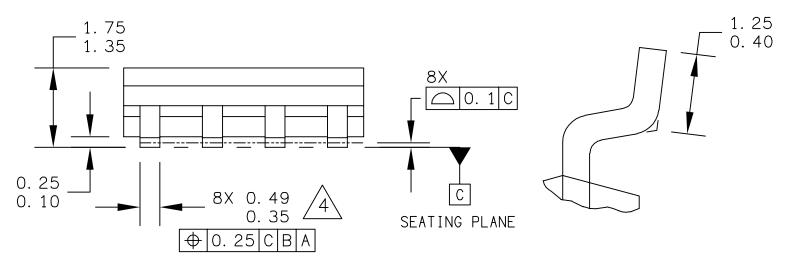
- 1. DIMENSIONING AND TOLERANCING PER ASME Y14.5M 1994.
- 2. ALL DIMENSIONS ARE IN INCHES.
- 3. 626-03 TO 626-06 OBSOLETE. NEW STANDARD 626-07.
- $\triangle$  DIMENSION TO CENTER OF LEAD WHEN FORMED PARALLEL.
- A PACKAGE CONTOUR OPTIONAL (ROUND OR SQUARE CONERS). STYLE 1:

PIN	1.	AC IN	
	2.	DC + IN	
	3.	DC - IN	
	4.	AC IN	

- 5. GROUND
- OUTPUT
  AUXILIARY
- 8. VCC

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STYLE 1: PIN 1. EMITTER 2. COLLECTOR 3. COLLECTOR 4. EMITTER 5. EMITTER 6. BASE 7. BASE 8. EMITTER	STYLE 2:      PIN 1.    COLLECTOR, DIE #1      2.    COLLECTOR, #1      3.    COLLECTOR, #2      4.    COLLECTOR, #2      5.    BASE, #2      6.    EMITTER, #2      7.    BASE, #1      8.    EMITTER, #1	STYLE 3: PIN 1. DRAIN, DIE #1 2. DRAIN, #1 3. DRAIN, #2 4. DRAIN, #2 5. GATE, #2 6. SOURCE, #2 7. GATE, #1 8. SOURCE, #1
STYLE 4:	STYLE 5:	STYLE 6:
PIN 1. ANODE	PIN 1. DRAIN	PIN 1. SOURCE
2. ANODE	2. DRAIN	2. DRAIN
3. ANODE	3. DRAIN	3. DRAIN
4. ANODE	4. DRAIN	4. SOURCE
5. ANODE	5. GATE	5. SOURCE
6. ANODE	6. GATE	6. GATE
7. ANODE	7. SOURCE	7. GATE
8. COMMON CATHODE	8. SOURCE	8. SOURCE
STYLE 7: PIN 1. INPUT 2. EXTERNAL BYPASS 3. THIRD STAGE SOURCE 4. GROUND 5. DRAIN 6. GATE 3 7. SECOND STAGE Vd 8. FIRST STAGE Vd	STYLE 8:      PIN 1.    COLLECTOR, DIE #1      2.    BASE, #1      3.    BASE, #2      4.    COLLECTOR, #2      5.    COLLECTOR, #2      6.    EMITTER, #2      7.    EMITTER, #1      8.    COLLECTOR, #1	STYLE 9: PIN 1. EMITTER, COMMON 2. COLLECTOR, DIE #1 3. COLLECTOR, DIE #2 4. EMITTER, COMMON 5. EMITTER, COMMON 6. BASE, DIE #2 7. BASE, DIE #1 8. EMITTER, COMMON
STYLE 10:	STYLE 11:	STYLE 12:
PIN 1. GROUND	PIN 1. SOURCE 1	PIN 1. SOURCE
2. BIAS 1	2. GATE 1	2. SOURCE
3. OUTPUT	3. SOURCE 2	3. SOURCE
4. GROUND	4. GATE 2	4. GATE
5. GROUND	5. DRAIN 2	5. DRAIN
6. BIAS 2	6. DRAIN 2	6. DRAIN
7. INPUT	7. DRAIN 1	7. DRAIN
8. GROUND	8. DRAIN 1	8. DRAIN
STYLE 13:	STYLE 14:	STYLE 15:
PIN 1. N.C.	PIN 1. N-SOURCE	PIN 1. ANODE 1
2. SOURCE	2. N-GATE	2. ANODE 1
3. SOURCE	3. P-SOURCE	3. ANODE 1
4. GATE	4. P-GATE	4. ANODE 1
5. DRAIN	5. P-DRAIN	5. CATHODE, COMMON
6. DRAIN	6. P-DRAIN	6. CATHODE, COMMON
7. DRAIN	7. N-DRAIN	7. CATHODE, COMMON
8. DRAIN	8. N-DRAIN	8. CATHODE, COMMON

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2. E 3. E	: EMITTER, BASE, EMITTER, BASE,	DIE #1 DIE #1 DIE #2 DIE #2	STYLE 1 PIN 1. 2. 3. 4.	7: VCC V20UT V10UT TXE	STYLE 1 PIN 1. 2. 3. 4.	8: ANODE ANODE SOURCE GATE
6. ( 7. (	COLLECTOR, COLLECTOR, COLLECTOR, COLLECTOR,	DIE #2 DIE #2 DIE #1 DIE #1	5. 6. 7. 8.	RXE VEE GND ACC	5. 6. 7. 8.	DRAIN DRAIN CATHODE CATHODE

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- 2. DIMENSIONING AND TOLERANCING PER ASME Y14.5M-1994.
- A. DIMENSION DOES NOT INCLUDE MOLD PROTRUSION. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.
- A. DIMENSION DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 TOTAL IN EXCESS OF THE DIMENSION AT MAXIMUM MATERIAL CONDITION.

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