

# ZR431L Adjustable precision shunt regulator

## Summary

#### Description

The ZR431L is a three terminal adjustable shunt regulator offering excellent temperature stability and output current handling capability up to 25mA. The output voltage may be set to any chosen voltage between 1.24 and 10 volts by selection of two external divider resistors.

The devices can be used as a replacement for zener diodes in many applications requiring an improvement in zener performance.

The ZR431L is particularly used in the feedback control loop of switch mode power supplies. In this application the device 1.24 volt reference enables the generation of low voltage supplies, typically 3.3 volts or 3 volts.

#### Features

- 2.5% and 1% tolerance
- Max. temperature coefficient 50 ppm/°C
- Temperature compensated for operation over -40 to 85°C
- 100mA to 25mA current sink capability
- Surface mount SOT23 package

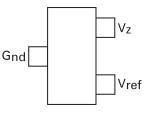
#### Applications

- Switch mode power supplies
- Shunt regulator
- Series regulator
- · Voltage monitor
- Over voltage / under voltage protection

#### **Ordering information**

Device	Pack	Part mark	Status	Quantity per reel	Reel size (inches)	TOL %
ZR431LF01TA	SOT23	43M	Active	3000	7	1
ZR431LF02TA	SOT23	43L	Active	3000	7	2.5
ZR431LC01STOB	TO92	ZR431L01	Obsolete	1500		1
ZR431LC02STOB	TO92	ZR431L02	Obsolete	1500		2.5
ZR431LC01L	TO92	ZR431L01	Obsolete		Loose	1
ZR431LC02L	TO92	ZR431L02	Obsolete		Loose	2.5





## Absolute maximum ratings

Parameter	Symbol	Limit	Unit
Cathode voltage	Vz	10	V
Cathode current		50	mA
Storage temperature	T <sub>STG</sub>	-55 to 105	°C
Junction temperature	Τ <sub>J</sub>	-40 to 125	°C

## **Power dissipation** (at $T_{amb} = 25^{\circ}C$ unless otherwise stated)

Package	Value	e Unit
SOT23	330	mW

## **Recommended operating conditions**

Parameter	Min.	Max.
Cathode voltage	V <sub>REF</sub>	10V
Cathode current	100µA	25mA
Operating temperature	-40°C	85°C

## **Block diagram**

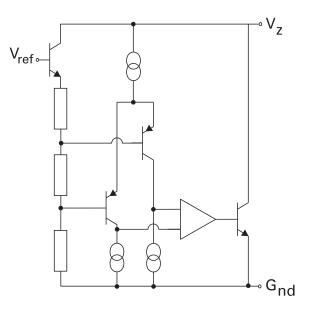
Vmax

Vmin

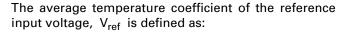
T1

Vdev = Vmax - Vmin

Temperature



Deviation of reference input voltage,  $V_{\text{dev}}$ , is defined as the maximum variation of the reference input voltage over the full temperature range.



$$Vref(ppmIC) = \frac{V_{dev}x1000000}{V_{ref}(T1-T2)}$$

The dynamic output impedance, R<sub>z</sub>, is defined as:

$$R_{Z} = \frac{\Delta V_{Z}}{\Delta I_{Z}}$$

Τ2

When the device is programmed with two external resistors, R1 and R2, (fig 2), the dynamic output impedance of the overall circuit, R', is defined as:

$$R' = R_Z (1 + \frac{R_I}{R_Z})$$

Parameter	Symbol	Min.	Тур.	Max.	Unit	Conditions
Reference Voltage 2.5% 1.0%	V <sub>ref</sub> V <sub>ref</sub>	1.209 1.228	1.24 1.24	1.271 1.252	V V	$I_L = 10mA$ (Fig1), $V_Z = V_{ref}$
Deviation of Reference Input Voltage over Temperature	V <sub>dev</sub>		4.0	8.0	mV	I <sub>L</sub> = 10mA, V <sub>Z</sub> = V <sub>ref</sub> T <sub>a</sub> = full range (Fig 1)
Ratio of the change in Reference Voltage to the change in Cathode Voltage)	$\frac{\Delta V_{ref}}{\Delta V_Z}$		0.5	2.0	mV/V	V <sub>Z</sub> from V <sub>ref</sub> to 10V I <sub>Z</sub> = 10mA (Fig2)
Reference Input Current	I <sub>ref</sub>	0.02	0.11	0.4	μA	R1 = 10k, R2 = O/C, I <sub>L</sub> = 10mA (fig2)
Deviation of Reference Input Current over Temperature	$\Delta I_{ref}$		0.02	0.2	μA	$\begin{array}{l} \text{R1} = 10\text{k}, \text{R2} = \text{O/C}, \\ \text{I}_{\text{L}} = 10\text{mA} \text{ T}_{\text{a}} = \text{full} \\ \text{range} (\text{Fig2}) \end{array}$
Minimum Cathode Current for Regulation	I <sub>Zmin</sub>		30	100	μΑ	
Off-state Current	I <sub>Zoff</sub>		10	30	μA	V <sub>Z</sub> = 10V, V <sub>ref</sub> = 0V (Fig3)
Dynamic Output Impedance	R <sub>Z</sub>		0.25	2	Ω	$V_Z = V_{ref}(Fig1), f = 0Hz, I_L = 10mA$

## **Electrical characteristics** (at $T_{amb} = 25^{\circ}C$ unless otherwise stated)

DC Test circuits

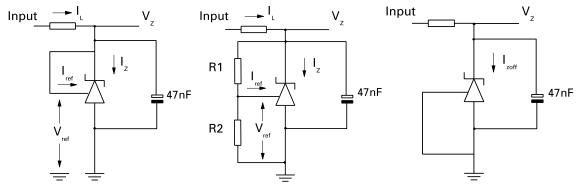
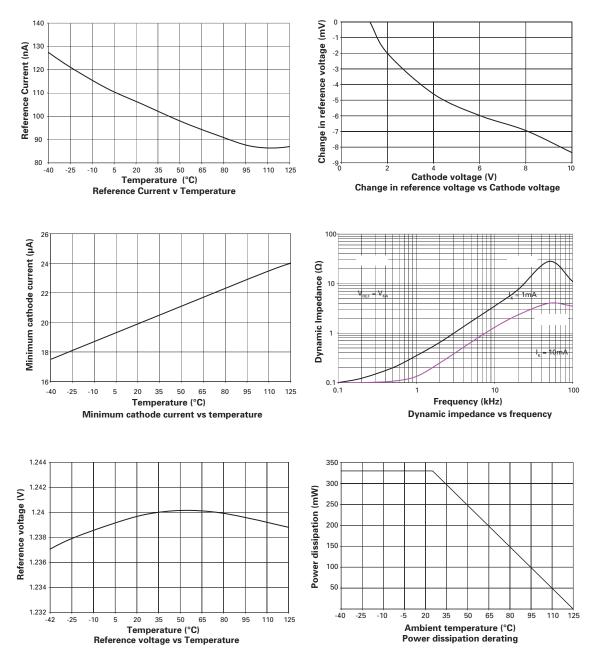
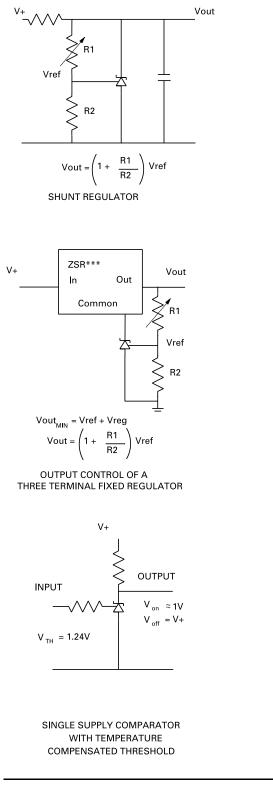


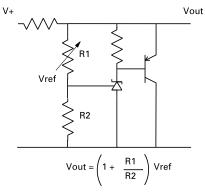
Fig 1 - Test Circuit for  $V_Z = V_{ref}$  Fig 2 - Test Circuit for  $V_Z > V_{ref}$  Fig 3 - Test Circuit for Off State current

## **Typical characteristics**

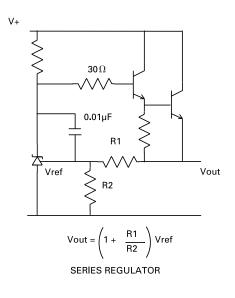


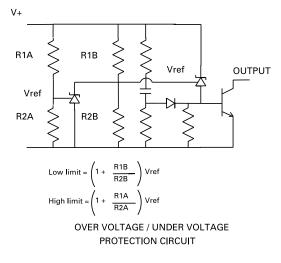
## **Application circuits**





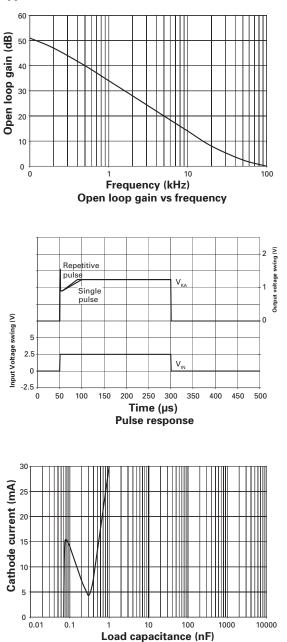
HIGHER CURRENT SHUNT REGULATOR





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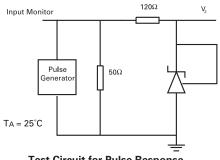
#### **Typical characteristics**



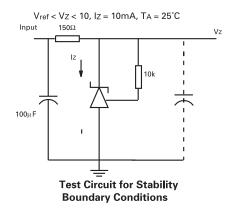
Stability boundary conditions

Vz Iz 240Ω 47k 10mF 忙 47k 닄  $Iz = 10 \text{mA}, TA = 25^{\circ}\text{C}$ 

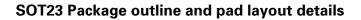
Test Circuit for Open Loop Voltage Gain

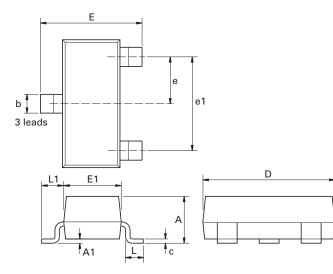


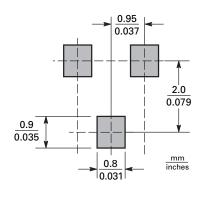
**Test Circuit for Pulse Response** 



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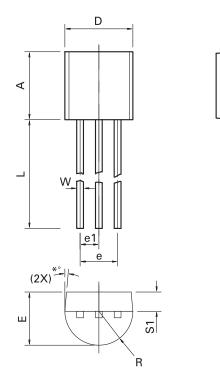




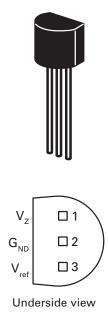
Dim.	Millin	neters	Inc	hes	Dim.	Millimeters		Inches	
	Min.	Max.	Min.	Max.		Min.	Max.	Min.	Max.
А	-	1.12	-	0.044	e1	1.90	NOM	0.075	NOM
A1	0.01	0.10	0.0004	0.004	E	2.10	2.64	0.083	0.104
b	0.30	0.50	0.012	0.020	E1	1.20	1.40	0.047	0.055
С	0.085	0.20	0.003	0.008	L	0.25	0.60	0.0098	0.0236
D	2.80	3.04	0.110	0.120	L1	0.45	0.62	0.018	0.024
е	0.95	NOM	0.037	NOM	-	-	-	-	-

Note: Controlling dimensions are in millimeters. Approximate dimensions are provided in inches.

## **TO92 Package outline**







Dim.	Millimeters		Inc	hes	
	Min.	Max.	Min.	Max.	
A	4.32	4.95	0.170	0.195	
b	0.36	0.51	0.014	0.020	
E	3.30	3.94	0.130	0.155	
е	2.41	2.67	0.095	0.105	
e1	1.14	1.40	0.045	0.055	
L	12.70	15.49	0.500	0.610	
R	2.16	2.41	0.085	0.095	
S1	1.14	1.52	0.045	0.060	
W	0.41	0.56	0.016	0.022	
D	4.45	4.95	0.175	0.195	
*0	4°	6°	4°	6°	

Note: Controlling dimensions are in millimeters. Approximate dimensions are provided in inches

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