

## PIC18F23/43K20 Family Silicon Errata and Data Sheet Clarification

The PIC18F23/43K20 family devices that you have received conform functionally to the current Device Data Sheet (DS41303G), except for the anomalies described in this document.

The silicon issues discussed in the following pages are for silicon revisions with the Device and Revision IDs listed in Table 1. The silicon issues are summarized in Table 2.

The errata described in this document will be addressed in future revisions of the PIC18F23/43K20 silicon.

**Note:** This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current. Only the issues indicated in the last column of Table 2 apply to the current silicon revision.

Data Sheet clarifications and corrections start on page 6, following the discussion of silicon issues.

The silicon revision level can be identified using the current version of MPLAB® IDE and Microchip's programmers, debuggers, and emulation tools, which are available at the Microchip corporate web site ([www.microchip.com](http://www.microchip.com)).

For example, to identify the silicon revision level using MPLAB IDE in conjunction with MPLAB ICD 2, MPLAB ICD 3, PICkit™ 2 or PICkit 3:

1. Using the appropriate interface, connect the device to the MPLAB ICD 2 programmer/debugger, PICkit 2 or PICkit 3.
2. From the main menu in MPLAB IDE, select Configure>Select Device, and then select the target part number in the dialog box.
3. Select the MPLAB hardware tool (Programmer>Select Tool).
4. Perform a "Connect" operation to the device (Programmer>Connect). Depending on the development tool used, the part number and Device Revision ID value appear in the **Output** window.

**Note:** If you are unable to extract the silicon revision level, please contact your local Microchip sales office for assistance.

The Device ID values for the various devices and silicon revisions are shown in Table 1.

**TABLE 1: SILICON DEVREV VALUES**

Part Number	Device ID <sup>(1)</sup>	Revision ID for Silicon Revision <sup>(2)</sup>	
		A0	A1
PIC18F23K20	20E0h	00h	01h
PIC18F43K20	20C0h	00h	01h

- Note 1:** The device and revision data is stored in the Device ID located at 3FFFFE:3FFFFFh in Configuration and ID memory.
- 2:** Refer to the "PIC18F2XK20/4XK20 Memory Programming Specification" (DS41297) for detailed information.

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**TABLE 2: SILICON ISSUE SUMMARY (PIC18F23/43K20)**

Module	Feature	Item Number	Issue Summary	Affected Revisions <sup>(1)</sup>	
				A0	A1
ECCP	Full-Bridge	1.	Dead band time is $4/F_{OSC}$ instead of $1/F_{OSC}$ .	X	X
ECCP	Full-Bridge	2.	Compromised Dead Band.	X	X
MSSP	SPI clock	3.	Improper start in Timer2/2 Clock mode.	X	X
MSSP	SPI Master	4.	Improper sampling of last bit.	X	X
MSSP	SPI Master	5.	Write collision on transmission.	X	X
MSSP	I <sup>2</sup> C™ Master	6.	Improper handling of Stop event.	X	X
EUSART	OERR Flag	7.	Clearing SPEN bit does not clear OERR flag.	X	X
EUSART	BAUDCON	8.	RCIDL may improperly stay low.	X	X
Data EE Mem.	Endurance	9.	Endurance limited to 10K cycles.	X	X
Program Mem.	Endurance	10.	Endurance limited to 1K cycles.	X	X
ADC	ADC Conversion	11.	ADC conversion may be limited to half scale.	X	

**Note 1:** Only those issues indicated in the last column apply to the current silicon revision.

## Silicon Errata Issues

**Note:** This document summarizes all silicon errata issues from all revisions of silicon, previous as well as current. Only the issues indicated by the shaded column in the following tables apply to the current silicon revision (A0 or A2, as applicable).

### 1. Module: ECCP

Changing direction in Full-Bridge mode inserts a dead band time of  $4/F_{osc} * (TMR2 \text{ Prescale})$  instead of  $1/F_{osc} * (TMR2 \text{ Prescale})$  as specified in the data sheet.

**Work around**

None.

**Affected Silicon Revisions**

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A0	A1						
X	X						

### 2. Module: ECCP

In Full-Bridge mode when  $PR2 = CCPR1L$  and  $DC1B<1:0> = 00$  and the direction is changed then the dead time before the modulated output starts is compromised. The modulated signal improperly starts immediately with the direction change and stays on for  $T_{osc} * TMR2Presale * DC1B<1:0>$ .

**Work around**

Avoid changing direction when the duty cycle is within three Least Significant steps of 100% duty cycle. Instead, clear the  $DC1B<1:0>$  bits before the direction change and then set them to the desired value after the direction change is complete.

**Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

### 3. Module: MSSP (SPI clock)

When the SPI clock is configured for Timer2/2 ( $SSPCON1<3:0> = 0011$ ), and the  $CKE$  bit of the  $SSPSTAT$  register is '1', then when  $SSPBUF$  is written the  $SCK$  output is improperly and immediately driven to the non-Idle state together with the  $MSb$  value of the  $SSPBUF$ . The duration at which  $SDO$  and  $SCK$  remain at these levels may be shorter than a full half-bit period. The remaining bits in the byte are output properly.

**Work around**

None.

**Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

### 4. Module: MSSP (SPI Master mode)

In SPI Master mode, when the  $CKE$  bit of the  $SSPSTAT$  register is cleared and the  $SMP$  bit of the  $SSPSTAT$  register is set, then the last bit of the incoming data stream (bit 0) at the  $SDI$  pin will not be sampled properly.

**Work around**

none.

**Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

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## 5. Module: MSSP (SPI Master mode)

In SPI Master mode, if the SSPBUF register is written while a byte is actively being transmitted, an extra clock pulse will be improperly generated at the end of the transmission. Further writes to the SSPBUF register will be inhibited although 8 or 9 clock pulses will be generated for each attempted write. The WCON bit of the SSPCON register is properly set indicating that a write collision occurred. However, the write collision condition can only be cleared by resetting the MSSP module. Clear the MSSP by clearing the SSPEN bit of the SSPCON1 register.

### **Work around**

Use the SSPIF bit of the PIR1 register or the BF bit of the SSPSTAT register to determine that the transmission is complete before writing the SSPBUF register. In the event that a write collision does occur, use the Slave Select feature to resynchronize the Slave clock.

### **Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

## 6. Module: MSSP (Master I<sup>2</sup>C™ mode)

In Master I<sup>2</sup>C Receive mode, if a Stop condition occurs in the middle of an address or data reception, then the SCL clock stream will continue endlessly and the RCEN bit of the SSPCON2 register will remain set improperly. When a Start condition occurs after the improper Stop condition, then 9 additional clocks will be generated followed by the RCEN bit going low.

### **Work around**

Use low-impedance pull-ups on the SDA line to reduce the possibility of noise glitches, which may trigger an improper Stop event. Use a time-out event timer to detect the unexpected Stop condition and resulting stuck RCEN bit. Clear stuck RCEN bit by clearing SSPEN bit of SSPCON1.

### **Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

## 7. Module: EUSART

The OERR flag of the RCSTA register is reset only by clearing the CREN bit of the RCSTA register or by a device Reset. Clearing the SPEN bit of the RCSTA register does not clear the OERR flag.

### **Work around**

Clear the OERR flag by clearing the CREN bit instead of clearing the SPEN bit.

### **Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

## 8. Module: EUSART

In Asynchronous Receive mode, the RCIDL bit of the BAUDCON register will properly go low when an invalid Start bit less than 1/16th of a bit time is received. The RCIDL bit will then properly go high 1/8th of a bit time later. However, if another invalid Start bit occurs less than 1 bit time after the leading edge of the first invalid Start bit then the RCIDL bit will improperly stay high then improperly go low one bit time later. The RCIDL bit will then stay low improperly until a valid Start bit is received.

### **Work around**

When monitoring the RCIDL bit, measure the length of time between the RCIDL going low and the RCIF flag going high. If this time is greater than one character time then restore the RCIDL bit by resetting the EUSART module. The EUSART module is reset when the SPEN bit of the RCSTA register is cleared.

### **Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

## 9. Module: Data EEPROM Memory

The write/erase endurance of Data EE Memory is limited to 10K cycles.

### **Work around**

Use error correction method that stores data in multiple locations.

### **Affected Silicon Revisions**

PIC18F23/43K20

A0	A1						
X	X						

## 10. Module: Program Flash Memory

The write/erase endurance of the Program Flash Memory is limited to 1K cycles when VDD is above 3V. Endurance degrades when VDD is below 3V.

### Work around

For data tables in Program Flash Memory use error correction method that stores data in multiple locations.

### Affected Silicon Revisions

PIC18F23/43K20

A0	A1						
X	X						

## 11. Module: ADC

After extended stress the Most Significant bit (MSb) of the ADC conversion result can become stuck at '0'. Conversions resulting in code 511 or less are still accurate, but conversions that should result in codes greater than 511 are instead pinned at 511.

The potential for failures is a function of several factors:

- The potential for failures increases over the life of the part. No failures have ever been seen for accelerated stress estimated to be equivalent to 34 years at room temperature. The failure rate after accelerated stress estimated to be equivalent to 146 years at room temperature can be as high as 10% for VDD = 1.8V. The time to failure will decrease as the operating temperature increases.
- The potential for failures is highest at low VDD and decreases as VDD increases.

### Work around

1. Restrict the input voltage to less than 1/2 of the ADC voltage reference so that the expected result is always a code less than or equal to 511.
2. Use manual acquisition time (ACQT<2:0> = 000) and put the part to Sleep after each conversion.

### Affected Silicon Revisions

PIC18F23/43K20

A0	A1						
X							

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## Data Sheet Clarifications

The following typographical corrections and clarifications are to be noted for the latest version of the device data sheet (DS41303G):

None.

## APPENDIX A: DOCUMENT REVISION HISTORY

### Rev. A Document (4/2009)

First revision of this document.

Data Sheet Clarification: Added Module 1: MSSP I<sup>2</sup>C™ (Table 17-3); Module 2: ADC (Equation 19-1); Module 3: Interrupts.

Added Module 1: ECCP; Module 2: ECCP; Module 3: MSSP; Module 4: MSSP; Module 5: MSSP; Module 6: MSSP; Module 7: EUSART; Module 8: EUSART; Module 9: Data EEPROM Memory; Module 10: Program Flash Memory; Added Module 11: ADC.

### Rev. B Document (9/2009)

Added Silicon Revision A1.

Removed Data Sheet Clarification items.

### Rev. C Document (7/2010)

Removed ADC Work around #2 and changed #3 to #2 (Module 11).

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NOTES:



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**Note the following details of the code protection feature on Microchip devices:**

- Microchip products meet the specification contained in their particular Microchip Data Sheet.
- Microchip believes that its family of products is one of the most secure families of its kind on the market today, when used in the intended manner and under normal conditions.
- There are dishonest and possibly illegal methods used to breach the code protection feature. All of these methods, to our knowledge, require using the Microchip products in a manner outside the operating specifications contained in Microchip's Data Sheets. Most likely, the person doing so is engaged in theft of intellectual property.
- Microchip is willing to work with the customer who is concerned about the integrity of their code.
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