

# DDR2 SDRAM UDIMM

**MT4HTF1664AY – 128MB**

**MT4HTF3264AY – 256MB**

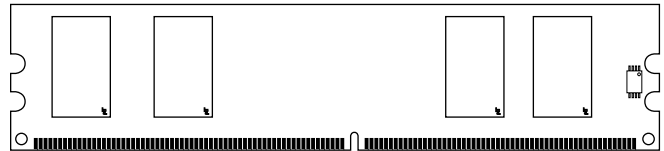
**MT4HTF6464AY – 512MB**

## Features

- 240-pin, unbuffered dual in-line memory module (UDIMM)
- Fast data transfer rates: PC2-3200, PC2-4200, PC2-5300, or PC2-6400
- 128MB (16 Meg x 64), 256MB (32 Meg x 64), 512MB (64 Meg x 64)
- $V_{DD} = V_{DDQ} = 1.8V$
- $V_{DDSPD} = 1.7-3.6V$
- JEDEC-standard 1.8V I/O (SSTL\_18-compatible)
- Differential data strobe (DQS, DQS#) option
- 4n-bit prefetch architecture
- Multiple internal device banks for concurrent operation
- Programmable CAS latency (CL)
- Posted CAS additive latency (AL)
- WRITE latency = READ latency - 1 tCK
- Programmable burst lengths (BL): 4 or 8
- Adjustable data-output drive strength
- 64ms, 8192-cycle refresh
- On-die termination (ODT)
- Serial presence detect (SPD) with EEPROM
- Gold edge contacts
- Single rank

**Figure 1: 240-Pin UDIMM (MO-237 R/C C)**

Module height 30.0mm (1.18in)



## Options

- Operating temperature
  - Commercial ( $0^{\circ}C \leq T_A \leq +70^{\circ}C$ )
  - Industrial ( $-40^{\circ}C \leq T_A \leq +85^{\circ}C$ )<sup>1</sup>
- Package
  - 240-pin DIMM (lead-free)
- Frequency/CL<sup>2</sup>
  - 2.5ns @ CL = 5 (DDR2-800)<sup>4</sup>
  - 2.5ns @ CL = 6 (DDR2-800)<sup>4</sup>
  - 3.0ns @ CL = 5 (DDR2-667)
  - 3.75ns @ CL = 4 (DDR2-533)<sup>3</sup>
  - 5.0ns @ CL = 3 (DDR2-400)<sup>3</sup>

## Marking

- None
- I
- Y
- 80E
- 800
- 667
- 53E
- 40E

- Notes:
1. Contact Micron for industrial temperature module offerings.
  2. CL = CAS (READ) latency.
  3. Contact Micron for product availability.
  4. Not available in 128MB and 256MB.

**Table 1: Key Timing Parameters**

Speed Grade	Industry Nomenclature	Data Rate (MT/s)				t <sub>RCD</sub> (ns)	t <sub>RP</sub> (ns)	t <sub>RC</sub> (ns)
		CL = 6	CL = 5	CL = 4	CL = 3			
-80E	PC2-6400	800	800	533	400	12.5	12.5	55
-800	PC2-6400	800	667	533	400	15	15	55
-667	PC2-5300	–	667	553	400	15	15	55
-53E	PC2-4200	–	–	553	400	15	15	55
-40E	PC2-3200	–	–	400	400	15	15	55



**Table 2: Addressing**

Parameter	128MB	256MB	512MB
Refresh count	8K	8K	8K
Row address	8K A[12:0]	8K A[12:0]	8K A[12:0]
Device bank address	4 BA[1:0]	4 BA[1:0]	8 BA[2:0]
Device configuration	256Mb (16 Meg x 16)	512Mb (32 Meg x 16)	1Gb (64 Meg x 16)
Column address	512 A[8:0]	1K A[9:0]	1K A[9:0]
Module rank address	1 S0#	1 S0#	1 S0#

**Table 3: Part Numbers and Timing Parameters – 128MB Modules (End of Life)**

Base device: MT47H16M16,<sup>1</sup> 256Mb DDR2 SDRAM

Part Number <sup>2</sup>	Module Density	Configuration	Module Bandwidth	Memory Clock/ Data Rate	Clock Cycles (CL- <sup>t</sup> RCD- <sup>t</sup> RP)
MT4HTF1664A(I)Y-667__	128MB	16 Meg x 64	5.3 GB/s	3.0ns/667 MT/s	5-5-5
MT4HTF1664A(I)Y-53E__	128MB	16 Meg x 64	4.3 GB/s	3.75ns/533 MT/s	4-4-4
MT4HTF1664A(I)Y-40E__	128MB	16 Meg x 64	3.2 GB/s	5.0ns/400 MT/s	3-3-3

**Table 4: Part Numbers and Timing Parameters – 256MB Modules**

Base device: MT47H32M16,<sup>1</sup> 512Mb DDR2 SDRAM

Part Number <sup>2</sup>	Module Density	Configuration	Module Bandwidth	Memory Clock/ Data Rate	Clock Cycles (CL- <sup>t</sup> RCD- <sup>t</sup> RP)
MT4HTF3264A(I)Y-80E__	256MB	32 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	5-5-5
MT4HTF3264A(I)Y-800__	256MB	32 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	6-6-6
MT4HTF3264A(I)Y-667__	256MB	32 Meg x 64	5.3 GB/s	3.0ns/667 MT/s	5-5-5
MT4HTF3264A(I)Y-53E__	256MB	32 Meg x 64	4.3 GB/s	3.75ns/533 MT/s	4-4-4
MT4HTF3264A(I)Y-40E__	256MB	32 Meg x 64	3.2 GB/s	5.0ns/400 MT/s	3-3-3

**Table 5: Part Numbers and Timing Parameters – 512MB Modules**

Base device: MT47H64M16,<sup>1</sup> 1Gb DDR2 SDRAM

Part Number <sup>2</sup>	Module Density	Configuration	Module Bandwidth	Memory Clock/ Data Rate	Clock Cycles (CL- <sup>t</sup> RCD- <sup>t</sup> RP)
MT4HTF6464A(I)Y-80E__	512MB	64 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	5-5-5
MT4HTF6464A(I)Y-800__	512MB	64 Meg x 64	6.4 GB/s	2.5ns/800 MT/s	6-6-6
MT4HTF6464A(I)Y-667__	512MB	64 Meg x 64	5.3 GB/s	3.0ns/667 MT/s	5-5-5
MT4HTF6464A(I)Y-53E__	512MB	64 Meg x 64	4.3 GB/s	3.75ns/533 MT/s	4-4-4
MT4HTF6464A(I)Y-40E__	512MB	64 Meg x 64	3.2 GB/s	5.0ns/400 MT/s	3-3-3

- Notes:
1. The data sheet for the base device can be found on Micron’s Web site.
  2. All part numbers end with a two-place code (not shown) that designates component and PCB revisions. Consult factory for current revision codes. Example: MT4HTF3264AY-667E1.



## Pin Assignments

**Table 6: Pin Assignments**

240-Pin UDIMM Front								240-Pin UDIMM Back							
Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol	Pin	Symbol
1	V <sub>REF</sub>	31	DQ19	61	A4	91	V <sub>SS</sub>	121	V <sub>SS</sub>	151	V <sub>SS</sub>	181	V <sub>DDQ</sub>	211	DM5
2	V <sub>SS</sub>	32	V <sub>SS</sub>	62	V <sub>DDQ</sub>	92	DQS5#	122	DQ4	152	DQ28	182	A3	212	NC
3	DQ0	33	DQ24	63	A2	93	DQS5	123	DQ5	153	DQ29	183	A1	213	V <sub>SS</sub>
4	DQ1	34	DQ25	64	V <sub>DD</sub>	94	V <sub>SS</sub>	124	V <sub>SS</sub>	154	V <sub>SS</sub>	184	V <sub>DD</sub>	214	DQ46
5	V <sub>SS</sub>	35	V <sub>SS</sub>	65	V <sub>SS</sub>	95	DQ42	125	DM0	155	DM3	185	CK0	215	DQ47
6	DQS0#	36	DQS3#	66	V <sub>SS</sub>	96	DQ43	126	NC	156	NC	186	CK0#	216	V <sub>SS</sub>
7	DQS0	37	DQS3	67	V <sub>DD</sub>	97	V <sub>SS</sub>	127	V <sub>SS</sub>	157	V <sub>SS</sub>	187	V <sub>DD</sub>	217	DQ52
8	V <sub>SS</sub>	38	V <sub>SS</sub>	68	NC	98	DQ48	128	DQ6	158	DQ30	188	A0	218	DQ53
9	DQ2	39	DQ26	69	V <sub>DD</sub>	99	DQ49	129	DQ7	159	DQ31	189	V <sub>DD</sub>	219	V <sub>SS</sub>
10	DQ3	40	DQ27	70	A10	100	V <sub>SS</sub>	130	V <sub>SS</sub>	160	V <sub>SS</sub>	190	BA1	220	CK2
11	V <sub>SS</sub>	41	V <sub>SS</sub>	71	BA0	101	SA2	131	DQ12	161	NC	191	V <sub>DDQ</sub>	221	CK2#
12	DQ8	42	NC	72	V <sub>DDQ</sub>	102	NC	132	DQ13	162	NC	192	RAS#	222	V <sub>SS</sub>
13	DQ9	43	NC	73	WE#	103	V <sub>SS</sub>	133	V <sub>SS</sub>	163	V <sub>SS</sub>	193	S0#	223	DM6
14	V <sub>SS</sub>	44	V <sub>SS</sub>	74	CAS#	104	DQS6#	134	DM1	164	NC	194	V <sub>DDQ</sub>	224	NC
15	DQS1#	45	NC	75	V <sub>DDQ</sub>	105	DQS6	135	NC	165	NC	195	ODT0	225	V <sub>SS</sub>
16	DQS1	46	NC	76	NC	106	V <sub>SS</sub>	136	V <sub>SS</sub>	166	V <sub>SS</sub>	196	NC	226	DQ54
17	V <sub>SS</sub>	47	V <sub>SS</sub>	77	NC	107	DQ50	137	CK1	167	NC	197	V <sub>DD</sub>	227	DQ55
18	NC	48	NC	78	V <sub>DDQ</sub>	108	DQ51	138	CK1#	168	NC	198	V <sub>SS</sub>	228	V <sub>SS</sub>
19	NC	49	NC	79	V <sub>SS</sub>	109	V <sub>SS</sub>	139	V <sub>SS</sub>	169	V <sub>SS</sub>	199	DQ36	229	DQ60
20	V <sub>SS</sub>	50	V <sub>SS</sub>	80	DQ32	110	DQ56	140	DQ14	170	V <sub>DDQ</sub>	200	DQ37	230	DQ61
21	DQ10	51	V <sub>DDQ</sub>	81	DQ33	111	DQ57	141	DQ15	171	NC	201	V <sub>SS</sub>	231	V <sub>SS</sub>
22	DQ11	52	CKE0	82	V <sub>SS</sub>	112	V <sub>SS</sub>	142	V <sub>SS</sub>	172	V <sub>DD</sub>	202	DM4	232	DM7
23	V <sub>SS</sub>	53	V <sub>DD</sub>	83	DQS4#	113	DQS7#	143	DQ20	173	NC	203	NC	233	NC
24	DQ16	54	NC/BA2 <sup>1</sup>	84	DQS4	114	DQS7	144	DQ21	174	NC	204	V <sub>SS</sub>	234	V <sub>SS</sub>
25	DQ17	55	NC	85	V <sub>SS</sub>	115	V <sub>SS</sub>	145	V <sub>SS</sub>	175	V <sub>DDQ</sub>	205	DQ38	235	DQ62
26	V <sub>SS</sub>	56	V <sub>DDQ</sub>	86	DQ34	116	DQ58	146	DM2	176	A12	206	DQ39	236	DQ63
27	DQS2#	57	A11	87	DQ35	117	DQ59	147	NC	177	A9	207	V <sub>SS</sub>	237	V <sub>SS</sub>
28	DQS2	58	A7	88	V <sub>SS</sub>	118	V <sub>SS</sub>	148	V <sub>SS</sub>	178	V <sub>DD</sub>	208	DQ44	238	V <sub>DDSPD</sub>
29	V <sub>SS</sub>	59	V <sub>DD</sub>	89	DQ40	119	SDA	149	DQ22	179	A8	209	DQ45	239	SA0
30	DQ18	60	A5	90	DQ41	120	SCL	150	DQ23	180	A6	210	V <sub>SS</sub>	240	SA1

Note: 1. Pin 54 is NC for 128MB and 256MB or BA2 for 512MB.

## Pin Descriptions

The pin description table below is a comprehensive list of all possible pins for all DDR2 modules. All pins listed may not be supported on this module. See Pin Assignments for information specific to this module.

**Table 7: Pin Descriptions**

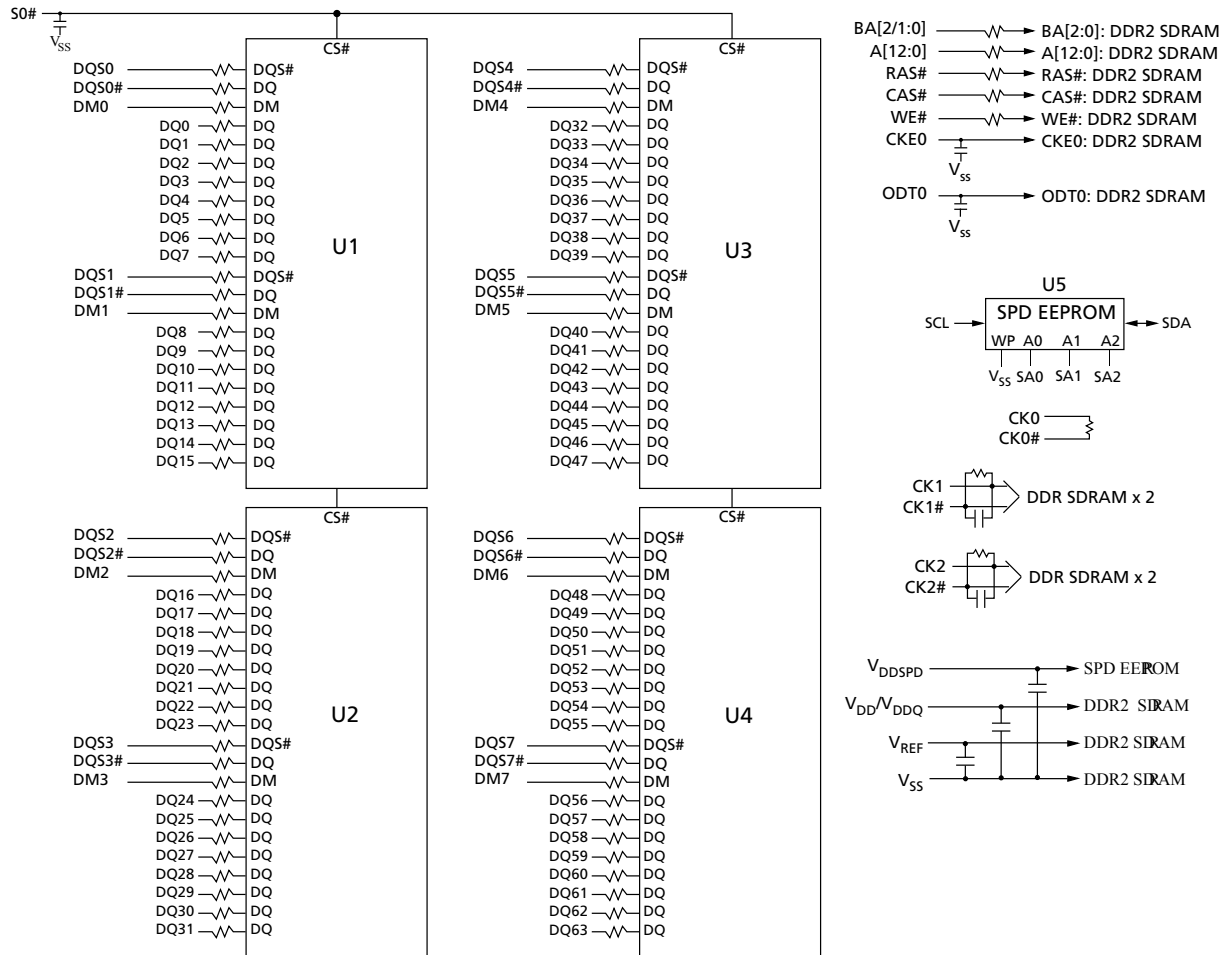
Symbol	Type	Description
Ax	Input	<b>Address inputs:</b> Provide the row address for ACTIVE commands, and the column address and auto precharge bit (A10) for READ/WRITE commands, to select one location out of the memory array in the respective bank. A10 sampled during a PRECHARGE command determines whether the PRECHARGE applies to one bank (A10 LOW, bank selected by BAx) or all banks (A10 HIGH). The address inputs also provide the op-code during a LOAD MODE command. See the Pin Assignments Table for density-specific addressing information.
BAx	Input	<b>Bank address inputs:</b> Define the device bank to which an ACTIVE, READ, WRITE, or PRECHARGE command is being applied. BA define which mode register (MR0, MR1, MR2, and MR3) is loaded during the LOAD MODE command.
CKx, CK#x	Input	<b>Clock:</b> Differential clock inputs. All control, command, and address input signals are sampled on the crossing of the positive edge of CK and the negative edge of CK#.
CKEx	Input	<b>Clock enable:</b> Enables (registered HIGH) and disables (registered LOW) internal circuitry and clocks on the DDR2 SDRAM.
DMx,	Input	<b>Data mask (x8 devices only):</b> DM is an input mask signal for write data. Input data is masked when DM is sampled HIGH, along with that input data, during a write access. Although DM pins are input-only, DM loading is designed to match that of the DQ and DQS pins.
ODTx	Input	<b>On-die termination:</b> Enables (registered HIGH) and disables (registered LOW) termination resistance internal to the DDR2 SDRAM. When enabled in normal operation, ODT is only applied to the following pins: DQ, DQS, DQS#, DM, and CB. The ODT input will be ignored if disabled via the LOAD MODE command.
Par_In	Input	<b>Parity input:</b> Parity bit for Ax, RAS#, CAS#, and WE#.
RAS#, CAS#, WE#	Input	<b>Command inputs:</b> RAS#, CAS#, and WE# (along with S#) define the command being entered.
RESET#	Input	<b>Reset:</b> Asynchronously forces all registered outputs LOW when RESET# is LOW. This signal can be used during power-up to ensure that CKE is LOW and DQ are High-Z.
S#x	Input	<b>Chip select:</b> Enables (registered LOW) and disables (registered HIGH) the command decoder.
SAx	Input	<b>Serial address inputs:</b> Used to configure the SPD EEPROM address range on the I <sup>2</sup> C bus.
SCL	Input	<b>Serial clock for SPD EEPROM:</b> Used to synchronize communication to and from the SPD EEPROM on the I <sup>2</sup> C bus.
CBx	I/O	<b>Check bits.</b> Used for system error detection and correction.
DQx	I/O	<b>Data input/output:</b> Bidirectional data bus.
DQSx, DQS#x	I/O	<b>Data strobe:</b> Travels with the DQ and is used to capture DQ at the DRAM or the controller. Output with read data; input with write data for source synchronous operation. DQS# is only used when differential data strobe mode is enabled via the LOAD MODE command.

**Table 7: Pin Descriptions (Continued)**

Symbol	Type	Description
SDA	I/O	<b>Serial data:</b> Used to transfer addresses and data into and out of the SPD EEPROM on the I <sup>2</sup> C bus.
RDQSx, RDQS#x	Output	<b>Redundant data strobe (x8 devices only):</b> RDQS is enabled/disabled via the LOAD MODE command to the extended mode register (EMR). When RDQS is enabled, RDQS is output with read data only and is ignored during write data. When RDQS is disabled, RDQS becomes data mask (see DMx). RDQS# is only used when RDQS is enabled and differential data strobe mode is enabled.
Err_Out#	Output (open drain)	<b>Parity error output:</b> Parity error found on the command and address bus.
V <sub>DD</sub> /V <sub>DDQ</sub>	Supply	<b>Power supply:</b> 1.8V ±0.1V. The component V <sub>DD</sub> and V <sub>DDQ</sub> are connected to the module V <sub>DD</sub> .
V <sub>DDSPD</sub>	Supply	<b>SPD EEPROM power supply:</b> 1.7–3.6V.
V <sub>REF</sub>	Supply	<b>Reference voltage:</b> V <sub>DD</sub> /2.
V <sub>SS</sub>	Supply	Ground.
NC	–	<b>No connect:</b> These pins are not connected on the module.
NF	–	<b>No function:</b> These pins are connected within the module, but provide no functionality.
NU	–	<b>Not used:</b> These pins are not used in specific module configurations/operations.
RFU	–	Reserved for future use.

## Functional Block Diagram

**Figure 2: Functional Block Diagram**



## General Description

DDR2 SDRAM modules are high-speed, CMOS dynamic random access memory modules that use internally configured 4 or 8-bank DDR2 SDRAM devices. DDR2 SDRAM modules use DDR architecture to achieve high-speed operation. DDR2 architecture is essentially a  $4n$ -prefetch architecture with an interface designed to transfer two data words per clock cycle at the I/O pins. A single read or write access for the DDR2 SDRAM module effectively consists of a single  $4n$ -bit-wide, one-clock-cycle data transfer at the internal DRAM core and eight corresponding  $n$ -bit-wide, one-half-clock-cycle data transfers at the I/O pins.

DDR2 modules use two sets of differential signals: DQS, DQS# to capture data and CK and CK# to capture commands, addresses, and control signals. Differential clocks and data strobes ensure exceptional noise immunity for these signals and provide precise crossing points to capture input signals. A bidirectional data strobe (DQS, DQS#) is transmitted externally, along with data, for use in data capture at the receiver. DQS is a strobe transmitted by the DDR2 SDRAM device during READs and by the memory controller during WRITEs. DQS is edge-aligned with data for READs and center-aligned with data for WRITEs.

DDR2 SDRAM modules operate from a differential clock (CK and CK#); the crossing of CK going HIGH and CK# going LOW will be referred to as the positive edge of CK. Commands (address and control signals) are registered at every positive edge of CK. Input data is registered on both edges of DQS, and output data is referenced to both edges of DQS, as well as to both edges of CK.

## Serial Presence-Detect EEPROM Operation

DDR2 SDRAM modules incorporate serial presence-detect. The SPD data is stored in a 256-byte EEPROM. The first 128 bytes are programmed by Micron to identify the module type and various SDRAM organizations and timing parameters. The remaining 128 bytes of storage are available for use by the customer. System READ/WRITE operations between the master (system logic) and the slave EEPROM device occur via a standard I<sup>2</sup>C bus using the DIMM's SCL (clock) SDA (data), and SA (address) pins. Write protect (WP) is connected to V<sub>SS</sub>, permanently disabling hardware write protection.

## Electrical Specifications

Stresses greater than those listed may cause permanent damage to the module. This is a stress rating only, and functional operation of the module at these or any other conditions outside those indicated in the device data sheet are not implied. Exposure to absolute maximum rating conditions for extended periods may adversely affect reliability.

**Table 8: Absolute Maximum Ratings**

Symbol	Parameter	Min	Max	Units	
$V_{DD}/V_{DDQ}$	$V_{DD}/V_{DDQ}$ supply voltage relative to $V_{SS}$	-0.5	2.3	V	
$V_{IN}, V_{OUT}$	Voltage on any pin relative to $V_{SS}$	-0.5	2.3	V	
$I_I$	Input leakage current; Any input $0V \leq V_{IN} \leq V_{DD}$ ; $V_{REF}$ input $0V \leq V_{IN} \leq 0.95V$ ; (All other pins not under test = $0V$ )	Address inputs, RAS#, CAS#, WE#, S#, CKE, ODT, BA	-20	20	$\mu A$
		CK, CK#	-10	10	
		DM	-5	5	
$I_{OZ}$	Output leakage current; $0V \leq V_{OUT} \leq V_{DDQ}$ ; DQ and ODT are disabled	DQ, DQS, DQS#	-5	5	$\mu A$
$I_{VREF}$	$V_{REF}$ leakage current; $V_{REF}$ = valid $V_{REF}$ level		-8	8	$\mu A$
$T_A$	Module ambient operating temperature	Commercial	0	70	$^{\circ}C$
		Industrial	-40	85	$^{\circ}C$
$T_C^1$	DDR2 SDRAM component operating temperature <sup>2</sup>	Commercial	0	85	$^{\circ}C$
		Industrial	-40	95	$^{\circ}C$

- Notes: 1. The refresh rate is required to double when  $T_C$  exceeds  $85^{\circ}C$ .  
2. For further information, refer to technical note TN-00-08: "Thermal Applications," available on Micron's Web site.





## DRAM Operating Conditions

Recommended AC operating conditions are given in the DDR2 component data sheets. Component specifications are available on Micron's Web site. Module speed grades correlate with component speed grades.

**Table 9: Module and Component Speed Grades**

DDR2 components may exceed the listed module speed grades; module may not be available in all listed speed grades

Module Speed Grade	Component Speed Grade
-1GA	-187E
-80E	-25E
-800	-25
-667	-3
-53E	-37E
-40E	-5E

## Design Considerations

### Simulations

Micron memory modules are designed to optimize signal integrity through carefully designed terminations, controlled board impedances, routing topologies, trace length matching, and decoupling. However, good signal integrity starts at the system level. Micron encourages designers to simulate the signal characteristics of the system's memory bus to ensure adequate signal integrity of the entire memory system.

### Power

Operating voltages are specified at the DRAM, not at the edge connector of the module. Designers must account for any system voltage drops at anticipated power levels to ensure the required supply voltage is maintained.

## I<sub>DD</sub> Specifications

**Table 10: DDR2 I<sub>DD</sub> Specifications and Conditions – 128MB**

Values shown for MT47H16M16 DDR2 SDRAM only and are computed from values specified in the 256Mb (16 Meg x 16) component data sheet

Parameter	Symbol	-667	-53E	-40E	Units	
<b>Operating one bank active-precharge current:</b> $t_{CK} = t_{CK}(I_{DD})$ , $t_{RC} = t_{RC}(I_{DD})$ , $t_{RAS} = t_{RAS\ MIN}(I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD0</sub>	360	320	300	mA	
<b>Operating one bank active-read-precharge current:</b> I <sub>OUT</sub> = 0mA; BL = 4, CL = CL(I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK}(I_{DD})$ , $t_{RC} = t_{RC}(I_{DD})$ , $t_{RAS} = t_{RAS\ MIN}(I_{DD})$ , $t_{RCD} = t_{RCD}(I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is same as I <sub>DD4W</sub>	I <sub>DD1</sub>	400	360	340	mA	
<b>Precharge power-down current:</b> All device banks idle; $t_{CK} = t_{CK}(I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2P</sub>	20	20	20	mA	
<b>Precharge quiet standby current:</b> All device banks idle; $t_{CK} = t_{CK}(I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2Q</sub>	200	140	100	mA	
<b>Precharge standby current:</b> All device banks idle; $t_{CK} = t_{CK}(I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD2N</sub>	160	140	120	mA	
<b>Active power-down current:</b> All device banks open; $t_{CK} = t_{CK}(I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD3P</sub>	Fast PDN exit MR[12] = 0	120	100	80	mA
		Slow PDN exit MR[12] = 1	24	24	24	
<b>Active standby current:</b> All device banks open; $t_{CK} = t_{CK}(I_{DD})$ , $t_{RAS} = t_{RAS\ MAX}(I_{DD})$ , $t_{RP} = t_{RP}(I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD3N</sub>	220	160	120	mA	
<b>Operating burst write current:</b> All device banks open; Continuous burst writes; BL = 4, CL = CL(I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK}(I_{DD})$ , $t_{RAS} = t_{RAS\ MAX}(I_{DD})$ , $t_{RP} = t_{RP}(I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4W</sub>	860	720	560	mA	
<b>Operating burst read current:</b> All device banks open; Continuous burst read, I <sub>OUT</sub> = 0mA; BL = 4, CL = CL(I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK}(I_{DD})$ , $t_{RAS} = t_{RAS\ MAX}(I_{DD})$ , $t_{RP} = t_{RP}(I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4R</sub>	760	640	480	mA	
<b>Burst refresh current:</b> $t_{CK} = t_{CK}(I_{DD})$ ; REFRESH command at every $t_{RFC}(I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD5</sub>	720	680	660	mA	
<b>Self refresh current:</b> CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I <sub>DD6</sub>	20	20	20	mA	



**Table 10: DDR2 I<sub>DD</sub> Specifications and Conditions – 128MB (Continued)**

Values shown for MT47H16M16 DDR2 SDRAM only and are computed from values specified in the 256Mb (16 Meg x 16) component data sheet

Parameter	Symbol	-667	-53E	-40E	Units
<b>Operating bank interleave read current:</b> All device banks interleaving reads; I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = t <sub>RCD</sub> (I <sub>DD</sub> ) - 1 × t <sub>CK</sub> (I <sub>DD</sub> ); t <sub>CK</sub> = t <sub>CK</sub> (I <sub>DD</sub> ), t <sub>RC</sub> = t <sub>RC</sub> (I <sub>DD</sub> ), t <sub>RRD</sub> = t <sub>RRD</sub> (I <sub>DD</sub> ), t <sub>RCD</sub> = t <sub>RCD</sub> (I <sub>DD</sub> ); CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I <sub>DD7</sub>	1000	960	920	mA

**Table 11: DDR2 I<sub>DD</sub> Specifications and Conditions – 256MB**

Values shown for MT47H32M16 DDR2 SDRAM only and are computed from values specified in the 512Mb (32 Meg x 16) component data sheet

Parameter	Symbol	-80E/ -800	-667	-53E	-40E	Units	
<b>Operating one bank active-precharge current:</b> $t_{CK} = t_{CK} (I_{DD})$ , $t_{RC} = t_{RC} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MIN} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD0</sub>	540	480	440	440	mA	
<b>Operating one bank active-read-precharge current:</b> I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RC} = t_{RC} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MIN} (I_{DD})$ , $t_{RCD} = t_{RCD} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is same as I <sub>DD4W</sub>	I <sub>DD1</sub>	660	600	540	520	mA	
<b>Precharge power-down current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2P</sub>	28	28	28	28	mA	
<b>Precharge quiet standby current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2Q</sub>	260	220	180	160	mA	
<b>Precharge standby current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD2N</sub>	280	240	200	180	mA	
<b>Active power-down current:</b> All device banks open; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	Fast PDN exit MR[12] = 0	I <sub>DD3P</sub>	160	140	120	100	mA
		Slow PDN exit MR[12] = 1	48	48	48	48	
<b>Active standby current:</b> All device banks open; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD3N</sub>	300	280	240	200	mA	
<b>Operating burst write current:</b> All device banks open; Continuous burst writes; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4W</sub>	1180	1000	820	640	mA	
<b>Operating burst read current:</b> All device banks open; Continuous burst read, I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4R</sub>	1100	940	780	620	mA	
<b>Burst refresh current:</b> $t_{CK} = t_{CK} (I_{DD})$ ; REFRESH command at every $t_{RFC} (I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD5</sub>	920	740	700	680	mA	
<b>Self refresh current:</b> CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I <sub>DD6</sub>	28	28	28	28	mA	



**Table 11: DDR2 I<sub>DD</sub> Specifications and Conditions – 256MB (Continued)**

Values shown for MT47H32M16 DDR2 SDRAM only and are computed from values specified in the 512Mb (32 Meg x 16) component data sheet

Parameter	Symbol	-80E/ -800	-667	-53E	-40E	Units
<b>Operating bank interleave read current:</b> All device banks interleaving reads; I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = t <sub>RCD</sub> (I <sub>DD</sub> ) - 1 × t <sub>CK</sub> (I <sub>DD</sub> ); t <sub>CK</sub> = t <sub>CK</sub> (I <sub>DD</sub> ), t <sub>RC</sub> = t <sub>RC</sub> (I <sub>DD</sub> ), t <sub>RRD</sub> = t <sub>RRD</sub> (I <sub>DD</sub> ), t <sub>RCD</sub> = t <sub>RCD</sub> (I <sub>DD</sub> ); CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I <sub>DD7</sub>	1480	1400	1360	1360	mA

**Table 12: DDR2 I<sub>DD</sub> Specifications and Conditions (Die Revision A) – 512MB**

Values shown for MT47H64M16 DDR2 SDRAM only and are computed from values specified in the 1Gb (64 Meg x 16) component data sheet

Parameter	Symbol	-80E/ -800	-667	-53E	-40E	Units	
<b>Operating one bank active-precharge current:</b> $t_{CK} = t_{CK} (I_{DD})$ , $t_{RC} = t_{RC} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MIN} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD0</sub>	600	540	440	440	mA	
<b>Operating one bank active-read-precharge current:</b> I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RC} = t_{RC} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MIN} (I_{DD})$ , $t_{RCD} = t_{RCD} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is same as I <sub>DD4W</sub>	I <sub>DD1</sub>	700	520	480	460	mA	
<b>Precharge power-down current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2P</sub>	28	28	28	28	mA	
<b>Precharge quiet standby current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2Q</sub>	300	260	180	160	mA	
<b>Precharge standby current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD2N</sub>	320	280	200	160	mA	
<b>Active power-down current:</b> All device banks open; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	Fast PDN exit MR[12] = 0	I <sub>DD3P</sub>	180	160	140	140	mA
		Slow PDN exit MR[12] = 1	56	56	56	56	mA
<b>Active standby current:</b> All device banks open; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD3N</sub>	340	300	240	220	mA	
<b>Operating burst write current:</b> All device banks open; Continuous burst writes; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4W</sub>	1260	800	720	640	mA	
<b>Operating burst read current:</b> All device banks open; Continuous burst read, I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4R</sub>	1280	880	720	640	mA	
<b>Burst refresh current:</b> $t_{CK} = t_{CK} (I_{DD})$ ; REFRESH command at every $t_{RFC} (I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD5</sub>	1120	1080	1000	960	mA	
<b>Self refresh current:</b> CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I <sub>DD6</sub>	28	28	28	28	mA	

**Table 12: DDR2 I<sub>DD</sub> Specifications and Conditions (Die Revision A) – 512MB (Continued)**

Values shown for MT47H64M16 DDR2 SDRAM only and are computed from values specified in the 1Gb (64 Meg x 16) component data sheet

Parameter	Symbol	-80E/ -800	-667	-53E	-40E	Units
<b>Operating bank interleave read current:</b> All device banks interleaving reads; I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = t <sub>RCD</sub> (I <sub>DD</sub> ) - 1 × t <sub>CK</sub> (I <sub>DD</sub> ); t <sub>CK</sub> = t <sub>CK</sub> (I <sub>DD</sub> ), t <sub>RC</sub> = t <sub>RC</sub> (I <sub>DD</sub> ), t <sub>RRD</sub> = t <sub>RRD</sub> (I <sub>DD</sub> ), t <sub>RCD</sub> = t <sub>RCD</sub> (I <sub>DD</sub> ); CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I <sub>DD7</sub>	1760	1400	1360	1320	mA

**Table 13: DDR2 I<sub>DD</sub> Specifications and Conditions (Die Revision E) – 512MB**

Values shown for MT47H64M16 DDR2 SDRAM only and are computed from values specified in the 1Gb (32 Meg x 16) component data sheet

Parameter	Symbol	-80E/ -800	-667	-53E	-40E	Units	
<b>Operating one bank active-precharge current:</b> $t_{CK} = t_{CK} (I_{DD})$ , $t_{RC} = t_{RC} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MIN} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD0</sub>	600	540	440	440	mA	
<b>Operating one bank active-read-precharge current:</b> I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RC} = t_{RC} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MIN} (I_{DD})$ , $t_{RCD} = t_{RCD} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data pattern is same as I <sub>DD4W</sub>	I <sub>DD1</sub>	700	520	480	460	mA	
<b>Precharge power-down current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2P</sub>	28	28	28	28	mA	
<b>Precharge quiet standby current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD2Q</sub>	300	260	180	160	mA	
<b>Precharge standby current:</b> All device banks idle; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is HIGH, S# is HIGH; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD2N</sub>	320	280	200	160	mA	
<b>Active power-down current:</b> All device banks open; $t_{CK} = t_{CK} (I_{DD})$ ; CKE is LOW; Other control and address bus inputs are stable; Data bus inputs are floating	I <sub>DD3P</sub>	Fast PDN exit MR[12] = 0	160	120	120	120	mA
		Slow PDN exit MR[12] = 1	40	40	40	40	mA
<b>Active standby current:</b> All device banks open; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD3N</sub>	340	300	240	220	mA	
<b>Operating burst write current:</b> All device banks open; Continuous burst writes; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4W</sub>	1260	800	720	640	mA	
<b>Operating burst read current:</b> All device banks open; Continuous burst read, I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = 0; $t_{CK} = t_{CK} (I_{DD})$ , $t_{RAS} = t_{RAS} \text{ MAX} (I_{DD})$ , $t_{RP} = t_{RP} (I_{DD})$ ; CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are switching; Data bus inputs are switching	I <sub>DD4R</sub>	1280	880	720	640	mA	
<b>Burst refresh current:</b> $t_{CK} = t_{CK} (I_{DD})$ ; REFRESH command at every $t_{RFC} (I_{DD})$ interval; CKE is HIGH, S# is HIGH between valid commands; Other control and address bus inputs are switching; Data bus inputs are switching	I <sub>DD5</sub>	1120	1080	1000	960	mA	
<b>Self refresh current:</b> CK and CK# at 0V; CKE ≤ 0.2V; Other control and address bus inputs are floating; Data bus inputs are floating	I <sub>DD6</sub>	28	28	28	28	mA	





**Table 13: DDR2 I<sub>DD</sub> Specifications and Conditions (Die Revision E) – 512MB (Continued)**

Values shown for MT47H64M16 DDR2 SDRAM only and are computed from values specified in the 1Gb (32 Meg x 16) component data sheet

Parameter	Symbol	-80E/ -800	-667	-53E	-40E	Units
<b>Operating bank interleave read current:</b> All device banks interleaving reads; I <sub>OUT</sub> = 0mA; BL = 4, CL = CL (I <sub>DD</sub> ), AL = <sup>t</sup> RCD (I <sub>DD</sub> ) - 1 × <sup>t</sup> CK (I <sub>DD</sub> ); <sup>t</sup> CK = <sup>t</sup> CK (I <sub>DD</sub> ), <sup>t</sup> RC = <sup>t</sup> RC (I <sub>DD</sub> ), <sup>t</sup> RRD = <sup>t</sup> RRD (I <sub>DD</sub> ), <sup>t</sup> RCD = <sup>t</sup> RCD (I <sub>DD</sub> ); CKE is HIGH, S# is HIGH between valid commands; Address bus inputs are stable during deselects; Data bus inputs are switching	I <sub>DD7</sub>	1760	1400	1320	1200	mA

## Serial Presence-Detect

For the latest SPD data, refer to Micron's SPD page: [www.micron.com/SPD](http://www.micron.com/SPD).

**Table 14: SPD EEPROM Operating Conditions**

Parameter/Condition	Symbol	Min	Max	Units
Supply voltage	$V_{DDSPD}$	1.7	3.6	V
Input high voltage: logic 1; All inputs	$V_{IH}$	$V_{DDSPD} \times 0.7$	$V_{DDSPD} + 0.5$	V
Input low voltage: logic 0; All inputs	$V_{IL}$	-0.6	$V_{DDSPD} \times 0.3$	V
Output low voltage: $I_{OUT} = 3mA$	$V_{OL}$	-	0.4	V
Input leakage current: $V_{IN} = GND$ to $V_{DD}$	$I_{LI}$	0.1	3	$\mu A$
Output leakage current: $V_{OUT} = GND$ to $V_{DD}$	$I_{LO}$	0.05	3	$\mu A$
Standby current	$I_{SB}$	1.6	4	$\mu A$
Power supply current, READ: SCL clock frequency = 100 kHz	$I_{CCR}$	0.4	1	mA
Power supply current, WRITE: SCL clock frequency = 100 kHz	$I_{CCW}$	2	3	mA

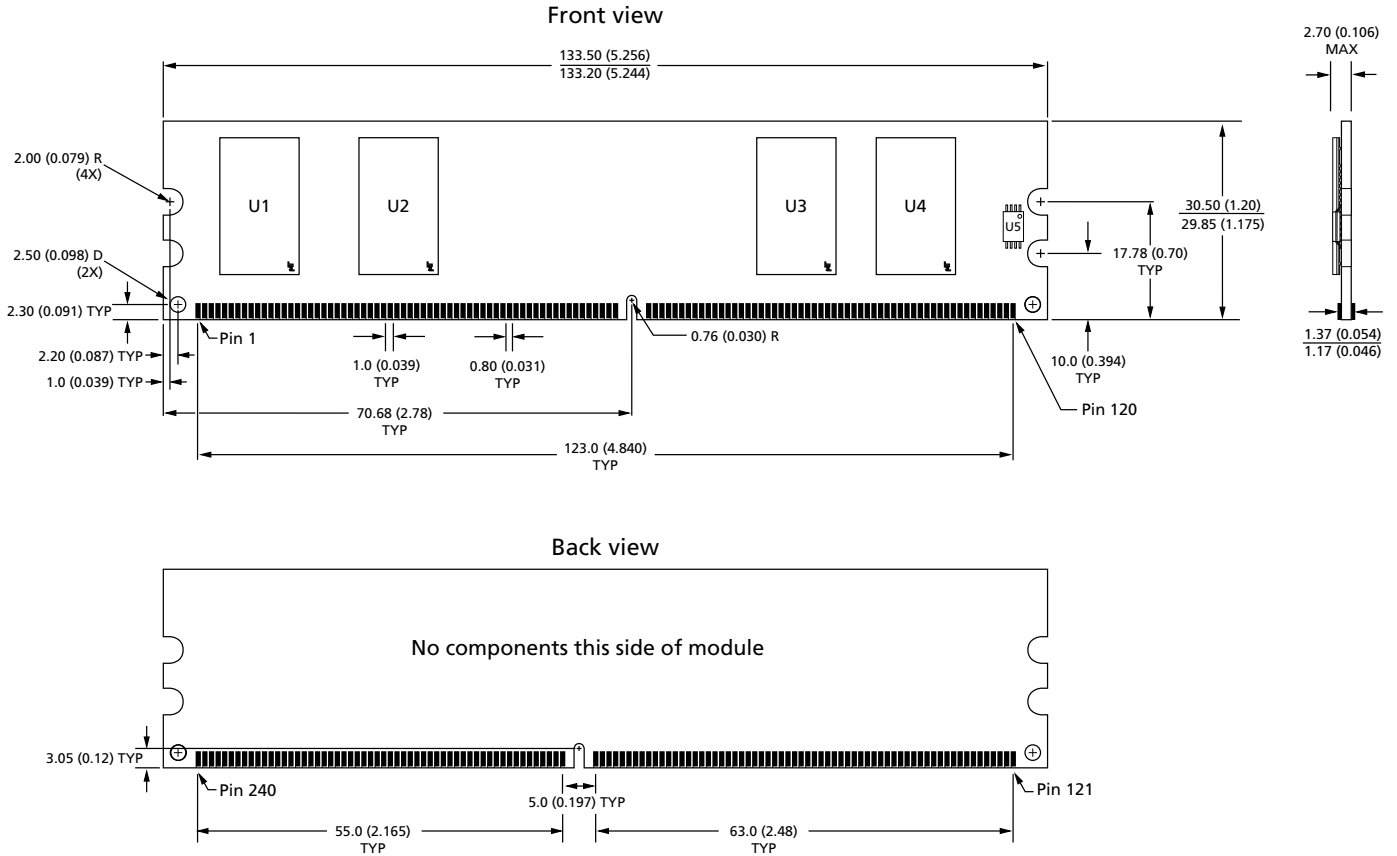
**Table 15: SPD EEPROM AC Operating Conditions**

Parameter/Condition	Symbol	Min	Max	Units	Notes
SCL LOW to SDA data-out valid	$t_{AA}$	0.2	0.9	$\mu s$	1
Time bus must be free before a new transition can start	$t_{BUF}$	1.3	-	$\mu s$	
Data-out hold time	$t_{DH}$	200	-	ns	
SDA and SCL fall time	$t_F$	-	300	ns	2
SDA and SCL rise time	$t_R$	-	300	ns	2
Data-in hold time	$t_{HD:DAT}$	0	-	$\mu s$	
Start condition hold time	$t_{HD:STA}$	0.6	-	$\mu s$	
Clock HIGH period	$t_{HIGH}$	0.6	-	$\mu s$	
Noise suppression time constant at SCL, SDA inputs	$t_I$	-	50	$\mu s$	
Clock LOW period	$t_{LOW}$	1.3	-	$\mu s$	
SCL clock frequency	$t_{SCL}$	-	400	kHz	
Data-in setup time	$t_{SU:DAT}$	100	-	ns	
Start condition setup time	$t_{SU:STA}$	0.6	-	$\mu s$	3
Stop condition setup time	$t_{SU:STO}$	0.6	-	$\mu s$	
WRITE cycle time	$t_{WRC}$	-	10	ms	4

- Notes:
1. To avoid spurious start and stop conditions, a minimum delay is placed between SCL = 1 and the falling or rising edge of SDA.
  2. This parameter is sampled.
  3. For a restart condition or following a WRITE cycle.
  4. The SPD EEPROM WRITE cycle time ( $t_{WRC}$ ) is the time from a valid stop condition of a write sequence to the end of the EEPROM internal ERASE/PROGRAM cycle. During the WRITE cycle, the EEPROM bus interface circuit is disabled, SDA remains HIGH due to pull-up resistance, and the EEPROM does not respond to its slave address.

## Module Dimensions

**Figure 3: 240-Pin DDR2 UDIMM**



- Notes: 1. All dimensions are in millimeters (inches); MAX/MIN or typical (TYP) where noted.  
 2. The dimensional diagram is for reference only. Refer to the JEDEC MO document for additional design dimensions.

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This data sheet contains minimum and maximum limits specified over the power supply and temperature range set forth herein. Although considered final, these specifications are subject to change, as further product development and data characterization sometimes occur.