# **General Description**

The MAX1920/MAX1921 step-down converters deliver over 400mA to outputs as low as 1.25V. These converters use a unique proprietary current-limited control scheme that achieves over 90% efficiency. These devices maintain extremely low quiescent supply current ( $50\mu$ A), and their high 1.2MHz (max) operating frequency permits small, low-cost external components. This combination makes the MAX1920/MAX1921 excellent high-efficiency alternatives to linear regulators in space-constrained applications.

Internal synchronous rectification greatly improves efficiency and eliminates the external Schottky diode required in conventional step-down converters. Both devices also include internal digital soft-start to limit input current upon startup and reduce input capacitor requirements.

The MAX1920 provides an adjustable output voltage (1.25V to 4V). The MAX1921 provides factory-preset output voltages (see the *Selector Guide*). Both are available in space-saving 6-pin SOT23 packages. The MAX1920 is also available in a 6-pin TDFN package.

### Applications

OUTPUT

1.5V UP TO 400mA

4.7µF

Next-Generation Wireless Handsets PDAs, Palmtops, and Handy-Terminals Battery-Powered Equipment CDMA Power Amplifier Supply

 $|\rangle$ 

PGND

OUT

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///XI///

MAX1921

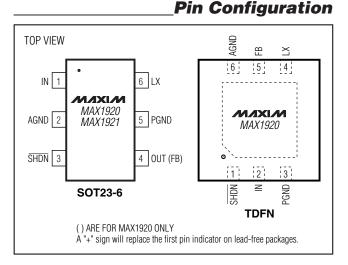
### \_Features

- 400mA Guaranteed Output Current
- Internal Synchronous Rectifier for >90% Efficiency
- Tiny 6-Pin SOT23 Package
- Available in 6-Pin TDFN Package (MAX1920)
- Up to 1.2MHz Switching Frequency for Small External Components
- 50µA Quiescent Supply Current
- ♦ 0.1µA Logic-Controlled Shutdown
- ♦ 2V to 5.5V Input Range
- Fixed 1.5V, 1.8V, 2.5V, 3V, and 3.3V Output Voltages (MAX1921)
- Adjustable Output Voltage (MAX1920)
- ±1.5% Initial Accuracy
- Soft-Start Limits Startup Current

# **\_Ordering Information**

PART	TEMP RANGE	PIN-PACKAGE
MAX1920EUT-T	-40°C to +85°C	6 SOT23-6
MAX1920EUT+T	-40°C to +85°C	6 SOT23-6
MAX1920ETT-T	-40°C to +85°C	6 TDFN
MAX1920ETT+T	-40°C to +85°C	6 TDFN
MAX1921EUTT	-40°C to +85°C	6 SOT23-6
MAX1921EUT+T	-40°C to +85°C	6 SOT23-6

**Note:** The MAX1921 offers five preset output voltage options. See the Selector Guide, and then insert the proper designator into the blanks above to complete the part number. +Denotes lead-free package.



# **Typical Operating Circuit**

4.7µH

5600nF

4.75kΩ

### 

INPLIT

2V TO 5.5V

CIN

ON

OFF

IN

AGND

SHDN

\_ Maxim Integrated Products 1

For pricing, delivery, and ordering information, please contact Maxim/Dallas Direct! at 1-888-629-4642, or visit Maxim's website at www.maxim-ic.com.

### **ABSOLUTE MAXIMUM RATINGS**

IN, FB,  $\overline{SHDN}$  to AGND .....-0.3V to +6V OUT to AGND, LX to PGND .....-0.3V to (IN + 0.3V) AGND to PGND .....-0.3V to (IN + 0.3V) OUT Short Circuit to GND ......10s Continuous Power Dissipation (TA = +70°C) 6-Pin SOT23-6 (derate 8.7mW/°C above +70°C) ....695mW 6-Pin TDFN (derate 18.2mW/°C above +70°C) ....1454.5mW

Operating Temperature Range	40°C to +85°C
Junction Temperature	+150°C
Storage Temperature	-65°C to +150°C
Lead Temperature (soldering 10s)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

# ELECTRICAL CHARACTERISTICS

(VIN = 3.6V, SHDN = IN, T<sub>A</sub> = 0°C to +85°C. Typical parameters are at T<sub>A</sub> = +25°C, unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	MAX	UNITS	
		I(LX) < 400mA	2.5		5.5		
Input Voltage Range	VIN	I(LX) < 200mA (MAX1921EUT15, MAX1921EUT18)	2.0		2.5	V	
Startup Voltage					2.0	V	
UVLO Threshold	UVLO	V <sub>IN</sub> rising		1.85	1.95	V	
OVEO THESHOLD	OVLO	V <sub>IN</sub> falling	1.50	1.65		v	
UVLO Hysteresis				200		mV	
Quiescent Supply Current	IIN	No switching, no load		50	70	μΑ	
Quiescent Supply Current Dropout	I <sub>IN</sub>	$\overline{\text{SHDN}} = \text{IN}, \text{OUT/FB} = 0$		220	300	μA	
Shutdown Supply Current	ISHDN	SHDN = GND		0.1	4.0	μA	
Output Voltage Accuracy (MAX1921)		$I_{OUT} = 0, T_A = +25^{\circ}C$	-1.5		+1.5	%	
		$I_{OUT} = 0$ to 400mA, $T_A = -40^{\circ}C$ to $+85^{\circ}C$	-3		+3		
	Ì	$I_{OUT} = 0$ to 200mA, $T_A = -40^{\circ}C$ to $+85^{\circ}C$	-3		+3	]	
OUT BIAS Current	lout	SHDN = 0	1				
COT BIAS Current	1001	OUT at regulation voltage		8	16	μA	
Output Voltage Range (MAX1920)		Figure 4, IN = 4.5V	1.25		4.00	V	
		T <sub>A</sub> = 25°C	1.231	1.25	1.269	<u> </u>	
FB Feedback Threshold (MAX1920)	VFB		1.220	1.25	1.280	V	
(111 0(1020)		$T_A = -40^{\circ}C \text{ to } +85^{\circ}C$	1.210		1.280		
FB Feedback Hysteresis (MAX1920)	V <sub>HYS</sub>			5		mV	
FB Bias Current (MAX1920)	I <sub>FB</sub>	FB = 1.5V		0.01	0.20	μA	
Load Regulation		I <sub>OUT</sub> = 0 to 400mA		0.005		%/mA	
Line Regulation		$V_{IN} = 2.5V \text{ to } 5.5V$		0.2		%/V	
SHDN Input Voltage High	VIH		1.6			V	
SHDN Input Voltage Low	VIL				0.4	V	
SHDN Leakage Current	ISHDN	SHDN = GND or IN	Ì	0.001	1.000	μA	
High-Side Current Limit	ILIMP		525	730	950	mA	

2

**Typical Operating Characteristics** 

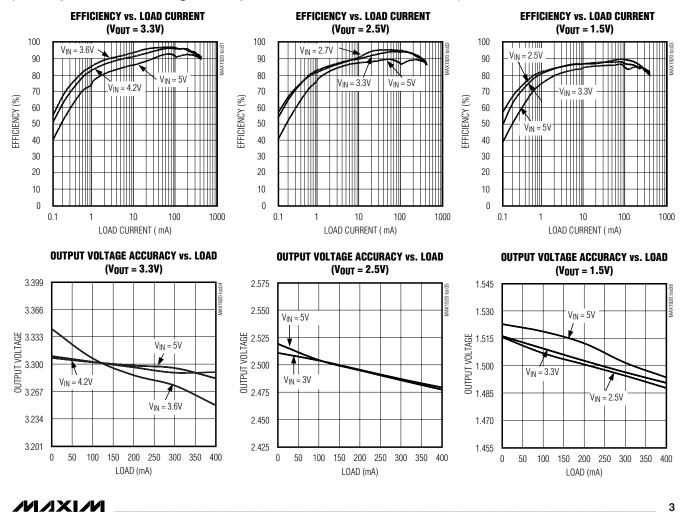
### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{IN} = 3.6V, \overline{SHDN} = IN, T_A = 0^{\circ}C$  to +85°C. Typical parameters are at  $T_A = +25^{\circ}C$ , unless otherwise noted.) (Note 1)

PARAMETER	SYMBOL	CONDITIONS	MIN	ТҮР	МАХ	UNITS
Low-Side Current Limit	ILIMN		350	550	800	mA
High-Side On-Resistance	Ronhs	$I_{LX} = -40 \text{mA}, V_{IN} = 3 \text{V}$		0.6	1.1	Ω
Rectifier On-Resistance	Ronsr	$I_{LX} = 40 \text{mA}, V_{IN} = 3 \text{V}$		0.5	0.9	Ω
Rectifier Off-Current Threshold	ILXOFF			60		mA
LX Leakage Current	ILXLEAK	$IN = \overline{SHDN} = 5.5V, LX = 0$ to IN		0.1	5.0	μA
LX Reverse Leakage Current	ILXLKR	IN unconnected, $V_{LX} = 5.5V$ , SHDN = GND		0.1	5.0	μA
Minimum On-Time	ton(MIN)		0.28	0.4	0.5	μs
Minimum Off-Time	toff(MIN)		0.28	0.4	0.5	μs

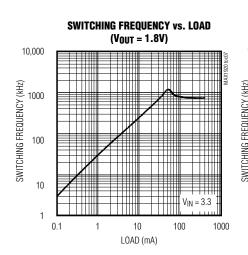
**Note 1:** All devices are 100% production tested at  $T_A = +25$ °C. Limits over the operating temperature range are guaranteed by design.

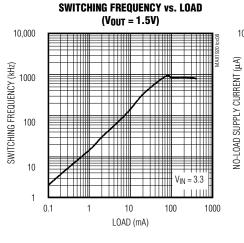
(C<sub>IN</sub> = 2.2µF ceramic, Circuit of Figure 1, components of Table 1, unless otherwise noted.)

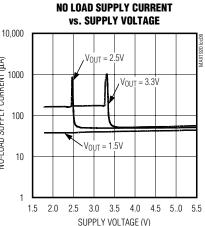


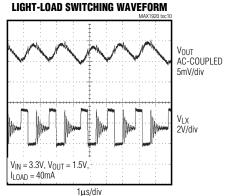
# **Typical Operating Characteristics (continued)**

(CIN = 2.2µF ceramic, Circuit of Figure 1, components of Table 1, unless otherwise noted.)

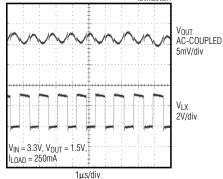




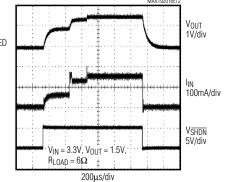


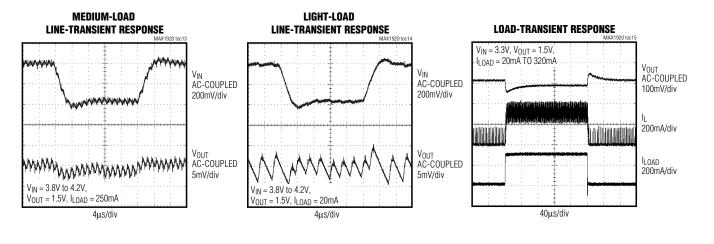






SOFT-START AND SHUTDOWN RESPONSE





# \_Pin Description

PIN	1	NAME	FUNCTION
TDFN*	SO	NAME	FUNCTION
2	1	IN	Supply voltage input for MAX1921EUT15 and MAX1921EUT18 is 2V to 5.5V. Supply voltage input for MAX1920 and other voltage versions of MAX1921 is 2.5V to 5.5V. Bypass IN to GND with a $2.2\mu$ F ceramic capacitor as close to IN as possible.
6	2	AGND	Analog Ground. Connect to PGND.
1	3	SHDN	Active-Low Shutdown Input. Connect $\overline{SHDN}$ to IN for normal operation. In shutdown, LX becomes high-impedance and quiescent current drops to 0.1 $\mu$ A.
_	4	OUT	MAX1921 Voltage Sense Input. OUT is connected to an internal voltage-divider.
5	4	FB	MAX1920 Voltage Feedback Input. FB regulates to 1.25V nominal. Connect FB to an external resistive voltage-divider between the output voltage and GND.
3	5	PGND	Power Ground. Connect to AGND.
4	6	LX	Inductor Connection

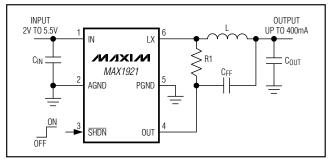
\*MAX1920 only.

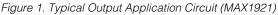
#### **Detailed Description**

The MAX1920/MAX1921 step-down DC-DC converters deliver over 400mA to outputs as low as 1.25V. They use a unique proprietary current-limited control scheme that maintains extremely low quiescent supply current ( $50\mu A$ ), and their high 1.2MHz (max) operating frequency permits small, low-cost external components.

#### **Control Scheme**

The MAX1920/MAX1921 use a proprietary, current-limited control scheme to ensure high-efficiency, fast transient response, and physically small external components. This control scheme is simple: when the output voltage is out of regulation, the error comparator begins a switching cycle by turning on the high-side switch. This switch remains on until the minimum on-time of 400ns expires and the output voltage regulates or the current-limit threshold is exceeded. Once off, the high-side switch remains off until the minimum off-time of 400ns expires and the output voltage falls out of regulation. During this period, the low-side synchronous rectifier turns on and





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remains on until either the high-side switch turns on again or the inductor current approaches zero. The internal synchronous rectifier eliminates the need for an external Schottky diode.

This control scheme allows the MAX1920/MAX1921 to provide excellent performance throughout the entire load-current range. When delivering light loads, the high-side switch turns off after the minimum on-time to reduce peak inductor current, resulting in increased efficiency and reduced output voltage ripple. When delivering medium and higher output currents, the MAX1920/MAX1921 extend either the on-time or the offtime, as necessary to maintain regulation, resulting in nearly constant frequency operation with high-efficiency and low-output voltage ripple.

#### **Shutdown Mode**

Connecting SHDN to GND places the MAX1920/ MAX1921 in shutdown mode and reduces supply current to  $0.1\mu$ A. In shutdown, the control circuitry, internal switching MOSFET, and synchronous rectifier turn off and LX becomes high impedance. Connect SHDN to IN for normal operation.

#### Soft-Start

The MAX1920/MAX1921 have internal soft-start circuitry that limits current draw at startup, reducing transients on the input source. Soft-start is particularly useful for higher impedance input sources, such as Li+ and alkaline cells. Soft-start is implemented by starting with the current limit at 25% of its full current value and gradually increasing it in 25% steps until the full current limit is reached. See Soft-Start and Shutdown Response in the *Typical Operating Characteristics*.

### **Design Procedure**

The MAX1920/MAX1921 are optimized for small external components and fast transient response. There are several application circuits (Figures 1 through 4) to allow the choice between ceramic or tantalum output capacitor and internally or externally set output voltages. The use of a small ceramic output capacitor is preferred for higher reliability, improved voltage-positioning transient response, reduced output ripple, and the smaller size and greater availability of ceramic versus tantalum capacitors.

#### **Voltage Positioning**

Figures 1 and 2 are the application circuits that utilize small ceramic output capacitors. For stability, the circuit obtains feedback from the LX node through R1, while load transients are fed-forward through CFF. Because there is no D.C. feedback from the output, the output voltage exhibits load regulation that is equal to the output load current multiplied by the inductor's series resistance. This small amount of load regulation is similar to voltage positioning as used by high-powered microprocessor supplies intended for personal computers. For the MAX1920/MAX1921, voltage positioning eliminates or greatly reduces undershoot and overshoot during load transients (see the *Typical Operating Characteristics*), which effectively halves the peak-to-peak output voltage excursions compared to traditional step-down converters.

For convenience, Table 1 lists the recommended external component values for use with the MAX1921 application circuit of Figure 1 with various input and output voltages.

#### Table 1. MAX1921 Suggested Components for Figure 1

		INPUT SOURCE				
OUTPUT	5V	3.3V, 1 Li+, 3 x AA	2.5V, 2 x AA			
3.3V 3.0V		<sup>O</sup> OUT = 10μF, CFF = 3300pF	N/A			
2.5V	$\label{eq:L} \begin{array}{l} {\sf L} = 6.8 \mu {\sf H}, \ {\sf C}_{{\sf O}{\sf U}{\sf T}} = 6.8 \mu {\sf F}, \\ {\sf R}1 = 5.62 k \Omega, \ {\sf C}_{{\sf F}{\sf F}} = 4700 {\sf p}{\sf F} \end{array}$		N/A			
1.8V 1.5V	$\begin{array}{l} L = 10 \mu H, \\ C_{OUT} = 10 \mu F, \\ R1 = 8.25 k \Omega, \\ C_{FF} = 3300 p F \end{array}$	L = 4.7μH, C( R1 = 4.75kΩ, (				

#### **Inductor Selection**

In order to calculate the smallest inductor, several calculations are needed. First, calculate the maximum duty cycle of the application as:

$$DutyCycle(MAX) = \frac{V_{OUT}}{V_{IN}(MIN)} \times 100\%$$

Second, calculate the critical voltage across the inductor as:

 $\label{eq:constraint} \begin{array}{l} \text{if } \text{DutyCycle}(\text{MAX}) < 50\%, \\ \text{then } \text{V}_{\text{CRITICAL}} = (\text{V}_{\text{IN}}(\text{MIN}) - \text{V}_{\text{OUT}}), \\ \text{else } \text{V}_{\text{CRITICAL}} = \text{V}_{\text{OUT}} \end{array}$ 

Last, calculate the minimum inductor value as:

$$L(MIN) = 2.5 \times 10^{-6} \times V_{CRITICAL}$$

Select the next standard value larger than L(MIN). The L(MIN) calculation already includes a margin for inductance tolerance. Although values much larger than L(MIN) work, transient performance, efficiency, and inductor size suffer.

A 550mA rated inductor is enough to prevent saturation for output currents up to 400mA. Saturation occurs when the inductor's magnetic flux density reaches the maximum level the core can support and inductance falls. Choose a low DC-resistance inductor to improve efficiency. Tables 2 and 3 list some suggested inductors and suppliers.

#### **Capacitor Selection**

For nearly all applications, the input capacitor,  $C_{IN,}$  may be as small as  $2.2\mu F$  ceramic with X5R or X7R

Table 2. Suggested Inductors

PART NUMBER	L (µH)	RL (ohms max)	Isat (A)	SIZE
	4.7	0.200	1.10	0.0 × 5 5 × 1.0
Coilcraft LPO1704	6.8	0.320	0.90	6.6 x 5.5 x 1.0 = 36.3mm <sup>3</sup>
2.0	10	0.410	0.80	- 00.01111
	4.7	0.080	0.90	0.0
Sumida CDRH3D16	6.8	0.095	0.73	3.8 x 3.8 x 1.8 = 26.0mm <sup>3</sup>
	10	0.160	0.55	= 20.0mm
Sumida	4.7	0.081	0.63	3.2 x 3.2 x 2.0
CDRH2D18	6.8	0.108	0.57	= 20.5mm <sup>3</sup>
Toko	4.7	0.38	0.74	3.6 x 3.6 x 1.2
D312F	10	0.79	0.50	= 15.6mm <sup>3</sup>
Toko	4.7	0.230	0.84	4.6 x 4.6 x 1.2
D412F	10	0.490	0.55	= 25.4mm <sup>3</sup>
Taka	4.7	0.087	1.14	EOVEOVOO
Toko D52LC	6.8	0.105	0.95	5.0 x 5.0 x 2.0 = 50.0mm <sup>3</sup>
	10	0.150	0.76	00.01111



dielectric. The input capacitor filters peak currents and noise at the voltage source and, therefore, must meet the input ripple requirements and voltage rating. Calculate the maximum RMS input current as:

$$I_{\rm IN}(\rm RMS) = I_{\rm OUT}(\rm MAX) \times \frac{\sqrt{V_{\rm OUT}(V_{\rm IN} - V_{\rm OUT})}}{V_{\rm IN}}$$

The output capacitor,  $C_{OUT}$ , may be either ceramic or tantalum depending upon the chosen application circuit (see Figures 1 through 4). Table 3 lists some suggested capacitor suppliers.

#### Ceramic Output Capacitor

For ceramic  $C_{OUT}$ , use the application circuit of Figure 1 or Figure 2. Calculate the minimum capacitor value as:

$$C_{OUT}(MIN) = 2.5 \times 10^{-6} \times V_{CRITICAL}$$

Select the next standard value larger than  $C_{OUT}(MIN)$ . The  $C_{OUT}(MIN)$  calculation already includes a margin for capacitor tolerance. Values much larger than  $C_{OUT}(MIN)$  always improve transient performance and stability, but capacitor size and cost increase.

#### Tantalum Output Capacitor

For tantalum  $C_{OUT}$ , use the application circuit of Figure 3 or Figure 4. With tantalum  $C_{OUT}$ , the equivalent series resistance (ESR) of  $C_{OUT}$  must be large enough for stability. Generally, 25mV of ESR-ripple at the feedback node is sufficient. The simplified calculation is:

$$ESR_{COUT}(MIN) = 8.0 \times 10^{-2} \times V_{OUT}$$

Because tantalum capacitors rarely specify minimum ESR, choose a capacitor with typical ESR that is about twice as much as ESR<sub>COUT</sub>(MIN). Although ESRs greater than this work, output ripple becomes larger.

For tantalum  $C_{OUT}$ , calculate the minimum output capacitance as:

$$C_{OUT}(MIN) = 1.25 \times \frac{L \times I_{OUT}(MAX)}{ESR_{COUT}(MIN) \times V_{CRITICAI}}$$

The 1.25 multiplier is for capacitor tolerance. Select any standard value larger than  $C_{OUT}(MIN)$ .

#### **Feedback and Compensation**

The MAX1921 has factory preset output voltages of 1.5V, 1.8V, 2.5V, 3V, and 3.3V, while the MAX1920 is externally adjusted by connecting FB to a resistive voltage-divider. When using a ceramic output capacitor, the feedback network must include a compensation feed-forward capacitor,  $C_{FF}$ .

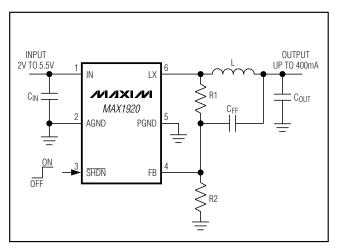


Figure 2. Typical Application Circuit (MAX1920)

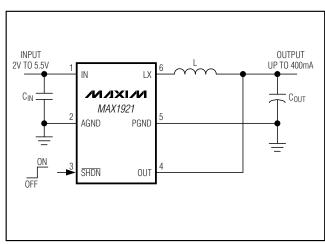


Figure 3. MAX1921 Application Circuit Using Tantalum Output Capacitor

UPPLIER PHONE		WEBSITE	
lcraft 847-639-6400		www.coilcraft.com	
	408-986-0424	www.kemet.com	
	814-237-1431	www.murata.com	
USA	847-956-0666	www.sumida.com	
Japan	81-3-3607-5111	www.surnida.com	
USA	408-573-4150	www.T-Yuden.com	
Japan	81-3-3833-5441	www.yuden.co.jp	
USA	847-297-0070	www.tokoam.com	
Japan	81-3-3727-1161	www.toko.co.jp	
	USA Japan USA Japan USA	847-639-6400        408-986-0424        814-237-1431        USA      847-956-0666        Japan      81-3-3607-5111        USA      408-573-4150        Japan      81-3-3833-5441        USA      847-297-0070	

#### **Table 3. Component Suppliers**

#### MAX1921 Using Ceramic COUT

When using the application circuit of Figure 1, the inductor's series resistance causes a small amount of load regulation, as desired for a voltage-positioning load transient response. Choose R1 such that V<sub>OUT</sub> is high at no load by about half of this load regulation. The simplified calculation is:

$$R1=5 \times 10^4 \times R_1$$
 (MAX)

where  $R_L(MAX)$  is the maximum series resistance of the inductor. Select a standard resistor value that is within 20% of this calculation.

Next, calculate CFF for 25mV ripple at the internal feedback node. The simplified calculation is:

$$C_{FF} = 2.5 \times 10^{-5} / R1$$

where R1 is the standard resistor value that is used. Select a standard capacitor value that is within 20% of the calculated CFF.

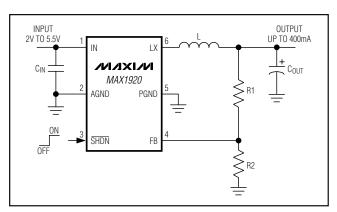


Figure 4. MAX1920 Application Circuit Using Tantalum Output Capacitor

#### MAX1920 Using Ceramic COUT

When using the application circuit of Figure 2, the inductor's series resistance causes a small amount of load regulation, as desired for a voltage-positioning load transient response. Choose R1 and R2 such that  $V_{OUT}$  is high at no load by about half of this load regulation:

$$R1 = R2 \times \left(\frac{V_{OUT} + R_L \times I_{OUT}(MAX)/2}{V_{REF}} - 1\right)$$

where R2 is chosen in the 50k $\Omega$  to 500k $\Omega$  range, VREF = 1.25V and R<sub>L</sub> is the typical series resistance of the inductor. Use 1% or better resistors.

Next, calculate the equivalent resistance at the FB node as:

$$\operatorname{Req} = \operatorname{R1} || \operatorname{R2} = \frac{\operatorname{R1} \times \operatorname{R2}}{\operatorname{R1} + \operatorname{R2}}$$

Then, calculate CFF for 25mV ripple at FB. The simplified calculation is:

$$C_{FF} = 2.5 \times 10^{-5} / \text{Reg}$$

Select a standard capacitor value that is within 20% of the calculated  $\ensuremath{\mathsf{CFF}}$  .

#### MAX1920 Using Tantalum COUT

When using the application circuit of Figure 4, choose R1 and R2 such as to obtain the desired  $V_{OUT}$ :

$$R1 = R2 \times \left(\frac{V_{OUT}}{V_{REF}} - 1\right)$$

where R2 is chosen to be less than 50k $\Omega$  and VREF = 1.25V. Use 1% or better resistors.

#### **Layout Considerations**

High switching frequencies make PC board layout a very important part of design. Good design minimizes excessive EMI on the feedback paths and voltage gradients in the ground plane, both of which can result in instability or regulation errors. Connect the inductor, input filter capacitor, and output filter capacitor as close to the device as possible, and keep their traces short, direct, and wide. Connect their ground pins at a single common node in a star ground configuration. The external voltage-feedback network should be very close to the FB pin, within 0.2in (5mm). Keep noisy traces, such as the LX trace, away from the voltagefeedback network; also keep them separate, using grounded copper. The MAX1920/MAX1921 evaluation kit data sheet includes a proper PC board layout and routing scheme.



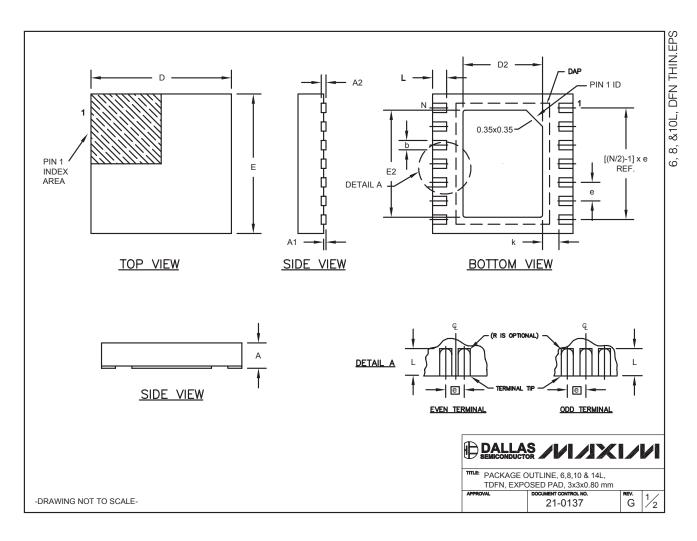
TRANSISTOR COUNT: 1467

# **Chip Information**

PART	V <sub>OUT</sub> (V)	TOP MARK
MAX1920EUT	Adjustable	ABCO
MAX1920ETT	Adjustable	ADR
MAX1921EUT33	3.3	ABCJ
MAX1921EUT30	3.0	ABCK
MAX1921EUT25	2.5	ABCL
MAX1921EUT18	1.8	ABCM
MAX1921EUT15	1.5	ABCN

# Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



# Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to www.maxim-ic.com/packages.)

COMMC	COMMON DIMENSIONS						
SYMBOL	MIN.	MAX.					
Α	0.70	0.80					
D	2.90	3.10					
E	2.90	3.10					
A1	0.00	0.05					
L	0.20	0.40					
k	0.25 MIN.						
A2	0.20 REF.						

PACKAGE VARIATIONS								
PKG. CODE	N	D2	E2	е	JEDEC SPEC	b	[(N/2)-1] x e	DOWNBONDS ALLOWED
T633-1	6	1.50±0.10	2.30±0.10	0.95 BSC	MO229 / WEEA	0.40±0.05	1.90 REF	NO
T633-2	6	1.50±0.10	2.30±0.10	0.95 BSC	MO229 / WEEA	0.40±0.05	1.90 REF	NO
T833-1	8	1.50±0.10	2.30±0.10	0.65 BSC	MO229 / WEEC	0.30±0.05	1.95 REF	NO
T833-2	8	1.50±0.10	2.30±0.10	0.65 BSC	MO229 / WEEC	0.30±0.05	1.95 REF	NO
T833-3	8	1.50±0.10	2.30±0.10	0.65 BSC	MO229 / WEEC	0.30±0.05	1.95 REF	YES
T1033-1	10	1.50±0.10	2.30±0.10	0.50 BSC	MO229 / WEED-3	0.25±0.05	2.00 REF	NO
T1433-1	14	1.70±0.10	2.30±0.10	0.40 BSC		0.20±0.05	2.40 REF	YES
T1433-2	14	1.70±0.10	2.30±0.10	0.40 BSC		0.20±0.05	2.40 REF	NO

NOTES:

- ALL DIMENSIONS ARE IN mm. ANGLES IN DEGREES.
  COPLANARITY SHALL NOT EXCEED 0.08 mm.
  WARPAGE SHALL NOT EXCEED 0.10 mm.

- 4. PACKAGE LENGTH/PACKAGE WIDTH ARE CONSIDERED AS
- SPECIAL CHARACTERISTIC(S).
- 5. DRAWING CONFORMS TO JEDEC M0229, EXCEPT DIMENSIONS "D2" AND "E2", AND T1433-1 & T1433-2.
  6. "N" IS THE TOTAL NUMBER OF LEADS.
  7. NUMBER OF LEADS SHOWN ARE FOR REFERENCE ONLY.

-DRAWING NOT TO SCALE-

M/IXI/M

G 2/2

DALLAS

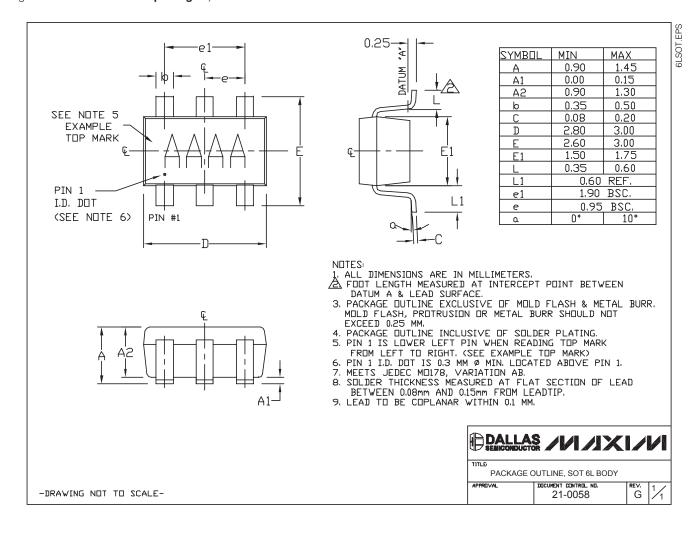
21-0137

PACKAGE OUTLINE, 6,8,10 & 14L, TDFN, EXPOSED PAD, 3x3x0.80 mm

APPROVAL

### \_Package Information (continued)

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information, go to **www.maxim-ic.com/packages**.)



Maxim cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim product. No circuit patent licenses are implied. Maxim reserves the right to change the circuitry and specifications without notice at any time.

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