

### L9826

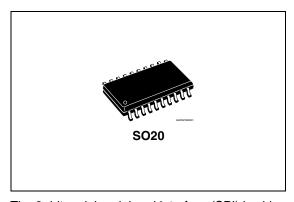
# Octal protected low-side driver with diagnostic and serial/parallel input control

#### **Features**

- 8 channels low side driver with 450 mA output current capability
- Typical R<sub>DSON</sub> 1.5  $\Omega$  at T<sub>J</sub> = 25 °C
- Parallel control for output 1 and 2
- SPI control on all outputs
- Reset function
- Diagnostic through 8 bit SPI
- Intrinsic output voltage clamping 50 V (Typ) protection for inductive load drive
- Short circuit current limitation and thermal shutdown for outputs 1 and 2
- Overcurrent and short circuit shutdown for outputs 3 to 8



The L9826 is a protected octal low-side driver IC designed for the automotive environment.



The 8 -bit serial peripheral interface (SPI) is able to control the device's eight channels and to provide its load's diagnosis. In addition output 1 and 2 can also be controlled through dedicated input pins NON1 and NON2.

Overcurrent and short-circuit protections are present as well as the output voltage clamping which is able to protect the L9826 during operation with inductive loads.

Table 1. Device summary

Order code	Order code Package	
L9826	SO20	Tube
L9826TR	SO20	Tape and reel
E-L9826	SO20	Tube
E-L9826TR	SO20	Tape and reel

February 2011 Doc ID 7214 Rev 9 1/19

Contents L9826

# **Contents**

1	Bloc	k Diagr	am	5
2	Pins	descri	ption	6
3	Elec	trical s <sub>l</sub>	pecifications	7
	3.1	Absolu	ute maximum ratings	7
	3.2	Therm	nal data	7
	3.3	Electri	ical characteristics	8
4	Арр	lication	information	11
5	Fund	ctional	description	12
	5.1	Gener	al	12
	5.2	Outpu	t stage control	12
		5.2.1	Via parallel, only for output 1 and 2	12
		5.2.2	Via 8-bit SPI for all the outputs	13
	5.3	Outpu	t stage diagnostics	14
		5.3.1	Diagnostic on Outputs 1 and 2 controlled via NON1/NON2	15
		5.3.2	Diagnostic on Outputs 1 to 8 controlled via SPI	15
	5.4	Protec	etions	16
		5.4.1	Flyback current	16
		5.4.2	Current regulation mode outputs 1 and 2	16
		5.4.3	Short circuits outputs 3 to 8	16
6	Pack	age inf	formation	17
7	Revi	sion his	storv	18



L9826 List of tables

# List of tables

Table 1.	Device summary	. 1
Table 2.	Pin description	. 6
Table 3.	Absolute maximum ratings for voltages and currents applied externally to the device	. 7
Table 4.	Absolute maximum ratings for currents determined within the device	. 7
Table 5.	Thermal data	. 7
Table 6.	Electrical characteristics	. 8
Table 7.	Outputs control tables	. 12
Table 8.	Diagnostic table for outputs 1 and 2 in parallel controlled mode	15
Table 9.	Diagnostic table for outputs 1 to 8 in SPI controlled mode	15
Table 10.	Document revision history	18



List of figures L9826

# **List of figures**

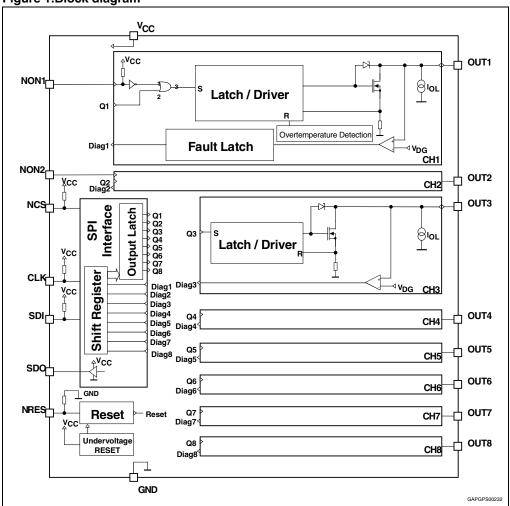
Figure 1.	Block diagram	. 5
Figure 2.	Connection diagram (top view)	
Figure 3.	Typical application circuit diagram	11
Figure 4.	Parallel control for output 1 and 2 (Example for Power-on)	12
Figure 5.	Output control register structure	13
Figure 6.	Timing of the serial interface	13
Figure 7.	The pulse diagram to read the outputs status register	14
Figure 8.	The structure of the outputs status register	14
Figure 9.	SO20 mechanical data and package dimensions	17



L9826 Block Diagram

# 1 Block Diagram





Pins description L9826

# 2 Pins description

Figure 2. Connection diagram (top view)

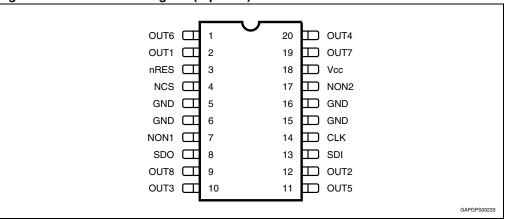


Table 2. Pin description

N°	Pin	Description
1	Out 6	Output 6
2	Out 1	Output 1
3	NRes	Asynchronous reset
4	NCS	Chip select (active low)
5	GND	Device ground
6	GND	Device ground
7	NON1	Control input 1
8	SDO	Serial data output
9	Out 8	Output 8
10	Out 3	Output 3
11	Out 5	Output 5
12	Out 2	Output 2
13	SDI	Serial data input
14	CLK	Serial clock
15	GND	Device ground
16	GND	Device ground
17	NON2	Control input 2
18	V <sub>CC</sub>	Supply voltage
19	Out 7	Output 7
20	Out 4	Output 4

# 3 Electrical specifications

### 3.1 Absolute maximum ratings

Table 3. Absolute maximum ratings for voltages and currents applied externally to the device

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit		
V <sub>CC</sub>	Supply voltage	-	-0.3		7	V		
Inputs and data lines (NONx, NCS, CLK, SDI, nRes)								
V <sub>IN</sub>	Voltage (NONx, NCS, CLK, SDI, nRes)		-0.3	-	7	V		
I <sub>IN</sub>	Protection diodes current <sup>(1)</sup>	T ≤ 1ms	-20	-	20	mA		
Outputs (Out1 Out8)								
V <sub>OUTc</sub>	Continuous output voltage	-	-0.7	-	45	V		
I <sub>OUT</sub>	Output current (2)	-	-2	-	1.0	Α		
E <sub>OUTcl</sub>	Output clamp energy	$I_{OUT} \leq 150 mA$	1	ı	10	mJ		

<sup>1.</sup> All inputs are protected against ESD according to MIL 883C; tested with HBM at 2 kV. It corresponds to a dissipated energy E  $\leq$  0.2 mJ.

Table 4. Absolute maximum ratings for currents determined within the device

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit	
Outputs (	Out1 Out8)						
I <sub>OUT</sub>	Output current (Out1, Out2)	-	-	-	I <sub>LIM</sub>	Α	
	Output current (Out3 Out8)	-	-	-	I <sub>SCB</sub>	Α	
$\Sigma I_{OUT1}$ i = 1-8	Total average-current all outputs (1)	T <sub>amb</sub> = 60°C	2.0	-		Α	

When operating the device with short circuit 1ch and 2ch outputs at the same time, damage due to electrical overstress might occur.

#### 3.2 Thermal data

Table 5. Thermal data

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit		
Thermal shutdown								
T <sub>JSC</sub>	Thermal shutdown threshold	-	150	165	-	°C		
Thermal resistance								
R <sub>thj a-one</sub>	Single output (junction ambient)	-	-	-	90	°C/W		
R <sub>thj a-all</sub>	All outputs (junction ambient)	-	-	-	75	°C/W		
R <sub>th j-pin</sub>	Junction to Pin	-	-	-	18	°C/W		

Doc ID 7214 Rev 9 7/19

<sup>2.</sup> Transient pulses in accordance to DIN40839 part 1, 3 and ISO 7637 Part 1, 3.

### 3.3 Electrical characteristics

Refer to 4.5 V  $\leq$  V  $_{CC} \leq$  5.5 V; -40  $^{\circ}C \leq$  T  $_{J} \leq$  150  $^{\circ}C;$  unless otherwise specified.

Table 6. Electrical characteristics

Symbol	Parameter Test condition		Min.	Тур.	Max.	Unit
Supply v	oltage					
I <sub>ccSTB</sub>	Standby current	without load (nRes = Low)	-	-	70	μΑ
I <sub>ccOPM</sub>	Operating mode	I <sub>OUT1 8</sub> = 500 mA SPI - CLK = 3 MHz NCS = LOW SDO no load	-	-	5	mA
Δl <sub>CC</sub>	$\Delta I_{CC}$ during reverse output current	I <sub>out</sub> = -2 A	-	-	100	mA
V <sub>DDRES</sub>	Undervoltage reset	Reset of all registers and disable of all outputs	3	-	4	V
Inputs (N	ONx. NCS, CLK, SDI, nRES)					
V <sub>INL</sub>	Low level	-	-0.3	-	0.2·V <sub>CC</sub>	V
V <sub>INH</sub>	High level	-	0.7·V <sub>CC</sub>	-	V <sub>CC</sub> +0,3	V
V <sub>hyst</sub>	Hysteresis voltage	-	0.85	-	-	V
I <sub>IN</sub>	Input current	NONx, NCS, CLK, SDI $V_{IN} = V_{CC}$	-	-	10	μА
		NRES (V <sub>IN</sub> = 0V)	-10	-	-	μΑ
$R_{IN}$	Pull-up resistance	(NONx, NCS, CLK, SDI) Pull-down resistance (NRes)	50	-	250	kΩ
C <sub>IN</sub>	Input capacitance	Guaranteed by design	-	-	10	pF
Serial da	ta outputs					
V <sub>SDOH</sub>	High output level	I <sub>SDO</sub> = -4mA	V <sub>CC</sub> -0.4	-	-	V
V <sub>SDOL</sub>	Low output level	I <sub>SDO</sub> = 3,2mA		-	0.4	V
I <sub>SDOL</sub>	Tristate leakage current	NCS = high; $0V \le V_{SDO} \le V_{CC}$	-10	-	10	μΑ
C <sub>SDO</sub>	Output capacitance	f <sub>SDO</sub> = 300 kHz, Guaranteed by design	-	-	10	pF
Outputs	OUT 1 8					
		OUTx = OFF; V <sub>OUTx</sub> = 25 V; V <sub>CC</sub> = 5 V	-	-	100	μА
I <sub>OUTL1 - 8</sub>	Leakage current	OUTx = OFF; V <sub>OUTx</sub> = 16 V; V <sub>CC</sub> = 5 V	-	-	100	μА
		OUTx = OFF; V <sub>OUTx</sub> = 16 V; V <sub>CC</sub> = 1 V	-	-	10	μА

Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
V <sub>clp</sub>	Output clamp voltage	1 mA $\leq$ I <sub>clp</sub> $\leq$ I <sub>outp</sub> ; I <sub>test</sub> = 10 mA with correlation	45	-	62	V
R <sub>DSon</sub>	On resistance OUT 1 8	I <sub>OUT</sub> = 250 mA; T <sub>j</sub> = +150 °C	-	-	3.0	Ω
C <sub>OUT</sub>	Output capacitance	V <sub>OUT</sub> = 16 V; f = 1 MHz guaranteed by design	-	-	300	pF
Outputs	short circuit protection					
I <sub>SBC</sub>	Overcurrent shutoff threshold	OUT3 OUT8	0.45	-	1.1	Α
I <sub>LIM</sub>	Short circuit current limitation	OUT1; OUT2	0.5	-	1.1	Α
t <sub>SCB</sub>	Delay shutdown	-	0.2	3,0	12	μS
Diagnost	ics					
V <sub>DG</sub>	Diagnostic threshold voltage	-	0.32 ⋅V <sub>CC</sub>	-	0.4·V <sub>CC</sub>	٧
l <sub>OL</sub>	Open load detection sink current	$V_{out} = V_{DG}$	20	-	100	μΑ
t <sub>df</sub>	Diagnostic detection filter time	for output 1 & 2 on each diagnostic condition	15	-	50	μs
Outputs ti	iming				'	
t <sub>don1</sub>	Turn ON delay of OUT 1 and 2	NON <sub>1, 2</sub> = 50% to $V_{OUT}$ = 0,9· $V_{bat}$ NCS = 50% to $V_{OUT}$ = 0,9· $V_{bat}$ ( $V_{BAT}$ = 16V, $R_L$ = 500 $\Omega$ )	-	-	5	μs
t <sub>don2</sub>	Turn ON delay of OUT 3 to 8	NCS = 50% to $V_{OUT} = 0.9 \cdot V_{bat}$ ( $V_{BAT} = 16V$ , $R_L = 500\Omega$ )	-	-	10	μs
t <sub>doff</sub>	Turn OFF delay of OUT 1 to 8	NCS = 50% to $V_{OUT} = 0.1 \cdot V_{bat}$ NON <sub>1, 2</sub> = 50% to $V_{OUT} = 0.1 \cdot V_{bat}$ ( $V_{BAT} = 16V, R_L = 500\Omega$ )	-	-	10	μs
dU <sub>on1/dt</sub>	Turn ON voltage slew-rate	For output 3 to 8; 90% to 30% of $V_{bat}$ ; $R_L = 500\Omega$ ; $V_{bat} = 16V$	0.7	-	3.5	V/μs
dU <sub>on2/dt</sub>	Turn ON voltage slew-rate	For output 1 and 2; 90% to 30% of V <sub>bat</sub> ; R <sub>L</sub> = 500Ω; V <sub>bat</sub> = 16V	2	-	10	V/μs
dU <sub>off1/dt</sub>	Turn OFF voltage slew-rate	For output 1 to 8; 30% to 90% of $V_{bat}$ ; $R_L = 500\Omega$ ; $V_{bat} = 16V$	2	-	10	V/μs
dU <sub>off2/dt</sub>	Turn OFF voltage slew-rate	For output 1 to 8; 30% to 80% of $V_{bat}$ ; $R_L = 500\Omega$ ; $V_{bat} = 0.9 \cdot V_{clp}$	2	-	15	V/μs
Serial dia	agnostic link (load capacitor at	SDO = 100 pF)				
f <sub>clk</sub>	Clock frequency	50 % duty cycle	-	-	3	MHz
t <sub>clh</sub>	Minimum time CLK = high	-	160	-	-	ns
t <sub>cll</sub>	Minimum time CLK = low	-	160	-	-	ns
t <sub>pcld</sub>	Propagation delay CLK to data at SDO valid	$4.9~V \leq V_{CC} \leq 5.1V$	-	-	100	ns

577

Doc ID 7214 Rev 9

9/19

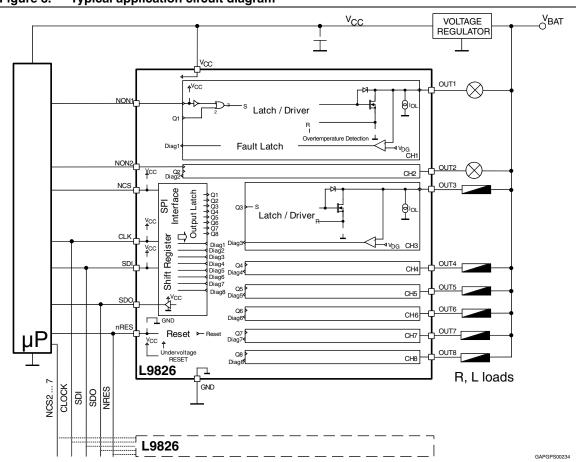
Table 6. Electrical characteristics (continued)

Symbol	Parameter	Test condition	Min.	Тур.	Max.	Unit
t <sub>csdv</sub>	NCS = LOW to data at SDO active	-	-	-	100	ns
t <sub>sclch</sub>	CLK low before NCS low	Setup time CLK to NCS change H/L	100	-	-	ns
t <sub>hclcl</sub>	CLK change L/H after NCS = low	-	100	-	-	ns
t <sub>scld</sub>	SDI input setup time	CLK change H/L after SDI data valid	20	1	ı	ns
t <sub>hcld</sub>	SDI input hold time	SDI data hold after CLK change H/L	ı	1	20	ns
t <sub>sclcl</sub>	CLK low before NCS high	-	150	-	-	ns
t <sub>hclch</sub>	CLK high after NCS high	-	150	-	-	ns
t <sub>pchdz</sub>	NCS L/H to output data float	-	-	-	100	ns
-	NCS pulse filter time	Multiple of 8 CLK cycles inside NCS period	-			-

### 4 Application information

The typical application diagram is shown in Figure 3.

Figure 3. Typical application circuit diagram



For higher current capability the two outputs of the same kind can be paralleled and the maximum flyback energy should not exceed the limit for a single output.

The circuit immunity at output transients have been verified during the characterization with Test Pulses 1, 2, 3a and 3b, DIN40839 or ISO7637 part 3.

The Test Pulses are coupled to the outputs with 200 pF series capacitor and all the outputs are able to withstand to test pulses without damage. The load applied was in the range of 30 to 100 ohm for the resistive part and 0 to 600 mH for the inductive one.

### 5 Functional description

#### 5.1 General

The L9826 is an 8-channel low-side driver assembled in SO20 package. Its 8-bit SPI serial interface is designed to control all the outputs and to provide their diagnosis. Channels 1 and 2 are controlled either via SPI or via parallel through the inputs pins NON1 and NON2. Diagnostic recognizes operative fault conditions: open load, short circuits to GND or to VB and overcurrent. Thermal shutdown for outputs 1 and 2 is available as well the output voltage clamp which is essential in case of working with inductive loads.

The reset feature is an OR function of the external reset nRes and the internal reset generate during the undervoltage condition

#### 5.2 Output stage control

#### 5.2.1 Via parallel, only for output 1 and 2

This is valid only for Outputs 1 and 2 which are controlled through the dedicated inputs NON1 and NON2 (both active low) which are internally configured as pull-up (see *Figure 3*). This is to guarantee that the outputs are off in case of inputs open.

A further feature is the possibility to drive these outputs through a PWM signal independently by SPI commands.

Reset signal is common for all the eight channels and it is active low. After an external reset condition (that means NRES pin switched from low to high) to drive outputs 1 and 2 through the parallel input (NON1 and NON2) it is necessary to disable the parallel input itself (NON1, NON2 high) and then subsequently to drive the outputs 1 and 2 at the logic state desiderated through NON1 and NON2. The duration of the command (T) as reported in the *Figure 4* should be at less in the order of 100 nSecond.

In the next *Figure 4* is shown this behavior and in the next *Table 7* is summarized the scenario of parallel/series commands.

Figure 4. Parallel control for output 1 and 2 (Example for Power-on)

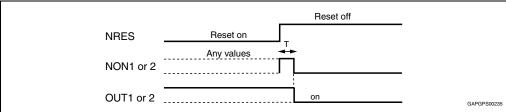


Table 7. Outputs control tables

Outputs 1, 2:				Outputs 3 to 8:			
NON1, 2	1	0	0	1	-	-	-
SPI-bit 1, 2	0	0	1	1	SPI-bit 3 8	0	1
Output 1, 2	off	on	on	on	Output 3 8	off	on

#### 5.2.2 Via 8-bit SPI for all the outputs

Control data are transmitted to SDI through a microcontroller in configuration master. The device is selected when NCS signal is low. The 8-bit command data are transmitted into L9826 shift registers every CLK falling edge (see *Figure 6* for SPI signals timing).

The NCS rising edge latches the new data from the shift register to the driver and the output are driven following the commands just sent.

The digital filter between NCS and the output latch ensures that the data are transferred only after 8 CLK cycles or multiple of 8 CLK cycles since the last NCS falling edge.

The NCS changes only at low CLK.

*Figure 5* shows the control register structure and in the detail its control-bit, while in the *Table 7* are summarized the controls outputs via SPI or dedicated input pins (NON1 and NON2).

Figure 5. Output control register structure

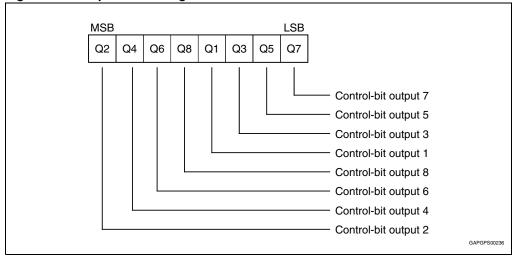
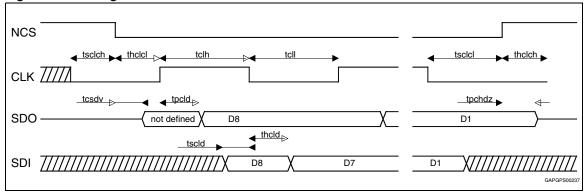


Figure 6. Timing of the serial interface



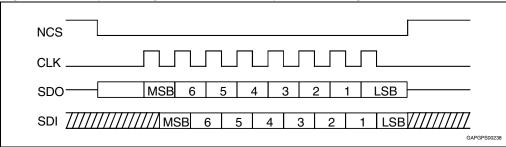
### 5.3 Output stage diagnostics

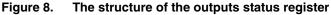
All the outputs voltage are compared with the diagnostic threshold (0.38 Typ · VCC) and this information is transferred in dedicated fault latches which are cleared when the NCS reaches the state low. Afterward the latch stores the status bit and the first reading after the error might be wrong. The second one is considered right.

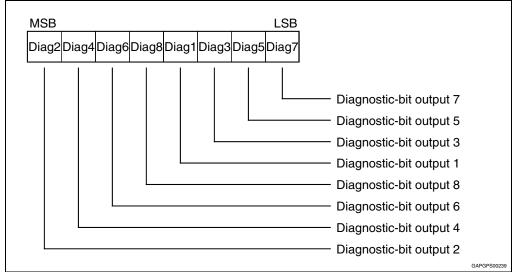
The next *Figure 7* and *8* show the diagnostic bits read out on SDO and their organization into the dedicated registers.

When NCS is low the data contained in the shift register are transferred to SDO output every CLK rising edge.

Figure 7. The pulse diagram to read the outputs status register







#### 5.3.1 Diagnostic on Outputs 1 and 2 controlled via NON1/NON2

#### Fault condition (1) "output shorted to Vbat"

The output has been previously switched-on and its voltage exceeds the diagnostics threshold. It operates in current regulation mode or it is switched-off if thermal shutdown threshold ( $T_{\rm JSC}$ ) is reached. The status bit is low.

#### Fault condition (2) "open load" or "output shorted to GND"

The output is switched-off and its voltage drops below the diagnostics threshold because the load current is lower than the output diagnostic current source. The diagnostic bit is low.

Table 8. Diagnostic table for outputs 1 and 2 in parallel controlled mode

Output 1, 2	Output-voltage	Status-bit	Output-mode	
off	> DG-threshold	high	correct operation	
off	< DG-threshold	low	fault condition 2)	
on	< DG-threshold	high	correct operation	
on	> DG-threshold	low	fault condition 1)	

#### 5.3.2 Diagnostic on Outputs 1 to 8 controlled via SPI

#### Fault condition (1) "output shorted to Vbat"

The output was previously switched-on, its voltage exceeds the diagnostic threshold and the result is that the output is switched-off. The diagnostic bit is high.

#### Fault condition (2) "open load" or "output shorted to GND"

It is the same behavior explained for the outputs 1 and 2 (see paragraph 5.3.1), at NCS falling edge the output status data are transferred to the shift register.

Table 9. Diagnostic table for outputs 1 to 8 in SPI controlled mode

Output 1 8	Output-voltage	Status-bit	Output-mode
off	> DG-threshold	high	correct operation
off	< DG-threshold	low	fault condition 2)
on	< DG-threshold	low	correct operation
on	> DG-threshold	high	fault condition 1)

Load diagnostic: when the output is in OFF condition a typical diagnostic current of 60  $\mu A$  is sinked.

#### 5.4 Protections

#### 5.4.1 Flyback current

Turning off the low side driver with an inductive load, its output voltage rises due to the inductor that tries to drive current. This voltage is internally clamped by the flyback circuit at  $V_{CPL}$  value, typical 50V

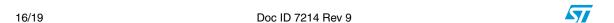
#### 5.4.2 Current regulation mode outputs 1 and 2

**Outputs 1 and 2** which are particularly dedicated for loads with inrush current (as lamps). When the channel is switched on and the current through the load exceeds the short circuit limit value ( $_{\text{Ilim}}$ ) for at least  $t_{\text{df}}$  time, the corresponding output goes in current regulation mode.

The output current is determinated by the output characteristic and its voltage depends on load resistance. In this mode, high power is dissipated in the output stage and its temperature increases rapidly. When the output stage temperature exceeds the thermal shutdown (T<sub>JSC</sub>), the overload latch is set and the corresponding output is switched off.

#### 5.4.3 Short circuits outputs 3 to 8

**Outputs 3 to 8** which are dedicated for loads without inrush currents. When the output current exceeds the short circuit threshold ( $I_{sbc}$ ) for at least  $T_{scb}$  time, the corresponding output is switched-off immediately and in the same time, the relative latch store the overload status.



L9826 Package information

# 6 Package information

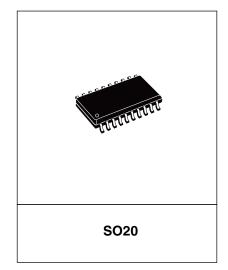
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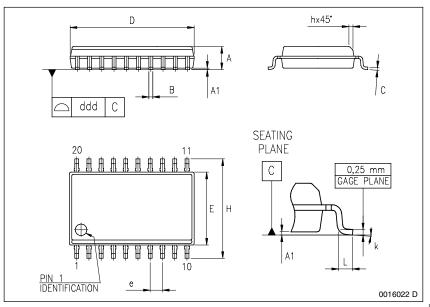
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Figure 9. SO20 mechanical data and package dimensions

DIM.	mm		inch			
	MIN.	TYP.	MAX.	MIN.	TYP.	MAX.
Α	2.35		2.65	0.093		0.104
A1	0.10		0.30	0.004		0.012
В	0.33		0.51	0.013		0.200
С	0.23		0.32	0.009		0.013
D (1)	12.60		13.00	0.496		0.512
Е	7.40		7.60	0.291		0.299
е		1.27			0.050	
Н	10.0		10.65	0.394		0.419
h	0.25		0.75	0.010		0.030
L	0.40		1.27	0.016		0.050
k		0	° (min.),	8° (max	.)	
ddd			0.10			0.004
(1) "D" dimension does not include mold flash, protusions or gate burrs. Mold flash, protusions or gate burrs shall not exceed 0.15mm per side.						







577

Doc ID 7214 Rev 9

Revision history L9826

# 7 Revision history

Table 10. Document revision history

Date	Revision	Changes
22-Apr-2004	7	Initial release in EDOCS
26-Jul-2005	8	Document reformatted.  Modify value R <sub>ON</sub> in the "Features".
08-Feb-2011	9	Updated Features and Description on page 1. Updated Table 1: Device summary on page 1. Updated Figure 3: Typical application circuit diagram. Reworked the content of the Section 5: Functional description.

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Doc ID 7214 Rev 9

19/19