

Synchronous PWM with VFC Controller

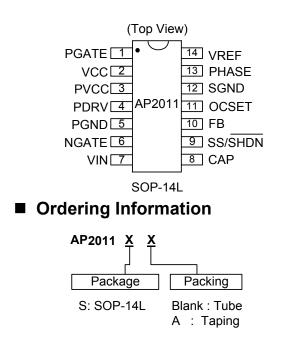
Features

- Single 10V to 40V Supply Application
- 1.25V + 2.0% Voltage Reference
- Virtual Frequency Control[™].
- Fast Transient Response.
- Synchronous Operation for High Efficiency
- Current Limit Function.
- Small Size with Minimum External Components
- Soft Start and Shutdown Functions
- Industrial Temperature Range
- Under Voltage Lockout Function
- SOP-14L **Pb-Free** Package

Applications

- Microprocessor Core Supply
- Low Cost Synchronous Applications
- Voltage Regulator Modules (VRM)
- Networking Power Supplies
- Sequenced Power Supplies
- Telecommunication Power Supplies.

Pin Assignments



General Description

The AP2011 is a low-cost, full featured, synchronous voltage-mode controller designed for use in single ended power supply applications primary where efficiency is of concern. Synchronous operation allows for the elimination of heat sinks in many applications. The AP2011 is ideal for implementing DC/DC converters needed to power advanced microprocessors in low cost systems or in distributed power applications where efficiency is important. Internal level-shift, high-side drive circuitry, and preset shoot-thru control, allows the use of inexpensive 1P+1N-channel power switches.

AP2011's features include temperature ompensated voltage reference, Virtual Frequency Control[™] method to reduce external component count, an internal virtual frequency 200KHz oscillator, under-voltage lockout protection, soft-start, shutdown function and current sense comparator circuitry.

Virtual Frequency Control is a trademark of PWRTEK, LLC.

Pin Descriptions

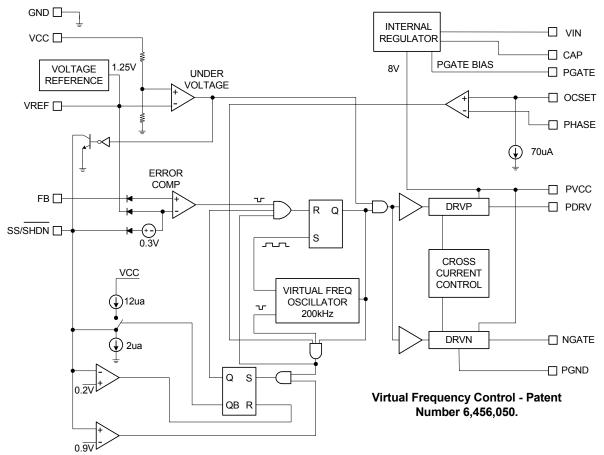
Pin Name	Pin No.	Description			
PGATE	1	Level shift-gate driver			
VCC	2	Internal regulator voltage			
PVCC	3	Power VCC			
PDRV	4	PMOS Gat driver			
PGND	5	Power Ground			
NGATE	6	Low side driver output (N MOSFET)			
VIN	7	Chip supply voltage			
CAP	8	Charge pump pin			
SS/SHDN	9	Soft start, a capacitor to ground sets the slow start time/set low for shutdown function.			
FB	10	Feedback input			
OCSET	11	Sets the converter over-current trip point			
SGND	12	Signal Ground			
		Input from the phase node between the MOSFETs			
VREF	14	Reference voltage			

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Block Diagram



AP2011 FUNCTIONAL BLOCK DIAGRAM

Absolute Maximum Ratings

Symbol	Parameter	Range.	Unit	
V _{IN}	VCC to GND	0 to 42	V	
V _{PHASE}	PHASE to GND	0 to 42	V	
PLC	Thermal Resistance Junction to Case	60	°C/W	
Θ_{JA}	Thermal Resistance Junction to Ambient	150	°C/W	
T _{OP}	Operating Temperature Range	-40 to +85	°C	
T _{ST}	Storage Temperature Range	-65 to +150	°C	
T _{LEAD}	Lead Temperature (Soldering) 10 Sec.	300	°C	



AP2011

Synchronous PWM Controller

Electrical Characteristics

$\begin{tabular}{ c c c c c c } \hline Power Supply & $$V_{IN}$ Supply Voltage (Recommended) & 10 & - & 40 & V \\ \hline V_{IN}$ Supply Current & $$0$ - & $$8$ & 10 & $$mA$ \\ \hline \Delta V_{Load}$ & Load Regulation & $$0$ A < $$I_{Load} < 3A & - & $$50$ & 70 & $$mV$ \\ \hline \Delta V_{LINE}$ & Line Regulation & $$V_{IN} = 10V to 40V$ & $$10V$ & $$10V$ & $$10V$ & $$10V$ & $$0$ & $$8$ & $$5$ & $$9$ & V$ \\ \hline V_{IN} -V_{CC}$ & Internal Regulator Voltage & $$V_{IN} = 10V$ to 40V$ & $$8$ & $$8.5$ & $$9$ & V$ \\ \hline V_{IN} -V_{CC}$ & $$C_{C}$ Dropout Voltage & $$V_{IN} = 10V$ to 40V$ & $$8$ & $$8.5$ & $$9$ & V$ \\ \hline V_{IN} -V_{CC}$ & $$C_{C}$ Dropout Voltage & $$V_{IN} = 10V$ & $$-0.4$ & $-$0$.2$ & $-$ & $$V$ \\ \hline Error Comparator & $$-$ & $$-$ & $$0$ & $$-$ & $$V$ \\ \hline Error Comparator & $$-$ & $$-$ & $$0$ & $$0$ & $$1$ & $$250 $ $ $$nS$ & $$1$ & $$-$ & $$0$ & $$0$ & $$1$ & $$2$ & $$0$ & $$nS$ & $$1$ & $$-$ & $$0$ & $$0$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$0$ & $$1$ & $$1$ & $$2$ & $$0$ & $$1$ & $$1$ & $$2$ & $$0$ & $$1$ & $$1$ & $$2$ & $$0$ & $$1$ & $$1$ & $$2$ & $$0$ & $$1$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ & $$1$ & $$2$ &$	Unless specified: V _{IN} =20V; GND = 0V;V₀ = 5V; T」 = 25°C							
$\begin{tabular}{ c c c c c c } \hline V_{\rm IN} & Supply Voltage (Recommended) & 10 & - & 40 & V \\ \hline I_{\rm IN} & Supply Current & - & 8 & 10 & mA \\ \hline \Delta V_{Load} & Load Regulation & 0A < I_{Load} < 3A & - & 50 & 70 & mV \\ \hline \Delta V_{LINE} & Line Regulation & V_{\rm IN}^{-10V to 40V} & - & 110 & 150 & mV \\ \hline V_{\rm CC} & Internal Regulator Voltage & V_{\rm IN} = 10V to 40V & 8 & 8.5 & 9 & V \\ \hline V_{\rm IN} -V_{\rm CC} & V_{\rm CC} Dropout Voltage & V_{\rm IN} = 10V to 40V & 8 & 8.5 & 9 & V \\ \hline V_{\rm IN} -V_{\rm CC} & V_{\rm CC} Dropout Voltage & - & 1.5 & 3.0 & V \\ \hline V_{\rm IN} -V_{\rm GATE} & P-Gate to Source Voltage (Off) & V_{\rm IN} = 10V & -0.4 & -0.2 & - & V \\ \hline error Comparator & & & & & & & & & & & & & & & & & & &$	Symbol	Parameter	Conditions	Min.	Тур.	Max.	Unit	
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$\begin{tabular}{ c c c c c c c c c c c c c c c c c c c$	V _{IN}	Supply Voltage (Recommended)		10	-	40	V	
$\begin{tabular}{ c c c c c c } \hline \Delta V_{LINE} & Line Regulation & V_{IN}^{I}=10V to 40V & - & 110 & 150 & mV \\ \hline V_{CC} & Internal Regulator Voltage & V_{IN} =10V to 40V & 8 & 8.5 & 9 & V \\ \hline V_{IN} -V_{CC} & V_{CC} Dropout Voltage & - & 1.5 & 3.0 & V \\ \hline V_{IN} -P_{GATE} & P-Gate to Source Voltage (Off) & V_{IN}^{I}=10V & -0.4 & -0.2 & - & V \\ \hline Error Comparator & & & & & & & & & & & & & & & & & & &$	I _{IN}	Supply Current		-	8	10	mA	
$\begin{tabular}{ c $	ΔV_{Load}	Load Regulation		-	50	70	mV	
$\begin{tabular}{ c c c c c } \hline V_{IN} -V_{CC} & V_{CC} Dropout Voltage & - & 1.5 & 3.0 & V \\ \hline V_{IN} -P_{GATE} & P-Gate to Source Voltage (Off) & V_{IN} = 10V & -0.4 & -0.2 & - & V \\ \hline \hline V_{IN} -P_{GATE} & P-Gate to Source Voltage (Off) & V_{IN} = 40V & -0.4 & -0.2 & - & V \\ \hline \hline \hline Error Comparator & & & & & & & & & & & & & & & & & & &$	ΔV_{LINE}	Line Regulation	I _{Load} =1A	-	110	150	mV	
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$\begin{array}{c c c c c c } \hline V_{\text{IN}} = P_{\text{GATE}} & P_{\text{Gate to Source Voltage (Off)} & V_{\text{IN}} = 40V & -0.4 & -0.2 & - & V \\ \hline \hline \text{Error Comparator} & & & & \\ \hline \hline \text{Error Comparator} & & & & & \\ \hline \hline \text{A}_{\text{OL}} & \text{Gain (A}_{\text{OL}}) & & - & 60 & - & dB \\ \hline \hline \text{I}_{\text{B}} & \text{Input Bias} & & - & 0.2 & 1 & uA \\ \hline \hline \text{Oscillator} & & & & \\ \hline \hline \text{Oscillator} & & & & \\ \hline \text{Oscillator Max Duty Cycle} & & & 80 & 85 & - & \% \\ \hline \hline \text{Protection} & & & & \\ \hline \hline \text{T}_{\text{DEAD}} & \text{Dead Time} & & 100 & 150 & 250 & nS \\ \hline \ \text{I}_{\text{OCSET}} & \text{Over Current Set Isink} & V_{\text{IN}} - 1.5V \leq & & - & 70 & - & uA \\ \hline \hline \text{Reference} & & & & \\ \hline \hline V_{\text{REF}} & & & & \\ \hline Reference & & & & \\ \hline \hline \text{Soft Start} & & & & \\ \hline \hline \text{I}_{\text{SSC}} & \text{Charge Current} & V_{\text{SS}} = 1.5V & 8.0 & 10 & 12 & uA \\ \hline \hline \text{I}_{\text{SSD}} & & & & \\ \hline \text{Discharge Current} & V_{\text{SS}} = 1.5V & 1.3 & 2 & 2.7 & uA \\ \hline \hline \text{Under voltage lockout (UVLO)} & & & \\ \hline \hline V_{\text{UT}} & & & & \\ \hline \hline V_{\text{UT}} & & & & \\ \hline V_{\text{UVT}} & & & & \\ \hline \end{array} $	V_{IN} - V_{CC}	V _{cc} Dropout Voltage		-	1.5	3.0	V	
$\begin{tabular}{ c c c c c c } \hline A_{OL} & Gain (A_{OL}) & & - & 60 & - & dB \\ \hline I_B & Input Bias & & - & 0.2 & 1 & uA \\ \hline Oscillator & & & & & & & & & & & & & & & & & & &$	V_{IN} -P _{GATE}	P-Gate to Source Voltage (Off)		-0.4	-0.2	-	V	
$\begin{tabular}{ c c c c c c } \hline Input Bias & - & 0.2 & 1 & uA \\ \hline Oscillator & & & & & & & & & & & & \\ \hline DC_{MAX} & Oscillator Max Duty Cycle & & & & & & & & & & & & & & & & & & &$	Error Comp	parator						
$ \begin{array}{c c c c c c c c c } \hline \textbf{Oscillator} & \textbf{Oscillator Max Duty Cycle} & \textbf{80} & \textbf{85} & - & \% \\ \hline \textbf{Protection} & & & & & & & & & & & & & & & & & & &$	A _{OL}	Gain (A _{OL})		-	60	-	dB	
$ \begin{array}{ c c c c c } \hline DC_{MAX} & Oscillator Max Duty Cycle & 80 & 85 & - & \% \\ \hline Protection & & & & & \\ \hline T_{DEAD} & Dead Time & 100 & 150 & 250 & nS \\ \hline I_{OCSET} & Over Current Set Isink & V_{IN} - 1.5V \leq \\ V_{OCSET} \leq V_{IN} & - & 70 & - & uA \\ \hline Reference & & & & \\ \hline V_{REF} & Reference Voltage & 0^{\circ}C to 70^{\circ}C & 1.225 & 1.25 & 1.275 & V \\ \hline Accuracy & 0^{\circ}C to 70^{\circ}C & 1.225 & 1.25 & 1.275 & V \\ \hline -2 & - & + 2 & \% \\ \hline Soft Start & & & \\ \hline I_{SSC} & Charge Current & V_{SS} = 1.5V & 8.0 & 10 & 12 & uA \\ \hline I_{SSD} & Discharge Current & V_{SS} = 1.5V & 1.3 & 2 & 2.7 & uA \\ \hline Under voltage & Iockout (UVLO) & & & \\ \hline V_{UT} & Upper Threshold Voltage (V_{CC}) & & T_A = 25^{\circ}C & - & 6.5 & - & V \\ \hline \end{array} $	I _B	Input Bias		-	0.2	1	uA	
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$\begin{array}{c c c c c c c c c c c c c c c c c c c $	Protection							
$\begin{tabular}{ c c c c c c c } \hline I_{OCSET} & OVer Current Set IsInk & V_{OCSET} \leq V_{IN} & - & I/O & - & UA \\ \hline Reference & & & & & & \\ \hline Reference & & & & & & & \\ \hline V_{REF} & Reference Voltage & 0^{\circ}C to 70^{\circ}C & 1.225 & 1.25 & 1.275 & V \\ \hline Accuracy & 0^{\circ}C to 70^{\circ}C & -2 & - & + 2 & \% \\ \hline Soft Start & & & & & & \\ \hline I_{SSC} & Charge Current & V_{SS} = 1.5V & 8.0 & 10 & 12 & uA \\ \hline I_{SSD} & Discharge Current & V_{SS} = 1.5V & 1.3 & 2 & 2.7 & uA \\ \hline Under voltage lockout (UVLO) & & & & \\ \hline V_{UT} & Upper Threshold Voltage (V_{CC}) & & & & & & & & V \\ \hline V_{LWT} & Lower Threshold Voltage (V_{CC}) & T_A = 25^{\circ}C & & & & & & & V \\ \hline \end{tabular}$	T _{DEAD}	Dead Time		100	150	250	nS	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	I _{OCSET}	Over Current Set Isink		-	70	-	uA	
V_{REF} Accuracy 0°C to 70°C -2 - + 2 % Soft Start I_{SSC Charge Current $V_{SS} = 1.5V$ 8.0 10 12 uA I_{SSD Discharge Current $V_{SS} = 1.5V$ 1.3 2 2.7 uA Under voltage lockout (UVLO) V_{UT} Upper Threshold Voltage (V_{CC}) $T_A = 25^{\circ}C$ $ 6.8$ $-$ V V_{LWT} Lower Threshold Voltage (V_{CC}) $T_A = 25^{\circ}C$ $ 6.5$ $-$ V	Reference							
Accuracy -2 - +2 % Soft Start ISSC Charge Current $V_{SS} = 1.5V$ 8.0 10 12 uA ISSD Discharge Current $V_{SS} = 1.5V$ 1.3 2 2.7 uA Under voltage lockout (UVLO) VUT Upper Threshold Voltage (V _{CC}) $T_A = 25^{\circ}C$ $ 6.8$ $-$ V V _{LWT} Lower Threshold Voltage (V _{CC}) $T_A = 25^{\circ}C$ $ 6.5$ $-$ V	M	Reference Voltage	-0°C to 70°C	1.225	1.25	1.275	V	
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III <th< td=""><td>Soft Start</td><td>•</td><td></td><td></td><td>•</td><td></td><td></td></th<>	Soft Start	•			•			
I_SSDDischarge Current $V_{SS} = 1.5V$ 1.322.7uAUnder voltage lockout (UVLO) V_{UT} Upper Threshold Voltage (V_{CC})-6.8-V V_{LWT} Lower Threshold Voltage (V_{CC}) $T_A = 25^{\circ}C$ -6.5-V	I _{SSC}	Charge Current	V _{SS} = 1.5V	8.0	10	12	uA	
V_{UT} Upper Threshold Voltage (V_{CC})-6.8-V V_{LWT} Lower Threshold Voltage (V_{CC}) $T_A = 25^{\circ}C$ -6.5-V		Discharge Current	V _{SS} = 1.5V	1.3	2	2.7	uA	
V_{LWT} Lower Threshold Voltage (V_{CC}) $T_A = 25^{\circ}C$ -6.5-V	Under volta	ge lockout (UVLO)				I		
	V _{UT}	• • • •		-	6.8	-	V	
V _{HT} Hysteresis (V _{CC}) - 300 - mV	V _{LWT}			-	6.5	-	V	
Nate 4. Consideration refere to Turning Application Circuit	V _{HT}			-	300	-	mV	

Note 1. Specification refers to Typical Application Circuit.

Note 2. This device is ESD sensitive. Use of standard ESD handling precautions is required. **Note 3.** Abnormal condition; Ex: over-current, output over-voltage, under-voltage lockout, soft-start disappear.

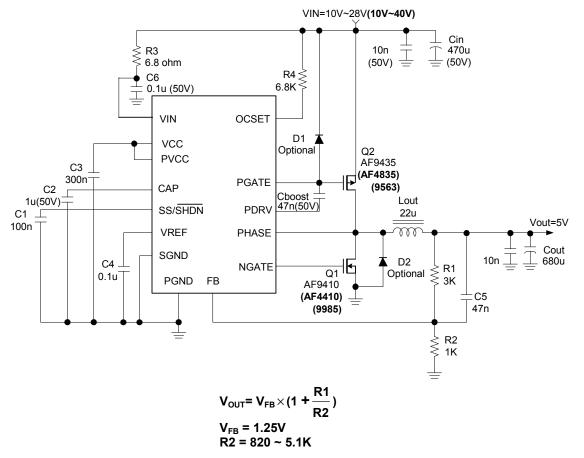
Note 4. V_{cc} pin should not be used to externally source current. It is not short protected.



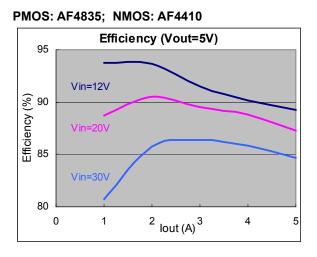
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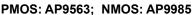
Synchronous PWM Controller

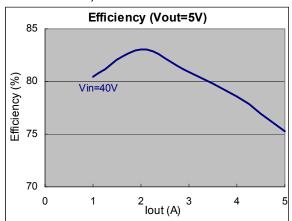
Typical Application Circuit



Typical Performance Characteristics



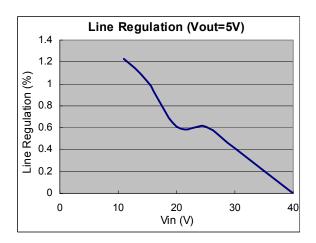


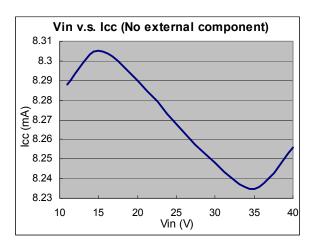


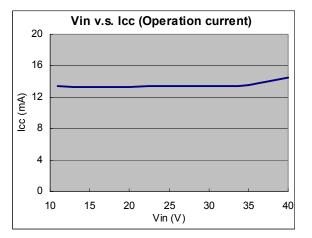


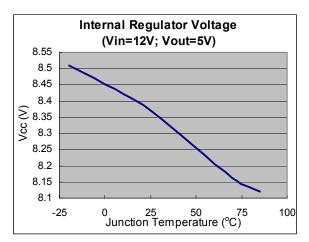
AP2011

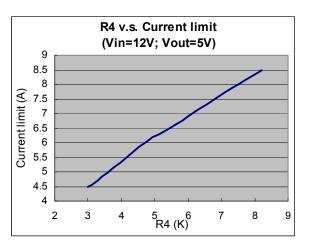
Typical Performance Characteristics









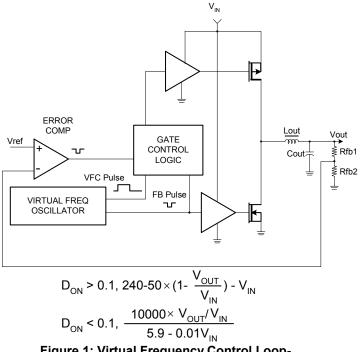


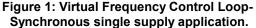


AP2011

Virtual Frequency Control

Frequency Control™ Virtual combines the advantages of constant frequency and constant off-time control in a single mode of operation. This allows fix frequency, precision switching voltage regulator control with fast transient response and the smallest solution size. Switch duty cycle can be adjusted from 0% to 100% on a pulse by pulse basis when responding to transient conditions. Both 0% and 100% duty cycle operation can be maintained for extended periods of time in response to load or line transients. Figure 1 depicts a simplified operation of the Virtual Frequency Control technique: The VFC oscillator generates a pulse of a known duration (VFC_Pulse). The regulator loop responds by returning a complementary feedback pulse (FB_Pulse). The FB_Pulse duration is a result of external conditions such as inductor size, the voltage across the inductor and the duration of the VFC_Pulse. A VFC control loop is then formed whereby the duration of the VFC_Pulse is modified as a result of the FB_Pulse duration. The VFC loop arrives at a state of equilibrium, where the operating frequency remains inherently constant.





Virtual frequency control is a technique that provides stable, constant frequency of operation for pulse controlled architectures such as constant off-time/on-time. This is all done internal to the IC with minimal number of components and without the need for connections to external terminals such as input and/or output. No external compensation is required, thus providing a low cost, high performance fix frequency solution for switching voltage regulators.

Virtual Frequency Control is a trademark of PWRTEK, LLC.



Synchronous PWM with VFC Controller

AP2011

Function Description

Synchronous Buck Converter

Primary V_{CORE} power is provided by a synchronous, voltage-mode pulse width modulated (PWM) controller. This section has all the features required to build a high efficiency synchronous buck converter, including soft-start, shutdown, and cycle-by-cycle current limit.

Referring to the functional block diagram FIG 1, the output voltage of the synchronous converter is set and controlled by the output of the error comparator. The external resistive divider reference voltage, is derived from an internal trimmed-bandgap voltage reference. The inverting input of the error comparator receives its voltage from the FB pin.

The internal oscillator uses an on-chip capacitor and trimmed precision current sources to set the virtual oscillation frequency to 200Khz. The virtual frequency oscillator sets the PWM latch. This pulls DRVN low, turning off the low-side N MOSFET and DRVP is pulled low, turning on the high-side P-MOSFET (once the cross-current control allows it). The triangular voltage ramp at the FB pin is then compared against the reference voltage at the inverting input of the error comparator. When the FB voltage increases above the reference voltage, the comparator output goes high. This pulls DRVP high, turning off the high-side P-MOSFET, and DRVN is pulled high, turning on the low-side N-MOSFET (once the cross-current control allows it). The Virtual Frequency Oscillator then generates a programmed off time to allow the FB voltage to return to the valley voltage of the triangular ramp. At the end of the off time the PWM latch is set and the cycle repeats again.

Under Voltage Lockout

The under voltage lockout circuit of the AP2011 assures that the high-side P-MOSFET driver outputs remain in the off state whenever the supply voltage drops below set parameters. Lockout occurs if V_{CC} falls below 6.5V. Normal operation resumes once V_{CC} rises above 6.8V.

R_{DS(ON)} Current Limiting

The current limit threshold is set by connecting an external resistor from the V_{CC} supply to OCSET. The voltage drop across this resistor is due to the 70uA internal sink sets the voltage at the pin. This voltage is compared to the voltage at the PHASE node. This comparison is made only when the high-side drive is high to avoid false current limit triggering due to uncontributing measurements from the MOSFETs off-voltage. When the voltage at PHASE is less than the voltage at OCSET, an overcurrent condition occurs and the soft start cycle is initiated. The synchronous switch turns on and SS/SHDN starts to sink 2uA. When SS/SHDN reaches 0.2V, it then starts to source 10uA and a new cycle begins. When the soft start voltage is below 0.9V the cycle is controlled with pulse by pulse current limiting.

Soft Start

Initially, SS/SHDN sources 10uA of current to charge an external capacitor. The inverting input of the error comparator is clamped to a voltage proportional to the voltage on SS/SHDN. This limits the on-time of the high-side P-MOSFET, thus leading to a controlled ramp-up of the output voltages.

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Synchronous PWM Controller

Function Description

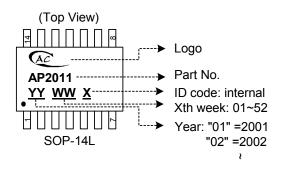
Hiccup Mode

During power up, the SS/ SHDN pin is internally pulled low until V_{CC} reaches the under-voltage lockout level of 6.8V. Once V_{CC} has reached 6.8V, the SS/ SHDN pin is released and begins to source 10uA of current to the external soft-start capacitor. As the soft-start voltage rises, the inverting input of the error comparator is clamped to this voltage. When the error signal reaches the level of the internal 1.25V reference, the output voltage is to have reached its programmed voltage. If an over-current condition has not occurred the soft-start voltage will continue to rise and level off at about 2.4V.

An over-current condition occurs when the high-side drive is turned on, but the PHASE node does not reach the voltage level set at the OCSET pin. Once an over-current occurs, the high-side drive is turned off <u>and</u> the low-side drive turns on and the SS/ SHDN pin begins to sink 2uA. The soft-start voltage will begin to decrease as the 2uA of current discharge the external capacitor. When the soft-start voltage reaches 0.2V, the SS/ SHDN pin will begin to source 10uA and begin to charge the external capacitor causing the soft-start voltage to rise again. If the over-current condition is no longer present, normal operation will continue. If the over-current condition is still present, the SS/ SHDN pin will again begin to sink 2uA. This cycle will continue indefinitely until the over-current condition is removed.

In order to prevent substrate glitching, a small-signal diode should be placed in close proximity to the chip with cathode connected to PHASE and anode connected to GND.

Marking Information



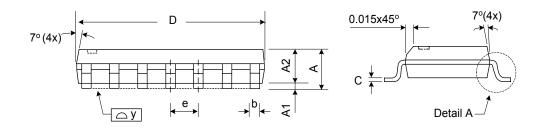


AP2011

Package Information

Package Type: SOP-14L

Pin 1 indent



Symbol	Dimensions In Millimeters		Dimensions In Inches			
Symbol	Min.	Nom.	Max.	Min.	Nom.	Max.
Α	1.47	1.60	1.730	0.0580	0.063	0.0680
A1	0.10	-	0.250	0.0040	-	0.0100
A2	-	1.45	-	-	0.057	-
b	0.33	0.41	0.510	0.0130	0.016	0.0200
С	0.19	0.20	0.250	0.0075	0.008	0.0098
D	8.53	8.64	8.740	0.3360	0.340	0.3440
E	5.80	6.00	6.200	0.2283	0.236	0.2441
E1	3.80	3.90	3.990	0.1496	0.153	0.1571
е	-	1.27	-	-	0.050	-
L	0.38	0.71	1.270	0.0150	0.028	0.0500
Y	-	-	0.076	-	-	0.0030
θ	0 ⁰	-	8 ⁰	0 ⁰	-	8 ⁰