LTM4612



Ultralow Noise 36V_{IN}, 15V_{OUT}, 5A, DC/DC µModule Regulator **DESCRIPTION**

The LTM[®]4612 is a complete, ultralow noise, high voltage input and output, 5A switching mode DC/DC power supply. Included in the package are the switching controller, power FETs, inductor and all support components. Operating over an input voltage range of 5V to 36V, the LTM4612 supports an output voltage range of 3.3V to 15V, set by a single resistor. Only bulk input and output capacitors are needed to finish the design.

High switching frequency and an adaptive on-time current mode architecture enables a very fast transient response to line and load changes without sacrificing stability.

The onboard input filter and noise cancellation circuits achieve low noise coupling, thus effectively reducing the electromagnetic interference (EMI)—see Figures 4 and 8. Furthermore, the DC/DC μ Module[®] can be synchronized with an external clock to reduce undesirable frequency harmonics and allow PolyPhase[®] operation for high load currents.

The LTM4612 is offered in a space saving and thermally enhanced 15mm \times 15mm \times 2.8mm LGA package, which enables utilization of unused space on the bottom of PC boards for high density point-of-load regulation. The LTM4612 is Pb-free and RoHS compliant.

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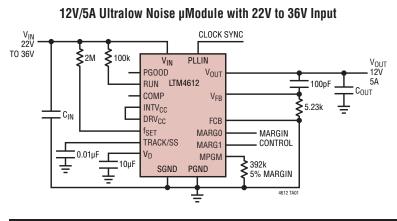
FEATURES

- Complete Low EMI Switch Mode Power Supply
- CISPR 22 Class B Compliant
- Wide Input Voltage Range: 5V to 36V
- 5A DC, 7A Peak Output Current
- 3.3V to 15V Output Voltage Range
- Low Input and Output Referred Noise
- Output Voltage Tracking and Margining
- PLL Frequency Synchronization
- ±1.5% Set Point Accuracy
- Power Good Tracks with Margining
- Current Foldback Protection (Disabled at Start-Up)
- Parallel/Current Sharing
- Ultrafast Transient Response
- Current Mode Control
- Programmable Soft-Start
- Output Overvoltage Protection
- –55°C to 125°C Operating Temperature Range (LTM4612MPV)
- Small Surface Mount Footprint, Low Profile (15mm × 15mm × 2.8mm) LGA Package

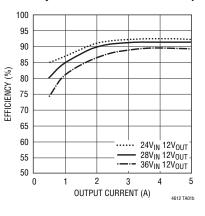
APPLICATIONS

- Telecom and Networking Equipment
- Industrial and Avionic Equipment
- RF Systems

TYPICAL APPLICATION



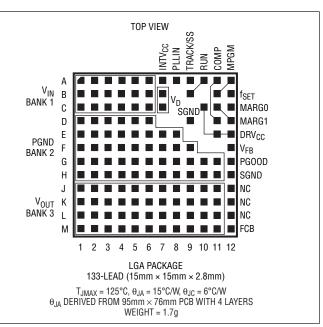
Efficiency vs Load Current at 12V Output



ABSOLUTE MAXIMUM RATINGS

(Note 1)
INTV _{CC.} DRV _{CC} 0.3V to 6V
V _{OUT} 0.3V to 16V
PLLIN, FCB, TRACK/SS, MPGM, MARGO,
MARG1, PGOOD0.3V to INTV _{CC} + 0.3V
RUN–0.3V to 5V
V _{FB} , COMP0.3V to 2.7V
V _{IN} , V _D –0.3V to 36V
Internal Operating Temperature Range (Note 2)
E and I Grades40°C to 125°C
MP Grade55°C to 125°C
Junction Temperature 125°C
Storage Temperature Range55°C to 125°C

PIN CONFIGURATION



ORDER INFORMATION

LEAD FREE FINISH	TRAY	PART MARKING*	PACKAGE DESCRIPTION	TEMPERATURE RANGE
LTM4612EV#PBF	LTM4612EV#PBF	LTM4612V	133-Lead (15mm \times 15mm \times 2.8mm) LGA	-40°C to 125°C
LTM4612IV#PBF	LTM4612IV#PBF	LTM4612V	133-Lead (15mm × 15mm × 2.8mm) LGA	-40°C to 125°C
LTM4612MPV#PBF	LTM4612MPV#PBF	LTM4612MPV	133-Lead (15mm \times 15mm \times 2.8mm) LGA	–55°C to 125°C

Consult LTC Marketing for parts specified with wider operating temperature ranges. *The temperature grade is identified by a label on the shipping container. For more information on lead free part marking, go to: http://www.linear.com/leadfree/

This product is only offered in trays. For more information go to: http://www.linear.com/packaging/

ELECTRICAL CHARACTERISTICS

The • denotes the specifications which apply over the full internal operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$, $V_{IN} = 24V$, unless otherwise noted. Per Typical Application (front page) configuration.

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V _{IN(DC)}	Input DC Voltage			5		36	V
V _{OUT(DC)}	Output Voltage	$ \begin{array}{c} C_{IN} = 10 \mu F \times 3, \ C_{OUT} = 300 \mu F; \ FCB = 0 \\ V_{IN} = 24 V, \ V_{OUT} = 12 V, \ I_{OUT} = 0 A \\ V_{IN} = 36 V, \ V_{OUT} = 12 V, \ I_{OUT} = 0 A \end{array} $	•	11.83 11.83	12.07 12.07	12.31 12.31	V V
Input Specificat	ions						
V _{IN(UVLO)}	Undervoltage Lockout Threshold	I _{OUT} = 0A			3.2	4.8	V
I _{INRUSH} (VIN)	Input Inrush Current at Start-Up	$\label{eq:IOUT} \begin{array}{l} I_{OUT} = 0A; \ C_{IN} = 10 \mu F \times 2, \ C_{OUT} = 200 \mu F; \\ V_{OUT} = 12V \\ V_{IN} = 24V \\ V_{IN} = 36V \end{array}$			0.6 0.7		A



ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the full internal operating temperature range, otherwise specifications are at T_A = 25°C, V_{IN} = 24V, unless otherwise noted. Per Typical Application (front page) configuration.

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
I _{Q(VIN)}	Input Supply Bias Current	$ \begin{array}{l} V_{IN} = 36V, V_{OUT} = 12V, Switching Continuous \\ V_{IN} = 24V, V_{OUT} = 12V, Switching Continuous \\ Shutdown, RUN = 0, V_{IN} = 36V \end{array} $			57 48 50		mA mA μA
I _{S(VIN)}	Input Supply Current	V_{IN} = 36V, V_{OUT} = 12V, I_{OUT} = 5A V_{IN} = 24V, V_{OUT} = 12V, I_{OUT} = 5A			1.85 2.72		A A
VINTVCC	Internal V _{CC} Voltage	V _{IN} = 36V, RUN > 2V, I _{OUT} = 0A		4.7	5	5.3	V
Output Specifica	tions						
I _{OUT(DC)}	Output Continuous Current Range	V _{IN} = 24V, V _{OUT} = 12V (Note 4)		0	-	5	A
$\frac{\Delta V_{OUT(LINE)}}{V_{OUT}}$	Line Regulation Accuracy	V_{OUT} = 12V, FCB = 0V, $V_{\rm IN}$ = 22V to 36V, $I_{\rm OUT}$ = 0A	•		0.05	0.3	%
$\frac{\Delta V_{OUT(LOAD)}}{V_{OUT}}$	Load Regulation Accuracy	V_{OUT} = 12V, FCB = 0V, I_{OUT} = 0A to 5A (Note 4) $V_{\rm IN}$ = 36V $V_{\rm IN}$ = 24V	•		0.3 0.3	0.6 0.6	%
VIN(AC)	Input Ripple Voltage	$\label{eq:IOUT} \begin{array}{l} I_{OUT} = 0 \text{A}, \\ C_{IN} = 2 \times 10 \mu \text{F X5R Ceramic and } 1 \times 100 \mu \text{F} \\ \text{Electrolytic, } 1 \times 10 \mu \text{F X5R Ceramic on } V_D \text{ Pins} \\ V_{IN} = 24 \text{V}, V_{OUT} = 5 \text{V} \\ V_{IN} = 24 \text{V}, V_{OUT} = 12 \text{V} \end{array}$			7.2 3.4		mV _{P-P}
V _{OUT(AC)}	Output Ripple Voltage	$ I_{OUT} = 0A, \\ C_{OUT} = 2 \times 22 \mu F, 2 \times 47 \mu F X5R \ Ceramic \\ V_{IN} = 24V, \ V_{OUT} = 5V \\ V_{IN} = 24V, \ V_{OUT} = 12V $			17.5 12.5		mV _{P-P} mV _{P-P}
f _S	Output Ripple Voltage Frequency	I _{OUT} = 1A, V _{IN} = 24V, V _{OUT} = 12V			940		kHz
$\Delta V_{OUT(START)}$	Turn-On Overshoot, TRACK/SS = 10nF	C_{OUT} = 200µF, V_{OUT} = 12V, I_{OUT} = 0A $V_{\rm IN}$ = 36V $V_{\rm IN}$ = 24V			20 20		mV mV
t _{start}	Turn-On Time, TRACK/SS = Open	C_{OUT} = 300µF, V_{OUT} = 12V, I_{OUT} = 1A Resistive Load V_{IN} = 36V V_{IN} = 24V			0.5 0.5		ms ms
$\Delta V_{OUT(LS)}$	Peak Deviation for Dynamic Load	Load: 0% to 50% to 0% of Full Load C _{OUT} = 2 × 22µF Ceramic, 150µF Bulk V _{IN} = 24V, V _{OUT} = 12V			153		mV
t _{SETTLE}	Settling Time for Dynamic Load Step	Load: 0% to 50% to 0% of Full Load, V_{IN} = 24V			37		μs
I _{OUT(PK)}	Output Current Limit	$C_{OUT} = 200 \mu F$ $V_{IN} = 36V, V_{OUT} = 12V$ $V_{IN} = 24V, V_{OUT} = 12V$			9 9		A
Control Section		· · · · · · · · · · · · · · · · · · ·					
V _{FB}	Voltage at V _{FB} Pin	$I_{OUT} = 0A, V_{OUT} = 12V$	٠	0.591	0.6	0.609	V
V _{RUN}	RUN Pin On/Off Threshold			1	1.5	1.9	V
I _{SS/TRACK}	Soft-Start Charging Current	V _{SS/TRACK} = 0V		-1	-1.5	-2	μA
V _{FCB}	Forced Continuous Threshold			0.57	0.6	0.63	V
I _{FCB}	Forced Continuous Pin Current	V _{FCB} = 0V			-1	-2	μA
t _{ON(MIN)}	Minimum On-Time	(Note 3)			50	100	ns
t _{OFF(MIN)}	Minimum Off-Time	(Note 3)			250	400	ns
R _{PLLIN}	PLLIN Input Resistor				50		kΩ



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ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the -40°C to 85°C operating temperature range, otherwise specifications are at T_A = 25°C, V_{IN} = 24V, unless otherwise noted. Per Typical Application (front page) configuration.

SYMBOL	PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
IDRVCC	Current into DRV _{CC} Pin	V _{OUT} = 12V, I _{OUT} = 1A		22	30	mA
R _{FBHI}	Resistor Between $V_{\mbox{OUT}}$ and $V_{\mbox{FB}}$ Pins		99.5	100	100.5	kΩ
V _{MPGM}	Margin Reference Voltage			1.18		V
V _{MARG0} , V _{MARG1}	MARG0, MARG1 Voltage Thresholds			1.4		V
PGOOD						
ΔV_{FBH}	PGOOD Upper Threshold	V _{FB} Rising	7	10	13	%
ΔV_{FBL}	PGOOD Lower Threshold	V _{FB} Falling	-7	-10	-13	%
ΔV _{FB(HYS)}	PGOOD Hysteresis	V _{FB} Returning		1.5		%
V _{PGL}	PGOOD Low Voltage	I _{PGOOD} = 5mA		0.15	0.4	V

Note 1: Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

Note 2: The LTM4612E is guaranteed to meet performance specifications over the 0°C to 125°C internal operating temperature range. Specifications over the -40°C to 125°C internal operating temperature range are assured by design, characterization and correlation with statistical process controls. The LTM4612I is guaranteed to meet specifications over the

-40°C to 125°C internal operating temperature range. The LTM4612MP is guaranteed and tested over the full -55°C to 125°C internal operating temperature range. Note that the maximum ambient temperature is determined by specific operating conditions in conjunction with board layout, the rated package thermal resistance and other environmental factors.

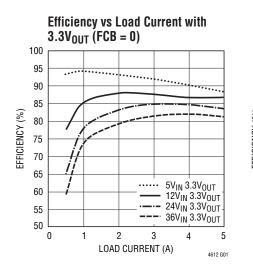
Note 3: 100% tested at die level only.

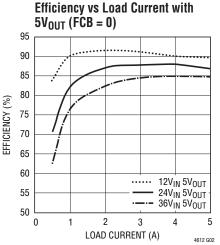
Note 4: See the Output Current Derating curves for different V_{IN} , V_{OUT} and T_A.





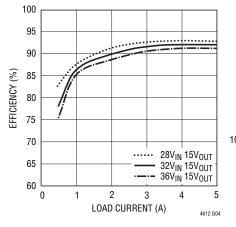
TYPICAL PERFORMANCE CHARACTERISTICS (Refer to Figure 18)





Efficiency vs Load Current with $12V_{OUT}$ (FCB = 0) 100 95 90 85 EFFICIENCY (%) 80 75 70 65 20VIN 12VOUT 60 24VIN 12VOUT 28VIN 12VOUT 55 36VIN 12VOUT ___ 50 2 3 0 1 4 5 LOAD CURRENT (A) 4612 G03

Efficiency vs Load Current with 15V_{OUT} (FCB = 0, Refer to Figure 20)

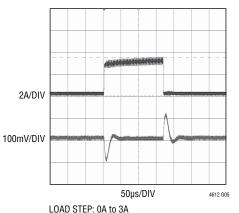


Transient Response from 24V_{IN} to 12V_{OUT}



 $C_{OUT} = 2 \times 22 \mu F$ CERAMIC CAPACITORS AND $2 \times 47 \mu F$ CERAMIC CAPACITORS

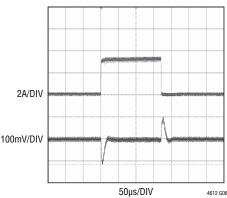
Transient Response from $12V_{IN}$ to $3.3V_{OUT}$



LOAD STEP: 0A to 3A $C_{OUT} = 2 \times 22\mu$ F CERAMIC CAPACITORS AND $2 \times 47\mu$ F CERAMIC CAPACITORS

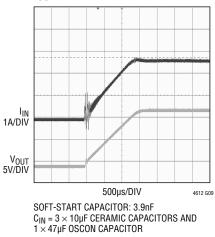
Start-Up with 24V_{IN} to 12V_{OUT} at I_{OUT} = 0A

Transient Response from $12 V_{\text{IN}}$ to $5 V_{\text{OUT}}$



LOAD STEP: 0A to 3A C_{OUT} = $2\times22\mu F$ CERAMIC CAPACITORS AND $2\times47\mu F$ CERAMIC CAPACITORS

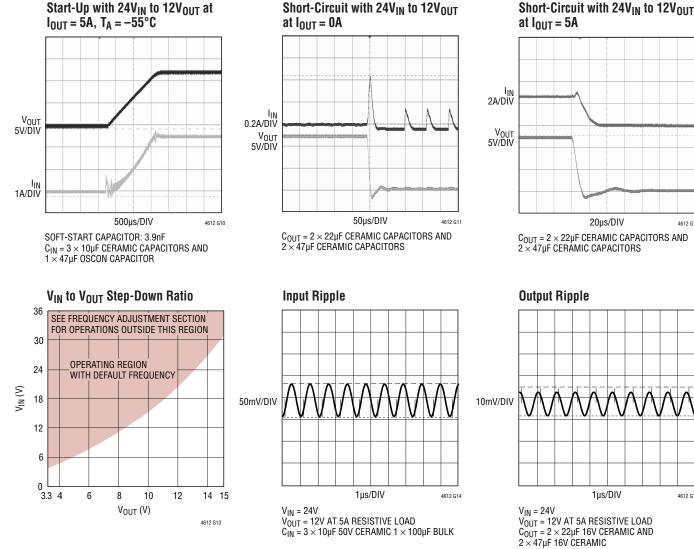
Start-Up with 24V $_{\rm IN}$ to 12V $_{\rm OUT}$ at I $_{\rm OUT}$ = 5A

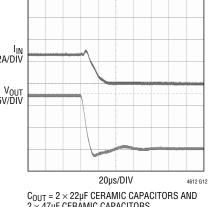


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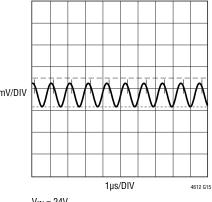
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TYPICAL PERFORMANCE CHARACTERISTICS





 $2 \times 47 \mu F$ CERAMIC CAPACITORS



 $V_{OUT} = 12V \text{ AT 5A RESISTIVE LOAD} \\ C_{OUT} = 2 \times 22 \mu\text{F 16V CERAMIC AND} \\ 2 \times 47 \mu\text{F 16V CERAMIC}$



PIN FUNCTIONS (See Package Description for Pin Assignments)

 $V_{\rm IN}$ (Bank 1): Power Input Pins. Apply input voltage between these pins and PGND pins. Recommend placing input decoupling capacitance directly between $V_{\rm IN}$ pins and PGND pins.

PGND (Bank 2): Power Ground Pins for Both Input and Output Returns.

V_{OUT} (Bank 3): Power Output Pins. Apply output load between these pins and PGND pins. Recommend placing output decoupling capacitance directly between these pins and GND pins (see the LTM4612 Pin Configuration below).

 V_D (Pins B7, C7): Top FET Drain Pins. Add more capacitors between V_D and ground to handle the input RMS current and reduce the input ripple further.

DRV_{CC} (Pins C10, E11, E12): These pins normally connect to $INTV_{CC}$ for powering the internal MOSFET drivers. They can be biased up to 6V from an external supply with about 50mA capability. This improves efficiency at the higher input voltages by reducing power dissipation in the module.

INTV_{CC} (Pin A7): This pin is for additional decoupling of the 5V internal regulator.

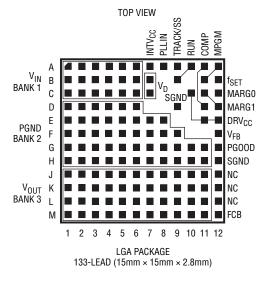
PLLIN (Pin A8): External Clock Synchronization Input to the Phase Detector. This pin is internally terminated to SGND with a 50k resistor. Apply a clock above 2V and below $INTV_{CC}$. See the Applications Information section.

FCB (Pin M12): Forced Continuous Input. Connect this pin to SGND to force continuous synchronization operation at low load, to $INTV_{CC}$ to enable discontinuous mode operation at low load or to a resistive divider from a secondary output when using a secondary winding.

TRACK/SS (Pin A9): Output Voltage Tracking and Soft-Start Pin. When the module is configured as a master output, then a soft-start capacitor is placed on this pin to ground to control the master ramp rate. A soft-start capacitor can be used for soft-start turn-on as a standalone regulator. Slave operation is performed by putting a resistor divider from the master output to the ground, and connecting the center point of the divider to this pin. See the Applications Information section.

MPGM (Pins A12, B11): Programmable Margining Input. A resistor from these pins to ground sets a current that is equal to 1.18V/R. This current multiplied by 10k will equal a value in millivolts that is a percentage of the 0.6V reference voltage. See the Applications Information section. To parallel LTM4612s, each requires an individual MPGM resistor. Do not tie MPGM pins together.

f_{SET} (Pin B12): Frequency Set Internally to 850kHz at 12V Output. An external resistor can be placed from this pin to ground to increase frequency. This pin can be decoupled with a 1000pF capacitor. See the Applications Information section for frequency adjustment.



LTM4612 Pin Configuration

PIN FUNCTIONS

 V_{FB} (Pin F12): The Negative Input of the Error Amplifier. Internally, this pin is connected to V_{OUT} with a 100k precision resistor. Different output voltages can be programmed with an additional resistor between the V_{FB} and SGND pins. See the Applications Information section.

MARGO (Pin C12): LSB Logic Input for the Margining Function. Together with the MARG1 pin, the MARG0 pin will determine if a margin high, margin low, or no margin state is applied. The pin has an internal pull-down resistor of 50k. See the Applications Information section.

MARG1 (Pins C11, D12): MSB Logic Input for the Margining Function. Together with the MARG0 pin, the MARG1 pin will determine if a margin high, margin low, or no margin state is applied. The pins have an internal pull-down resistor of 50k. See the Applications Information section.

SGND (Pins D9, H12): Signal Ground Pins. These pins connect to PGND at output capacitor point.

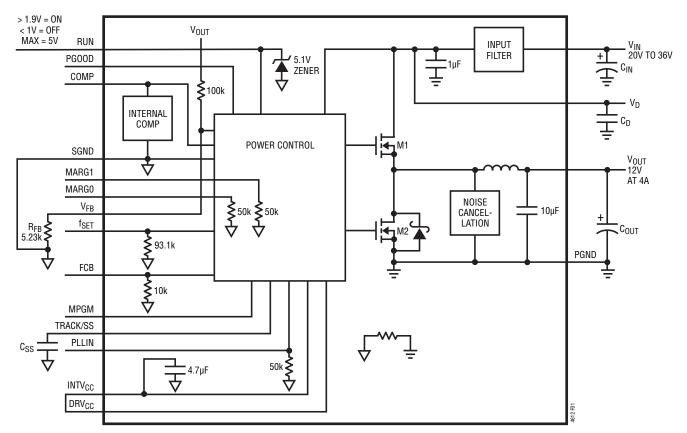
COMP (Pins A11, D11): Current Control Threshold and Error Amplifier Compensation Point. The current comparator threshold increases with this control voltage. The voltage ranges from 0V to 2.4V with 0.7V corresponding to zero sense voltage (zero current).

PGOOD (Pin G12): Output Voltage Power Good Indicator. Open-drain logic output that is pulled to ground when the output voltage is not within $\pm 10\%$ of the regulation point, after a 25µs power bad mask timer expires.

RUN (Pins A10, B9): Run Control Pins. A voltage above 1.9V will turn on the module, and below 1V will turn off the module. A programmable UVLO function can be accomplished with a resistor from V_{IN} to this pin that is has a 5.1V zener to ground. Maximum pin voltage is 5V.

NC (Pins J12, K12, L12): No Connect Pins.

BLOCK DIAGRAM





DECOUPLING REQUIREMENTS Specifications are at $T_A = 25^{\circ}C$. Use Figure 1 configuration.

SYMBOL	PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
C _{IN}	External Input Capacitor Requirement (V _{IN} = 20V to 36V, V _{OUT} = 12V)	I _{OUT} = 4A	10			μF
C _{OUT}	External Output Capacitor Requirement (V _{IN} = 20V to 36V, V _{OUT} = 12V)	I _{OUT} = 4A	100	150		μF



9

OPERATION

Power Module Description

The LTM4612 is a standalone nonisolated switching mode DC/DC power supply. It can deliver 5A of DC output current with some external input and output capacitors. This module provides precisely regulated output voltage programmable via one external resistor from $3.3V_{DC}$ to $15V_{DC}$ over a 5V to 36V wide input voltage. The typical application schematic is shown in Figure 18.

The LTM4612 has an integrated constant on-time current mode regulator, ultralow $R_{DS(ON)}$ FETs with fast switching speed and integrated Schottky diodes. The typical switching frequency is 850kHz at full load at 12V output. With current mode control and internal feedback loop compensation, the LTM4612 module has sufficient stability margins and good transient performance under a wide range of operating conditions and with a wide range of output capacitors, even all ceramic output capacitors.

Current mode control provides cycle-by-cycle fast current limiting. Moreover, foldback current limiting is provided in an overcurrent condition while V_{FB} drops. Internal overvoltage and undervoltage comparators pull the open-drain PGOOD output low if the output feedback voltage exits a $\pm 10\%$ window around the regulation point. Furthermore, in an overvoltage condition, internal top FET M1 is turned off and bottom FET M2 is turned on and held on until the overvoltage condition clears.

Input filter and noise cancellation circuitry reduce the noise coupling to I/O sides, and ensure the electromagnetic interference (EMI) meets the limits of CISPR 22 and CISPR 25.

Pulling the RUN pin below 1V forces the controller into its shutdown state, turning off both M1 and M2. At low load currents, discontinuous mode (DCM) operation can be enabled to achieve higher efficiency compared to continuous mode (CCM) by setting FCB pin higher than 0.6V.

When the DRV_{CC} pin is connected to $INTV_{CC}$, an integrated 5V linear regulator powers the internal gate drivers. If a 5V external bias supply is applied on DRV_{CC} pin, then an efficiency improvement will occur due to the reduced power loss in the internal linear regulator. This is especially true at the higher input voltage range.

The MPGM, MARGO, and MARG1 pins are used to support voltage margining, where the percentage of margin is programmed by the MPGM pin, and the MARGO and MARG1 selected margining. The PLLIN pin provides frequency synchronization of the device to an external clock. The TRACK/SS pin is used for power supply tracking and soft-start programming.

The typical LTM4612 application circuit is shown in Figure 18. External component selection is primarily determined by the maximum load current and output voltage. Refer to Table 2 for specific external capacitor requirements for a particular application.

VIN to VOUT Stepdown Ratios

There are restrictions in the maximum V_{IN} and V_{OUT} step down ratio that can be achieved for a given input voltage. These constraints are shown in the Typical Performance Characteristic curve labeled " V_{IN} to V_{OUT} Step-Down Ratio." Note that additional thermal derating may be applied. See the Thermal Considerations and Output Current Derating section in this data sheet.

Output Voltage Programming and Margining

The PWM controller has an internal 0.6V reference voltage. As shown in the Block Diagram, a 100k internal feedback resistor connects the V_{OUT} and V_{FB} pins together. Adding a resistor, R_{FB} , from the V_{FB} pin to the SGND pin programs the output voltage.

$$V_{OUT} = 0.6V \bullet \frac{100k + R_{FB}}{R_{FB}}$$

Table 1. R_{FB} Standard 1% Resistor Values vs V_{OUT}

V _{OUT} (V)	3.3	5	6	8	10	12	14	15
$\mathbf{R}_{\mathbf{FB}}$ (k Ω)	22.1	13.7	11	8.06	6.34	5.23	4.42	4.12

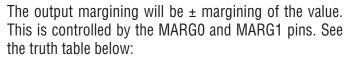
The MPGM pin programs a current that when multiplied by an internal 10k resistor sets up the 0.6V reference \pm offset for margining. A 1.18V reference divided by the R_{PGM} resistor on the MPGM pin programs the current. Calculate V_{OUT(MARGIN)}:

$$V_{OUT(MARGIN)} = \frac{\% V_{OUT}}{100} \bullet V_{OUT}$$

Where %V_{OUT} is the percentage of V_{OUT} to be margined, and V_{OUT(MARGIN)} is the margin quantity in volts:

$$R_{PGM} = \frac{V_{OUT}}{0.6V} \bullet \frac{1.18V}{V_{OUT(MARGIN)}} \bullet 10k$$

Where $\mathsf{R}_{\mathsf{PGM}}$ is the resistor value to place on the MPGM pin to ground.



MARG1	MARGO	MODE
LOW	LOW	NO MARGIN
LOW	HIGH	MARGIN UP
HIGH	LOW	MARGIN DOWN
HIGH	HIGH	NO MARGIN

Operating Frequency

The operating frequency of the LTM4612 is optimized to achieve the compact package size and the minimum output ripple voltage while still keeping high efficiency. As shown in Figure 2, the frequency is linearly increased with larger output voltages to keep the low output current ripple. Figure 3 shows the inductor current ripple ΔI with different output voltages. In most applications, no additional frequency adjusting is required.

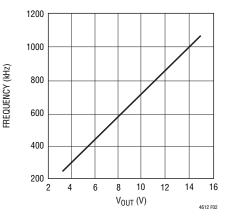


Figure 2. Operating Frequency vs Output Voltage

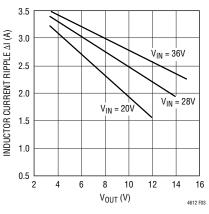


Figure 3. Inductor Current Ripple vs Output Voltage



If lower output ripple is required, the operating frequency f can be increased by adding a resistor R_{fSFT} between f_{SFT} pin and SGND, as shown in Figure 19.

$$f = \frac{V_{OUT}}{1.5 \bullet 10^{-10} (R_{fSET} || 93.1k)}$$

For output voltages more than 12V, the frequency can be higher than 1 MHz, thus reducing the efficiency significantly. Additionally, the minimum off time 400ns normally limits the operation when the input voltage is close to the output voltage. Therefore, it is recommended to lower the frequency in these conditions by connecting a resistor (R_{fSFT}) from the f_{SFT} pin to V_{IN}, as shown in Figure 20.

$$f = \frac{V_{OUT}}{5 \cdot 10^{-11} \left(\frac{3 \cdot R_{fSET} \cdot 93.1k}{R_{fSET} - 2 \cdot 93.1k} \right)}$$

The load current can affect the frequency due to its constant on-time control. If constant frequency is a necessity, the PLLIN pin can be used to synchronize the frequency of the LTM4612 to an external clock, as shown in Figures 21 to 23.

Input Capacitors

LTM4612 is designed to achieve the low input conducted EMI noise due to the fast switching of turn-on and turn-off. In the LTM4612, a high-frequency inductor is integrated into the input line for noise attenuation. V_D and V_{IN} pins are available for external input capacitors to form a high frequency π filter. As shown in Figure 18, the ceramic capacitor C1 on the V_D pins is used to handle most of the RMS current into the converter, so careful attention is needed for capacitor C1 selection.

For a buck converter, the switching duty cycle can be estimated as:

$$D = \frac{V_{OUT}}{V_{IN}}$$

Without considering the inductor current ripple, the RMS current of the input capacitor can be estimated as:

$$I_{CIN(RMS)} = \frac{I_{OUT(MAX)}}{\eta} \bullet \sqrt{D \bullet (1-D)}$$

12

In this equation, η is the estimated efficiency of the power module. Note the capacitor ripple current ratings are often based on temperature and hours of life. This makes it advisable to properly derate the input capacitor, or choose a capacitor rated at a higher temperature than required. Always contact the capacitor manufacturer for derating requirements.

In a typical 5A output application, one very low ESR, X5R or X7R, 10µF ceramic capacitor is recommended for C1. This decoupling capacitor should be placed directly adjacent to the module V_{D} pins in the PCB layout to minimize the trace inductance and high frequency AC noise. Each 10µF ceramic is typically good for 2A to 3A of RMS ripple current. Refer to your ceramics capacitor catalog for the RMS current ratings.

To attenuate the high frequency noise, extra input capacitors should be connected to the V_{IN} pads and placed before the high frequency inductor to form the π filter. One of these low ESR ceramic input capacitors is recommended to be close to the connection into the system board. A large bulk 100µF capacitor is only needed if the input source impedance is compromised by long inductive leads or traces. Figure 4 shows the conducted EMI testing results to meet the Level 5 of the CISPR 25 limit. For different applications, input capacitance may be varied to meet different conducted EMI limits.

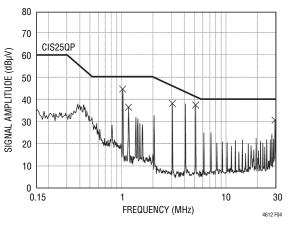


Figure 4. Conducted Emission Scan with 24V_{IN} to $12V_{OUT}$ at 5A (3 \times 10µF Ceramic Capacitors on V_{IN} Pads and $1 \times 10 \mu F$ Ceramic Capacitor on V_D Pads).



Output Capacitors

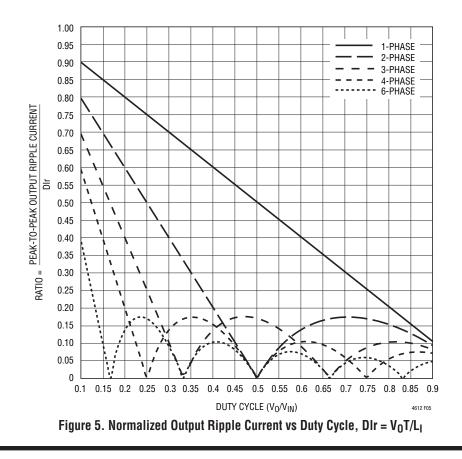
The LTM4612 is designed for low output voltage ripple. The bulk output capacitors defined as C_{OUT} are chosen with low enough effective series resistance (ESR) to meet the output voltage ripple and transient requirements. C_{OUT} can be low ESR tantalum capacitor, low ESR polymer capacitor or ceramic capacitor. The typical capacitance is 150µF if all ceramic output capacitors are used. Additional output filtering may be required by the system designer, if further reduction of output ripple or dynamic transient spike is required. Table 2 shows a matrix of different output voltage droop and overshoot during a 2A/µs transient. The table optimizes total equivalent ESR and total bulk capacitance to maximize transient performance.

Multiphase operation with multiple LTM4612 devices in parallel will also lower the effective output ripple current due to the phase interleaving operation. Refer to Figure 5 for the normalized output ripple current versus the duty cycle. Figure 5 provides a ratio of peak-to-peak output ripple current to the inductor ripple current as functions of duty cycle and the number of paralleled phases. Pick the corresponding duty cycle and the number of phases to get the correct output ripple current value. For example, each phase's inductor ripple current DIr at zero duty cycle is ~4.3A for a 36V to 12V design. The duty cycle is about 0.33. The 2-phase curve has a ratio of ~0.33 for a duty cycle of 0.33. This 0.33 ratio of output ripple current to the inductor ripple current DIr at 4.3A equals 1.4A of the output ripple current (ΔI_L).

The output voltage ripple has two components that are related to the amount of bulk capacitance and effective series resistance (ESR) of the output bulk capacitance. The equation is:

$$\Delta V_{OUT(P-P)} \approx \left(\frac{\Delta I_L}{8 \bullet f \bullet N \bullet C_{OUT}}\right) + ESR \bullet \Delta I_L$$

Where f is the frequency and N is the number of paralleled phases.





Fault Conditions: Current Limit and **Overcurrent Foldback**

LTM4612 has a current mode controller, which inherently limits the cycle-by-cycle inductor current not only in steady state operation, but also in transient.

To further limit current in the event of an overload condition, the LTM4612 provides foldback current limiting. If the output voltage falls by more than 50%, then the maximum output current is progressively lowered to about one sixth of its full current limit value.

Soft-Start and Tracking

The TRACK/SS pin provides a means to either soft-start the regulator or track it to a different power supply. A capacitor on this pin will program the ramp rate of the output voltage. A 1.5µA current source will charge up the external soft-start capacitor to 80% of the 0.6V internal voltage reference minus any margin delta. This will control the ramp of the internal reference and the output voltage. The total soft-start time can be calculated as:

$$t_{SOFTSTART} \cong 0.8 \bullet (0.6 - 0.6 \bullet V_{OUT} Margin \%) \bullet \frac{C_{SS}}{1.5 \mu A}$$

If the RUN pin falls below 2.5V, then the soft-start pin is reset to allow for the proper soft-start again. Current foldback and force continuous mode are disabled during the soft-start process. The soft-start function can also be used to control the output ramp rising time, so that another regulator can be easily tracked.

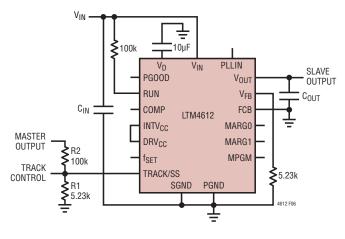


Figure 6. Coincident Tracking

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Output Voltage Tracking

Output voltage tracking can be programmed externally using the TRACK/SS pin. The output can be tracked up and down with another regulator. The master regulator's output is divided down with an external resistor divider that is the same as the slave regulator's feedback divider. Figure 6 shows an example of coincident tracking. Ratiometric modes of tracking can be achieved by selecting different resistor values to change the output tracking ratio. The master output must be greater than the slave output for the tracking to work. Figure 7 shows the coincident output tracking.

RUN Enable

The RUN pin is used to enable the power module. The pin has an internal 5.1V zener to ground. The pin can be driven with 5V logic levels.

The RUN pin can also be used as an undervoltage lockout (UVLO) function by connecting a resistor divider from the input supply to the RUN pin. The equation for UVLO threshold:

$$V_{UVL0} = \frac{R1 + R2}{R2} \bullet 1.5V$$

where R1 is the top resistor, and R2 is the bottom resistor.

Power Good

The PGOOD pin is an open-drain pin that can be used to monitor valid output voltage regulation. This pin monitors a $\pm 10\%$ window around the regulation point, and tracks with margining.

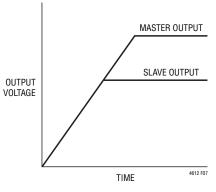


Figure 7. Coincident Output Tracking



COMP Pin

The pin is the external compensation pin. The module has already been internally compensated for most output voltages. An Excel design tool from Linear Technology will be provided for more control loop optimization.

FCB Pin

The FCB pin determines whether the bottom MOSFET remains on when current reverses in the inductor. Tying this pin above its 0.6V threshold enables discontinuous operation where the bottom MOSFET turns off when inductor current reverses. FCB pin below the 0.6V threshold forces continuous synchronous operation, allowing current to reverse at light loads and maintaining high frequency operation.

PLLIN Pin

The power module has a phase-locked loop comprised of an internal voltage controlled oscillator and a phase detector. This allows the internal top MOSFET turn-on to be locked to the rising edge of the external clock. The frequency range is $\pm 30\%$ around the set operating frequency. A pulse detection circuit is used to detect a clock on the PLLIN pin to turn on the phase-locked loop. The pulse width of the clock has to be at least 400ns, and 2V in amplitude. During the start-up of the regulator, the phase-locked loop function is disabled.

$\mathsf{INTV}_{\mathsf{CC}}$ and $\mathsf{DRV}_{\mathsf{CC}}$ Connection

An internal low dropout regulator produces an internal 5V supply that powers the control circuitry and DRV_{CC} for driving the internal power MOSFETs. Therefore, if the system does not have a 5V power rail, the LTM4612 can be directly powered by V_{IN} . The gate driver current through the LDO is about 20mA. The internal LDO power dissipation can be calculated as:

 $P_{LDO_LOSS} = 20mA \bullet (V_{IN} - 5V)$

The LTM4612 also provides the external gate driver voltage pin DRV_{CC}. If there is a 5V rail in the system, it is recommended to connect the DRV_{CC} pin to the external 5V rail. This is especially true for higher input voltages. Do not apply more than 6V to the DRV_{CC} pin.

Parallel Operation

The LTM4612 device is an inherently current mode controlled device. This allows the paralleled modules to have very good current sharing and balanced thermal on the design. Figure 21 shows a schematic of the parallel design. The voltage feedback equation changes with the variable N as modules are paralleled. The equation:

$$V_{OUT} = 0.6V \frac{\frac{100k}{N} + R_{FB}}{R_{FB}}$$

N is the number of paralleled modules.

Radiated EMI Noise

High radiated EMI noise is a disadvantage for switching regulators by nature. Fast switching turn-on and turn-off make the large di/dt change in the converters, which act as the radiation sources in most systems. LTM4612 integrates the feature to minimize the radiated EMI noise to meet the most applications with low noise requirements. An optimized gate driver for the MOSFET and a noise cancellation network are installed inside the LTM4612 to achieve the low radiated EMI noise. Figure 8 shows a typical example for the LTM4612 to meet the Class B of CISPR 22 radiated emission limit.

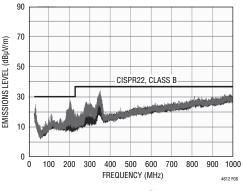


Figure 8. Radiated Emission Scan with $24V_{IN}$ to $12V_{OUT}$ at 5A Measured in 10 Meter Chamber

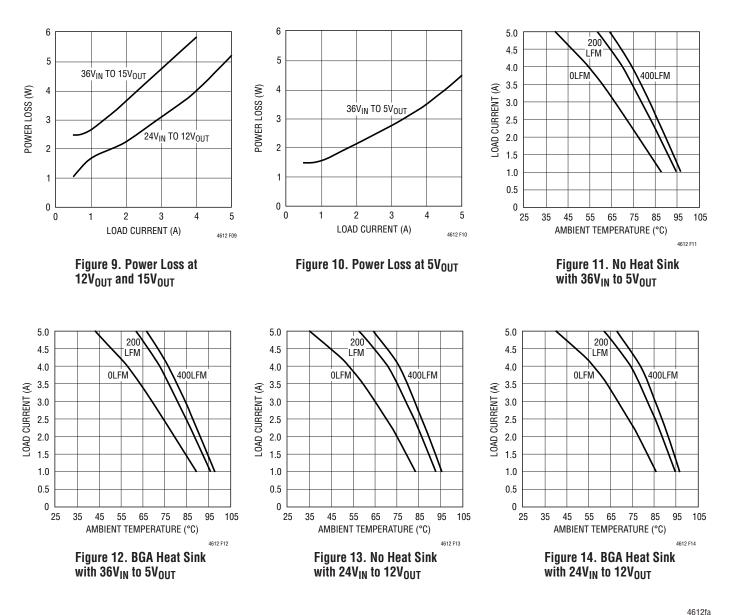
Thermal Considerations and Output Current Derating

In different applications, LTM4612 operates in a variety of thermal environments. The maximum output current is limited by the environment thermal condition. Sufficient cooling should be provided to help ensure reliable opera-



tion. When the cooling is limited, proper output current derating is necessary, considering ambient temperature, airflow, input/output condition, and the need for increased reliability.

The power loss curves in Figures 9 and 10 can be used in coordination with the load current derating curves in Figures 11 to 16 for calculating an approximate θ_{JA} for the module. Graph designation delineates between no heat sink, and a BGA heat sink. Each of the load current derating curves will lower the maximum load current as a function of the increased ambient temperature to keep the maximum junction temperature of the power module at 125°C maximum. This will maintain the maximum operating temperature below 125°C. Each of the derating curves and the power loss curve that corresponds to the correct output voltage can be used to solve for the approximate θ_{JA} of the condition. Each figure has three curves that are taken at three different air flow conditions. Each of the derating curves in Figures 11 to 16 can be used with the appropriate power loss curve in either Figure 9 or Figure 10 to derive an approximate θ_{JA} . Table 3 provides the approximate θ_{JA} for Figures 11 to 16. A complete explanation of the thermal characteristics is provided in the thermal application note, AN110.



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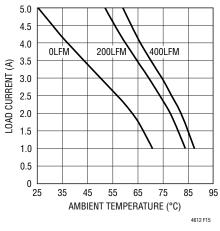


Figure 15. No Heat Sink with $36V_{IN}$ to $15V_{OUT}$

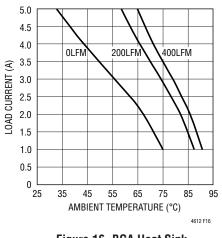


Figure 16. BGA Heat Sink with $36V_{IN}$ to $15V_{OUT}$

Table 2. Output Voltage Response Versus	Component Matrix (Refer to Figure 20)

VENDORS		PART NUM	BER			VENDORS		PART NUMBER	}	
Murata		GRM32ER6	GRM32ER61C476KEI5L (47µF, 16V)			Murata		GRM32ER71H106K (10µF, 50V)		
Vurata		GRM32ER6	61C226KE20L (22µ	F, 16V)		TDK		C3225X5RIC22	26M (22µF, 16V)	
V _{OUT} (V)	C _{in} (Ceramic)	C _{IN} (BULK)	C _{out1} (ceramic)	C _{OUT2} (BULK)	V _{IN} (V)	DROOP (mV)	PEAK-TO- PEAK (mV)	RECOVERY TIME (µs)	LOAD STEP (A/µs)	R _{FB} (kΩ)
5	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F 16V$	150µF 25V	12	86	156	26	3	13.7
5	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	12	86	178	14.8	3	13.7
5	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F 16V$	150µF 25V	24	83	166	27	3	13.7
5	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	24	86	169	14.8	3	13.7
5	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F 16V$	150µF 25V	36	86	178	25	3	13.7
5	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	36	86	172	15.2	3	13.7
10	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F \ 16 V$	150µF 25V	24	111	209	30	3	6.34
10	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	24	171	325	35	3	6.34
10	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F \ 16 V$	150µF 25V	36	108	197	35	3	6.34
10	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	36	153	288	39	3	6.34
12	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F 16V$	150µF 25V	24	153	281	37	3	5.23
12	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	36	184	375	34.4	3	5.23
15	$2 \times 10 \mu F 50 V$	100µF 50V	$2 \times 22 \mu F 16V$	150µF 25V	28	178	338	70	3	4.12
15	$2 \times 10 \mu F 50 V$	100µF 50V	$4 \times 47 \mu F 16V$	None	36	134	250	70	3	4.12

Table 3. 12V and 15V Outputs

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W)
Figures 11, 13, 15	24, 36	Figure 9	0	None	13
Figures 11, 13, 15	24, 36	Figure 9	200	None	9.3
Figures 11, 13, 15	24, 36	Figure 9	400	None	8.3
Figures 12, 14, 16	24, 36	Figure 9	0	BGA Heat Sink	12.2
Figures 12, 14, 16	24, 36	Figure 9	200	BGA Heat Sink	8.6
Figures 12, 14, 16	24, 36	Figure 9	400	BGA Heat Sink	7.7



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Table 4. 5V Output

DERATING CURVE	V _{IN} (V)	POWER LOSS CURVE	AIR FLOW (LFM)	HEAT SINK	θ _{JA} (°C/W)
Figures 18, 21	36	Figure 10	0	None	14.9
Figures 18, 21	36	Figure 10	200	None	11.1
Figures 18, 21	36	Figure 10	400	None	10
Figures 10, 13, 16	36	Figure 10	0	BGA Heat Sink	14
Figures 10, 13, 16	36	Figure 10	200	BGA Heat Sink	10.4
Figures 10, 13, 16	36	Figure 10	400	BGA Heat Sink	9.3

Heat Sink Manufacturer

Wakefield Engineering	Part No: LTN20069	Phone: 603-635-2800

Safety Considerations

The LTM4612 modules do not provide isolation from $V_{\rm IN}$ to $V_{\rm OUT}$. There is no internal fuse. If required, a slow blow fuse with a rating twice the maximum input current needs to be provided to protect each unit from catastrophic failure.

Layout Checklist/Example

The high integration of LTM4612 makes the PCB board layout very simple and easy. However, to optimize its electrical and thermal performance, some layout considerations are still necessary.

- Use large PCB copper areas for high current path, including $V_{\rm IN},$ PGND and $V_{\rm OUT}.$ It helps to minimize the PCB conduction loss and thermal stress.
- Place high frequency ceramic input and output capacitors next to the $V_D,\,PGND$ and V_{OUT} pins to minimize high frequency noise.
- Place a dedicated power ground layer underneath the unit.
- Use round corners for the PCB copper layer to minimize the radiated noise.
- To minimize the EMI noise and reduce module thermal stress, use multiple vias for interconnection between top layer and other power layers.

- Do not put vias directly on pads.
- If vias are placed onto the pads, the the vias must be capped.
- Interstitial via placement can also be used if necessary.
- Use a separated SGND ground copper area for components connected to signal pins. Connect the SGND to PGND underneath the unit.
- Place one or more high frequency ceramic capacitors close to the connection into the system board.

Figure 17 gives a good example of the recommended layout.

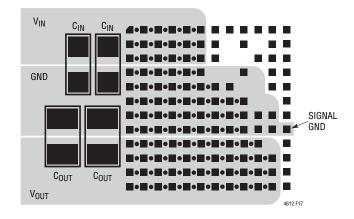


Figure 17. Recommended PCB Layout



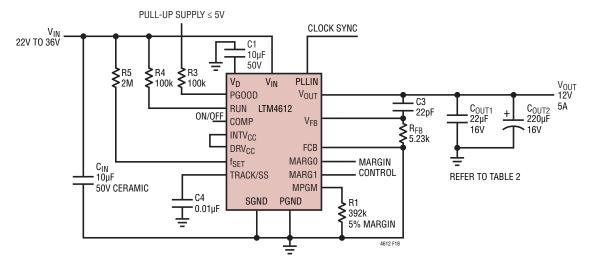


Figure 18. Typical 22V to $36V_{IN}$, 12V at 5A Design

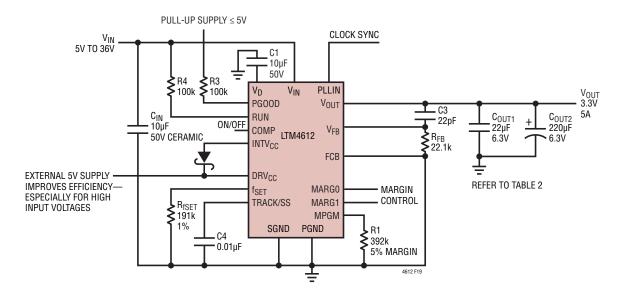


Figure 19. Typical 5V to $36V_{IN}$, 3.3V at 5A Design with 400kHz Frequency



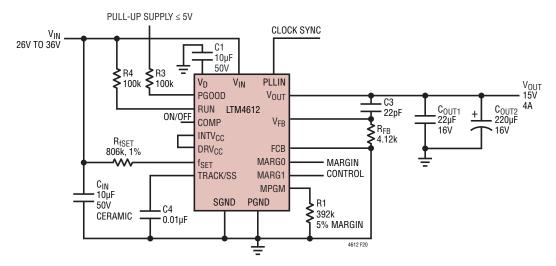


Figure 20. 26V to 36V_{IN}, 15V at 4A Design with Reduced Frequency

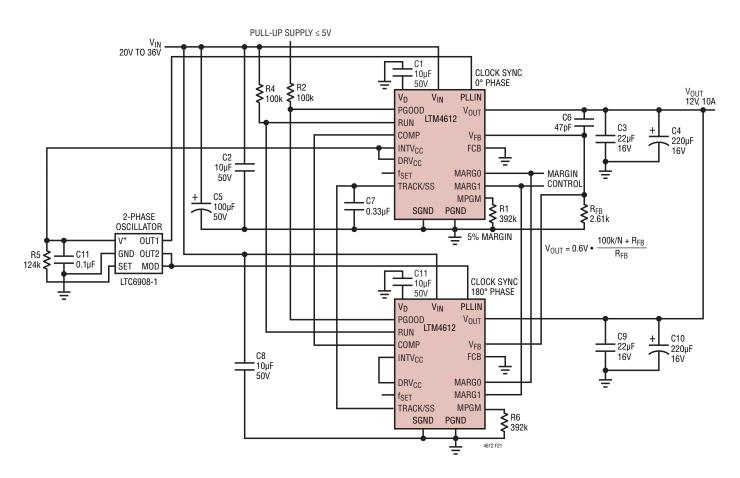


Figure 21. 2-Phase, Parallel 12V at 10A Design



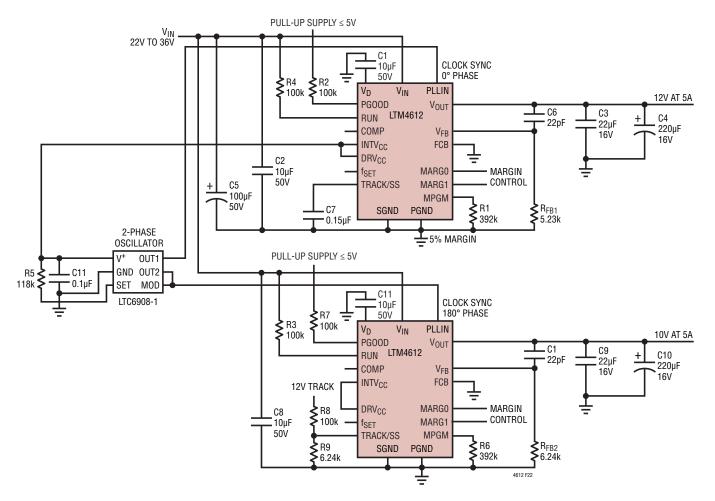


Figure 22. 2-Phase, 12V and 10V at 5A Design

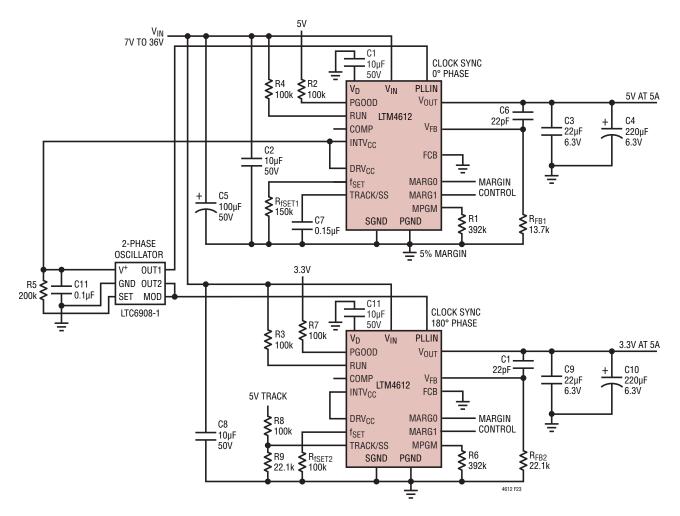


Figure 23. 2-Phase, 5V and 3.3V at 5A Design with 500kHz Frequency



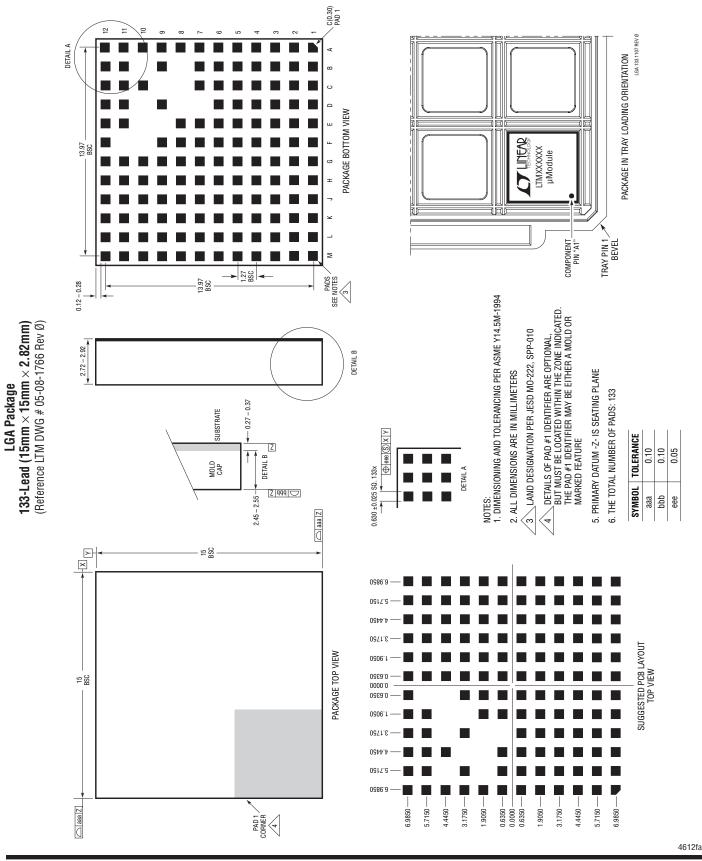
PACKAGE DESCRIPTION

Pin Assignment Tables (Arranged by Pin Function)

PIN NAME	PIN N		PIN	INAME	PI	N NAME
A1 V _{IN} A2 V _{IN} A3 V _{IN} A4 V _{IN} A5 V _{IN} A6 V _{IN}	D1 D2 D3 D4 D5 D6	PGND PGND PGND PGND PGND PGND PGND	J1 J2 J3 J4 J5 J6	V _{OUT} V _{OUT} V _{OUT} V _{OUT} V _{OUT}	A7 A8 A9 A10 A11 A12	INTV _{CC} PLLIN TRACK/SS RUN COMP MPGM
B1 VIN B2 VIN B3 VIN B4 VIN B5 VIN B6 VIN	E1 E2 E3 E4 E5 E6 E7	E2 PGND J8 E3 PGND J9 E4 PGND J10 E5 PGND J11 E6 PGND K1 E7 PGND K2 E8 PGND K3 F1 PGND K5 F3 PGND K6 F3 PGND K7 F5 PGND K9 F6 PGND K10 F7 PGND K10	J8 J9 J10 J11 K1	Vout Vout Vout Vout Vout Vout Vout Vout	B7 B8 B9 B10 B11 B12 C7 C8 C9 C10 C10 C11 C12 D7 D8 D9	V _D - RUN - MPGM f _{SET}
C1 V _{IN} C2 V _{IN} C3 V _{IN} C4 V _{IN} C5 V _{IN} C6 V _{IN}	E8 F1 F2 F3 F4 F5 F6 F7		K3 K4 K5 K6 K7 K8	Vout Vout Vout Vout Vout Vout Vout Vout		V _D - DRV _{CC} MARG1 MARG0 - - SGND
	F8 PGND F9 PGND G1 PGND G2 PGND G3 PGND G4 PGND G5 PGND G6 PGND G7 PGND G8 PGND G9 PGND G11 PGND H2 PGND H3 PGND H4 PGND H5 PGND H6 PGND H7 PGND H8 PGND H9 PGND H10 PGND	L1 L2 L3 L4 L5 L6	Vout Vout Vout Vout Vout Vout Vout	D10 D11 D12 E9 E10 E11	- COMP MARG1 - - DRV _{CC}	
		L7 L8 L9 L10 L11 M1	Vout Vout Vout Vout Vout Vout	E12 F10 F11 F12 G12	DRV _{CC} V _{FB} PG00D	
		M2 M3 M4 M5 M6 M7 M8 M9 M10 M11	M2 V _{OUT} M3 V _{OUT} M4 V _{OUT} M5 V _{OUT} M6 V _{OUT} M7 V _{OUT} M8 V _{OUT} M9 V _{OUT}	H12 J12 K12 L12 M12	SGND NC NC NC FCB	



PACKAGE DESCRIPTION



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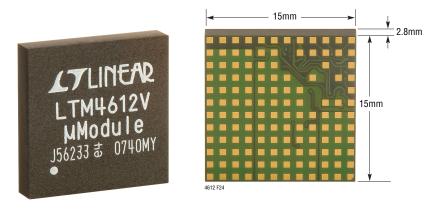
REVISION HISTORY

REV	DATE	DESCRIPTION	PAGE NUMBER
Α	03/10	Changes to Title and Description	1
		Changes to Absolute Maximum Ratings	1
		Changes to Electrical Characteristics	2, 3
		Text Changes to Operation Section	10
		Text Changes to Applications Information Section	12, 14
		Changes to Figures 18, 19, 20, 21, 22	19, 20, 21, 22
		Changes to Related Parts	26



Information furnished by Linear Technology Corporation is believed to be accurate and reliable. However, no responsibility is assumed for its use. Linear Technology Corporation makes no representation that the interconnection of its circuits as described herein will not infringe on existing patent rights.

PACKAGE PHOTOGRAPH



RELATED PARTS

PART NUMBER	DESCRIPTION	COMMENTS
LTM4606	Ultralow Noise 6A, DC/DC µModule	Ultralow Noise, with PLL, Output Tracking and Margining, LTM4612 Pin Compatible
LTM4600	10A DC/DC µModule	Basic 10A DC/DC µModule, LGA Package
LTM4600HVMP	Military Plastic 10A DC/DC µModule	Guaranteed Operation from –55°C to 125°C Ambient, LGA Package
LTM4601/ LTM4601A	12A DC/DC µModule with PLL, Output Tracking/ Margining and Remote Sensing	Synchronizable, PolyPhase Operation, LTM4601-1/LTM4601A-1 Version Has No Remote Sensing, LGA Package
LTM4602	6A DC/DC μModule	Pin Compatible with the LTM4600, LGA Package
LTM4603	6A DC/DC μModule with PLL and Output Tracking/ Margining and Remote Sensing	Synchronizable, PolyPhase Operation, LTM4603-1 Version Has No Remote Sensing, Pin Compatible with the LTM4601, LGA Package
LTM4604A	Low V _{IN} 4A DC/DC µModule	$2.375V \leq V_{IN} \leq 5.5V$, 0.8V $\leq V_{OUT} \leq 5V$, 9mm \times 15mm \times 2.3mm LGA Package
LTM4608A	Low V _{IN} 8A DC/DC µModule	$2.4V \le V_{IN} \le 5.5V$; $0.6V \le V_{OUT} \le 5V$; $9mm \times 15mm \times 2.8mm$ LGA Package
LTM8020	High V _{IN} 0.2A DC/DC Step-Down µModule	$4V \le V_{IN} \le 36V$, $1.25V \le V_{OUT} \le 5V$ $6.25mm \times 6.25mm \times 2.3mm$ LGA Package
LTM8021	High V _{IN} 0.5A DC/DC Step-Down µModule	$3V \le V_{IN} \le 36V$, $0.8V \le V_{OUT} \le 5V 6.25mm \times 11.25mm \times 2.8mm$ LGA Package
LTM8022/LTM8023	36V _{IN} , 1A and 2A DC/DC μModule	Pin Compatible; $4.5V \le V_{IN} \le 36V$; $9mm \times 11.25mm \times 2.8mm$ LGA Package

